

Future Technology Devices International Ltd. Application Note AN_100 AN_100 Using the FT232R/FT245R with an External Crystal or Oscillator

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This document provides details of the steps required to replace the internal oscillator of the FT232/245R IC with an external clock source.



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1 Introduction

The FTDI FT232R and FT245R devices have an integrated clock oscillator to simplify USB designs and reduce component count. In some applications it may be necessary to use an external clock source. For example when operating at a reduced VCC supply voltage or for improved EMC. This document describes how to disable the internal oscillator and enable the external clock source.

Users can use the example schematic and functional software code to begin their design. Note that software code is not guaranteed and not supported by FTDI. It is provided as an illustration only.

2 External Oscillator - Hardware Requirements

With the internal oscillator enabled both the OSCI pin and the OSCO pin are disconnected from the signals internally to the chip and should be left unconnected on the PCB.

Enabling and disabling the internal oscillator is done in the EEPROM as described in Section 3.0. By default a FT232R/245R device is delivered with the internal oscillator enabled.

When using an external crystal a crystal must be connected across the OSCI and OSCO pins.

The crystal frequency must be $12.0 \text{MHz} \pm 0.5\%$. An AT-cut crystal is recommended.

Note: The load capacitance (C_L) will be specified on the datasheet of the crystal.

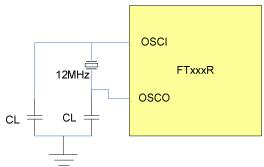


Figure 2.1 Crystal Connection

If using an external oscillator or other clock source then the frequency must also be 12.0MHz \pm 0.5%. It must also drive at +5V CMOS levels or be AC coupled to centre around +VCC/2. In this case the source drives the OSCI pin. The OSCO pin is tied to GND.

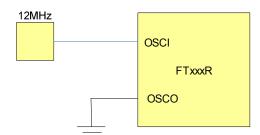


Figure 2.2 Oscillator Connection

3 External Oscillator - EEPROM modification requirements

To disable the internal oscillator the EEPROM must be re-configured. This EEPROM modification cannot be done using the FTDI programming utility, MPROG. The EEPROM can only be re-configured from a custom application.

3.1 Sample C++ Application

The sample code below shows how this can be done using a C++ application.

