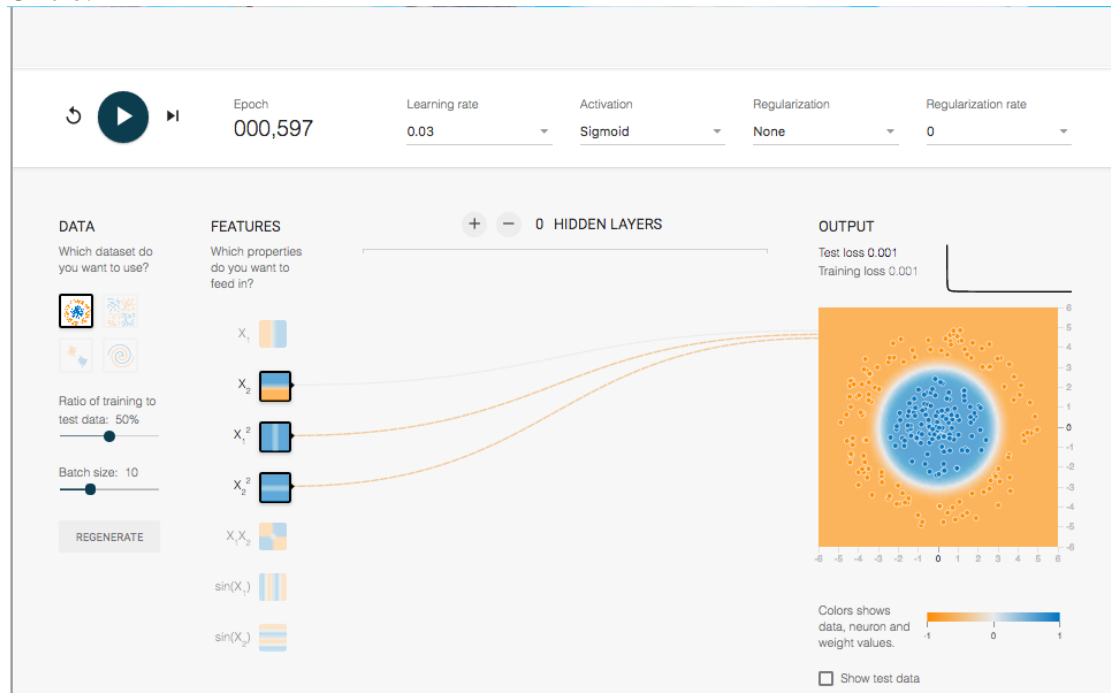


Brandon Peck  
CS4501 - Machine Learning  
Homework 3

1.1

	Features	Iterations	Test Loss
Circle	$X_2, X_1^2, X_2^2$	573	0.001
Exclusive OR	$X_1 X_2$	421	0.001
Gaussian	$X_1, X_2$	326	0.001
Spiral	$\sin(X_1), \sin(X_2)$	757	0.530

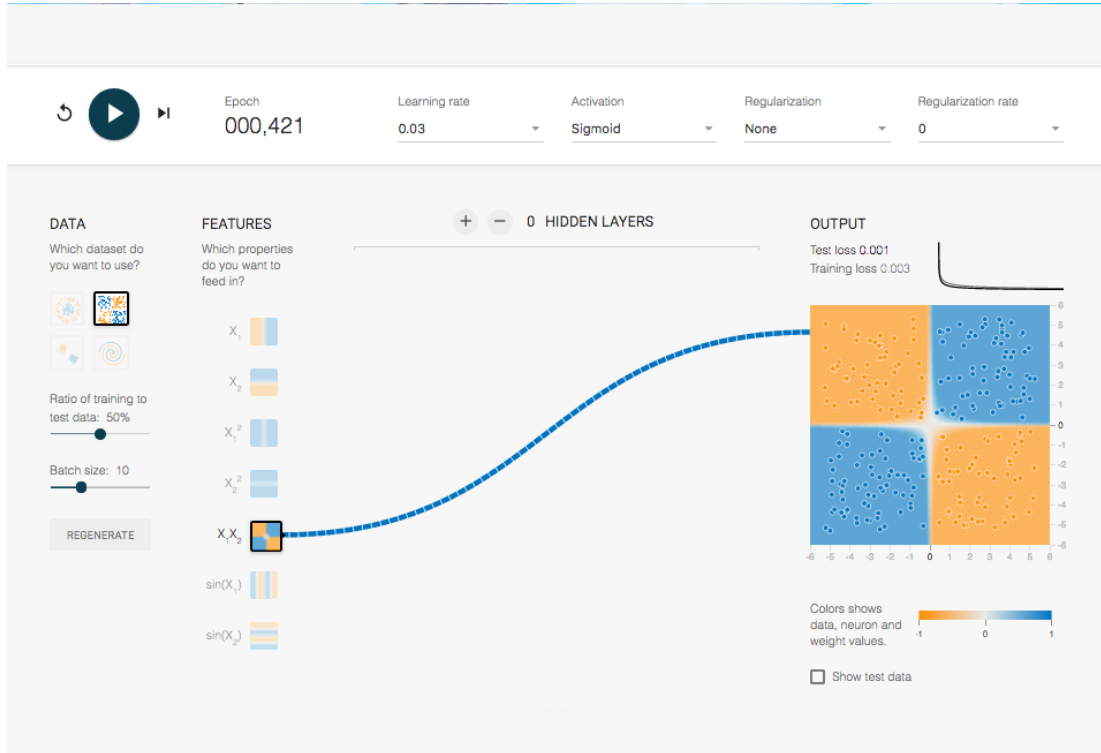
Circle:



Intuition:

From this configuration we see that  $X_1^2$  and  $X_2^2$  are the perceptrons primarily used to create the model. This is because the model creates a circle around the data points. We know that the equation of a circle is  $(X_1 - h)^2 + (X_2 - k)^2 = r^2$ , so it is up to the model to determine the coefficients and radius.

