

# mangOH to GCloud Tutorial







### Overview

This tutorial illustrates how to send data to a **Google Cloud IoT platform** from a **Legato** application running on a **AirPrime WP module** on **mangOH Green** or **mangOH Red** open source hardware platforms.

The tutorial details the source files of the Legato application and shows how to build, install and run the Legato application that sends MangOH native sensor data [ temperature + gyroscope ] to the cloud through MQTT protocol.

We'll build, install and run the application with the open source Linux-based embedded platform **Legato** toolchain and installation command line.

To quickly test this sample, just download the source code and follow the guidelines <u>here</u>;



### **Prerequisites**

# Setting up your mangOH board & Legato development environment

Before starting this tutorial, you must have followed mangoh Getting Started documentation on <a href="mailto:getting-started">getting-started</a> and ensured that your development environment is properly set up by building, compiling and running the Hello World Legato application.

### Install MQTT client Legato application

MQTT is the protocol used to communicate with the Cloud in this tutorial. You can find a MQTT client Legato application <a href="here">here</a>.

You must build, install and run the client on your board before running any application using MQTT protocol.

Note that you will find all information in the MQTT client repository.

### Setting up your Google IoT Cloud account

Furthermore, you must follow Google Cloud IoT <u>documentation</u> to setup your <u>gcloud</u> account and create your <u>project</u>, <u>registry</u>, <u>devices</u> and <u>channels</u>.

You must generate all public/private key pair registered in your Google Cloud IoT project.



### Good to know

The mangOH board is using the LSM6DS3 module which is an accelerometer + gyroscope sensor. This module provide a 8kb buffer and an embedded processing interrupt functions specifically targed for the smart market.

Thanks to the full open hardware philosophy of project MangOH, you can find all design resources in the official website.

Theses are somes features available from the LSM6DS3:

- Accelerometer for super accurate movement sensing
- Gyroscope data
- Temperature
- Built-in FIFO buffer
- Pedometer
- Shocks detection
- **Drive interrupt** pins by embedded functions or by FIFO low-capacity/overflow warning.

The LSM6DS3 module is using the I2C (Inter-Integrated Circuit) which is a multi-{master,slave}, single-ended and serial computer bus.

Theses are interested links around this usecase:

- I2c device interface
- I2c specification
- LSM6DS3 specification

### **Application skeleton**



```
mangohToGCloud.adef
      mqtt.api
      myComponent
          Component.cdef
          config
              - ec_private.pem
               ec_public.pem
               rsa_cert.pem
               rsa_private.pem
           main.cc
          deviceToCloud.cc
          deviceToCloud.hh
          utils
             - i2c
              ├── i2c.cc
                 __ i2c.hh
              1sm6ds3
                 - imu.hh
                  1sm6ds3.cc
                  1sm6ds3.hh
                  lsm6ds3 registers.hh
                  lsm6ds3_types.hh
5 directories, 19 files
```

You have **myComponent**, the main Legato component of our application and some utils (i2c, lsm6ds3) that you can use with other applications.

**MPORTANT:** the config directory must contain your generated public/private keys generated using openssl for **RSA key pair** or **Elliptic Curve key pair** and registered in you Google Cloud IoT during the last step -- cf. the chapter prerequisites.

**SHORT CUT**: the following chapters explain the structure and source code of the Legato application. To may want to jump immediately to the <u>Compile, Install, Run section</u> and come back here later to understand how the code works.



# Application definition file

Let's take a look at our mangohToGcloud.adef file:

```
version: 1.0.0
maxFileSystemBytes: 512K
start: manual
sandboxed: true
executables:
 mangohToGCloud = ( myComponent )
processes:
  envVars:
    LE_LOG_LEVEL = DEBUG
 run:
    ( mangohToGCloud )
```



```
// maximum size of core dump files.
maxCoreDumpFileBytes: 512K

// files are not allowed to grow bigger than this.
maxFileBytes: 512K
}

bindings:
{
    // we want to use mqtt services (from an external app)
    mangohToGCloud.myComponent.mqtt -> mqttService.mqtt

    // we want to use the radio WAN app so that we can start an IP session over WAN
(3G)
    mangohToGCloud.myComponent.le_data -> dataConnectionService.le_data

    // we want to use le_mdc because we need to know if the WAN interface is up
    mangohToGCloud.myComponent.le_mdc -> modemService.le_mdc
}

requires:
{
    device:
    {
        // allow read + write access to I2C port.
        [rw] /dev/i2c-0 /dev/i2c-0
     }
}
```

Pay attention to the 'bindings' section that allows us to connect the application to others services (MQTT, Legato data + mdc) and the 'requires' section that allows access to the I2C bus.

