

Gamma-Poisson Inference, Part 2

STAT 251, Unit 5B

Review

Derivation of the Posterior Distribution in Gamma-Poisson Setting

Examples of Gamma-Poisson Inference

Inference with multiple observations, y_1, y_2, \dots, y_n

Review

Recap from Gamma-Poisson, Part 1

We focused on the Poisson and Gamma families.

- Poisson distribution is a natural candidate for modeling count data with no upper bound (and which do not consist of a specific number of trials).
- Gamma distribution is a natural candidate for the prior distribution of the Poisson's rate parameter.
- Two forms for writing the probability density function of the gamma distribution
 - $\text{Gamma}(\text{shape}=a, \text{rate}=b)$
 - $\text{Gamma}(\text{shape}=a, \text{scale}=\beta)$
- Mean, variance of Poisson and Gamma distributions

- Analytical derivation of the posterior distribution of θ when $Y|\theta$ has the $Poisson(\theta)$ distribution and θ has the $Gamma(a,b)$ distribution (the so-called *Gamma-Poisson* setting).
- Practice with posterior inference in the Gamma-Poisson setting.
- Discuss inference if multiple y measurements are made.

Derivation of the Posterior Distribution in Gamma-Poisson Setting

Assume the so-called *Gamma-Poisson* setting. That is:

- $Y|\theta$ has the $Poisson(\theta)$ distribution
- θ has the $\text{Gamma}(\text{shape}=a, \text{rate}=b)$ prior distribution
- we observe a single observation, y

In this specific setting, the posterior distribution of $\theta|y$ is the $\text{Gamma}(\text{shape}=a+y, \text{rate}=b+1)$ distribution.

Gamma-Poisson Posterior Derivation, by definition (part 1)

$$\begin{aligned}\pi(\theta|y) &= \frac{\pi(\theta)f(y|\theta)}{f(y)} \\&= \frac{\pi(\theta)f(y|\theta)}{\int \pi(\theta)f(y|\theta)d\theta} \\&= \frac{\frac{b^a}{\Gamma(a)}\theta^{a-1}e^{-b\theta}\mathbb{1}_{\theta>0}\frac{\theta^y e^{-\theta}}{y!}\mathbb{1}_{y\in\{0,1,2,\dots\}}}{\int \frac{b^a}{\Gamma(a)}\theta^{a-1}e^{-b\theta}\mathbb{1}_{\theta>0}\frac{\theta^y e^{-\theta}}{y!}\mathbb{1}_{y\in\{0,1,2,\dots\}}d\theta} \\&= \frac{\frac{b^a}{\Gamma(a)y!}\theta^{a+y-1}e^{-(b+1)\theta}\mathbb{1}_{\theta>0}}{\frac{b^a}{\Gamma(a)y!}\int \theta^{a+y-1}e^{-(b+1)\theta}\mathbb{1}_{\theta>0}d\theta} \\&= \frac{\theta^{a+y-1}e^{-(b+1)\theta}\mathbb{1}_{\theta>0}}{\int \theta^{a+y-1}e^{-(b+1)\theta}\mathbb{1}_{\theta>0}d\theta} \\&= \frac{\theta^{a+y-1}e^{-(b+1)\theta}\mathbb{1}_{\theta>0}}{\int_0^\infty \theta^{a+y-1}e^{-(b+1)\theta}d\theta}\end{aligned}$$

Continued on next slide:

Gamma-Poisson Posterior Derivation, by definition (part 2)

