

Introduction to Computational and Biological Vision - Assignment 2

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Question 1 - Edge Detection

Section A

Given $I(x, y) = x + \sin y$

And the following Edge Detectors:

E_1 = edge detector based on the local maximum of $|\nabla I|$

E_2 = Edge detector based on finding the ZC of the Laplacian ΔI

Compute analytically the edge points detected by each of the edge detectors:

For E_1 :

first eval $|\nabla I|$:

$$|\nabla I| = \left(\frac{\partial I}{\partial x}, \frac{\partial I}{\partial y} \right) = \|(1, \cos y)\| = \sqrt{1^2 + \cos^2(y)}$$

we got an expression that independent of x , so we will assume that any x will work, and find the extramum for y :

$$\begin{aligned} \frac{\partial}{\partial y} |\nabla I| &= \frac{\partial}{\partial y} \left(\sqrt{1^2 + \cos^2(y)} \right) = -\frac{\sin(2y)}{2\sqrt{1 + \cos^2(y)}} \\ \frac{\partial}{\partial y} |\nabla I| &= 0 \\ -\frac{\sin(2y)}{2\sqrt{1 + \cos^2(y)}} &= 0 \\ \sin(2y) &= 0 \\ y &= \frac{\pi}{2} + \pi k, \pi k, \forall k \in \mathbb{N} \end{aligned}$$

and now for the second derviative:

$$\begin{aligned} \frac{\partial^2}{\partial y^2} |\nabla I| &= -\frac{4 \cos(2y) (1 + \cos^2(y)) + \sin^2(2y)}{4 (1 + \cos^2(y)) \sqrt{1 + \cos^2(y)}} \\ \left(\frac{\partial^2}{\partial y^2} |\nabla I| \right)_{y=\frac{\pi}{2}} &= -\frac{4 \cos(2(\frac{\pi}{2})) (1 + \cos^2(\frac{\pi}{2})) + \sin^2(2(\frac{\pi}{2}))}{4 (1 + \cos^2(\frac{\pi}{2})) \sqrt{1 + \cos^2(\frac{\pi}{2})}} \\ &= -\frac{4 \cos(\pi) (1 + \cos^2(\frac{\pi}{2})) + \sin^2(\pi)}{4 (1 + \cos^2(\frac{\pi}{2})) \sqrt{1 + \cos^2(\frac{\pi}{2})}} \\ &= 1 \\ \left(\frac{\partial^2}{\partial y^2} |\nabla I| \right)_{y=\pi} &= -\frac{4 \cos(2(\pi)) (1 + \cos^2(\pi)) + \sin^2(2(\pi))}{4 (1 + \cos^2(\pi)) \sqrt{1 + \cos^2(\pi)}} \\ &= -\frac{\sqrt{2}}{2} \end{aligned}$$

for the first assignment of y we got positive value, so its not an extramum point.

so we got that $(x, \pi k) \quad \forall k \in \mathbb{N}$ is our extramum points.
for E_2 :
lets calc the laplacian:

$$\begin{aligned}\Delta I &= \frac{\partial^2 I}{\partial x^2} + \frac{\partial^2 I}{\partial y^2} \\ &= \frac{\partial^2}{\partial x^2} (x + \sin y) + \frac{\partial^2}{\partial y^2} (x + \sin y) \\ &= \frac{\partial}{\partial x} (1) + \frac{\partial}{\partial y} (\cos(y)) \\ &= 0 - \sin(y) \\ &= \sin(y)\end{aligned}$$

lets find all the points where $\Delta I = 0$:

$$\begin{aligned}\Delta I &= 0 \\ \sin(y) &= 0 \\ y &= \pi k \quad \forall k \in \mathbb{N}\end{aligned}$$

so our edge points according to E_2 are: $(x, \pi k) \quad \forall k \in \mathbb{N}$.
The result are identical, but its clearly that the computations of E_2 are much more simpler.

Question 2 – Parametric Curves

Section A

The parametric equation of a straight line in 3D is $a(t) = (x(t), y(t), z(t))$.

The parametric equation of a straight line in 2D is $a_{2d}(t) = (x(t), y(t))$.