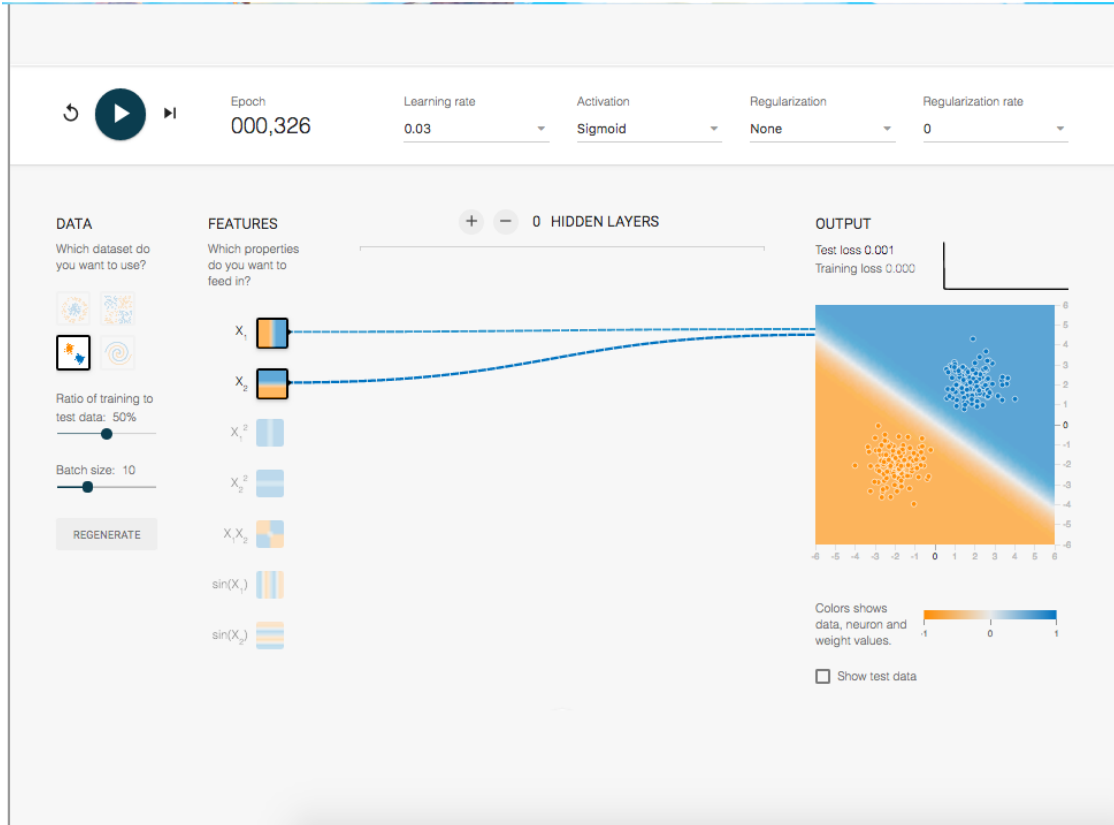
## Exclusive OR:



### Intuition:

From this configuration we see that the  $X_1X_2$  perceptron creates the most accurate model around exclusive or. Setting  $X_1X_2$  to a constant, we can divide by  $X_2$  and easily see how the function models the  $1/X$  equation, so  $X_1 = c/X_2$  and creates an accurate separation of data points across exclusive or.

