

Algorithms – I (CS29003/203)

Autumn 2022, IIT Kharagpur

Graphs

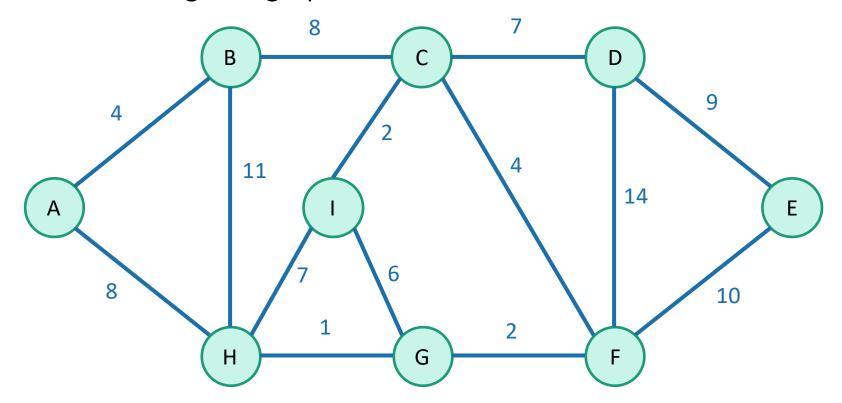


Resources

- Apart from the book
- UC Riverside, CS 141 course, Fall 2021 by Prof. Yan Gu and Prof. Yihan Sun
- Stanford University, CS 161 course, Winter 2022 by Prof. Moses Charikar and Prof. Nima Anari

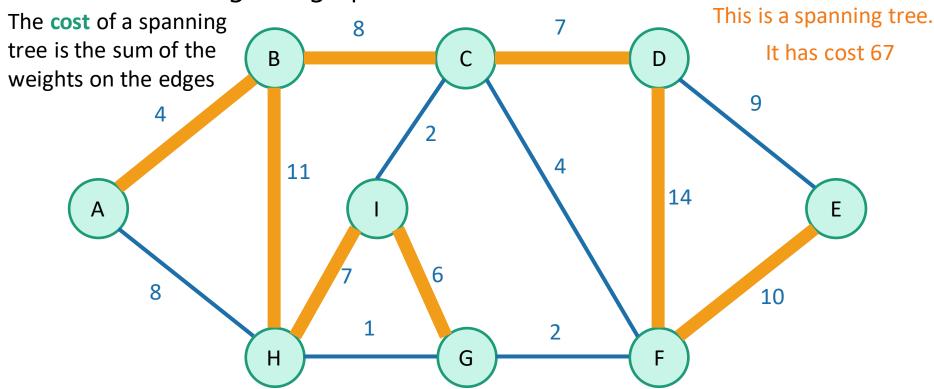


• For today we will focus on connected graphs. Say we have an undirected weighted graph



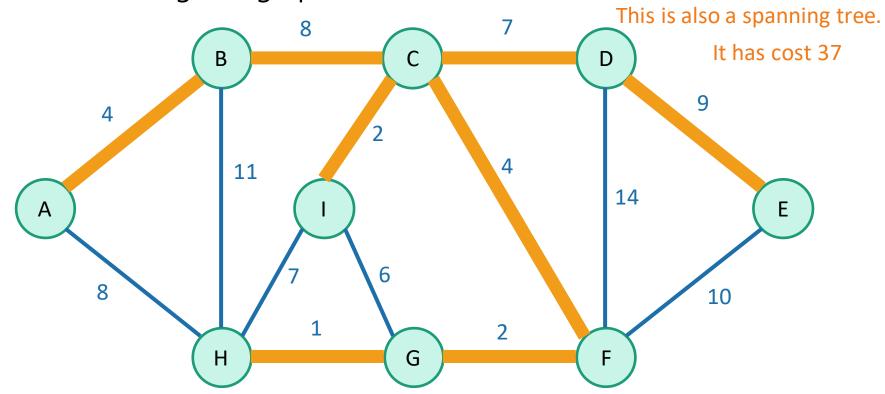


• For today we will focus on connected graphs. Say we have an undirected weighted graph



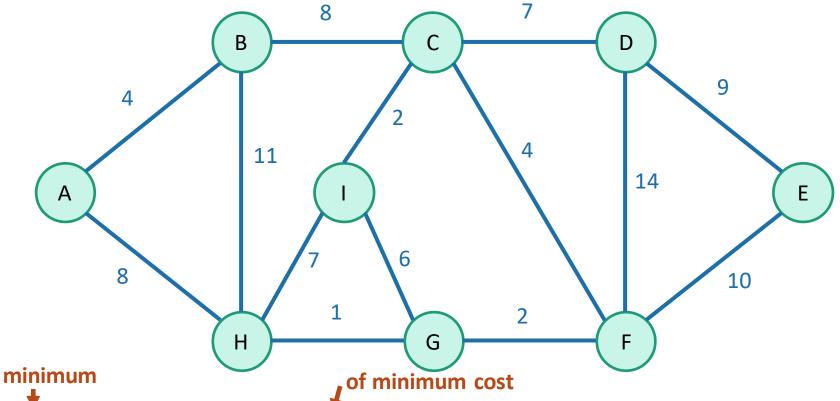


• For today we will focus on connected graphs. Say we have an undirected weighted graph





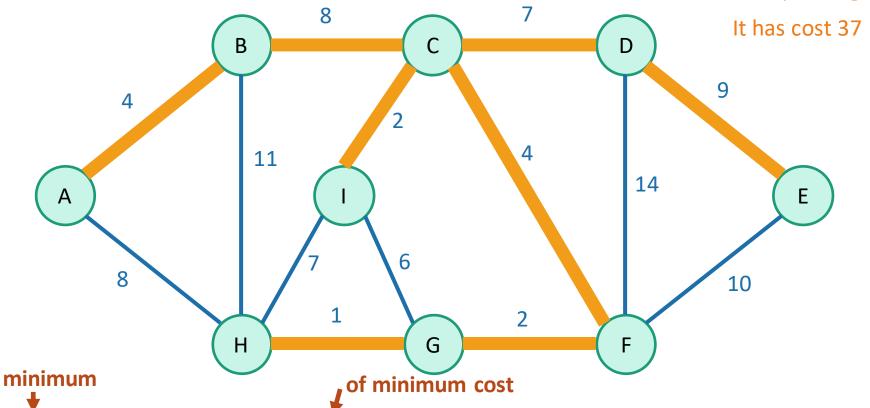
• For today we will focus on connected graphs. Say we have an undirected weighted graph





• For today we will focus on connected graphs. Say we have an undirected weighted graph

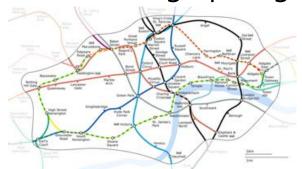
This is a minimum spanning tree

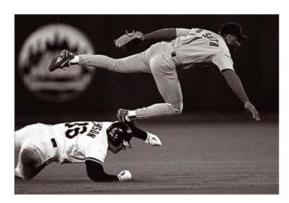




Why Minimum Spanning Trees

- Network Design
 - Connecting cities with roads/electricity/telephone/...
- Cluster analysis
 - e.g., genetic distance
- Image processing
 - e.g., image segmentation
- Useful primitive
 - for other graph algorithms



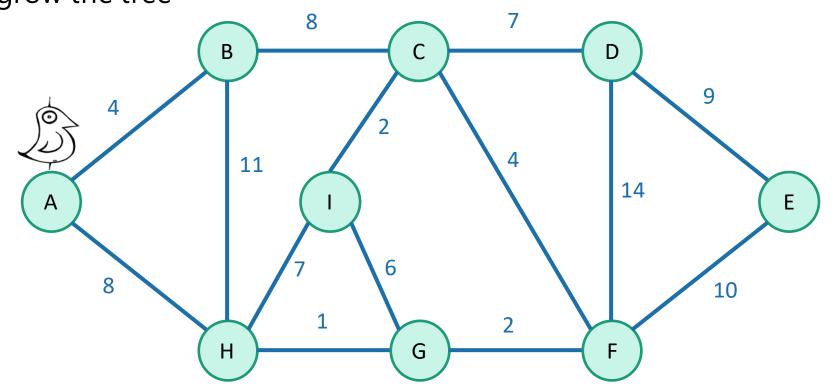




Ref: Felzenswalb et. Al., Efficient graph-based image segmentation, IJCV 2004

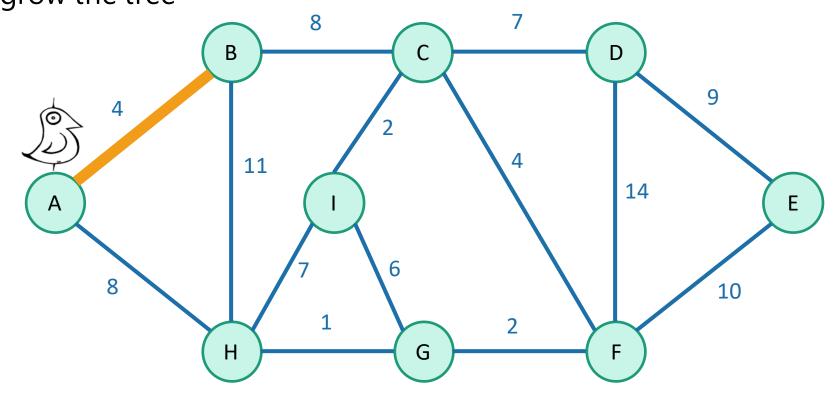


We will see two greedy algorithms





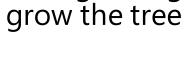
We will see two greedy algorithms

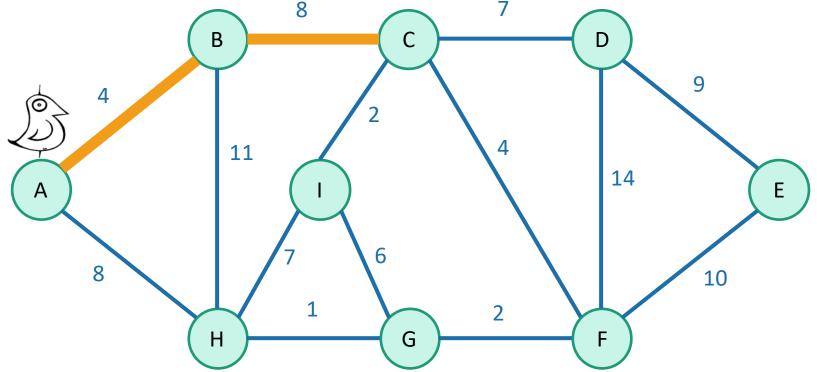




We will see two greedy algorithms

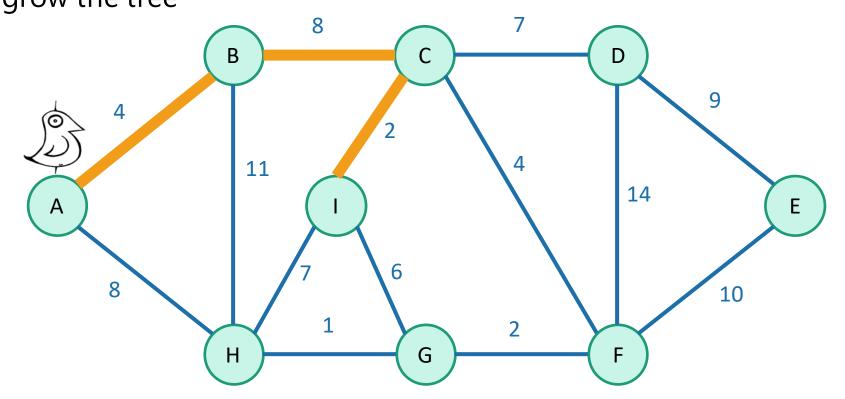
• Start growing a tree, greedily add the shortest edge we can to





