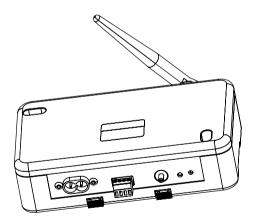
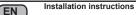


# RS485 RTS TRANSMITTER





page 2

SOMFY hereby declares that this product complies with the essential requirements and other relevant provisions of Directive 1999/5/EC. A Declaration of Conformity is available at the web address www.somfy.com/CE. Suitable for use in EU, CH and NO.

#### SAFETY AND IMPORTANT INFORMATION

- This Somfy product must be installed by a professional motorisation and home automation installer, for whom these instructions are intended.
- Before installation, check that this product is compatible with the associated equipment and accessories
- These instructions describe how to install, commission and use this product.
- Moreover, the installer must comply with current standards and legislation in the country in which the product is being installed, and inform his customers of the operating and maintenance conditions for the product.
- Any use outside the sphere of application specified by Somfy is not approved. Such use, or any failure to comply with the instructions given herein will invalidate the warranty, and Somfy refuses to accept liability.

#### PRODUCT DESCRIPTION

The RS485 RTS transmitter is a motor controller witch allow to manage all your Somfy RTS applications with the same centralized home control system.

It can control up to 16 groups of SOMFY RTS motors and receivers.

It is impossible to set a motor or a receiver with this RS485 RTS transmitter.

The RS485 RTS transmitter is for internal use only.

#### ENVIRONMENT



Damaged electric products and batteries should not be disposed of with normal household waste

Make sure to drop them in specially provided containers or at an authorized organization that will ensure they are recycled.

#### INSTALLATION

Wall installation

#### DIN rail installation

#### WIRING

## Controls wiring

1) For RS485 Control Plug the RS485 control to the RS485 connector.

NC: Not Use

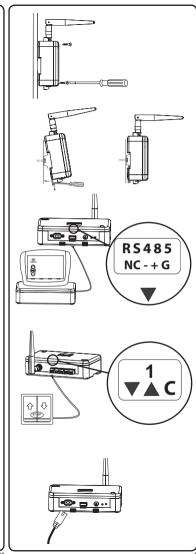
- + : RS 485 Bus +
- : RS 485 Bus G : Ground
- 2) For Dry Contact Control

Plug the dry contact control to the dry contact connector.

- ▼: Down
- **▲**: Up
- C : Commun

#### Power wiring

Connect the transmitter to a standard AC power source.



#### COMMISSIONING

Before assign a product to the transmitter. this product must be set.

## Assign a product with a RS485 control

1) Press the programming button on the back of the RTS control point or the RTS receiver until the motor joas. The product is in programming mode.

2) Send by the RS485 control, the corresponding RTS frame on the desired

The product is assigned to the transmitter's channel with a motor jog.

#### Assign a product with a DRY CONTACT control

1) Select the RTS adress on the Channel selector corresponding to dry contact connectors.

- The dry contact connector n°1 has per default, the RTS address n°1

- The dry contact connector n°2 has per default, the RTS address n°2

channel

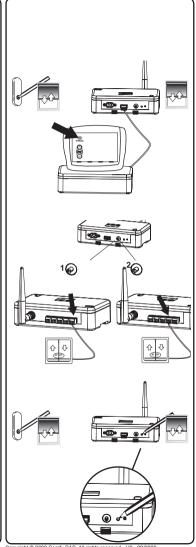
- The dry contact connector n°5 has per default, the RTS address n°5

2) Press the programming button on the

back of the RTS control point or the RTS receiver until the motor jogs. The product is in programming mode.

3) Press the programming button on the RS485 RTS transmitter until the motor jogs.

The product is assigned to the transmitter.



USE

#### Dry contact

#### Up, Down, Stop and My

#### Un

Press the Up button of the control

#### Down

Press the Down button of the control

#### Stop / Mv

Press the Stop button of the control. If the product move, it will stop.

If the product don't move, the product

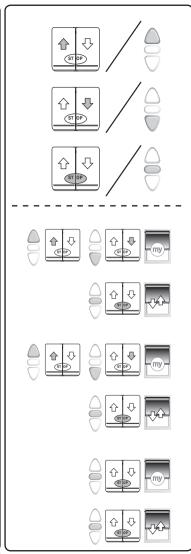
goes to the My position (if a My position is

# My position

recorded).

1) Recording My position. To set the My position, move the

- product to the desired position with the UP and DOWN buttons then press the My button until the shade joas or the light blink.
- 2) Changing the My position To change the My position go to the new desired My position with the UP and DOWN buttons then press the My button until the product jogs or the light hlink
- 3) Delete the My position To delete the MY position, move to this position and press the My button until the product jogs or the light blink.



#### RS485 communication standard

All signals on the physical link between devices should comply with EIA/TIA-485-A standard.

Recommended cable : Shielded , two twisted- pair type 22 - 24 AWG (120  $\Omega$ )

Communication mode : half-duplex

Between two messages, leave 100 ms approx.

