

Fractional Brownian Motion with Variable Hurst Parameter: Definition and Properties

Jelena Ryvkina

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Abstract A class of Gaussian processes generalizing the usual *fractional Brownian motion* for Hurst indices in $(1/2, 1)$ and *multifractal Brownian motion* introduced in Ralchenko and Shevchenko (2010 Theory Probab Math Stat 80:119–130) and Boufoussi et al. (Bernoulli 16(4):1294–1311, 2010) is presented. Any measurable function assuming values in this interval can now be chosen as a variable Hurst parameter. These processes allow for modeling of phenomena where the regularity properties can change with time either continuously or through jumps, such as in the volatility of a stock or in Internet traffic. Some properties of the sample paths of the new process class, including different types of continuity and long-range dependence, are discussed. It is found that the regularity properties of the Hurst function chosen directly correspond to the regularity properties of the sample paths of the processes. The long-range dependence property of fractional Brownian motion is preserved in the larger process class. As an application, Fokker–Planck-type equations for a time-changed *fractional Brownian motion with variable Hurst parameter* are found.

Keywords Fractional Brownian motion · Gaussian processes · Variable Hurst parameter · Self-similarity · Sample path regularity

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1 Introduction

Fractional Brownian motion (fBM) is a class of zero-mean Gaussian processes with covariance functions given by

J. Ryvkina (✉)
Department of Mathematics, Tufts University, 503 Boston Ave., Medford, MA 02155, USA
e-mail: jelryvkina@googlemail.com

$$\text{Cov}(t, s) = \frac{1}{2} \left(s^{2H} + t^{2H} - |t - s|^{2H} \right) \quad \text{for } s, t \geq 0,$$

where the so-called Hurst parameter H is a constant in $(0,1)$. This process was first introduced by Kolmogorov [21]. The name fBM goes back to Mandelbrot and van Ness, who found a representation as an integral with respect to regular *Brownian motion* (BM) in [23]. fBM has stationary increments, is a.s. Hölder continuous of any order $\gamma < H$ on compact intervals, and is H -self-similar.

fBM is used for models in numerous areas such as finance, hydrology, and telecommunications. The Hurst parameter is what determines the path behavior of fBM and hence the value of H directly reflects the types of phenomena which can be modeled by the corresponding fBM . In particular, the case $H < 1/2$ yields negatively correlated increments and rather erratic paths suitable for modeling systems with fast changing states. In the case $H > 1/2$, the increments are positively correlated and the process exhibits long-range dependence, i.e., fBM with such H is used when slowly decaying effects are observed. The case $H = 1/2$ yields the usual BM and hence independent increments are obtained [7].

In nature, one often observes changes in the dynamics of a system over time. For example, during market shocks, one can deduce unusual movements in the volatility of a stock price. Even though, due to long-range dependence in the data, fBM with $H > 1/2$ seems to be a good choice for modeling the volatility—as was suggested in [11], it was demonstrated in [10] that different H values for different time intervals are necessary. Another example is the use of fBM in image processing. In [20], projections of images of osteoporosis affected bone matter are modeled as fBM with a spatial index. It is likely that the model could be improved, where the Hurst parameter allowed to vary over the different areas of the sample, since the disease does not affect all bone matter uniformly. Further examples, where a constant H seems unrealistic, can be easily found in computer traffic [31] and other fields. Consequently, a Gaussian process exhibiting long-range dependence and variable in its path behavior is of interest not only theoretically but for various applications as well.

The objective of this paper is to define a class of Gaussian processes, extending fBM for $H > 1/2$ by permitting arbitrary measurable functions $H(\cdot)$ as variable Hurst parameters. Some initial properties such as path-regularity properties and long-range dependence shall be derived. Other generalizations of fBM have been considered before, but the class of permissible Hurst index functions was usually restricted due to the purpose or the inherent properties of the respective construction. *Multifractal Brownian motion* ($mfBM$) for example was introduced in [29] and [8] and involves Hölder continuous parameter functions. For the process class considered in [26] and [5], the aim was to obtain sufficiently regular processes and hence only Hölder continuous parameter functions were used in the definition of *multifractional Brownian motion* (mBM) as well. A further extension of mBM was then presented in [14] and includes some lower semi-continuous functions, but a construction involving limits of Hölder functions and limits of corresponding processes was needed in order to maintain the regularity properties of the resulting processes. Other generalizations (see, e.g., [27]) are limited to piecewise constant H .

Here, a different approach inspired by Decreusefond's idea in [13] involving an appropriate class of covariance functions is pursued. His focus on Volterra processes yields a generalization of fBM under some strong regularity assumption on the function $H(\cdot)$. However, in Sect. 2 of this paper, it will be shown that it is possible to extend this approach. The use of covariance functions to define Gaussian processes presents a coherent way to extend fBM and $mfBM$ to a class of processes parametrized by the set of all measurable functions with values in $(1/2, 1)$ and different from mBM . Possible discontinuities in the paths of the resulting processes are of interest for applications involving non-continuous but long-range dependent processes, especially since the location of their occurrence can be controlled through the parameter function, as will be seen in Sect. 3.2.

This paper is structured as follows: In Sect. 2, the class of covariance functions R_H is defined and several representations of $R_H(\cdot, \cdot)$ are given. *Fractional Brownian motion with variable Hurst parameter (fBMvH)* is defined. In Sect. 3, asymptotic behavior of the covariance functions is used to investigate some path properties of $fBMvH$. Interestingly, the regularity properties of the Hurst function turn out to be directly reflected in the regularity properties of the paths of $fBMvH$ (e.g., jumps yield jumps and Hölder continuity yields Hölder continuity). Further, it is shown that the long-range dependence property, which makes fBM with $H > 1/2$ a realistic model for persistent systems, is preserved for the extended class. As an application, in Sect. 4, a Fokker–Plank-type equation for the time-changed $fBMvH$ is presented. In Sect. 5, the process is modeled and plots of several different $fBMvH$ s are shown.

2 $fBMvH$

The first objective in obtaining an extension of the fBM class will be to find a class of covariance functions involving a time varying H . Once a suitable class of functions is found, it is straightforward to define a new class of Gaussian processes.

In the case $H > 1/2$, the covariance function of fBM can be obtained as

$$\text{Cov}(t, s) = \int_0^{s \wedge t} K(t, u) K(s, u) du, \text{ where} \\ K(t, s) = \left[c_H s^{\frac{1}{2}-H} \int_s^t (u-s)^{H-\frac{3}{2}} u^{H-\frac{1}{2}} du \right] \mathbb{1}_{[0,t]}(s), \quad (2.1)$$

for $c_H = \left(\frac{H(2H-1)}{\beta(2-2H, H-1/2)} \right)^{1/2}$, where $\beta(\cdot, \cdot)$ denotes the beta function (see, e.g., [2]). This paper makes use of L. Decreusefond's idea in [13], where under certain regularity assumptions, Volterra processes were obtained by replacing the constant H in (2.1) with a function $H(t)$. It will be shown however that the measurability of $H(\cdot)$ alone is sufficient in order to define a Gaussian process.

Let $T > 0$ and $H : [0, T] \rightarrow (1/2, 1)$ be a function and $R_H^T : [0, T] \times [0, T] \rightarrow \mathbb{R}$ be defined by

$$R_H^T(t, s) = \int_0^{s \wedge t} K_H(t, u) K_H(s, u) \, du, \quad (2.2)$$

with

$$K_H(t, s) = \left[c_{H_t} s^{\frac{1}{2} - H_t} \int_s^t (u - s)^{H_t - \frac{3}{2}} u^{H_t - \frac{1}{2}} \, du \right] \mathbb{1}_{[0, t]}(s) \quad (2.3)$$

for $s, t \in [0, T]$ and where $H_t = H(t)$. Clearly, R_H^T is symmetric. Furthermore, R_H^T can be used as covariance function for a Gaussian process on $[0, T]$ due to the next theorem.

Theorem 2.1 *Let H be measurable. Then, R_H^T is positive semidefinite.*

Proof Let K be the integral operator defined on $L^2([0, T])$ via K_H , i.e., $Kf(t) = \int_0^T K_H(t, s)f(s) \, ds$. If K_H is in $L^2([0, T] \times [0, T])$, then K has an adjoint on $L^2([0, T])$ (see [12]) given by $K^*g(s) = \int_s^T K_H(t, s)g(t) \, dt$ for $g \in L^2$. For $\alpha_1, \dots, \alpha_n \in \mathbb{R}$ and $t_1, \dots, t_n \in [0, T]$,

$$\sum_{i,j} \alpha_i \alpha_j R_H^T(t_i, t_j) = \int_0^T \left[K^* \left(\sum_i \alpha_i \delta_{t_i} \right) (s) \right]^2 \, ds \geq 0, \quad (2.4)$$

where δ_t denotes the Dirac delta. It remains to show that $\int_{[0, T]^2} K_H(t, s)^2 \, ds \, dt$ is finite.

$$\begin{aligned} & \int_{[0, T]^2} K_H(t, s)^2 \, ds \, dt \\ &= \int_0^T \int_0^T \int_{u \vee v}^T c_{H_t}^2(uv)^{H_t - \frac{1}{2}} \int_0^{u \wedge v} s^{1-2H_t} (u-s)^{H_t - \frac{3}{2}} (v-s)^{H_t - \frac{3}{2}} \, ds \, dt \, du \, dv. \\ &= \int_0^T \int_0^T \int_{u \vee v}^T c_{H_t}^2(u-v)^{2H_t-2} \beta(H_t - 1/2, 2 - 2H_t) \, dt \, du \, dv \text{ by Lemma 6.1} \\ &= \int_0^T c_{H_t}^2 \beta(H_t - 1/2, 2 - 2H_t) \int_0^t \int_0^t (u-v)^{2H_t-2} \, du \, dv \, dt \\ &= \int_0^T t^{2H_t} \, dt, \end{aligned}$$

which is finite for all measurable H with values in $(1/2, 1)$. \square

The following theorem shows that (2.4) is in fact strict and will become useful in Sect. 5.