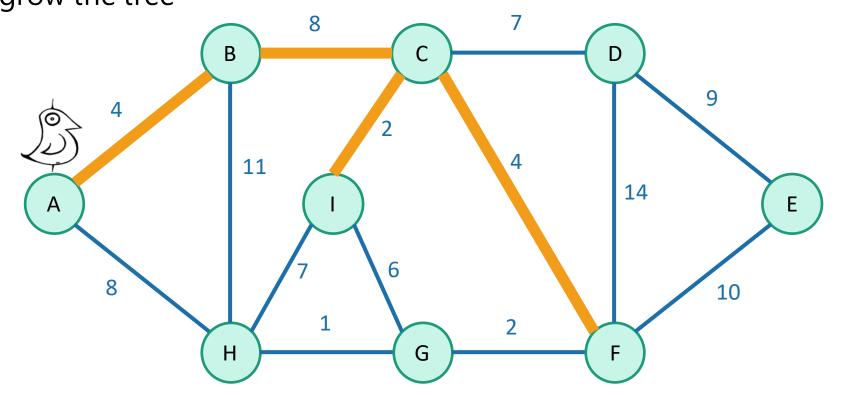


We will see two greedy algorithms



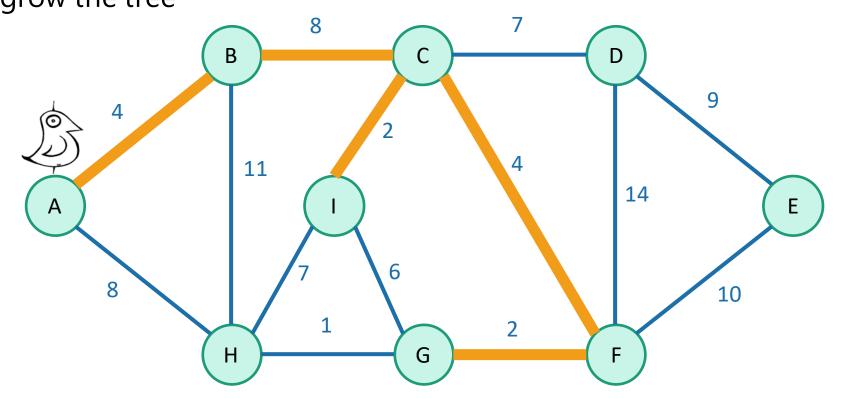


We will see two greedy algorithms



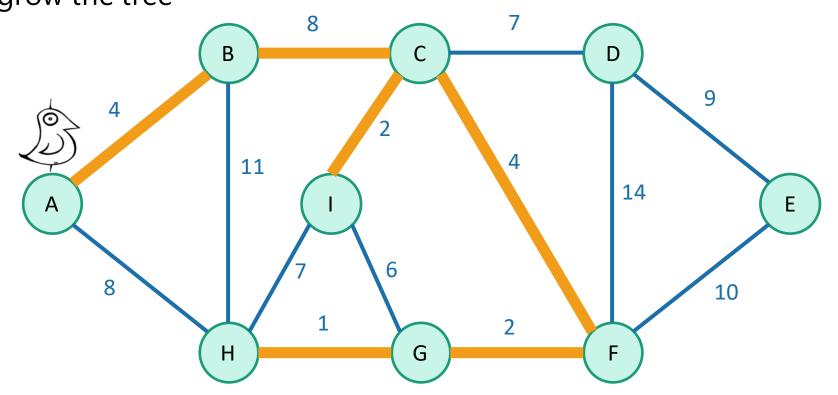


We will see two greedy algorithms



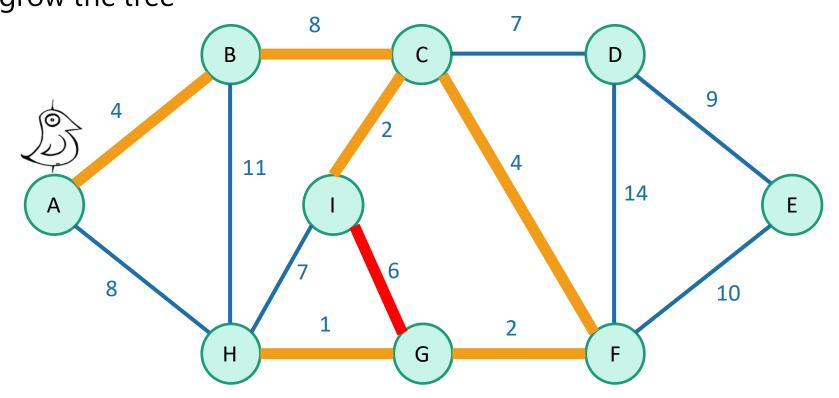


We will see two greedy algorithms



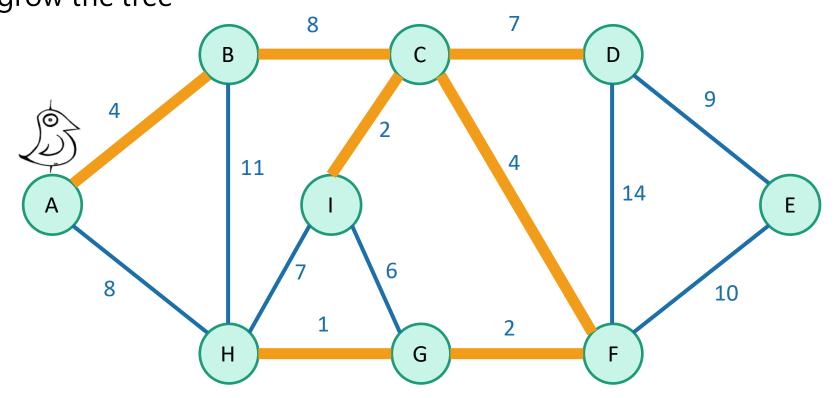


We will see two greedy algorithms



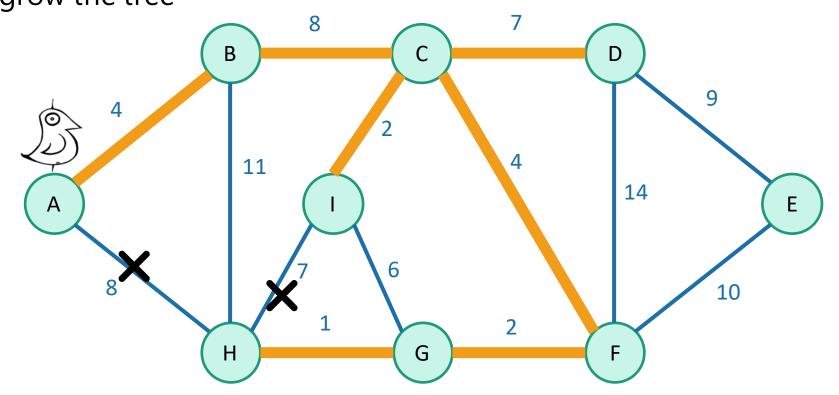


We will see two greedy algorithms



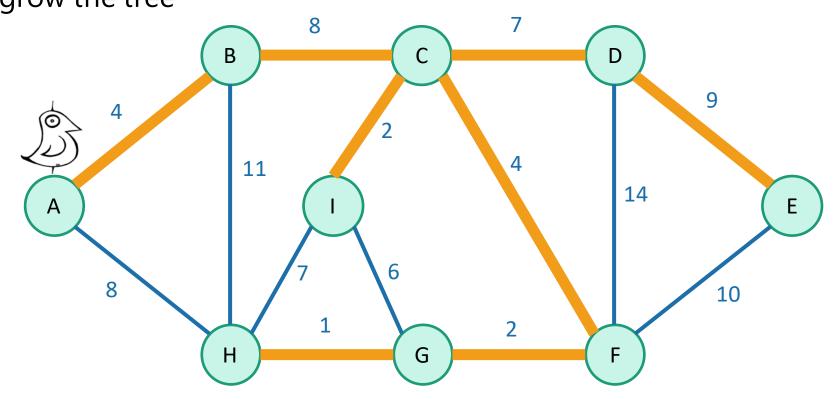


We will see two greedy algorithms

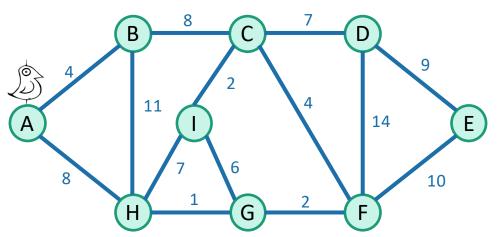




We will see two greedy algorithms

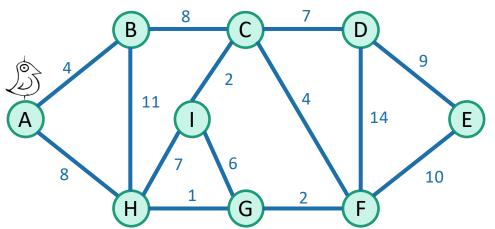






	key	π
А	0	Null
В	&	Null
С	∞	Null
D	∞	Null
E	&	Null
F	&	Null
G	8	Null
Н	8	Null
I	8	Null

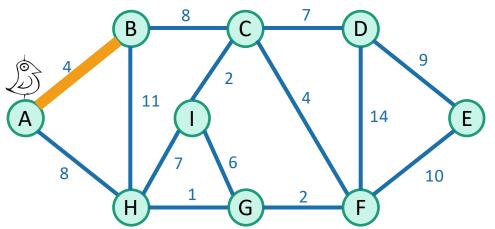




	key	π
A	0	Null
В	⇔ 4	Null A
С	&	Null
D	∞	Null
E	&	Null
F	8	Null
G	&	Null
Н	∞ 8	Null A
I	∞	Null

- Now A is out.
- Also, AB is the greedy choice. So, I shall first update the neighbors of B and I shall not consider B again
- Note that A's neighbors are already in updated state in the priority queue

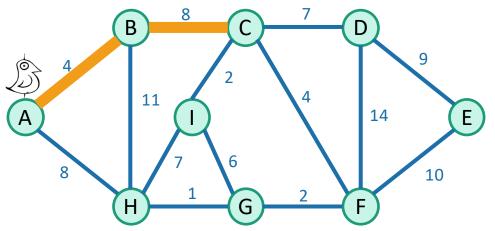




		key	π
	✓ A	0	Null
(✓ B	∞ 4	Null A
	С	∞ 8	Null B
	D	&	Null
	E	8	Null
	F	8	Null
	G	8	Null
	Н	⇔ 8 11	Null A B
	I	∞	Null

- Now A is out.
- Also, AB is the greedy choice. So, I shall first update the neighbors of B and I shall not consider B again
- Note that A's neighbors are already in updated state in the priority queue

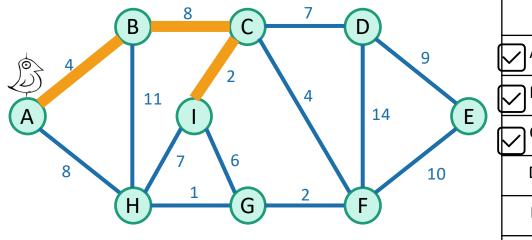




	<u> </u>	
	key	π
Α	0	Null
\searrow B	∞ 4	Null A
√) c	∞ 8	Null B
D	∞ 7	Null C
E	∞	Null
F	∞ 4	Null C
G	∞	Null
Н	∞ 8	Null A
I	∞ 2	Null C

- Now B is out
- Also, BC is the greedy choice. So, I shall first update the neighbors of C and I shall not consider C again