#### Each character is coded as follow:

Character coding					
Baud Rate	4800	+/-1%			
Start bit	Logical Level 0				
Data bits	8	Less significant bit transmitted first			
Parity	Odd				
Stop bit	Logical Level 1				

lessage	Forma	t							
Description	Refer to 'MSG' column in the table below for a list of available messages.	Refer to 'LEN' column to have the correct value depending on message.	Aways 05h when message sent to RS485 RTS transmitter Always 50h when message received from RS485 RTS RTS transmitter	NodeID of the transmitter (SouRCe address)	NodeID of the receiver (DESTination address)	Information on DATA fields can be found below: - Length of DATA, part (in byte count) - Type of every DATA fields - Available values for each DATA fields	CHECKSUM is one's complement of sum of bytes 1 to byte (n-2)	If CHECKSUM not correct, message is ignored.	
Value	See Message Table		05h / 50h	Node dependant (refer to product label)		See Message Table		byte 1 + + byte (n-z)	
Name	MSG	LEN	Reserved	SRC@ (*)	DEST@	DATA	CHECKSUM		
Byte Number	-	2	ε	4 - 6	7 -9	:	Byte n-1	Byte n	

# Messages table

Command Type	Command Description	Message Name (MSG)
Setting	Configure application modes :  - CE/US ergonomics - Rolling / Tilting mode - MODULIS mode	SET_FORMAT (90h)
	Set number of RTS frames to send on a CTRL_TILT order	SET_TILT_FRAMECOUNT (91h)
	Set number of RTS frames to send on a CTRL_DIM order	SET_DIM_FRAMECOUNT (92h)
	Sun Auto ON / OFF	SET_SUN_AUTO (93h)
	Lock / Unlock dry contacts inputs	SET_DCT_LOCK (94h)
	Send PROG command	SET_CHANNEL (97h)
	Open the programmation mode	SET_OPEN_PROG (98h)
	Save favorite position as Intermediate Position	SET_IP (9Ah)

LEN	DATA Length	DATA Type	DATA Value	
0Fh	4	8-bits	0 to 15 = RTS channel selection	
		8-bits	0 = CE Mode 1 = US Mode (Default)	
		8-bits	0 = Rolling Mode (Default) 1 = Tilting Mode	
		8-bits	0 = Normal Mode 1 = Modulis Mode (Default)	
0Eh	3	8-bits	0 to 15 = RTS channel selection	
		8-bits	US mode (range = 4 to 255)	
		8-bits	CE mode (range = 2 to 13)	
0Dh	2	8-bits	0 to 15 = RTS channel selection	
		8-bits	Range = 4 to 255	
0Dh	2	8-bits	0 to 15 = RTS channel selection	
		8-bits	0 = ON 1 = OFF	
0Ch	1	8-bits	Bits 1 to 5 control inputs 1 to 5 0 = Unlock 1= Lock	
0Ch	1	8-bits	0 to 15 = RTS channel selection	
0Ch	1	8-bits	0 to 15 = RTS channel selection	
0Ch	1	8-bits	0 to 15 = RTS channel selection	

Command Type	Command Description	Message Name (MSG)	
Control	Move UP / Light ON Move DOWN / Light OFF STOP movement Move to favorite position / Switch light ON with favorite light level	CTRL_POSITION (80h)	
	Tilt + / -	CTRL_TILT (81h)	
	Dim + / -	CTRL_DIM (82h)	

LEN	DATA Length	DATA Type	DATA Value	
		8-bits	0 to 15 = RTS channel selection	
0Dh	2	8-bits	1 = UP / ON 2 = DOWN / OFF 3 = STOP 4 = Favorite position / light level	
0Eh	3	8-bits	0 to 15 = RTS channel selection	
		8-bits	0 = Tilt + 1 = Tilt -	
		8-bits	Tilting value (1 to 127)	
0Eh	3	8-bits	0 to 15 = RTS channel selection	
		8-bits	0 = Dim + 1 = Dim -	
		8-bits	Diming value (1 to 127)	

Command Type	Command Description	Message Name (MSG)	
	Read application modes configuration	GET_CHANNEL_MODE (A0h)	
Status	Answer to GET_CHANNEL_MODE	POST_CHANNEL_MODE (B0h)	
	Read RTS frame count for CTRL_TILT order	GET_TILT_FRAMECOUNT (A1h)	
	Answer to GET_TILT_FRAMECOUNT	POST_TILT_FRAMECOUNT (B1h)	
	Read RTS frame count for CTRL_DIM order	GET_DIM_FRAMECOUNT (A2h)	
	Answer to GET_DIM_FRAMECOUNT	POST_DIM_FRAMECOUNT (B2h)	
	Read dry contacts lock configuration	GET_DCT_LOCK (A4h)	
	Answer to GET_DCT_LOCK	POST_DCT_LOCK (B4h)	

Warning: All messages named POST\_Something are messages sent by the product as an answer to the corresponding GET\_Something request. If POST\_Something message is sent to the product, it will be ignored.