# Component

The main directory is our myComponent

```
// things the component needs from its runtime environment.
requires:
```



Pay attention to IPC APIs definition 'api' section: MQTT, Data, etc.

# Application code explained

This chapter focuses on the explanation of the main classes.

Utils classes like Lsm6ds3 or I2c are well commented and are simply wrappers from common specifications. Let's explore our simple entry point:



### Main

```
COMPONENT_INIT
{
   LE_INFO("Hi, from mangohToGoogleCloud app!");

   // instantiate our application as a singleton
   DeviceToCloud* s = DeviceToCloud::getInstance();
   s->start();
}
```

We decide to create a singleton for more flexibility and to handle callback stuff with ease.

#### DeviceToCloud class

- The first thing to do is managing termination/cleaning handlers.

```
DeviceToCloud::DeviceToCloud() : _is_mqtt_connected(false)
{
    // blocks SIGTERM in the calling thread
    le_sig_Block(SIGTERM);

    // sets SIGTERM event handler for the calling thread.
    le_sig_SetEventHandler(SIGTERM, DeviceToCloud::appTerminationCallback);

    // register appCleanup as the method to be called on exit
    ::atexit(DeviceToCloud::appCleanUp);
}
```

- Generate Json Web Token for authentication:

```
void SensorToGoogleCloud::generateJWT()
{
    // Reading the private key file
    std::ifstream ifs("config/rsa_private.pem");
```



Configure and connecting MQTT publisher is pretty simple

```
void DeviceToCloud::configureMQTT()
{
    // connect to external services
    le_data_ConnectService();

    // connect to mqtt service
    mqtt_ConnectService();

LE_INFO("MQTT CONNECTED!");
```



```
// an experiment to see if we can close mqtt if has been left connected
if(mqtt_GetConnectionState()) {
    DeviceToCloud::appCleanUp();
}

// Lambda for mqtt session
auto mqttSessionCallback = [](bool is_connected, int32_t connect_err_code,
int32_t sub_err_code, void* ctxt_ptr) {
    if(is_connected) {
        DeviceToCloud::getInstance()->setMqttSession(true);
    }
    else {
        LE_INFO("MQTT DISCONNECTED - error:%d and sub erorr: %d", connect_err_code,
sub_err_code);
    }
};

// setting up the mqtt service
mqtt_AddSessionStateHandler(mqttSessionCallback, NULL);

// configure mqtt session with AirVantage informations
mqtt_Config(MQTT_BRIDGE_HOSTNAME, MQTT_BRIDGE_PORT, MQTT_KEEP_ALIVE, MQTT_QOS);
}
```

Thanks to the mqtt.api we can use all MQTT client functions.

For configuration we are using values defined in our header, this is a sample where the password is stored as **JWT** generated our device with private key

Time to check our main loop

```
void DeviceToCloud::start()
{
    // calling lsm6ds3 configuration section
    _lsm6ds3.begin();

LE_INFO("LSM6DS3 SET");
```



```
le_clk_Time_t repeat_interval;
repeat interval.sec = 10;
repeat_interval.usec = 0;
_timer_ref = le_timer_Create("mainLoopTimer");
auto callback = [](le_timer* timer) {
  DeviceToCloud* s = DeviceToCloud::getInstance();
 s->fetch();
 s->dump();
 s->send();
le timer SetHandler( timer ref, callback);
le_timer_SetInterval(_timer_ref, repeat_interval);
le_timer_SetRepeat(_timer_ref, 0);
le_timer_Start(_timer_ref);
return;
```

When everything is initialized as **LSM6DS3** and MQTT configuration, we just create a timer calling a simple loop to fetch, display and send acquired data.

