

# Tensor Network Machine Learning

An Introduction

# About Me

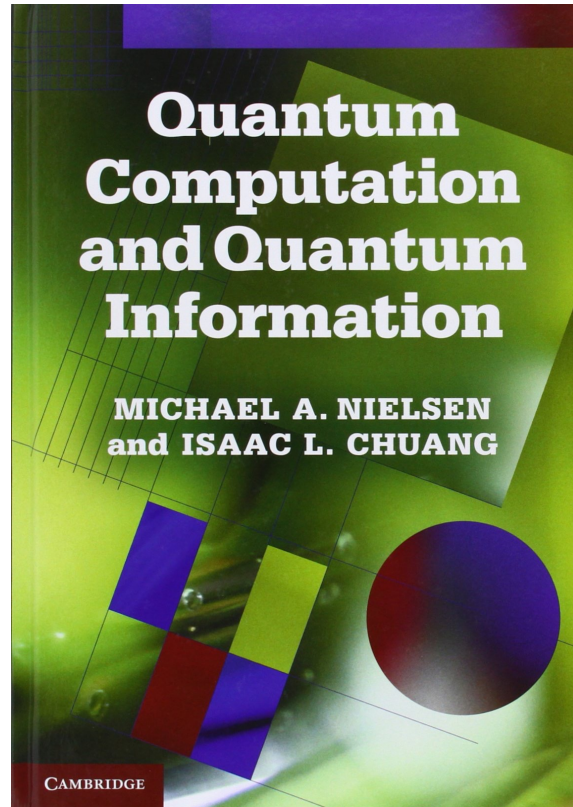
- Head of Data Science at Novomatic AG
- Lecturer at University of Applied Sciences Wiener Neustadt
- Previously
  - Researcher in Quantum Physics
  - Full Stack Software Engineer

# Outline

- Quantum States
- Tensors
- Tensor Networks States
- Tensor Network Machine Learning

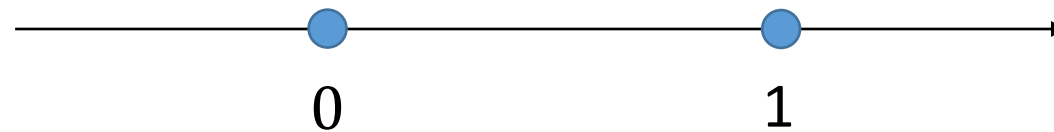
# Quantum States

# Nielsen & Chuang



# Classical Bit

$$x \in \{0,1\}$$

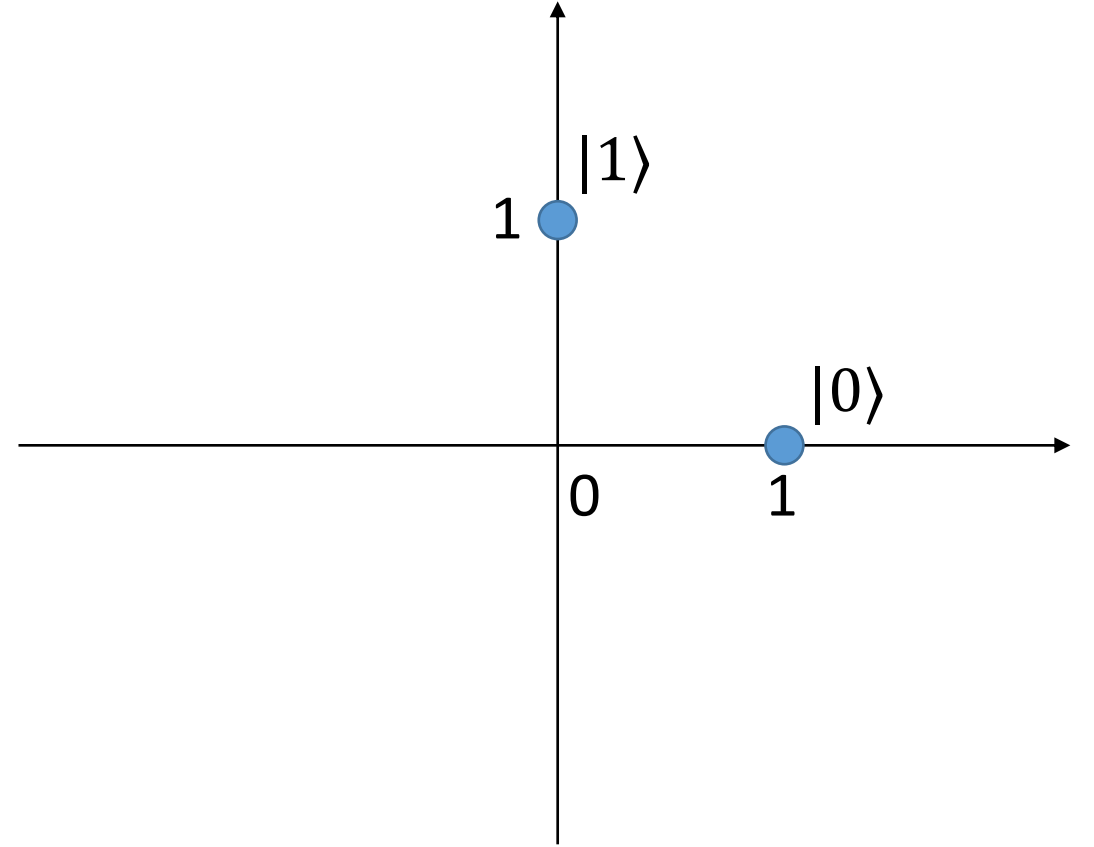


# Vector Space Representation

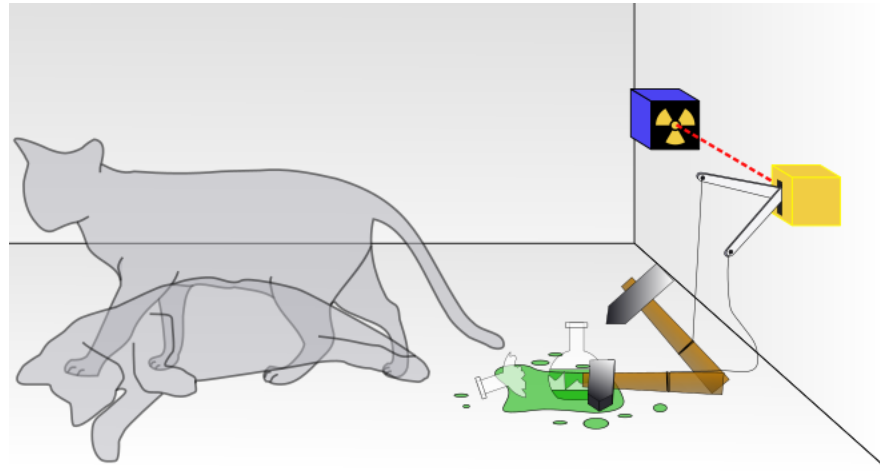
$$0 \rightarrow \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \vec{e}_0 = |0\rangle$$

$$1 \rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \vec{e}_1 = |1\rangle$$

$$\vec{x} \in \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\} = \{|0\rangle, |1\rangle\}$$



