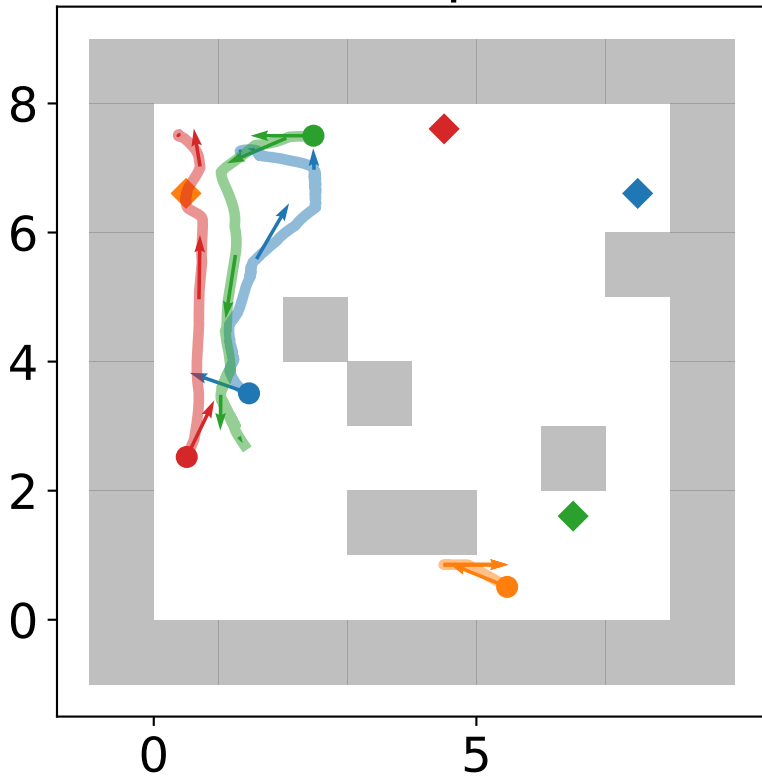
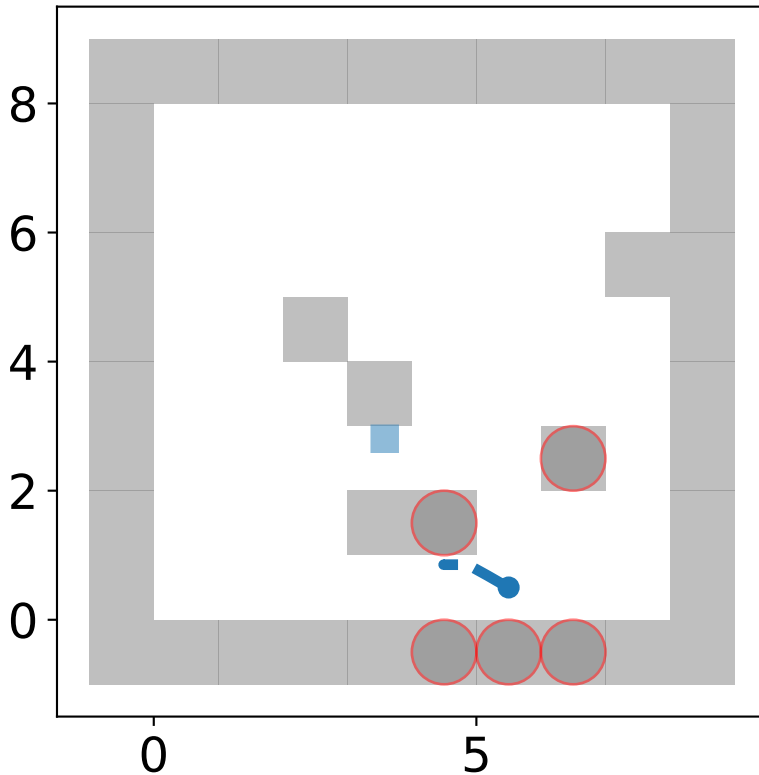


