

#1.

$$\begin{aligned}\dot{x} &= rx + x^3 - x^5 \\ &= x(r + x^2 - x^4) \\ &\Rightarrow r = x^4 - x^2\end{aligned}$$

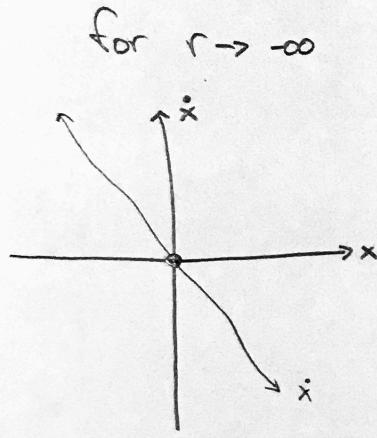
(looked up quartic solution)

if $x = \infty$
and $r = \infty$
 $\dot{x} = \infty$

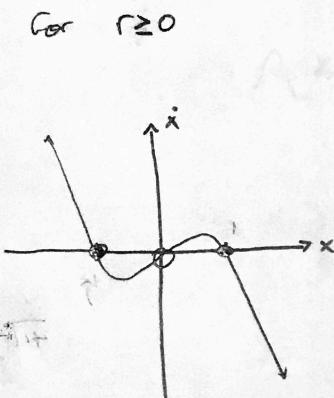
P1

$$x_c = 0, \pm \frac{\sqrt{1-\sqrt{4r+1}}}{\sqrt{2}}, \pm \frac{\sqrt{1+\sqrt{4r+1}}}{\sqrt{2}}$$

} 5 fixed points, matches
5th degree eq, according to
Fundamental Theorem of Algebra

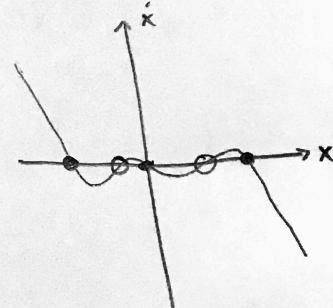


one critical point $x_c = 0$



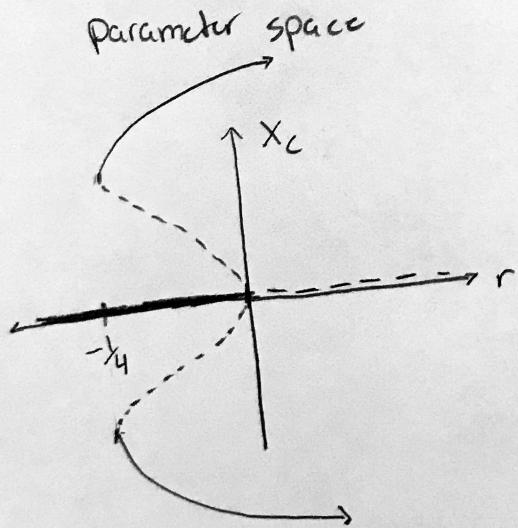
$$x_c = \pm \frac{\sqrt{1+\sqrt{4r+1}}}{\sqrt{2}}$$

for $-\lambda_4 \leq r < 0$



all 5 fixed points appear
in this region of r

The stability can be seen from the direction of the slope



Transcritical Bifurcation

the fixed point at $x_c = 0$ exists for $-\infty < r < 0$, however it changes stability at $r = 0$, but continues to exist for all values. The continual existence and exchange of stability is characteristic of a transcritical bifurcation

#2

$$\dot{x} = ax - bxy$$

$$\dot{y} = -cy + dx\dot{y}$$

$$a = \frac{b}{d}$$

$$c = \frac{d}{x}$$

$$\dot{x} = \frac{\partial x}{\partial t} \left[\frac{m}{s} \right]$$

$$\dot{y} = \frac{\partial y}{\partial t} \left[\frac{g}{s} \right]$$

variables: $[x, y, t]$ params $[a, b, c, d]$

params-dimensions = $\#$ of dimensions \rightarrow

$$4 - 3 = 1 \quad (\text{found to be } \left(\frac{c}{a} \right))$$

$$\dot{x} = \frac{[m]}{s} + \frac{[m][g]}{s^2 g}$$

$$a \left[\frac{1}{s} \right]$$

$$b \left[\frac{1}{g s} \right]$$

$$\dot{y} = \frac{[g]}{s} + \frac{[g][m]}{m s} \quad c \left[\frac{1}{s} \right]$$

$$d \left[\frac{1}{m s} \right]$$

$$\dot{x} = \frac{[m]}{(m s)} \left(\frac{s}{1} \right) = \frac{x \dot{d}}{a} \quad x = \dot{x} \left(\frac{a}{\dot{d}} \right)$$