# Quantum World – Superposition Principle





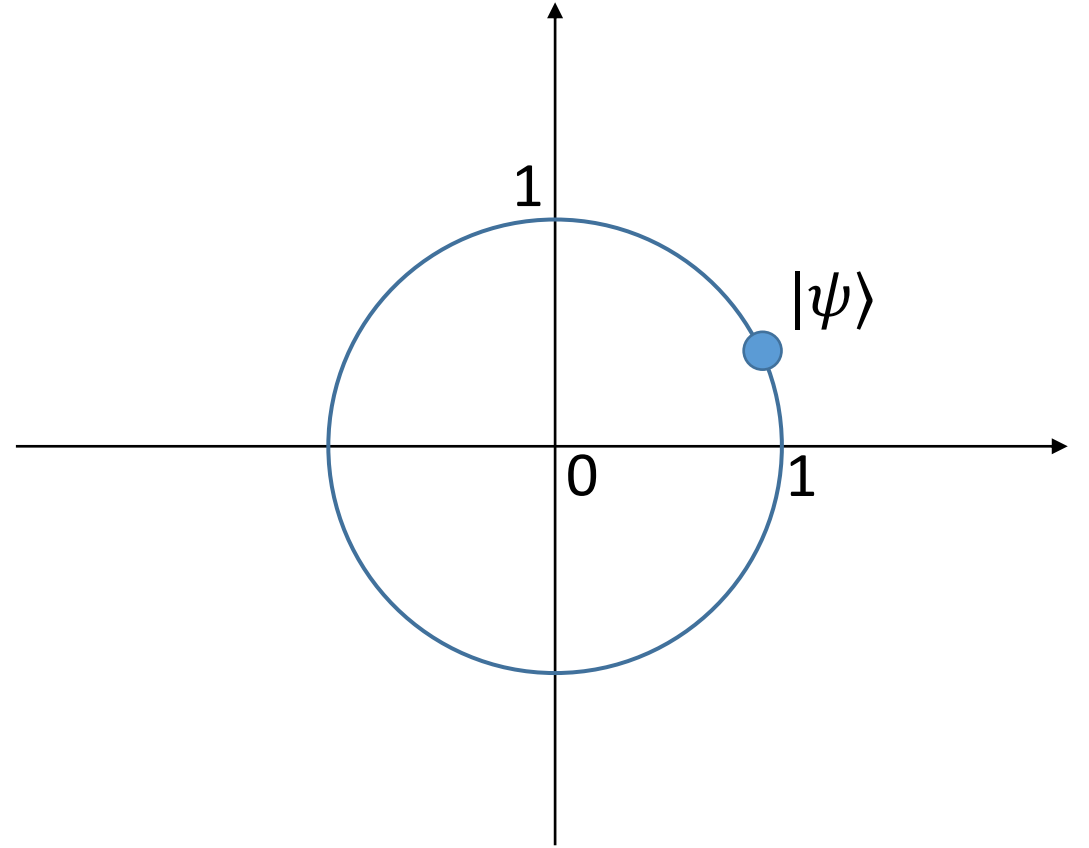
# Quantum Bit - Qubit

$$|\psi\rangle = \alpha|0\rangle + \beta|1\rangle$$

$$|\psi\rangle = \alpha \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \beta \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$$

$$\|\psi\|^2 = \langle\psi|\psi\rangle = 1$$

$$|\psi\rangle \in \left\{ \sum_{i=0}^1 \psi_i |i\rangle \mid \|\psi\|^2 = 1 \right\}$$



# Two-Bit System

$$\overrightarrow{x_1} \in \{|0\rangle, |1\rangle\}$$

$$\overrightarrow{x_2} \in \{|00\rangle, |01\rangle, |10\rangle, |11\rangle\}$$

$$|00\rangle = |0\rangle \otimes |0\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \vec{e}_{00} \quad |01\rangle = |0\rangle \otimes |1\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \otimes \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} = \vec{e}_{01}$$

$$|10\rangle = |1\rangle \otimes |0\rangle = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \otimes \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = \vec{e}_{10} \quad |11\rangle = |1\rangle \otimes |1\rangle = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \otimes \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} = \vec{e}_{11}$$

# Two-Qubit System

$$|\psi\rangle = \alpha|00\rangle + \beta|01\rangle + \gamma|10\rangle + \delta|11\rangle$$

$$|\psi\rangle = \psi_{00}|00\rangle + \psi_{01}|01\rangle + \psi_{10}|10\rangle + \psi_{11}|11\rangle = \begin{pmatrix} \psi_{00} \\ \psi_{01} \\ \psi_{10} \\ \psi_{11} \end{pmatrix}$$

$$|\psi\rangle \in \left\{ \sum_{i_1, i_2=0}^1 \psi_{i_1 i_2} |i_1 i_2\rangle \mid \|\psi\|^2 = 1 \right\}$$

# N-Qubit System

$$|\psi\rangle = \sum_{i_1, i_2 \dots i_N=0}^1 \psi_{i_1 i_2 \dots i_N} |i_1 i_2 \dots i_N\rangle$$

Computational problem: deal with huge dimension =  $2^N$  !!!

For  $N \approx 130$  the number of amplitudes is greater than the number of atoms in the known universe!

