

# Two Dimensional Phase Retrieval from Local Measurements

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## ABSTRACT

2D or not 2D, that is the tribe called question

**Keywords:** Phase Retrieval, Local Measurements, Two Dimensional Imaging, Ptychography

## 1. INTRODUCTION

In this paper we consider the problem of approximately recovering an unknown two dimensional sample transmission function  $q : \mathbb{R}^2 \rightarrow \mathbb{C}$  with compact support,  $\text{supp}(q) \subset [0, 1]^2$ , from phaseless Fourier measurements of the form

$$|(\mathcal{F}[aS_{x_0, y_0}q])(u, v)|^2, \quad (u, v) \in \Omega \subset \mathbb{R}^2, \quad (x_0, y_0) \in \mathcal{L} \subset [0, 1]^2 \quad (1)$$

where  $\mathcal{F}$  denotes the 2 dimensional Fourier transform,  $a : \mathbb{R}^2 \rightarrow \mathbb{C}$  is a known illumination function from an illuminating beam,  $S_{x_0, y_0}$  is a shift operator defined by  $(S_{x_0, y_0}q)(x, y) := q(x - x_0, y - y_0)$ ,  $\Omega$  is a finite set of sampled frequencies, and  $\mathcal{L}$  is a finite set of shifts. When the illuminating beam is sharply focussed one can further assume that  $a$  is also (effectively) compactly supported within a smaller region  $[0, \delta']^2$  for  $\delta' \ll 1$ . This is known as the *ptychographic imaging problem* and is of great interest in the physics community (see, e.g., Rodenburg<sup>7</sup>). Herein we will make the further assumption that all the utilized shifts of  $q$  also have their supports contained in  $[0, 1]^2$ . That is, that

$$\bigcup_{(x_0, y_0) \in \mathcal{L}} \text{supp}(S_{x_0, y_0}q) \subseteq [0, 1]^2$$

holds. Note that this assumption can always be achieved via rescaling.

Discretizing (??) using periodic boundary conditions we obtain a finite dimensional problem aimed at recovering an unknown matrix  $Q \in \mathbb{C}^{d \times d}$  from phaseless measurements of the form

$$\left| \frac{1}{d^2} \sum_{j=1}^d \sum_{k=1}^d A_{j,k} (S_\ell Q S_{\ell'}^*)_{j,k} e^{\frac{-2\pi i}{d}(ju + kv)} \right|^2 \quad (2)$$

where  $A \in \mathbb{C}^{d \times d}$  is a known measurement matrix representing our illuminating beam, and  $S_\ell : \mathbb{C}^d \mapsto \mathbb{C}^d$  is the discrete circular shift operator defined by  $(S_\ell \mathbf{x})_j := x_{j+\ell \bmod d}$  for all  $\mathbf{x} \in \mathbb{C}^d$  and  $j, \ell \in [d] := \{1, \dots, d\}$ . Herein we will make the simplifying assumption that our original illuminating beam function  $a$  is not only sharply focused, but also separable. Using this assumption we let weighted measurement matrix be  $\frac{1}{d^2}A := \mathbf{a}\mathbf{b}^*$  where  $\mathbf{a}, \mathbf{b} \in \mathbb{C}^d$  both have  $a_j = b_j = 0$  for all  $j \in [d] \setminus \{1, \dots, \delta\}$ . Here  $\delta \in \mathbb{Z}^+$  is much smaller than  $d$ .

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Using the small support and separability of  $\frac{1}{d^2}A := \mathbf{a}\mathbf{b}^*$  we can now rewrite the measurements (??) as

$$\left| \sum_{j=1}^{\delta} \sum_{k=1}^{\delta} a_j \overline{b_k} (S_{\ell} Q S_{\ell'}^*)_{j,k} e^{\frac{-2\pi i}{d}(ju+kv)} \right|^2 = \left| \sum_{j=1}^{\delta} \sum_{k=1}^{\delta} \overline{a_j} e^{\frac{2\pi i ju}{d}} b_k e^{\frac{2\pi i kv}{d}} (S_{\ell} Q S_{\ell'}^*)_{j,k} \right|^2 = |\langle S_{\ell} Q S_{\ell'}^*, \mathbf{a}_u \mathbf{b}_v^* \rangle_{\text{HS}}|^2 \quad (3)$$

