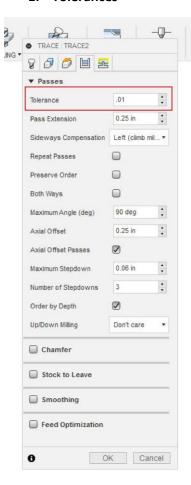
Setting up Fusion 360 CAM for use on the Gerber Sabre 408

Before outputting from Fusion CAM to the Gerber Sabre 408, you must first install the Post Processor for the Gerber in the Fusion Post Processor Local Directory. Instructions for how to add a custom Post Processor to the Fusion local directory can be found here:

https://knowledge.autodesk.com/support/fusion-360/learnexplore/caas/sfdcarticles/sfdcarticles/How-to-add-a-Post-Processor-to-your-Personal-Posts-in-Fusion-360.html

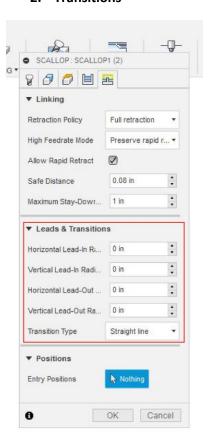
After that there are just a few adjustments that you should follow in Fusion CAM for best result on the Gerber 408

1. Tolerances



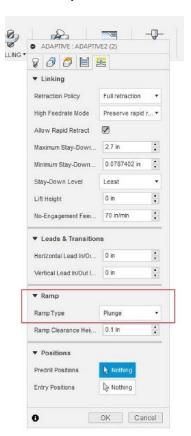
The Gerber 408 router will do its best to interpret the CNC code from Fusion, however you should lower the Tolerances in any toolpath setup to make it easier on the machine. If the work you are producing cannot allow for an error tolerance of .01 inch than perhaps another machine should be used.

2. Transitions



Lead Ins and Outs should be removed to minimize errors in circular interpolation.

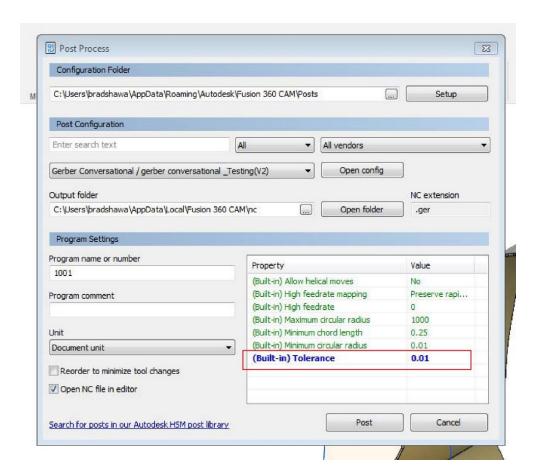
3. Entry



This version of the Post Processor only allows for Plunge entry into the part. For best results, set the entry type to Plunge.

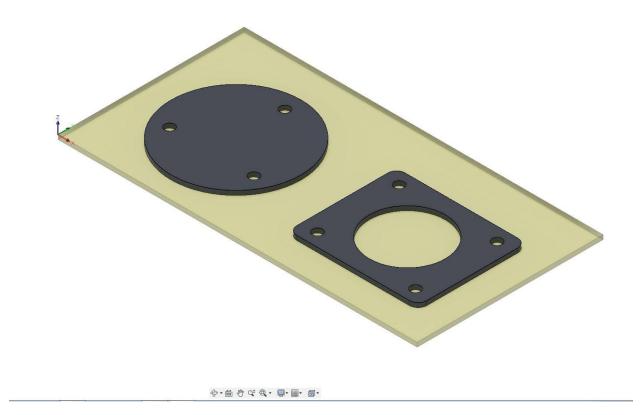
4. Post Process overrides

Before Posting out of Fusion 360, make sure to override the Built-In Tolerance default and set it to 0.01 inch.



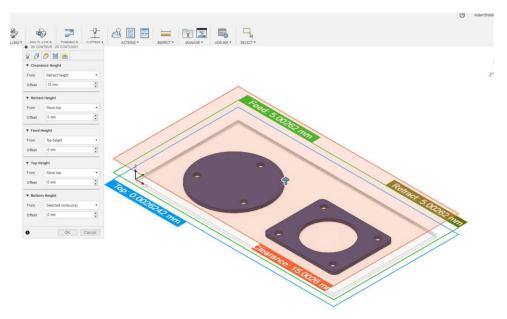
5. WCS and Part Orientation

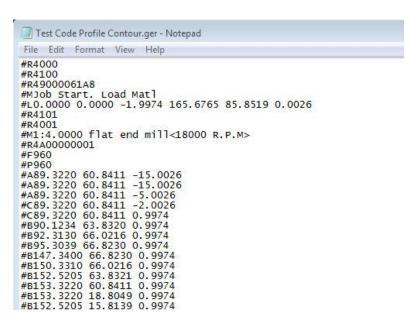
The WCS for all setups in Fusion CAM should be set to the top of the Stock with the origin set to the lower Left corner of the stock.



6. Planes/Retracts/Clearances

With the WCS set to the top of the Stock all moves related to planes, retracts and clearances will post out of Fusion CAM with a Negative value. Conversely, all cutting moves will have a Positive value.





The Clearance Plane in this Code is actually 15.0026 millimeters above the Part Origin. The Feed Plane is 5.0026 millimeters above the part and the first cutting move is 1 millimeter deep into the 1.9974 thick stock.