

7.1.2 $\dot{r} = r(1-r^2)(9-r^2)$ $r_c = \pm 1, \pm 3$ (0)
 $\dot{\theta} = 1$

Jacobian $\begin{pmatrix} \frac{\partial \dot{r}}{\partial x} & \frac{\partial \dot{r}}{\partial y} \\ \frac{\partial \dot{\theta}}{\partial x} & \frac{\partial \dot{\theta}}{\partial y} \end{pmatrix} = \begin{pmatrix} 9-30r^2+5r^4 & 0 \\ 0 & 0 \end{pmatrix}$

$J(\pm 1):$

$\begin{pmatrix} -16 & 0 \\ 0 & 0 \end{pmatrix}$

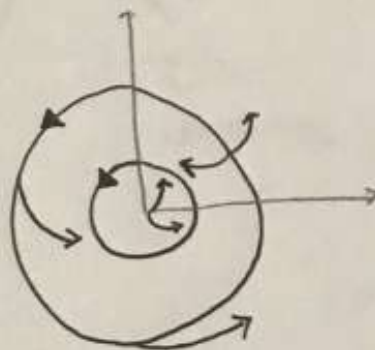
$\tau < 0$
stable

$J(\pm 3):$

$\begin{pmatrix} 144 & 0 \\ 0 & 0 \end{pmatrix}$

$\tau > 0$ unstable

for all $r, \dot{\theta} = 1$



7.1.3

$$\dot{r} = r(1-r^2)(4-r^2)$$

$$r_c = \pm 1, \pm 2 \quad (0)$$

$$\dot{\theta} = 2 - r^2$$

at

$$\dot{\theta}(\pm 1) > 0, \dot{\theta}(\pm 2) < 0$$

Jacobian:

$$\begin{pmatrix} \frac{\partial \dot{r}}{\partial r} & \frac{\partial \dot{r}}{\partial \theta} \\ \frac{\partial \dot{\theta}}{\partial r} & \frac{\partial \dot{\theta}}{\partial \theta} \end{pmatrix} = \begin{pmatrix} 4-15r^2+5r^4 & 0 \\ -2r & 0 \end{pmatrix}$$

$$J(\pm 1)$$

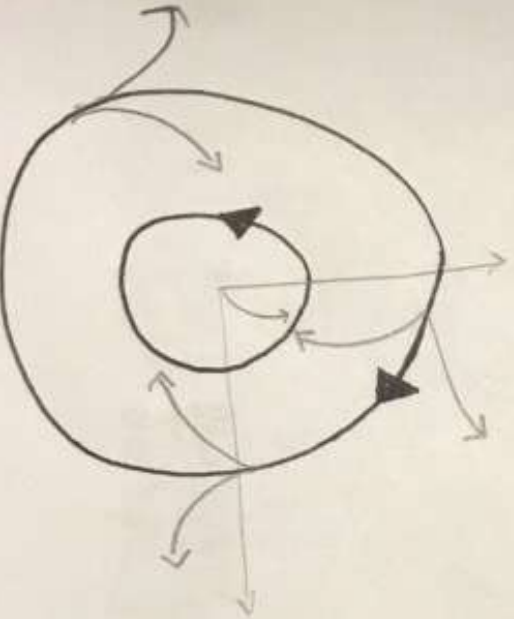
$$\begin{pmatrix} -6 & 0 \\ \pm 2 & 0 \end{pmatrix}$$

$\tau < 0$
stable

$$J(\pm 2)$$

$$\begin{pmatrix} 24 & 0 \\ \pm 4 & 0 \end{pmatrix}$$

$\tau > 0$
unstable



#7.1.6

P3

a)

current
voltage across a capacitor is
known to be

$$i = C_{ap} \frac{\partial V}{\partial t}$$

$$\Rightarrow \frac{\partial V}{\partial t} = \dot{V} = \frac{i}{C_{ap}}$$

using the governing equations of Kirchhoff's Law

$$\text{we know } V_S = V_C + V_L$$

and when i is low $V_S = -V_L$

(from question "negative resistor" at low current)

thus

$$V_C = V_S + V_L$$

$$V_C = f(i) + L \frac{\partial i}{\partial t}$$

$$b) \frac{\partial \omega}{\partial \tau} = \frac{\partial \omega}{\partial t} \left(\frac{\partial t}{\partial \tau} \right)$$

$$\frac{\partial \omega}{\partial t} \left(\frac{\partial t}{\partial \tau} \right) = \frac{C^{1/2} (-i) (LC)^{1/2}}{C}$$

$$\omega = C^{1/2} V$$

$$\Rightarrow \frac{\partial \omega}{\partial \tau} = -i \sqrt{L}$$

$$\frac{\partial \omega}{\partial t} = C^{1/2} \frac{\partial V_C}{\partial t} = C^{1/2} \left(\frac{-i}{C_{ap}} \right)$$

$$\text{where } x = i \sqrt{L}$$

$$\frac{\partial \omega}{\partial \tau} = -x$$

$$\frac{\partial \tau}{\partial t} \tau = t (LC)^{1/2}$$

$$\frac{\partial \tau}{\partial t} = (LC)^{-1/2}$$

7.3.1

$$\dot{x} = x - y - x(x^2 + 5y^2) = f$$

$$\dot{y} = x + y - y(x^2 + y^2) = g$$

p4

a) fixed point @ (0,0)