Solution: represent Quantum States as Tensor Networks

# Tensors

# Rank 1 Tensor

Example: 1-qubit state. Can be represented as vector:

$$|\psi\rangle = \sum_{i=0}^1 a_i |i\rangle$$

$$|\psi\rangle = \frac{1}{\sqrt{2}} |0\rangle + \frac{1}{\sqrt{2}} |1\rangle$$

$$a_0 = \frac{1}{\sqrt{2}}, a_1 = \frac{1}{\sqrt{2}}$$

$$a_i \equiv \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix}$$

$$a_i \equiv \text{blue circle with index } i \text{ below it}$$

# Rank 2 Tensor

Example: 2-qubit state. Can be represented as matrix:

$$|\psi\rangle = \sum_{i,j=0}^1 a_{ij} |ij\rangle$$

$$|\psi\rangle = \frac{1}{\sqrt{2}} |00\rangle + \frac{1}{\sqrt{2}} |11\rangle = \begin{pmatrix} 1/\sqrt{2} \\ 0 \\ 0 \\ 1/\sqrt{2} \end{pmatrix}$$

$$a_{00} = \frac{1}{\sqrt{2}}, a_{11} = \frac{1}{\sqrt{2}}$$

$$a_{ij} \equiv \begin{pmatrix} 1/\sqrt{2} & 0 \\ 0 & 1/\sqrt{2} \end{pmatrix}$$

$$a_{ij} \equiv \begin{array}{c} \boxed{\phantom{00}} \\ | \\ i \quad j \end{array}$$

# Rank 3 Tensor

Example: 3-qubit state

$$|\psi\rangle = \sum_{i,j,k=0}^1 a_{ijk} |ijk\rangle$$

$$|W\rangle = \frac{1}{\sqrt{3}} (|001\rangle + |010\rangle + |100\rangle) = \frac{1}{\sqrt{3}} \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{aligned} a_{001} &= \frac{1}{\sqrt{3}} \\ a_{010} &= \frac{1}{\sqrt{3}} \\ a_{100} &= \frac{1}{\sqrt{3}} \end{aligned}$$



# Rank 3 Tensor

Can be represented as an array of matrices:

$$a_{ijk} \equiv \left[ \begin{pmatrix} a_{000} & a_{001} \\ a_{010} & a_{011} \end{pmatrix}, \begin{pmatrix} a_{100} & a_{101} \\ a_{110} & a_{111} \end{pmatrix} \right] = \frac{1}{\sqrt{3}} \left[ \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \right]$$

```
In [3]: np.array([0,1,1,0,1,0,0,0]).reshape((2, 2, 2))
```

```
Out[3]: array([[[0, 1],  
                [1, 0]],  
              [[1, 0],  
                [0, 0]]])
```

$$a_{ijk} \equiv \begin{array}{c} \boxed{\phantom{a_{ijk}}} \\ | \quad | \quad | \\ i \quad j \quad k \end{array}$$

# Tensor Contraction

# Rank-2-Tensor-Vector Contraction

Is just a Matrix-Vector dot product:

$$\vec{c} = A\vec{b}$$

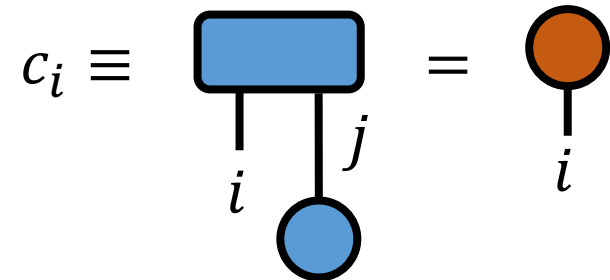
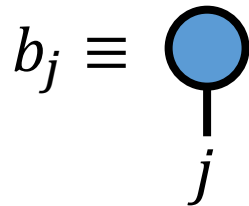
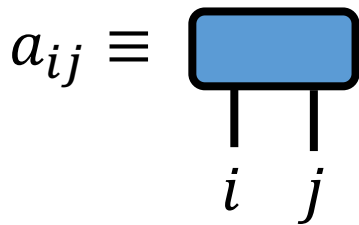
$$A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$$

$$\vec{b} = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$$

$$\vec{c} = \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

$$c_i = \sum_{j=0}^1 a_{ij} b_j$$

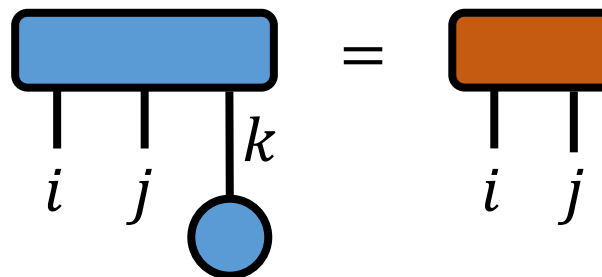
$$\vec{c} = \begin{pmatrix} a_{11}b_1 + a_{12}b_2 \\ a_{21}b_1 + a_{22}b_2 \end{pmatrix}$$



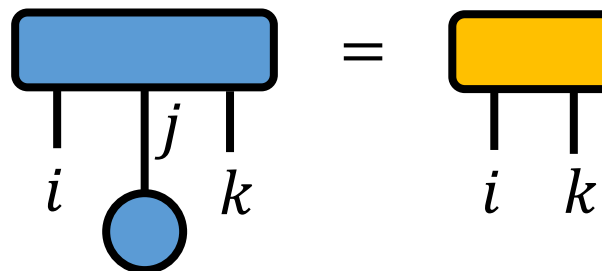
# Rank-3-Tensor-Vector Contraction

Examples:

$$c_{ij} = \sum_{k=0}^1 a_{ijk} b_k$$



$$d_{ij} = \sum_{j=0}^1 a_{ijk} b_j$$



# Example

$$A = \left( \begin{pmatrix} a_{111} & a_{112} \\ a_{121} & a_{122} \end{pmatrix}, \begin{pmatrix} a_{211} & a_{212} \\ a_{221} & a_{222} \end{pmatrix} \right) = \left( \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}, \begin{pmatrix} 5 & 6 \\ 7 & 8 \end{pmatrix} \right) \quad \vec{b} = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

```
In [113]: A=np.array(range(1,9)).reshape((2, 2, 2)) # i,j,k  
print(A)
```