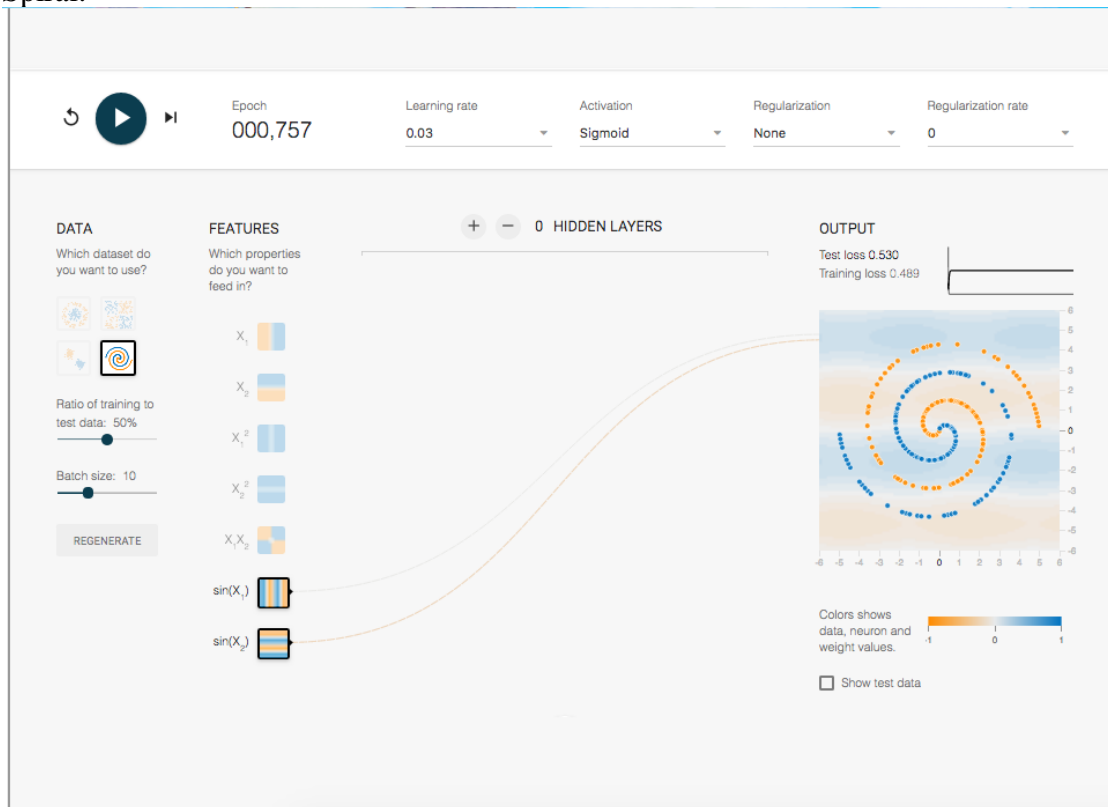
## Gaussian:



### Intuition:

From this configuration we can see that the  $X_1$  and  $X_2$  perceptrons create the best model across the Gaussian distribution. Since there is a clear dividing line across the data the equation  $X_1 = c * X_2$ , where in this case  $c$  is negative, creates an accurate model.

## Spiral:



## Intuition:

Modeling this set of data points is not as straight forward since a function following the spiral is not continuous. Because the data is distributed in “waves” across both axes, I chose to create a model with  $\sin(X_1) \sin(X_2)$ . However the Test loss of the model is too poor to say the model is accurate so I cannot conclude some equation with  $\sin(X_1)$  and  $\sin(X_2)$  models the data.

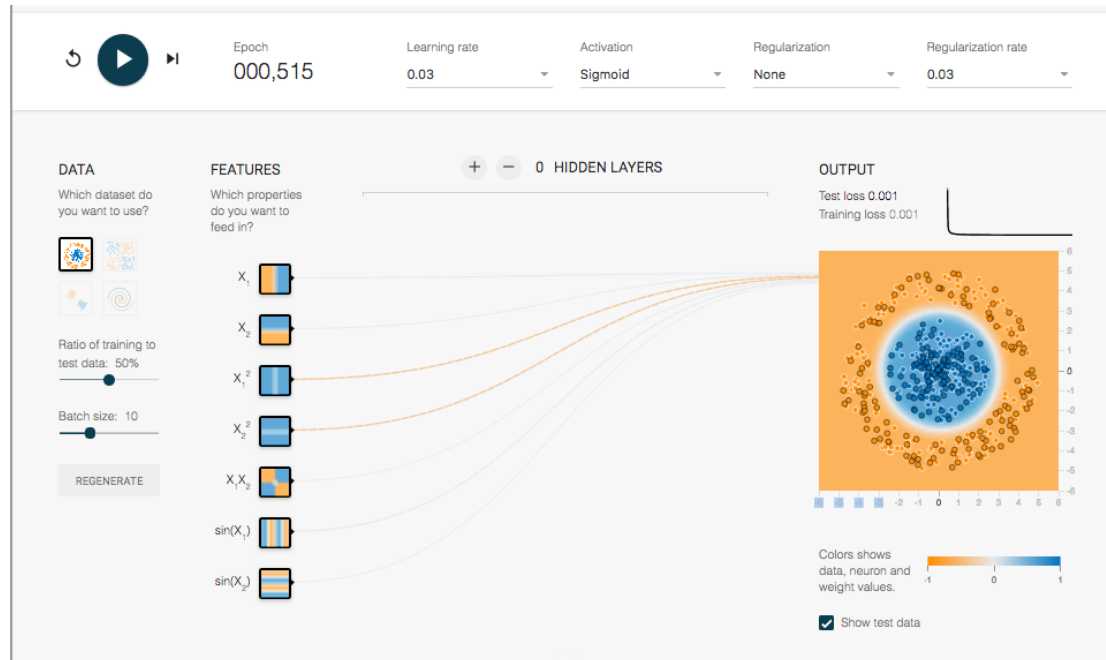
1.2

Task A:

Evaluations were performed with Epochs = 500, Regularization Rate = 0.03, Batch Size = 10, Test:Train = 1:1

	Estimated Decision Boundary	Test Loss
<b>Circle</b>	None: $x^2+y^2=9$ L1: $x^2+y^2=9$ L2: $x^2+y^2=9$	<b>None: 0.001</b> L1: 0.005 L2: 0.002
<b>Exclusive OR</b>	None: $(x=0.2, y=0)$ L1: $(x=0.2, y=0)$ L2: $(x=0.2, y=0)$	<b>None: 0.003</b> L1: 0.013 L2: 0.012
<b>Gaussian</b>	None: $x=0, y=-2$ L1: $y = -x$ L2: $y = -x$	<b>None: 0.000</b> L1: 0.006 L2: 0.002