where  $\mathbf{a}_u, \mathbf{b}_v \in \mathbb{C}^d$  are defined by  $(a_u)_j := e^{\frac{-2\pi i ju}{d}} a_j$  and  $(b_v)_k := e^{\frac{2\pi i kv}{d}} b_k$  for all  $j, k \in [d]$ . Continuing to rewrite (??) we can now see that our discretized measurements will all take the form of

$$|\langle S_{\ell} Q S_{\ell'}^*, \mathbf{a}_u \mathbf{b}_v^* \rangle_{\text{HS}}|^2 = |\text{Trace}(\mathbf{b}_v \mathbf{a}_u^* S_{\ell} Q S_{\ell'}^*)|^2 = |\text{Trace}(S_{\ell'}^* \mathbf{b}_v (S_{\ell}^* \mathbf{a}_u)^* Q)|^2 = |\langle Q, S_{\ell}^* \mathbf{a}_u (S_{\ell'}^* \mathbf{b}_v)^* \rangle_{\text{HS}}|^2 \quad (4)$$

for a finite set of frequencies  $(u, v) \in \Omega \subset \mathbb{R}^2$  and shifts  $(\ell, \ell') \in \mathcal{L} \subseteq [d] \times [d]$ .

Motivated by ptychographic imaging we propose a new efficient numerical scheme for solving discrete phase retrieval problems using measurements of type (??) herein.

OUTLINE OF REMAINING SECTIONS HERE!!!!

## 2. AN EFFICIENT METHOD FOR SOLVING THE DISCRETE 2D PHASE RETRIEVAL PROBLEM

In this section we present a lifted formulation<sup>?</sup> of the discrete 2D phase retrieval from local measurements of type (??). We then use this lifted formulation to rapidly solve for  $Q \in \mathbb{C}^{d \times d}$  using a modified variant of the BlockPR algorithm.<sup>?, ?</sup> More specifically, we will consider the collection of measurements given by

$$y_{(\ell, \ell', u, v)} := |\langle Q, S_{\ell}^* \mathbf{a}_u \mathbf{b}_v^* S_{\ell'} \rangle_{\text{HS}}|^2$$

for all  $(\ell, \ell', u, v) \in [d]^2 \times [2\delta - 1]^2$  herein.<sup>\*</sup> Thus, we collect a total of  $D := (2\delta - 1)^2 \cdot d^2$  measurements, where each measurement is due to a vertical and horizontal shift of a rank one 2D illumination pattern  $\mathbf{a}_u \mathbf{b}_v^*$ . As above, the inner product is the Hilbert-Schmidt inner product.

Let  $X \in \mathbb{C}^{d \times d}$  and consider measurements of the form

$$y_I = |\langle X, S_{\ell}^* \mathbf{m}_j \mathbf{m}_{j'}^* S_{\ell'} \rangle_{\text{HS}}|^2$$

where the inner product is the Hilbert-Schmidt inner product. Here,  $S_{\ell} : \mathbb{C}^d \mapsto \mathbb{C}^d$  and  $\mathbf{m}_j$  are as usual, and  $I = (j, j', \ell, \ell')$  is a multi-index with  $j, j' \in [2\delta - 1]$ , and  $\ell, \ell' \in [d]_0$ . Define the multi-index set  $\mathcal{I} = [2\delta - 1]^2 \times [d]_0^2$  and note that, .