Continued from previous slide:

$$\begin{aligned}\pi(\theta|y) &= \frac{\theta^{a+y-1} e^{-(b+1)\theta} \mathbb{1}_{\theta>0}}{\int_0^\infty \theta^{a+y-1} e^{-(b+1)\theta} d\theta} \\&= \frac{\frac{(b+1)^{a+y}}{\Gamma(a+y)} \theta^{a+y-1} e^{-(b+1)\theta} \mathbb{1}_{\theta>0}}{\underbrace{\int_0^\infty \frac{(b+1)^{a+y}}{\Gamma(a+y)} \theta^{a+y-1} e^{-(b+1)\theta} d\theta}_{=1}} \\&= \frac{(b+1)^{a+y}}{\Gamma(a+y)} \theta^{a+y-1} e^{-(b+1)\theta} \mathbb{1}_{\theta>0} \\&= \text{pdf of the } \textit{Gamma}(a^* = a + y, b^* = b + 1) \text{ distribution}\end{aligned}$$

The posterior distribution after observing a single y is

$$\theta|y \sim \textit{Gamma}(a^* = a + y, b^* = b + 1).$$

Analytical Derivation, using a shortcut

$$\begin{aligned}\pi(\theta|y) &= \frac{\pi(\theta)f(y|\theta)}{f(y)} \\ &\propto \pi(\theta)f(y|\theta) \\ &= \frac{b^a}{\Gamma(a)} \theta^{a-1} e^{-b\theta} \mathbb{1}_{\theta>0} \frac{\theta^y e^{-\theta}}{y!} \mathbb{1}_{y \in \{0,1,2,\dots\}} \\ &\propto \underbrace{\theta^{a+y-1} e^{-(b+1)\theta} \mathbb{1}_{\theta>0}}_{\text{kernel of Gamma}(a+y, b+1) \text{ pdf}} \\ &\propto \frac{(b+1)^{a+y}}{\Gamma(a+y)} \theta^{a+y-1} e^{-(b+1)\theta} \mathbb{1}_{\theta>0} \\ &= \text{pdf of } \text{Gamma}(a^* = a+y, b^* = b+1) \text{ dist.}\end{aligned}$$

Although the above equations imply the posterior is *proportional* to the $\text{Gamma}(a^*, b^*)$ *distribution*, why are we able to conclude that the posterior (i.e., $\pi(\theta|y)$) *IS* the $\text{Gamma}(a^*, b^*)$ distribution?

The *kernel* of a pmf/pdf is the portion that depends explicitly on the variable.

Examples of Gamma-Poisson Inference

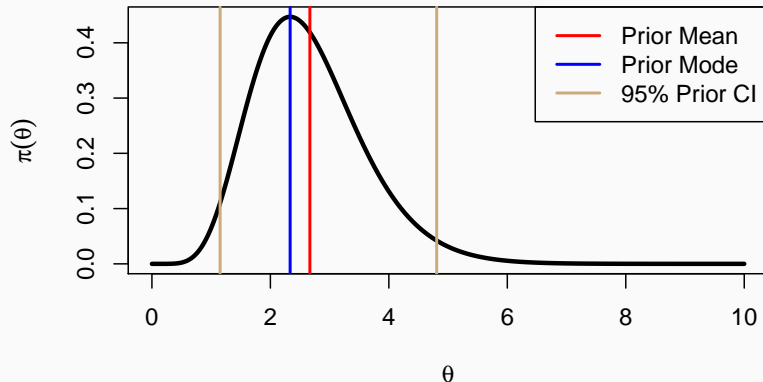
Suppose that we are considering the scoring ability of the 2016 BYU women's soccer team. Specifically, we are interested in θ = expected number of goals scored in a randomly selected game.

I will assume that given θ , Y = number of goals scored in a game has the *Poisson*(θ) distribution.

My prior distribution is the Gamma(shape=8, rate=3) distribution.

Plot of my Prior, with selected Prior Summaries

**My Prior Distribution for Expected Goals in a Game:
Gamma(shape=8, rate=3)**



Prior Mean: $a/b = 8/3$; Prior Mode: $(a-1)/b = 7/3$; 95% Prior Credible Interval (from 2.5th, 97.5th percentiles): (1.15, 4.81).

Posterior (after 1 game)

In first non-exhibition game, BYU won 2-1 over Washington State.
With this match result, what is my posterior distribution?

