



Proximal schemes for the estimation of the reproduction number of Covid19:
From convex optimization to Monte Carlo sampling

Séminaire Données et Aléatoire Théorie & Applications

Laboratoire Jean Kuntzmann

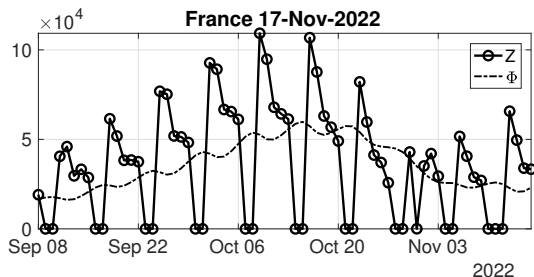
April 6th 2023

Barbara Pascal

Joint work with P. Abry, N. Pustelnik, S. Roux, R. Gribonval, P. Flandrin;
G. Fort, H. Artigas; Juliana Du

- Pandemic study: modeling at the service of monitoring
- Reproduction number estimation from minimization of penalized likelihood
- Bayesian framework for credibility interval estimation
- Conclusion & Perspectives

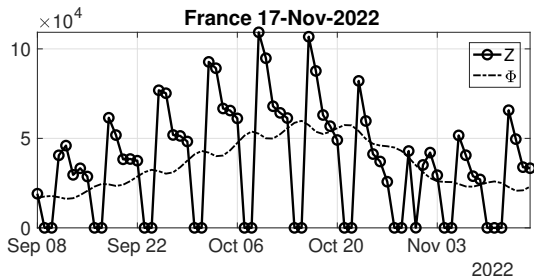
Counts of daily new infections



data from National Health Agencies collected by Johns Hopkins University

\Rightarrow number of cases not informative enough: need to capture the **dynamics**

Counts of daily new infections



data from National Health Agencies collected by Johns Hopkins University

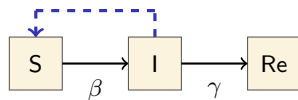
⇒ number of cases not informative enough: need to capture the **dynamics**

Design adapted counter measures and evaluate their effectiveness

- efficient monitoring tools
- robust to low quality of the data
- accompanied by reliable confidence level

*epidemiological model,
managing erroneous counts,
credibility intervals.*

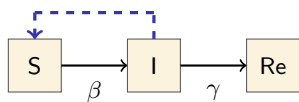
Susceptible-Infected-Recovered (SIR), among *compartmental models*



– ODE: $\frac{dS_t}{dt} = -\beta S_t I_t$, $\frac{dI_t}{dt} = \beta S_t I_t - \gamma I_t$, $\frac{dRe_t}{dt} = \gamma I_t$

– Stochastic model: likelihood maximization to infer β, γ

Susceptible-Infected-Recovered (SIR), among *compartmental models*



– ODE: $\frac{dS_t}{dt} = -\beta S_t I_t$, $\frac{dI_t}{dt} = \beta S_t I_t - \gamma I_t$, $\frac{dRe_t}{dt} = \gamma I_t$

– Stochastic model: likelihood maximization to infer β, γ

Limitations:

- refinement needed to get socially realistic model
- quadratic increase of the number of parameters
- Bayesian framework: heavy computational burden
- need consolidated and accurate datasets

✗ not adapted to real-time monitoring of Covid19 pandemic

Reproduction number in Cori model

“averaged number of secondary cases generated by a typical infectious individual”

(Cori et al., 2013, *Am. Journal of Epidemiology*; Liu et al., 2018, *PNAS*)

Reproduction number in Cori model

"averaged number of secondary cases generated by a typical infectious individual"

(Cori et al., 2013, *Am. Journal of Epidemiology*; Liu et al., 2018, *PNAS*)

Interpretation: at day t

$R_t > 1$ the virus propagates at exponential speed,

$R_t < 1$ the epidemic shrinks with an exponential decay,

$R_t = 1$ the epidemic is stable.

⇒ one single indicator accounting for the overall pandemic mechanism

Pandemic study: modeling at the service of monitoring

Reproduction number in Cori model

“averaged number of secondary cases generated by a typical infectious individual”

(Cori et al., 2013, *Am. Journal of Epidemiology*; Liu et al., 2018, *PNAS*)

Interpretation: at day t

$R_t > 1$ the virus propagates at exponential speed,

$R_t < 1$ the epidemic shrinks with an exponential decay,

$R_t = 1$ the epidemic is stable.

⇒ one single indicator accounting for the overall pandemic mechanism

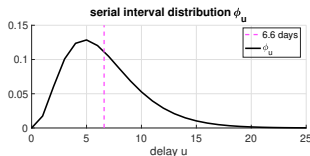
Principle: Z_t new infections at day t

$$\mathbb{E}[Z_t] = R_t \Phi_t, \quad \Phi_t = \sum_{u=1}^{\tau_\Phi} \phi_u Z_{t-u}$$

with Φ_t global “infectiousness” in the population

$\{\phi_u\}_{u=1}^{\tau_\Phi}$ distribution of delay between onset of symptoms in primary and secondary cases

Gamma distribution truncated at 25 days, of mean 6.6 days and standard deviation 3.5 days

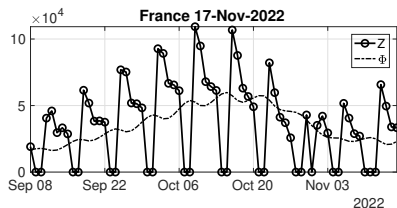


Pandemic study: modeling at the service of monitoring

Data: daily counts $\mathbf{Z} = (Z_1, \dots, Z_T)$

Model: Poisson distribution

$$\mathbb{P}(Z_t | \mathbf{Z}_{t-\tau_\Phi:t-1}, R_t) = \frac{(R_t \phi_t)^{Z_t} e^{-R_t \phi_t}}{Z_t!}$$

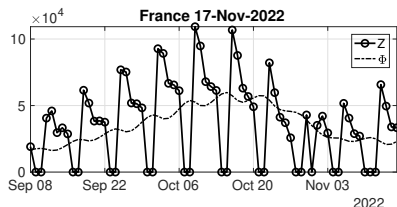


Pandemic study: modeling at the service of monitoring

Data: daily counts $\mathbf{Z} = (Z_1, \dots, Z_T)$

Model: Poisson distribution

$$\mathbb{P}(Z_t | \mathbf{Z}_{t-\tau_\Phi:t-1}, R_t) = \frac{(R_t \Phi_t)^{Z_t} e^{-R_t \Phi_t}}{Z_t!}$$



Maximum Likelihood Estimate (MLE)

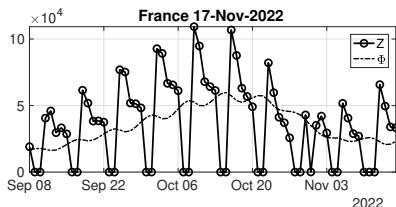
$$\begin{aligned} \ln(\mathbb{P}(Z_t | \mathbf{Z}_{t-\tau_\Phi:t-1}, R_t)) &= Z_t \ln(R_t \Phi_t) - R_t \Phi_t - \ln(Z_t!) \\ &\underset{Z_t \gg 1}{\simeq} Z_t \ln(R_t \Phi_t) - R_t \Phi_t - Z_t \ln(Z_t) + Z_t \\ &\stackrel{(\text{def.})}{=} -d_{\text{KL}}(Z_t | R_t \Phi_t) \quad (\text{Kullback-Leibler}) \end{aligned}$$

Pandemic study: modeling at the service of monitoring

Data: daily counts $\mathbf{Z} = (Z_1, \dots, Z_T)$

Model: Poisson distribution

$$\mathbb{P}(Z_t | \mathbf{Z}_{t-\tau_\Phi:t-1}, R_t) = \frac{(R_t \Phi_t)^{Z_t} e^{-R_t \Phi_t}}{Z_t!}$$



Maximum Likelihood Estimate (MLE)

$$\begin{aligned} \ln(\mathbb{P}(Z_t | \mathbf{Z}_{t-\tau_\Phi:t-1}, R_t)) &= Z_t \ln(R_t \Phi_t) - R_t \Phi_t - \ln(Z_t!) \\ &\underset{Z_t \gg 1}{\simeq} Z_t \ln(R_t \Phi_t) - R_t \Phi_t - Z_t \ln(Z_t) + Z_t \\ &\underset{(\text{def.})}{=} -d_{\text{KL}}(Z_t | R_t \Phi_t) \quad (\text{Kullback-Leibler}) \end{aligned}$$

$$\Rightarrow \hat{R}_t^{\text{MLE}} = Z_t / \Phi_t = Z_t / \sum_{u=1}^{\tau_\Phi} \phi_u Z_{t-u}$$

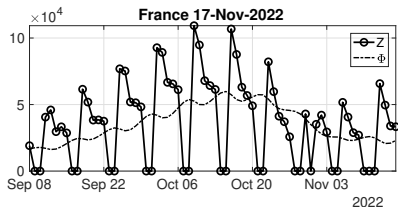
ratio of moving averages

Pandemic study: modeling at the service of monitoring

Data: daily counts $\mathbf{Z} = (Z_1, \dots, Z_T)$

Model: Poisson distribution

$$\mathbb{P}(Z_t | \mathbf{Z}_{t-\tau_\Phi:t-1}, R_t) = \frac{(R_t \phi_t)^{Z_t} e^{-R_t \phi_t}}{Z_t!}$$

