





Proximal schemes for the estimation of the reproduction number of Covid19:

From convex optimization to Monte Carlo sampling

### Signal and image processing seminar

#### **Barbara Pascal**

Joint work with P. Abry, N. Pustelnik, S. Roux, R. Gribonval, P. Flandrin; G. Fort, H. Artigas; Juliana Du

### Outline

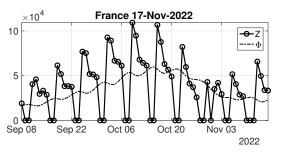
• Pandemic study: modeling at the service of monitoring

• Reproduction number estimation from minimization of penalized likelihood

• Bayesian framework for credibility interval estimation

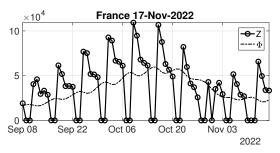
Conclusion & Perspectives

### Counts of daily new infections



data from National Health Agencies collected by Johns Hopkins University  $\Longrightarrow \mathsf{number} \; \mathsf{of} \; \mathsf{cases} \; \mathsf{not} \; \mathsf{informative} \; \mathsf{enough} ; \; \mathsf{need} \; \mathsf{to} \; \mathsf{capture} \; \mathsf{the} \; \mathsf{\textit{dynamics}}$ 

### Counts of daily new infections



data from National Health Agencies collected by Johns Hopkins University

—> number of cases not informative enough: need to capture the **dynamics** 

Design adapted counter measures and evaluate their effectiveness

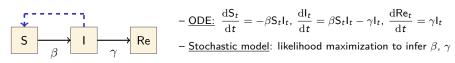
- → efficient monitoring tools
- $\rightarrow$  robust to low quality of the data
- ightarrow accompanied by reliable confidence level

epidemiological model,

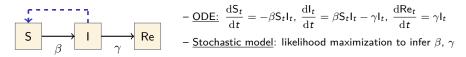
managing erroneous counts,

credibility intervals.

### Susceptible-Infected-Recovered (SIR), among compartmental models



## Susceptible-Infected-Recovered (SIR), among compartmental models



#### Limitations:

- refinement needed to get socially realistic model
- quadratic increase of the number of parameters
- Bayesian framework: heavy computational burden
- need consolidated and accurate datasets

X not adapted to real-time monitoring of Covid19 pandemic

#### Reproduction number in Cori model

"averaged number of secondary cases generated by a typical infectious individual" (Cori et al., 2013, Am. Journal of Epidemiology; Liu et al., 2018, PNAS)

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#### **Interpretation:** at day t

 $R_t > 1$  the virus propagates at exponential speed,

 $R_t < 1$  the epidemic shrinks with an exponential decay,

 $R_t = 1$  the epidemic is stable.

⇒ one single indicator accounting for the overall pandemic mechanism

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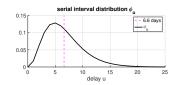
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 $\Longrightarrow$  one single indicator accounting for the overall pandemic mechanism

### **Principle:** $Z_t$ new infections at day t

$$\mathbb{E}\left[\mathsf{Z}_{t}\right] = \mathsf{R}_{t} \mathsf{\Phi}_{t}, \quad \mathsf{\Phi}_{t} = \sum_{u=1}^{\tau_{\Phi}} \phi_{u} \mathsf{Z}_{t-u}$$

with  $\Phi_t$  global "infectiousness" in the population



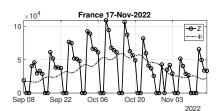
 $\{\phi_u\}_{u=1}^{\tau_{\Phi}}$  distribution of delay between onset of symptoms in primary and secondary cases

Gamma distribution truncated at 25 days, of mean 6.6 days and standard deviation 3.5 days

**Data:** daily counts  $\mathbf{Z} = (Z_1, \dots, Z_T)$ 

Model: Poisson distribution

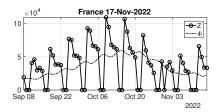
$$\mathbb{P}(\mathsf{Z}_t|\boldsymbol{\mathsf{Z}}_{t-\tau_{\boldsymbol{\Phi}}:t-1},\mathsf{R}_t) = \frac{\left(\mathsf{R}_t\boldsymbol{\Phi}_t\right)^{\mathsf{Z}_t}\mathrm{e}^{-\mathsf{R}_t\boldsymbol{\Phi}_t}}{\mathsf{Z}_t!}$$



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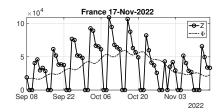
## Maximum Likelihood Estimate (MLE)

$$\begin{split} & \text{In}\left(\mathbb{P}(Z_t|\boldsymbol{Z}_{t-\tau_{\boldsymbol{\Phi}}:t-1},\boldsymbol{R}_t)\right) \\ &= & Z_t \ln(\boldsymbol{R}_t \boldsymbol{\Phi}_t) - \boldsymbol{R}_t \boldsymbol{\Phi}_t - \ln(\boldsymbol{Z}_t!) \\ &\underset{\boldsymbol{Z}_t \gg 1}{\simeq} Z_t \ln(\boldsymbol{R}_t \boldsymbol{\Phi}_t) - \boldsymbol{R}_t \boldsymbol{\Phi}_t - Z_t \ln(\boldsymbol{Z}_t) + Z_t \\ &= & -d_{KL}(\boldsymbol{Z}_t|\boldsymbol{R}_t \boldsymbol{\Phi}_t) \quad (\text{Kullback-Leibler}) \end{split}$$

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## Maximum Likelihood Estimate (MLE)

$$\ln \left( \mathbb{P}(\mathsf{Z}_t | \mathsf{Z}_{t-\tau_{\Phi}:t-1}, \mathsf{R}_t) \right)$$

$$= Z_t \ln(R_t \Phi_t) - R_t \Phi_t - \ln(Z_t!)$$

$$\underset{Z_t \gg 1}{\simeq} Z_t \ln(R_t \Phi_t) - R_t \Phi_t - Z_t \ln(Z_t) + Z_t$$

$$\underset{(\text{def.})}{=} - \mathsf{d}_{\mathsf{KL}} (\mathsf{Z}_t | \mathsf{R}_t \Phi_t) \ \ (\mathsf{Kullback-Leibler})$$

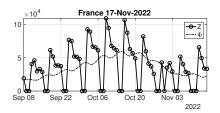
$$\Longrightarrow \widehat{\mathsf{R}}_t^{\mathsf{MLE}} = \mathsf{Z}_t/\Phi_t = \mathsf{Z}_t/\sum_{u=1}^{ au_{\Phi}} \phi_u \mathsf{Z}_{t-u}$$

ratio of moving averages

**Data:** daily counts  $\mathbf{Z} = (Z_1, \dots, Z_T)$ 

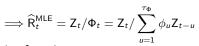
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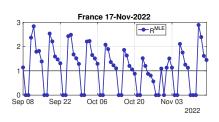