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observed $y = 2$.

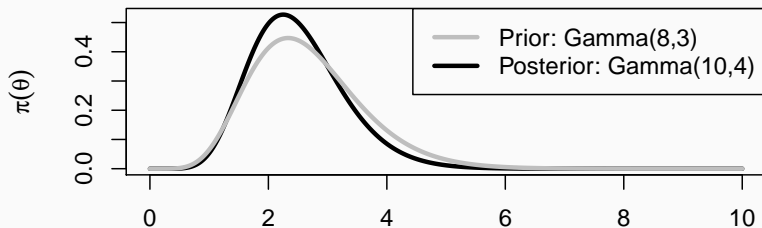
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Posterior: $\theta|y \sim \text{Gamma}(a^* = a + y = 10, b^* = b + 1 = 4)$.

My Prior/Posterior Distributions for Expected Goals in a Game, 1 game into the 2016 season



Posterior (after 2nd game)

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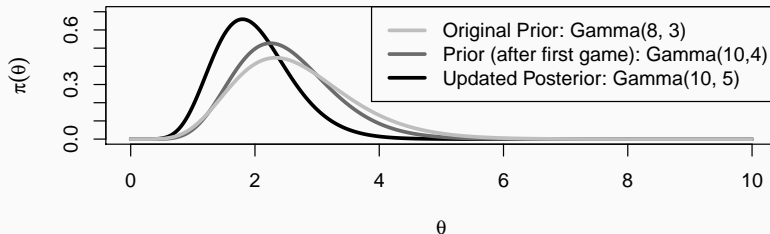
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Updated Posterior:

$\theta|y \sim \text{Gamma}(a^* = a + y = 10, b^* = b + 1 = 5)$.

**My Prior/Posterior Distributions for
Expected Goals in a Game, 1 game into the 2016 season**



Prior Elicitation for Gamma-Poisson Setting

In the setting where $Y|\theta \sim \text{Poisson}(\theta)$ and $\theta \sim \text{Gamma}(\text{shape} = a, \text{rate} = b)$:

- If we have little idea of what θ might be, it is common to choose both a and b to be very small (e.g., $a=1$, $b=1$ or even $a=.01$, $b=.01$)
- If we can choose the prior mean, $E(\theta) = \mu$, and the prior standard deviation, $SD(\theta) = \sigma$, then we can solve for a and b using the fact that for a Gamma random variable, the mean is $\mu = \frac{a}{b}$ and the standard deviation is $\sigma = \frac{\sqrt{a}}{b}$.

Another alternative for Prior Elicitation

As with the beta prior distribution, we can choose a and b by considering how our prior beliefs would equate to an equivalent number of observations. To use such a method for the gamma distribution, we interpret b as the total number of prior units “observed”, and a as the total number of prior occurrences “observed” in the prior units.

For example, suppose I equate my knowledge about the scoring ability of BYU's 2017 women's soccer team to be about six games' worth of information, with about 17 total goals scored. Then I could use the $\text{gamma}(a = 17, b = 6)$ prior distribution for θ .

I find this approach difficult to implement because it is often abstract.

Inference with multiple observations,

y_1, y_2, \dots, y_n

What to do with multiple observations?

We have placed greatest emphasis on observing a single random variable y .

Often, multiple observations are made. That is, we have y_1, y_2, \dots, y_n , where n represents the number of observed y 's.

This will produce only a slight change in the implementation of our Bayesian procedure. As before, we note that

$posterior = \frac{prior \times likelihood}{marginal\ likelihood}$, and $posterior \propto prior \times likelihood$.

The change is in how we compute the

likelihood— $f(y_1, y_2, \dots, y_n | \theta)$ —and consequently also the marginal likelihood— $f(y_1, y_2, \dots, y_n)$.

Determining $f(y_1, y_2, \dots, y_n|\theta)$: Conditional Independence

In STAT 251, we will assume that observations are *conditionally independent and identically distributed*. What does this mean?