$$\dot{y} = \frac{[g]}{(g s)} \left(\frac{s}{1} \right) = \frac{y \dot{b}}{a} \Rightarrow y = \dot{y} \left(\frac{a}{\dot{b}} \right)$$

$$t = [s] \left(\frac{1}{s} \right) = t a$$

$$t \in \sqrt{\frac{b}{s}} \approx t a$$

$$\begin{cases} \text{let } I = x \\ J = y \end{cases}$$

$$\frac{\partial \dot{x}}{\partial t} = \left(\frac{\partial \dot{x}}{\partial x} \right) \left(\frac{\partial t}{\partial t} \right) \left(\frac{\partial x}{\partial t} \right)$$

$$\frac{\partial \dot{y}}{\partial t} = \frac{\partial \dot{y}}{\partial y} \frac{\partial t}{\partial t} \frac{\partial y}{\partial t}$$

$$\frac{\partial \dot{x}}{\partial x} = \frac{\partial}{\partial x} \left[\frac{1}{m s} \right] \left[\frac{s}{1} \right]$$

$$\frac{\partial \dot{y}}{\partial y} = \frac{b}{a} \left[\frac{1}{g s} \right] [s]$$

$$\frac{\partial t}{\partial t} = \frac{1}{a} \left[\frac{s}{1} \right]$$

$$\frac{\partial t}{\partial t} = \frac{1}{a} \left[\frac{s}{1} \right]$$

$$\frac{\partial \dot{x}}{\partial t} = \left(\frac{\partial}{\partial a} \right) \left(\frac{1}{a} \right) (ax - bxy) + \left[\frac{s}{m} \right] \left[\frac{m}{s} - \frac{m}{s} \right] = \frac{\partial x}{a} - \frac{\partial bxy}{a^2} = \underbrace{\frac{\partial}{\partial a} (ax - bxy)}_{\dot{x}} = \dot{x}$$

$$\frac{\partial \dot{y}}{\partial t} = \left(\frac{\partial}{\partial b} \right) \left(\frac{1}{a} \right) (-cy + dx\dot{y}) + \left[\frac{s}{g} \right] \left[\frac{g}{s} + \frac{g}{s} \right] = -\frac{by}{a} + \frac{bdxy}{a^2} = \underbrace{\frac{b}{a^2} (-cy + dx\dot{y})}_{\dot{y}} = \dot{y}$$

$$\frac{\partial^2}{\partial a^2} (\dot{x}) = a \left(\frac{\partial}{\partial a} \right)^2 (x) - b \left(\frac{\partial}{\partial a} \right) \left(\frac{\partial}{\partial b} \right) (y)$$

$$\dot{y} = \dot{y} \left(\frac{a^2}{b} \right) = -c \dot{y} \left(\frac{a}{b} \right) + d \left(\frac{\partial}{\partial a} \right) \left(\frac{\partial}{\partial b} \right) (y)$$

$$\rightarrow \dot{x} = \dot{x} - \dot{x} \dot{y}$$

$$\dot{y} = -\dot{y} \left(\frac{a}{b} \right) + \frac{\partial}{\partial a} (y)$$

dimensionless param.

$$\text{Jacobian} = \begin{pmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{pmatrix} = \begin{pmatrix} 1-\tilde{y} & -\tilde{x} \\ \tilde{y} & -\frac{c}{a} + \tilde{x} \end{pmatrix}$$

(P3)

fixed points or dimensionless

$$\dot{x}=0 = \dot{x} - \tilde{x}\tilde{y}$$

$$\dot{y}=1 \Rightarrow \dot{y}(1)=0 = (1)\left(\frac{c}{a}\right) + \tilde{x}(1)$$