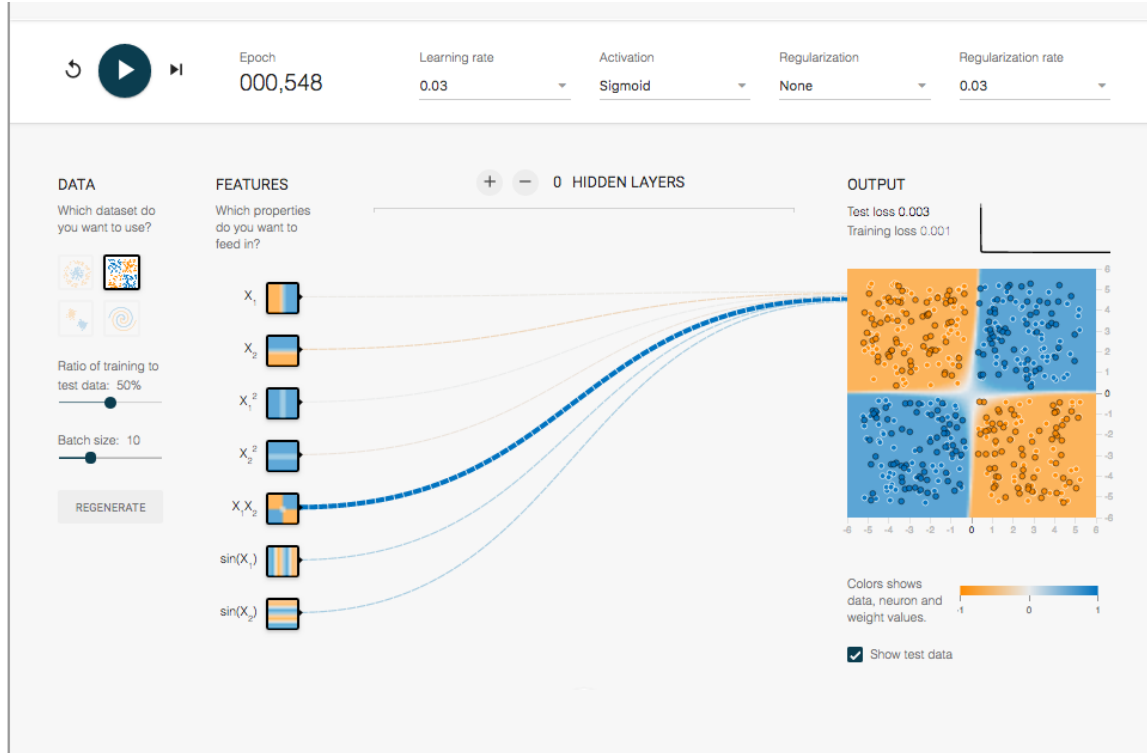
Circle:



Intuition:

$X_1^2$  and  $X_2^2$  with no regularization formed the decision boundary around the circle data points. As stated in the previous problem it is clear that these two perceptrons create the best models around the data because they can be trained to set the decision boundary around the data to a circle. The most successful model was the one without L1 or L2 regularization because the test and train data was so similar that a well fitted model to the train data accurately model the test data.

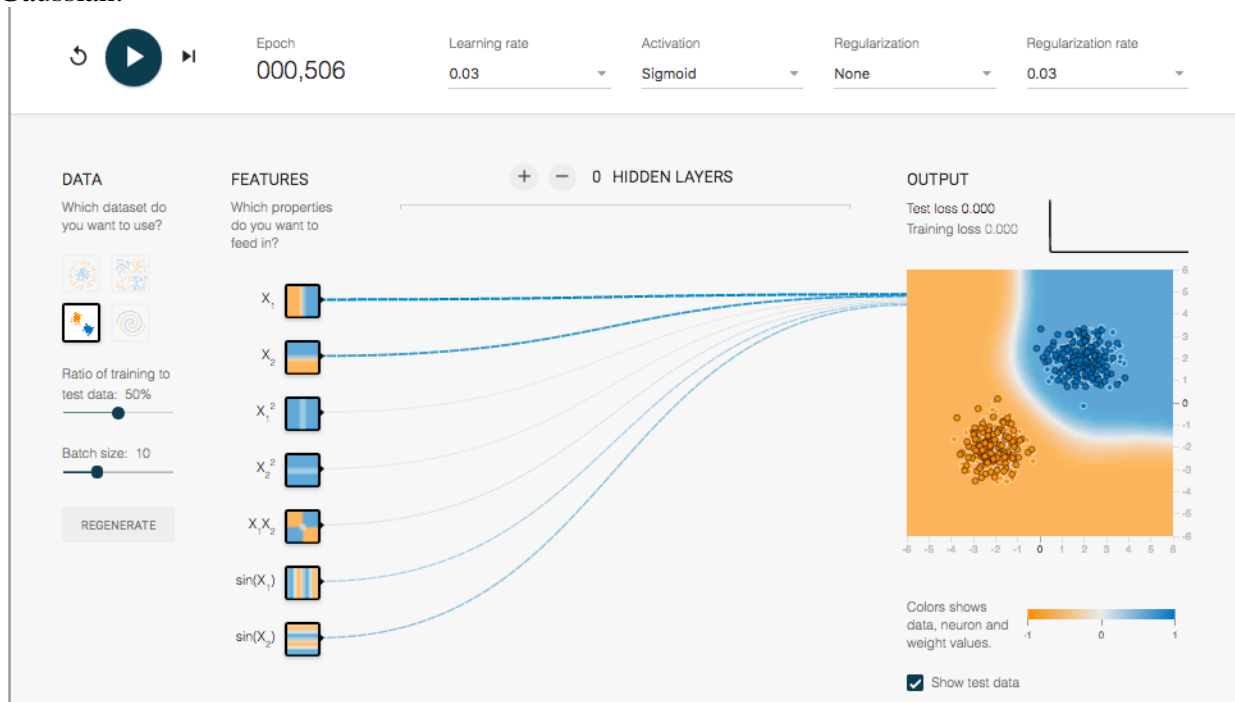
Exclusive OR:



Intuition:

The  $X_1X_2$  perceptron has the highest weights as predicted in the previous question because of its ability to create a decision boundary modeling the  $1/X$  equation. This model also uses the sine function across both the vertical and horizontal axes which we can assume allow the model to be less straight. Again, the most successful model was the one without L1 or L2 regularization because the test and train data was so similar that a well fitted model to the train data accurately model the test data.

## Gaussian:



### Intuition:

Like in the previous question we see that  $X_1$  and  $X_2$  have the highest weights contributing to the decision boundary. In this model, sine equations are used as well, creating a closer fit to the training data.

Like in the previous questions, the most successful model was the one without L1 or L2 regularization because the test and train data was so similar that a well fitted model to the train data accurately model the test data. However, if the distribution had more outlier points we could presume that a regularized model could create a more accurate decision boundary around the points.

Task B:

The features with higher weights were the ones used in the previous question. Below is a table of the feature weights for each data distribution. I bolded the most relevant features for each set of data.

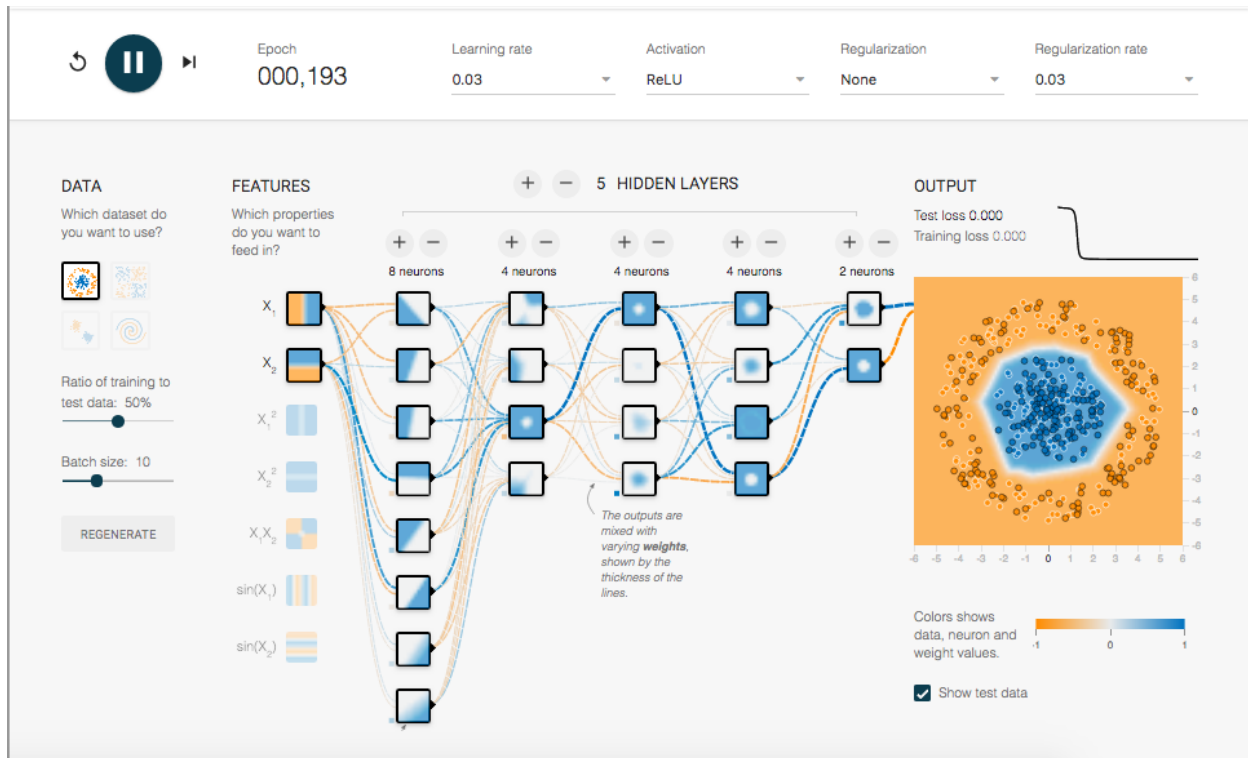
	$X_1$	$X_2$	$X_1^2$	$X_2^2$	$X_1 X_2$	$\sin(X_1)$	$\sin(X_2)$
Circle	-.011	-.016	<b>.29</b>	<b>.27</b>	.0023	0	.05
XOR	.011	-.13	-.015	-.01	<b>1.6</b>	.083	.14
Gaussian	<b>.41</b>	<b>.53</b>	-.045	.012	-.047	.47	<b>.71</b>