First consider conditional independence:

The random variables $Y_1|\theta, Y_2|\theta, \dots, Y_n|\theta$ are said to be *conditionally independent* if, conditional on θ , each Y_i is mutually independent of the others.

If $Y_1|\theta, Y_2|\theta, \dots, Y_n|\theta$ are conditionally independent, then

$$\begin{aligned} f(\{y_1, y_2, \dots, y_n\}|\theta) &= f_{y_1|\theta}(y_1|\theta) f_{y_2|\theta}(y_2|\theta) \cdots f_{y_n|\theta}(y_n|\theta) \\ &= \prod_{i=1}^n f_{y_i|\theta}(y_i|\theta) \end{aligned}$$

The subscripts on the pdf/pmf, (e.g., $f_{y_1|\theta}$ and $f_{y_2|\theta}$) are to allow for the possibility that $Y_i|\theta$ and $Y_j|\theta$ have different marginal distributions.

Determining $f(y_1, y_2, \dots, y_n|\theta)$: Conditionally Identically Distributed

The random variables $Y_1|\theta, Y_2|\theta, \dots, Y_n|\theta$ are said to be *conditionally identically distributed* if, conditional on θ , each Y_i has the exact same distribution.

That is, $f_{y_1|\theta}(y|\theta) = f_{y_2|\theta}(y|\theta) = \dots = f_{y_n|\theta}(y|\theta)$ for all y

Because identically distributed random variables share the same pmf/pdf, then there is no need to have a separate subscript for each pmf/pdf. That is, instead of writing $f_{y_1|\theta}$ or $f_{y_2|\theta}$, we can simply write $f_{y|\theta}$ or even just f .

Determining $f(y_1, y_2, \dots, y_n|\theta)$: Conditionally Independent and Identically Distributed

$Y_1|\theta, Y_2|\theta, \dots, Y_n|\theta$ are said to be *conditionally independent and identically distributed* if they are conditionally independent and they are conditionally identically distributed.

Conditionally independent and identically distributed is abbreviated as conditionally **iid**.

If $Y_1|\theta, Y_2|\theta, \dots, Y_n|\theta$ are conditionally *iid* then

$$f(\{y_1, y_2, \dots, y_n\}|\theta) = \prod_{i=1}^n f(y_i|\theta).$$

Likelihood of n conditionally *iid* Poisson observations

Suppose that

$$y_i | \theta \stackrel{iid}{\sim} \text{Poisson}(\theta),$$

so that $f(y_i | \theta) = \frac{\exp(-\theta)\theta^{y_i}}{y_i!}$ for all i .

Note the notation above to state that the Y_i 's are (conditionally) independent and identically distributed: $\stackrel{iid}{\sim}$

Then the likelihood is

$$\begin{aligned} f(y_1, y_2, \dots, y_n | \theta) &= \prod_{i=1}^n f(y_i | \theta) \\ &= \prod_{i=1}^n \frac{\exp(-\theta)\theta^{y_i}}{y_i!} \\ &= \frac{\exp(-n\theta)\theta^{\sum y_i}}{\prod_{i=1}^n y_i!} \end{aligned}$$

We often regard the Y_i 's as being *conditionally independent*, which means that each $y_i|\theta$ is independent of every other $Y_j|\theta$.

Technical Note: Why would we NOT be able to say that (marginally) Y_i and Y_j are independent? Because both depend on θ , and this induces some dependence between Y_i and Y_j . For example, if θ is large, $Y_i|\theta$ and $Y_j|\theta$ both are likely to be large; if θ is small, they are both likely to be small. Across the distribution for θ , then, there is some positive association between Y_i and Y_j .

Back to the soccer example

Let's consider the likelihood function for the number of goals scored in the first game, y_1 , then for the second game, y_2 , etc.

We will assume the number of goals scored in each game are *conditionally iid*.