# Maximum Likelihood Estimate (MLE)

$$\begin{split} & \ln \left( \mathbb{P} \big( Z_t | \boldsymbol{Z}_{t-\tau_{\boldsymbol{\Phi}}:t-1}, \boldsymbol{R}_t \big) \big) \\ & = \ \, Z_t \ln \big( \boldsymbol{R}_t \boldsymbol{\Phi}_t \big) - \boldsymbol{R}_t \boldsymbol{\Phi}_t - \ln \big( \boldsymbol{Z}_t ! \big) \\ & \overset{\sim}{\underset{\boldsymbol{Z}_t \gg 1}{\sim}} \ \, Z_t \ln \big( \boldsymbol{R}_t \boldsymbol{\Phi}_t \big) - \boldsymbol{R}_t \boldsymbol{\Phi}_t - \boldsymbol{Z}_t \ln \big( \boldsymbol{Z}_t \big) + \boldsymbol{Z}_t \\ & \overset{=}{\underset{(\text{def.})}{\sim}} - d_{\text{KL}} \big( \boldsymbol{Z}_t | \boldsymbol{R}_t \boldsymbol{\Phi}_t \big) \ \, \text{(Kullback-Leibler)} \end{split}$$



ratio of moving averages



- huge variability along time/ no local trend
- not robust to pseudo-periodicity/ misreported counts

State-of-the-art: smooth regularization over a temporal window

$$\widehat{\mathsf{R}}_{\mathsf{t},\mathsf{s}}^{\mathsf{EpiEstim}}$$
, with  $\mathsf{s}=\mathsf{7}$  days (Cori et al., 2013, Am. Journal of Epidemiology)

EpiEstim: Estimate Time Varying Reproduction Numbers from Epidemic Curves

Tools to quantify transmissibility throughout an epidemic from the analysis of time series of incidence as described in Cori et al. (2013)



(re-implemented in Matlab following Cori et al., 2013, Am. Journal of Epidemiology)

 $\implies$  smoother than naive MLE but hampered by low quality data and dependent on s

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Solution 1: regularization through nonlinear filtering

$$\widehat{\mathbf{R}}^{\mathsf{PKL}} = \underset{\mathbf{R} \in \mathbb{R}_{+}^{T}}{\min} \ \sum_{t=1}^{T} \mathsf{d_{KL}}\left(\mathsf{Z}_{t} \left| \mathsf{R}_{t} \Phi_{t} \right.\right) + \lambda_{\mathsf{R}} \mathcal{P}(\mathbf{R}) \quad \text{(penalized Kullback-Leibler)}$$

with  $\mathcal{P}(\mathbf{R})$  favoring some temporal regularity

(Abry et al., 2020, PLOSOne)

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$$\widehat{\mathbf{R}}^{\mathsf{PKL}} = \underset{\mathbf{R} \in \mathbb{R}_{+}^{T}}{\operatorname{argmin}} \ \sum_{t=1}^{I} \mathsf{d_{KL}} \left( \mathsf{Z}_{t} \left| \mathsf{R}_{t} \boldsymbol{\Phi}_{t} \right. \right) + \lambda_{\mathsf{R}} \mathcal{P}(\mathbf{R}) \ \ \text{(penalized Kullback-Leibler)}$$

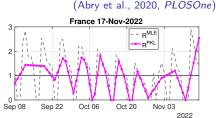
with  $\mathcal{P}(\textbf{R})$  favoring some temporal regularity

$$\mathcal{P}(\mathbf{R}) = \|\mathbf{D}_2\mathbf{R}\|_1$$

$$(\mathbf{D}_{2}\mathbf{R})_{t} = \mathbf{R}_{t+1} - 2\mathbf{R}_{t} + \mathbf{R}_{t-1}$$

2nd order derivative &  $\ell_1$ -norm

$$\Longrightarrow$$
 piecewise linearity

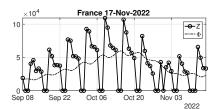


captures global trend, more regular than MLE, but pseudo-oscillations

New infection counts **Z** are corrupted by

- missing samples,
- non meaningful negative counts,
- retrospected cumulated counts,
- pseudo-seasonality effects.

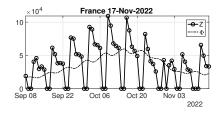
⇒ full parametric modeling out of reach



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Solution 1': first correct  $\mathbf{Z}$ , then apply penalized Kullback-Leibler on corrected  $\mathbf{Z}^{(C)}$ 

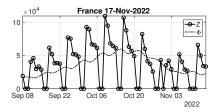
 $\Longrightarrow$  two-step procedure not optimal: accumulates correction & regularization biases

(Abry et al., 2020, Eng. Med. Biol. Conf.)

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Solution 2: one-step procedure performing jointly

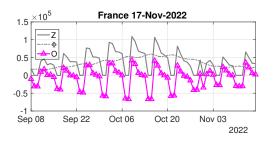
correction of corrupted  $Z_t$  & estimation of regularized  $R_t$ 

(Pascal et al., 2022, Trans. Sig. Process.)

**Extended Cori Model:** additional latent variable  $O_t$  accounting for misreport

$$Z_t \sim \text{Poiss}(R_t \Phi_t + O_t), \quad R_t \Phi_t + O_t \geq 0$$

nonzero values of  $O_t$  concentrated on specific days (Sundays, day-offs, ...)



### Interpretation:

$$\label{eq:poiss_equation} \text{Poiss}\left(\mathsf{R}_t \Phi_t + \mathsf{O}_t\right) \sim \left\{ \begin{array}{ll} \text{Poiss}\left(\mathsf{R}_t \Phi_t\right) + \text{Poiss}\left(\mathsf{O}_t\right) & \text{if } \mathsf{O}_t \geq 0, \\ \\ \text{Poiss}\left(\alpha_t \mathsf{R}_t \Phi_t\right), \ \alpha_t = 1 - \frac{-\mathsf{O}_t}{\mathsf{R}_t \Phi_t} \in [0,1] & \text{if } \mathsf{O}_t < 0. \end{array} \right.$$