Theorem 2.2 *Let H be measurable. Then, R_H^T is positive definite.*

Proof Without loss of generality, let $n \geq 2$ be fixed and $t_1, \dots, t_n \in [0, T]$ be distinct. Further, let $\alpha_1, \dots, \alpha_n \in \mathbb{R} - \{0\}$. By (2.4), it is sufficient to show that $K^*(\sum_i \alpha_i \delta_{t_i})(s) = \sum_i \alpha_i K_H(t_i, s) \neq 0$ on some interval contained in $[0, T]$. Assume the t_i are ordered by magnitude, i.e., $t_1 < t_2 < \dots < t_n$. For $s \in (t_{n-1}, t_n)$

$$\sum_i \alpha_i K_H(t_i, s) = \alpha_n K_H(t_n, s) \neq 0$$

by (2.3) and hence

$$\sum_{i,j} \alpha_i \alpha_j R_H^T(t_i, t_j) \geq \alpha_n^2 \int_{t_{n-1}}^{t_n} K_H(t_n, s)^2 ds > 0.$$

□

R_H^T is easily extended to the positive real line. Let $H : [0, \infty) \rightarrow (1/2, 1)$ be measurable and let the covariance function R_H be defined by $R_H : [0, \infty) \times [0, \infty) \rightarrow \mathbb{R}_+$ with $R_H(t, s) = R_H^T(t, s)$ for $t, s \leq T$. This definition is consistent, since $R_H^{T_1}(t, s) = R_H^{T_2}(t, s)$ on $[0, T_1 \wedge T_2] \times [0, T_1 \wedge T_2]$. R_H is positive semidefinite (and positive), because R_H^T has this property for all T .

Definition 2.3 *Fractional Brownian motion with variable Hurst parameter (fBMvH)* is defined as the centered Gaussian process X^H on $[0, \infty)$ starting at zero and with covariance function given by R_H .

For constant H , X^H coincides with the usual fBM on \mathbb{R}_+ and hence the class of processes $\{X^H : H : [0, \infty) \rightarrow (1/2, 1) \text{ is measurable}\}$ is a generalization of fBM with $H > 1/2$. In the proof of Theorem 2.1, it was shown that $K_H(\cdot, \cdot) \in L^2([0, T] \times [0, T])$ and hence $K_H(t, \cdot) \in L^2([0, T])$ for each $t \in (0, T]$ fixed. By the Itô isometry, X^H can be constructed on $[0, T]$ as

$$X_t^H = \int_0^t K_H(t, s) dB_s \quad \text{for } t \in [0, T], \quad (2.5)$$

where $(B_s)_{s \in [0, T]}$ is a regular BM. For Hölder continuous parameter functions H , fBMvH coincides with mfBM studied in [29] and [8].

Remark 2.4 Under further regularity assumptions on the function H , i.e., if H assumes values in a compact interval and if the Hölder exponent α of H satisfies $\alpha > \sup_t H_t$, mfBM is shown to be locally asymptotically self-similar in [8]. Further, if H is additionally assumed to be of bounded variations, the authors of [8] show that the stochastic calculus developed in [2] holds for mfBM and establish results on the local time of the process.

Several forms of R_H are useful and will be given in the next proposition. One of them involves the Gauss hypergeometric function defined by

$${}_2F_1(a, b; c; z) = \sum_{n=0}^{\infty} \frac{(a)_n(b)_n}{(c)_n} \frac{z^n}{n!} \quad \text{for } |z| < 1, \quad (2.6)$$

on the unit disc and analytically extendible. $(x)_n$ denotes here the Pochhammer symbol, i.e., $(x)_0 = 1$ and $(x)_n = x(x+1) \cdots (x+n-1)$ for $n > 0$. For properties of ${}_2F_1$, the interested reader is referred to Chapter 15 of [1].

In the following, let

$$c_{t,s} = c_{H_t} c_{H_s} \text{ and } \tilde{\beta}_{t,s} = \beta_{t,s}^1 \beta_{t,s}^2 + \beta_{s,t}^1 \beta_{s,t}^2, \quad (2.7)$$

both of which are symmetric in s and t , with

$$\beta_{t,s}^1 = \beta(H_t - 1/2, 2 - H_t - H_s), \quad \beta_{t,s}^2 = \beta(H_t - H_s + 1, H_t + H_s - 1). \quad (2.8)$$

Proposition 2.5 (Various forms of R_H) *The following are equivalent forms of R_H . For $s, t \geq 0$*

(i)

$$R_H(t, s) = c_{t,s} \left[\tilde{\beta}_{t,s} \frac{(s \wedge t)^{H_t+H_s}}{H_t+H_s} + \beta_{s \wedge t, s \vee t}^1 \int_{s \wedge t}^{s \vee t} \int_0^{s \wedge t} \left(\frac{y}{z} \right)^\alpha (y-z)^{H_t+H_s-2} dz dy \right], \quad (2.9)$$

where $\alpha = (H_t - H_s) \mathbb{1}_{\{s \leq t\}} + (H_s - H_t) \mathbb{1}_{\{s > t\}}$.

Assuming $t \geq s \geq 0$, (2.9) reduces to

$$R_H(t, s) = c_{t,s} \left[\tilde{\beta}_{t,s} \frac{s^{H_t+H_s}}{H_t+H_s} + \beta_{s,t}^1 \int_s^t \int_0^s \left(\frac{y}{z} \right)^{H_t-H_s} (y-z)^{H_t+H_s-2} dz dy \right]. \quad (2.10)$$

(ii)

$$R_H(t, s) = \frac{c_{t,s}}{H_t+H_s} \left[\beta_{t,s}^1 \beta_{t,s}^2 s^{H_t+H_s} + \beta_{s,t}^1 \left[s^{H_t+H_s} \int_{\frac{s}{t}}^1 v^{-2H_t} (1-v)^{H_s+H_t-2} dv \right. \right. \\ \left. \left. + t^{H_t+H_s} \int_0^{\frac{s}{t}} v^{H_s-H_t} (1-v)^{H_s+H_t-2} dv \right] \right], \quad (2.11)$$

where by convention, $0 \cdot \infty = 0$ and hence $R_H^T(t, 0) = 0$;

(iii)

$$R_H(t, s) = \frac{c_{t,s}}{H_t + H_s} \left[\beta_{t,s}^1 \beta_{t,s}^2 s^{H_t + H_s} + \beta_{s,t}^1 \beta_{s,t}^2 t^{H_t + H_s} + \frac{\beta_{s,t}^1 t (t-s)^{H_t + H_s - 1}}{H_t + H_s - 1} \left(\frac{t}{s} \right)^{H_t - H_s} \right. \\ \left. \times \left[{}_2F_1 \left(1, 2H_t; H_s + H_t; \frac{s-t}{s} \right) - {}_2F_1 \left(1, H_t - H_s; H_s + H_t; \frac{s-t}{s} \right) \right] \right]. \quad (2.12)$$

(iv)

$$R_H(t, s) = c_{t,s} \int_0^t \int_0^s \left[\beta_{t,s}^1 \mathbb{1}_{\{y > z\}} + \beta_{t,s}^1 \mathbb{1}_{\{y < z\}} \right] \times \left(\frac{y}{z} \right)^{H_t - H_s} |y - z|^{H_s + H_t - 2} dz dy. \quad (2.13)$$

(v) For $t \geq s \geq 0$

$$R_H(t, s) = \frac{c_{t,s}}{H_t + H_s} \left[\frac{\beta_{t,s}^1 \beta_{t,s}^2}{H_t + H_s} s^{H_t + H_s} + \frac{\beta_{s,t}^1 \beta_{s,t}^2}{H_t + H_s} t^{H_t + H_s} \right. \\ \left. - \beta_{s,t}^1 \int_s^t \int_z^t \left(\frac{y}{z} \right)^{H_t - H_s} (y - z)^{H_s + H_t - 2} dy dz \right]. \quad (2.14)$$

Proof Form (2.10), (2.9), and (2.11) are derived using Lemma 6.1, “Appendix 1”. The integrals in representation (2.11) can be expressed in terms of the Gauss hypergeometric function (see [28, p. 301], or Lemma 7.1 (v), in “Appendix 2”). Using 15.3.9 in [1] (Lemma 7.1 (i), in “Appendix 2”), form (2.12) is obtained. Equations (2.13) and (2.14) were derived for *mfBM* in [8] and [29], respectively. \square

Corollary 2.6 For $s, t \in [0, T]$ such that $H_t = H_s$

$$R_H^T(t, s) = \frac{1}{2} \left(s^{2H_t} + t^{2H_t} - |t - s|^{2H_t} \right).$$

Further, the variance function of *fBMvH* X^H is given by $R_H^T(t, t) = t^{2H_t}$.

Remark 2.7 For Hölder continuous parameter functions H , *mBM* was introduced in [5] and [26] and has a covariance function of type $g(H_t, H_s)(t^{H_t + H_s} + s^{H_t + H_s} + |t - s|^{H_t + H_s})$ (see [4]), where $g(x, y)$ is smooth on $(\frac{1}{2}, 1) \times (\frac{1}{2}, 1)$ and symmetric in x and y , and $g(H_t, H_s)$ does not directly depend on s and t . Hence, for general Hölder continuous H , the covariance functions of *fBMvH* and *mBM* cannot be transformed into each other upon multiplication by a function solely dependent on H_s and H_t [see, e.g., form (2.12)]. Accordingly, the processes cannot be generally obtained from each other through just $H(\cdot)$ -dependent normalization, i.e., for a general Hölder continuous H , *mBM* and *fBMvH* will exhibit different dependence structures.

