

# Recursion

recursion

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# Binary Search

```
public int binSearch (int[ ] a, int k) {
    int left = 0;
    int right = 0;
    while (left <= right) {
        int mid = (left + right) / 2;
        if (a[mid] == k) return mid;
        if ( a[mid] < k ) left = mid+1; //left half starts here now
        else right = mid-1;           //right half ends here now
    }
    return -1; //K is not found
}
```

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# Recursion

Approaches to large problem:

Find the simple, **base-case(s)**  
trivial cases that can simply return the answer

Find relationship from large case to simpler cases (Each sub-division of problem moves closer to the base-case)

Sometimes recursion is more clear than explicit looping (*this point is arguable*)

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# Binary Search

Given a sorted array of size N

Find the value K in  $O(\log_2 N)$  time

1, 3, 4, 6, 8, 10, 13, 22, 40, 50

Start at middle:

if ( $K < \text{middle value}$ ) search left half

if ( $K > \text{middle value}$ ) search right half

can divide a list in half only  $\log_2 N$  times! hence  $O(\log_2 N)$

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# Recursion

A process that solves larger problems by dividing the problem into similar, but simpler problems

solve that problem, by solving that problem!

Humor: Google "Recursion": *Did you mean Recursion?*

Russian *Matryoshka* dolls

N Factorial:  $= n * (n-1 \text{ factorial})$

Fibonacci sequence:  $F(n) = F(n-1) + F(n-2)$

sort (alist);

sort (Llist) && sort (Rlist) ...

Divide and conquer

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# Examples

```
public int factorial (int n) {
```

```
    if (n == 0) return 1; //base case
```

```
    return n * factorial(n-1); //recursive call
```

```
}
```

Does it fulfill the requirements?

base case exists (*in this case,  $0! = 1$  by definition*)

each call moves closer to the base case

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# Examples

```
public int fibonacci (int n) {  
    if (n == 0) return 0;      //base case  
    if (n == 1) return 1;      //base case  
    return fibonacci(n-1) + fibonacci(n-2); //recursive calls  
}
```

Note multiple base cases

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# Recursion

Wikipedia:

**Recursion** in computer science is a method where the solution to a problem depends on solutions to smaller instances of the same problem

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## Greatest Common Divisor

Euclid (ancient Greek guy)

$$\text{gcd}(x, y) = \begin{cases} x & \text{if } y=0 \\ \text{gcd}(y, \text{remainder}(x,y)) & \text{if } y > 0 \end{cases}$$

```
public int gcd (int x, int y)  
{  
    if (y == 0) return x;  
    return gcd (y, x % y);  
}
```

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## Sierpinski Triangle

Draw an equilateral triangles within equilateral triangles...

sierpinski (a, b, c)

find midpoints of each side (divide by 2)

midAB, midBC, midAC

sierpinski (a, midAB, midBC)

sierpinski (midAB, b, midBC)

sierpinski (midAC, midBC, C)

Requires a base case - because theoretically there will always be a divide by 2

*Usually a value signifying the "order" and each recursive call reduces the order by 1. Base case is order == 0*

Could also make base case be when midpoint length < S

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## Sierpinski Applet

Show applet

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## Towers of Hanoi

Three pegs; N disks of increasing diameter

Start with all disks on left peg in order of decreasing size.

Cannot place larger diameter onto small diameter

Move all disks one-at-a-time

BEWARE

Goal: move all disks to right peg

Time complexity is  $2^{n-1}$

Challenging problem:

Extreme growth rate!!!!

*End of the world legend*

1) What is the base case?

move one disk from **x** to **y**

2) What is the recursive problem?

move (n-1) disks from **x** to **h**; then move disk **n** to **y**

move (n-1) disks from **h** to **y**

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# Binary Search

## Recursive Edition

```
public int binSearch (int [ ] a, int k)    // "starter" method (common for recursion)
    return binSearch (a, k, 0, a.length-1); // begin the recursive

public int binSearch (int[] a, int k, int left, int right)
    if (left > right) return -1;
    int mid = (left + right) / 2;
    if (a[mid] == k) return mid;
    if (a[mid] < k)      1, 2, 3, 5, 8, 12, 14, 15, 20, 26
        return binSearch (a, k, mid+1, right);
    else
        return binSearch (a, k, left, mid-1);
```

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# QuickSort

## Naturally recursive algorithm

if list size > 1

Pick an element (pivot) from the list

Partitioning: Reorder so that all values less than pivot  
are on the left; all values greater than pivot on the right  
sorted = qsort (lefthalf) + pivot + qsort (righthalf)

base case: list size < 2

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# QuickSort

## Partitioning

```
choose pivot & move to top of array a[hi]
left = lo; right = hi-1;
while (left < right)
    move left up finding un-sorted value
    move right down until find un-sorted value
    if (left < right) swap a[left] and a[right]
swap pivot and a[right]
```

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# QuickSort

Worst case?

What about all equal values?

Best case?

Average runtime  $O(n \log_2 n)$

slightly behind linear! (this is very good)

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