(NOTE: This code is not supported or guaranteed by FTDI).

```
#include <windows.h>
#include <stdio.h>
#include "ftd2xx.h"
int main(int argc, char* argv[])
{
      FT HANDLE fthandle;
      FT STATUS status;
 status = FT Open(0, &fthandle);
          if(status != FT OK)
              printf("open status not ok %d\n", status);
      FT PROGRAM DATA ftData;
      WORD VendorIdBuf = 0x0403;
      WORD ProductIdBuf = 0x6001;
      char ManufacturerBuf[32];
      char ManufacturerIdBuf[16];
      char DescriptionBuf[64];
      char SerialNumberBuf[16];
       ftData.Signature1 = 0x000000000;
       ftData.Signature2 = 0xffffffff;
       ftData. Version = 2; //'0 = 'BM device, 1 = 'C Device, 2 = 'R device
       ftData.VendorId = VendorIdBuf;
       ftData.ProductId = ProductIdBuf;
      ftData.Manufacturer = ManufacturerBuf;
       ftData.ManufacturerId = ManufacturerIdBuf;
       ftData.Description = DescriptionBuf;
       ftData.SerialNumber = SerialNumberBuf;
       ftData.MaxPower = 90;
       ftData.PnP = 1;
       ftData.SelfPowered = 0;
      ftData.RemoteWakeup = 0;
//'R features require section below
       ftData.UseExtOsc; // Use External Oscillator
       ftData.HighDriveIOs; // High Drive I/Os
       ftData.EndpointSize; // Endpoint size
       ftData.PullDownEnableR; // non-zero if pull down enabled
ftData.SerNumEnableR; // non-zero if serial number to be used
       ftData.InvertTXD; // non-zero if invert TXD
       ftData.InvertRXD; // non-zero if invert RXD
       ftData.InvertRTS; // non-zero if invert RTS
       ftData.InvertCTS; // non-zero if invert CTS
       ftData.InvertDTR; // non-zero if invert DTR
       ftData.InvertDSR; // non-zero if invert DSR
      ftData.InvertDCD; // non-zero if invert DCD
       ftData.InvertRI; // non-zero if invert RI
       ftData.Cbus0; // Cbus Mux control
```



```
ftData.Cbus1; // Cbus Mux control
       ftData.Cbus2; // Cbus Mux control
       ftData.Cbus3; // Cbus Mux control
       ftData.Cbus4; // Cbus Mux control
       ftData.RIsVCP; // non-zero if using VCP drivers
       status = FT EE Read(fthandle, &ftData);
              if (status != FT OK)
                     printf("EE Read status not ok %d\n", status);
              else
              //It is optional to print out all the parameters.
              {
                     printf("Signature1 = 0x\%04x\n", ftData.Signature1);
                     printf("Signature2 = 0x\%04x\n", ftData.Signature2);
                     printf("Version = 0x\%04x\n", ftData.Version);
                     printf("Manufacturer = %s\n", ftData.Manufacturer);
                     printf("ManufacturerID = %s\n", ftData.ManufacturerId);
                     printf("Description = %s\n", ftData.Description);
                     printf("SerialNumber = %s\n", ftData.SerialNumber);
                     printf("MaxPower = %d\n", ftData.MaxPower);
                     printf("PnP = %x\n", ftData.PnP);
                     printf("SelfPowered = %x\n", ftData.SelfPowered);
                     printf("RemoteWakeup = %x\n", ftData.RemoteWakeup);
                     printf("Use Ext Osc = %x\n", ftData.UseExtOsc);
                     printf("High Drives = %x\n", ftData.HighDriveIOs);
                     printf("Endpoint Size = %x\n", ftData.EndpointSize);
                     printf("Pull Down Enabled = %x\n", ftData.PullDownEnableR);
                     printf("Serial Number Enabled = %x\n", ftData.SerNumEnableR);
                     printf("Invert TXD = %x\n", ftData.InvertTXD);
printf("Invert RXD = %x\n", ftData.InvertRXD);
                     printf("Invert RTS = %x\n", ftData.InvertRTS);
                     printf("Invert CTS = %x\n", ftData.InvertCTS);
                     printf("Invert DTR = %x\n", ftData.InvertDTR);
printf("Invert DSR = %x\n", ftData.InvertDSR);
printf("Invert DCD = %x\n", ftData.InvertDCD);
                     printf("Invert RI = %x\n", ftData.InvertRI);
                     printf("CBUS0 = %x\n", ftData.Cbus0);
                     printf("CBUS1 = %x\n", ftData.Cbus1);
                     printf("CBUS2 = %x\n", ftData.Cbus2);
printf("CBUS3 = %x\n", ftData.Cbus3);
printf("CBUS4 = %x\n", ftData.Cbus4);
                     printf("RIsVCP = %x\n", ftData.RIsVCP);
//use external clock.
       ftData.UseExtOsc = 1; //Enabling use of external oscillator
      status = FT EE Program(fthandle, &ftData);
       status = FT Close(fthandle);
              if (status != FT OK)
              printf("EE Program status not ok %d\n", status);
              else
                     printf("EE Program status ok %d\n", status);
      return 0;
}
```

CAUTION: IF THE INTERNAL OSCILLATOR IS DISABLED IN THE EEPROM, THE DEVICE WILL NOT FUNCTION UNTIL AN EXTERNAL CLOCK SOURCE IS APPLIED.

THIS EXTERNAL CLOCK SOURCE WILL BE NECESSARY IF THE APPLICATION NEEDS TO RE-ENABLE THE INTERNAL CLOCK SOURCE.

3.2 Sample Visual Basic.NET Application

The sample code below shows how to accomplish the same EEPROM modification through a Visual Basic program. To avoid accidentally programming other FT2xxR devices that may be plugged into the host PC, this program is configured to only work when a single FTDI device is installed. The Visual Basic.NET project and source code for this application is available upon request to support1@ftdichip.com.

This basic dialog shows the necessary information to interact with the user.

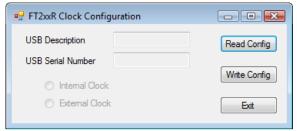


Figure 3.1 FT2xxR Clock Configuration – Initial Dialog

When the "Read Config" button is clicked, the USB description (Product Description in MPROG) and USB Serial Number are read from the EEPROM, as well as the current clock setting, and displayed.