3 Properties

3.1 (Non)-self-similarity

In order to achieve variability in the path behavior over time for the $fBMvH$ class, clearly, the stationarity of the increments as well as self-similarity properties had to be relaxed. Instead, the following proposition holds.

Proposition 3.1 *For any $a > 0$ fixed, $fBMvH$ X^H satisfies*

$$X_{at}^H \sim a^{\overline{H}_t} X_t^{\overline{H}}$$

in the sense of finite dimensional distributions and with $\overline{H}(t) = H(at)$.

Proof Using (2.2), one can easily check that

$$\text{Cov}(X_{at}^H, X_{as}^H) = a^{\overline{H}_t + \overline{H}_s} \text{Cov}(X_t^{\overline{H}}, X_s^{\overline{H}}).$$

□

Remark 3.2 If H is constant, Proposition 3.1 yields the usual self-similarity property of fBM .

3.2 Continuity of the Paths

The path regularity of $fBMvH$ is closely related to the regularity properties of the parameter function H . In the following paragraphs, it is shown that a continuous H is a prerequisite for any kind of continuity of the sample paths and that discontinuities of H yield discontinuities in the paths of X^H . If H is Hölder continuous, the process possesses an almost surely continuous modification and is Hölder continuous as well. Furthermore, H then impacts the path regularity directly at each point t , i.e., the local Hölder exponent of $fBMvH$ at time t is given by H_t .

3.2.1 Continuity in Probability and Discontinuities

It will be useful to establish that a continuous H implies a continuous covariance function R_H . This fact can then be used to link continuity of the parameter function to stochastic continuity of the process X^H .

Lemma 3.3 *The function $H : [0, \infty) \rightarrow (1/2, 1)$ is continuous on \mathbb{R}_+ if and only if the covariance function $R_H(\cdot, \cdot)$ is continuous in each variable and the variance $\text{Var}(X_t^H)$ is continuous as well.*

Proof First, assume that H_t is continuous for $t \in \mathbb{R}_+$. Then, $\text{Var}(X_t^H) = t^{2H_t}$ is clearly continuous in t as well. To establish continuity of $R_H(\cdot, \cdot)$ consider the following cases.

Case 1: Let t be fixed and (s_n) be a sequence converging to $s > 0$ with $t > s$. For all n sufficiently large $s_n < t$. The convergence of the integral terms in the form (2.11) of $R_H(t, s_n)$ to the integral terms of $R_H(t, s)$ follows by Lebesgues's dominated convergence theorem. The non-integral term is clearly continuous.

Case 2: For a sequence (s_n) with $s_n \downarrow 0$ and $t > 0$ fixed, $R_H(t, s_n) \rightarrow 0$, since by Lebesgues's dominated convergence theorem, the integral part of the form (2.10) converges to 0. If $t = 0$, convergence of $R_H(s_n, 0)$ to 0 becomes obvious.

Case 3: If s is fixed and (t_n) is a sequence converging to $t > s > 0$, the continuity of $R_H(\cdot, s)$ at t can be established using the same arguments as in Case 1.

Case 4: To see that $R_H(t_n, t) \rightarrow R_H(t, t)$ for $t_n \rightarrow t$, one can first consider increasing and decreasing sequences and proceed as in Case 1 and then use $R_H(t_n, t) = R_H(t_n, t)\mathbb{1}_{\{t_n \leq t\}} + R_H(t_n, t)\mathbb{1}_{\{t_n > t\}}$ for an arbitrary sequence converging to t .

Now, suppose that $R_H(\cdot, \cdot)$ is continuous in each variable and that $\text{Var}(X^H)$ is continuous as well. H has to be continuous at any $t_0 \in \mathbb{R}_+ - \{1\}$, since $t^{2H_t} \rightarrow t_0^{2H_{t_0}}$ for $t \rightarrow t_0$. That H is also continuous at $t_0 = 1$ can be deduced from the form of the coefficient functions in (2.11). \square

Proposition 3.4 *The process X^H is continuous in probability if and only if H is continuous on \mathbb{R}_+ .*

Proof By Theorem 8.12 in [19], X^H is stochastically continuous if and only if $R_H(\cdot, \cdot)$ is continuous in each variable and $\text{Var}(X^H)$ is continuous as well. The claim follows by Lemma 3.3. \square

The following Lemma will be useful for showing that a discontinuity in H at t_0 implies either a jump of X^H at t_0 or a sequence of discontinuity points converging to t_0 .

Lemma 3.5 *If H is discontinuous at $t_0 > 0$, then*

- (i) $R_H(\cdot, t_0)$ is discontinuous at t_0 ;
- (ii) X^H is stochastically discontinuous at t_0 .

Proof Part (i): Let (t_n) be a sequence such that $t_n \rightarrow t_0$ and $H_{t_n} \rightarrow \hat{H}_{t_0} \neq H_{t_0}$. Using the same reasoning as in the proof of Lemma 3.3, one can show that $R_H(t_n, t_0) \rightarrow \frac{c_{t, \hat{t}_0}}{H_{t_0} + \hat{H}_{t_0}} \tilde{\beta}_{t_0, \hat{t}_0} t_0^{H_{t_0} + \hat{H}_{t_0}}$, where the subscript \hat{t}_0 indicates that H_{t_0} has to be replaced by \hat{H}_{t_0} in the coefficient function in question.

Part(ii): Let (t_n) be again a sequence such that $t_n \rightarrow t_0$ and $H_{t_n} \rightarrow \hat{H}_{t_0} \neq H_{t_0}$ and $\varepsilon > 0$. Then,

$$\begin{aligned} P(|X_{t_n}^H - X_{t_0}^H| > \varepsilon) &= P\left(\frac{|X_{t_n}^H - X_{t_0}^H|}{\sqrt{\text{Var}(X_{t_n}^H - X_{t_0}^H)}} > \frac{\varepsilon}{\sqrt{\text{Var}(X_{t_n}^H - X_{t_0}^H)}}\right) \\ &= 2\left(1 - \Phi\left(\frac{\varepsilon}{\sqrt{\text{Var}(X_{t_n}^H - X_{t_0}^H)}}\right)\right), \end{aligned}$$

where Φ denotes the Gaussian cumulative distribution function. Due to part (i) and its proof $\text{Var}(X_{t_n}^H - X_{t_0}^H) = t_n^{2H_{t_n}} + t_0^{2H_{t_0}} - 2R_H(t_n, t_0)$ converges to some constant $c > 0$ depending on t_0 and the sequence (t_n) . Consequently, $P(|X_{t_n}^H - X_{t_0}^H| > \varepsilon) \rightarrow 0$. \square

For the next proposition, consider X^H to be separable. It is well known that any process indexed by a subset of \mathbb{R} has a separable version (see for example Theorem 2.4 in [15]). Also, any continuous version is automatically separable.

Proposition 3.6 *If H has a discontinuity at $t_0 \neq 0$, then X^H has almost surely discontinuous sample paths. Then, $P(X^H \text{ is discontinuous at } t_0) > 0$ and the paths of X^H have either a discontinuity at t_0 or a sequence of discontinuity points converging to t_0 .*

Proof By Lemma 3.5, part (ii) it follows that X^H is discontinuous in probability at t_0 . Hence, the process is also not almost surely continuous at t_0 and $P(X^H \text{ is discontinuous at } t_0) > 0$. Let

$A_n = \{X^H \text{ is discontinuous on } [t_0 - 1/n, t_0 + 1/n]\}$. It follows that

$$P(A_n) \geq P(X^H \text{ is discontinuous at } t_0) > 0.$$

Theorem 2 in [9] states that a separable Gaussian process is continuous on a closed interval with probability either 0 or 1, which yields that $P(A_n) = 1$ for all n . Since $A_n \downarrow A = \bigcap_{n \geq 1} A_n$, by continuity

$$P(A) = \lim_{n \rightarrow \infty} P(A_n) = 1.$$

\square

3.2.2 Existence of an a.s. Continuous and Hölder Continuous Modification

In [29], it was shown that for an α -Hölder continuous parameter functions H , the modification given in (2.5) has a. s. continuous sample paths which are also a.s. Hölder continuous on any compact interval $[a, b] \in \mathbb{R}_+$ with exponents in $(0, \alpha \wedge \min_{t \in [a, b]} H_t)$. The authors used the particular form of the process as well as the Garsia–Rodemich–Rumsey inequality to establish the result. In [8], representation (2.5) is shown to be a. s. continuous under the assumptions that H has values in a compact interval and that the Hölder parameter of H satisfies $\alpha > \max H_t$. If H assumes values in a compact interval and is α_T -Hölder continuous on each interval $[0, T]$, a concise proof for the existence of a modification of X^H , which is Hölder

continuous on each $[0, T]$ with exponents in $(0, \frac{\alpha_T}{2})$, can be found in [30]. This proof utilizes a slightly modified version of Kolmogorov's continuity theorem.

At this point, it remains unclear whether an a.s. continuous modification still exists if the Hölder continuity condition on H is relaxed to continuity. A necessary condition for the existence of an a.s. continuous modification can be formulated in terms of the existence of a majorizing measure (see for example Theorem 12.9 in [22]).