**Data:** reported counts  $\mathbf{Z} = (\mathsf{Z}_1, \dots, \mathsf{Z}_T)$ 

$$\textbf{Model:} \text{ corrected Poisson } \quad \mathbb{P}\big(Z_t|\boldsymbol{Z}_{t-\tau_{\boldsymbol{\Phi}}:t-1},\boldsymbol{R}_t, \underset{t}{O}_t\big) = \frac{\big(\boldsymbol{R}_t\boldsymbol{\Phi}_t + \underset{t}{O}_t\big)^{Z_t}e^{-(\boldsymbol{R}_t\boldsymbol{\Phi}_t + \underset{t}{O}_t)}}{Z_t!}$$

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#### Generalized Penalized Kullback-Leibler

$$(\widehat{\boldsymbol{R}},\widehat{\boldsymbol{O}}) \in \operatorname*{Argmin}_{(\boldsymbol{R},\boldsymbol{O}) \in \mathbb{R}_{+}^{T} \times \mathbb{R}^{T}} \ \sum_{t=1}^{I} d_{\mathsf{KL}} \left( \boldsymbol{Z}_{t} \, | \, \boldsymbol{R}_{t} \boldsymbol{\Phi}_{t} + \boldsymbol{O}_{t} \, \right) + \lambda_{\mathsf{R}} \| \boldsymbol{D}_{2} \boldsymbol{R} \|_{1} + \iota_{\geq 0}(\boldsymbol{R}) + \lambda_{\mathsf{O}} \| \boldsymbol{O} \|_{1}$$

 $\Longrightarrow$  estimates piecewise linear, non-negative  $R_t$  and sparse  $O_t$ 

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 $\implies$  estimates piecewise linear, non-negative  $R_t$  and sparse  $O_t$ 

### properties of the objective function:

- sum of convex functions composed with linear operators ⇒ globally convex;
- feasible domain:  $(\forall t, R_t \ge 0)$  & (if  $Z_t > 0, R_t \Phi_t + O_t > 0$ , else  $R_t \Phi_t + O_t \ge 0$ );
- $p_t \mapsto d_{KL}(Z_t | p_t)$  is strictly-convex.

**Data:** reported counts  $\mathbf{Z} = (Z_1, \dots, Z_T)$ 

$$\textbf{Model:} \text{ corrected Poisson } \quad \mathbb{P}(\mathsf{Z}_t | \mathbf{Z}_{t-\tau_{\Phi}:t-1}, \mathsf{R}_t, \mathsf{O}_t) = \frac{\left(\mathsf{R}_t \Phi_t + \mathsf{O}_t\right)^{\mathsf{Z}_t} \mathrm{e}^{-\left(\mathsf{R}_t \Phi_t + \mathsf{O}_t\right)}}{\mathsf{Z}_t!}$$

#### Generalized Penalized Kullback-Leibler

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### **Theorem** (Pascal et al., 2022, *Trans. Sig. Process.*)

- + The minimization problem has at least one solution  $(\widehat{\mathbf{R}}, \widehat{\mathbf{O}})$ .
- + The estimated time-varying Poisson intensity  $\hat{p}_t = \hat{R}_t \Phi_t + \hat{O}_t$  is unique.

$$\underset{(\textbf{R},\textbf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \ \sum_{t=1}^T d_{KL} \left( Z_t \, \big| \, R_t \Phi_t + O_t \, \right) + \lambda_R \| \textbf{D}_2 \textbf{R} \|_1 + \iota_{\geq 0} (\textbf{R}) + \lambda_0 \| \textbf{O} \|_1$$

- each term of the functional is convex:
- $\ell_1$ -norm and indicative function  $\Longrightarrow$  nonsmooth;
- gradient of  $p_t \mapsto d_{KL}(Z_t | p_t)$  is not Lipschitzian;
- $\bullet$  linear operator  $\textbf{D}_2 \Longrightarrow$  no explicit form for  $\mathsf{prox}_{\|\textbf{D}_2\cdot\|_1}$

X gradient descent

X forward-backward

• need splitting

$$\underset{(\mathbf{R},\mathbf{O}) \in \mathbb{R}_{t}^{T} \times \mathbb{R}^{T}}{\text{minimize}} \sum_{t=1}^{T} d_{\mathsf{KL}} \left( \mathsf{Z}_{t} \, | \, \mathsf{R}_{t} \boldsymbol{\Phi}_{t} + \mathsf{O}_{t} \, \right) + \lambda_{\mathsf{R}} \| \mathbf{D}_{2} \mathbf{R} \|_{1} + \iota_{\geq 0}(\mathbf{R}) + \lambda_{\mathsf{O}} \| \mathbf{O} \|_{1}$$

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 ${\it X}$  forward-backward

need splitting

$$\iff \underset{(R,O) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \quad f(R,O|\mathbf{Z}) + h(\mathbf{A}(R,O)), \quad \mathbf{A} \text{ linear; } f,h \text{ proximable}$$

$$\mathbf{A}(\mathbf{R}, \mathbf{O}) = (\lambda_{\mathbf{R}} \mathbf{D}_{2} \mathbf{R}, \mathbf{R}, \lambda_{\mathbf{O}} \mathbf{O}); \quad h(\mathbf{Q}_{1}, \mathbf{Q}_{2}, \mathbf{Q}_{3}) = \|\mathbf{Q}_{1}\|_{1} + \iota_{\geq 0}(\mathbf{Q}_{2}) + \|\mathbf{Q}_{3}\|_{1}$$

$$\underset{(\textbf{R},\textbf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \ \sum_{t=1}^T d_{KL} \left( Z_t \, | \, R_t \Phi_t + O_t \, \right) + \lambda_R \| \textbf{D}_2 \textbf{R} \|_1 + \iota_{\geq 0} (\textbf{R}) + \lambda_0 \| \textbf{O} \|_1$$

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$$\iff \underset{(\mathsf{R}, \mathsf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\mathsf{minimize}} \quad f(\mathsf{R}, \mathsf{O}|\mathsf{Z}) + h(\mathsf{A}(\mathsf{R}, \mathsf{O})), \quad \mathsf{A} \text{ linear; } f, h \text{ proximable}$$

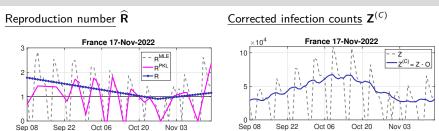
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### Primal-dual algorithm

(Chambolle et al., 2011, Int. Conf. Comput. Vis.)