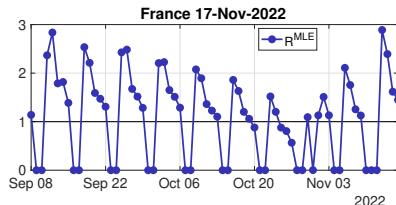


Maximum Likelihood Estimate (MLE)

$$\begin{aligned} \ln(\mathbb{P}(Z_t | \mathbf{Z}_{t-\tau_\Phi:t-1}, R_t)) &= Z_t \ln(R_t \phi_t) - R_t \phi_t - \ln(Z_t!) \\ &\underset{Z_t \gg 1}{\simeq} Z_t \ln(R_t \phi_t) - R_t \phi_t - Z_t \ln(Z_t) + Z_t \\ &\underset{(\text{def.})}{=} -d_{\text{KL}}(Z_t | R_t \phi_t) \quad (\text{Kullback-Leibler}) \end{aligned}$$

$$\Rightarrow \hat{R}_t^{\text{MLE}} = Z_t / \phi_t = Z_t / \sum_{u=1}^{\tau_\Phi} \phi_u Z_{t-u}$$

ratio of moving averages



- huge variability along time/
no local trend
- not robust to pseudo-periodicity/
misreported counts

Solution 0: (state-of-the-art) smoothing over a temporal window

$$\hat{R}_{t,s}^{\text{MLE}}, \text{ with } s = 7 \text{ days}$$

(Cori et al., 2013, *Am. Journal of Epidemiology*)

⇒ not able to detect rapid surge, nor fast decrease following sanitary restrictions

Solution 0: (state-of-the-art) smoothing over a temporal window

$$\hat{R}_{t,s}^{\text{MLE}}, \text{ with } s = 7 \text{ days}$$

(Cori et al., 2013, *Am. Journal of Epidemiology*)

⇒ not able to detect rapid surge, nor fast decrease following sanitary restrictions

Solution 1: regularization through nonlinear filtering

$$\hat{\mathbf{R}}^{\text{PKL}} = \underset{\mathbf{R} \in \mathbb{R}_+^T}{\operatorname{argmin}} \sum_{t=1}^T d_{\text{KL}}(Z_t | \mathbf{R}_t \Phi_t) + \lambda_R \mathcal{P}(\mathbf{R}) \quad (\text{penalized Kullback-Leibler})$$

with $\mathcal{P}(\mathbf{R})$ favoring some temporal regularity

(Abry et al., 2020, *PLOSOne*)

Reproduction number estimation from minimization of penalized likelihood

Solution 0: (state-of-the-art) smoothing over a temporal window

$$\hat{R}_{t,s}^{\text{MLE}}, \text{ with } s = 7 \text{ days}$$

(Cori et al., 2013, *Am. Journal of Epidemiology*)

⇒ not able to detect rapid surge, nor fast decrease following sanitary restrictions

Solution 1: regularization through nonlinear filtering

$$\hat{\mathbf{R}}^{\text{PKL}} = \underset{\mathbf{R} \in \mathbb{R}_+^T}{\operatorname{argmin}} \sum_{t=1}^T d_{\text{KL}}(Z_t | \mathbf{R}_t \Phi_t) + \lambda_R \mathcal{P}(\mathbf{R}) \quad (\text{penalized Kullback-Leibler})$$

with $\mathcal{P}(\mathbf{R})$ favoring some temporal regularity

(Abry et al., 2020, *PLOSOne*)

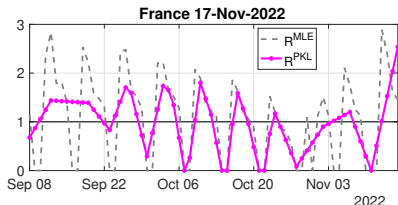
$$\mathcal{P}(\mathbf{R}) = \|\mathbf{D}_2 \mathbf{R}\|_1$$

$$(\mathbf{D}_2 \mathbf{R})_t = R_{t+1} - 2R_t + R_{t-1}$$

2nd order derivative & ℓ_1 -norm

⇒ piecewise linearity

captures global **trend**, more **regular** than MLE, but **pseudo-oscillations**

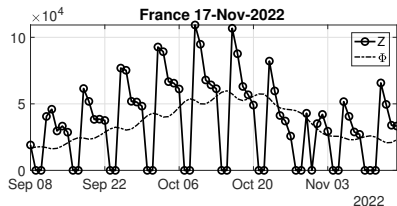


Reproduction number estimation from minimization of penalized likelihood

New infection counts \mathbf{Z} are corrupted by

- missing samples,
- non meaningful negative counts,
- retrospected cumulated counts,
- pseudo-seasonality effects.

⇒ full parametric modeling out of reach

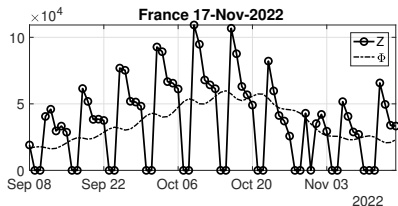


Reproduction number estimation from minimization of penalized likelihood

New infection counts \mathbf{Z} are corrupted by

- missing samples,
- non meaningful negative counts,
- retrospected cumulated counts,
- pseudo-seasonality effects.

⇒ full parametric modeling out of reach



Solution 1': first correct \mathbf{Z} , then apply penalized Kullback-Leibler on corrected $\mathbf{Z}^{(C)}$

⇒ two-step procedure not optimal: accumulates correction & regularization biases

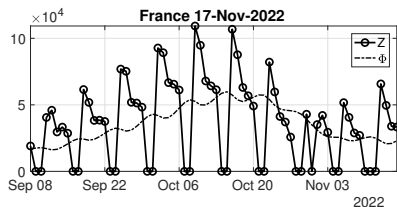
(Abry et al., 2020, *Eng. Med. Biol. Conf.*)

Reproduction number estimation from minimization of penalized likelihood

New infection counts \mathbf{Z} are corrupted by

- missing samples,
- non meaningful negative counts,
- retrospected cumulated counts,
- pseudo-seasonality effects.

⇒ full parametric modeling out of reach



Solution 1': first correct \mathbf{Z} , then apply penalized Kullback-Leibler on corrected $\mathbf{Z}^{(C)}$

⇒ two-step procedure not optimal: accumulates correction & regularization biases

(Abry et al., 2020, *Eng. Med. Biol. Conf.*)

Solution 2: **one-step** procedure performing jointly

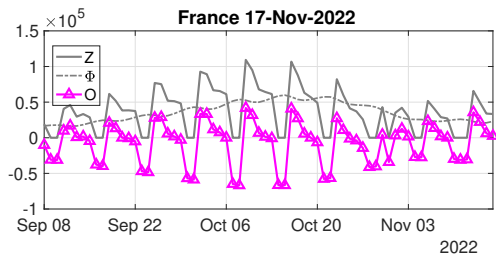
correction of corrupted Z_t & estimation of regularized R_t

(Pascal et al., 2022, *Trans. Sig. Process.*)

Extended Cori Model: additional latent variable O_t accounting for misreport

$$Z_t \sim \text{Poiss}(R_t \Phi_t + O_t), \quad R_t \Phi_t + O_t \geq 0$$

nonzero values of O_t concentrated on specific days (Sundays, day-offs, ...)



Interpretation:

$$\text{Poiss}(R_t \Phi_t + O_t) \sim \begin{cases} \text{Poiss}(R_t \Phi_t) + \text{Poiss}(O_t) & \text{if } O_t \geq 0, \\ \text{Poiss}(\alpha_t R_t \Phi_t), \alpha_t = 1 - \frac{-O_t}{R_t \Phi_t} \in [0, 1] & \text{if } O_t < 0. \end{cases}$$

Data: reported counts $\mathbf{Z} = (Z_1, \dots, Z_T)$

Model: corrected Poisson $\mathbb{P}(Z_t | \mathbf{Z}_{t-\tau_\phi:t-1}, R_t, O_t) = \frac{(R_t \phi_t + O_t)^{Z_t} e^{-(R_t \phi_t + O_t)}}{Z_t!}$

Data: reported counts $\mathbf{Z} = (Z_1, \dots, Z_T)$

Model: corrected Poisson $\mathbb{P}(Z_t | \mathbf{Z}_{t-\tau_\phi:t-1}, R_t, O_t) = \frac{(R_t \phi_t + O_t)^{Z_t} e^{-(R_t \phi_t + O_t)}}{Z_t!}$

Generalized Penalized Kullback-Leibler

$$(\hat{\mathbf{R}}, \hat{\mathbf{O}}) \in \underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{Argmin}} \sum_{t=1}^T d_{\text{KL}}(Z_t | R_t \phi_t + O_t) + \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \iota_{\geq 0}(\mathbf{R}) + \lambda_O \|\mathbf{O}\|_1$$

\implies estimates piecewise linear, non-negative R_t and sparse O_t

Data: reported counts $\mathbf{Z} = (Z_1, \dots, Z_T)$

Model: corrected Poisson $\mathbb{P}(Z_t | \mathbf{Z}_{t-\tau_\Phi:t-1}, R_t, O_t) = \frac{(R_t \Phi_t + O_t)^{Z_t} e^{-(R_t \Phi_t + O_t)}}{Z_t!}$

Generalized Penalized Kullback-Leibler

$$(\hat{\mathbf{R}}, \hat{\mathbf{O}}) \in \underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{Argmin}} \sum_{t=1}^T d_{\text{KL}}(Z_t | R_t \Phi_t + O_t) + \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \iota_{\geq 0}(\mathbf{R}) + \lambda_O \|\mathbf{O}\|_1$$

\implies estimates piecewise linear, non-negative R_t and sparse O_t

properties of the objective function:

- sum of convex functions composed with linear operators \implies globally convex;
- feasible domain: $(\forall t, R_t \geq 0)$ & (if $Z_t > 0, R_t \Phi_t + O_t > 0$, else $R_t \Phi_t + O_t \geq 0$);
- $p_t \mapsto d_{\text{KL}}(Z_t | p_t)$ is strictly-convex.

