Brahma S. Payse

CONTACT Information Email: pavse@wisc.edu

Webpage: https://brahmasp.github.io

Google Scholar: https://scholar.google.com/citations?user=2Dc_GnUAAAAJ&hl

EDUCATION

University of Wisconsin - Madison (01/2022 - present)

- Ph.D. in Computer Science.
- Interests: reinforcement learning, representation learning, hierarchical RL.
- Advisor: Josiah P. Hanna.
- Cisco Systems Distinguished Graduate Fellow.

University of Texas at Austin (2015 - 2020)

- B.S and M.S. in Computer Science.
- Advisor: Peter Stone.

ACADEMIC RESEARCH EXPERIENCE

University of Wisconsin - Madison, Madison, WI, USA

Research Assistant and Cisco Systems Distinguished Fellow Spring 2022 -

- Currently investigating how to learn effective state representations for planning in hierarchical reinforcement learning agents that learn from raw sensorimotor experience.
- Developed novel algorithms to improve the quality of representations for dataefficient and accurate evaluation of untested reinforcement learning agents.
- Developed techniques to improve robustness of reinforcement learning agents in queuing network problems with exogenous stochasticity and unbounded state spaces.
- Mentored three undergraduate students.

University of Texas at Austin, Austin, TX, USA

Research Assistant

August 2018 - August 2020

- Developed algorithms to accurately and data-efficiently evaluate untested reinforcement learning agents.
- Developed an imitation from observation and reinforcement learning algorithm to speed up sample efficiency on a real robot.

INDUSTRY
RESEARCH
EXPERIENCE

Netflix Research, Los Gatos, CA, USA

Machine Learning Research Intern — Recommendations team Summer 2025

- Mentor: Qitong Gao. Collaborator: Adith Swaminathan.
- Developed the first RL-based system for personalizing images of titles at Netflix.
- Implemented the data and training pipeline to train and evaluate offline RL algorithms such as SARSA and conservative Q-learning.
- Achieved comparable performance to a decade-old bandit system on short-term metrics and captured long-term return better than the bandit model by 33%.
- Currently undergoing A/B test evaluations.

Sony AI America, Remote, USA

AI Research Intern — Reinforcement learning team

Summer 2023

• Mentor: Varun Kompella.

Brahma S. Pavse: Curriculum Vitae Last Updated: 16 October 2025

- Leveraged value iteration networks to improve the quality of representations learned to speedup sample efficiency of an RL agent.
- Simulation results showed improvements in data-efficiency over baseline agent.

Industry Engineering Experience

Salesforce.com, San Francisco, CA, USA

Software Engineer — Database Optimization team Aug. 2020 - Jan. 2022

Salesforce.com, San Francisco, CA, USA

Software Engineering Intern — Database Optimization team Summer 2019, 2018, 2017

SAS Institute, Cary, NC, USA

Software Engineering Intern — Data Management team Summer 2016

AWARDS AND HONORS

- Cisco Systems Distinguished Graduate Fellowship (2025).
- NeurIPS Top Reviewer Award (Top 8%) (2025, 2024, 2023).
- AAAI Student Scholarship (2023).
- UW Madison CS Summer Research Fellowship Award (2022).
- UW Madison CS Graduate Scholarship (2022).
- UT Austin CS Special Departmental Honors (Research) (2020).
- Eva Stevenson Woods Endowed Presidential Scholarship (2019).
- National Instruments Endowed Scholarship (2019).
- RoboCup 3D Simulation League World Champions (2019, 2018).

Publications (*= contribution)

Peer-reviewed Conference Papers

- Brahma S. Pavse, Yudong Chen, Qiaomin Xie, and Josiah P. Hanna. Stable Offline Value Function Learning with Bisimulation-based Representations. International Conference on Machine Learning (ICML), July 2025. Acceptance rate: 26.9%. [PDF].
- Brahma S. Pavse, Matthew Zurek, Yudong Chen, Qiaomin Xie, and Josiah P. Hanna. Learning to Stabilize Online Reinforcement Learning in Unbounded State Spaces. International Conference on Machine Learning (ICML), July 2024. Acceptance rate: 27.5%. [PDF].
- 4. **Brahma S. Pavse** and Josiah P. Hanna. State-Action Similarity-Based Representations for Off-Policy Evaluation. Neural Information Processing Systems (NeurIPS), December 2023. Acceptance rate: 26.1%. [PDF].
- 3. Brahma S. Pavse and Josiah P. Hanna. Scaling Marginalized Importance Sampling to High-Dimensional State-Spaces via State Abstraction. Association for the Advancement of Artificial Intelligence (AAAI), February 2023. Acceptance rate: 19.6%. Selected for oral presentation. [PDF].
- 2. Brahma S. Pavse*, Faraz Torabi*, Josiah P. Hanna, Garrett Warnell, Peter Stone. RIDM: Reinforced Inverse Dynamics Modeling for Learning From a Single Observed Demonstration. IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), October 2020. Acceptance rate: 47%. 2nd place in the RoboCup 3D Sim Scientific Challenge 2019. [PDF].
- Brahma S. Pavse, Ishan Durugkar, Josiah P. Hanna, and Peter Stone. Reducing Sampling Error in Batch Temporal Difference Learning. International Conference on Machine Learning (ICML), July 2020. Acceptance rate: 21.8%. [PDF].