X gradient descent

$$\begin{array}{c|c} \text{for } k=1,2\dots \text{do} \\ & \mathbf{Q}^{[k+1]} = \mathsf{prox}_{\sigma h^*}(\mathbf{Q}^{[k]} + \sigma \mathbf{A}(\overline{\mathbf{R}}^{[k]}, \overline{\mathbf{O}}^{[k]})) & \text{dual} \\ & (\mathbf{R}^{[k+1]}, \mathbf{O}^{[k+1]}) = \mathsf{prox}_{\tau f(\cdot | \mathbf{Z})}((\mathbf{R}^{[k+1]}, \mathbf{O}^{[k+1]}) - \tau \mathbf{A}^* \mathbf{Q}^{[k+1]}) & \text{primal} \\ & (\overline{\mathbf{R}}^{[k+1]}, \overline{\mathbf{O}}^{[k+1]}) = 2(\mathbf{R}^{[k+1]}, \mathbf{O}^{[k+1]}) - (\mathbf{R}^{[k]}, \mathbf{O}^{[k]}) & \text{auxiliary} \end{array}$$

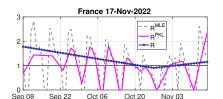


⇒ no more pseudo-seasonality, local trends well captured, smooth behavior

2022

2022



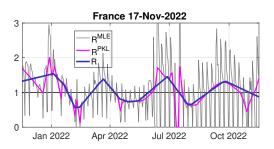


## Corrected infection counts $\mathbf{Z}^{(C)}$



⇒ no more pseudo-seasonality, local trends well captured, smooth behavior

2022



**fast numerical scheme**: 15 to 30 sec for 70 days to 1 year

New infection counts per county:  $\mathbf{Z} = \left\{ \mathbf{Z}_t^{(d)}, \ d \in [1, D], \ t \in [1, T] \right\}$ 

 $\Rightarrow$  multivariate time-varying reproduction number  $\mathsf{R}_t^{(d)}$ 

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 $\Rightarrow$  multivariate time-varying reproduction number  $\mathsf{R}_{t}^{(d)}$ 

#### Multivariate extended penalized Kullback-Leibler

$$\begin{split} \left(\widehat{\mathbf{R}}, \widehat{\mathbf{O}}\right) &= \underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_{+}^{D \times T} \times \mathbb{R}^{D \times T}}{\operatorname{argmin}} \sum_{d=1}^{D} \sum_{t=1}^{T} \mathsf{d}_{\mathsf{KL}} \left( \mathsf{Z}_{t}^{(d)} \left| \mathsf{R}_{t}^{(d)} \boldsymbol{\Phi}_{t}^{(d)} + \mathsf{O}_{t}^{(d)} \right. \right) \\ &+ \lambda_{\mathsf{R}} \| \mathbf{D}_{2} \mathbf{R} \|_{1} + \iota_{\geq 0}(\mathbf{R}) + \lambda_{\mathsf{space}} \| \mathbf{G} \mathbf{R} \|_{1} + \lambda_{\mathsf{O}} \| \mathbf{O} \|_{1} \\ &\Longrightarrow \| \mathbf{G} \mathbf{R} \|_{1} \text{ favors piecewise constancy in space} \end{split}$$

New infection counts per county:  $\mathbf{Z} = \left\{ \mathbf{Z}_t^{(d)}, \ d \in [1, D], \ t \in [1, T] \right\}$ 

 $\Rightarrow$  multivariate time-varying reproduction number  $R_t^{(d)}$ 

#### Multivariate extended penalized Kullback-Leibler

$$\begin{split} \left(\widehat{\mathbf{R}}, \widehat{\mathbf{O}}\right) &= \underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_{+}^{D \times T} \times \mathbb{R}^{D \times T}}{\operatorname{argmin}} \sum_{d=1}^{D} \sum_{t=1}^{T} \mathsf{d}_{\mathsf{KL}} \left( \mathsf{Z}_{t}^{(d)} \left| \mathsf{R}_{t}^{(d)} \boldsymbol{\Phi}_{t}^{(d)} + \mathsf{O}_{t}^{(d)} \right. \right) \\ &+ \lambda_{\mathsf{R}} \| \mathbf{D}_{2} \mathbf{R} \|_{1} + \iota_{\geq 0}(\mathbf{R}) + \lambda_{\operatorname{space}} \| \mathbf{G} \mathbf{R} \|_{1} + \lambda_{\mathsf{O}} \| \mathbf{O} \|_{1} \end{split}$$

 $\Longrightarrow \|\mathbf{GR}\|_1$  favors **piecewise constancy** in space

**Graph Total Variation** 

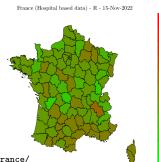
$$\|\mathsf{GR}\|_1 = \sum_{t=1}^T \sum_{d_1 \sim d_2} \left| \mathsf{R}_t^{(d_1)} - \mathsf{R}_t^{(d_2)} \right|$$

sum over neighboring counties

here:  $d_1 \sim d_2 \Leftrightarrow$  share terrestrial border

$$\widetilde{\mathbf{A}}(\mathbf{R},\mathbf{O}) = (\lambda_{R}\mathbf{D}_{2}\mathbf{R},\mathbf{R},\lambda_{\text{space}}\mathbf{G}\mathbf{R},\lambda_{O}\mathbf{O})$$

http://barthes.enssib.fr/coronavirus/cartes/RFrance/



0.2

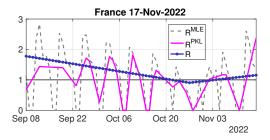
<u>Pointwise estimate</u> of parameter  $\theta = (R, 0)$  from observations **Z** 

<u>Pointwise estimate</u> of parameter  $\theta = (R, O)$  from observations **Z** 

**Q:** what is the value of R today? **A:** solve the minimization problem and output  $\widehat{R}_{\mathcal{T}}$ .

<u>Pointwise estimate</u> of parameter  $\theta = (R, O)$  from observations **Z** 

 $\textbf{Q}\!:$  what is the value of R today?  $\textbf{A}\!:$  solve the minimization problem and output  $\widehat{R}_{\mathcal{T}}.$ 



$$\widehat{\mathsf{R}}_{T}=1.2955$$

Pointwise estimate of parameter  $\theta = (R, 0)$  from observations **Z** 

**Bayesian reformulation:** interpret  $(\widehat{\mathbf{R}},\widehat{\mathbf{O}})$  as the MAP of  $\pi(\theta) \propto \exp(-f(\theta|\mathbf{Z}) - h(\mathbf{A}\theta))$ 

- $\exp(-f(\theta|\mathbf{Z})) \sim \text{likelihood of the observation}$
- ullet exp $(-h(\mathbf{A}oldsymbol{ heta}))\sim$  prior on the parameter of interest

<u>Pointwise estimate</u> of parameter  $\theta = (R, O)$  from observations **Z** 

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- $\exp(-f(\theta|\mathbf{Z})) \sim \text{likelihood of the observation}$
- $\exp(-h(\mathbf{A}\boldsymbol{\theta})) \sim \text{prior on the parameter of interest}$