Data: reported counts $\mathbf{Z} = (Z_1, \dots, Z_T)$

Model: corrected Poisson $\mathbb{P}(Z_t | \mathbf{Z}_{t-\tau_\Phi:t-1}, \mathbf{R}_t, \mathbf{O}_t) = \frac{(\mathbf{R}_t \Phi_t + \mathbf{O}_t)^{Z_t} e^{-(\mathbf{R}_t \Phi_t + \mathbf{O}_t)}}{Z_t!}$

Generalized Penalized Kullback-Leibler

$$(\hat{\mathbf{R}}, \hat{\mathbf{O}}) \in \underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{Argmin}} \sum_{t=1}^T d_{\text{KL}}(Z_t | \mathbf{R}_t \Phi_t + \mathbf{O}_t) + \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \iota_{\geq 0}(\mathbf{R}) + \lambda_O \|\mathbf{O}\|_1$$

\implies estimates piecewise linear, non-negative \mathbf{R}_t and sparse \mathbf{O}_t

properties of the objective function:

- sum of convex functions composed with linear operators \implies globally convex;
- feasible domain: $(\forall t, R_t \geq 0)$ & (if $Z_t > 0, R_t \Phi_t + O_t > 0$, else $R_t \Phi_t + O_t \geq 0$);
- $p_t \mapsto d_{\text{KL}}(Z_t | p_t)$ is strictly-convex.

Theorem (Pascal et al., 2022, *Trans. Sig. Process.*)

- + The minimization problem has at least one solution $(\hat{\mathbf{R}}, \hat{\mathbf{O}})$.
- + The estimated time-varying Poisson intensity $\hat{p}_t = \hat{\mathbf{R}}_t \Phi_t + \hat{\mathbf{O}}_t$ is unique.

$$\underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \quad \sum_{t=1}^T d_{\text{KL}}(Z_t \mid R_t \Phi_t + O_t) + \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \iota_{\geq 0}(\mathbf{R}) + \lambda_O \|\mathbf{O}\|_1$$

- each term of the functional is convex;
- ℓ_1 -norm and indicative function \implies nonsmooth;
- gradient of $p_t \mapsto d_{\text{KL}}(Z_t \mid p_t)$ is not Lipschitzian;
- linear operator $\mathbf{D}_2 \implies$ no explicit form for $\text{prox}_{\|\mathbf{D}_2 \cdot\|_1}$

✗ gradient descent

✗ forward-backward

♣ need splitting

$$\underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \quad \sum_{t=1}^T d_{\text{KL}}(Z_t | R_t \Phi_t + O_t) + \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \iota_{\geq 0}(\mathbf{R}) + \lambda_O \|\mathbf{O}\|_1$$

- each term of the functional is convex;
- ℓ_1 -norm and indicative function \implies nonsmooth;
- gradient of $p_t \mapsto d_{\text{KL}}(Z_t | p_t)$ is not Lipschitzian;
- linear operator $\mathbf{D}_2 \implies$ no explicit form for $\text{prox}_{\|\mathbf{D}_2 \cdot\|_1}$

✗ gradient descent

✗ forward-backward

♣ need splitting

$$\iff \underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \quad f(\mathbf{R}, \mathbf{O} | \mathbf{Z}) + h(\mathbf{A}(\mathbf{R}, \mathbf{O})), \quad \mathbf{A} \text{ linear}; f, h \text{ proximable}$$

$$\mathbf{A}(\mathbf{R}, \mathbf{O}) = (\lambda_R \mathbf{D}_2 \mathbf{R}, \mathbf{R}, \lambda_O \mathbf{O}); \quad h(\mathbf{Q}_1, \mathbf{Q}_2, \mathbf{Q}_3) = \|\mathbf{Q}_1\|_1 + \iota_{\geq 0}(\mathbf{Q}_2) + \|\mathbf{Q}_3\|_1$$

Reproduction number estimation from minimization of penalized likelihood

$$\underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \quad \sum_{t=1}^T d_{\text{KL}}(Z_t | R_t \Phi_t + O_t) + \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \iota_{\geq 0}(\mathbf{R}) + \lambda_O \|\mathbf{O}\|_1$$

- each term of the functional is convex;
- ℓ_1 -norm and indicative function \implies nonsmooth; ✗ gradient descent
- gradient of $p_t \mapsto d_{\text{KL}}(Z_t | p_t)$ is not Lipschitzian; ✗ forward-backward
- linear operator $\mathbf{D}_2 \implies$ no explicit form for $\text{prox}_{\|\mathbf{D}_2 \cdot\|_1}$ ♣ need splitting

$$\iff \underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \quad f(\mathbf{R}, \mathbf{O} | \mathbf{Z}) + h(\mathbf{A}(\mathbf{R}, \mathbf{O})), \quad \mathbf{A} \text{ linear}; f, h \text{ proximable}$$

$$\mathbf{A}(\mathbf{R}, \mathbf{O}) = (\lambda_R \mathbf{D}_2 \mathbf{R}, \mathbf{R}, \lambda_O \mathbf{O}); \quad h(\mathbf{Q}_1, \mathbf{Q}_2, \mathbf{Q}_3) = \|\mathbf{Q}_1\|_1 + \iota_{\geq 0}(\mathbf{Q}_2) + \|\mathbf{Q}_3\|_1$$

Primal-dual algorithm

(Chambolle et al., 2011, *Int. Conf. Comput. Vis.*)

for $k = 1, 2 \dots$ do

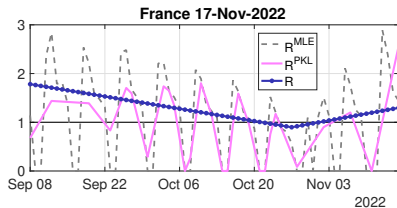
$$\mathbf{Q}^{[k+1]} = \text{prox}_{\sigma h^*}(\mathbf{Q}^{[k]} + \sigma \mathbf{A}(\bar{\mathbf{R}}^{[k]}, \bar{\mathbf{O}}^{[k]})) \quad \text{dual}$$

$$(\mathbf{R}^{[k+1]}, \mathbf{O}^{[k+1]}) = \text{prox}_{\tau f(\cdot | \mathbf{Z})}((\mathbf{R}^{[k+1]}, \mathbf{O}^{[k+1]}) - \tau \mathbf{A}^* \mathbf{Q}^{[k+1]}) \quad \text{primal}$$

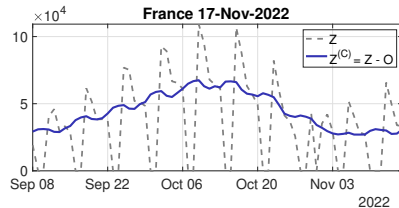
$$(\bar{\mathbf{R}}^{[k+1]}, \bar{\mathbf{O}}^{[k+1]}) = 2(\mathbf{R}^{[k+1]}, \mathbf{O}^{[k+1]}) - (\mathbf{R}^{[k]}, \mathbf{O}^{[k]}) \quad \text{auxiliary}$$

Reproduction number estimation from minimization of penalized likelihood

Reproduction number \hat{R}



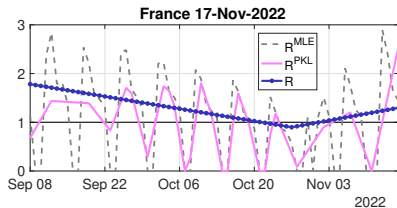
Corrected infection counts $Z^{(C)}$



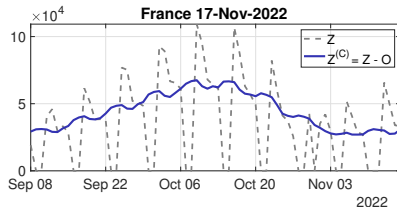
⇒ no more pseudo-seasonality, local trends well captured, smooth behavior