3.3 Asymptotic Behavior of R_H and Local Hölder Continuity

In the following lemmas and theorem, the asymptotic behavior of $R_H(t+h, t)$ and $\text{Var}(X_{t+h}^H - X_t^H)$ will be analyzed for $h \rightarrow 0$ and $R_H(t+h, t)$ will be studied in the case $h \rightarrow \infty$ as well. A direct application is a local Hölder continuity result.

Lemma 3.7 *For any $t > 0$ fixed and $h \downarrow 0$,*

$$R_H^T(t+h, t) = \frac{c_{t+h,t}}{H_{t+h} + H_t} \left[\beta_{t+h,t}^1 \beta_{t+h,t}^2 t^{H_{t+h}+H_t} + \beta_{t,t+h}^1 \beta_{t,t+h}^2 (t+h)^{H_{t+h}+H_t} \right. \\ \left. - \frac{\beta_{t,t+h}^1}{H_{t+h} + H_t - 1} \left(\frac{t+h}{t} \right)^{H_{t+h}-H_t+1} h^{H_{t+h}+H_t} + O\left(h^{H_{t+h}+H_t+1}\right) \right].$$

For $h \uparrow 0$,

$$R_H^T(t, t+h) = \frac{c_{t,t+h}}{H_{t+h} + H_t} \left[\beta_{t,t+h}^1 \beta_{t,t+h}^2 (t+h)^{H_{t+h}+H_t} + \beta_{t+h,t}^1 \beta_{t+h,t}^2 t^{H_{t+h}+H_t} \right. \\ \left. - \frac{\beta_{t+h,t}^1}{H_{t+h} + H_t - 1} \left(\frac{t}{t+h} \right)^{H_t-H_{t+h}+1} |h|^{H_{t+h}+H_t} + O\left(|h|^{H_{t+h}+H_t+1}\right) \right].$$

Proof First, assume $t > h > 0$ for all h small enough. By (2.6)

$${}_2F_1\left(1, 2H_{t+h}; H_t + H_{t+h}; -\frac{h}{t}\right) - {}_2F_1\left(1, H_{t+h} - H_t; H_t + H_{t+h}; -\frac{h}{t}\right) \\ = -\frac{h}{t} + \sum_{n=0}^{\infty} \frac{(2H_{t+h})_{n+2} - (H_{t+h} - H_t)_{n+2}}{(H_{t+h} + H_t)_{n+2}} \left(-\frac{h}{t}\right)^{n+2}$$

and since $(x)_{n+k} = (x)_k(x+k)_n$,

$$\left| \sum_{n=0}^{\infty} \frac{(2H_{t+h})_{n+2} - (H_{t+h} - H_t)_{n+2}}{(H_{t+h} + H_t)_{n+2}} \left(-\frac{h}{t}\right)^{n+2} \right| \\ \leq \left(\frac{h}{t}\right)^2 \left[\frac{(2H_{t+h})_2}{(H_{t+h} + H_t)_2} \sum_{n=0}^{\infty} \frac{(2H_{t+h} + 2)_n}{(H_{t+h} + H_t + 2)_n} \left(\frac{h}{t}\right)^n \right]$$

$$+ \frac{|(H_{t+h} - H_t)_2|}{(H_{t+h} + H_t)_2} \sum_{n=0}^{\infty} \frac{(H_{t+h} - H_t + 2)_n}{(H_{t+h} + H_t + 2)_n} \left(\frac{h}{t}\right)^n \Bigg] \\ \leq C \left(\frac{h}{t}\right)^2 \left[{}_2F_1\left(1, 4; 3; \frac{h}{t}\right) + {}_2F_1\left(1, 2.5; 3; \frac{h}{t}\right) \right].$$

for some $C > 0$. The Gauss hypergeometric series (2.6) has 1 as radius of convergence and hence ${}_2F_1(1, 4; 3; \frac{h}{t}) + {}_2F_1(1, 2.5; 3; \frac{h}{t}) \rightarrow 2$ for $h \rightarrow 0$. Plugging the above into (2.12) and noting that $\beta_{t,t+h}^1$ is bounded since $H_t \subset (1/2, 1)$ is fixed yields the first part of the claim. The second part is obtained analogously. \square

In the following, let $\sigma_{t,h}^2 = \text{Var}(X_{t+h}^H - X_t^H)$ and for $h > 0$ let

$$\tilde{\sigma}_{t,h}^2 = t^{2H_t} + (t+h)^{2H_{t+h}} \\ - \frac{2c_{t+h,t}}{H_{t+h} + H_t} \left[\beta_{t+h,t}^1 \beta_{t+h,t}^2 t^{H_{t+h}+H_t} + \beta_{t,t+h}^1 \beta_{t,t+h}^2 (t+h)^{H_{t+h}+H_t} \right. \\ \left. - \frac{\beta_{t,t+h}^1}{H_{t+h} + H_t - 1} \left(\frac{t+h}{t}\right)^{H_{t+h}-H_t+1} h^{H_{t+h}+H_t} \right].$$

In this definition, the covariance part of $\sigma_{t,h}^2$ was replaced by the asymptotically equivalent function found in Lemma 3.7.

Theorem 3.8 *Let H be Hölder continuous with exponent $1 \geq \alpha > \sup_t H_t$ and $H \in [a, b] \subset (1/2, 1)$. For any fixed t and $h \rightarrow 0$,*

$$\frac{\sigma_{t,h}^2}{|h|^{2H_t}} \rightarrow 1.$$

Proof First, assume $h > 0$. If $t = 0$, then $\frac{\sigma_{0,h}^2}{|h|^{2H_0}} = h^{2H_h-2H_0} \rightarrow 1$, hence let $t > 0$.

Step 1: $\tilde{\sigma}_{t,h}^2/|h|^{2H_t} \rightarrow 1$ for $h \rightarrow 0$.

The coefficient functions

$$f(H_{t+h}, H_t) = \frac{2c_{t+h,t} \beta_{t+h,t}^1 \beta_{t+h,t}^2}{H_{t+h} + H_t} \text{ and } f(H_t, H_{t+h}) = \frac{2c_{t+h,t} \beta_{t,t+h}^1 \beta_{t,t+h}^2}{H_{t+h} + H_t}$$

are both smooth with bounded partial derivatives of any order on $[a, b] \times [a, b]$. Denoting $\partial_x f(x, y)|_{x=y}$ by $g(y)$, it follows by Taylor's theorem that

$$f(H_{t+h}, H_t) = 1 + g(H_t)(H_{t+h} - H_t) + O((H_{t+h} - H_t)^2) \text{ and} \\ f(H_t, H_{t+h}) = 1 + g(H_{t+h})(H_t - H_{t+h}) + O((H_{t+h} - H_t)^2) \\ = 1 + g(H_t)(H_t - H_{t+h}) + O((H_{t+h} - H_t)^2).$$

By the Hölder continuity of H , it follows that

$$\begin{aligned}\tilde{\sigma}_{t,h}^2 &= t^{2H_t} - t^{H_{t+h}+H_t} + (t+h)^{2H_{t+h}} - (t+h)^{H_{t+h}+H_t} \\ &\quad - g(H_t)(H_{t+h} - H_t)(t^{H_{t+h}+H_t} - (t+h)^{H_{t+h}+H_t}) \\ &\quad + \frac{2c_{t+h,t}}{(H_{t+h} + H_t)} \frac{\beta_{t,t+h}^1}{(H_{t+h} + H_t - 1)} \left(\frac{t+h}{t}\right)^{1+H_{t+h}-H_t} h^{H_{t+h}+H_t} + O(h^{2\alpha}).\end{aligned}$$

Using Taylor expansions to see

$$\begin{aligned}t^{2H_t} - t^{H_{t+h}+H_t} &= \ln(t)t^{2H_t}(H_t - H_{t+h}) + O(h^{2\alpha}), \\ (t+h)^{2H_{t+h}} - (t+h)^{H_{t+h}+H_t} &= -\ln(t+h)(t+h)^{2H_{t+h}}(H_t - H_{t+h}) + O(h^{2\alpha}), \\ \ln(t+h) &= \ln(t) + O(h) \text{ and} \\ t^{2H_t} - (t+h)^{2H_{t+h}} &= t^{2H_t} - t^{2H_{t+h}} + O(h) = O(h^\alpha) + O(h) \text{ and} \\ t^{H_{t+h}+H_t} - (t+h)^{H_{t+h}+H_t} &= O(h),\end{aligned}$$

one obtains

$$\begin{aligned}\tilde{\sigma}_{t,h}^2 &= \frac{2c_{t+h,t}}{(H_{t+h} + H_t)} \frac{\beta_{t,t+h}^1}{(H_{t+h} + H_t - 1)} \left(\frac{t+h}{t}\right)^{1+H_{t+h}-H_t} h^{H_{t+h}+H_t} \\ &\quad + O(h^{1+\alpha}) + O(h^{2\alpha}),\end{aligned}$$

and hence

$$\begin{aligned}\lim_{h \rightarrow 0} \frac{\tilde{\sigma}_{t,h}^2}{h^{2H_t}} &= \lim_{h \rightarrow 0} \frac{2c_{t+h,t}}{(H_{t+h} + H_t)} \frac{\beta_{t,t+h}^1}{(H_{t+h} + H_t - 1)} \left(\frac{t+h}{t}\right)^{1+H_{t+h}-H_t} h^{H_{t+h}+H_t} \\ &= 1.\end{aligned}$$

Step 2: $\sigma_{t,h}^2/\tilde{\sigma}_{t,h}^2 \rightarrow 1$.

$$\frac{\sigma_{t,h}^2}{\tilde{\sigma}_{t,h}^2} = 1 + \frac{\sigma_{t,h}^2 - \tilde{\sigma}_{t,h}^2}{\tilde{\sigma}_{t,h}^2} = 1 + \frac{O(h^{1+H_{t+h}+H_t})}{h^{2H_t}} \left(\frac{h^{2H_t}}{\tilde{\sigma}_{t,h}^2}\right) = 1 + o(1) \frac{h^{2H_t}}{\tilde{\sigma}_{t,h}^2} \rightarrow 1$$

for $h \rightarrow 0$ by Lemma 3.7.