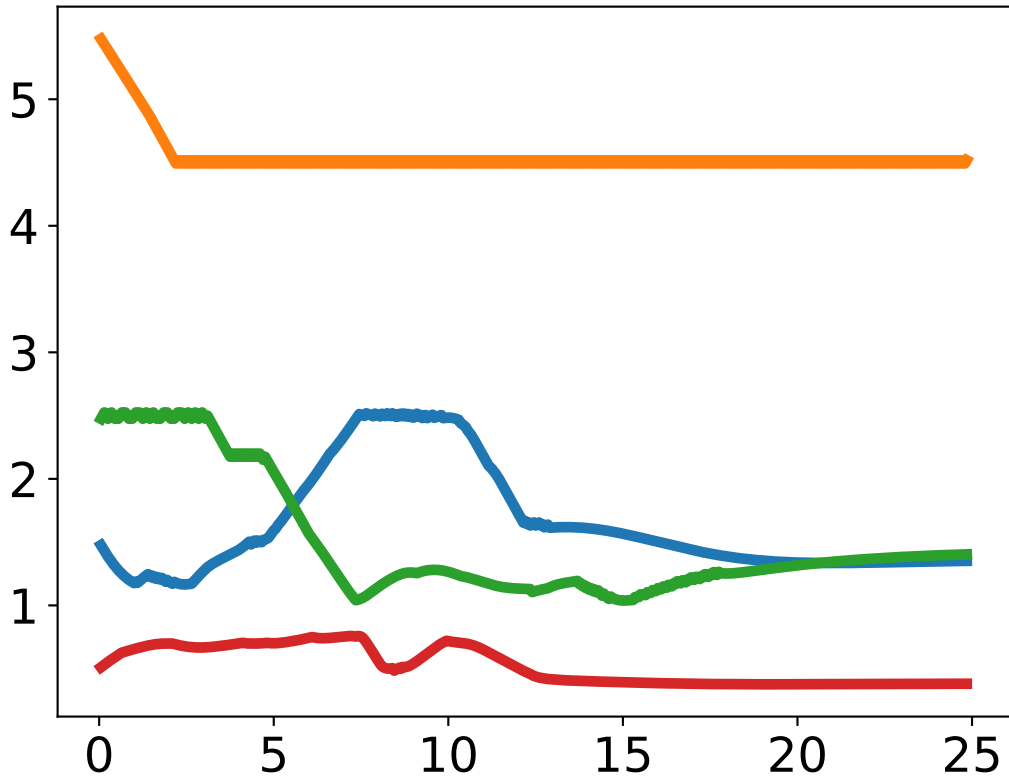
State Space



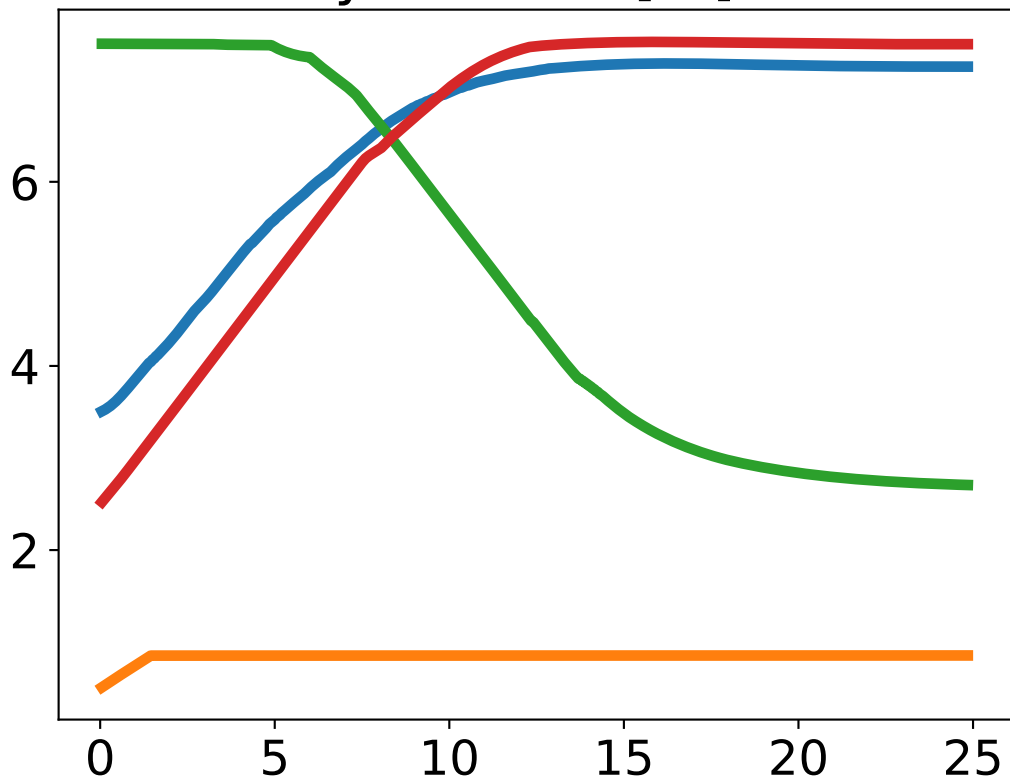
State at $t=0.0$ for robot=1