Reproduction number estimation from minimization of penalized likelihood

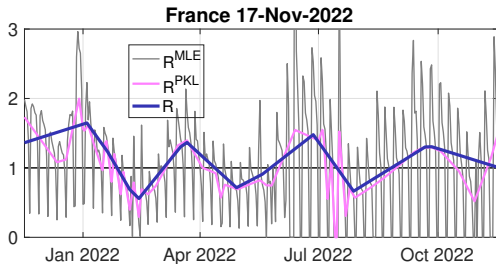
Reproduction number \hat{R}



Corrected infection counts $Z^{(C)}$



⇒ no more pseudo-seasonality, local trends well captured, smooth behavior



fast numerical scheme: 15 to 30 sec for 70 days to 1 year

New infection counts per county: $\mathbf{Z} = \left\{ Z_t^{(d)}, d \in [1, D], t \in [1, T] \right\}$

\Rightarrow multivariate time-varying reproduction number $R_t^{(d)}$

New infection counts per county: $\mathbf{Z} = \left\{ Z_t^{(d)}, d \in [1, D], t \in [1, T] \right\}$

\Rightarrow multivariate time-varying reproduction number $R_t^{(d)}$

Multivariate extended penalized Kullback-Leibler

$$\begin{aligned} (\hat{\mathbf{R}}, \hat{\mathbf{O}}) = \underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_+^{D \times T} \times \mathbb{R}^{D \times T}}{\operatorname{argmin}} \quad & \sum_{d=1}^D \sum_{t=1}^T d_{\text{KL}} \left(Z_t^{(d)} \mid R_t^{(d)} \Phi_t^{(d)} + O_t^{(d)} \right) \\ & + \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \iota_{\geq 0}(\mathbf{R}) + \lambda_{\text{space}} \|\mathbf{GR}\|_1 + \lambda_O \|\mathbf{O}\|_1 \\ \Rightarrow \quad & \|\mathbf{GR}\|_1 \text{ favors piecewise constancy in space} \end{aligned}$$

Reproduction number estimation from minimization of penalized likelihood

New infection counts per county: $\mathbf{Z} = \left\{ Z_t^{(d)}, d \in [1, D], t \in [1, T] \right\}$

\Rightarrow multivariate time-varying reproduction number $R_t^{(d)}$

Multivariate extended penalized Kullback-Leibler

$$\begin{aligned} (\hat{\mathbf{R}}, \hat{\mathbf{O}}) = \underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_+^{D \times T} \times \mathbb{R}^{D \times T}}{\operatorname{argmin}} \quad & \sum_{d=1}^D \sum_{t=1}^T d_{\text{KL}} \left(Z_t^{(d)} \mid R_t^{(d)} \Phi_t^{(d)} + O_t^{(d)} \right) \\ & + \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \iota_{\geq 0}(\mathbf{R}) + \lambda_{\text{space}} \|\mathbf{GR}\|_1 + \lambda_O \|\mathbf{O}\|_1 \end{aligned}$$

$\Rightarrow \|\mathbf{GR}\|_1$ favors **piecewise constancy** in space

France (Hospital based data) - R - 15-Nov-2022

Graph Total Variation

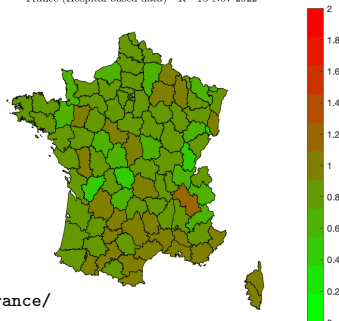
$$\|\mathbf{GR}\|_1 = \sum_{t=1}^T \sum_{d_1 \sim d_2} \left| R_t^{(d_1)} - R_t^{(d_2)} \right|$$

sum over neighboring counties

here: $d_1 \sim d_2 \Leftrightarrow$ share terrestrial border

$$\tilde{\mathbf{A}}(\mathbf{R}, \mathbf{O}) = (\lambda_R \mathbf{D}_2 \mathbf{R}, \mathbf{R}, \lambda_{\text{space}} \mathbf{GR}, \lambda_O \mathbf{O})$$

<http://barthes.enssib.fr/coronavirus/cartes/RFrance/>



Bayesian framework for credibility interval estimation

Pointwise estimate of parameter $\theta = (\mathbf{R}, \mathbf{O})$ from observations \mathbf{Z}

$$\underset{\theta \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \quad f(\theta|\mathbf{Z}) + h(\mathbf{A}\theta) \quad (\text{Pascal et al., 2022, } \textit{Trans. Sig. Process.})$$

Bayesian framework for credibility interval estimation

Pointwise estimate of parameter $\theta = (\mathbf{R}, \mathbf{O})$ from observations \mathbf{Z}

$$\underset{\theta \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \quad f(\theta|\mathbf{Z}) + h(\mathbf{A}\theta) \quad (\text{Pascal et al., 2022, } \textit{Trans. Sig. Process.})$$

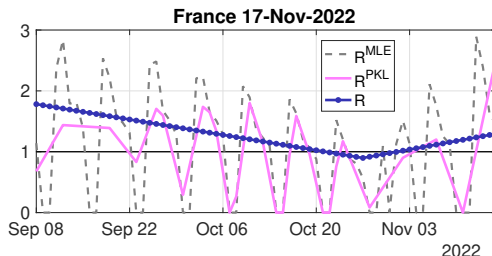
Q: what is the value of R today? **A:** solve the minimization problem and output \hat{R}_T .

Bayesian framework for credibility interval estimation

Pointwise estimate of parameter $\theta = (\mathbf{R}, \mathbf{O})$ from observations \mathbf{Z}

$$\underset{\theta \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \quad f(\theta|\mathbf{Z}) + h(\mathbf{A}\theta) \quad (\text{Pascal et al., 2022, Trans. Sig. Process.})$$

Q: what is the value of R today? **A:** solve the minimization problem and output \hat{R}_T .



$$\hat{R}_T = 1.2955$$

Bayesian framework for credibility interval estimation

Pointwise estimate of parameter $\theta = (\mathbf{R}, \mathbf{O})$ from observations \mathbf{Z}

$$\underset{\theta \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \quad f(\theta|\mathbf{Z}) + h(\mathbf{A}\theta) \quad (\text{Pascal et al., 2022, } \textit{Trans. Sig. Process.})$$

Bayesian reformulation: interpret $(\hat{\mathbf{R}}, \hat{\mathbf{O}})$ as the MAP of

$$\pi(\theta) \propto \exp(-f(\theta|\mathbf{Z}) - h(\mathbf{A}\theta))$$

- $\exp(-f(\theta|\mathbf{Z})) \sim$ likelihood of the observation
- $\exp(-h(\mathbf{A}\theta)) \sim$ prior on the parameter of interest

Bayesian framework for credibility interval estimation

Pointwise estimate of parameter $\theta = (\mathbf{R}, \mathbf{O})$ from observations \mathbf{Z}

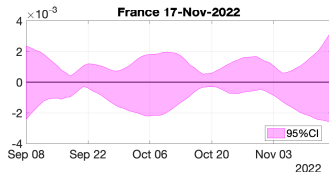
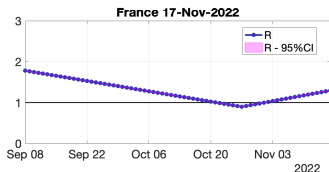
$$\underset{\theta \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \quad f(\theta|\mathbf{Z}) + h(\mathbf{A}\theta) \quad (\text{Pascal et al., 2022, Trans. Sig. Process.})$$

Bayesian reformulation: interpret $(\hat{\mathbf{R}}, \hat{\mathbf{O}})$ as the MAP of

$$\pi(\theta) \propto \exp(-f(\theta|\mathbf{Z}) - h(\mathbf{A}\theta))$$

- $\exp(-f(\theta|\mathbf{Z})) \sim$ likelihood of the observation
- $\exp(-h(\mathbf{A}\theta)) \sim$ prior on the parameter of interest

\Rightarrow instead of focusing on \hat{R}_t , the **pointwise** MAP, probe π to get $R_t \in [\underline{R}_t, \bar{R}_t]$ with 95% probability, i.e., **credibility interval** estimates



$$\hat{R}_T \in [1.2987, 1.3047]$$

Log-likelihood from Poisson model

$$\mathcal{D} = \{\boldsymbol{\theta} \mid \forall t, R_t \Phi_t + O_t \geq 0, R_t \geq 0\}$$

$$f(\boldsymbol{\theta} \mid \mathbf{Z}) := \begin{cases} -\sum_{t=1}^T (Z_t \ln(R_t \Phi_t + O_t) - (R_t \Phi_t + O_t) + \mathcal{C}(Z_t)) & \text{if } \boldsymbol{\theta} \in \mathcal{D}, \\ \infty & \text{otherwise,} \end{cases}$$

Log-likelihood from Poisson model

$$\mathcal{D} = \{\theta \mid \forall t, R_t \Phi_t + O_t \geq 0, R_t \geq 0\}$$

$$f(\theta) := \begin{cases} -\sum_{t=1}^T (Z_t \ln(R_t \Phi_t + O_t) - (R_t \Phi_t + O_t)) & \text{if } \theta \in \mathcal{D}, \\ \infty & \text{otherwise,} \end{cases}$$

