

Source code for `qutip.sesolve`

```

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#####
"""
This module provides solvers for the unitary Schrodinger equation.
"""

__all__ = ['sesolve']

import os
import types
from functools import partial
import numpy as np
import scipy.integrate
from scipy.linalg import norm

from qutip.qobj import Qobj, isket
from qutip.rhs_generate import rhs_generate
from qutip.solver import Result, Options, config, _solver_safety_check
from qutip.rhs_generate import _td_format_check, _td_wrap_array_str
from qutip.interpolate import Cubic_Spline
from qutip.settings import debug
from qutip.cy.spmatfuncs import (cy_expect_psi, cy_ode_rhs,
                                cy_ode_psi_func_td,
                                cy_ode_psi_func_td_with_state)
from qutip.cy.codegen import Codegen

from qutip.ui.progressbar import BaseProgressBar

if debug:

```

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import inspect
```

[\[docs\]](#)

```
def sesolve(H, rho0, tlist, e_ops=[], args={}, options=None,
            progress_bar=BaseProgressBar(),
            _safe_mode=True):
    """
    Schrodinger equation evolution of a state vector for a given Hamiltonian.

    Evolve the state vector or density matrix (`rho0`) using a given
    Hamiltonian (`H`), by integrating the set of ordinary differential
    equations that define the system.

    The output is either the state vector at arbitrary points in time
    (`tlist`), or the expectation values of the supplied operators
    (`e_ops`). If e_ops is a callback function, it is invoked for each
    time in `tlist` with time and the state as arguments, and the function
    does not use any return values.

    Parameters
    -----

    H : :class:`qutip.qobj`
        system Hamiltonian, or a callback function for time-dependent
        Hamiltonians.

    rho0 : :class:`qutip.qobj`
        initial density matrix or state vector (ket).

    tlist : *list* / *array*
        list of times for :math:t`.

    e_ops : list of :class:`qutip.qobj` / callback function single
        single operator or list of operators for which to evaluate
        expectation values.

    args : *dictionary*
        dictionary of parameters for time-dependent Hamiltonians and
        collapse operators.

    options : :class:`qutip.Qdeoptions`
        with options for the ODE solver.

    Returns
    -----

    output: :class:`qutip.solver`

    An instance of the class :class:`qutip.solver`, which contains either
    an *array* of expectation values for the times specified by `tlist`, or
    an *array* or state vectors or density matrices corresponding to the
    times in `tlist` [if `e_ops` is an empty list], or
    nothing if a callback function was given inplace of operators for
    which to calculate the expectation values.

    """
    if _safe_mode:
        _solver_safety_check(H, rho0, c_ops=[], e_ops=e_ops, args=args)
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if isinstance(e_ops, Qobj):
    e_ops = [e_ops]

if isinstance(e_ops, dict):
    e_ops_dict = e_ops
    e_ops = [e for e in e_ops.values()]
else:
    e_ops_dict = None

# convert array based time-dependence to string format
H, _, args = _td_wrap_array_str(H, [], args, tlist)
# check for type (if any) of time-dependent inputs
n_const, n_func, n_str = _td_format_check(H, [])

if options is None:
    options = Options()

if (not options.rhs_reuse) or (not config.tdfunc):
    # reset config time-dependence flags to default values
    config.reset()

if n_func > 0:
    res = _sesolve_list_func_td(H, rho0, tlist, e_ops, args, options,
                               progress_bar)

elif n_str > 0:
    res = _sesolve_list_str_td(H, rho0, tlist, e_ops, args, options,
                              progress_bar)

elif isinstance(H, (types.FunctionType,
                    types.BuiltinFunctionType,
                    partial)):
    res = _sesolve_func_td(H, rho0, tlist, e_ops, args, options,
                           progress_bar)

else:
    res = _sesolve_const(H, rho0, tlist, e_ops, args, options,
                         progress_bar)

if e_ops_dict:
    res.expect = {e: res.expect[n]
                  for n, e in enumerate(e_ops_dict.keys())}

return res

```

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# -----
# A time-dependent unitary wavefunction equation on the list-function format
#
def _sesolve_list_func_td(H_list, psi0, tlist, e_ops, args, opt,
                          progress_bar):
    """
    Internal function for solving the master equation. See mesolve for usage.
    """

    if debug:
        print(inspect.stack()[0][3])

    #