1.3

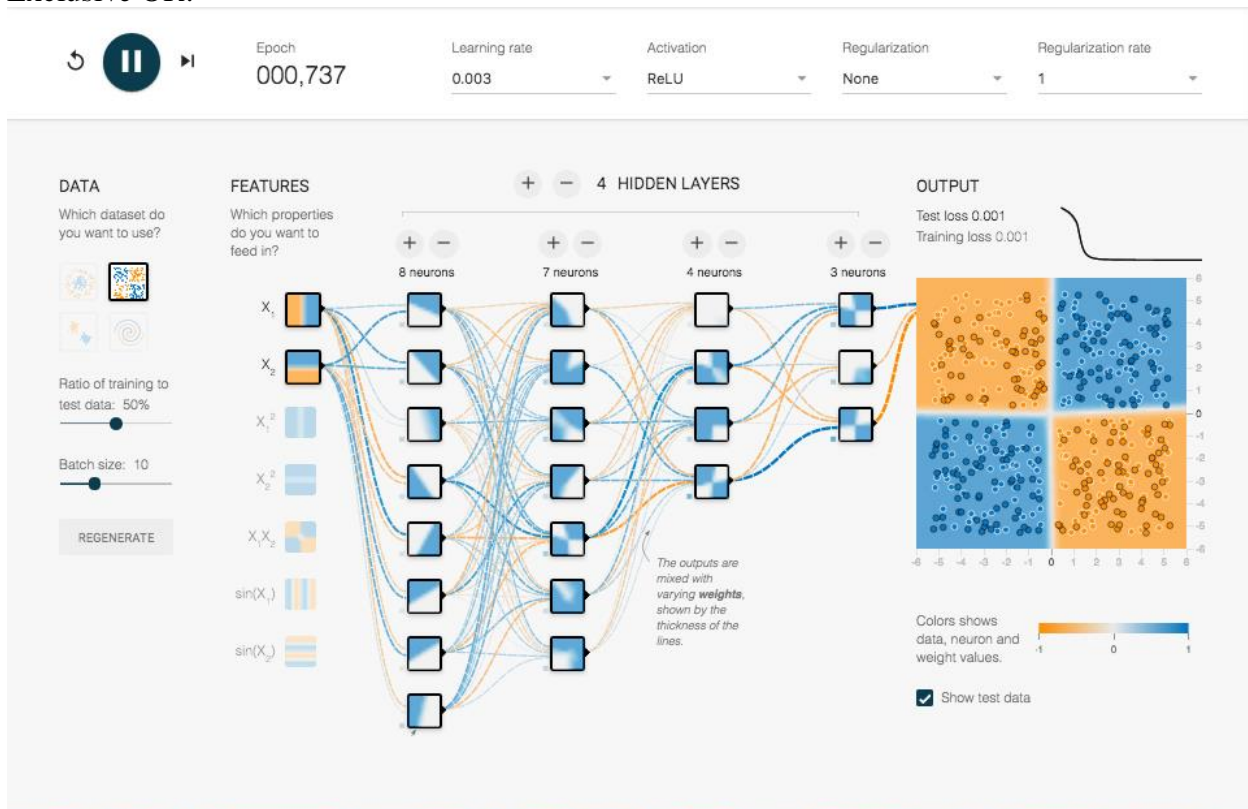
For this question I changed the activation function to reLU since this does not change the gradient for large input values, creating potentially more accurate and quicker learning. To find an accurate model I started with a large number of neurons and depth and decreased the number of neurons in a layer if I saw the layer contained a neuron that had a very low weight. Removing more neurons also appeared to increase the bias of the model which I found helpful when modeling the Exclusive Or data.

Circle:



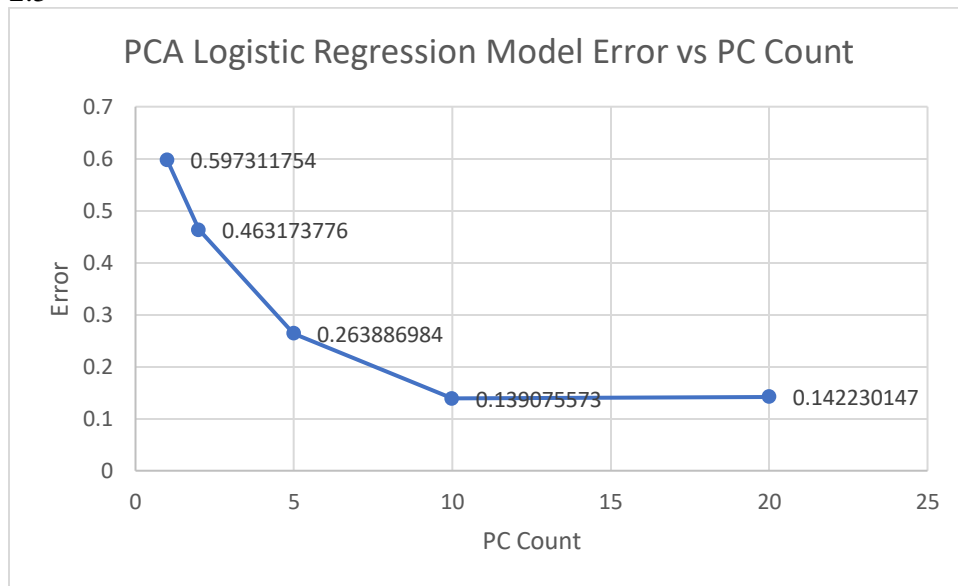
The test loss for this is 0 and the model was created in only 193 iterations. I used the reLU activation function. This beats the .01 test loss I had for question 1.1. I believe this model works because multiple hidden layers allow for single reLU regressions to be combine to create a circular model around the data.