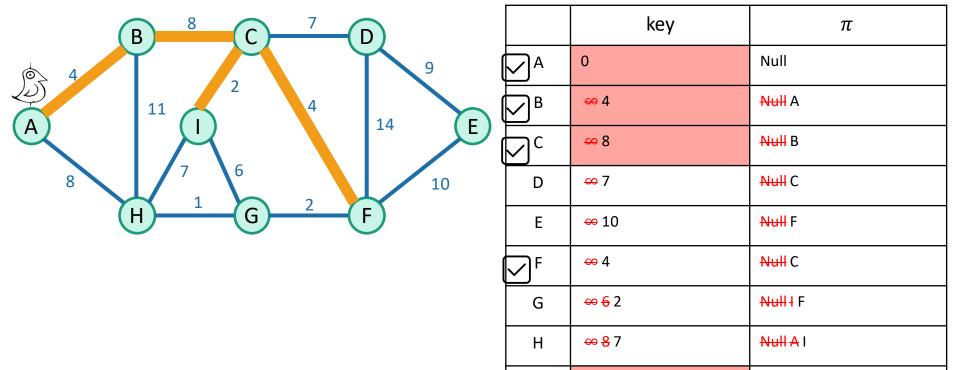
	key	π
✓ A	0	Null
\searrow B	∞ 4	Null A
√) c	∞ 8	Null B
D	∞ 7	Null C
E	8	Null
F	⇔ 4	Null C
G	⇔ 6	Null I
Н	∞ 8 7	Null A I
\ _	⇔ 2	Null C

- Now C is out
- Also, CI is the greedy choice. So, I shall first update the neighbors of I and I shall not consider I again

∞ 2



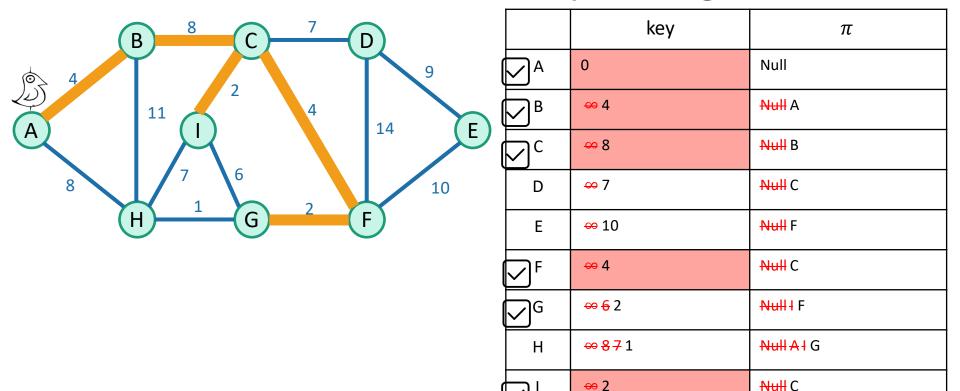
How to find Minimum Spanning Trees



- Now *I* is out
- Also, CF is the greedy choice. So, I shall first update the neighbors of F and I shall not consider F again

Null C



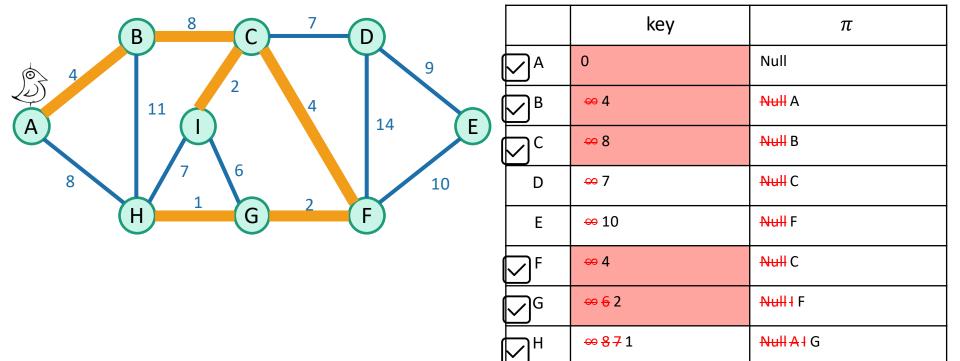


- Now *F* is out.
- Also, FG is the greedy choice. So, I shall first update the neighbors of G and I shall not consider G again

∞ 2



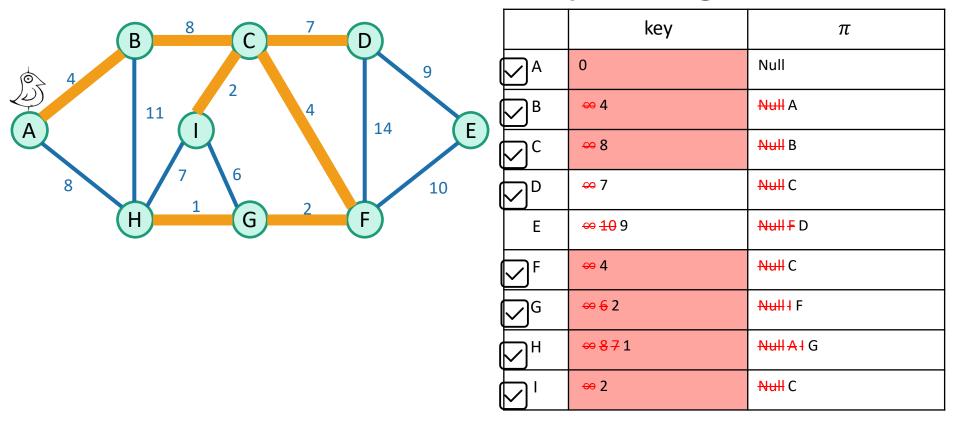
How to find Minimum Spanning Trees



- Now G is out
- Also, GH is the greedy choice. So, I shall first update the neighbors of H and I shall not consider H again
- In fact, all neighbors are out in this case This also means a cycle would come. So we don't do anything
- Same scenario with next greedy choices, GI, HI

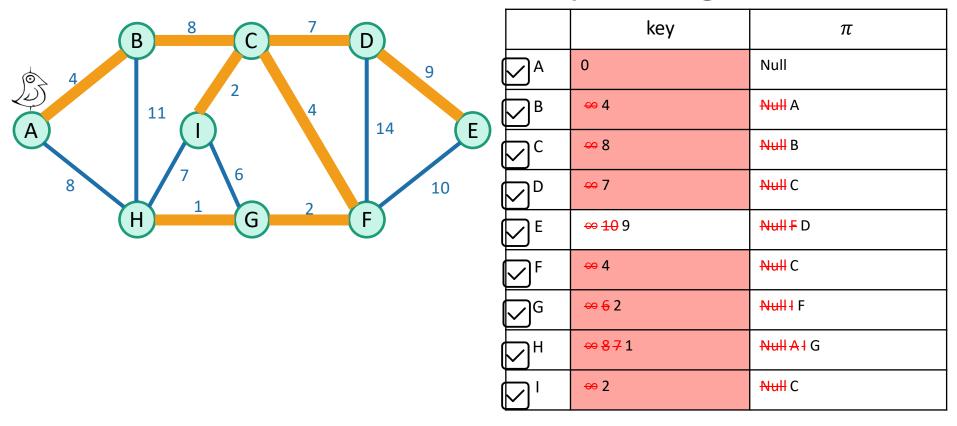
Null C





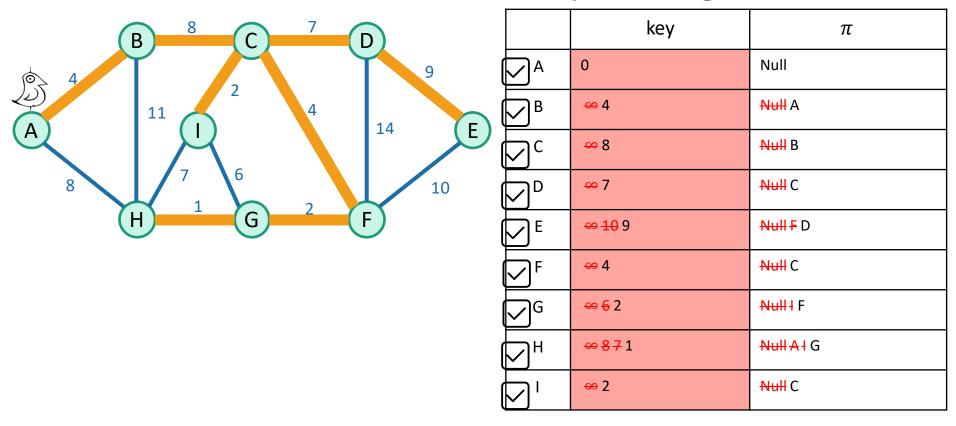
• Our next greedy choice is CD. So, I shall first update the neighbors of D and I shall not consider D again





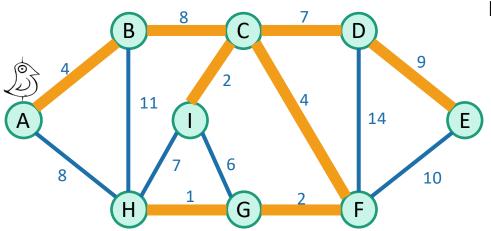
- Our next greedy choice is DE. However, E's neighbors are already updated
- Note choosing DE is not completing any cycle, but exploring its neighbors can
- Now the priority queue is empty, so we stop





- Our next greedy choice is DE. However, E's neighbors are already updated
- Note choosing DE is not completing any cycle, but exploring its neighbors can
- Now the priority queue is empty, so we stop



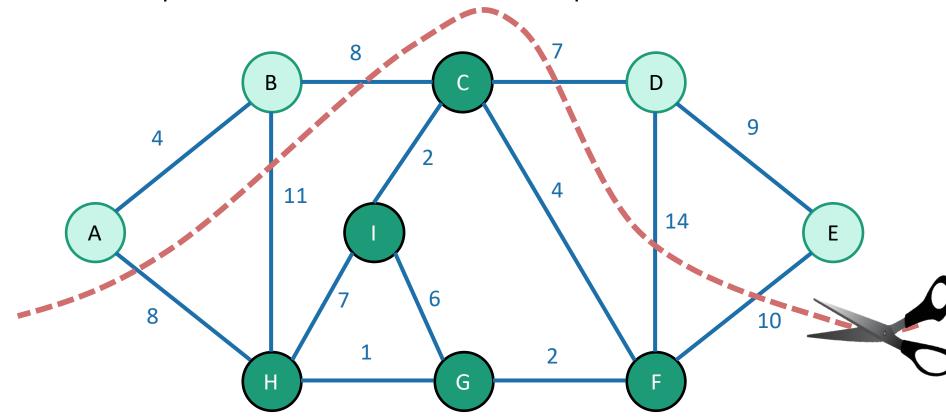


```
Prim(G)
select a source s
for each vertex u \in G. V
u. key = \infty, u.\pi = Null
s. key = 0
// Initialize a data structure for the vertices Q = \phi // Priority queue
for each vertex u \in G. V
Q. Insert(u)
while Q \neq \phi
u = Q. getMin()
for each neighbor v \in G. Adj[u]
if v \in QAND w(u,v) < v. key
v. key = w(u,v)
v. \pi = u
```



Brief Aside

• A cut is a partition of the vertices into two parts

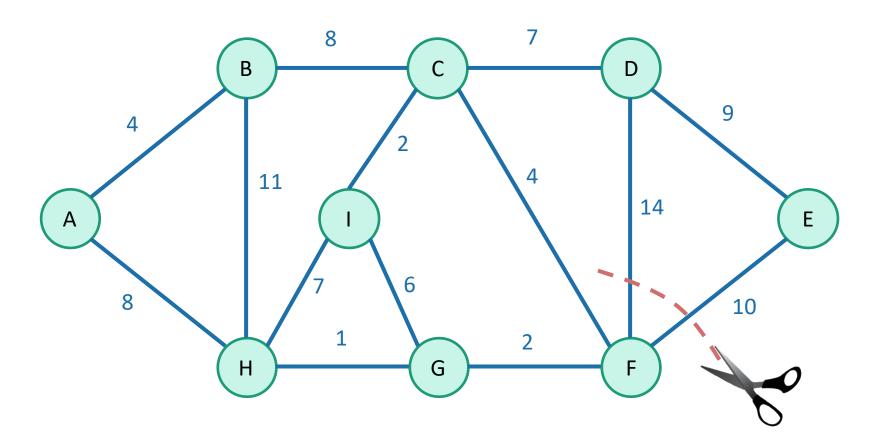


This is the cut "{A,B,D,E} and {C,I,H,G,F}"