```

```

# check initial state
#
if not isket(psi0):
    raise TypeError("The unitary solver requires a ket as initial state")

#
# construct Liouvillian in list-function format
#
L_list = []
if not opt.rhs_with_state:
    constant_func = lambda x, y: 1.0
else:
    constant_func = lambda x, y, z: 1.0

# add all hamitonian terms to the Lagrangian list
for h_spec in H_list:

    if isinstance(h_spec, Qobj):
        h = h_spec
        h_coeff = constant_func

    elif isinstance(h_spec, list):
        h = h_spec[0]
        h_coeff = h_spec[1]

    else:
        raise TypeError("Incorrect specification of time-dependent " +
                        "Hamiltonian (expected callback function)")

    L_list.append([-1j * h.data, h_coeff])

L_list_and_args = [L_list, args]

#
# setup integrator
#
initial_vector = psi0.full().ravel()
if not opt.rhs_with_state:
    r = scipy.integrate.ode(psi_list_td)
else:
    r = scipy.integrate.ode(psi_list_td_with_state)
r.set_integrator('zvode', method=opt.method, order=opt.order,
                 atol=opt.atol, rtol=opt.rtol, nsteps=opt.nsteps,
                 first_step=opt.first_step, min_step=opt.min_step,
                 max_step=opt.max_step)
r.set_initial_value(initial_vector, tlist[0])
r.set_f_params(L_list_and_args)

#
# call generic ODE code
#
return _generic_ode_solve(r, psi0, tlist, e_ops, opt, progress_bar,
                          dims=psi0.dims)

#
# evaluate dpsi(t)/dt according to the master equation using the
# [Qobj, function] style time dependence API
#
def psi_list_td(t, psi, H_list_and_args):

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H_list = H_list_and_args[0]
args = H_list_and_args[1]

H = H_list[0][0] * H_list[0][1](t, args)
for n in range(1, len(H_list)):
    #
    # args[n][0] = the sparse data for a Qobj in operator form
    # args[n][1] = function callback giving the coefficient
    #
    H = H + H_list[n][0] * H_list[n][1](t, args)

return H * psi

```

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def psi_list_td_with_state(t, psi, H_list_and_args):

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    H_list = H_list_and_args[0]
    args = H_list_and_args[1]

    H = H_list[0][0] * H_list[0][1](t, psi, args)
    for n in range(1, len(H_list)):
        #
        # args[n][0] = the sparse data for a Qobj in operator form
        # args[n][1] = function callback giving the coefficient
        #
        H = H + H_list[n][0] * H_list[n][1](t, psi, args)

    return H * psi

```

```

# -----
# Wave function evolution using a ODE solver (unitary quantum evolution) using
# a constant Hamiltonian.
#
def _solve_const(H, psi0, tlist, e_ops, args, opt, progress_bar):
    """!
    Evolve the wave function using an ODE solver
    """
    if debug:
        print(inspect.stack()[0][3])

    if not isket(psi0):
        raise TypeError("psi0 must be a ket")

    #
    # setup integrator.
    #
    initial_vector = psi0.full().ravel()
    r = scipy.integrate.ode(cy_ode_rhs)
    L = -1.0j * H
    r.set_f_params(L.data.data, L.data.indices, L.data.indptr) # cython RHS
    r.set_integrator('zvode', method=opt.method, order=opt.order,
                    atol=opt.atol, rtol=opt.rtol, nsteps=opt.nsteps,
                    first_step=opt.first_step, min_step=opt.min_step,
                    max_step=opt.max_step)

    r.set_initial_value(initial_vector, tlist[0])