Exclusive OR:



The test loss for this is .01 and the model was created in only 193 iterations. I used the reLU activation function. This ties the .01 test loss I had for question 1.1. I believe this model works because multiple hidden layers allow for single reLU regressions to combine to model the  $1/x$  equation from question 1.1 across several layers of depth.

2.5



Since I was not given the labels for the test data, I scored the regression model on its train data. While this isn't going to show the actual accuracy of the model, it does still show how the accuracy changes with reduced PCs. The error follows a logistic curve with respect to the PC count, where the error decreases as the number of PCs increases. This seems fairly intuitive as more features creates a model that better fits the data.

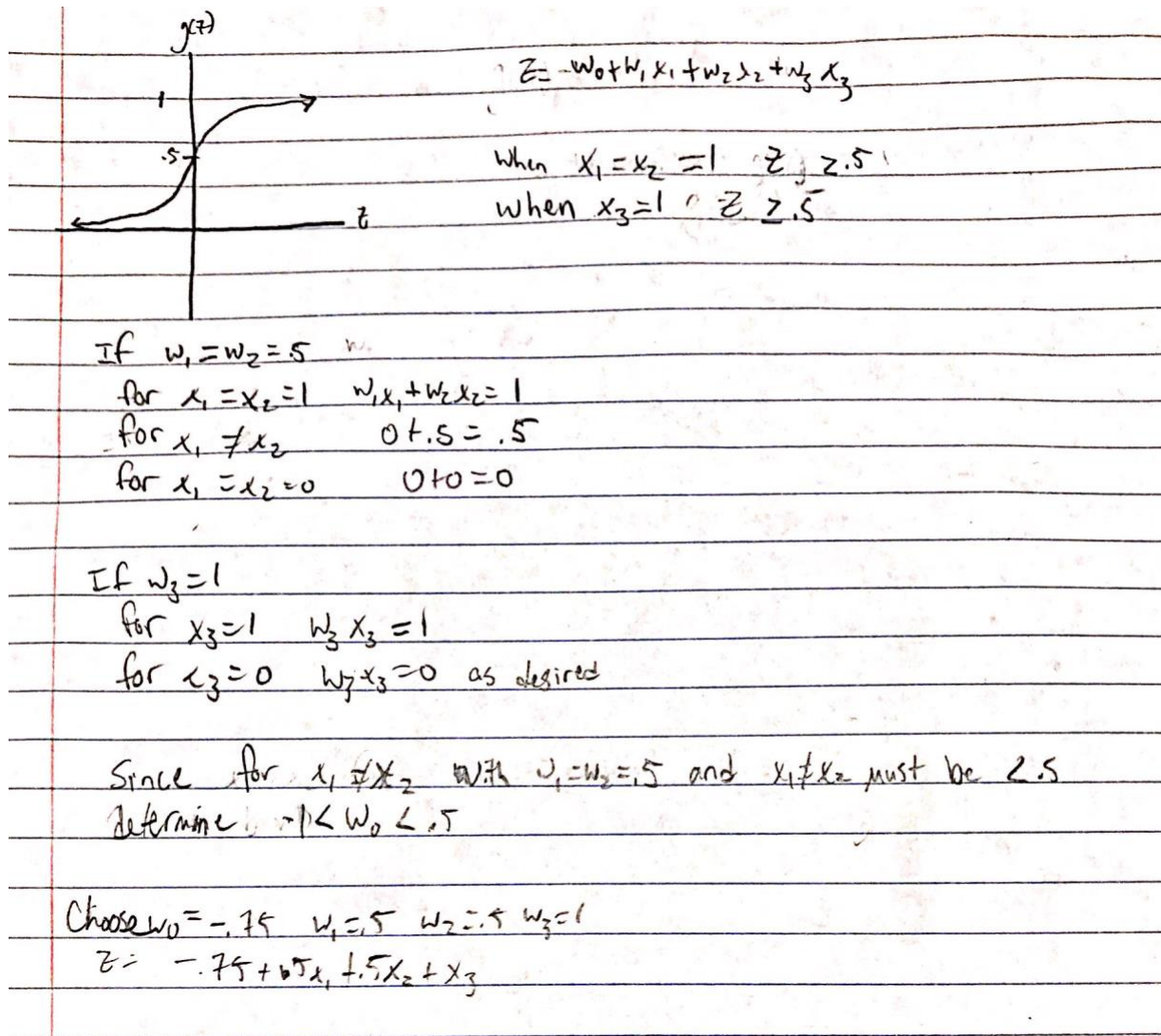
Error without PCs is .98 which is accurate since the model is scored using its train data. Since it's a logistic regression model it is intuitive to think that the accuracy will not be 1, as the regression does not exactly fit the data.

3)

1.

(a)

We know that  $g(z)$  creates a logistic function where  $g(z) > 0$  at  $z = 0$ .