Cuts in Graphs

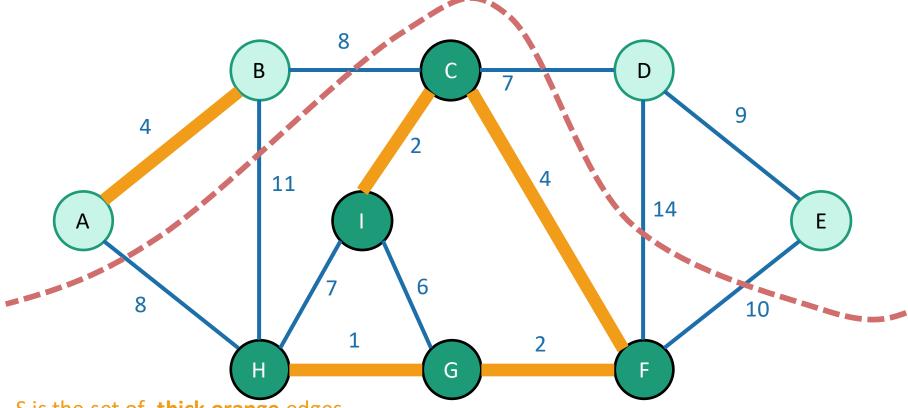
• This is **not** a cut. Cuts are partitions of vertices





Let S be a set of edges in G

- We say a cut **respects** S if no edges in S cross the cut
- An edge crossing a cut is called **light** if it has the smallest weight of any edge crossing the cut



S is the set of **thick orange** edges

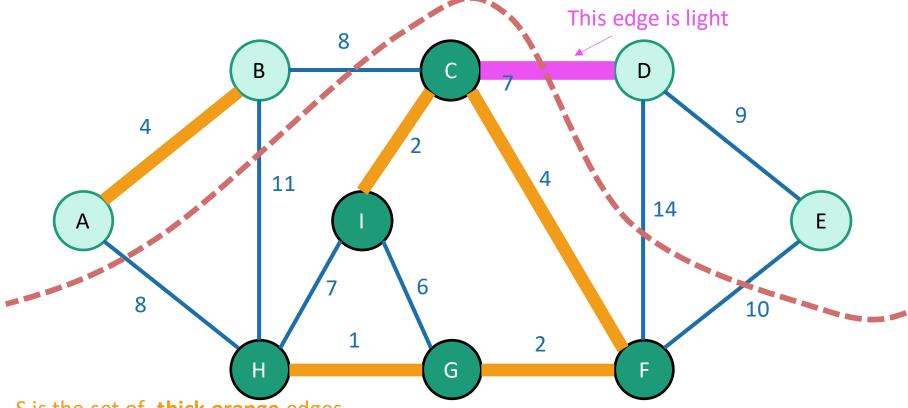
Source: Stanford, CS 161 course, Winter 2022 CS21003/CS21203 / Algorithms - I | Graphs

Nov 02, 03, 04, 2022



Let S be a set of edges in G

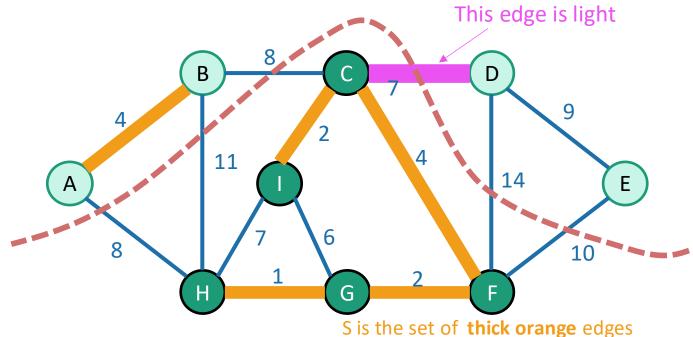
- We say a cut **respects** S if no edges in S cross the cut
- An edge crossing a cut is called **light** if it has the smallest weight of any edge crossing the cut





Lemma

- Let S be a set of edges, and consider a cut that respects S
- Suppose there is an MST containing S
- Let {u,v} be a light edge
- Then there is an MST containing S ∪ {{u,v}}

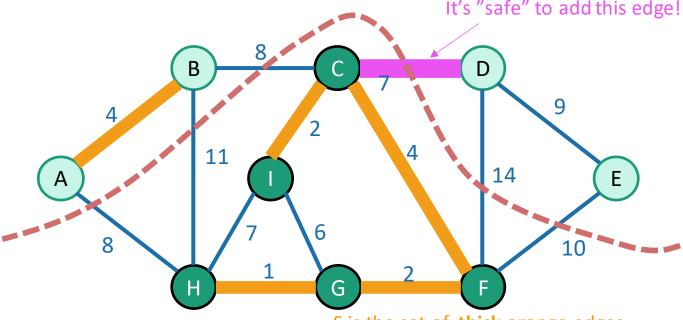




Lemma

- Let S be a set of edges, and consider a cut that respects S
- Suppose there is an MST containing S
- Let {u,v} be a light edge
- Then there is an MST containing S ∪ {{u,v}}

If we haven't ruled out the possibility of success so far, then adding a light edge still won't rule it out.

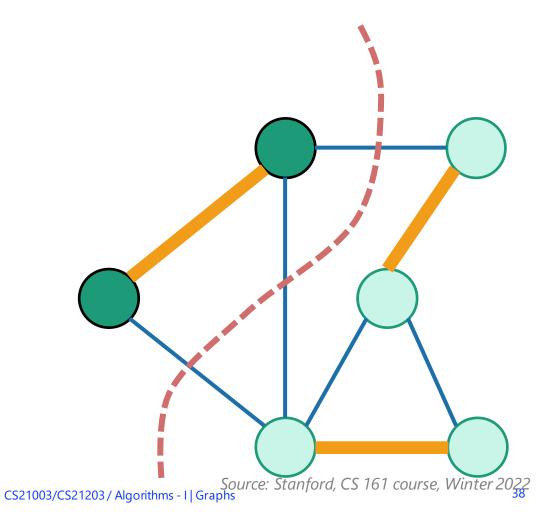


S is the set of **thick orange** edges

Source: Stanford, CS 161 course, Winter 2022 CS21003/CS21203 / Algorithms - I | Graphs



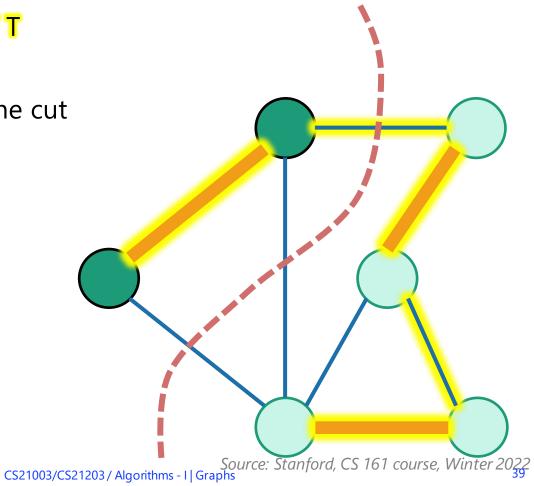
- Assume that we have:
 - a cut that respects S





- Assume that we have:
 - a cut that respects S
 - S is part of some MST T
- Say that {u,v} is light

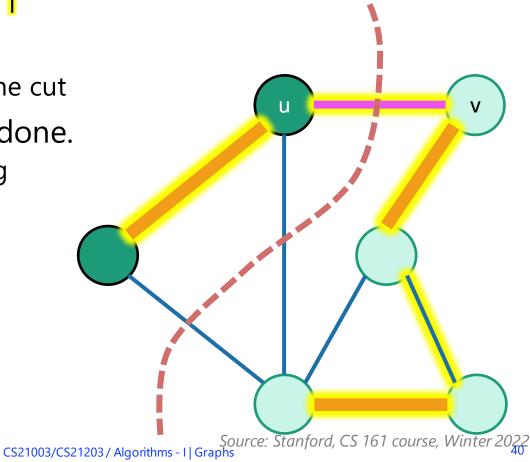
lowest cost crossing the cut



Nov 02, 03, 04, 2022



- Assume that we have:
 - a cut that respects S
 - S is part of some MST T
- Say that {u,v} is light
 - lowest cost crossing the cut
- If {u,v} is in T, we are done.
 - T is an MST containing both {u,v} and S.





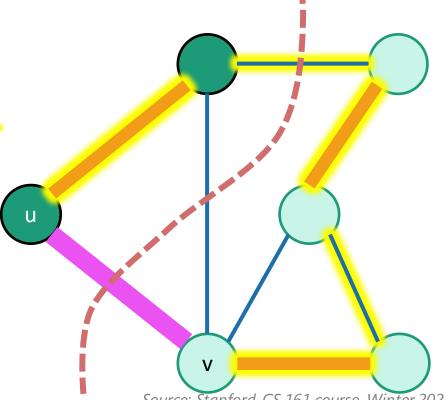
- Assume that we have:
 - a cut that respects S
 - S is part of some MST T
- Say that {u,v} is light.
 - lowest cost crossing the cut
- Say {u,v} is not in T

Note that adding {u,v} to T

will make a cycle

Claim: Adding any additional edge to a spanning tree will create a cycle

Proof: Both endpoints are already in the tree and connected to each other.

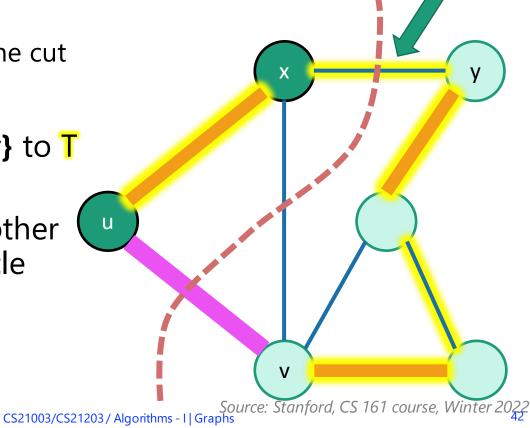




- Assume that we have:
 - a cut that respects S
 - S is part of some MST T
- Say that {u,v} is light.
 - lowest cost crossing the cut
- Say {u,v} is not in T
- Note that adding {u,v} to T will make a cycle
- There is at least one other edge, {x,y}, in this cycle crossing the cut

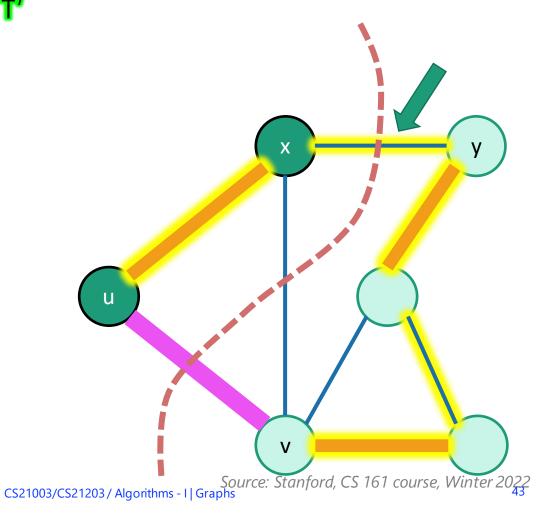
Claim: Adding any additional edge to a spanning tree will create a cycle

Proof: Both endpoints are already in the tree and connected to each other.