    #

```

```

# call generic ODE code
#
return _generic_ode_solve(r, psi0, tlist, e_ops, opt,
                          progress_bar, dims=psi0.dims)

#
# evaluate dpsi(t)/dt [not used. using cython function is being used instead]
#
def _ode_psi_func(t, psi, H):
    return H * psi

# -----
# A time-dependent dissipative master equation on the list-string format for
# cython compilation
#
def _sesolve_list_str_td(H_list, psi0, tlist, e_ops, args, opt,
                          progress_bar):
    """
    Internal function for solving the master equation. See mesolve for usage.
    """

    if debug:
        print(inspect.stack()[0][3])

    #
    # check initial state: must be a density matrix
    #
    if not isket(psi0):
        raise TypeError("The unitary solver requires a ket as initial state")

    #
    # construct Liouvillian
    #
    Ldata = []
    Linds = []
    Lptrs = []
    Lcoeff = []
    Lobj = []

    # Loop over all hamiltonian terms, convert to superoperator form and
    # add the data of sparse matrix representation to h_coeff
    for h_spec in H_list:

        if isinstance(h_spec, Qobj):
            h = h_spec
            h_coeff = "1.0"

        elif isinstance(h_spec, list):
            h = h_spec[0]
            h_coeff = h_spec[1]

        else:
            raise TypeError("Incorrect specification of time-dependent " +
                             "Hamiltonian (expected string format)")

        L = -1j * h

        Ldata.append(L.data.data)

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Linds.append(L.data.indices)
Lptrs.append(L.data.indptr)
if isinstance(h_coeff, Cubic_Spline):
    Lobj.append(h_coeff.coeffs)
Lcoeff.append(h_coeff)

# the total number of liouvillian terms (hamiltonian terms +
# collapse operators)
n_L_terms = len(Ldata)

#
# setup ode args string: we expand the list Ldata, Linds and Lptrs into
# and explicit list of parameters
#
string_list = []
for k in range(n_L_terms):
    string_list.append("Ldata[%d], Linds[%d], Lptrs[%d]" % (k, k, k))
# Add object terms to end of ode args string
for k in range(len(Lobj)):
    string_list.append("Lobj[%d]" % k)

for name, value in args.items():
    if isinstance(value, np.ndarray):
        string_list.append(name)
    else:
        string_list.append(str(value))
parameter_string = ",".join(string_list)

#
# generate and compile new cython code if necessary
#
if not opt.rhs_reuse or config.tdfunc is None:
    if opt.rhs_filename is None:
        config.tdname = "rhs" + str(os.getpid()) + str(config.cgen_num)
    else:
        config.tdname = opt.rhs_filename
    cgen = Codegen(h_terms=n_L_terms, h_tdterms=Lcoeff, args=args,
                  config=config)
    cgen.generate(config.tdname + ".pyx")

    code = compile('from ' + config.tdname + ' import cy_td_ode_rhs',
                  '<string>', 'exec')
    exec(code, globals())
    config.tdfunc = cy_td_ode_rhs

#
# setup integrator
#
initial_vector = psi0.full().ravel()
r = scipy.integrate.ode(config.tdfunc)
r.set_integrator('zvode', method=opt.method, order=opt.order,
                atol=opt.atol, rtol=opt.rtol, nsteps=opt.nsteps,
                first_step=opt.first_step, min_step=opt.min_step,
                max_step=opt.max_step)
r.set_initial_value(initial_vector, tlist[0])
code = compile('r.set_f_params(' + parameter_string + ')',
                '<string>', 'exec')

exec(code, locals(), args)

```



```

#
# call generic ODE code
#
return _generic_ode_solve(r, psi0, tlist, e_ops, opt, progress_bar,
                          dims=psi0.dims)