Combining steps 1 and 2, the statement follows for any null sequence with $h > 0$ for all h :

$$\frac{\sigma_{t,h}^2}{h^{2H_t}} = \frac{\sigma_{t,h}^2}{\tilde{\sigma}_{t,h}^2} \left(\frac{\tilde{\sigma}_{t,h}^2}{h^{2H_t}}\right) \rightarrow 1.$$

If the second part of Lemma 3.7 is used to define $\tilde{\sigma}_{t,h}^2$, then the claim follows in the case $h < 0$ for all h by the same arguments as above. Finally, the statement holds for any sequence $h \rightarrow 0$ since

$$\left| \frac{\sigma_{t,h}^2}{|h|^{2H_t}} - 1 \right| \leq \left| \frac{\sigma_{t,|h|}^2}{|h|^{2H_t}} - 1 \right| + \left| \frac{\sigma_{t,-|h|}^2}{|h|^{2H_t}} - 1 \right| \rightarrow 0 \text{ for } h \rightarrow 0.$$

□

Corollary 3.9 *Let H be Hölder continuous with exponent $1 \geq \alpha > \sup_t H_t$ and $H \in [a, b] \subset (1/2, 1)$. For any fixed t and $h \rightarrow 0$*

$$\frac{X_{t+h}^H - X_t^H}{|h|^{H_t}} \xrightarrow{\mathcal{L}} \mathcal{N}(0, 1).$$

Proof The claim follows by Lévy’s continuity theorem combined with Theorem 3.8. □

The next corollary uses Theorem 3.8 in order to show that under the Hölder continuity assumption on H , the local regularity of the path of fBM_vH at each point t is governed by the function H . H_t is identified as the local Hölder exponent for X^H at time t . In [29] and [8], this result was obtained using the representation of the process as an integral with respect to BM and an alternative definition of local Hölder exponent, and an asymptotic self-similarity result, respectively.

Definition 3.10 A function f has local Hölder exponent γ at t if

$$\gamma = \sup \left\{ \alpha : \lim_{h \rightarrow 0} \frac{|f(t+h) - f(t)|}{|h|^\alpha} = 0 \right\}.$$

This is equivalent to the following:

$$\begin{aligned} \lim_{h \rightarrow 0} \frac{|f(t+h) - f(t)|}{|h|^\alpha} &= 0 \quad \text{for all } 0 < \alpha < \gamma \text{ and} \\ \limsup_{h \rightarrow 0} \frac{|f(t+h) - f(t)|}{|h|^\alpha} &= \infty \quad \text{for all } \alpha > \gamma > 0. \end{aligned}$$

In the following corollary, X^H is again assumed to be separable.

Corollary 3.11 *Let H be Hölder continuous with exponent $1 \geq \alpha > \sup_t H_t$ and $H \in [a, b] \subset (1/2, 1)$. Then, for each $t > 0$, the local Hölder exponent of X^H at t is almost surely H_t .*

Proof Let $t \geq 0$ be fixed and $0 < \gamma < H_t$. Further, let $(h_m)_{m \geq 1}$ be a null sequence and

$$E = \left\{ \limsup_{m \rightarrow \infty} \frac{|X_{t+h_m}^H - X_t^H|}{|h_m|^\gamma} > 0 \right\} = \bigcup_{n=1}^{\infty} A_n,$$

where

$$A_n = \limsup_{m \rightarrow \infty} B_m^n, \quad B_m^n = \left\{ \frac{|X_{t+h_m}^H - X_t^H|}{|h_m|^\gamma} > \frac{1}{n} \right\}.$$

In order to show $P(E) = 0$, $P(A_n) = 0$ for all n will be established first. Let $Z \sim \mathcal{N}(0, 1)$ and let Φ again denote the cumulative distribution function of a standard normal. It follows that

$$\begin{aligned} P(B_m^n) &= 1 - P\left(-\frac{|h_m|^\gamma}{n} \leq X_{t+h_m}^H - X_t^H \leq \frac{|h_m|^\gamma}{n}\right) \\ &= 1 - P\left(-\frac{|h_m|^\gamma}{n\sigma_{t,h_m}} \leq Z \leq \frac{|h_m|^\gamma}{n\sigma_{t,h_m}}\right) \\ &= 2\left(1 - \Phi\left(\frac{|h_m|^\gamma}{n\sigma_{t,h_m}}\right)\right) \\ &\leq 2\frac{n\sigma_{t,h_m}}{|h_m|^\gamma} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(|h_m|^\gamma/n\sigma_{t,h_m})^2} \end{aligned}$$

by the known inequality $1 - \Phi(x) \leq \frac{1}{\sqrt{2\pi}} \frac{1}{x} e^{-\frac{x^2}{2}}$ for $x > 0$.

By Theorem 3.8

$$\sum_{m=1}^{\infty} P(B_m^n) < \infty$$

and hence that $P(A_n) = 0$ by the Borel–Cantelli lemma. Consequently, $P(E) = 0$. Thus,

$$\limsup_{m \rightarrow \infty} \frac{|X_{t+h_m}^H - X_t^H|}{|h_m|^\gamma} = 0 \text{ a.s.}$$

Since the process is separable and the sequence $(h_m)_{m \geq 1}$ was chosen arbitrarily, it follows that $\limsup_{h \rightarrow 0} \frac{|X_{t+h}^H - X_t^H|}{|h|^\gamma} = 0$ and hence

$$\lim_{h \rightarrow 0} \frac{|X_{t+h}^H - X_t^H|}{|h|^\gamma} = 0 \quad \text{for } \gamma < H_t.$$

Now, let $\gamma > H_t$ and $(h_n)_{n \geq 1}$ be a null sequence. Then,

$$\frac{|h_n|^\gamma}{|X_{t+h_n}^H - X_t^H|} \xrightarrow{P} 0 \quad \text{for } n \rightarrow \infty,$$

since for any fixed $\varepsilon > 0$

$$\begin{aligned} P\left(\frac{|h_n|^\gamma}{|X_{t+h_n}^H - X_t^H|} > \varepsilon\right) &= P\left(-\frac{|h_n|^\gamma}{\varepsilon} \leq X_{t+h_n}^H - X_t^H \leq \frac{|h_n|^\gamma}{\varepsilon}\right) \\ &= P\left(-\frac{|h_n|^\gamma}{\varepsilon\sigma_{t,h_n}} \leq Z \leq \frac{|h_n|^\gamma}{\varepsilon\sigma_{t,h_n}}\right) \\ &= 2\Phi\left(\frac{|h_n|^\gamma}{\varepsilon\sigma_{t,h_n}}\right) - 1 \rightarrow 0 \quad \text{for } n \rightarrow \infty \end{aligned}$$

by Theorem 3.8. Consequently, there exists a subsequence $(h_{n_k})_{k \geq 1}$ for which

$$\frac{|h_{n_k}|^\gamma}{|X_{t+h_{n_k}}^H - X_t^H|} \xrightarrow{k \rightarrow \infty} 0 \text{ a.s.}$$

and hence

$$\limsup_{n \rightarrow \infty} \frac{|X_{t+h_n}^H - X_t^H|}{|h_n|^\gamma} \geq \limsup_{k \rightarrow \infty} \frac{|X_{t+h_{n_k}}^H - X_t^H|}{|h_{n_k}|^\gamma} = \infty.$$

□

The next lemma concerns the asymptotic behavior of $R_H(t+h, t)$ for $h \rightarrow \infty$. It will be useful in establishing the long-range dependence property of $fBM_\nu H$.

For two real-valued functions f_1 and f_2 on \mathbb{R} , $f_1 \sim f_2$ will denote that there exist constants $C > c > 0$ such that $0 < c < f_1(h)/f_2(h) < C < \infty$ for all h sufficiently large.

Lemma 3.12 *Let $H : [0, \infty) \rightarrow [a, b] \subset (1/2, 1)$. For any t fixed*

$$\begin{aligned} R_H(t+h, t) &= g_{t,1}(h)h^{2H_{t+h}-1} + \mathbb{1}_{\{H_t=H_{t+h}\}}g_{t,2}(h)[(t+h)^{2H_{t+h}} \\ &\quad - (t+h)h^{2H_{t+h}-1}] + g_{t,3}(h) \end{aligned} \quad (3.1)$$

where $g_{t,1}(h) \sim 1$, $g_{t,2}(h) \sim 1$, and $g_{t,3}(h) \sim 1$ as $h \rightarrow \infty$.