$$\tilde{x}_c = \frac{c}{a}$$

$$(\tilde{x}_c, \tilde{y}_c) = \left(\frac{c}{a}, 1\right)$$

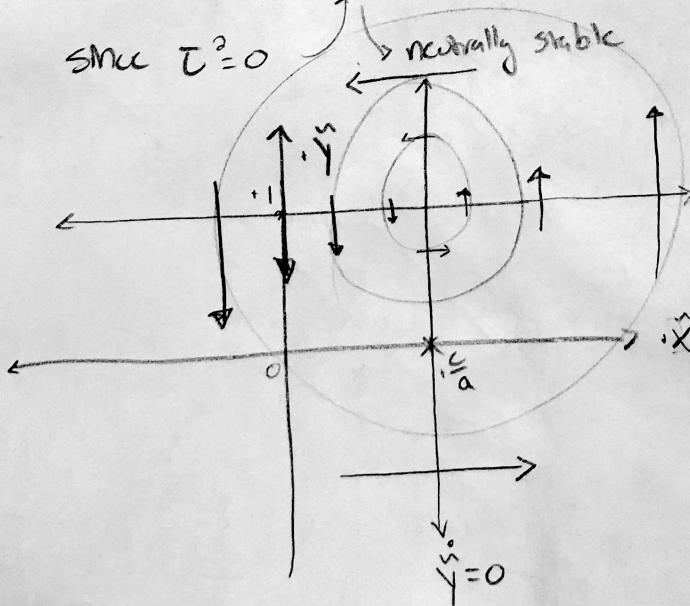
$$\text{Jac} \left(\frac{c}{a}, 1 \right) = \begin{pmatrix} 1-1 & -\frac{c}{a} \\ 1 & -\frac{c}{a} + \frac{c}{a} \end{pmatrix} = \begin{pmatrix} 0 & -\frac{c}{a} \\ 1 & 0 \end{pmatrix}$$

$$\lambda = \frac{c \pm \sqrt{c^2 - 4\Delta}}{2} = \pm \sqrt{-4\frac{c}{a}} = \pm \sqrt{-\frac{c}{a}} \quad \text{Imaginary}$$

$$c, a > 0 \quad \Delta = \frac{c}{a} > 0$$

$$c, a > 0$$

$$c^2 - 4\Delta < 0 = \text{spirals/centers}$$



for $\tilde{y} \rightarrow \infty$

$$\dot{x}=0 = \dot{x} - \tilde{x}\tilde{y} \rightarrow -\infty$$

$$\tilde{y} \rightarrow -\infty \quad \dot{x} - \tilde{x}\tilde{y} \rightarrow \infty$$

for $\tilde{x}=0$

$$\dot{y}=0 = -\frac{c}{a}\tilde{y} + 0$$

$$\Rightarrow -\frac{c}{a}\tilde{y} < 0 \quad \text{for } \tilde{y} > 0$$

for $\tilde{x} \rightarrow \infty$

$$-\frac{c}{a}\tilde{y} + \tilde{x}\tilde{y} \rightarrow \infty$$

#3. Particular system involving

(P4)

$$\text{energy } E \rightarrow \left[\frac{\text{kg} \cdot \text{m}^2}{\text{s}^2} \right] \rightarrow \frac{\text{mass}}{\text{time}^2}$$

$$\text{density } D \rightarrow \left[\frac{\text{kg}}{\text{m}^3} \right] \rightarrow \frac{\text{mass}}{\text{length}^3}$$

$$\begin{aligned} \text{radius } R &\rightarrow [m] & \rightarrow \text{length} \\ \text{time } t &\rightarrow [s] & \rightarrow \text{time} \end{aligned}$$

Dimensions [mass, length, time]

Buckingham pi theorem

Parameters - Dimensions = Dimensionless parameters

$$4 - 3 = 1$$

$$\left(\frac{\text{kg} \cdot \text{m}^2}{\text{s}^2} \right) \left(\frac{\text{m}^3}{\text{kg}} \right) \left(\text{s}^2 \right) \left(\frac{1}{\text{m}^5} \right)$$

$$(E) \left(\frac{1}{D} \right) (t^2) \left(\frac{1}{R^5} \right) = \text{dimensionless} = [1]$$

#4.

$$\dot{x} = a(1-x) - xy^2 \quad \dot{y}(y_c=0) =$$

$$\dot{y} = xy^2 - (a+b)y \rightarrow y_c = 0$$

$$\rightarrow y_c = \frac{a+b}{x}$$

(P5)

$$\dot{x}(y=0) = a(1-x) = 0 \rightarrow x_c = 1 \quad s_p(1,0)$$

$$\dot{x}\left(y=\frac{a+b}{x}\right) = a\left(1-x\right) - x\left(\frac{a+b}{x}\right)^2 = 0$$

$$= a - ax - \frac{(a+b)^2}{x} = 0$$

$$-ax^2 + ax - (a+b)^2 = 0$$

$$x_c = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} = \frac{-a \pm \sqrt{a^2 + 4(a)(a+b)^2}}{-2a} = \frac{-a \pm \sqrt{a^2 - 4a(a+b)^2}}{2a}$$

If $\sqrt{a^2 - 4a(a+b)^2} < 0$, x_c is imaginary

" " > 0 , x_c exists thus when

$$\underbrace{\sqrt{a^2 - 4a(a+b)^2}}_{} = 0 \quad \text{the fixed points suddenly}$$

appear, characteristic at a bifurcation point, specifically a saddle-node bifurcation

$$\Rightarrow a^2 - 4a(a+b)^2 = 0$$

$$\frac{a}{4} = (a+b)^2$$

$$\Rightarrow b_c = \frac{\sqrt{a}}{2} - a$$