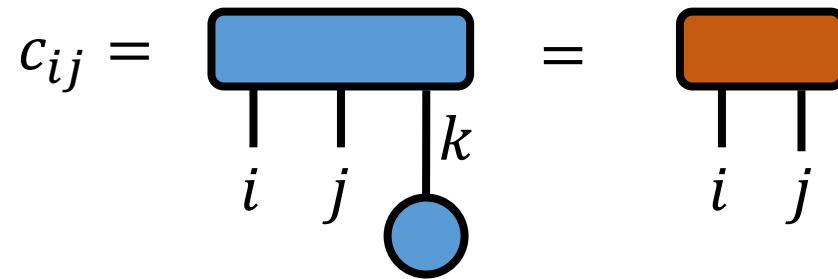
```
[[[1 2]  
  [3 4]]
```

```
 [[5 6]  
  [7 8]]]
```

```
In [115]: b=np.array([1,2]).reshape((2,1)) # k  
print(b)
```

```
[[1]  
 [2]]
```

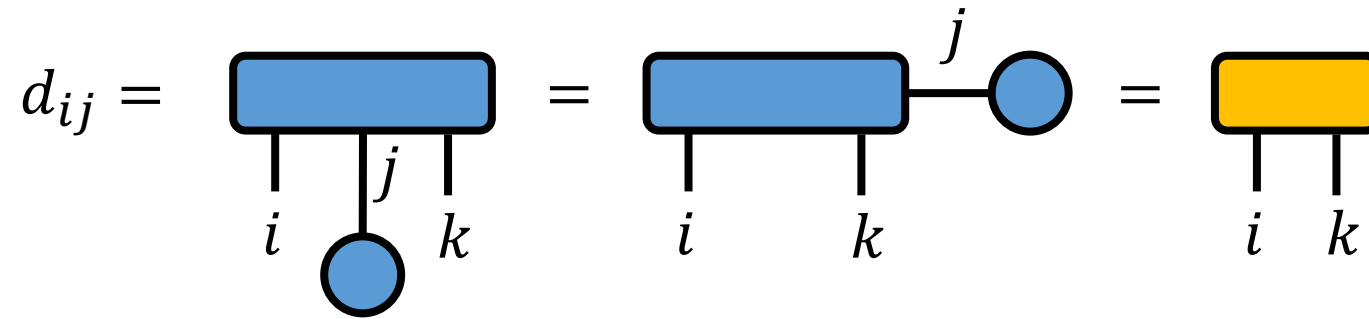
... continued



```
In [118]: C=np.tensordot(A,b, axes=([2],[0]))      # i,j  
print(C)  
  
[[ 5 11]  
 [17 23]]
```

```
In [122]: C_mat_mul = (A.reshape(4,2)@b).reshape(2,2)  
print(C_mat_mul)  
  
[[ 5 11]  
 [17 23]]
```

... continued



```
In [119]: D=np.tensordot(A,b, axes=([1],[0]))      # i,j  
print(D)  
  
[[ 7 10]  
 [19 22]]
```

```
In [123]: D_mat_mul = (A.transpose(0,2,1).reshape(4,2)@b).reshape(2,2)  
print(D_mat_mul)  
  
[[ 7 10]  
 [19 22]]
```

# Tensor Network States



# Many Particle Quantum States

$$|\psi\rangle = \sum_{i_1, i_2 \dots i_N=0}^{d-1} a_{i_1 i_2 \dots i_N} |i_1 i_2 \dots i_N\rangle$$

Computational problem: deal with huge dimension =  $2^N$ !!!

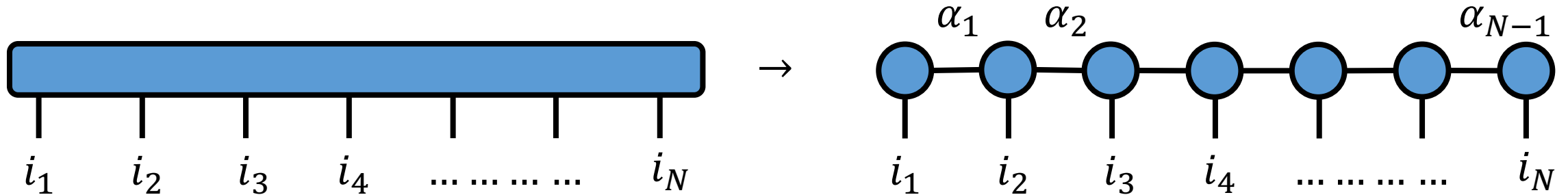
For  $N \approx 130$  the number of amplitudes is greater than the number of atoms in the known universe!

Solution: represent Quantum States as a Matrix Product State

# Matrix Product States (MPS)

Rewrite amplitude as a product of tensors with 3 indices:

$$a_{i_1 i_2 \dots i_N} \rightarrow \sum_{\alpha_1, \alpha_2, \dots, \alpha_{N-1}}^D A_{i_1, \alpha_1}^{[1]} A_{i_2, \alpha_1 \alpha_2}^{[2]} A_{i_3, \alpha_2 \alpha_3}^{[3]} \dots A_{i_N, \alpha_{N-1}}^{[N]} = A_{i_1}^{[1]} \cdot A_{i_2}^{[2]} \cdot A_{i_3}^{[3]} \dots A_{i_N}^{[N]}$$



# Why?

The MPS representation can be significantly more efficient:

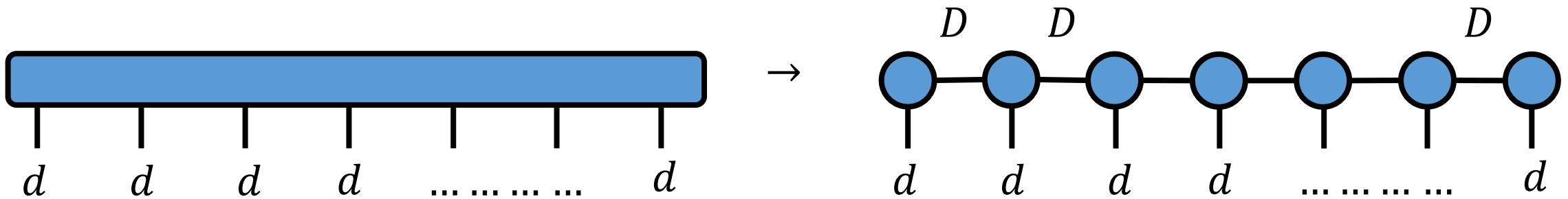
$$a_{i_1 i_2 \dots i_N} \rightarrow A_{i_1}^{[1]} \cdot A_{i_2}^{[2]} \cdot A_{i_3}^{[3]} \dots A_{i_N}^{[N]}$$