Proof For simplicity, let $\beta^* = \beta(H_{t+h} + H_t - 1, 1 - 2H_{t+h})$. Note that the beta function is defined for non-integer negative arguments by $\beta(a, b) = \frac{\Gamma(a)\Gamma(b)}{\Gamma(a+b)}$, where $\Gamma(\cdot)$ denotes the gamma function. β^* is bounded since $H \in [a, b]$. Applying Lemma 7.1, part (vi), “Appendix 2,” and using that ${}_2F_1(a, b; c; z) = 1$ whenever $a = 0$ or $b = 0$ [see (2.6)]

$$\begin{aligned} &{}_2F_1\left(1, 2H_{t+h}; H_{t+h} + H_t; -\frac{h}{t}\right) \\ &= (H_{t+h} + H_t - 1)\left(\frac{t}{t+h}\right)\left[\frac{{}_2F_1\left(1, H_t - H_{t+h}; 2 - 2H_{t+h}; \frac{t}{t+h}\right)}{2H_{t+h} - 1}\right. \\ &\quad \left.+ \mathbb{1}_{\{H_t \neq H_{t+h}\}}\beta^*\left(\frac{t}{t+h}\right)^{2H_{t+h}-1}\left(\frac{h}{t+h}\right)^{1-H_{t+h}-H_t}\right] \end{aligned} \quad (3.2)$$

and

$$\begin{aligned}
 & {}_2F_1\left(1, H_{t+h} - H_t; H_{t+h} + H_t; -\frac{h}{t}\right) \\
 &= \mathbb{1}_{\{H_t=H_{t+h}\}} + \mathbb{1}_{\{H_t \neq H_{t+h}\}}(H_{t+h} + H_t - 1) \left(\frac{t}{t+h}\right) \\
 &\quad \times \left[\frac{{}_2F_1\left(1, 2H_t; 2 - H_{t+h} + H_t; \frac{t}{t+h}\right)}{H_{t+h} - H_t - 1} \right. \\
 &\quad \left. + \beta_{t,t+h}^2 \left(\frac{t}{t+h}\right)^{H_{t+h}-H_t-1} \left(\frac{h}{t+h}\right)^{1-H_{t+h}-H_t} \right]
 \end{aligned} \quad (3.3)$$

are obtained. Let

$$\begin{aligned}
 f_t(h) &= \frac{{}_2F_1\left(1, H_t - H_{t+h}; 2 - 2H_{t+h}; \frac{t}{t+h}\right)}{2H_{t+h} - 1} \\
 &\quad + \mathbb{1}_{\{H_t \neq H_{t+h}\}} \frac{{}_2F_1\left(1, 2H_t; 2 - H_{t+h} + H_t; \frac{t}{t+h}\right)}{1 + H_t - H_{t+h}}.
 \end{aligned}$$

First, plugging (3.2) and (3.3) into form (2.12) and then regrouping the terms yields

$$\begin{aligned}
 R_H(t+h, t) &= \frac{c_{t+h,t}}{H_t + H_{t+h}} \left[\beta_{t,t+h}^1 t \left(\frac{t+h}{th}\right)^{H_{t+h}-H_t} f_t(h) h^{2H_{t+h}-1} \right. \\
 &\quad + \mathbb{1}_{\{H_t=H_{t+h}\}} \left[\beta_{t,t+h}^1 \beta_{t,t+h}^2 (t+h)^{H_t+H_{t+h}} \right. \\
 &\quad \left. - \frac{\beta_{t,t+h}^1}{H_t + H_{t+h} - 1} (t+h) h^{H_t+H_{t+h}-1} \right] \\
 &\quad \left. + \left[\beta_{t+h,t}^1 \beta_{t+h,t}^2 + \mathbb{1}_{\{H_t \neq H_{t+h}\}} \beta_{t,t+h}^1 \beta^* \right] t^{H_{t+h}+H_t} \right].
 \end{aligned}$$

Noting that $\beta_{t,t}^2 = \frac{1}{2H_t-1}$ and that $\frac{c_{t+h,t}}{H_t+H_{t+h}} \beta_{t,t+h}^1 \beta_{t,t+h}^2 \mathbb{1}_{\{H_t=H_{t+h}\}} = \frac{1}{2} \mathbb{1}_{\{H_t=H_{t+h}\}}$, let

$$\begin{aligned}
 g_{t,1}(h) &= \frac{c_{t+h,t}}{H_{t+h} + H_t} \beta_{t,t+h}^1 t \left(\frac{1}{h} + \frac{1}{t}\right)^{H_{t+h}-H_t} f_t(h), \\
 g_{t,2}(h) &= \frac{1}{2}, \text{ and} \\
 g_{t,3}(h) &= \frac{c_{t+h,t}}{H_{t+h} + H_t} [\beta_{t+h,t}^1 \beta_{t+h,t}^2 + \mathbb{1}_{\{H_t \neq H_{t+h}\}} \beta_{t+h,t}^1 \beta^*] t^{H_{t+h}+H_t},
 \end{aligned}$$

which yields (3.1). It remains to show that $g_{t,i}(h) \sim 1$ for $i = 1, 2, 3$. This is clearly the case for $i = 2$ and $i = 3$, since $a \leq H \leq b$ and all beta functions involved are bounded. For $i = 3$, one approximates

$$\sum_{n=0}^{\infty} \frac{(1)_n}{(2.5)_n} \left(\frac{t}{t+h} \right)^n \leq {}_2F_1 \left(1, 2H_t; 2-H_{t+h}+H_t; \frac{t}{t+h} \right) \leq \sum_{n=0}^{\infty} \frac{(2)_n}{(1.5)_n} \left(\frac{t}{t+h} \right)^n.$$

Both bounds are converging to 1 for $h \rightarrow \infty$ as argued in the proof of Lemma 3.7. Similarly,

$$\begin{aligned} & {}_2F_1 \left(1, H_t - H_{t+h}; 2 - 2H_{t+h}; \frac{t}{t+h} \right) \\ &= 1 + \left(\frac{t}{t+h} \right) \left(\frac{H_t - H_{t+h}}{2 - 2H_{t+h}} \right) \sum_{n=0}^{\infty} \frac{(H_t - H_{t+h} + 1)_n}{(3 - 2H_{t+h})_n} \left(\frac{t}{t+h} \right)^n \rightarrow 1 \end{aligned}$$

for $h \rightarrow \infty$. In the case $\{H_t = H_{t+h}\}$, $f_t(h) = 1/(2H_t - 1)$. Hence, $f_t(h) \sim 1$ and $g_{t,1}(h) \sim 1$, $g_{t,2}(h) \sim 1$ and $g_{t,3}(h) \sim 1$ for any fixed t . \square

Remark 3.13 For constant H , the proof of Lemma 3.12 yields the covariance function of fBM .

3.4 Long-Range Dependence

$fBM \vee H$ retains the long-range dependence property, which makes fBM with $H > 1/2$ an attractive model in situations where the dependence on past events decays slowly in time.

There are several ways to define long-range dependence mathematically. All of them refer to slowly decaying correlations in some way (see, e.g., [4]). For a second-order process X , let $\text{Cor}_X(t, s)$ denote the correlation of X_t and X_s . In the next proposition, it will be shown that $\text{Cor}_{X^H}(t+h, t)$ decays not faster than h^{-1} for $h \rightarrow \infty$ and the definition of long-range dependence used here will be the following:

Definition 3.14 A second-order process X is said to have long-range dependence if

$$\sum_{k=0}^{\infty} |\text{Cor}_X(t + \delta k, t)| = \infty \quad \text{for all } t > 0 \text{ and } \delta > 0.$$

Remark 3.15 The correlation rather than the covariance is used in this definition. For non-stationary processes, the correlation and covariance of increments are not multiples of each other and while the sum of the covariances may diverge, the correlation can still be decreasing fast enough in time.

Proposition 3.16 Let $H : [0, \infty) \rightarrow [a, b] \subset (1/2, 1)$. Then, X^H has long-range dependence.

Proof Taylor expansions yield

$$\begin{aligned} h^{2H_{t+h}-1} &= (t+h)^{2H_{t+h}-1} + o(1) \text{ for } h \rightarrow \infty \text{ and} \\ h^{2H_{t+h}} &= (t+h)^{2H_{t+h}} - 2H_{t+h}t(t+h)^{2H_{t+h}-1} + o(1) \text{ for } h \rightarrow \infty. \end{aligned}$$

By Lemma 3.12, it follows that

$$\begin{aligned} R_H(t+h, t) &= [g_{t,1}(h) + \mathbb{1}_{\{H_t=H_{t+h}\}}g_{t,2}(h)t(2H_{t+h}-1)](t+h)^{2H_{t+h}-1} \\ &\quad + g_{t,3}(h) + o(1) \\ &\sim (t+h)^{2H_{t+h}-1} \text{ for } h \rightarrow \infty. \end{aligned}$$

Hence, $\text{Cor}_{X^H}(t+h, t) \sim (t+h)^{H_{t+h}-1}$ and it follows that

$$\sum_{k=0}^{\infty} |\text{Cor}_{X^H}(t+\delta k, t)| \geq c \sum_{k=0}^{\infty} (t+\delta k)^{-1/2} = \infty \quad \text{for all } t > 0 \text{ and } \delta > 0$$

for some constant $c > 0$. □

Remark 3.17 $\text{Cor}_{X^H}(t+h, t) \sim (t+h)^{H_{t+h}-1}$ implies that for each starting point t , the correlation structure evolves differently.

4 A Fokker–Planck Equation for Time-changed $fBM_{\nu}H$

This section establishes a Fokker–Planck equation (FPE) for the densities of a time-changed $fBM_{\nu}H$ under the differentiability assumption on the parameter function H . The time-change process is the inverse of a stable subordinator, which yields a fractional derivative in the FPE. FPEs involving time-fractional derivatives are used as a powerful tool in the study and modeling of anomalous diffusion processes (see for example [6, 18, 25, 32]).

A stable subordinator W^α with index α is a nonnegative and strictly increasing Lévy process starting at 0 and exhibiting the self-similarity property $W_{ct}^\alpha \sim c^{1/\alpha} W_t^\alpha$ for all $t > 0$ and any $c > 0$ in the sense of finite dimensional distributions [3]. The inverse of a stable subordinator W^α is defined by $E_t^\alpha = \inf\{s : W_s^\alpha > t\}$ for $t \geq 0$. Since W^α is strictly increasing, E^α is non-decreasing and continuous and hence a suitable time-change process [24].