# -----
# Wave function evolution using a ODE solver (unitary quantum evolution), for
# time dependent hamiltonians
#
def _sesolve_list_td(H_func, psi0, tlist, e_ops, args, opt, progress_bar):
    """
    Evolve the wave function using an ODE solver with time-dependent
    Hamiltonian.
    """

    if debug:
        print(inspect.stack()[0][3])

    if not isket(psi0):
        raise TypeError("psi0 must be a ket")

    #
    # configure time-dependent terms and setup ODE solver
    #
    if len(H_func) != 2:
        raise TypeError('Time-dependent Hamiltonian list must have two terms.')
    if (not isinstance(H_func[0], (list, np.ndarray))) or \
        (len(H_func[0]) <= 1):
        raise TypeError('Time-dependent Hamiltonians must be a list with two '
                        + 'or more terms')
    if (not isinstance(H_func[1], (list, np.ndarray))) or \
        (len(H_func[1]) != (len(H_func[0]) - 1)):
        raise TypeError('Time-dependent coefficients must be list with ' +
                        'length N-1 where N is the number of ' +
                        'Hamiltonian terms.')

    tflag = 1
    if opt.rhs_reuse and config.tdfunc is None:
        print("No previous time-dependent RHS found.")
        print("Generating one for you...")
        rhs_generate(H_func, args)
    lenh = len(H_func[0])
    if opt.tidy:
        H_func[0] = [(H_func[0][k]).tidyup() for k in range(lenh)]
    # create data arrays for time-dependent RHS function
    Hdata = [-1.0j * H_func[0][k].data.data for k in range(lenh)]
    Hinds = [H_func[0][k].data.indices for k in range(lenh)]
    Hptrs = [H_func[0][k].data.indptr for k in range(lenh)]
    # setup ode args string
    string = ""
    for k in range(lenh):
        string += ("Hdata[" + str(k) + "], Hinds[" + str(k) +
                  "], Hptrs[" + str(k) + "],")

    if args:
        td_consts = args.items()
        for elem in td_consts:
            string += str(elem[1])
            if elem != td_consts[-1]:

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        string += (",")

# run code generator
if not opt.rhs_reuse or config.tdfunc is None:
    if opt.rhs_filename is None:
        config.tdname = "rhs" + str(os.getpid()) + str(config.cgen_num)
    else:
        config.tdname = opt.rhs_filename
    cgen = Codegen(h_terms=n_L_terms, h_tdterms=Lcoeff, args=args,
                  config=config)
    cgen.generate(config.tdname + ".pyx")

    code = compile('from ' + config.tdname + ' import cy_td_ode_rhs',
                  '<string>', 'exec')
    exec(code, globals())
    config.tdfunc = cy_td_ode_rhs

#
# setup integrator
#
initial_vector = psi0.full().ravel()
r = scipy.integrate.ode(config.tdfunc)
r.set_integrator('zvode', method=opt.method, order=opt.order,
                atol=opt.atol, rtol=opt.rtol, nsteps=opt.nsteps,
                first_step=opt.first_step, min_step=opt.min_step,
                max_step=opt.max_step)
r.set_initial_value(initial_vector, tlist[0])
code = compile('r.set_f_params(' + string + ')', '<string>', 'exec')
exec(code)

#
# call generic ODE code
#
return _generic_ode_solve(r, psi0, tlist, e_ops, opt, progress_bar
                        , dims=psi0.dims)

# -----
# Wave function evolution using a ODE solver (unitary quantum evolution), for
# time dependent hamiltonians
#
def _solve_func_td(H_func, psi0, tlist, e_ops, args, opt, progress_bar):
    """!
    Evolve the wave function using an ODE solver with time-dependent
    Hamiltonian.
    """

    if debug:
        print(inspect.stack()[0][3])

    if not isket(psi0):
        raise TypeError("psi0 must be a ket")

    #
    # setup integrator
    #
    new_args = None

    if type(args) is dict:
        new_args = {}
        for key in args:

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        if isinstance(args[key], Qobj):
            new_args[key] = args[key].data
        else:
            new_args[key] = args[key]

    elif type(args) is list or type(args) is tuple:
        new_args = []
        for arg in args:
            if isinstance(arg, Qobj):
                new_args.append(arg.data)
            else:
                new_args.append(arg)

        if type(args) is tuple:
            new_args = tuple(new_args)
    else:
        if isinstance(args, Qobj):
            new_args = args.data
        else:
            new_args = args

    initial_vector = psi0.full().ravel()

    if not opt.rhs_with_state:
        r = scipy.integrate.ode(cy_ode_psi_func_td)
    else:
        r = scipy.integrate.ode(cy_ode_psi_func_td_with_state)

    r.set_integrator('zvode', method=opt.method, order=opt.order,
                    atol=opt.atol, rtol=opt.rtol, nsteps=opt.nsteps,
                    first_step=opt.first_step, min_step=opt.min_step,
                    max_step=opt.max_step)
    r.set_initial_value(initial_vector, tlist[0])
    r.set_f_params(H_func, new_args)

    #
    # call generic ODE code
    #
    return _generic_ode_solve(r, psi0, tlist, e_ops, opt, progress_bar,
                             dims=psi0.dims)

#
# evaluate dpsi(t)/dt for time-dependent hamiltonian
#
def _ode_psi_func_td(t, psi, H_func, args):
    H = H_func(t, args)
    return -1j * (H * psi)

def _ode_psi_func_td_with_state(t, psi, H_func, args):
    H = H_func(t, psi, args)
    return -1j * (H * psi)

# -----
# Solve an ODE which solver parameters already setup (r). Calculate the
# required expectation values or invoke callback function at each time step.
#
def _generic_ode_solve(r, psi0, tlist, e_ops, opt, progress_bar, dims=None):

```

```

"""
Internal function for solving ODEs.
"""

if opt.normalize_output:
    state_norm_func = norm
else:
    state_norm_func = None

#
# prepare output array
#
n_tsteps = len(tlist)
output = Result()
output.solver = "sesolve"
output.times = tlist

if opt.store_states:
    output.states = []

if isinstance(e_ops, types.FunctionType):
    n_expt_op = 0
    expt_callback = True

elif isinstance(e_ops, list):
    n_expt_op = len(e_ops)
    expt_callback = False

    if n_expt_op == 0:
        # fallback on storing states
        output.states = []
        opt.store_states = True
    else:
        output.expect = []
        output.num_expect = n_expt_op
        for op in e_ops:
            if op.isherm:
                output.expect.append(np.zeros(n_tsteps))
            else:
                output.expect.append(np.zeros(n_tsteps, dtype=complex))
else:
    raise TypeError("Expectation parameter must be a list or a function")

#
# start evolution
#
progress_bar.start(n_tsteps)

dt = np.diff(tlist)
for t_idx, t in enumerate(tlist):
    progress_bar.update(t_idx)

    if not r.successful():
        raise Exception("ODE integration error: Try to increase "
                        "the allowed number of substeps by increasing "
                        "the nsteps parameter in the Options class.")

    if state_norm_func:
        data = r.y / state_norm_func(r.y)

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        r.set_initial_value(data, r.t)

    if opt.store_states:
        output.states.append(Qobj(r.y, dims=dims))

    if expt_callback:
        # use callback method
        e_ops(t, Qobj(r.y, dims=psi0.dims))

    for m in range(n_expt_op):
        output.expect[m][t_idx] = cy_expect_psi(e_ops[m].data,
                                                r.y, e_ops[m].isherm)

    if t_idx < n_tsteps - 1:
        r.integrate(r.t + dt[t_idx])

progress_bar.finished()

if not opt.rhs_reuse and config.tdname is not None:
    try:
        os.remove(config.tdname + ".pyx")
    except:
        pass

if opt.store_final_state:
    output.final_state = Qobj(r.y, dims=dims)

return output

```