 $\Longrightarrow$  instead of focusing on  $\widehat{R}_t$ , the **pointwise** MAP, probe  $\pi$  to get  $R_t \in [R_t, \overline{R}_t]$  with 95% probability, i.e., **credibility interval** estimates





$$\widehat{\mathsf{R}}_{\mathcal{T}} \in [1.2987, 1.3047]$$

#### Log-likelihood from Poisson model

$$\begin{aligned} & \textbf{g-likelihood from Poisson model} & \mathcal{D} = \{\boldsymbol{\theta} \,|\, \forall t, \;\; \mathsf{R}_t \boldsymbol{\Phi}_t + \mathsf{O}_t \geq 0, \;\; \mathsf{R}_t \geq 0\} \\ & f(\boldsymbol{\theta} \,|\, \boldsymbol{Z}) := \left\{ \begin{array}{l} -\sum_{t=1}^{\mathcal{T}} (\mathsf{Z}_t \,|\, \mathsf{n}(\mathsf{R}_t \boldsymbol{\Phi}_t + \mathsf{O}_t) - (\mathsf{R}_t \boldsymbol{\Phi}_t + \mathsf{O}_t) + \mathcal{C}(\mathsf{Z}_t)) & \text{if } \boldsymbol{\theta} \in \mathcal{D}, \\ \infty & \text{otherwise,} \end{array} \right. \end{aligned}$$

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Prior distribution of 
$$\theta = (R, O) = (R_1, \dots, R_T, O_1, \dots, O_T) \in (\mathbb{R}_+)^T \times \mathbb{R}^T$$

• reproduction number:  $R_t - 2R_{t-1} + R_{t-2} \sim Laplace(\lambda_R)$ 

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- outliers  $O_t \sim Laplace(\lambda_O)$

#### Log-likelihood from Poisson model

$$\begin{aligned} & \text{$f$-likelihood from Poisson model} & \mathcal{D} = \{\theta \,|\, \forall t, \;\; \mathsf{R}_t \Phi_t + \mathsf{O}_t \geq 0, \;\; \mathsf{R}_t \geq 0\} \\ & f(\theta) & := \left\{ \begin{array}{ll} -\sum_{t=1}^T (\mathsf{Z}_t \, \mathsf{In}(\mathsf{R}_t \Phi_t + \mathsf{O}_t) - (\mathsf{R}_t \Phi_t + \mathsf{O}_t)) & \text{if } \theta \in \mathcal{D}, \\ \infty & \text{otherwise,} \end{array} \right. \end{aligned}$$

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- outliers  $O_t \sim Laplace(\lambda_O)$

$$\Rightarrow g(\theta) = \lambda_{\mathsf{R}} \|\mathbf{D}_{2}\mathbf{R}\|_{1} + \lambda_{\mathsf{O}} \|\mathbf{O}\|_{1}, \quad \mathbf{D}_{2} = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 & -2 & 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & -2 & 1 & 0 & \dots & 0 \\ \dots & & & & & \dots \\ 0 & \dots & & & & 1 & -2 & 1 \end{bmatrix}$$

### **Log-likelihood from Poisson model** $\mathcal{D} = \{\theta \mid \forall t, \ \mathsf{R}_t \Phi_t + \mathsf{O}_t \geq 0, \ \mathsf{R}_t \geq 0\}$

$$f(\boldsymbol{\theta}) \quad := \left\{ \begin{array}{l} -\sum_{t=1}^{T} (\mathsf{Z}_t \ln(\mathsf{R}_t \boldsymbol{\Phi}_t + \mathsf{O}_t) - (\mathsf{R}_t \boldsymbol{\Phi}_t + \mathsf{O}_t)) & \text{if } \boldsymbol{\theta} \in \mathcal{D}, \\ \infty & \text{otherwise,} \end{array} \right.$$

### Prior distribution of $\theta = (R, O) = (R_1, \dots, R_T, O_1, \dots, O_T) \in (\mathbb{R}_+)^T \times \mathbb{R}^T$

- reproduction number:  $R_t 2R_{t-1} + R_{t-2} \sim Laplace(\lambda_R)$
- outliers  $O_t \sim \mathsf{Laplace}(\lambda_\mathsf{O})$

$$\Rightarrow g(\theta) = \lambda_{R} \|\mathbf{D}_{2}\mathbf{R}\|_{1} + \lambda_{O} \|\mathbf{O}\|_{1}, \quad \mathbf{D}_{2} = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 & -2 & 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & -2 & 1 & 0 & \dots & 0 \\ \dots & & & & \dots & \dots \\ 0 & \dots & & & 1 & -2 & 1 \end{bmatrix}$$
Laplacian

## Posterior distribution of unknown parameters $\theta = (\mathsf{R}, \mathsf{O})$

$$\pi(oldsymbol{ heta}) \propto \exp\left(-f(oldsymbol{ heta}) - g(oldsymbol{ heta})
ight) \mathbb{1}_{\mathcal{D}}(oldsymbol{ heta})$$

- f, g convex
- f smooth, g nonsmooth

**Purpose:** sampling the random variable  $\theta = (\mathbf{R}, \mathbf{O}) \in \mathbb{R}^{2T}$  according to the posterior  $\pi(\theta) \propto \exp\left(-f(\theta) - g(\theta)\right) \mathbb{1}_{\mathcal{D}}(\theta)$ 

 $<sup>^{\</sup>dagger}$   $\pi$  is defined up to a normalizing constant

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**Principle:** 1) generate a random sequence  $\{\theta^n, n \in \mathbb{N}\}$  such that

- $\theta^{n+1}$  only depends on  $\theta^n$ ,
- at convergence, i.e., as  $n \to \infty$ ,  $\theta^n \sim \pi$ ,
- 2) compute Bayesian estimators, e.g., credibility intervals, on samples  $\{\theta^n, n \geq N\}$

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#### Simple and very general approach: Hastings-Metropolis random walk

(i) propose a random move according to

$$\boldsymbol{\theta}^{n+\frac{1}{2}} = \boldsymbol{\theta}^n + \sqrt{2\gamma}\Gamma\xi^{n+1}, \quad \xi^{n+1} \sim \mathcal{N}_{2T}(0, \mathbf{I})$$

with  $\gamma$  positive step size,  $\Gamma \in \mathbb{R}^{2T \times 2T}$ 

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with  $\gamma$  positive step size,  $\Gamma \in \mathbb{R}^{2T \times 2T}$ 