The user simply needs to select the appropriate radio button and click "Write Config". If the external clock option is selected, a warning appears, asking for confirmation that the target circuit indeed has an external clock or crystal.

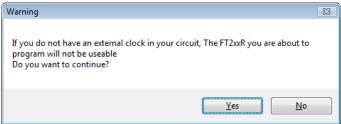


Figure 3.2 FT2xxR Clock Configuration - External Clock Warning

There are additional information dialog boxes that will appear to indicate when the EEPROM has been read or written, and to reset the target upon exiting the program.

Other EEPROM settings can be modified in the same manner and added to the dialog box.

The following D2XX function calls, as defined by the <u>Managed .NET wrapper</u>, are used to read and write the EEPROM:

- **GetNumberOfDevices** = Obtains the number of FTDI devices connected to the host PC. If the number <> 1, then the program will exit.
- **GetDeviceList** = Obtains the enumerated information including the USB Product String and USB Serial Number that were read by the operating system upon enumeration.
- **OpenByDescription** = Obtains the handle to the FT2xxR device.
- ReadFT232REEPROM = Reads the content of the FT2xxR EEPROM and populates the data structure.
- **WriteFT232REEPROM** = Writes the new settings as indicated in the dialog box.
- CyclePort = Forces the operating system to re-enumerate the FT2xxR

Note that the same .NET wrapper can be used in any of the Visual Studio.NET languages.

CAUTION: IF THE INTERNAL OSCILLATOR IS DISABLED IN THE EEPROM, THE DEVICE WILL NOT FUNCTION UNTIL AN EXTERNAL CLOCK SOURCE IS APPLIED.

THIS EXTERNAL CLOCK SOURCE WILL BE NECESSARY IF THE APPLICATION NEEDS TO RE-ENABLE THE INTERNAL CLOCK SOURCE.

4 Contact Information

Head Office - Glasgow, UK

Future Technology Devices International Limited Unit 1, 2 Seaward Place Centurion Business Park Glasgow G41 1HH United Kingdom

Tel: +44 (0) 141 429 2777 Fax: +44 (0) 141 429 2758

E-mail (Sales) <u>sales1@ftdichip.com</u> E-mail (Support) <u>support1@ftdichip.com</u>

E-mail (General Enquiries) admin1@ftdichip.com

Web Site URL http://www.ftdichip.com Web Shop URL http://www.ftdichip.com

Branch Office - Taipei, Taiwan

Future Technology Devices International Limited (Taiwan) 2F, No. 516, Sec. 1, NeiHu Road

Taipei 114 Taiwan , R.O.C.

Tel: +886 (0) 2 8791 3570 Fax: +886 (0) 2 8791 3576

E-mail (Sales) <u>tw.sales1@ftdichip.com</u>

E-mail (Support) <u>tw.support1@ftdichip.com</u> E-mail (General Enquiries) <u>tw.admin1@ftdichip.com</u>

Web Site URL http://www.ftdichip.com

Branch Office - Hillsboro, Oregon, USA

Future Technology Devices International Limited (USA) 7235 NW Evergreen Parkway, Suite 600 Hillsboro, OR 97123-5803 USA

Tel: +1 (503) 547 0988 Fax: +1 (503) 547 0987

E-Mail (Sales) us.sales@ftdichip.com E-Mail (Support) us.admin@ftdichip.com Web Site URL http://www.ftdichip.com

Branch Office - Shanghai, China

Future Technology Devices International Limited (China) Room 408, 317 Xianxia Road, Shanghai, 200051

China

Tel: +86 21 62351596 Fax: +86 21 62351595

E-mail (Sales) <u>cn.sales@ftdichip.com</u> E-mail (Support) <u>cn.support@ftdichip.com</u>

E-mail (General Enquiries) cn.admin@ftdichip.com

Web Site URL http://www.ftdichip.com

Distributor and Sales Representatives

Please visit the Sales Network page of the FTDI Web site for the contact details of our distributor(s) and sales representative(s) in your country.

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Appendix A - List of Figures and Tables

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Appendix B - Revision History

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