

Dynamic Branch Prediction

- In deeper and superscalar pipelines, branch penalty is more significant
- Use dynamic prediction
 - Branch prediction buffer (aka branch history table)
 - Indexed by recent branch instruction addresses
 - Stores outcome (taken/not taken)
 - To execute a branch
 - Check table, expect the same outcome
 - Start fetching from fall-through or target
 - If wrong, flush pipeline and flip prediction

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1-Bit Predictor

```
addi $t0, $0, 4
addi $t1, $0, 1
```

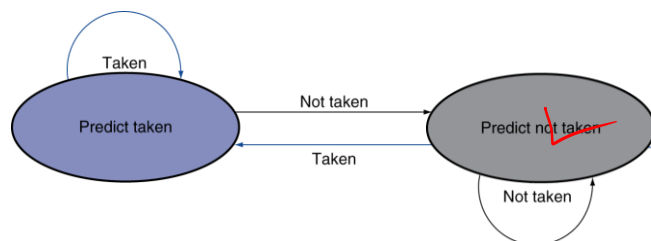
→ OUT:

```
addi $t2, $0, 1
```

IN:

```
addi $t2, $t2, 1
bne $t2, $t0, IN ←
    4 4
```

```
addi $t1, $t1, 1
bne $t1, $t0, OUT
    4 4
```

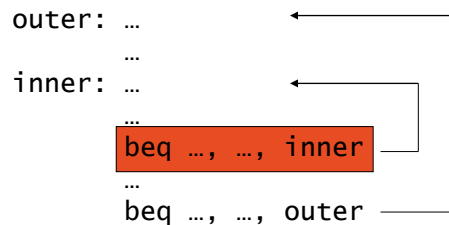


Initial predict: Not Take			
IN		Out	
Correct	Incorrect	Correct	Incorrect
+++			

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1-Bit Predictor: Shortcoming

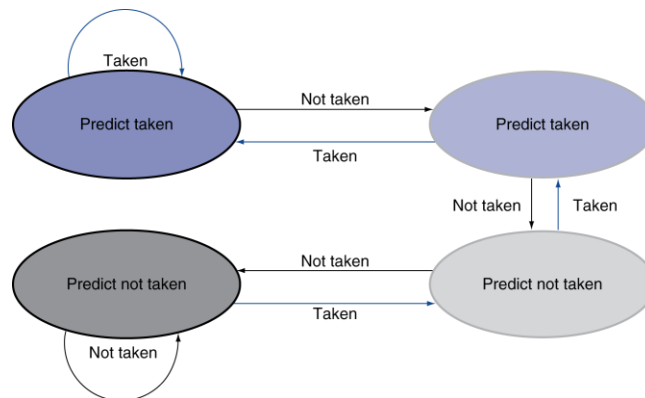
- Inner loop branches mispredicted twice!
 - Mispredict as taken on last iteration of inner loop
 - Then mispredict as not taken on first iteration of inner loop next time around



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2-Bit Predictor

- Only change prediction on two successive mispredictions



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Calculating the Branch Target

- Even with predictor, still need to calculate the target address
 - 1-cycle penalty for a taken branch
- Branch target buffer
 - Cache of target addresses
 - Indexed by PC when instruction fetched
 - If hit and instruction is branch predicted taken, can fetch target immediately

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Exceptions and Interrupts

- “Unexpected” events requiring change in flow of control
 - Different ISAs use the terms differently
- Exception
 - Arises within the CPU
 - e.g., undefined opcode, overflow, syscall, ...
- Interrupt
 - From an external I/O controller
- Dealing with them without sacrificing performance is hard

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Handling Exceptions

- In MIPS, exceptions managed by a System Control Coprocessor (CP0)
- Save PC of offending (or interrupted) instruction
 - In MIPS: Exception Program Counter (EPC)
- Save indication of the problem
 - In MIPS: Cause register
 - We'll assume 1-bit
 - 0 for undefined opcode, 1 for overflow
- Jump to handler at 8000 00180

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An Alternate Mechanism

- Vectored Interrupts
 - Handler address determined by the cause
- Example:

▪ Undefined opcode:	C000 0000
▪ Overflow:	C000 0020
▪ ...:	C000 0040
- Instructions either
 - Deal with the interrupt, or
 - Jump to real handler

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Handler Actions

- Read cause, and transfer to relevant handler
- Determine action required
- If restartable
 - Take corrective action
 - use EPC to return to program
- Otherwise
 - Terminate program
 - Report error using EPC, cause, ...

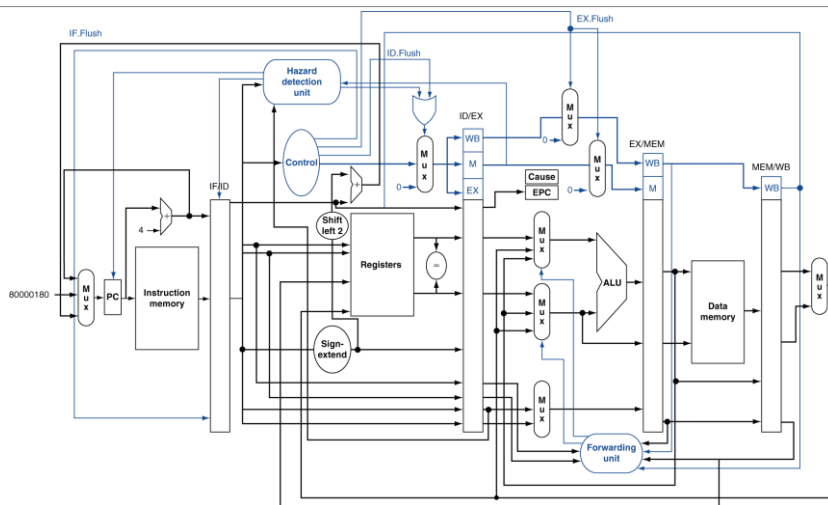
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Exceptions in a Pipeline

- Another form of control hazard
- Consider overflow on add in EX stage
 - add \$1, \$2, \$1
 - Prevent \$1 from being clobbered
 - Complete previous instructions
 - Flush add and subsequent instructions
 - Set Cause and EPC register values
 - Transfer control to handler
- Similar to mispredicted branch
 - Use much of the same hardware

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Pipeline with Exceptions



ALU overflow signal is an input to the control unit (not shown)

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Exception Properties

- Restartable exceptions
 - Pipeline can flush the instruction
 - Handler executes, then returns to the instruction
 - Refetched and executed from scratch
- PC saved in EPC register
 - Identifies causing instruction
 - Actually PC + 4 is saved
 - Handler must adjust

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Multiple Exceptions

- Pipelining overlaps multiple instructions
 - Could have multiple exceptions at once
- Simple approach: deal with exception from earliest instruction
 - Flush subsequent instructions
 - “Precise” exceptions
- In complex pipelines
 - Multiple instructions issued per cycle
 - Out-of-order completion
 - Maintaining precise exceptions is difficult!

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Imprecise Exceptions

- Just stop pipeline and save state
 - Including exception cause(s)
- Let the handler work out
 - Which instruction(s) had exceptions
 - Which to complete or flush
 - May require “manual” completion
- Simplifies hardware, but more complex handler software
- Not feasible for complex multiple-issue out-of-order pipelines

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