Get native sensor data

```
void SensorToGoogleCloud::fetch()
{
    // get last temperature from LSM6DS3 (C as Celsius)
```



```
_last_temperature = _lsm6ds3.readTemperatureByUnity('C');

// same for X->Z gyroscope axis
    _last_gyroscope.Ax = _lsm6ds3.readAccelerationByAxis('X');
    _last_gyroscope.Ay = _lsm6ds3.readAccelerationByAxis('Y');
    _last_gyroscope.Az = _lsm6ds3.readAccelerationByAxis('Z');
}
```

- Send data to the cloud with MQTT

```
void DeviceToCloud::send()
{
    // reference to the modem data connection profile (here: default profile)
    le_mdc_ProfileRef_t profile = le_mdc_GetProfile(LE_MDC_DEFAULT_PROFILE);

    // connection state value
    le_mdc_ConState_t mdc_state;

    char json_payload[2048];
    int32_t json_err_code;

    // get WAN connected info
    le_mdc_GetSessionState(profile, &mdc_state);

    // check that we have WAN
    if(mdc_state == LE_MDC_DISCONNECTED) {
        le_data_Request();
        LE_INFO("WAN CONNECTED");
    }
    else if(!_is_mqtt_connected) {
        // check that mqttService is up
        mqtt_Connect(MQTT_BROKER_PASSWORD);
        LE_INFO("MQTT CONNECTED");
}
else {
        // format our data into json
        sprintf
        (json_payload,
```



```
"{"
    "\"sensor.temperature\":%f,"
    "\"sensor.AX\":%f,"
    "\"sensor.AZ\":%f,"
    "\"sensor.AZ\":%f"
    "\",
    _last_temperature,
    _last_gyroscope.Ax,
    _last_gyroscope.Ay,
    _last_gyroscope.Az);

// send playload to AirVantage
mqtt_SendJson(json_payload, &json_err_code);
}
```

The purpose is to simply verify connection, format last acquired data and send a playload as a MQTT publisher.

# Compile, Install, Run

In your development environment, call **make** and specify the target (here 'wp85' for Sierra Wireless AirPrime WP85xx module) and install the Legato application onto the board:

```
mkapp -v -t wp85 \
    -i myComponent/utils/i2c \
    -i myComponent/utils/lsm6ds3 \
    mangohToGCloud.adef
Command-line arguments from previous run not found.
Parsing file: '/srcstmp/mangohToGCloud.adef'.
Modelling application: 'mangohToGCloud'
    defined in: '/srcstmp/mangohToGCloud.adef'
```



Finally, check that the application is running on your board by login in onto your mangOH board target:

```
>>> ssh root@192.168.2.2
root@swi-mdm9x15:~# app status
[running] audioService
...
[running] mqttService
[stopped] mangohToGCloud
root@swi-mdm9x15:~# app start mangohToGCloud
root@swi-mdm9x15:~# Logread
...
Jul 25 17:06:37 swi-mdm9x15 user.info Legato: INFO |
mangohToGCloud[8312]/myComponent T=main | main.cc _myComponent_COMPONENT_INIT() 24
| Hi, from mangohToGoogleCloud app!
...
```

After building and installing our new application, we can see on the logread terminal that we have some data outputs:

```
root@swi-mdm9x15:~# logread -f

Jul 25 17:07:57 swi-mdm9x15 user.info Legato: INFO |

mangohToGCloud[8312]/myComponent T=main | deviceToCloud.cc dump() 143 | DUMP:

24.875000 0.017080 -0.025376 -0.990640

Jul 25 17:07:57 swi-mdm9x15 user.debug Legato: DBUG |
```



```
mangohToGCloud[8312]/framework T=main | le mdc client.c le mdc GetProfile() 950 |
Sending message to server and waiting for response : 4 bytes sent
Jul 25 17:07:57 swi-mdm9x15 user.debug Legato: DBUG |
mangohToGCloud[8312]/framework T=main | le_mdc_client.c le_mdc_GetSessionState()
1542 | Sending message to server and waiting for response : 4 bytes sent
Jul 25 17:07:57 swi-mdm9x15 user.debug Legato: DBUG |
mangohToGCloud[8312]/framework T=main | mqtt_client.c mqtt_SendJson() 786 | Sending
message to server and waiting for response : 101 bytes sent
Jul 25 17:07:57 swi-mdm9x15 user.info Legato: INFO |
mqttService[6918]/mqttServiceComponent T=main | mqttService.c mqtt_SendJson() 198 |
send
json({"sensor.temperature":24.875000, "sensor.ax":0.017080, "sensor.ay":-0.025376, "se
nsor.az":-0.990640})
Jul 25 17:07:57 swi-mdm9x15 user.info Legato: INFO |
mqttService[6918]/mqttServiceComponent T=main | mqttService.c
mqttService_SendMessageJson() 83 | topic('359377060005641/messages/json')
payload('{"sensor.temperature":24.875000,"sensor.ax":0.017080,"sensor.ay":-0.025376
```

### Result in Google Cloud console

After building and installing our new application, open the Google Cloud console and check the data is coming in.