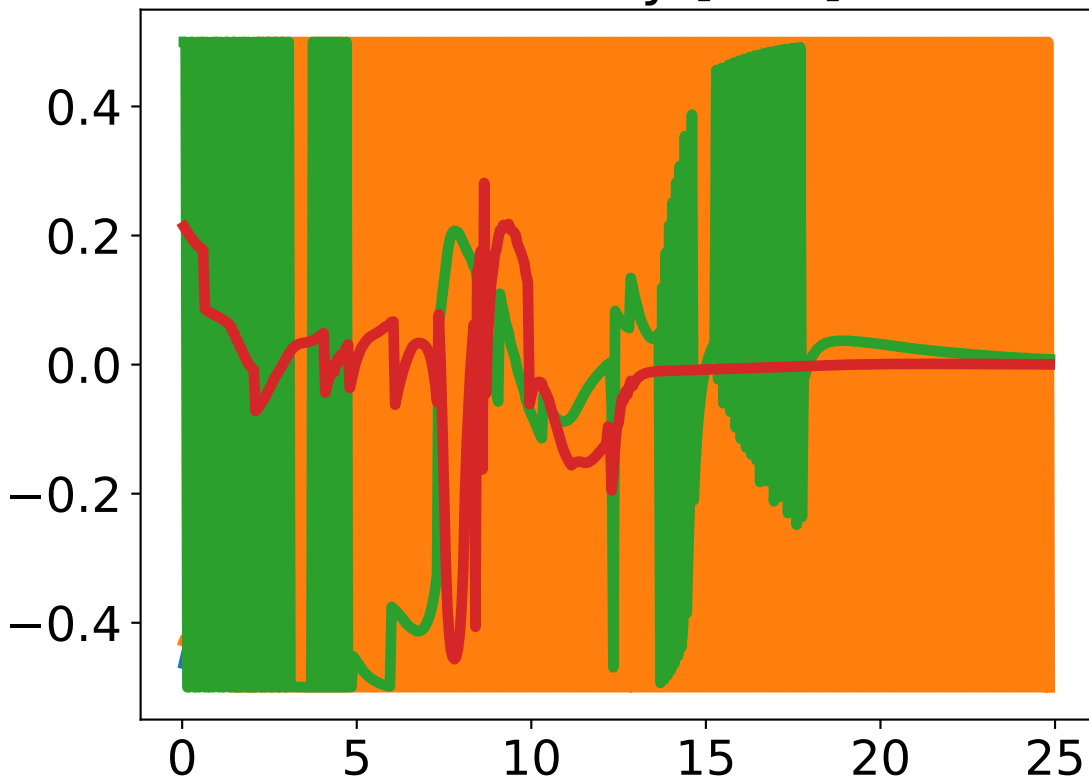
x-Position [m]



y-Position [m]



x-Velocity [m/s]



y-Velocity [m/s]