Prior distribution of $\theta = (\mathbf{R}, \mathbf{O}) = (R_1, \dots, R_T, O_1, \dots, O_T) \in (\mathbb{R}_+)^T \times \mathbb{R}^T$

- reproduction number: $R_t - 2R_{t-1} + R_{t-2} \sim \text{Laplace}(\lambda_R)$

Log-likelihood from Poisson model

$$\mathcal{D} = \{\theta \mid \forall t, R_t \Phi_t + O_t \geq 0, R_t \geq 0\}$$

$$f(\theta) := \begin{cases} -\sum_{t=1}^T (Z_t \ln(R_t \Phi_t + O_t) - (R_t \Phi_t + O_t)) & \text{if } \theta \in \mathcal{D}, \\ \infty & \text{otherwise,} \end{cases}$$

Prior distribution of $\theta = (\mathbf{R}, \mathbf{O}) = (R_1, \dots, R_T, O_1, \dots, O_T) \in (\mathbb{R}_+)^T \times \mathbb{R}^T$

- reproduction number: $R_t - 2R_{t-1} + R_{t-2} \sim \text{Laplace}(\lambda_R)$
- outliers $O_t \sim \text{Laplace}(\lambda_O)$

Log-likelihood from Poisson model

$$\mathcal{D} = \{\boldsymbol{\theta} \mid \forall t, R_t \Phi_t + O_t \geq 0, R_t \geq 0\}$$

$$f(\boldsymbol{\theta}) := \begin{cases} -\sum_{t=1}^T (Z_t \ln(R_t \Phi_t + O_t) - (R_t \Phi_t + O_t)) & \text{if } \boldsymbol{\theta} \in \mathcal{D}, \\ \infty & \text{otherwise,} \end{cases}$$

Prior distribution of $\boldsymbol{\theta} = (\mathbf{R}, \mathbf{O}) = (R_1, \dots, R_T, O_1, \dots, O_T) \in (\mathbb{R}_+)^T \times \mathbb{R}^T$

- reproduction number: $R_t - 2R_{t-1} + R_{t-2} \sim \text{Laplace}(\lambda_R)$
- outliers $O_t \sim \text{Laplace}(\lambda_O)$

$$\Rightarrow g(\boldsymbol{\theta}) = \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \lambda_O \|\mathbf{O}\|_1, \quad \mathbf{D}_2 = \frac{1}{\sqrt{6}} \underbrace{\begin{bmatrix} 1 & -2 & 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & -2 & 1 & 0 & \dots & 0 \\ \dots & & & & & & \dots \\ 0 & \dots & & & 1 & -2 & 1 \end{bmatrix}}_{\text{Laplacian}}$$

Bayesian framework for credibility interval estimation

Log-likelihood from Poisson model

$$\mathcal{D} = \{\boldsymbol{\theta} \mid \forall t, R_t \Phi_t + O_t \geq 0, R_t \geq 0\}$$

$$f(\boldsymbol{\theta}) := \begin{cases} -\sum_{t=1}^T (Z_t \ln(R_t \Phi_t + O_t) - (R_t \Phi_t + O_t)) & \text{if } \boldsymbol{\theta} \in \mathcal{D}, \\ \infty & \text{otherwise,} \end{cases}$$

Prior distribution of $\boldsymbol{\theta} = (\mathbf{R}, \mathbf{O}) = (R_1, \dots, R_T, O_1, \dots, O_T) \in (\mathbb{R}_+)^T \times \mathbb{R}^T$

- reproduction number: $R_t - 2R_{t-1} + R_{t-2} \sim \text{Laplace}(\lambda_R)$
- outliers $O_t \sim \text{Laplace}(\lambda_O)$

$$\Rightarrow g(\boldsymbol{\theta}) = \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \lambda_O \|\mathbf{O}\|_1, \quad \mathbf{D}_2 = \frac{1}{\sqrt{6}} \underbrace{\begin{bmatrix} 1 & -2 & 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & -2 & 1 & 0 & \dots & 0 \\ \dots & & & & & & \dots \\ 0 & \dots & & & 1 & -2 & 1 \end{bmatrix}}_{\text{Laplacian}}$$

Posterior distribution of unknown parameters $\boldsymbol{\theta} = (\mathbf{R}, \mathbf{O})$

$$\pi(\boldsymbol{\theta}) \propto \exp(-f(\boldsymbol{\theta}) - g(\boldsymbol{\theta})) \mathbb{1}_{\mathcal{D}}(\boldsymbol{\theta})$$

- f, g convex
- f smooth, g nonsmooth

Markov Chain Monte Carlo sampling

Purpose: sampling the random variable $\theta = (\mathbf{R}, \mathbf{O}) \in \mathbb{R}^{2T}$ according to the posterior[†]

$$\pi(\theta) \propto \exp(-f(\theta) - g(\theta)) \mathbb{1}_{\mathcal{D}}(\theta)$$

[†] π is defined up to a normalizing constant

Markov Chain Monte Carlo sampling

Purpose: sampling the random variable $\theta = (\mathbf{R}, \mathbf{O}) \in \mathbb{R}^{2T}$ according to the posterior[†]

$$\pi(\theta) \propto \exp(-f(\theta) - g(\theta)) \mathbb{1}_{\mathcal{D}}(\theta)$$

Principle: 1) generate a random sequence $\{\theta^n, n \in \mathbb{N}\}$ such that

- θ^{n+1} only depends on θ^n ,
- at convergence, i.e., as $n \rightarrow \infty$, $\theta^n \sim \pi$,

2) compute Bayesian estimators, e.g., **credibility intervals**, on samples $\{\theta^n, n \geq N\}$

[†] π is defined up to a normalizing constant

Markov Chain Monte Carlo sampling

Purpose: sampling the random variable $\theta = (\mathbf{R}, \mathbf{O}) \in \mathbb{R}^{2T}$ according to the posterior[†]

$$\pi(\theta) \propto \exp(-f(\theta) - g(\theta)) \mathbb{1}_{\mathcal{D}}(\theta)$$

Principle: 1) generate a random sequence $\{\theta^n, n \in \mathbb{N}\}$ such that

- θ^{n+1} only depends on θ^n ,
- at convergence, i.e., as $n \rightarrow \infty$, $\theta^n \sim \pi$,

2) compute Bayesian estimators, e.g., **credibility intervals**, on samples $\{\theta^n, n \geq N\}$

Simple and very general approach: *Hastings-Metropolis random walk*

(i) propose a random move according to

$$\theta^{n+\frac{1}{2}} = \theta^n + \sqrt{2\gamma}\Gamma\xi^{n+1}, \quad \xi^{n+1} \sim \mathcal{N}_{2T}(0, \mathbf{I})$$

with γ positive step size, $\Gamma \in \mathbb{R}^{2T \times 2T}$

[†] π is defined up to a normalizing constant

Markov Chain Monte Carlo sampling

Purpose: sampling the random variable $\theta = (\mathbf{R}, \mathbf{O}) \in \mathbb{R}^{2T}$ according to the posterior[†]

$$\pi(\theta) \propto \exp(-f(\theta) - g(\theta)) \mathbb{1}_{\mathcal{D}}(\theta)$$

Principle: 1) generate a random sequence $\{\theta^n, n \in \mathbb{N}\}$ such that

- θ^{n+1} only depends on θ^n ,
- at convergence, i.e., as $n \rightarrow \infty$, $\theta^n \sim \pi$,

2) compute Bayesian estimators, e.g., **credibility intervals**, on samples $\{\theta^n, n \geq N\}$

Simple and very general approach: *Hastings-Metropolis random walk*

(i) propose a random move according to

$$\theta^{n+\frac{1}{2}} = \theta^n + \sqrt{2\gamma}\Gamma\xi^{n+1}, \quad \xi^{n+1} \sim \mathcal{N}_{2T}(0, \mathbf{I})$$

with γ positive step size, $\Gamma \in \mathbb{R}^{2T \times 2T}$

(ii) accept: $\theta^{n+1} = \theta^{n+\frac{1}{2}}$, with probability $1 \wedge \frac{\pi(\theta^{n+\frac{1}{2}})}{\pi(\theta^n)}$, or reject: $\theta^{n+1} = \theta^n$

[†] π is defined up to a normalizing constant

Metropolis Adjusted Langevin Algorithm (MALA)

Langevin dynamics: $\theta^{n+\frac{1}{2}} = \mu(\theta^n) + \sqrt{2\gamma}\xi^{n+1}$, (Kent, 1978, *Adv Appl Probab*)

$\mu(\theta)$ adapted to $\pi(\theta) = \exp(-f(\theta) - g(\theta))\mathbb{1}_{\mathcal{D}}(\theta)$

Metropolis Adjusted Langevin Algorithm (MALA)

Langevin dynamics: $\theta^{n+\frac{1}{2}} = \mu(\theta^n) + \sqrt{2\gamma}\xi^{n+1}$, (Kent, 1978, *Adv Appl Probab*)

$\mu(\theta)$ adapted to $\pi(\theta) = \exp(-f(\theta) - g(\theta))\mathbb{1}_{\mathcal{D}}(\theta)$