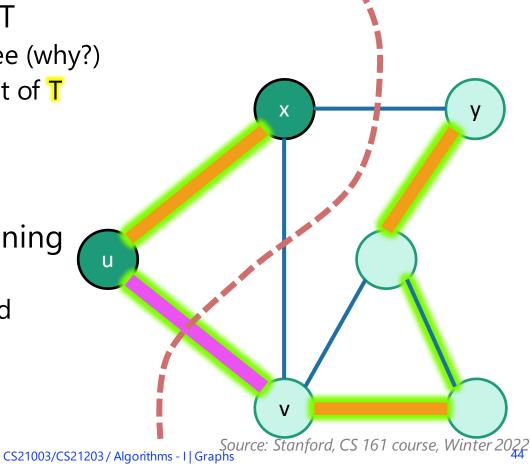


- Consider swapping {u,v} for {x,y} in T
 - Call the resulting tree T'





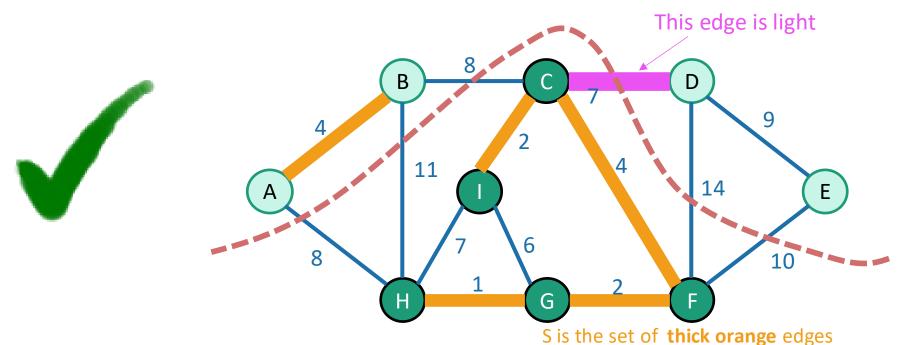
- Consider swapping {u,v} for {x,y} in T
 - Call the resulting tree T'
- Claim: T' is still an MST
 - It is still a spanning tree (why?)
 - It has cost at most that of T
 - Because {u,v} was light
 - T had minimal cost
 - So T' does too
- So T' is an MST containing S and {u,v}
 - This is what we wanted





Lemma

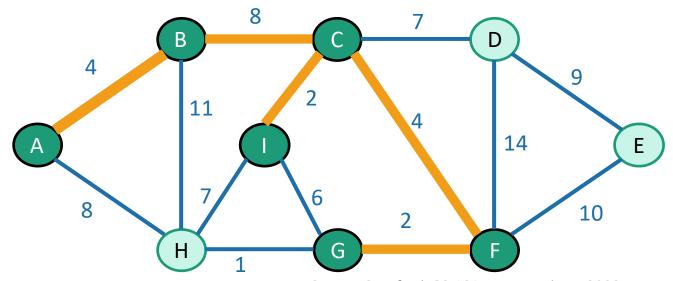
- Let S be a set of edges, and consider a cut that respects S
- Suppose there is an MST containing S
- Let {u,v} be a light edge
- Then there is an MST containing S ∪ {{u,v}}





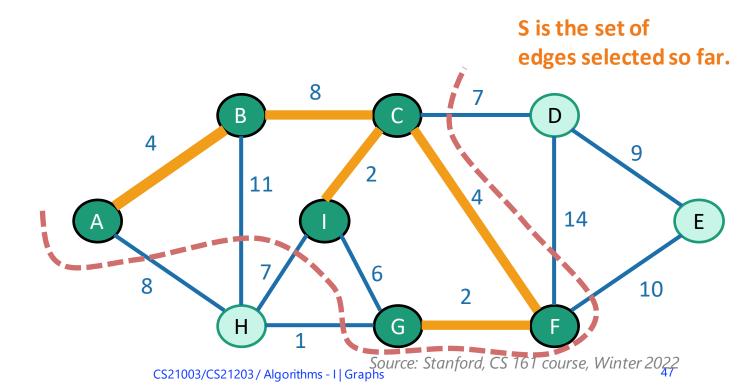
- Assume that our choices S so far don't rule out success
 - There is an MST consistent with those choices
- How can we use our lemma to show that our next choice also does not rule out success?

S is the set of edges selected so far.



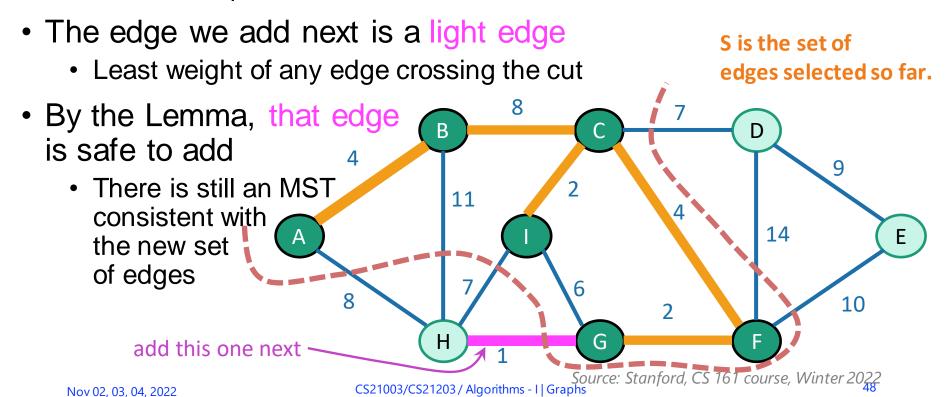


- Assume that our choices S so far don't rule out success
 - There is an MST consistent with those choices
- Consider the cut {visited, unvisited}
 - This cut respects S





- Assume that our choices S so far don't rule out success
 - There is an MST consistent with those choices
- Consider the cut {visited, unvisited}
 - This cut respects S



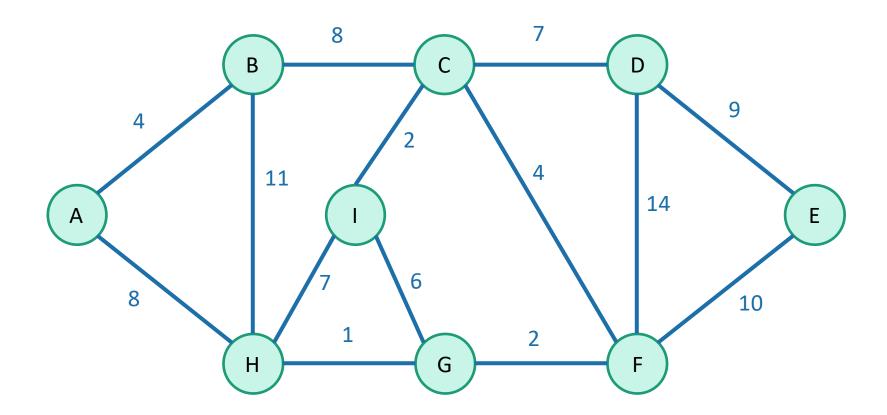


• Our greedy choices don't rule out success.

• This is enough (along with an argument by induction) to guarantee correctness of Prim's algorithm.

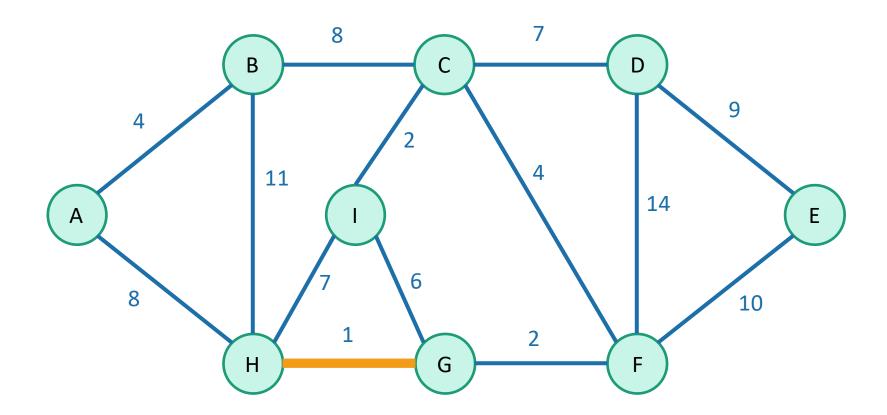


- what if we just always take the cheapest edge?whether or not it's connected to what we have so far?



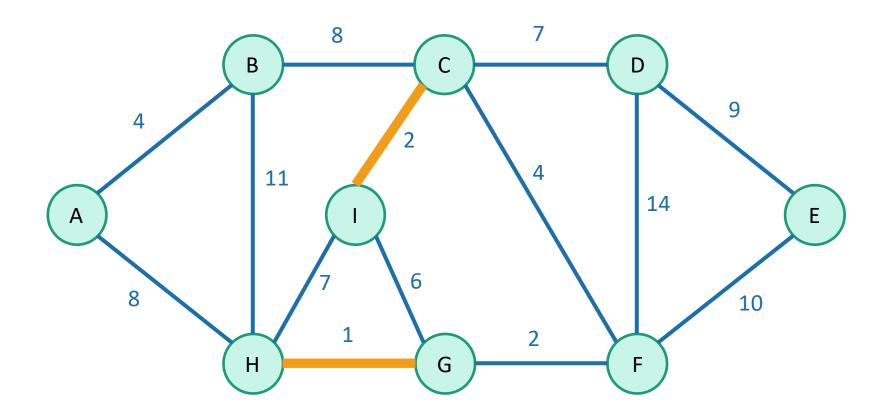


- what if we just always take the cheapest edge?whether or not it's connected to what we have so far?



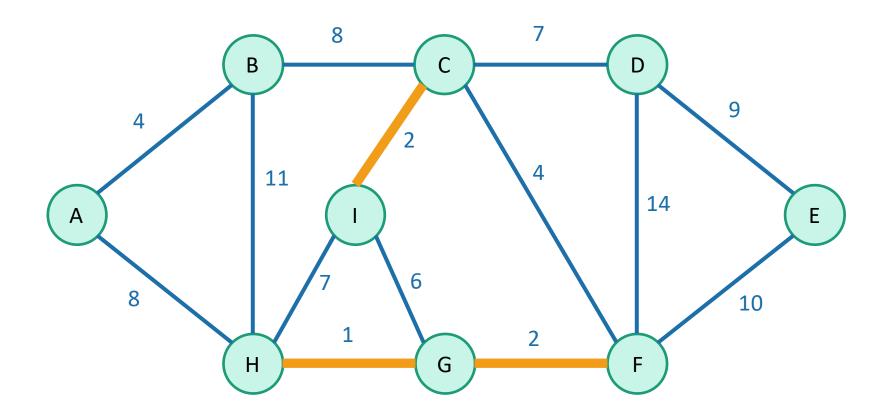


- what if we just always take the cheapest edge?whether or not it's connected to what we have so far?



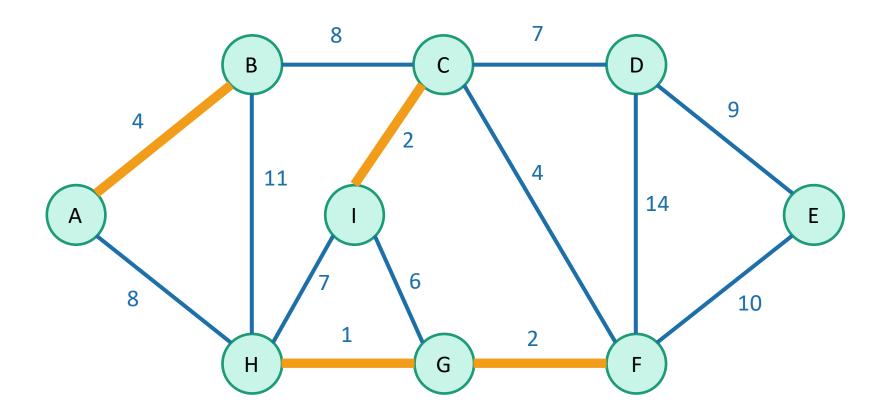


- what if we just always take the cheapest edge?whether or not it's connected to what we have so far?