(b)

- i) True. Linear regression can use matrix algebra by using the normal equation  $\theta = (X^T X)^{-1} X^T y$  which we derived in class. Linear regression can be implemented with stochastic gradient descent by repeatedly updating the theta coefficient based on reducing error across data records.
- ii) True. The error surface is created from the gradient of the sum of squared error. Since this sum changes with the data the gradient surface will change.
- iii) False. Since stochastic gradient descent looks at random individual points, if the points chosen to do the regression with are an accurate representation of the distribution, SGD can be much faster than batch gradient descent while maintaining model accuracy.
  - a. True
    - i. If we use some modified function other than the  $g(z)$  given by the problem, negating the weights could negate the output.
  - b. False

$$g(z) = \frac{1}{1 + \exp(-z)}$$
$$z = w_0 + w_1 x_1 + w_2 x_2$$

Negating the coefficients we get:

$$-w_0 - w_1 x_1 - w_2 x_2 = -1(w_0 + w_1 x_1 + w_2 x_2)$$
$$= -z$$
$$\frac{1}{1 + \exp(z)}$$

This flips our sigmoid function graph across the z axis, so it's clear negating the weights may not change the sign of the unit output

- iv) False. Since when calculating delta  $w_2$  we are we are squaring the  $x_2$  value and the update equation is the sum of

$$J(w_0, w_1, w_2) = \frac{1}{2n} \sum_{i=1}^n (t_i - o_i)^2$$

$$w_0 = w_0 - 2 \frac{d}{dw_0} J(w_0, w_1, w_2)$$

$$w_1 = w_1 - 2 \frac{d}{dw_1} J(w_0, w_1, w_2)$$

$$w_2 = w_2 - 2 \frac{d}{dw_2} J(w_0, w_1, w_2)$$

$$\frac{d}{dw_0} = \frac{1}{2} \sum_{i=1}^n (t_i - o_i)$$

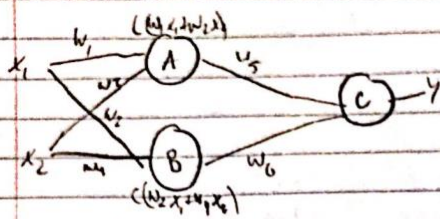
$$\frac{d}{dw_1} = \frac{1}{2} \sum_{i=1}^n (t_i - o_i)(x_{i1} + 1)$$

$$\frac{d}{dw_2} = \frac{1}{2} \sum_{i=1}^n (t_i - o_i)(x_{i2})^2$$



2)

(a)  $A=L$   $B=L$   $C=L$



$$\begin{aligned}
 y &= CW_5 (W_1 x_1 + W_2 x_2) + CW_6 (W_3 x_1 + W_4 x_2) \\
 &= CW_5 W_1 x_1 + CW_5 W_2 x_2 + CW_6 W_3 x_1 + CW_6 W_4 x_2 \\
 &= x_1 (CW_5 W_1 + CW_6 W_3) + x_2 (CW_5 W_2 + CW_6 W_4) \\
 &= B_1 x_1 + B_2 x_2
 \end{aligned}$$

(b)

$$\begin{aligned}
 a &= W_5 (CW_1 x_1 + CW_2 x_2) + W_6 (CW_3 x_1 + CW_4 x_2) \\
 &= CW_5 W_1 x_1 + CW_5 W_2 x_2 + CW_6 W_3 x_1 + CW_6 W_4 x_2 \\
 &= x_1 (CW_5 W_1 + CW_6 W_3) + x_2 (CW_5 W_2 + CW_6 W_4) \\
 B_1 &= C(W_5 W_1 + W_6 W_3) \quad B_2 = C(W_5 W_2 + W_6 W_4) \\
 &= B_1 x_1 + B_2 x_2
 \end{aligned}$$

$$S(a) = \text{sgn} \left( \frac{1}{1 + \exp(-a)} - 0.5 \right)$$

for  $B_1 x_1 + B_2 x_2 < 0$   $y = -1$  as desired

for  $B_1 x_1 + B_2 x_2 > 0$   $y = 1$  as desired

c) Derived above

$$B_1 = C(W_5 W_1 + W_6 W_3)$$

$$B_2 = C(W_5 W_2 + W_6 W_4)$$

3)

Graph 1:

Since the sigmoid function inputs a linear equation with respect to X and W we know that the relationship between X and W create a decision boundary used by the second layer of the network.

Setting  $N_1$  to zero we get

$$w_{10} + w_{11}X_1 + w_{12}X_2 = 0$$
$$X_2 = \frac{-w_{11}X_1 - w_{10}}{w_{12}}$$

We know that the  $X_1$  coefficient is negative, creating negative linear equation over the data justifying the solution given.

It follows that  $N_2$  will have a positive line separating the data in the opposite direction.

$V_1$  and  $V_2$  are the output of the  $N_1$   $N_2$  equations entered in their respective sigmoid functions.

Since  $N_1$  has a negative weighted coefficient we know that putting a negative value in the sigmoid function will look like an inverted sigmoid graph. The normal sigmoid graph will be the output of the  $N_2$  equation. We can take points like (2,3) on the graph, look that they will be above the  $N_1$  decision boundary, and know that they will input a larger value into  $V_1$  so will be at a higher value in the resulting graph. Since we also know that values on the lower side of the  $N_1$  decision boundary will be smaller and therefore less to the extreme of the sigmoid graph they will be smaller on the  $V_1$  graph. This reasoning validates how the points are displayed on the  $N_3$  graph. It's clear to see how a linear decision boundary will be formed on the  $N_3$  graph using the reasoning above.