Case 1: $g = 0$ and $-\ln \pi = f$ is smooth (Roberts & Tweedie, 1996, *Bernoulli*)

$$\mu(\theta) = \theta - \gamma \Gamma \Gamma^\top \nabla f(\theta) = \theta + \gamma \Gamma \Gamma^\top \nabla \ln \pi(\theta)$$

\implies move towards areas of higher probability

Metropolis Adjusted Langevin Algorithm (MALA)

Langevin dynamics: $\theta^{n+\frac{1}{2}} = \mu(\theta^n) + \sqrt{2\gamma}\xi^{n+1}$, (Kent, 1978, *Adv Appl Probab*)

$\mu(\theta)$ adapted to $\pi(\theta) = \exp(-f(\theta) - g(\theta))\mathbb{1}_{\mathcal{D}}(\theta)$

Case 1: $g = 0$ and $-\ln \pi = f$ is smooth (Roberts & Tweedie, 1996, *Bernoulli*)

$$\mu(\theta) = \theta - \gamma \Gamma \Gamma^\top \nabla f(\theta) = \theta + \gamma \Gamma \Gamma^\top \nabla \ln \pi(\theta)$$

\implies move towards areas of higher probability

Case 2: $-\ln \pi = f + g$ is nonsmooth

$$\mu(\theta) = \text{prox}_{\gamma g}^{\Gamma \Gamma^\top}(\theta - \gamma \Gamma \Gamma^\top \nabla f(\theta))$$

combining *Langevin* and *proximal*[†] approaches

[†] $\text{prox}_{\gamma g}^{\Gamma \Gamma^\top}(y) = \underset{x \in \mathbb{R}^d}{\operatorname{argmin}} \left(\frac{1}{2} \|x - y\|_{\Gamma \Gamma^\top}^2 + \gamma g(x) \right)$: preconditioned proximity operator of g

Posterior density of $\theta = (\mathbf{R}, \mathbf{O})$: $\pi(\theta) \propto \exp(-f(\theta) - g(\theta)) \mathbb{1}_{\mathcal{D}}(\theta)$

- **smooth** negative log-likelihood

$$\text{if } \theta \in \mathcal{D}, \quad f(\theta) = -\sum_{t=1}^T (Z_t \ln p_t(\theta) - p_t(\theta)), \quad p_t(\theta) = R_t(\Phi Z)_t + O_t$$

- **nonsmooth** convex lower-semicontinuous negative a priori log-distribution

$$g(\theta) = \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \lambda_O \|\mathbf{O}\|_1 = h(\mathbf{A}\theta)$$

$$\mathbf{A} : \theta \mapsto (\mathbf{D}_2 \mathbf{R}, \mathbf{O}) \text{ linear operator, } h(\cdot_1, \cdot_2) = \lambda_R \|\cdot_1\|_1 + \lambda_O \|\cdot_2\|_1$$

Posterior density of $\theta = (\mathbf{R}, \mathbf{O})$: $\pi(\theta) \propto \exp(-f(\theta) - g(\theta)) \mathbb{1}_{\mathcal{D}}(\theta)$

- **smooth** negative log-likelihood

$$\text{if } \theta \in \mathcal{D}, \quad f(\theta) = -\sum_{t=1}^T (Z_t \ln p_t(\theta) - p_t(\theta)), \quad p_t(\theta) = R_t(\Phi Z)_t + O_t$$

- **nonsmooth** convex lower-semicontinuous negative a priori log-distribution

$$g(\theta) = \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \lambda_O \|\mathbf{O}\|_1 = h(\mathbf{A}\theta)$$

$$\mathbf{A} : \theta \mapsto (\mathbf{D}_2 \mathbf{R}, \mathbf{O}) \text{ linear operator, } h(\cdot_1, \cdot_2) = \lambda_R \|\cdot_1\|_1 + \lambda_O \|\cdot_2\|_1$$

Case 3: $-\ln \pi = f + h(\mathbf{A}\cdot)$ (Fort et al., 2022, *preprint*)

closed-form expression of $\text{prox}_{\gamma h}$ but **not** of $\text{prox}_{\gamma h(\mathbf{A}\cdot)}$

1) extend \mathbf{A} into **invertible** $\bar{\mathbf{A}}$, and h in \bar{h} such that $\bar{h}(\bar{\mathbf{A}}\theta) = h(\mathbf{A}\theta)$

2) reason on the **dual** variable $\tilde{\theta} = \bar{\mathbf{A}}\theta$

Langevin: drift toward higher probability regions

$$\operatorname{argmax}_{\boldsymbol{\theta} \in \mathbb{R}^{2T}} \ln \pi(\boldsymbol{\theta}) = \operatorname{argmin}_{\boldsymbol{\theta} \in \mathbb{R}^{2T}} f(\boldsymbol{\theta}) + \bar{h}(\bar{\mathbf{A}}\boldsymbol{\theta}) = \mathbf{A}^{-1} \operatorname{argmin}_{\tilde{\boldsymbol{\theta}} \in \mathbb{R}^{2T}} f(\bar{\mathbf{A}}^{-1}\tilde{\boldsymbol{\theta}}) + \bar{h}(\tilde{\boldsymbol{\theta}})$$

Langevin: drift toward higher probability regions

$$\begin{aligned} \operatorname{argmax}_{\boldsymbol{\theta} \in \mathbb{R}^{2T}} \ln \pi(\boldsymbol{\theta}) &= \operatorname{argmin}_{\boldsymbol{\theta} \in \mathbb{R}^{2T}} f(\boldsymbol{\theta}) + \bar{h}(\bar{\mathbf{A}}\boldsymbol{\theta}) = \mathbf{A}^{-1} \operatorname{argmin}_{\tilde{\boldsymbol{\theta}} \in \mathbb{R}^{2T}} f(\bar{\mathbf{A}}^{-1}\tilde{\boldsymbol{\theta}}) + \bar{h}(\tilde{\boldsymbol{\theta}}) \\ \Rightarrow \quad \mu(\boldsymbol{\theta}) &= \underbrace{\bar{\mathbf{A}}^{-1}}_{\text{back to } \boldsymbol{\theta}} \underbrace{\operatorname{prox}_{\gamma \bar{h}} \left(\bar{\mathbf{A}}\boldsymbol{\theta} - \gamma \bar{\mathbf{A}}^{-\top} \nabla f(\boldsymbol{\theta}) \right)}_{\text{proximal-gradient on } \tilde{\boldsymbol{\theta}}} \end{aligned}$$

Langevin: drift toward higher probability regions

$$\begin{aligned} \operatorname{argmax}_{\boldsymbol{\theta} \in \mathbb{R}^{2T}} \ln \pi(\boldsymbol{\theta}) &= \operatorname{argmin}_{\boldsymbol{\theta} \in \mathbb{R}^{2T}} f(\boldsymbol{\theta}) + \bar{h}(\bar{\mathbf{A}}\boldsymbol{\theta}) = \mathbf{A}^{-1} \operatorname{argmin}_{\tilde{\boldsymbol{\theta}} \in \mathbb{R}^{2T}} f(\bar{\mathbf{A}}^{-1}\tilde{\boldsymbol{\theta}}) + \bar{h}(\tilde{\boldsymbol{\theta}}) \\ \Rightarrow \quad \mu(\boldsymbol{\theta}) &= \underbrace{\bar{\mathbf{A}}^{-1}}_{\text{back to } \boldsymbol{\theta}} \underbrace{\operatorname{prox}_{\gamma \bar{h}} \left(\bar{\mathbf{A}}\boldsymbol{\theta} - \gamma \bar{\mathbf{A}}^{-\top} \nabla f(\boldsymbol{\theta}) \right)}_{\text{proximal-gradient on } \tilde{\boldsymbol{\theta}}} \end{aligned}$$

Two strategies to extend $\mathbf{A} = \begin{pmatrix} \mathbf{D}_2 & 0 \\ 0 & \mathbf{I} \end{pmatrix} \in \mathbb{R}^{(2T-1) \times 2T}$ into $\bar{\mathbf{A}} = \begin{pmatrix} \bar{\mathbf{D}} & 0 \\ 0 & \mathbf{I} \end{pmatrix} \in \mathbb{R}^{2T \times 2T}$:

Langevin: drift toward higher probability regions

$$\begin{aligned} \operatorname{argmax}_{\theta \in \mathbb{R}^{2T}} \ln \pi(\theta) &= \operatorname{argmin}_{\theta \in \mathbb{R}^{2T}} f(\theta) + \bar{h}(\bar{\mathbf{A}}\theta) = \mathbf{A}^{-1} \operatorname{argmin}_{\tilde{\theta} \in \mathbb{R}^{2T}} f(\bar{\mathbf{A}}^{-1}\tilde{\theta}) + \bar{h}(\tilde{\theta}) \\ \Rightarrow \mu(\theta) &= \underbrace{\bar{\mathbf{A}}^{-1}}_{\text{back to } \theta} \underbrace{\operatorname{prox}_{\gamma \bar{h}} \left(\bar{\mathbf{A}}\theta - \gamma \bar{\mathbf{A}}^{-\top} \nabla f(\theta) \right)}_{\text{proximal-gradient on } \tilde{\theta}} \end{aligned}$$