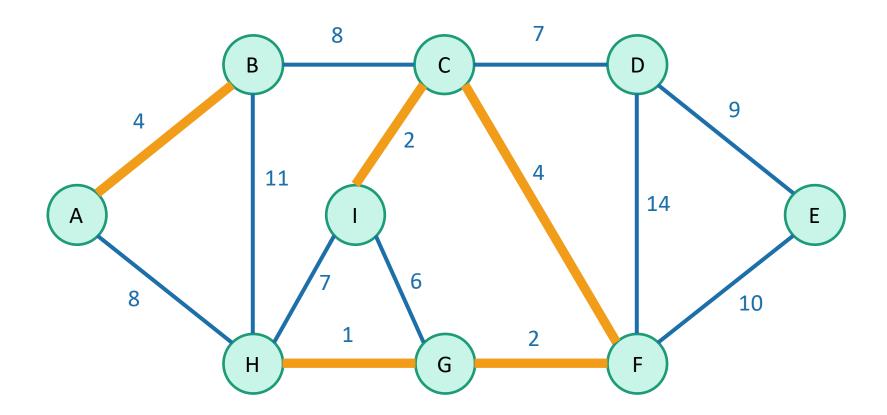


- what if we just always take the cheapest edge?whether or not it's connected to what we have so far?



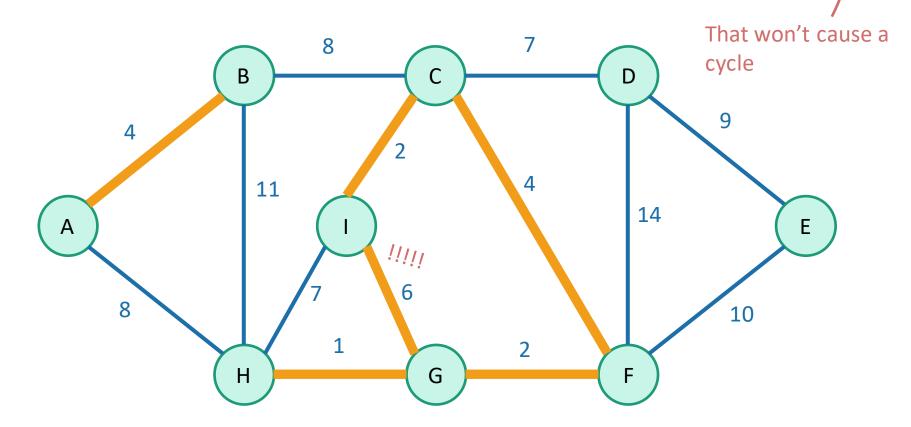


- what if we just always take the cheapest edge?whether or not it's connected to what we have so far?



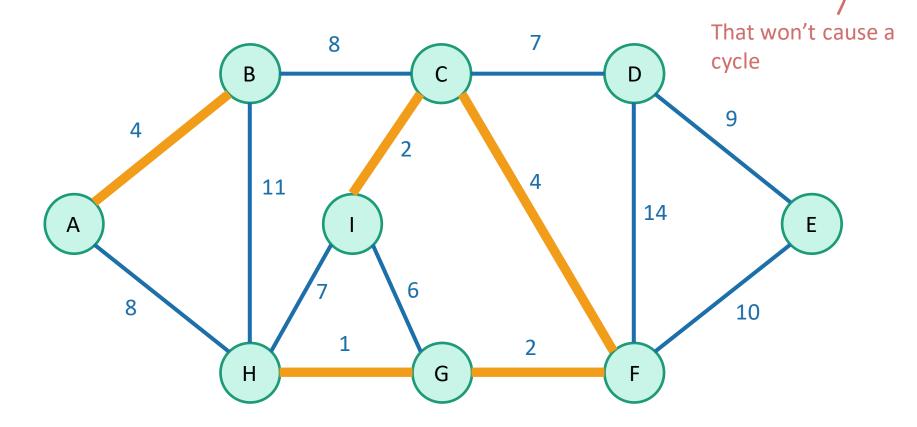


- what if we just always take the cheapest edge?
 whether or not it's connected to what we have so far?



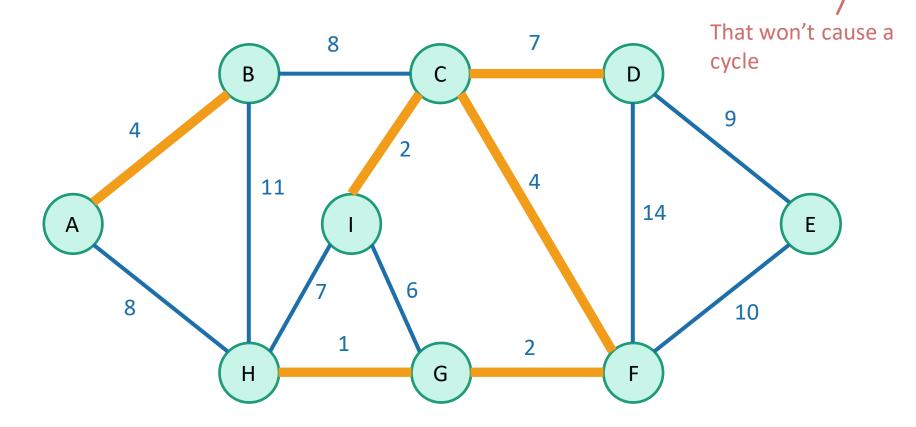


- what if we just always take the cheapest edge?
 whether or not it's connected to what we have so far?



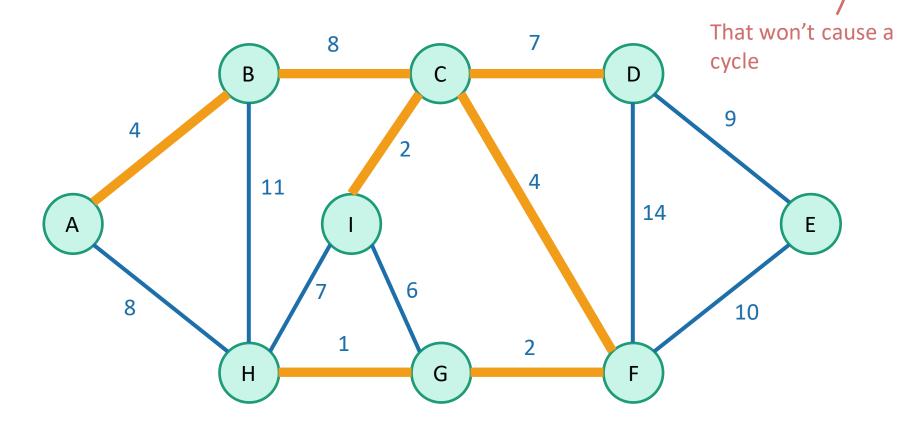


- what if we just always take the cheapest edge?
 whether or not it's connected to what we have so far?



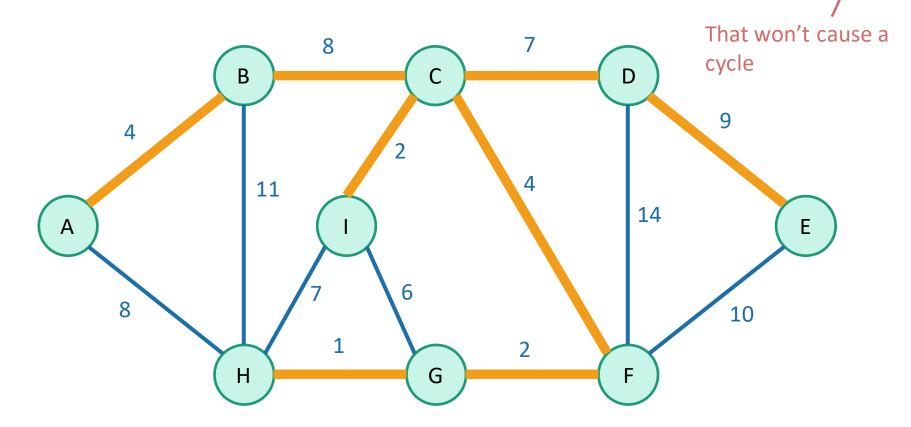


- what if we just always take the cheapest edge?
 whether or not it's connected to what we have so far?





- what if we just always take the cheapest edge?
 whether or not it's connected to what we have so far?



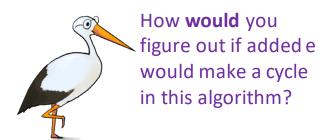


We've Reached Kruskal's Algorithm

- slowKruskal(G = (V,E)):
 - Sort the edges in E by non-decreasing weight.
 - MST = {}
 - for e in E (in sorted order):
 - if adding e to MST won't cause a cycle:
 - add e to MST.
 - return MST

|E| iterations through this loop

How do we check this?



Naively, the running time is ???:

- For each of |E| iterations of the for loop:
 - Check if adding e would cause a cycle...



Two questions

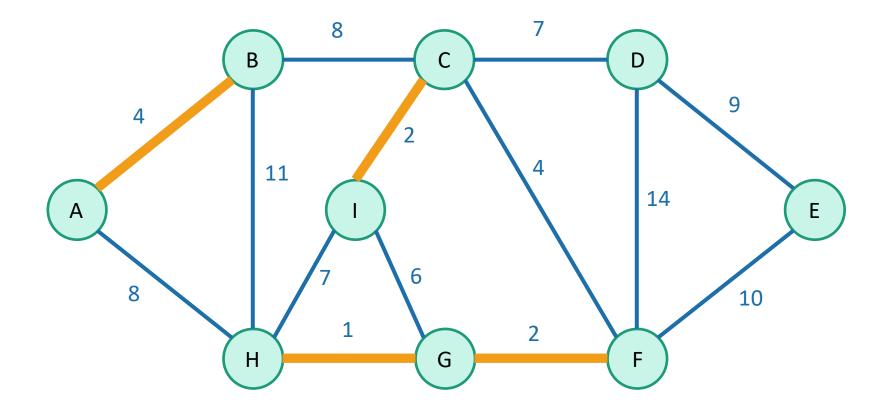
- Does it work?
 - That is, does it actually return a MST?
- How do we actually implement this?
 - The pseudocode above says "slowKruskal" ...





