

Vaios **Papaspyros**

Robotics & Machine Learning Engineer

Experience

Address

Lausanne Area Canton de Vaud. Switzerland

03/18 - Now Research Intern École Polytechnique Fédérale de Lausanne, Lausanne, Switzerland

Team: Laboratoire de Systèmes Robotiques (LSRO)

Research Topic: Self-Adaptive Mixed Societies of Animals and Robots.

Research Topic: Unmanned Heterogeneous Swarm of Sensor Platforms. Funding: European Defense Agency (EDA) "EuroSWARM" Project.

Supervisors: Frank Bonnet, Francesco Mondada.

11/17 - 02/18 Robotics Software Engineer

Myrmex Inc., Ilioupoli, Greece

Telephone

+30 698 2253076 (Greek) 06/17 - 11/17 Research Engineer

MEAD, Univ. of Patras, Patras, Greece

Mail

epfl.ch

b.papaspyros@ gmail.com vaios.papaspyros@

05/16 - 10/16 Research Intern

Inria Nancy Grand-Est, Nancy, France

Team: LARSEN/Resibots

Internship Title: Intelligent Trial & Error with the iCub humanoid robot. **Research Topic**: Robot damage recovery with safety constraints.

Supervisor: Jean-Baptiste Mouret.

Team: Applied Mechanics Lab

Funding: European Research Council (ERC) "ResiBots" Project.

Related Publications: "Safety-Aware Robot Damage Recovery Using

Constrained Bayesian Optimization and Simulated Priors".

Web & Git

Personal Website 😯

Twitter >

LinkedIn in

Github ()

Bitbucket 5

Education

OS Preference Linux ★★★★★ Windows ★★★★

MacOS ★★★★★

Languages Greek **** English ★★★★★ French **** 09/12 - 11/17 M.Eng in Computer Engineering & Science

GPA: 7.35 / 10

Diploma Thesis Subject: Safety-Aware Intelligent Trial-and-Error for

Robot Damage Recovery.

Grade: 10/10.

Supervisors: Ioannis Hatzilygeroudis, Jean-Baptiste Mouret.

09/10 - 06/12 **High School**

Costeas-Geitonas School, Athens, Greece

Univ. of Patras, Patras, Greece

GPA: 19.2 / 20

2013 - Now **Online Courses** Coursera, MIT and Stanford open courseware

I have attended over 10 courses covering a wide range of topics such as Machine Learning, Software Engineering, Android Development, Parallel Programming, Linear Algebra, Computer Architecture, Data Structures, Digital Signal Processing, etc.

Publications

Peer-Reviewed Workshops

Papaspyros, V., Chatzilygeroudis, K., Vassiliades, V. and Mouret, J.B., 2016.

Safety-Aware Robot Damage Recovery Using Constrained Bayesian Optimization and Simulated Priors

BayesOpt 2016: Proceedings of the International Workshop on "Bayesian Optimization" at NIPS 2016 | Supplementary Video

Reviews

2017 - NIPS Workshop - BayesOpt 2017

Reviewer for the BayesOpt 2017 Workshop of the Neural Information Processing Systems (NIPS) Conference.

Programming Assignments & Experience

ΑI,

Machine Learning,

& Robotics Interested in advancing in this field

• Research intern at Inria - Intelligent Trial & Error with the iCub humanoid

robot.

• Research intern at EPFL - Self-Adaptive Mixed Societies of Animals and

Robots.

C/C++ Co-author to robot dart

robot_dart is a flexible and generic C++11 wrapper for DART and is suitable

for evolutionary computation

C/C++ Contributor to limbo

limbo is a highly templated C++11 Bayesian optimization framework.

C/C++ Experienced with: Boost, LEDA, OpenMP, CUDA, OpenCL, OpenGL,

data structures, posix threads, TCP/IP protocols.

Python Experienced with: matplotlib, numpy and the waf build system.

Multiple assignments using python for data analysis or algorithmic design

(e.g. Aho-Corasick).

Matlab/Octave Plenty of experience with data analysis using Matlab.

University assignments for: Scientific Computation, Digital Telecomunications (quantizer, huffman code, PCM, FSK, PSK implementations) courses. Also, assignments for the online course "Machine Learning" (Coursera).

Java/Android Java and JavaFX, multiple Android data structure APIs.

Multiple university assignments requiring the use of Java and JavaF and

Android development. Also, a few personal Android projects.

Databases MySQL, sqlite, JDBC

University assignments: Database design, implementation & deployment.

Web HTML, CSS, PHP, Javascript

Examples of assignments: Simple mailing list manager (with a simple interface) using the campaign monitor php API, courrier-like complete system.

Competitions

02/2013 IEEExtreme9.0 IEEE

Team "Tokyooo" | Ranked top 25% worldwide.

Certifications

English Language Cambridge

Proficiency Level (C2)

French Language International Centre for French Studies

DELF (B2)

European Computer Driving Licence (ECDL) ECDL Foundation

International Certificate in IT Skills

Cambridge

Summary of skills

Advanced C/C++(11), Python, Boost, Eigen, Robot Operating System (ROS), Mat-

lab/Octave, LATEX, bash scripting, Object Oriented Design & Program-

ming, Policy-based design

Intermediate OpenMP, CUDA, OpenGL, Java, MySQL & Sqlite, HTML 5, CSS, PHP,

Javascript

Summary of language skills

Greek Native

English Fluent - Professional working proficiency

French Moderate - Limited working proficiency

Interests

Machine Learning

Artificial Intelligence

Programming

Robotics

Basketball

Music/Guitar

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