LEN	DATA Length	DATA Type	DATA Value		
0Ch	1	8-bits	0 to 15 = RTS channel selection		
		8-bits	0 to 15 = RTS channel selection		
0Fh	4	8-bits	0 = CE Mode 1 = US Mode		
		16-bits	0 = Rolling Mode 1 = Tilting Mode		
		16-bits	0 = Normal Mode 1 = Modulis Mode		
0Ch	1	8-bits	0 to 15 = RTS channel selection		
		8-bits	0 to 15 = RTS channel selection		
0Eh	3	8-bits	Frame count in US mode		
		16-bits	Frame count in CE mode		
0Ch	1	8-bits	0 to 15 = RTS channel selection		
0Dh	2	8-bits	0 to 15 = RTS channel selection		
ווטט	2	8-bits	Frame count		
0Bh	0		n/a		
0Ch	1	8-bits	Bits 1 to 5 control inputs 1 to 5 0 = Unlock 1= Lock		

### Example

#### Steps to follow to create a correct data frame :

- 1. Create frame with values as indicated in the tables above => «raw data»
- 2. Invert all data bytes => «actual data»3. Calculate the checksum on «actual data» (sum of all inverted bytes)
- Calculate the checksum on «actual data» (sum of all inverted bytes)
   Data to send are the concatenation of «actual data» and checksum

#### Steps to follow when receiving data from a product :

- 1. Received data are the concatenation of  $\mbox{\tt ``actual data''}$  and checksum
- 2. Remove the last 2 bytes to isolate the checksum and get «Actual data»
- 3. Invert all remaining data bytes to get the «raw data»

The following examples show the data to send on the bus for different message types. Examples are given for a communication between a host and a slave using the following addresses:

Host@ = FF:FF:00 (FF FF 00 <= @ <= FF FF FE for a non-SOMFY host) Slave@ = 05:00:02 (See NodeID label on product)

Co	Messages	Direction		Data
pyright © 2008 Somfy Sa	CTRL_POSITION Parameters: ( Channel4, DOWN ) >> Send DOWN command on channel 4	Command Host >> Slave	Raw data     Actual Data     Checksum     Data to send	80 0D 05 00 FF FF 02 00 05 04 02 7F F2 FA FF 00 00 FD FF FA FB FD 08 58 7F F2 FA FF 00 00 FD FF FA FB FD 08 58
AS. All rights reserved - V	CTRL_TILT Parameters : ( Channel8, Tilt-, 30 ) >> Send a TILT command of -30 pulses	Command Host >> Slave	Raw data     Actual Data     Checksum     Data to send	81 0E 05 00 FF FF 02 00 05 08 01 1E 7E F1 FA FF 00 00 FD FF FA F7 FE E1 09 34 7E F1 FA FF 00 00 FD FF FA F7 FE E1 09 34
/0 - 09/2008	GET_CHANNEL_MODE Parameters : ( Channel6 ) >> Read configuration of channel 6	Request Host >> Slave	Raw data     Actual Data     Checksum     Data to send	A0 0C 05 00 FF FF 02 00 05 06 5F F3 FA FF 00 00 FD FF FA F9 07 3A 5F F3 FA FF 00 00 FD FF FA F9 07 3A
	POST_CHANNEL_MODE Parameters : ( Channel6, US, Rolling, MODULIS) >> Answer to the previous status request	Answer 1. Received da Slave >> Host 2. Actual data 3. Raw data	Answer 1. Received data >> Host 2. Actual data 3. Raw data	4F F0 AF FD FF FA FF 00 00 F9 FE FF FE 09 D7 4F F0 AF FD FF FA FF 00 00 F9 FE FF FE B0 0F 50 02 00 05 00 FF FF 06 01 00 01

RS485 command for a blind MOVE UP Allow to open the blind. MOVE DOWN Allow to close the blind INTERMEDIATE POSITION Allow to move the blind to the intermediate position. STOP Allow to stop the blind. Allow to move the venitian slats in one way. TILT + TILT -Allow to move the venitian slats in the other wav. Allow to record, change or delete an SAVE FAVORITE POSITION intermediate position. AS INTERMEDIATE POSITION (cf: USE / My position p 5). SUN AUTO ON Allow to activate the sun automatism. SUN AUTO OFF Allow to desactivate the sun automatism for light Light ON Allow to switch on the light. Light OFF Allow to switch off the light. ON (favourite light position) Allow to switch on the light to a favorite level. DIM + Allow to increase the light intensity. DIM -Allow to dicrease the light intensity.

Voltage	90V → 255V		
Voltage Frequency	50Hz → 60Hz		
Operating temperature	0°C / 60 °C		
Protection rating	IP20		
Control	Dry Contact / RS485		
RTS Frequency	433 MHz	447 MHz	

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