Let  $\mathcal{P}$  be the projection onto the span of

$$\left\{ \overrightarrow{(S_{\ell}^* \mathbf{m}_j)^T \otimes (S_{\ell'}^* \mathbf{m}_{j'})^*} \overleftarrow{((S_{\ell}^* \mathbf{m}_j)^T \otimes (S_{\ell'}^* \mathbf{m}_{j'})^*)} \right\}_{(j, j', \ell, \ell')},$$

i.e.,  $\mathcal{P}$  is analogous to  $T_{\delta}$  from our last paper (as will become apparent shortly). Note that each of our measurements  $y_I$  is of the form  $|\langle X, \mathbf{a}\mathbf{b}^* \rangle|^2$  where  $\mathbf{a}, \mathbf{b} \in \mathbb{C}^d$ . So, denoting by  $\overrightarrow{X} \in \mathbb{C}^{d^2}$  the (matlab-style)

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<sup>\*</sup>For any  $n \in \mathbb{Z}^+$  we will let  $[n] := \{1, 2, 3, \dots, n\} \subset \mathbb{Z}^+$ .

vectorization of  $X$ , and by  $A \otimes B$  the Kronecker product of  $A$  and  $B$ , we can write

$$\begin{aligned}
|\langle X, \mathbf{a}\mathbf{b}^* \rangle_{HS}|^2 &= |\text{Tr}(\mathbf{b}\mathbf{a}^* X)|^2 \\
&= |\mathbf{a}^* X \mathbf{b}|^2 = |\langle \overrightarrow{\mathbf{b}^T \otimes \mathbf{a}^*}, \overrightarrow{X} \rangle_{\ell_2^{d^2}}|^2 \\
&= \left( \langle \overrightarrow{\mathbf{b}^T \otimes \mathbf{a}^*}, \overrightarrow{X} \rangle_{\ell_2^{d^2}} \right)^* \cdot \langle \overrightarrow{\mathbf{b}^T \otimes \mathbf{a}^*}, \overrightarrow{X} \rangle_{\ell_2^{d^2}} \\
&= \overrightarrow{X}^* \overrightarrow{\mathbf{b}^T \otimes \mathbf{a}^*} (\overrightarrow{\mathbf{b}^T \otimes \mathbf{a}^*})^* \overrightarrow{X} \\
&= \text{Tr} \left( \overrightarrow{X} \overrightarrow{X}^* \overrightarrow{\mathbf{b}^T \otimes \mathbf{a}^*} (\overrightarrow{\mathbf{b}^T \otimes \mathbf{a}^*})^* \right) \\
&= \left\langle \overrightarrow{X} \overrightarrow{X}^*, \overrightarrow{\mathbf{b}^T \otimes \mathbf{a}^*} (\overrightarrow{\mathbf{b}^T \otimes \mathbf{a}^*})^* \right\rangle_{HS}
\end{aligned} \tag{5}$$

Accordingly, let  $\mathcal{A}$  be the linear operator given by

$$\mathcal{A} : (\mathbb{C}^{d^2 \times d^2}) \rightarrow \mathbb{R}^D$$

$$Z \mapsto \left( \left\langle Z, \overrightarrow{(S_\ell^* \mathbf{m}_j)^T \otimes (S_{\ell'}^* \mathbf{m}_{j'})^*} \overrightarrow{((S_\ell^* \mathbf{m}_j)^T \otimes (S_{\ell'}^* \mathbf{m}_{j'})^*)^*} \right\rangle_{HS} \right)_{(j,j',\ell,\ell') \in \mathcal{I}} \tag{6}$$

To generalize our theorem from the ACHA submission, we need (at least) two ingredients: The spectral gap of the adjacency matrix  $\mathcal{P}(\mathbb{1}\mathbb{1}^*)$  and the condition number of the linear operator  $\mathcal{A}$ .

## 2.1 Spectral gap of the adjacency matrix $\mathcal{P}(\mathbb{1}\mathbb{1}^*)$

Here note that the doubly indexed vertices  $(i, j), (i', j') \in [d] \times [d]$  are connected by an edge if and only if

$$|i - i'| \bmod d < \delta \quad \text{and} \quad |j - j'| \bmod d < \delta.$$

That is, the graph is the tensor-product of two identical graphs, each with adjacency matrix  $T_\delta(\mathbb{e}_d \mathbb{e}_d^*)$ . So that now

$$\mathcal{P}(\mathbb{e}_{d^2} \mathbb{e}_{d^2}^*) = T_\delta(\mathbb{e}_d \mathbb{e}_d^*) \otimes T_\delta(\mathbb{e}_d \mathbb{e}_d^*).$$

Using the fact that the eigenvalues of the Kronecker product are the pairwise products of the eigenvalues of the individual matrices, the spectral gap is now  $\mathcal{O}(\frac{\delta^4}{d^2})$ .