Exponential  
scaling

$$= d^N$$

$$\approx NdD^2$$

Linear  
scaling

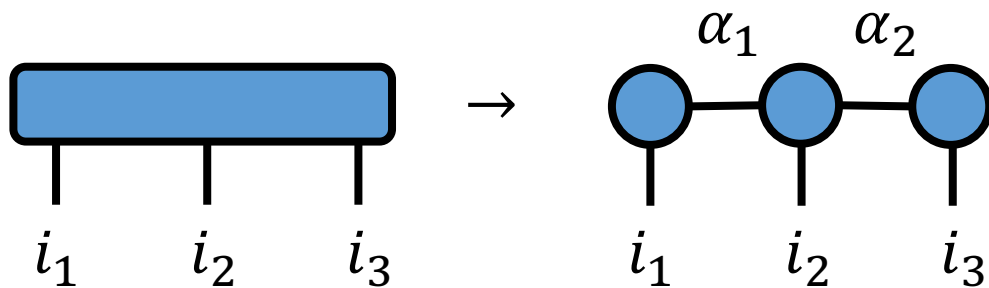


Computational complexity:  $\mathcal{O}(NdD^3)$

# The W state as MPS

$$|W\rangle = \frac{1}{\sqrt{3}} (|001\rangle + |010\rangle + |100\rangle) = \frac{1}{\sqrt{3}} \sum_{i_1, i_2, i_3=0}^1 a_{i_1 i_2 i_3} |i_1 i_2 i_3\rangle$$

$$a_{i_1 i_2 i_3} \rightarrow \sum_{\alpha_1, \alpha_2, \alpha_3=1}^D A_{i_1, \alpha_1}^{[1]} A_{i_2, \alpha_1 \alpha_2}^{[2]} A_{i_3, \alpha_2}^{[3]}$$



# ... continued

```
In [125]: A1=np.array([1,0,0,1]).reshape((2, 2)) # [d_1, D_1]
          print(A1)

          [[1 0]
           [0 1]]
```

```
In [126]: A2=np.array([1,0,0,1,0,1,0,0]).reshape((2, 2, 2)) # [d_2, D_1, D_2]
          print(A2)

          [[[1 0]
            [0 1]]

           [[0 1]
            [0 0]]]
```

```
In [127]: A3=np.array([0,1,1,0]).reshape((2, 2)) # [d_3, D_3]
          print(A3)

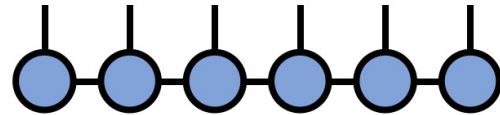
          [[0 1]
           [1 0]]
```

```
In [133]: A12 = np.tensordot(A1,A2, axes=([1],[1])) # [d1, d2, D2]
          A123 = np.tensordot(A12,A3, axes=([2],[1])) # [d1, d2, d3]
          print(A123.reshape(8))

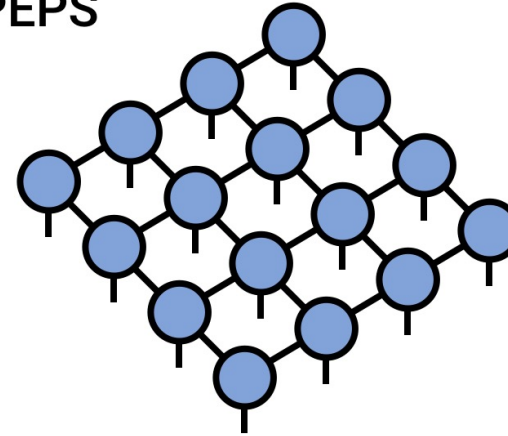
          [0 1 1 0 1 0 0 0]
```

# Generalizations

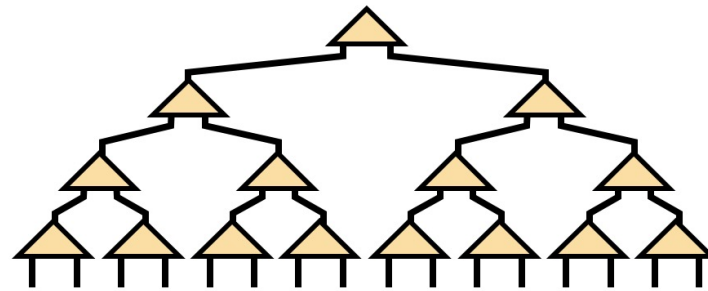
Matrix Product State /  
Tensor Train



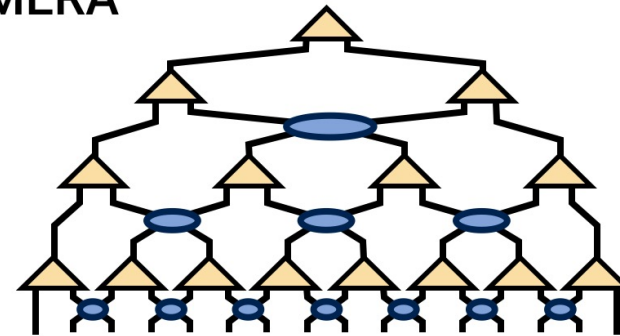
PEPS



Tree Tensor Network /  
Hierarchical Tucker



MERA



# Tensor Network Machine Learning

Stoudenmire, E.M., & Schwab, D. (2016). Supervised Learning with Tensor Networks. *NIPS*.

Novikov, A., Trofimov, M., & Oseledets, I. (2016). Tensor Train polynomial models via Riemannian optimization. *ArXiv*, *abs/1605.03795*.