• We are maintaining a forest

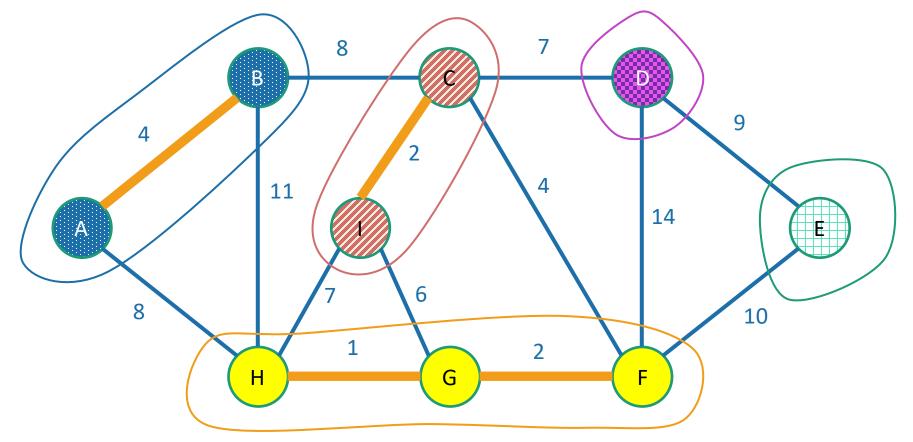






- We are maintaining a forest
 When we add an edge, we merge two trees

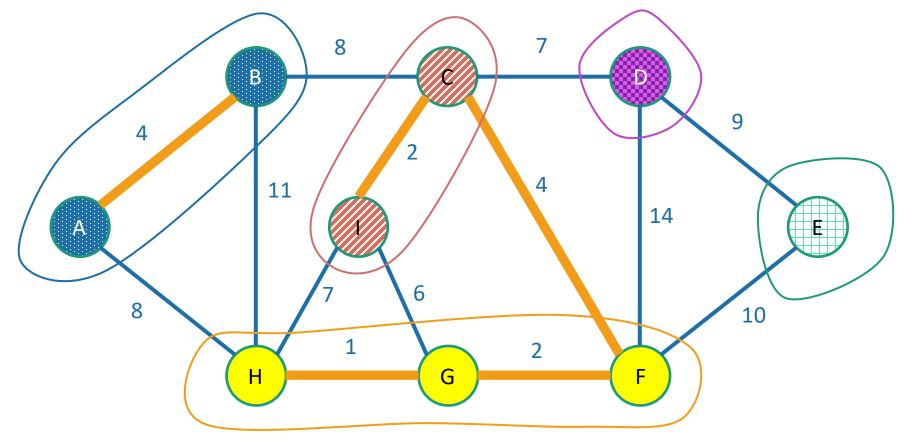






- We are maintaining a forest
 When we add an edge, we merge two trees



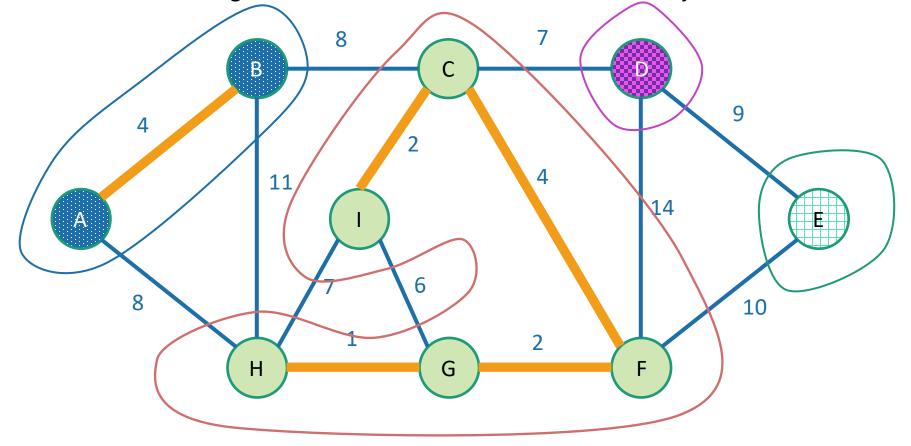




- We are maintaining a forest
 When we add an edge, we merge two trees
 We never add an edge within a tree since that would create a cycle









Keep the Trees in a Special Data Structure

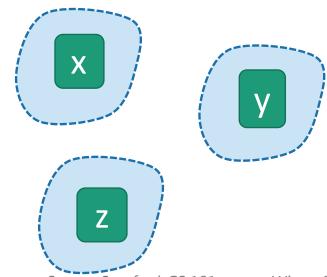




Union-find Data Structure

- Also called disjoint-set data structure
- Used for storing collections of sets
- Supports
 - makeSet(u): create a set {u}
 - find(u): return the set that u is in
 - union(u,v): merge the set that u is in with the set that v is in

makeSet(x)
makeSet(y)
makeSet(z)
union(x,y)

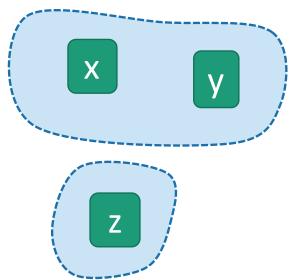




Union-find Data Structure

- Also called disjoint-set data structure
- Used for storing collections of sets
- Supports
 - makeSet(u): create a set {u}
 - find(u): return the set that u is in
 - union(u,v): merge the set that u is in with the set that v is in

```
makeSet(x)
makeSet(y)
makeSet(z)
union(x,y)
```





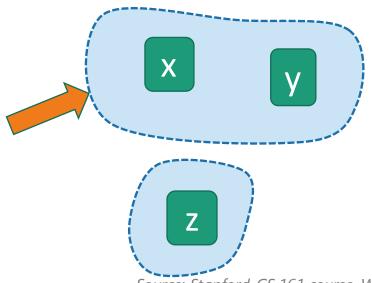
Union-find Data Structure

- Also called disjoint-set data structure
- Used for storing collections of sets
- Supports
 - makeSet(u): create a set {u}
 - find(u): return the set that u is in
 - union(u,v): merge the set that u is in with the set that v is in

```
makeSet(x)
makeSet(y)
makeSet(z)

union(x,y)

find(x)
```





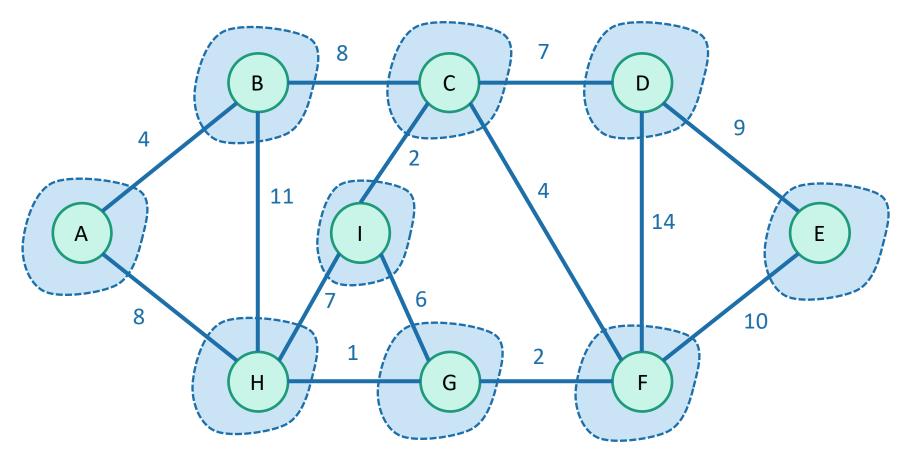
Kruskal Pseudocode

- **Kruskal**(G = (V,E)):
 - Sort the edges in E by non-decreasing weight.

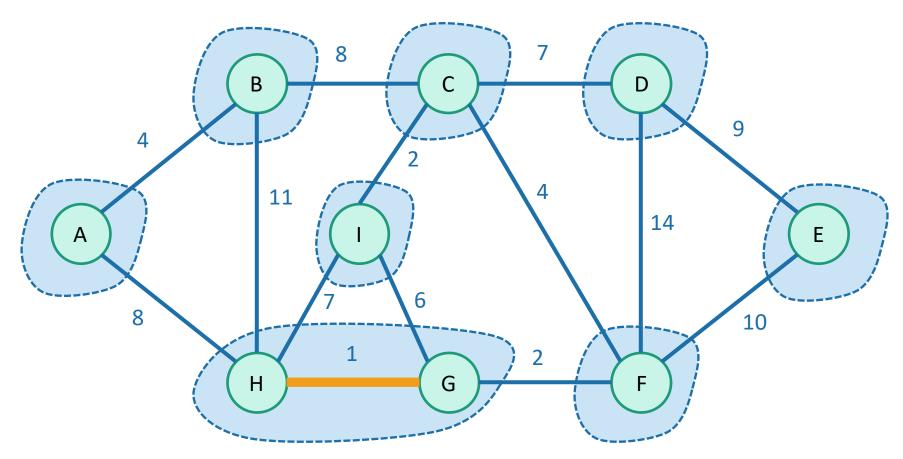


Once More ...

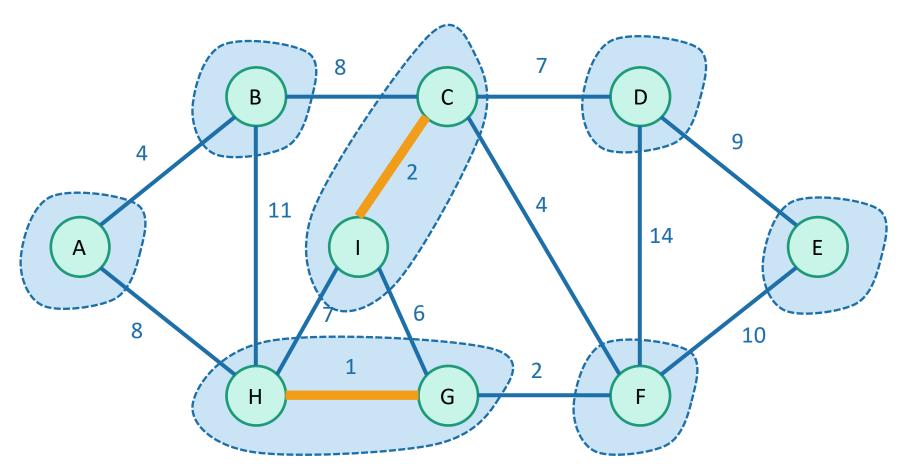
• To start, every vertex is in its own tree



