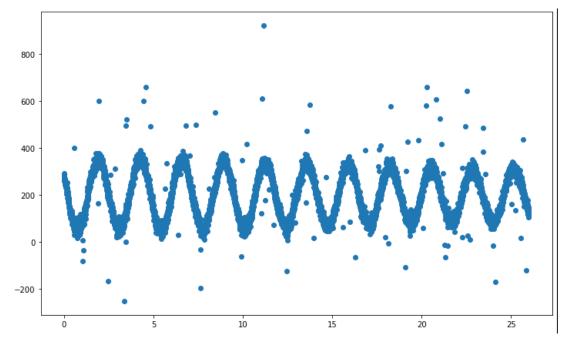
prepared by Danila Danko

Please, refer to Project setup to run the code.

**Task 1**In Task 1, I took the dataset for my case (case 1) and visualized it.



I noticed that the points resemble a sin wave. That's why, I decided not to use Linear Regression.

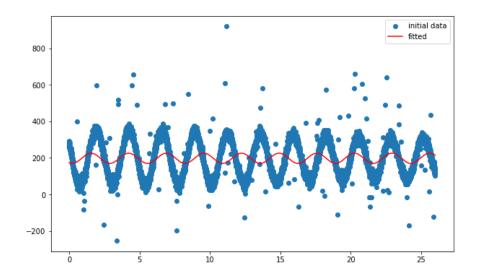
Instead, I learned about Gauss-Newton's method here (<u>link</u>) and implemented it for my problem.

I switched to the following formulation of my problem:

Gauss-Newton algorithm directly deals with this type of problems. Given m data points  $(x_i, y_i)$  for regression with a function of n parameters  $\vec{\beta} = (\beta_1, \dots, \beta_n)$ 

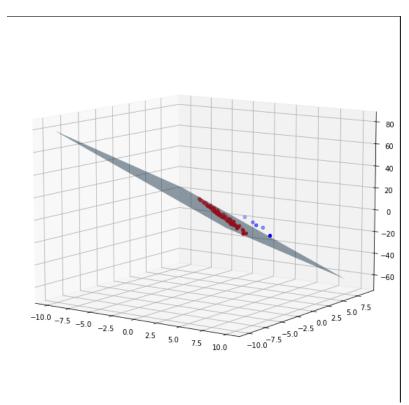
$$min_{ec{eta}} \ S(ec{eta}) \ where \ S(ec{eta}) = \sum_{i=1}^m r_i (ec{eta})^2 = (y_i - f(ec{eta}, x_i))^2$$

And implemented the suggested algorithm. I tried it with different initial values and <u>damping factor</u>, and it was unable to find the correct amplitude. Unsurprisingly, because the algorithm <u>may not converge</u>. Here is the final result.



Task 2

In task 2, I used **dataset 8** and sklearn.linear\_model.RANSACRegressor to fit the data provided there. To make an experiment, I nade some points the outliers (blue). The inliers are red.



For residual\_threshold, I applied median absolute deviation since it's a "robust estimator of dispersion".

I set min\_samples = 3, since it's the minimal number of points required to construct a plane from a non-degenerate triangle. That the data represents a plane is obvious from the scatter plots.

Finally, I observed that 100 iterations are enough to exclude all my outliers.