ICTP 2018 Lecture: <https://www.youtube.com/watch?v=kzbVHT36aLE>

ICTP 2018 Slides: <http://indico.ictp.it/event/8331/session/41/contribution/159/material/slides/0.pdf>

# Linear Regression Problem

Training set:

$$\{(\vec{x}^{(1)}, y^{(1)}), (\vec{x}^{(2)}, y^{(2)}), \dots, (\vec{x}^{(m)}, y^{(m)})\} \quad \vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{pmatrix} \quad y \in \mathbb{R}$$

Model:  $f_W(\vec{x}^{(i)}) = \bar{y}^{(i)}$

Train by minimizing the cost function with respect to parameters  $W$ :

$$C(W) = \frac{1}{2m} \sum_{i=1}^m (\bar{y}^{(i)} - y^{(i)})^2 = \frac{1}{2m} \sum_{i=1}^m (f_W(\vec{x}^{(i)}) - y^{(i)})^2$$



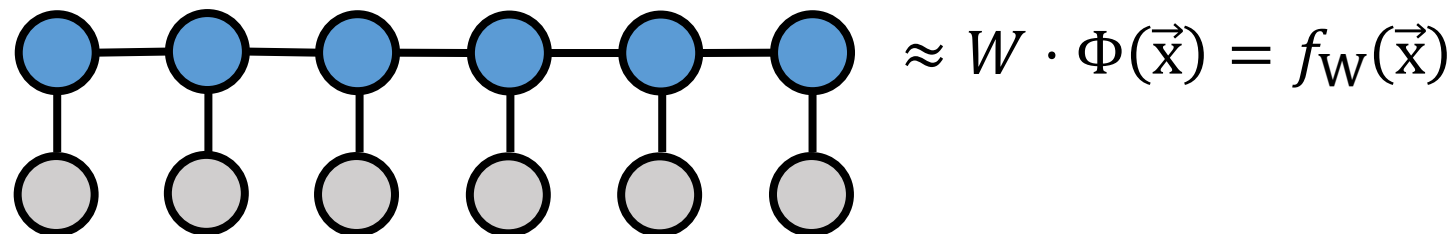
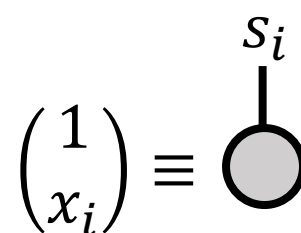
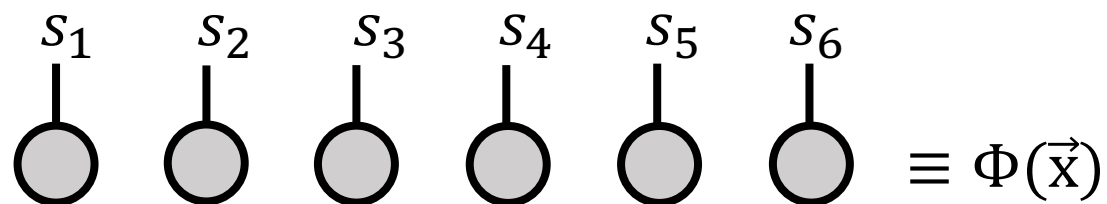
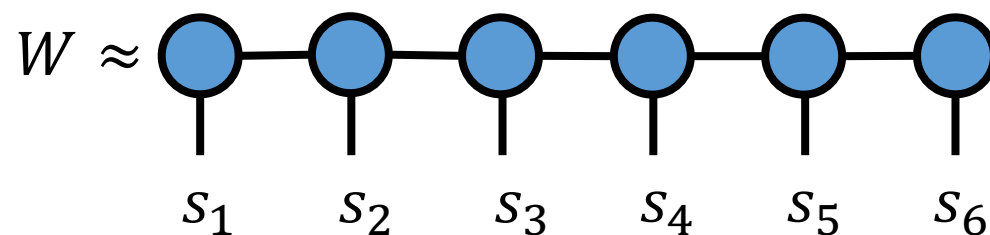
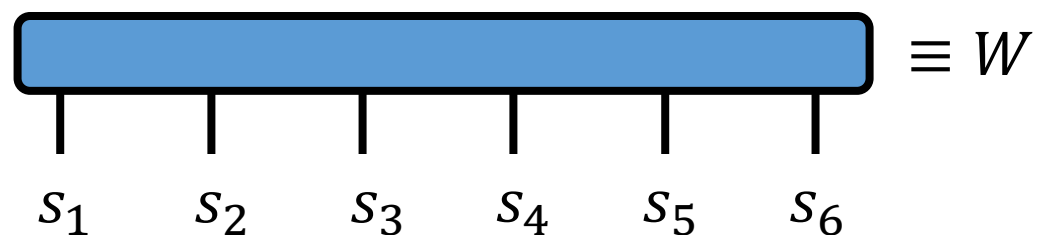
# Linear Regression with TN

Choose:  $f_W(\vec{x}) = W \cdot \Phi(\vec{x}) = \sum_{s_i=0}^1 W_{s_1 s_2 s_3 \dots s_N} x_1^{s_1} x_2^{s_2} x_3^{s_3} \dots x_N^{s_N}$

Coefficients look the same as amplitudes of a Many-Body wave function. For instance in the case of a problem with 3 features:

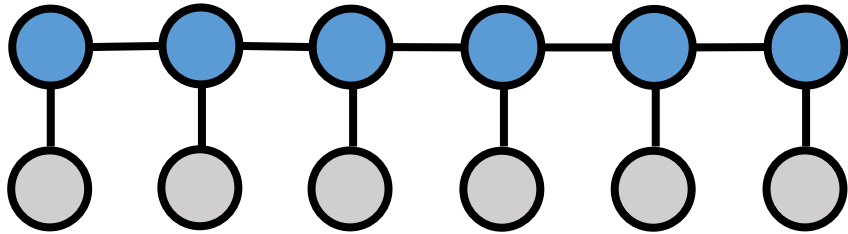
$$\begin{aligned} f_W(\vec{x}) &= W \cdot \Phi(\vec{x}) = \sum_{s_i=0}^1 W_{s_1 s_2 s_3} x_1^{s_1} x_2^{s_2} x_3^{s_3} \\ &= W_{000} + W_{100}x_1 + W_{010}x_2 + W_{001}x_3 \\ &\quad + W_{110}x_1x_2 + W_{101}x_1x_3 + W_{011}x_2x_3 \\ &\quad + W_{111}x_1x_2x_3 \end{aligned}$$