The Caputo–Djrbashian fractional-order derivative D_t^α of order $\alpha \in (0, 1)$ is given by

$$D_t^\alpha g(t) = \frac{1}{\Gamma(1-\alpha)} \int_0^t \frac{g'(\tau)}{(t-\tau)^\alpha} d\tau.$$

By convention, $D_t^1 = \frac{d}{dt}$. The fractional integration operator of order $\alpha > 0$ is defined via

$$J_t^\alpha g(t) = \frac{1}{\Gamma(\alpha)} \int_0^t g(\tau)(t-\tau)^{\alpha-1} d\tau.$$

The relationship between the above three operators is given by $D_t^\alpha = J_t^{1-\alpha} \circ \frac{d}{dt}$ (for details, see [16]).

The following theorem is an adaptation of Proposition 1 in [17] to the specific setting of $fBMvH$.

Theorem 4.1 *Let X^H be a $fBMvH$ with differentiable Hurst parameter function H . The transition probabilities $p(t, x)$ of X^H satisfy*

$$\partial_t p(t, x) = \left(H'_t \ln(t) + \frac{H_t}{t} \right) t^{2H_t} \partial_x^2 p(t, x), \quad t > 0, \quad x \in \mathbb{R}.$$

If H is differentiable, then $\text{Var}(X_t^H) = t^{2H_t}$ is differentiable as well. t^{2H_t} is Laplace transformable, since $t^{2H_t} \leq t \vee t^2$. Thus, the conditions of Theorem 3 in [17] are satisfied and the following theorem is obtained.

Let \tilde{g} denote the $(t \rightarrow s)$ -Laplace transform of a function $g = g(t)$ and let $\mathcal{L}_{s \rightarrow t}^{-1}$ denote the inverse Laplace transform.

Theorem 4.2 *Let X^H be a $fBMvH$ with H differentiable on $(0, \infty)$. Further, let E^α be the inverse of a stable subordinator W^α of index $\alpha \in (0, 1)$, independent of X^H . Then, the transition probabilities $q(t, x)$ of the time-changed process $(X_{E_t^\alpha}^H)_{t \geq 0}$ satisfy the equivalent PDEs*

$$D_t^\alpha q(t, x) = J_t^{1-\alpha} \Lambda_{X^H, t}^\alpha \partial_x^2 q(t, x), \quad t > 0, \quad x \in \mathbb{R}$$

and

$$\partial_t q(t, x) = \Lambda_{X^H, t}^\alpha \partial_x^2 q(t, x), \quad t > 0, \quad x \in \mathbb{R},$$

where $\Lambda_{X^H, t}^\alpha$ is the operator acting on t given by

$$\Lambda_{X^H, t}^\alpha g(t) = \frac{\alpha}{2} \mathcal{L}_{s \rightarrow t}^{-1} \left[\frac{1}{2\pi i} \int_{\mathcal{C}} (s^\alpha - z^\alpha) \tilde{R}_H(s^\alpha - z^\alpha) \tilde{g}(z) \, dz \right] (t),$$

with initial condition $q(0, x) = \delta_0(x)$.

For further details on the operator $\Lambda_{X^H, t}^\alpha$, see [17].

Remark 4.3 The proof uses the fact that given the independence of X^H and E^α , the relationship between the transition probabilities $p(\tau, x)$ for $\tau > 0$, $x \in \mathbb{R}$ of the process and the transition probabilities of the time-changed version is given by $q(t, x) = \int_0^\infty f_{E_t^\alpha}(\tau) p(\tau, x) \, d\tau$, $t > 0$, with $f_{E_t^\alpha}$ denoting the density function of E_t^α . The time change yields the occurrence of the fractional-order derivative.

Remark 4.4 The choice of the time-change process can be extended to the inverse of an arbitrary mixture of independent stable subordinators (see [17]).

5 Modeling

The plots in this section were generated using the Cholesky decomposition of the covariance matrix. For that, let $t_1, \dots, t_n \in [0, T]$ for some $T > 0$. By Theorem 2.2, the covariance matrix Σ of the vector $(X_{t_1}^H, \dots, X_{t_n}^H)$ is positive definite and can hence be decomposed as

$$\Sigma = LL^T,$$

where L is a lower triangular matrix. Let $Y = (Y_1, \dots, Y_n)$ be a standard normal vector with the identity matrix as the covariance matrix. Then, LY has Σ as covariance matrix, since

$$\text{Cov}(LY) = E[LY(LY)^T] = LE[YY^T]L^T = LL^T = \Sigma.$$

Hence, LY is a sample path of a $fBMvH$ with parameter function H and at the times t_1, \dots, t_n .

Using the Cholesky decomposition in order to obtain a sample path of a Gaussian process generates an exact sample path of the process in question. The disadvantage of such an algorithm is the long computational time needed to compute the $n \times n$ covariance matrix and the Cholesky factorisation matrix L . For applications, an algorithm based on the convergence of fBM s with indices $H_n \rightarrow H_t$ such as in [26] would be preferable in practice, even though it would not generate an exact sample path.

5.1 Plots

The following are exact sample paths of $fBMvH$ with various parameter functions $H(\cdot)$ (Figs. 1, 2, 3, 4, 5).

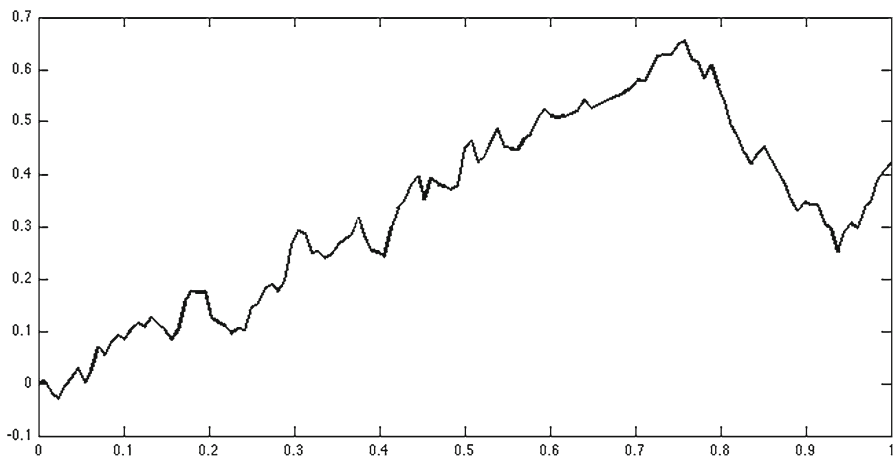


Fig. 1 This is the usual fBM with constant Hurst parameter $H = .75$

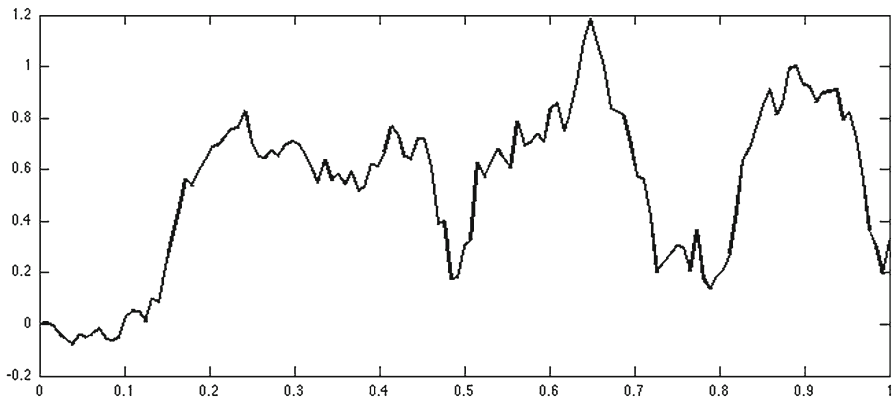


Fig. 2 $H(t) = .51 + (t - .5)^2$ for $t < .5$ and $H(t) = .51$ for $t \geq .5$. The Hurst parameter approaches .51 as $t \rightarrow 1/2$

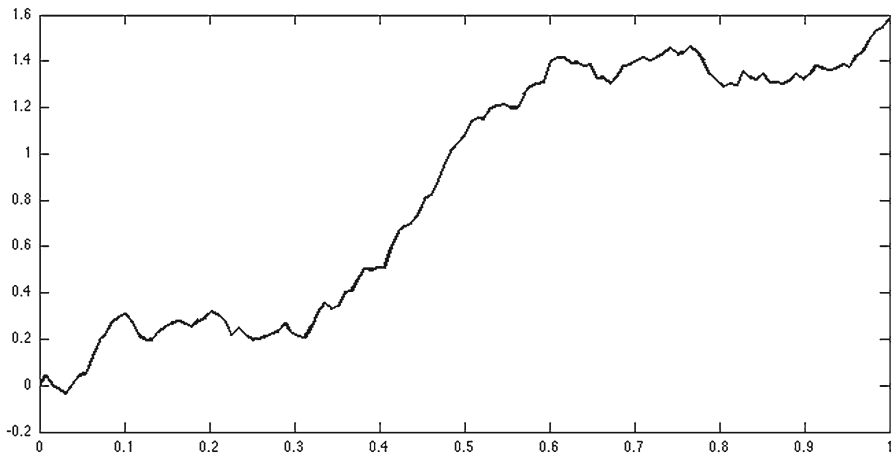


Fig. 3 $H(t) = \frac{2}{3} + \frac{\sin(t)}{12}$. The Hurst parameter oscillates between $7/12$ and $9/12$