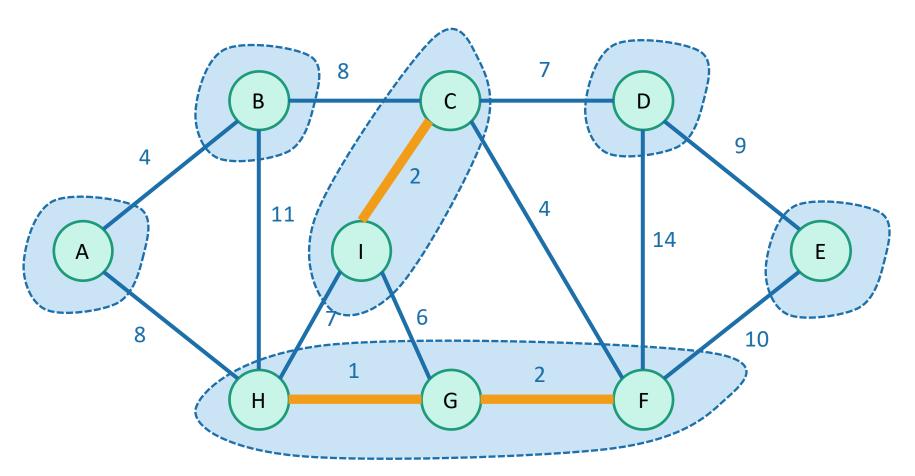




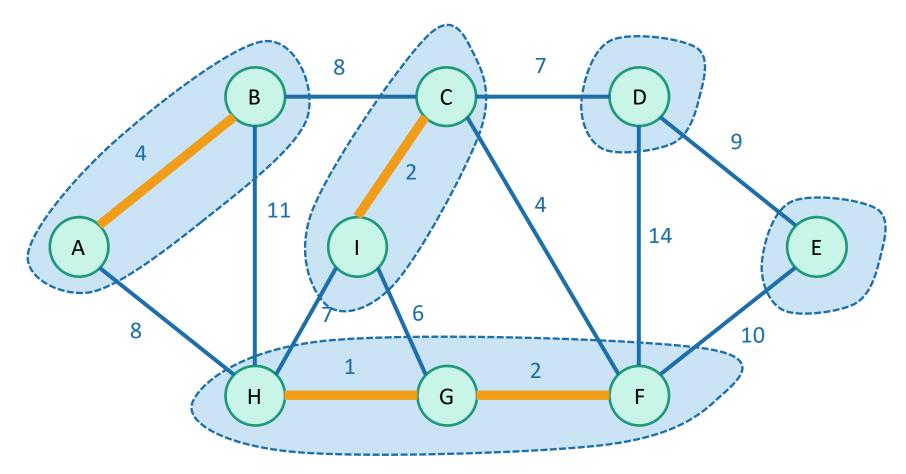




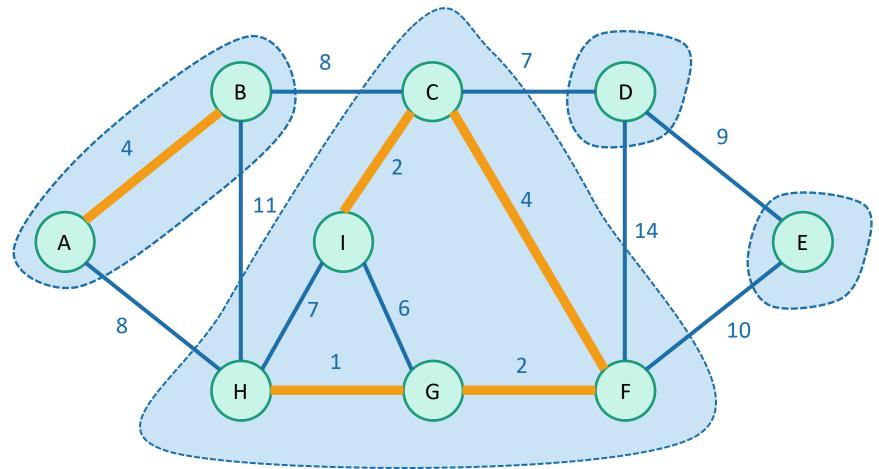




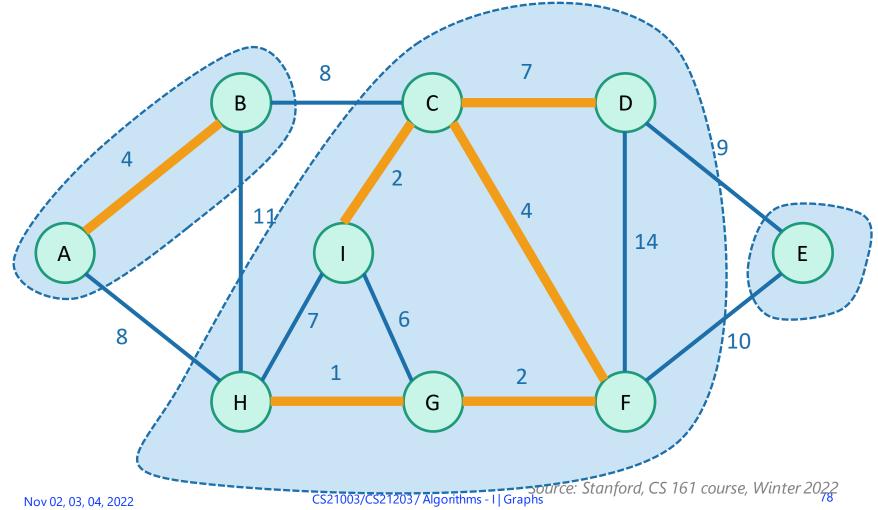




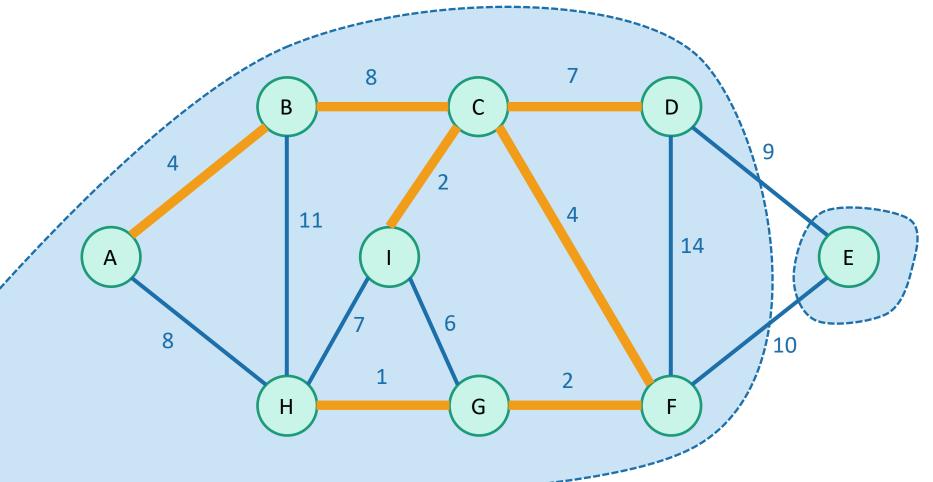




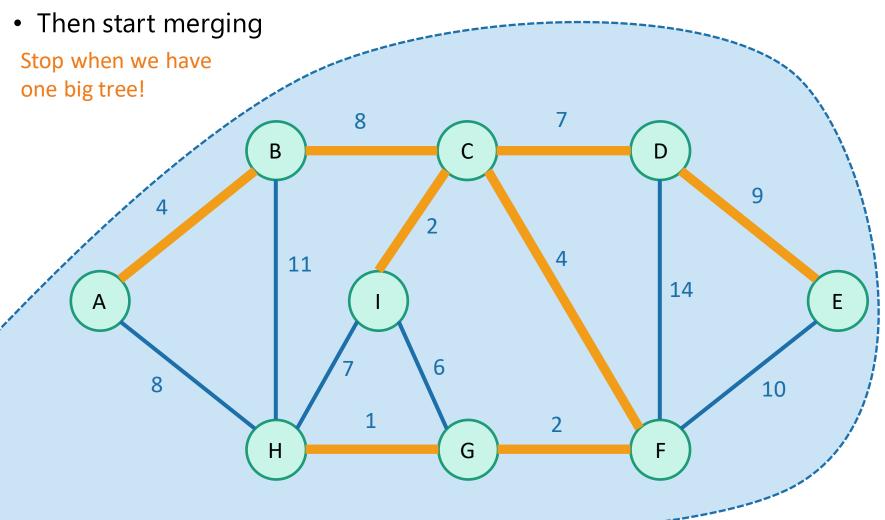














Running Time

- Sorting the edges takes $O(|E| \log |V|)$
- For the rest
 - |V| calls to makeSet
 - Put each vertex in its own set
 - |2*E*| calls to **find**
 - For each edge, find its end points
 - |V-1| calls to union
 - We will never add more than |V-1| edges to the tree
 - So, we will never call **union** more than |V-1| times
- Total running time:
 - Worst-case $O(|E|\log|V|)$

In practice, each of makeSet, find, and union run in constant time*



Two questions

- Does it work?
 - That is, does it actually return a MST?

Now that we understand this "tree-merging" view, let's do this one

- How do we actually implement this?
 - The pseudocode above says "slowKruskal" ...
 - Worst-case running time $O(|E| \log |V|)$ using a union-find data structure



Does it Work?

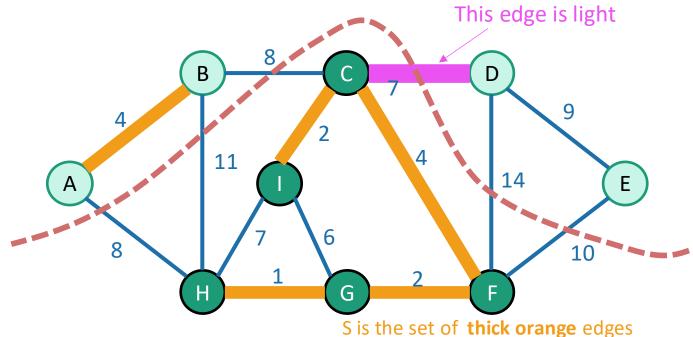
- We need to show that our greedy choices don't rule out success
- That is, at every step:
 - There exists an MST that contains all of the edges we have added so far
- Now it is time to use our lemma!

again!



Lemma

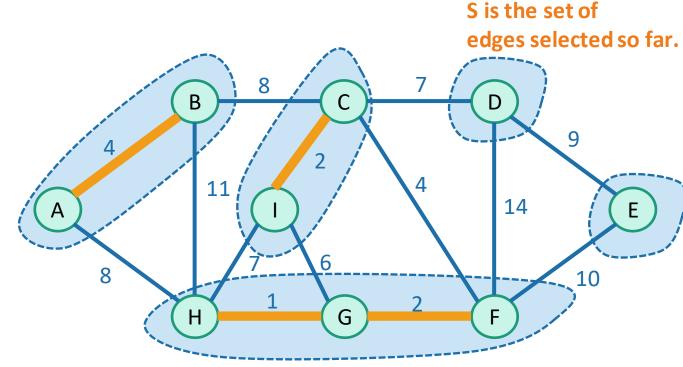
- Let S be a set of edges, and consider a cut that respects S
- Suppose there is an MST containing S
- Let {u,v} be a light edge
- Then there is an MST containing S ∪ {{u,v}}





Partway through Kruskal

- Assume that our choices S so far don't rule out success
 - There is an MST extending them

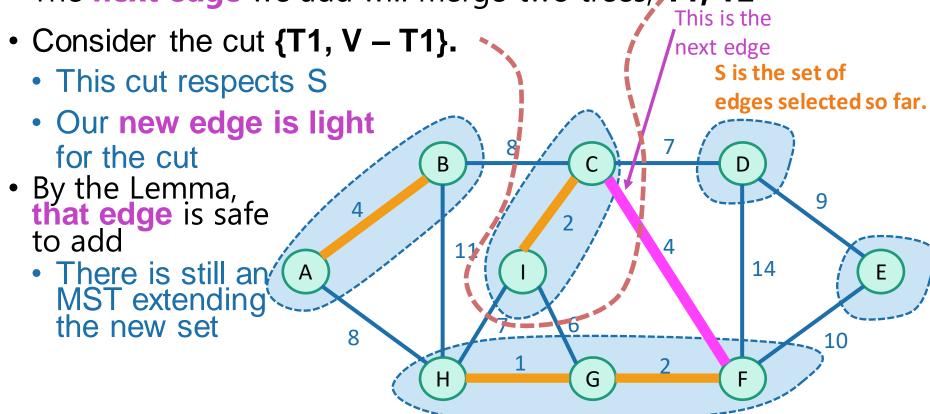




Partway through Kruskal

- Assume that our choices S so far don't rule out success
 - There is an MST extending them

• The next edge we add will merge two trees, T1, T2





Partway through Kruskal

• Our greedy choices don't rule out success.

• This is enough (along with an argument by induction) to guarantee correctness of Kruskal's algorithm.



Two questions

- Does it work?
 - That is, does it actually return a MST?
 - Yes
- How do we actually implement this?
 - The pseudocode above says "slowKruskal" ...
 - Using a union-find data structure!



Recap

- Two algorithms for Minimum Spanning Tree
 - Prim's algorithm
 - Kruskal's algorithm
- Both are greedy algorithms
 - Make a series of choices
 - Show that at each step, your choice does not rule out success
 - At the end of the day, you haven't ruled out success, so you must be successful



SSSP Again

- We have seen Dijkstra's method
 - One drawback is that it needs non-negative edge weights
- Bellman-Ford algorithm
 - It is a dynamic programming algorithm
 - It has a higher cost than Dijkstra, but can handle graphs with negative edge weights

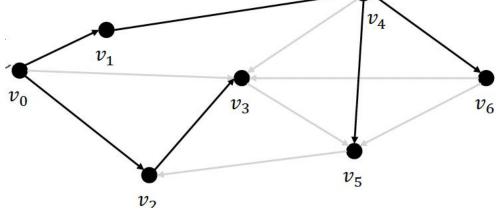


Bellman-Ford as DP

- Let $D_{i,k}$ indicate the shortest distance from source s to vertex i using no more than k hops (number of edges)
- Consider the last edge:

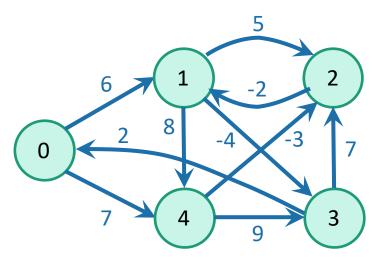
•
$$D_{i,k} = \min \begin{cases} D_{i,k-1} \\ \min_{(j,i) \in E} \{D_{j,k-1} + w(j,i)\} \end{cases}$$

- Boundaries: $D_{s,0} = 0$, $D_{i,0} = \infty$ $(i \neq s)$
- Final answer to vertex i is $D_{i,n-1}$





SSSP Again





Thank You