## 2.2 Condition number of the linear operator $\mathcal{A}$

We will show that  $\mathcal{A} = \mathcal{M} \otimes \mathcal{M}$  for an appropriate linear operator  $\mathcal{M} : T_\delta(\mathbb{C}^{d \times d}) \rightarrow \mathbb{R}^{d(2\delta-1)}$ .

### Observation 1:

Recall that each row of the matrix representation of  $\mathcal{A}$  from (??) is a vectorized version of a rank-1 matrix of the form  $\overrightarrow{\mathbf{b}^T \otimes \mathbf{a}^*} \overrightarrow{(\mathbf{b}^T \otimes \mathbf{a}^*)^*}$  as can be seen in (??), appropriately restricted (but let's worry about that later). Now, observe that

$$\overrightarrow{\mathbf{b}^T \otimes \mathbf{a}^*} \overrightarrow{(\mathbf{b}^T \otimes \mathbf{a}^*)^*} = (b_1 \mathbf{a}^*, \dots, b_d \mathbf{a}^*)^T (\bar{b}_1 \mathbf{a}, \dots, \bar{b}_d \mathbf{a})$$

so that the entries of the rank-1 matrix  $\overrightarrow{\mathbf{b}^T \otimes \mathbf{a}^*} \overrightarrow{(\mathbf{b}^T \otimes \mathbf{a}^*)^*}$  can be multi-indexed via

$$(\overrightarrow{\mathbf{b}^T \otimes \mathbf{a}^*} \overrightarrow{(\mathbf{b}^T \otimes \mathbf{a}^*)^*})_{m,n,m',n'} = b_m \bar{a}_n \bar{b}_{m'} a_{n'} = b_m \bar{b}_{m'} \bar{a}_n a_{n'}. \tag{7}$$

On the other hand, note that

$$\overrightarrow{\mathbf{a}^T \otimes \mathbf{a}^*} \overrightarrow{(\mathbf{b}^T \otimes \mathbf{b}^*)^*} = (a_1 \mathbf{a}^*, \dots, a_d \mathbf{a}^*)^T (\bar{b}_1 \mathbf{b}, \dots, \bar{b}_d \mathbf{b})$$

so that

$$\overrightarrow{(\mathbf{a}^T \otimes \mathbf{a}^*} \overrightarrow{(\mathbf{b}^T \otimes \mathbf{b}^*)^*})_{n', n, m', m} = b_m \bar{b}_{m'} \bar{a}_n a_{n'}. \quad (8)$$

Comparing (??) and (??) and noting that  $m, n$  and  $m', n'$  all range over the same set we see that (??) and (??) are the same up-to a permutation.

**Observation 2:**

In our case, each row of  $\mathcal{A}$  corresponds to some  $\mathbf{a} = S_{\ell'}^* \mathbf{m}_{j'}$  and  $\mathbf{b} = S_{\ell}^* \mathbf{m}_j$ , where every combination of  $(j, j', \ell, \ell') \in \mathcal{I}$  is taken. That is, every row of  $\mathcal{A}$  is a permutation of (a vectorized version) of

$$\overrightarrow{(S_{\ell}^* \mathbf{m}_j)^T \otimes (S_{\ell}^* \mathbf{m}_j)^*} \overrightarrow{((S_{\ell'}^* \mathbf{m}_{j'})^T \otimes (S_{\ell'}^* \mathbf{m}_{j'})^*)^*}$$

for some  $(j, j', \ell, \ell') \in \mathcal{I}$ . In other words we have a permutation of the Kronecker product of

$$\mathcal{M} : X \in \mathbb{C}^{d \times d} \mapsto (\langle X, (S_{\ell}^* \mathbf{m}_j)(S_{\ell}^* \mathbf{m}_j)^* \rangle)_{j, \ell}$$

with itself.

## ACKNOWLEDGMENTS

This work was supported in part by NSF DMS-1416752.