Two strategies to extend $\mathbf{A} = \begin{pmatrix} \mathbf{D}_2 & 0 \\ 0 & \mathbf{I} \end{pmatrix} \in \mathbb{R}^{(2T-1) \times 2T}$ into $\bar{\mathbf{A}} = \begin{pmatrix} \bar{\mathbf{D}} & 0 \\ 0 & \mathbf{I} \end{pmatrix} \in \mathbb{R}^{2T \times 2T}$:

Invert

$$\bar{\mathbf{D}}_2 := \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ -2/\sqrt{5} & 1/\sqrt{5} & 0 & \cdots & 0 \\ & \mathbf{D}_2 & & & \end{bmatrix}$$

Langevin: drift toward higher probability regions

$$\begin{aligned} \operatorname{argmax}_{\theta \in \mathbb{R}^{2T}} \ln \pi(\theta) &= \operatorname{argmin}_{\theta \in \mathbb{R}^{2T}} f(\theta) + \bar{h}(\bar{\mathbf{A}}\theta) = \mathbf{A}^{-1} \operatorname{argmin}_{\tilde{\theta} \in \mathbb{R}^{2T}} f(\bar{\mathbf{A}}^{-1}\tilde{\theta}) + \bar{h}(\tilde{\theta}) \\ \Rightarrow \mu(\theta) &= \underbrace{\bar{\mathbf{A}}^{-1}}_{\text{back to } \theta} \underbrace{\operatorname{prox}_{\gamma \bar{h}}(\bar{\mathbf{A}}\theta - \gamma \bar{\mathbf{A}}^{-\top} \nabla f(\theta))}_{\text{proximal-gradient on } \tilde{\theta}} \end{aligned}$$

Two strategies to extend $\mathbf{A} = \begin{pmatrix} \mathbf{D}_2 & 0 \\ 0 & \mathbf{I} \end{pmatrix} \in \mathbb{R}^{(2T-1) \times 2T}$ into $\bar{\mathbf{A}} = \begin{pmatrix} \bar{\mathbf{D}} & 0 \\ 0 & \mathbf{I} \end{pmatrix} \in \mathbb{R}^{2T \times 2T}$:

Invert

$$\bar{\mathbf{D}}_2 := \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ -2/\sqrt{5} & 1/\sqrt{5} & 0 & \cdots & 0 \\ & \mathbf{D}_2 & & & \end{bmatrix}$$

Ortho

$$\bar{\mathbf{D}}_o := \begin{bmatrix} \mathbf{v}_1^\top \\ \mathbf{v}_2^\top \\ \mathbf{D}_2 \end{bmatrix} \quad \begin{array}{l} \mathbf{v}_1, \mathbf{v}_2 \in \mathbb{R}^{2T} \\ \mathbf{v}_1 \perp \mathbf{v}_2, \mathbf{v}_1, \mathbf{v}_2 \in (\mathbf{D}_2^\top)^\perp \end{array}$$

Proximal-Gradient dual sampler PGdual

Langevin: drift toward higher probability regions

$$\begin{aligned} \operatorname{argmax}_{\theta \in \mathbb{R}^{2T}} \ln \pi(\theta) &= \operatorname{argmin}_{\theta \in \mathbb{R}^{2T}} f(\theta) + \bar{h}(\bar{\mathbf{A}}\theta) = \mathbf{A}^{-1} \operatorname{argmin}_{\tilde{\theta} \in \mathbb{R}^{2T}} f(\bar{\mathbf{A}}^{-1}\tilde{\theta}) + \bar{h}(\tilde{\theta}) \\ \Rightarrow \mu(\theta) &= \underbrace{\bar{\mathbf{A}}^{-1}}_{\text{back to } \theta} \frac{\operatorname{prox}_{\gamma \bar{h}} \left(\bar{\mathbf{A}}\theta - \gamma \bar{\mathbf{A}}^{-\top} \nabla f(\theta) \right)}{\text{proximal-gradient on } \tilde{\theta}} \end{aligned}$$

Two strategies to extend $\mathbf{A} = \begin{pmatrix} \mathbf{D}_2 & 0 \\ 0 & \mathbf{I} \end{pmatrix} \in \mathbb{R}^{(2T-1) \times 2T}$ into $\bar{\mathbf{A}} = \begin{pmatrix} \bar{\mathbf{D}} & 0 \\ 0 & \mathbf{I} \end{pmatrix} \in \mathbb{R}^{2T \times 2T}$:

Invert

$$\bar{\mathbf{D}}_2 := \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ -2/\sqrt{5} & 1/\sqrt{5} & 0 & \cdots & 0 \\ & \mathbf{D}_2 & & & \end{bmatrix}$$

Ortho

$$\bar{\mathbf{D}}_o := \begin{bmatrix} \mathbf{v}_1^\top \\ \mathbf{v}_2^\top \\ \mathbf{D}_2 \end{bmatrix} \quad \begin{array}{l} \mathbf{v}_1, \mathbf{v}_2 \in \mathbb{R}^{2T} \\ \mathbf{v}_1 \perp \mathbf{v}_2, \mathbf{v}_1, \mathbf{v}_2 \in (\mathbf{D}_2^\top)^\perp \end{array}$$

Proposed PGdual **drift terms** on $\theta = (\mathbf{R}, \mathbf{O})$:

reproduction numbers $\mu_{\mathbf{R}}(\theta) = \bar{\mathbf{D}}^{-1} \operatorname{prox}_{\gamma_{\mathbf{R}} \lambda_{\mathbf{R}} \|(\cdot)_{3:T}\|_1} \left(\bar{\mathbf{D}} \mathbf{R} - \gamma_{\mathbf{R}} \bar{\mathbf{D}}^{-\top} \nabla_{\mathbf{R}} f(\theta) \right)$

outliers $\mu_{\mathbf{O}}(\theta) = \operatorname{prox}_{\gamma_{\mathbf{O}} \lambda_{\mathbf{O}} \|\cdot\|_1} (\mathbf{O} - \gamma_{\mathbf{O}} \nabla_{\mathbf{O}} f(\theta))$

Markov Chain Monte Carlo sampling scheme

Data: $\overline{\mathbf{D}} = \overline{\mathbf{D}}_2$ (Invert) or $\overline{\mathbf{D}} = \overline{\mathbf{D}}_o$ (Ortho)

$\gamma_R, \gamma_O > 0$, $N_{\max} \in \mathbb{N}_*$, $\theta^0 = (\mathbf{R}^0, \mathbf{O}^0) \in \mathcal{D}$

Result: A \mathcal{D} -valued sequence $\{\theta^n = (\mathbf{R}^n, \mathbf{O}^n), n \in 0, \dots, N_{\max}\}$

for $n = 0, \dots, N_{\max} - 1$ **do**

Sample $\xi_R^{n+1} \sim \mathcal{N}_T(0, \mathbf{I})$ and $\xi_O^{n+1} \sim \mathcal{N}_T(0, \mathbf{I})$;

Set $\mathbf{R}^{n+\frac{1}{2}} = \mu_R(\theta^n) + \sqrt{2\gamma_R} \overline{\mathbf{D}}^{-1} \overline{\mathbf{D}}^{-\top} \xi_R^{n+1}$;

$\mathbf{O}^{n+\frac{1}{2}} = \mu_O(\theta^n) + \sqrt{2\gamma_O} \xi_O^{n+1}$;

$\theta^{n+\frac{1}{2}} = (\mathbf{R}^{n+\frac{1}{2}}, \mathbf{O}^{n+\frac{1}{2}})$;

Set $\theta^{n+1} = \theta^{n+\frac{1}{2}}$ with probability

$$1 \wedge \frac{\pi(\theta^{n+\frac{1}{2}})}{\pi(\theta^n)} \frac{q_R(\theta^{n+\frac{1}{2}}, \theta_R^n)}{q_R(\theta^n, \theta_R^{n+\frac{1}{2}})} \frac{q_O(\theta^{n+\frac{1}{2}}, \theta_O^n)}{q_O(\theta^n, \theta_O^{n+\frac{1}{2}})},$$

$q_{R/O}$: Gaussian kernel stemming from nonsymmetric proposal

and $\theta^{n+1} = \theta^n$ otherwise.