# Tensor Networks Representation

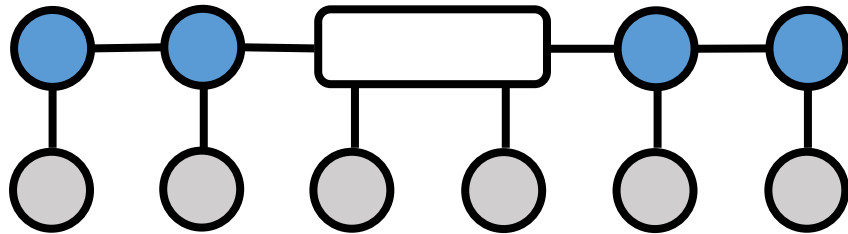


# Algorithm

Start with a random MPS  $W$  and express the model scoring  $f_W(\vec{x})$  as:



Combine 2 sites:



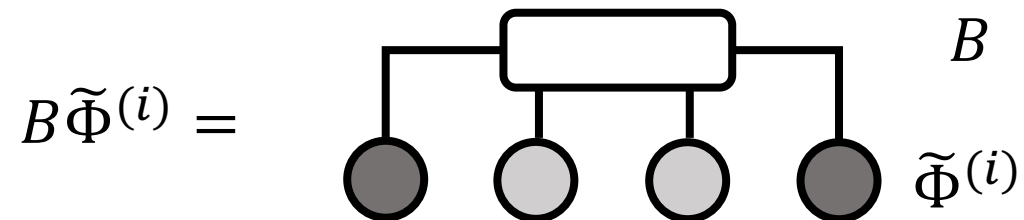
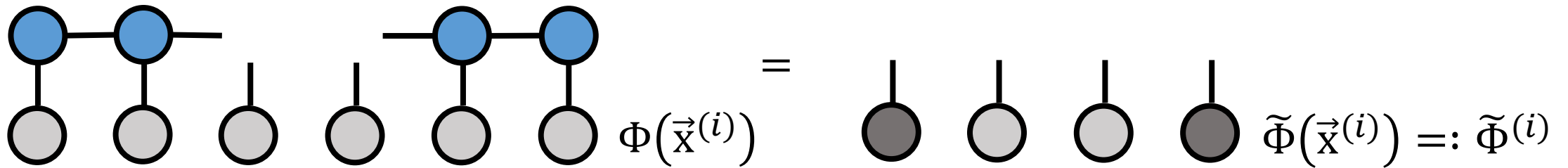
$$B_{ijkl} := \text{---} \boxed{\phantom{B_{ijkl}}} \text{---}$$

A diagram of the  $B_{ijkl}$  tensor, represented as a white rectangle with four legs: two horizontal legs (top and bottom) and two vertical legs (left and right).

# ...continued

Fix other sites and optimize  $B$ , such that the cost function is minimized as a function  $B$ :

$$C(W) \propto \sum_{i=1}^m (W \Phi(\vec{x}^{(i)}) - y^{(i)})^2 \rightarrow C(B) \propto \sum_{i=1}^m (B \tilde{\Phi}(\vec{x}^{(i)}) - y^{(i)})^2$$

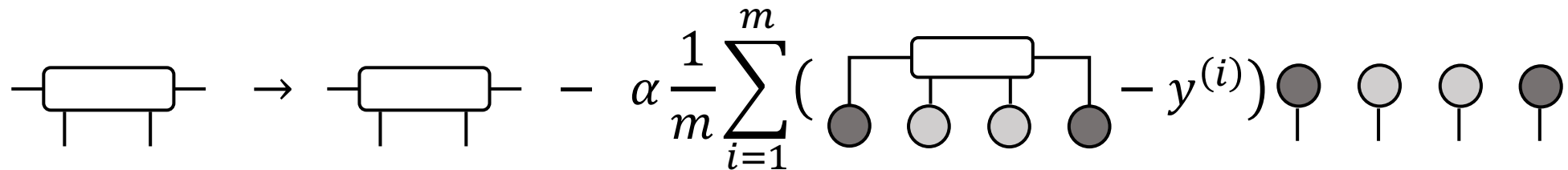


...continued

Use Gradient Descent to compute find  $\min_B C(B)$ :

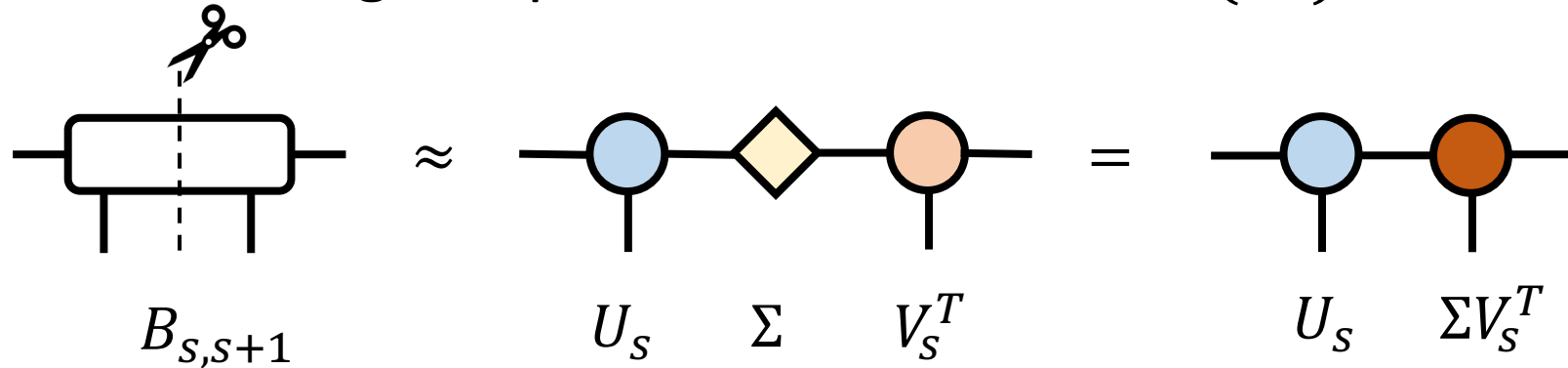
$$B \rightarrow B - \alpha \Delta B$$

$$\Delta B = \frac{1}{2m} \frac{\partial}{\partial B} \sum_{i=1}^m (B \tilde{\Phi}^{(i)} - y^{(i)})^2 = \frac{1}{m} \sum_{i=1}^m (B \tilde{\Phi}^{(i)} - y^{(i)}) \tilde{\Phi}^{(i)}$$