(ii) accept: 
$$m{ heta}^{n+1} = m{ heta}^{n+rac{1}{2}}$$
, with probability  $1 \wedge rac{\pi(m{ heta}^{n+rac{1}{2}})}{\pi(m{ heta}^n)}$ , or reject:  $m{ heta}^{n+1} = m{ heta}^n$ 

 $<sup>^{\</sup>dagger}$   $\pi$  is defined up to a normalizing constant

# Metropolis Adjusted Langevin Algorithm (MALA)

Langevin dynamics: 
$$\theta^{n+\frac{1}{2}}=\mu(\theta^n)+\sqrt{2\gamma}\xi^{n+1}$$
, (Kent, 1978, *Adv Appl Probab*) 
$$\mu(\theta) \text{ adapted to } \pi(\theta)=\exp(-f(\theta)-g(\theta))\mathbb{1}_{\mathcal{D}}(\theta)$$

# Metropolis Adjusted Langevin Algorithm (MALA)

Case 1: 
$$g = 0$$
 and  $-\ln \pi = f$  is smooth (Roberts & Tweedie, 1996, *Bernoulli*) 
$$\mu(\theta) = \theta - \gamma \Gamma \Gamma^{\top} \nabla f(\theta) = \theta + \gamma \Gamma \Gamma^{\top} \nabla \ln \pi(\theta)$$
$$\implies \text{move towards areas of higher probability}$$

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Langevin dynamics:  $\theta^{n+\frac{1}{2}}=\mu(\theta^n)+\sqrt{2\gamma}\xi^{n+1}$ , (Kent, 1978, *Adv Appl Probab*)  $\mu(\theta) \text{ adapted to } \pi(\theta)=\exp(-f(\theta)-g(\theta))\mathbb{1}_{\mathcal{D}}(\theta)$ 

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  $\Longrightarrow$  move towards areas of higher probability

$$\underline{\mathsf{Case}\ 2:} - \mathsf{In}\ \pi = f + g\ \mathsf{is}\ \mathsf{nonsmooth}$$

$$\mu(\boldsymbol{\theta}) = \mathsf{prox}_{\gamma\sigma}^{\mathsf{\Gamma}\mathsf{\Gamma}^{\mathsf{T}}}(\boldsymbol{\theta} - \gamma\mathsf{\Gamma}\mathsf{\Gamma}^{\mathsf{T}}\nabla f(\boldsymbol{\theta}))$$

combining Langevin and proximal<sup>†</sup> approaches

$$^{\dagger}\operatorname{prox}_{\gamma g}^{\Gamma\Gamma^{\top}}(y) = \operatorname{argmin}_{x \in \mathbb{R}^d} \left( \frac{1}{2} \|x - y\|_{\Gamma\Gamma^{\top}}^2 + \gamma g(x) \right) : \text{ preconditioned proximity operator of } g$$

Posterior density of  $\theta = (\mathbf{R}, \mathbf{O})$ :  $\pi(\theta) \propto \exp(-f(\theta) - g(\theta)) \mathbb{1}_{\mathcal{D}}(\theta)$ 

• smooth negative log-likelihood

if 
$$\theta \in \mathcal{D}$$
,  $f(\theta) = -\sum_{t=1}^{T} (Z_t \ln p_t(\theta) - p_t(\theta))$ ,  $p_t(\theta) = R_t(\Phi Z)_t + O_t$ 

• nonsmooth convex lower-semicontinuous negative a priori log-distribution

$$g(\theta) = \lambda_{\mathsf{R}} \| \mathbf{D}_2 \mathbf{R} \|_1 + \lambda_{\mathsf{O}} \| \mathbf{O} \|_1 = h(\mathbf{A}\theta)$$

$$\mathbf{A}: \boldsymbol{\theta} \mapsto (\mathbf{D}_2 \mathbf{R}, \mathbf{O})$$
 linear operator,  $h(\cdot_1, \cdot_2) = \lambda_{\mathbf{R}} \|\cdot_1\|_1 + \lambda_{\mathbf{O}} \|\cdot_2\|_1$ 

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Case 3: 
$$-\ln \pi = f + h(\mathbf{A} \cdot)$$
 (Fort et al., 2022, *preprint*)

closed-form expression of  $\mathsf{prox}_{\gamma h}$  but not of  $\mathsf{prox}_{\gamma h(\mathbf{A}\cdot)}$ 

- 1) extend **A** into **invertible**  $\overline{\mathbf{A}}$ , and h in  $\overline{h}$  such that  $\overline{h}(\overline{\mathbf{A}}\theta) = h(\mathbf{A}\theta)$
- 2) reason on the **dual** variable  $\tilde{\theta} = \overline{\mathbf{A}}\theta$

Langevin: drift toward higher probability regions

$$\underset{\boldsymbol{\theta} \in \mathbb{R}^{2T}}{\operatorname{argmin}} \ f(\boldsymbol{\theta}) = \underset{\boldsymbol{\theta} \in \mathbb{R}^{2T}}{\operatorname{argmin}} \ f(\boldsymbol{\theta}) + \bar{h}(\overline{\mathbf{A}}\boldsymbol{\theta}) = \mathbf{A}^{-1}\underset{\tilde{\boldsymbol{\theta}} \in \mathbb{R}^{2T}}{\operatorname{argmin}} \ f(\overline{\mathbf{A}}^{-1}\tilde{\boldsymbol{\theta}}) + \bar{h}(\tilde{\boldsymbol{\theta}})$$

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Two strategies to extend 
$$\mathbf{A} = \begin{pmatrix} \mathbf{D}_2 & \mathbf{0} \\ \mathbf{0} & \mathbf{I} \end{pmatrix} \in \mathbb{R}^{(2T-1)\times 2T}$$
 into  $\overline{\mathbf{A}} = \begin{pmatrix} \overline{\mathbf{D}} & \mathbf{0} \\ \mathbf{0} & \mathbf{I} \end{pmatrix} \in \mathbb{R}^{2T\times 2T}$ :

Langevin: drift toward higher probability regions 
$$\begin{aligned} & \underset{\theta \in \mathbb{R}^{2T}}{\operatorname{argmax}} \ln \pi(\theta) = \underset{\theta \in \mathbb{R}^{2T}}{\operatorname{argmin}} \ f(\theta) + \bar{h}(\overline{\mathbf{A}}\theta) = \mathbf{A}^{-1} \underset{\tilde{\theta} \in \mathbb{R}^{2T}}{\operatorname{argmin}} \ f(\overline{\mathbf{A}}^{-1}\tilde{\theta}) + \bar{h}(\tilde{\theta}) \\ \\ & \Longrightarrow \quad \mu(\theta) = \underbrace{\overline{\mathbf{A}}^{-1}}_{\text{back to }\theta} \ \underbrace{\operatorname{prox}_{\gamma\bar{h}}\left(\overline{\mathbf{A}}\theta - \gamma\overline{\mathbf{A}}^{-\top}\nabla f(\theta)\right)}_{\text{proximal-gradient on }\tilde{\theta}} \end{aligned}$$