Journal Articles

Brahma S. Pavse*, Faraz Torabi*, Josiah P. Hanna, Garrett Warnell, Peter Stone. RIDM: Reinforced Inverse Dynamics Modeling for Learning From a Single Observed Demonstration. IEEE Robotics and Automation Letters, July 2020.
 2nd place in the RoboCup 3D Sim Scientific Challenge 2019.

Peer-reviewed Workshop Papers

- Josiah P. Hanna, Brahma S. Pavse, and Abhinav Narayan Harish. Replacing Implicit Regression with Classification in Policy Gradient Reinforcement Learning. Workshop on Finding the Frame: An RLC Workshop for Examining Conceptual Frameworks, Reinforcement Learning Conference (RLC), August 2024.
- Brahma S. Pavse and Josiah P. Hanna. Scaling Marginalized Importance Sampling to High-Dimensional State-Spaces via State Abstraction. Workshop on Offline Reinforcement Learning, Neural Information Processing Systems (NeurIPS), December 2022.
- Brahma S. Pavse, Josiah P. Hanna, Ishan Durugkar, and Peter Stone. On Sampling Error in Batch Action-Value Prediction Algorithms. Workshop on Offline Reinforcement Learning, Neural Information Processing Systems (NeurIPS), December 2020.

Book Chapters

- Patrick MacAlpine, Faraz Torabi, Brahma Pavse, and Peter Stone. UT Austin Villa: RoboCup 2019 3D Simulation League Competition and Technical Challenge Champions. In RoboCup 2019: Robot World Cup XXIII, Lecture Notes in Artificial Intelligence, Springer, 2019.
- Patrick MacAlpine, Faraz Torabi, Brahma Pavse, John Sigmon, and Peter Stone. UT Austin Villa: RoboCup 2018 3D Simulation League Champions. In RoboCup 2018: Robot Soccer World Cup XXII, Lecture Notes in Artificial Intelligence, Springer, 2019.

TEACHING EXPERIENCE

University of Wisconsin – Madison, Madison, WI, USA

Teaching Assistant — Introduction to Artificial Intelligence

Fall 2024

University of Texas at Austin, Austin, TX, USA

Teaching Assistant — Data Structures — Rating: 4.5/5.0

Fall 2016

SERVICE

- Officer, Research to Impact at UW-Madison (2025).
- Coordinator, UW-Madison Reinforcement Learning Reading Group (2022-2025).
- Graduate Student Mentor, Wisconsin Science and Computing Emerging Research Stars [WISCERS] (2025, 2022).
- Reviewer, UT Austin Computer Science Dept. MS Admissions Committee (2020).

REVIEWING

- Reinforcement Learning Conference (RLC) 2025, 2024.
- International Conference on Machine Learning (ICML) 2023-2025.
- International Conference on Learning Representations (ICLR) 2025, 2023, 2022.
- Neural Information Processing Systems (NeurIPS) 2022-2025.

- RLC Finding the Frame: An RLC Workshop for Examining Conceptual Frameworks 2024
- NeurIPS Goal-Conditioned Reinforcement Learning Workshop 2023.
- Association for the Advancement of Artificial Intelligence (AAAI) 2023.
- International Conference on Robotics and Automation (ICRA) 2021.

Mentoring

UW Madison Undergraduates

- Stuti Pandey (2024-)
- Lucas Poon (2024). Next: CS PhD student at Oregon State University.
- Adhit Sankaran (2022 2023). Next: MS in CS at Cornell University.

INVITED TALKS

- Netflix Machine Learning and Inference seminar. July 2025.
- UW-Madison Systems, Information, Learning, Optimization (SILO) seminar. November 2024.
- UT Austin Reinforcement Learning Reading Group. April 2024.
- EdIntelligence at The University of Edinburgh. July 2020.

TECHNICAL SKILLS

- Languages: Python, Java, C++, Matlab
- Robotics simulators: MuJoCo
- Frameworks/Libraries/Tools: HTC Condor, PyTorch, OpenAI Gym, Pandas

Personal Details

• Citizenship: USA