Vaios Papaspyros

PhDc in Machine Learning & Robotics @ EPFL

General	Evnerience			
Information	Experience			
Nationality: Greek Birthday: 28/04/1994	06/18 - <i>Now</i>	Doctoral Assistant	EPFL, Lausanne, Switzerland	
Address EPFL STI IBI-STI BIOROB ME B3 30 (Bâtiment ME) Station 9 CH-1015 Lausanne Switzerland		Team: Mobots @ Biorobotics laboratory (Biorob). Research Topic: Self-Adaptive Mixed Societies of Animals and Robots. Thesis director: Francesco Mondada. Funding: Swiss National Science Formation (SNF).		
	03/18 - 05/18	Research Intern	EPFL, Lausanne, Switzerland	
		Team : Mobots @ Laboratoire de Systèmes Robotiques (LSRO). Research Topic : Self-Adaptive Mixed Societies of Animals and Robots. Supervisors : Frank Bonnet, Francesco Mondada.		
Telephone +41 78 860 11 13 (Mobile) +41 21 693 56 80 (Work)	06/17 - 11/17	Research Engineer	MEAD, Univ. of Patras, Patras, Greece	
		Team: EuroSWARM team @ Applied Mechanics Lab. Research Topic: Unmanned Heterogeneous Swarm of Sensor Platforms. Funding: European Defense Agency (EDA) EuroSWARM Project.		
	05/16 - 10/16	Research Intern	Inria Nancy Grand-Est, Nancy, France	
Mail (Academic) vaios.papaspyros@ epfl.ch		Team: LARSEN/Resibots. Internship Title: Intelligent Trial & Error with the iCub humanoid robot. Research Topic: Robot damage recovery with safety constraints. Supervisor: Jean-Baptiste Mouret.		
(Personal)		Funding: European Research Council (ERC) ResiBots Project.		
b.papaspyros@ gmail.com	Educati	on		
Web & Git Personal Website Twitter LinkedIn Github Bitbucket	06/18 - <i>Now</i>	Doctor of Philosophy - PhD Candidate Robotics, Control, and Intelligent Systems	EPFL, Lausanne, Switzerland	
	09/12 - 11/17	M.Eng in Computer Engineering & Scie GPA: 7.35 / 10	nce Univ. of Patras, Patras, Greece	
		Diploma Thesis Subject: Safety-Aware Intelligent Trial-and-Error for Robot Damage Recovery. Grade: 10/10.		
OS Preference Linux ***** Windows **** MacOS ****		Supervisors: Ioannis Hatzilygeroudis, Jean-Baptiste Mouret. Related Publications: Safety-Aware Robot Damage Recovery Using Constrained Bayesian Optimization and Simulated Priors.		
	09/10 - 06/12	High School C GPA: 19.2 / 20	osteas-Geitonas School, Athens, Greece	

Languages
Greek ****
English ****
French ****

Teaching

02/19 - 06/19 Robotics practicals | Robot Operating System (ROS) basics

4h / week - 1st year Master of Robotics

EPFL

Publications

· Peer-Reviewed Journals

Aug 2019 Bidirectional interactions facilitate the integration of a robot into a shoal of

zebrafish Danio rerio, Papaspyros V, Bonnet F, Collignon B, Mondada F.

PLoS One

TBD A data-driven method for reconstructing and modelling social interactions in

moving animal groups, Escobedo R, Lecheval V, Papaspyros V, Bonnet F, Mondada F, Sire C, Theraulaz G.

Peer-Reviewed Workshops

Dec 2016 Safety-aware robot damage recovery using constrained bayesian optimiza-

tion and simulated priors, Papaspyros V, Chatzilygeroudis K, Vassiliades V, Mouret JB. Proceedings of the International Workshop on "Bayesian Optimization" at

NIPS 2016

Reviewer

BayesOpt International workshop on bayesian optimization of the Neural Information

Processing Systems (NIPS) Conference.

IISA 10th International Conference on Information, Intelligence, Systems and Ap-

plications.

Open-source project contributions

Co-author to robot dart C/C++

robot dart is a flexible and generic C++11 wrapper for DART and is suitable

for evolutionary computation.

C/C++ Contributor to limbo

limbo is a highly templated C++11 Bayesian optimization framework.

Honors & Awards

05/2018 **SwissZebra Conference**

3rd prize for best poster (100 CHF).

Programming skills

Advanced C & modern C++, Boost, Eigen, Python, LATEX, Robot Operating System

(ROS), Matlab/Octave, bash scripting, Policy-based design

Intermediate OpenMP, CUDA, OpenGL, Java, MySQL & Sqlite, HTML 5, CSS, PHP,

Javascript

Interests

Machine Learning & AI
 Programming

Robotics

- Basketball & Music