Two strategies to extend 
$$\mathbf{A} = \begin{pmatrix} \mathbf{D}_2 & 0 \\ 0 & I \end{pmatrix} \in \mathbb{R}^{(2T-1)\times 2T}$$
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Invert

$$\overline{\mathbf{D}}_2 := \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ -2/\sqrt{5} & 1/\sqrt{5} & 0 & \cdots & 0 \\ & \mathbf{D}_2 & & & \end{bmatrix}$$

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 into  $\overline{\mathbf{A}} = \begin{pmatrix} \overline{\mathbf{D}} & \mathbf{0} \\ \mathbf{0} & \mathbf{I} \end{pmatrix} \in \mathbb{R}^{2T\times 2T}$ : Invert Ortho 
$$\overline{\mathbf{D}}_2 := \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ -2/\sqrt{5} & 1/\sqrt{5} & 0 & \cdots & 0 \\ \mathbf{D}_2 & & \mathbf{D}_2 & & \mathbf{D}_0 := \begin{bmatrix} \mathbf{v}_1^\top \\ \mathbf{v}_2^\top \\ \mathbf{D}_2 \end{bmatrix} & \mathbf{v}_1, \mathbf{v}_2 \in \mathbb{R}^{2T} \\ \mathbf{v}_1 \perp \mathbf{v}_2, \mathbf{v}_1, \mathbf{v}_2 \in (\mathbf{D}_2^\top)^{\perp} \end{bmatrix}$$

Langevin: drift toward higher probability regions 
$$\underset{\theta \in \mathbb{R}^{2T}}{\operatorname{argmax}} \ln \pi(\theta) = \underset{\theta \in \mathbb{R}^{2T}}{\operatorname{argmin}} f(\theta) + \bar{h}(\overline{\mathbf{A}}\theta) = \mathbf{A}^{-1} \underset{\tilde{\theta} \in \mathbb{R}^{2T}}{\operatorname{argmin}} f(\overline{\mathbf{A}}^{-1}\tilde{\boldsymbol{\theta}}) + \bar{h}(\tilde{\boldsymbol{\theta}})$$
 
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Invert

$$\overline{\mathbf{D}}_2 := \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ -2/\sqrt{5} & 1/\sqrt{5} & 0 & \cdots & 0 \\ & \mathbf{D}_2 & & & \end{bmatrix} \qquad \overline{\mathbf{D}}_o := \begin{bmatrix} \mathbf{v}_1^\top \\ \mathbf{v}_2^\top \\ \mathbf{D}_2 \end{bmatrix} \quad \mathbf{v}_1, \mathbf{v}_2 \in \mathbb{R}^{2T} \\ \mathbf{v}_1 \perp \mathbf{v}_2, \mathbf{v}_1, \mathbf{v}_2 \in (\mathbf{D}_2^\top)^\perp$$

Proposed PGdual **drift terms** on 
$$\theta = (R, O)$$
:

reproduction numbers 
$$\mu_{\mathsf{R}}(\boldsymbol{\theta}) = \overline{\mathbf{D}}^{-1} \operatorname{prox}_{\gamma_{\mathsf{R}} \lambda_{\mathsf{R}} \parallel (\cdot)_{3:T} \parallel_1} \left( \overline{\mathbf{D}} \, \mathbf{R} - \gamma_{\mathsf{R}} \overline{\mathbf{D}}^{-\top} \, \nabla_{\mathsf{R}} f(\boldsymbol{\theta}) \right)$$
 outliers  $\mu_{\mathsf{O}}(\boldsymbol{\theta}) = \operatorname{prox}_{\gamma_{\mathsf{O}} \lambda_{\mathsf{O}} \parallel \cdot \parallel_1} \left( \mathbf{O} - \gamma_{\mathsf{O}} \nabla_{\mathsf{O}} f(\boldsymbol{\theta}) \right)$ 

```
Data: \overline{\mathbf{D}} = \overline{\mathbf{D}}_2 (Invert) or \overline{\mathbf{D}} = \overline{\mathbf{D}}_o (Ortho)
                      \gamma_{\mathsf{R}}, \gamma_{\mathsf{O}} > 0, N_{\max} \in \mathbb{N}_{\star}, \boldsymbol{\theta}^{\mathsf{O}} = (\mathsf{R}^{\mathsf{O}}, \mathsf{O}^{\mathsf{O}}) \in \mathcal{D}
Result: A \mathcal{D}-valued sequence \{\theta^n = (\mathbf{R}^n, \mathbf{O}^n), n \in \mathbb{O}, \dots, N_{\max}\}
for n = 0, ..., N_{max} - 1 do
            Sample \xi_{R}^{n+1} \sim \mathcal{N}_{T}(0, I) and \xi_{Q}^{n+1} \sim \mathcal{N}_{T}(0, I);
            Set \mathbf{R}^{n+\frac{1}{2}} = \mu_{\mathsf{R}}(\boldsymbol{\theta}^n) + \sqrt{2\gamma_{\mathsf{R}}}\overline{\mathbf{D}}^{-1}\overline{\mathbf{D}}^{-\top}\boldsymbol{\xi}_{\mathsf{P}}^{n+1}:
                         \mathbf{O}^{n+\frac{1}{2}} = \mu_{\mathcal{O}}(\boldsymbol{\theta}^n) + \sqrt{2\gamma_{\mathcal{O}}} \, \mathcal{E}_{\mathcal{O}}^{n+1}:
                         \theta^{n+\frac{1}{2}} = (\mathbf{R}^{n+\frac{1}{2}}, \mathbf{O}^{n+\frac{1}{2}}):
            Set \theta^{n+1} = \theta^{n+\frac{1}{2}} with probability
                                         1 \wedge \frac{\pi(\boldsymbol{\theta}^{n+\frac{1}{2}})}{\pi(\boldsymbol{\theta}^{n})} \frac{q_{\mathsf{R}}(\boldsymbol{\theta}^{n+\frac{1}{2}}, \boldsymbol{\theta}_{\mathsf{R}}^{n})}{q_{\mathsf{D}}(\boldsymbol{\theta}^{n}, \boldsymbol{\theta}_{\mathsf{D}}^{n+\frac{1}{2}})} \frac{q_{\mathsf{O}}(\boldsymbol{\theta}^{n+\frac{1}{2}}, \boldsymbol{\theta}_{\mathsf{O}}^{n})}{q_{\mathsf{O}}(\boldsymbol{\theta}^{n}, \boldsymbol{\theta}_{\mathsf{D}}^{n+\frac{1}{2}})},
                                          q_{R/O}: Gaussian kernel stemming from nonsymmetric proposal
                 and \theta^{n+1} = \theta^n otherwise.
```