Algorithm 1: Proximal-Gradient dual: PGdual Invert and PGdual Ortho

Comparison of MCMC sampling schemes

Gaussian proposal: $\theta^{n+\frac{1}{2}} = \mu(\theta^n) + \sqrt{2\gamma}\Gamma\xi^{n+1}$

- random walks: $\mu(\theta) = \theta$

RW: $\Gamma = \mathbf{I}$; RW Invert: $\Gamma = \overline{\mathbf{D}}_2^{-1}\overline{\mathbf{D}}_2^{-\top}$; RW Ortho: $\Gamma = \overline{\mathbf{D}}_o^{-1}\overline{\mathbf{D}}_o^{-\top}$

- Proximal-Gradient dual: $\mu_R(\theta), \mu_O(\theta), \Gamma = \overline{\mathbf{D}}^{-1}\overline{\mathbf{D}}^{-\top}$

PGdual Invert: $\overline{\mathbf{D}} = \overline{\mathbf{D}}_2$; PGdual Ortho: $\overline{\mathbf{D}} = \overline{\mathbf{D}}_o$

Practical settings: $N_{\max} = 10^7$ iterations, 15 independent runs

Comparison of MCMC sampling schemes

Gaussian proposal: $\theta^{n+\frac{1}{2}} = \mu(\theta^n) + \sqrt{2\gamma}\Gamma\xi^{n+1}$

- random walks: $\mu(\theta) = \theta$

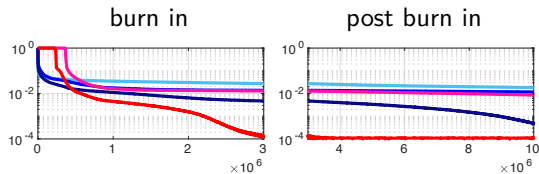
RW: $\Gamma = \mathbf{I}$; RW Invert: $\Gamma = \overline{\mathbf{D}}_2^{-1}\overline{\mathbf{D}}_2^{-\top}$; RW Ortho: $\Gamma = \overline{\mathbf{D}}_o^{-1}\overline{\mathbf{D}}_o^{-\top}$

- Proximal-Gradient dual: $\mu_R(\theta), \mu_O(\theta), \Gamma = \overline{\mathbf{D}}^{-1}\overline{\mathbf{D}}^{-\top}$

PGdual Invert: $\overline{\mathbf{D}} = \overline{\mathbf{D}}_2$; PGdual Ortho: $\overline{\mathbf{D}} = \overline{\mathbf{D}}_o$

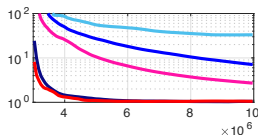
Practical settings: $N_{\max} = 10^7$ iterations, 15 independent runs

log-density



$$(\ln \pi(\theta^n) - \max \ln \pi) / (\ln \pi(\theta^0) - \max \ln \pi)$$

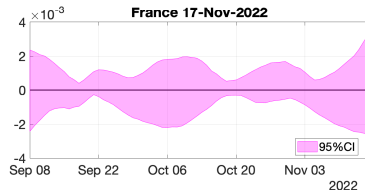
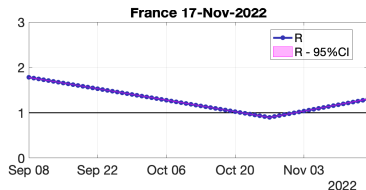
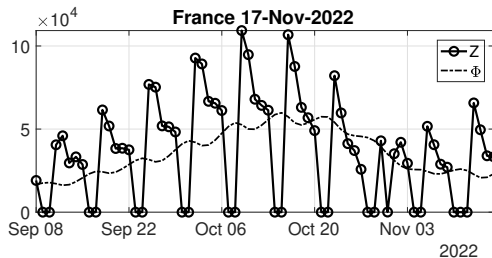
Gelman-Rubin



ANOVA-type criterion

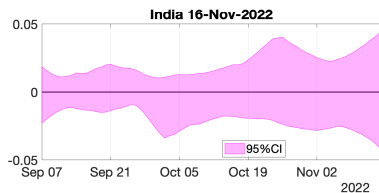
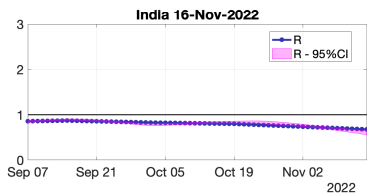
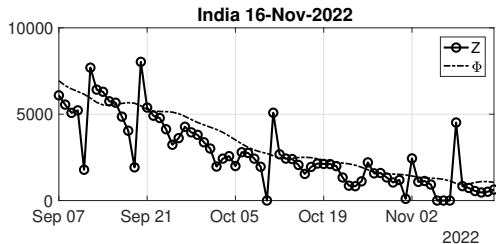
PGdual credibility interval estimation of the reproduction number

Sanitary situation in France



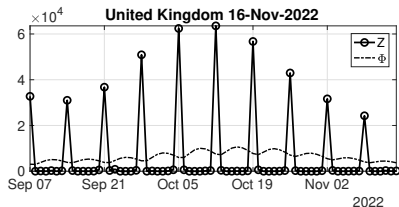
PGdual credibility interval estimation of the reproduction number

Worldwide Covid19 monitoring



Why not United Kingdom?

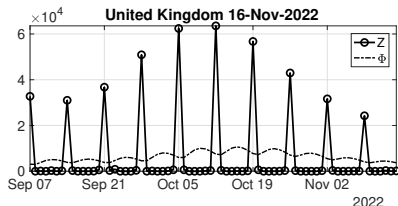
Why not United Kingdom?



rate of erroneous counts: 6/7!

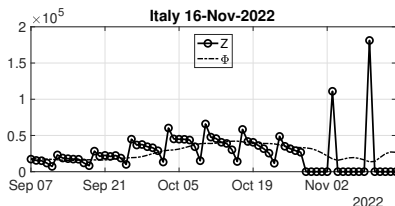
PGdual credibility interval estimation of the reproduction number

Why not United Kingdom?



rate of erroneous counts: 6/7!

And Italy?



seems to adopt the same reporting rate ...

⇒ call for new tools, robust to very scarce data

- ✓ Extended Cori model handling erroneous reported counts via a latent variable

$$Z_t | \mathbf{Z}_{t-\tau_\phi:t-1}, R_t, O_t \sim \text{Pois}(R_t \Phi_t + O_t)$$

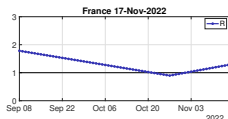
Conclusion

- ✓ Extended Cori model handling erroneous reported counts via a latent variable

$$Z_t | \mathbf{Z}_{t-\tau_\Phi:t-1}, \mathbf{R}_t, \mathbf{O}_t \sim \text{Pois}(\mathbf{R}_t \Phi_t + \mathbf{O}_t)$$

- ✓ Estimation of piecewise linear \mathbf{R}_t and corrected counts via convex optimization

$$\underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \sum_{t=1}^T d_{\text{KL}}(Z_t | \mathbf{R}_t \Phi_t + \mathbf{O}_t) + \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \iota_{\geq 0}(\mathbf{R}) + \lambda_O \|\mathbf{O}\|_1$$



$$\hat{R}_T = 1.1959$$

(Pascal et al., 2022, *Trans. Sig. Process.*;

)

Conclusion

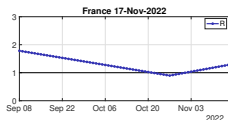
- ✓ Extended Cori model handling erroneous reported counts via a latent variable

$$Z_t | \mathbf{Z}_{t-\tau_\Phi:t-1}, \mathbf{R}_t, \mathbf{O}_t \sim \text{Pois}(\mathbf{R}_t \Phi_t + \mathbf{O}_t)$$

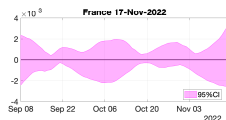
- ✓ Estimation of piecewise linear \mathbf{R}_t and corrected counts via convex optimization

$$\underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \sum_{t=1}^T d_{\text{KL}}(Z_t | \mathbf{R}_t \Phi_t + \mathbf{O}_t) + \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \iota_{\geq 0}(\mathbf{R}) + \lambda_O \|\mathbf{O}\|_1$$

- ✓ Bayesian credibility interval estimates via proximal Langevin MCMC samplers



$$\hat{R}_T = 1.1959$$



$$\hat{R}_T \in [1.1978, 1.2016]$$

(Pascal et al., 2022, *Trans. Sig. Process.*; Fort et al., 2022, *arXiv:2203.09142*)

→ Avoid mixing errors O_t with the pandemic mechanism $R_t\Phi_t$: anomaly models

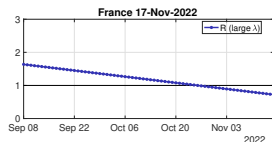
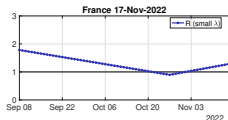
$$Z_t | \mathbf{Z}_{t-\tau_\Phi:t-1}, R_t, O_t \sim \text{Pois}((1 - e_t)R_t\Phi_t + e_t O_t), \quad e_t \in \{0, 1\}$$

→ Avoid mixing errors O_t with the pandemic mechanism $R_t\Phi_t$: anomaly models

$$Z_t | \mathbf{Z}_{t-\tau_\Phi:t-1}, R_t, O_t \sim \text{Poiss}((1 - e_t)R_t\Phi_t + e_t O_t), \quad e_t \in \{0, 1\}$$

→ Selection of regularization parameters λ_R, λ_O

$$\underset{(\mathbf{R}, \mathbf{O}) \in \mathbb{R}_+^T \times \mathbb{R}^T}{\text{minimize}} \sum_{t=1}^T d_{\text{KL}}(Z_t | R_t\Phi_t + O_t) + \lambda_R \|\mathbf{D}_2 \mathbf{R}\|_1 + \iota_{\geq 0}(\mathbf{R}) + \lambda_O \|\mathbf{O}\|_1$$



Juliana Du PhD thesis

→ Synthetic data