More precisely, we assume $Y_i|\theta \stackrel{iid}{\sim} \text{Poisson}(\theta)$.

Suppose (temporarily—just for the next four slides) that we knew $\theta = 3.1$.

What is the likelihood of the soccer team scoring 2 goals in a game?

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Suppose (temporarily—just for the next four slides) that we knew $\theta = 3.1$.

What is the likelihood of the soccer team scoring 2 goals in a game? $f(2|\theta = 3.1) = \frac{\exp(-3.1)3.1^2}{2!}$

```
dpois(2, 3.1)
```

```
## [1] 0.2164614
```

Soccer Example, continued

What is the likelihood of the soccer team scoring 0 goals in a game?

```
dpois(0, 3.1)
```

```
## [1] 0.0450492
```

What is the likelihood of the soccer team scoring 2 goals in the first game **and** 0 goals in the second?

Soccer Example, continued

What is the likelihood of the soccer team scoring 0 goals in a game?

```
dpois(0, 3.1)
```

```
## [1] 0.0450492
```

What is the likelihood of the soccer team scoring 2 goals in the first game **and** 0 goals in the second?

Because we assumed the goals scored are conditionally iid,

$$f(y_1 = 2, y_2 = 0 | \theta = 3.1) = f(y_1 = 2 | \theta = 3.1) f(y_2 = 0 | \theta = 3.1)$$

```
dpois(2, 3.1)* dpois(0, 3.1)
```

```
## [1] 0.009751414
```


R trick to compute likelihoods when assuming data are conditionally iid

The R functions `dbinom`, `dpois`, and `dnorm` can accept multiple values for the first argument. When a vector of values are passed as the first argument, it evaluates the probability/density at each value. Compare with the previous two slides:

```
dpois( c( 0, 2), 3.1)
```

```
## [1] 0.0450492 0.2164614
```

To get the likelihood for conditionally iid data, you can feed the vector of data values into the function and then take the product using the *prod()* function. Compare with the previous slide:

```
prod( dpois( c(0,2), 3.1) )
```

```
## [1] 0.009751414
```

Compute the likelihood function for all 19 regular season games

Here is a vector of the goals scored:

```
goals <- c(2, 0, 3, 5, 2, 4, 3, 3, 7, 1,  
           0, 4, 1, 0, 3, 2, 4, 4, 6)
```

Evaluate the likelihood of observing these data if θ were known to equal 3.1

Evaluate the likelihood of observing these data if θ were known to equal 2.5

Evaluate the likelihood of observing these data if θ were known to equal $\bar{y} = 54/19$; this is the maximum likelihood estimate of θ

How do we interpret these likelihood values? And why are they so small?

Posterior Inference after observing y_1, y_2, \dots, y_n

If $Y_i|\theta \stackrel{iid}{\sim} \text{Poisson}(\theta)$, and if $\theta \sim \text{Gamma}(a, b)$, then
 $\theta|\{y_1, y_2, \dots, y_n\} \sim \text{Gamma}(a + \sum y_i, b + n)$

Derivation: on board

Soccer Goal Example, finalized

Recall that we have a vector for the goals scored in each game. A quick method to determine n is to find out the *length* (Number of elements) in the data vector *goals*.

```
length(goals)
```

```
## [1] 19
```

A quick method to determine the total number of occurrences of interest (in this case, total goals scored), is to use the *sum* function.

```
sum(goals)
```

```
## [1] 54
```

Posterior for $\theta \equiv$ expected goals scored in a game, after observing all 19 Regular Season match scores

The prior was the $\text{Gamma}(a=8, b=3)$ distribution, and thus the posterior (after observing that 54 goals were scored in 19 games) is the $\text{Gamma}(a^* = 8 + 54 = 62, b^* = 3 + 19 = 22)$ distribution.

My Prior/Posterior Distributions for Expected Goals in a Game, 19 games into the 2016 season