Jacobian

$$\begin{pmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{pmatrix} = \begin{pmatrix} 1-3x^2-5y^2 & -1-10yx \\ 1-2yx & 1-x^2-3y^2 \end{pmatrix} \bigg|_{(0,0)} = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$$

$$\tau = 2 > 0 \text{ unstable}$$

$$\Delta = 2$$

$$\tau^2 - 4\Delta < 0 \text{ spiral}$$

b) rewrite in polar: $r\dot{r} = x\dot{x} + y\dot{y}$, $\dot{\theta} = \frac{(x\dot{y} - y\dot{x})}{r^2}$

$$r\dot{r}(f,g) = x(x - y - x(x^2 + 5y^2)) + y(x + y - y(x^2 + y^2))$$

$$= x^2 - xy - x^2(x^2 + 5y^2) + yx + y^2 - y^2(x^2 + y^2)$$

$$= \underbrace{x^2 + y^2}_{r^2} - \underbrace{x^4 + y^4}_{(x^2+y^2)(x^2+y^2)} - 6x^2y^2$$

$$= r^2 - (x^4 + y^4) - 6x^2y^2$$

$$= r^2 - (x^2 + y^2)^2 - 2x^2y^2$$

$$= r^2 - r^4 + 2x^2y^2 - 6x^2y^2 = r^2 - r^4 - 4x^2y^2$$

$$= r^2 - r^4 - 4(r\cos\theta)^2(r\sin\theta)^2$$

$$r\dot{r} = r^2(1 - r^2 - 4r^2\cos^2\theta\sin^2\theta)$$

$$\dot{r} = r(1 - r^2 - 4r^2\cos^2\theta\sin^2\theta)$$

$$\begin{aligned}
 r^2 \ddot{\theta} &= (x\dot{y} - y\dot{x}) = x(x + y - y(x^2 + y^2)) - y(x - y - x(x^2 + y^2)) \\
 &= x^2 + xy - yx - y^2(x^2 + y^2) - yx + y^2 + yx + y^2(x^2 + y^2) \\
 &= x^2 + y^2 + y^3x = r^2 + 4(r \sin \theta)^3 (r \cos \theta)
 \end{aligned}$$

$$\ddot{\theta} r^2 = r^2 (1 + 4r^2 \sin^3 \theta \cos \theta)$$

$$\left[\begin{aligned} \dot{\theta} &= 1 + 4r^2 \sin^3 \theta \cos \theta \\ \dot{r} &= r - r^3 (1 + 4 \cos^2 \theta \sin^2 \theta) \end{aligned} \right]$$

c) Determine r_{\max} such that all trajectories have radially outward for any θ $\dot{r} > 0$

$$(\sin \theta \cos \theta) \text{ maximised @ } \theta = \frac{\pi}{4}$$

$$(\sin \frac{\pi}{4})(\sin \frac{\pi}{4})(\cos \frac{\pi}{4})(\cos \frac{\pi}{4}) = (\frac{\sqrt{2}}{2})(\frac{\sqrt{2}}{2})(\frac{\sqrt{2}}{2})(\frac{\sqrt{2}}{2}) = \frac{4}{16} = \frac{1}{4}$$

$$\dot{r} = r - r^3 \left(1 + 4\left(\frac{1}{4}\right)\right) = r - 2r^3 > 0$$

$$r(1 - 2r^2) > 0 \text{ true for}$$

$$0 < r < \frac{1}{\sqrt{2}}$$

max radius
outward

$$\dot{r} = -1 < 0$$

d) Determine minimum radius such that all ^{any θ} trajectories meet (P.C.)
radially ^{inward} outward comp.

$$\dot{r} = r - r^3 (1 + 4\cos^3\theta \sin^2\theta) < 0$$

\nwarrow minimum

$$\dot{r} < 0$$

($\sin\theta \cos\theta$) minimized @ $\theta = 0, \pi$

$$\sin(0)\sin(0)\cos(0)\cos(0) = 0$$

with radius inward

$$\dot{r} = r - r^3 < 0 \quad r_c = 1$$

if $r < 1$ true for $\forall \theta$
 $\dot{r} > 0$ $\forall \theta$ $r > 1$

e) $r = \sqrt{2}$ is the maximum radius for outward radially $r = 1$ is minimum radius for inward radially

these radii form the boundaries of a confined trajectory excluding the point $(0,0)$ this satisfies the Poincaré-Bendixon theorem conditions and lead to the conclusion that a limit cycle exists in the bounded region of r
 $\sqrt{2} < r < 1$