Algorithm 1: Proximal-Gradient dual: PGdual Invert and PGdual Ortho

## Comparison of MCMC sampling schemes

**Gaussian proposal:** 
$$\theta^{n+\frac{1}{2}} = \mu(\theta^n) + \sqrt{2\gamma} \Gamma \xi^{n+1}$$

• random walks:  $\mu(\boldsymbol{\theta}) = \boldsymbol{\theta}$ 

RW: 
$$\Gamma = I$$
; RW Invert:  $\Gamma = \overline{\mathbf{D}}_2^{-1}\overline{\mathbf{D}}_2^{-\top}$ ; RW Ortho:  $\Gamma = \overline{\mathbf{D}}_o^{-1}\overline{\mathbf{D}}_o^{-\top}$ 

• Proximal-Gradient dual:  $\mu_{R}(\theta)$ ,  $\mu_{O}(\theta)$ ,  $\Gamma = \overline{\mathbf{D}}^{-1}\overline{\mathbf{D}}^{-\top}$ 

PGdual Invert: 
$$\overline{\mathbf{D}} = \overline{\mathbf{D}}_2$$
; PGdual Ortho:  $\overline{\mathbf{D}} = \overline{\mathbf{D}}_o$ 

**Practical settings:**  $N_{\text{max}} = 10^7$  iterations, 15 independent runs

# Comparison of MCMC sampling schemes

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$$\theta^{n+\frac{1}{2}} = \mu(\theta^n) + \sqrt{2\gamma}\Gamma\xi^{n+1}$$

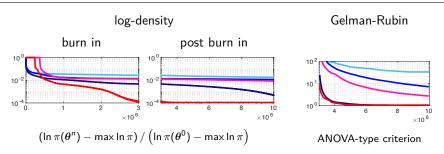
• random walks:  $\mu(\theta) = \theta$ 

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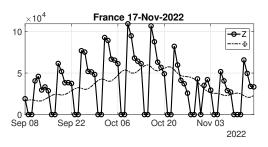
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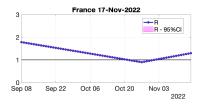
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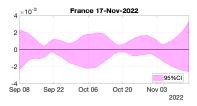
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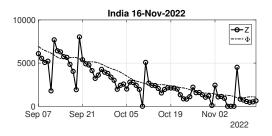
#### Sanitary situation in France

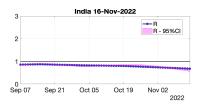


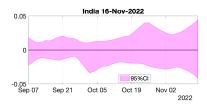




#### Worldwide Covid19 monitoring

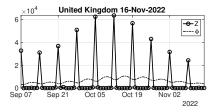






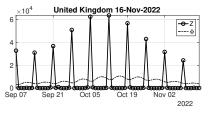
Why not United Kingdom?

#### Why not United Kingdom?

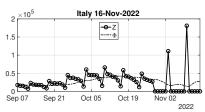


rate of erroneous counts: 6/7!

#### Why not United Kingdom?



And Italy?



rate of erroneous counts: 6/7!

seems to adopt the same reporting rate  $\dots$ 

 $\Longrightarrow$  call for new tools, robust to very scarce data

### Conclusion

 $\checkmark$  Extended Cori model handling erroneous reported counts via a latent variable

$$\mathsf{Z}_t | \mathbf{Z}_{t-\tau_{\boldsymbol{\Phi}}:t-1}, \mathsf{R}_t, \textcolor{red}{\mathsf{O}_t} \sim \mathsf{Poiss}(\mathsf{R}_t \Phi_t + \textcolor{red}{\mathsf{O}_t})$$

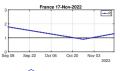
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 $\checkmark$  Estimation of piecewise linear  $R_t$  and corrected counts via convex optimization

$$\underset{(\textbf{R},\textbf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \ \sum_{t=1}^T d_{KL} \left( Z_t \, \big| \, \mathsf{R}_t \boldsymbol{\Phi}_t + O_t \, \right) + \lambda_R \| \boldsymbol{D}_2 \boldsymbol{R} \|_1 + \iota_{\geq 0}(\boldsymbol{R}) + \lambda_O \| \boldsymbol{O} \|_1$$



$$\widehat{R}_T = 1.1959$$

(Pascal et al., 2022, Trans. Sig. Process.;

#### Conclusion

✓ Extended Cori model handling erroneous reported counts via a latent variable

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✓ Bayesian credibility interval estimates via proximal Langevin MCMC samplers



(Pascal et al., 2022, Trans. Sig. Process.; Fort et al., 2022, arXiv:2203.09142)

### Perspectives

 $\longrightarrow$  Avoid mixing errors  $O_t$  with the pandemic mechanism  $R_t\Phi_t:$  anomaly models

$$Z_t | \boldsymbol{Z}_{t-\tau_{\boldsymbol{\Phi}}:t-1}, R_t, O_t \sim Poiss \big( (1-e_t) R_t \boldsymbol{\Phi}_t + e_t O_t \big), \quad e_t \in \{0,1\}$$

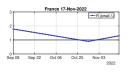
### Perspectives

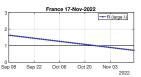
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$$Z_t | \boldsymbol{Z}_{t-\tau_{\boldsymbol{\Phi}}:t-1}, R_t, O_t \sim \mathsf{Poiss}((1-e_t)R_t \boldsymbol{\Phi}_t + e_t O_t), \quad e_t \in \{0,1\}$$

 $\longrightarrow$  Selection of regularization parameters  $\lambda_{\rm R}, \, \lambda_{\rm O}$ 

$$\underset{(\textbf{R},\textbf{O}) \in \mathbb{R}_{+}^{T} \times \mathbb{R}^{T}}{\text{minimize}} \ \sum_{t=1}^{T} d_{KL} \left( Z_{t} \, | \, R_{t} \boldsymbol{\Phi}_{t} + \boldsymbol{O}_{t} \, \right) + \lambda_{R} \| \boldsymbol{D}_{2} \boldsymbol{R} \|_{1} + \iota_{\geq 0} (\boldsymbol{R}) + \lambda_{O} \| \boldsymbol{O} \|_{1}$$





Juliana Du PhD thesis

### $\longrightarrow$ Synthetic data