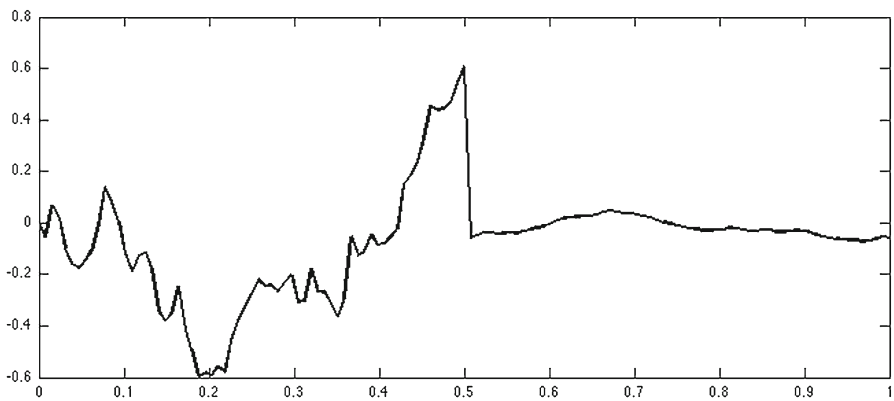


Fig. 4 $H(t) = .55$ for $t \leq .5$ and $H(t) = .95$ for $t > .5$. The Hurst parameter jumps at .5

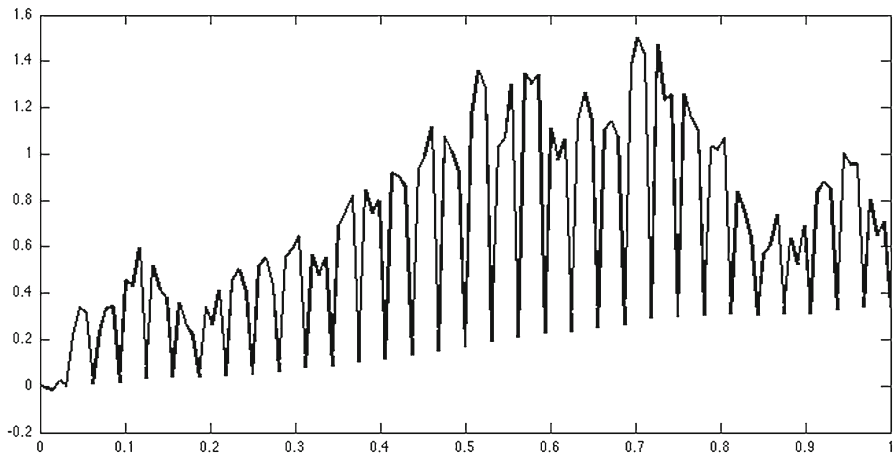


Fig. 5 The Hurst parameter jumps periodically: $H(t) = .99$ if $128t \bmod 4 = 0$ and $H(t) = .51$ else

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6 Appendix 1

Lemma 6.1 Let $\alpha < 2$, $\gamma > 1/2$, $\delta > 1/2$ and $I = \int_0^a u^{1-\alpha} (b-u)^{\gamma-\frac{3}{2}} (a-u)^{\delta-\frac{3}{2}} du$, then

(i)

$$I = (b-a)^{\gamma+\delta-2} \int_{\frac{b}{a}}^{\infty} (x-1)^{\alpha-\delta-\gamma} x^{\gamma-\frac{3}{2}} (ax-b)^{1-\alpha} dx.$$

(ii) If additionally $\alpha = \gamma + \delta$, then

$$I = (b-a)^{\alpha-2} \int_{\frac{b}{a}}^{\infty} x^{\gamma-\frac{3}{2}} (ax-b)^{1-\alpha} dx = (b-a)^{\alpha-2} b^{\frac{1}{2}-\delta} a^{\frac{1}{2}-\gamma} \beta(\delta-1/2, 2-\alpha).$$

(iii) If $\alpha, \gamma \in (-1, 1)$ arbitrary, $0 < a < b$ and $J = \int_a^b y^{-\alpha} \int_0^a z^{\alpha} (y-z)^{-\gamma} dz dy$, then

$$J = \frac{a^{2-\gamma}}{2-\gamma} \int_{\frac{a}{b}}^1 v^{\alpha+\gamma-2} (1-v)^{-\gamma} dv$$

$$+ \frac{b^{2-\gamma}}{2-\gamma} \int_0^{\frac{a}{b}} v^\alpha (1-v)^{-\gamma} dv - \frac{a^{2-\gamma}}{2-\gamma} \beta(\alpha+1, 1-\gamma).$$

Proof Part (i) is obtained via substituting $x = \frac{u-b}{u-a}$. Part (ii) follows by substituting $y = \frac{b}{ax}$. For (iii) $z = yv$ is substituted and it follows that

$$\begin{aligned} J &= \int_a^b y^{1-\gamma} \int_0^{\frac{a}{y}} v^\alpha (1-v)^{-\gamma} dv dy \\ &= \int_{\frac{a}{b}}^1 v^\alpha (1-v)^{-\gamma} \int_{\frac{a}{v}}^{\frac{a}{b}} y^{1-\gamma} dy dv + \int_0^{\frac{a}{b}} v^\alpha (1-v)^{-\gamma} \int_a^b y^{1-\gamma} dy dv \\ &= \frac{a^{2-\gamma}}{2-\gamma} \int_{\frac{a}{b}}^1 v^{\alpha+\gamma-2} (1-v)^{-\gamma} dv + \frac{b^{2-\gamma}}{2-\gamma} \int_0^{\frac{a}{b}} v^\alpha (1-v)^{-\gamma} dv \\ &\quad - \frac{a^{2-\gamma}}{2-\gamma} \beta(\alpha+1, 1-\gamma). \end{aligned}$$

□

7 Appendix 2

Formulas (i)–(iv) below can be found in *The Handbook of mathematical functions*, p. 559 by Abramowitz and Stegun [1]. Formula (v) is from the *Integrals and Series* handbook by Prudnikov et al. [28].

Lemma 7.1 Let a, b, c be real numbers and $z \in \mathbb{C}$.

(i) For $|\arg(z)|, |\arg(1-z)| < \pi$ and when all terms are defined,

$$\begin{aligned} {}_2F_1(a, b; c; z) &= \frac{\Gamma(c)\Gamma(c-a-b)}{\Gamma(c-a)\Gamma(c-b)} z^{-a} {}_2F_1\left(a, a-c+1; a+b-c+1; 1-\frac{1}{z}\right) \\ &\quad + \frac{\Gamma(c)\Gamma(a+b-c)}{\Gamma(a)\Gamma(b)} (1-z)^{c-a-b} z^{a-c} {}_2F_1\left(c-a, 1-a; c-a-b+1; 1-\frac{1}{z}\right). \end{aligned}$$

(ii) If $(1-z)^{-a}$ is defined,

$${}_2F_1(a, b; c; z) = (1-z)^{-a} {}_2F_1\left(a, c-b; c; \frac{z}{z-1}\right).$$

(iii) For $|\arg(1-z)| < \pi$ and when all terms are defined,

$$\begin{aligned} {}_2F_1(a, b; c; z) &= \frac{\Gamma(c)\Gamma(c-a-b)}{\Gamma(c-a)\Gamma(c-b)} {}_2F_1(a, b; a+b-c+1; 1-z) \\ &\quad + \frac{\Gamma(c)\Gamma(a+b-c)}{\Gamma(a)\Gamma(b)} (1-z)^{c-a-b} {}_2F_1(c-a, c-b; c-a-b+1; 1-z). \end{aligned}$$

(iv) If $(1-z)^{c-a-b}$ is defined,

$${}_2F_1(a, b; c; z) = (1-z)^{c-a-b} {}_2F_1(c-a, c-b; c; z).$$

(v)

$$\begin{aligned} &\int_a^b (x-a)^{\alpha-1} (b-x)^{\delta-1} (cx+d)^\gamma dx \\ &= \beta(\alpha, \delta)(b-a)^{\alpha+\delta-1} (ac+d)^\gamma {}_2F_1\left(\alpha, -\gamma; \alpha+\delta; \frac{c(a-b)}{ac+d}\right) \end{aligned}$$

if $\operatorname{Re}(\alpha) > 0$, $\operatorname{Re}(\delta) > 0$ and $|\arg((d+cb)/(d+ca))| < \pi$.

(vi) Under the assumptions of (ii), (iii), and (iv)

$$\begin{aligned} {}_2F_1(a, b; c; z) &= \mathbb{1}_{\{a=0 \vee b=0\}} \\ &\quad + \mathbb{1}_{\{a \neq 0 \wedge b \neq 0\}} (1-z)^{-a} \left[\frac{\Gamma(c)\Gamma(b-a)}{\Gamma(c-a)\Gamma(b)} {}_2F_1\left(a, c-b; a-b+1; \frac{1}{1-z}\right) \right. \\ &\quad \left. + \frac{\Gamma(c)\Gamma(a-b)}{\Gamma(a)\Gamma(c-b)} \left(\frac{z}{z-1}\right)^{1-c} \left(\frac{1}{1-z}\right)^{b-a} {}_2F_1\left(b-c+1, 1-a; b-a+1; \frac{1}{1-z}\right) \right]. \end{aligned}$$

Proof Part (vi): The equality is obtained by consecutively applying parts (ii) and (iii) of the Lemma to ${}_2F_1(a, b; c; z)$ and then applying part (iv) to the second term of what was obtained in the first two steps. The indicator functions make up for the case that $a = 0$ or $b = 0$, i.e., when (iii) cannot be applied. \square

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