Without loss of generality, we assume that the center of projection is at the origin. Upon projection onto the plane $z = f$, the image of the point (x_0, y_0, z_0) is:

$$x_i = \frac{f}{z(t)} * x(t)$$

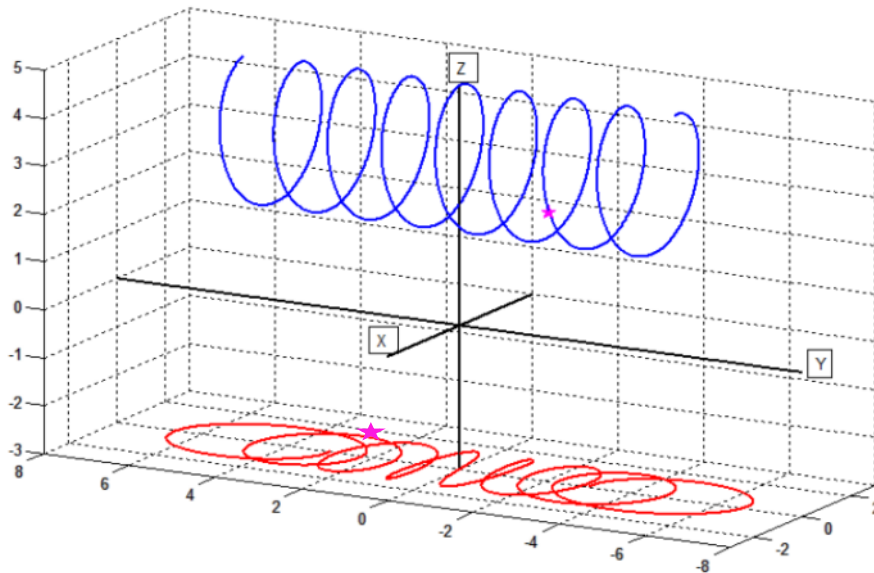
$$y_i = \frac{f}{z(t)} * y(t)$$

Dividing $\frac{x_i}{y_i}$ we get:

$$\frac{f * x(t)}{z(t)} * \frac{z(t)}{f * y(t)} = \frac{x(t)}{y(t)}$$

And we know that $a(t)$ is a straight line in 3D, so for every t , $\frac{x(t)}{y(t)} = m$ for some constant m which is the slope of $a(t)$. **So, the projection also has a constant slope, hence it is a straight line.**

Section B



1. The projection of the star is marked on the image plane as a pink star.
2. First, we have that:

$$\begin{aligned} a(0) &= (0, 0, 5), \\ a(-8\pi) &= \left(0, -\frac{8\pi}{5}, 5\right) \\ Z_{min} &= 2, Z_{max} = 5 \end{aligned}$$

We can see that this trace is created by a circle which is continuously moved along the y axis, so the x and z coordinates will be some variation of cos and sin of some expression. We have

$$a(-8\pi) = \left(0, -\frac{8\pi}{5}, 5\right)$$

And so we know that when $s = -8\pi$, then $x = 0$.

We also know that when $s = 0$, then, $x = 0$. In order to get 8 full circles in the span of 16π , we have to have the expression $\cos(s)$ and in order to adjust for the starting and 0 points, we add $\frac{\pi}{2}$ to the angle, leaving us with $\cos(s + \frac{\pi}{2})$. The final adjustment is for the radius which is 1.5 (we have $Z_{min} = 2, Z_{max} = 5$), and so we get:

$$x = 1.5\cos(s + \frac{\pi}{2}).$$

Y changes constantly and ranges from $-\frac{8\pi}{5}$ to $\frac{8\pi}{5}$, so we get:

$$y = \frac{s}{5}.$$

The definition of z comes similarly to x ; the only difference is that the circle radius is at a distance of 3.5 from the XY plane, because $Z_{min} = 2, Z_{max} = 5$, and so we get:
 $z = 3.5 + 1.5\sin(s + \frac{\pi}{2})$.

3. $\hat{o}(s)$ is the perspective projection of $\alpha(s)$, so for every point p we will define its projected point $p_i = \left(\frac{p_x * f}{p_z}, \frac{p_y * f}{p_z} \right)$, so we substitute the terms and get:

$$p_i = \left(\frac{6\cos(s + \frac{\pi}{2})}{3.5 + 1.5\sin(s + \frac{\pi}{2})}, \frac{3s}{3.5 + 1.5\sin(s + \frac{\pi}{2})} \right)$$