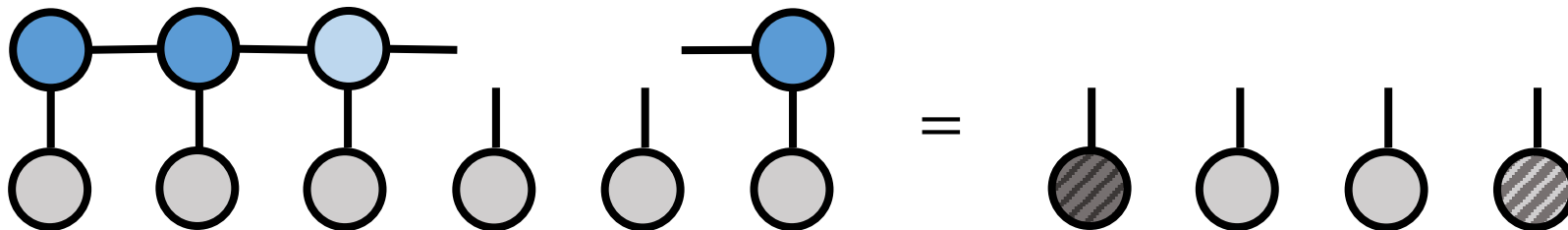


...continued

Once B has converged, split the 2-site tensor:  $\mathcal{C}(W)$

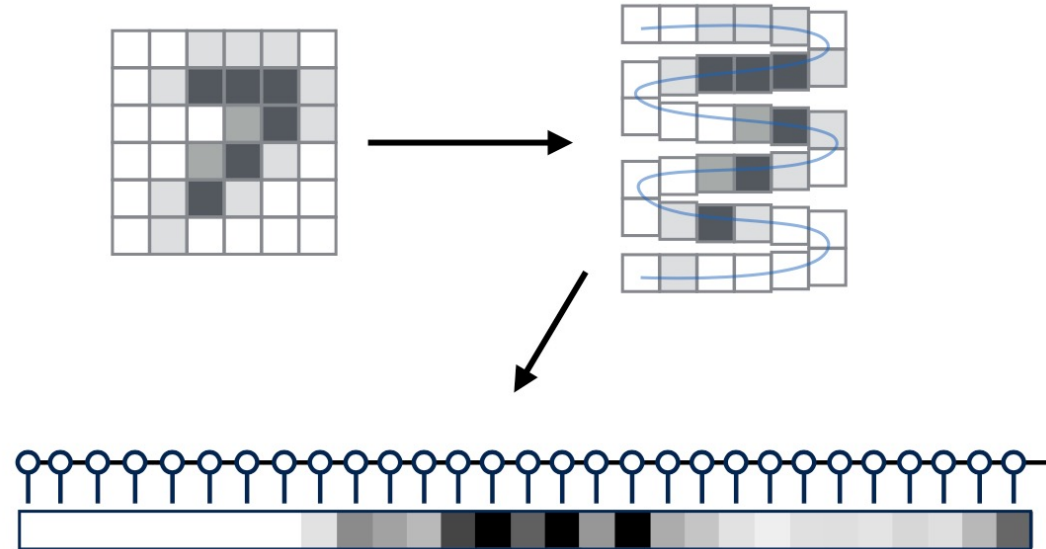
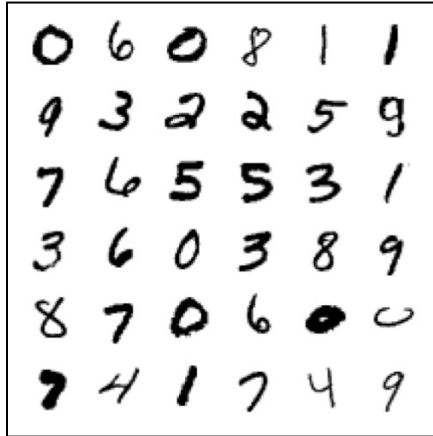


And move one site further in the chain:



**Sweep back and forth** until  $\mathcal{C}(W)$  has converged.

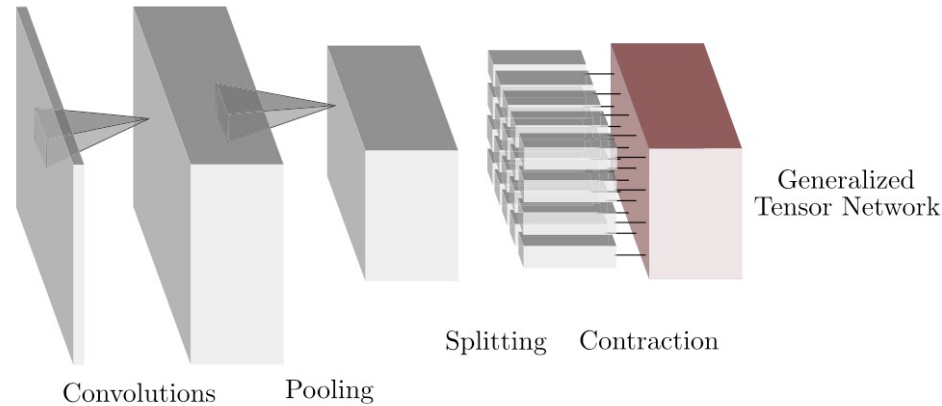
# Results – MNIST



Train to 99.95% accuracy on 60,000 training images

Obtain **99.03%** accuracy on 10,000 test images  
(only 97 incorrect)

# Results – Fashion MNIST



Method	Accuracy
Support Vector Machine	84.1%
EPS + linear classifier	86.3%
Multilayer perceptron	87.7%
EPS-SBS	88.6%
Snake-SBS	89.2%
AlexNet	89.9%
CNN-snake-SBS	92.3%
GoogLeNet	93.7%



# Libraries

- TensorNetwork (Python)
- TorchMPS (Python)
- Itensor (C++, Julia)
- TensorLy (Python)

# Benefits

- Realized Benefits
  - Linear scaling in nr of inputs
  - Adaptive weights, i.e. model complexity changes dynamically
  - Learning data “features”
- Future benefits?
  - Interpretability
  - Better algorithms
  - Quantum computing

Thank you!

# NOVOMATIC

