Introduction to Deep Learning and Transfer Learning



Input/output

- Goal: infer a function from an input (often tensor) space to an output (often tensor) space, $\mathbf{y} = f(\mathbf{x})$,
- **Example:** input can be an image, output a vector where the largest value indicate the category the image belongs to.

Error/Loss

- Loss L: nonnegative measure of the discrepancy between expected output ŷ and obtained output y.
- **Example:** output should be [0, 1] but is [0.2, 0.8].

Parameters

- $f = f_w$ contains **parameters W** to be trained,
- In most cases, an ideal f_w exists but is hard to find in practice,
- Learning is a regression ill-posed problem.

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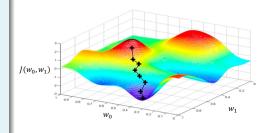
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- Loss: $J(\mathbf{W}) = \sum_{i} \mathcal{L}(f(\mathbf{x}^{(i)}, \mathbf{W}), \mathbf{y}^{(i)}), i = \text{examples}$
- Model parameters: $\mathbf{W}^* = argmin(J(\mathbf{W}))$

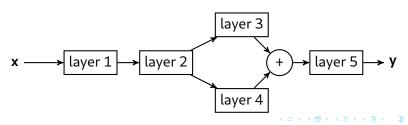
Training Algorithm

- Randomly Initialize model weights
- Compute Gradient of the Loss $\frac{\partial J(\mathbf{W})}{\partial \mathbf{W}}$
- Update weights $\mathbf{W} \leftarrow \mathbf{W} \eta \frac{\partial J(\mathbf{W})}{\partial \mathbf{W}}$
- Repeat until convergence

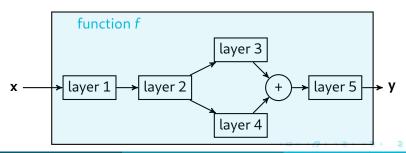


from MIT course introtodeeplearning.com

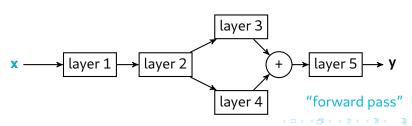
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- End-to-end learning: Tune all atomic functions together
- Training: Backpropagate throughout the architecture (to compute the gradient of the loss wrt all layers parameters)



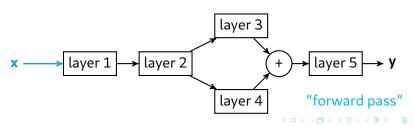
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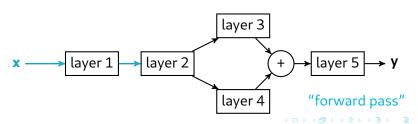
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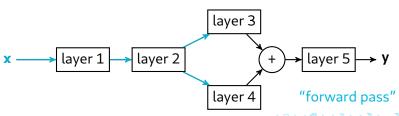
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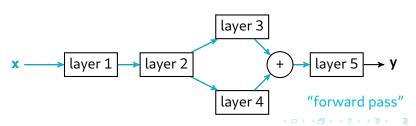
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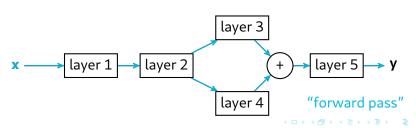
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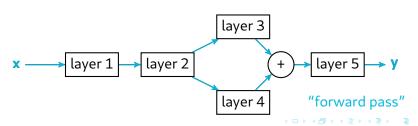
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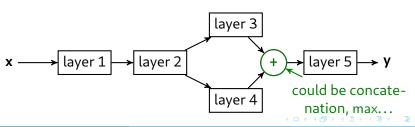
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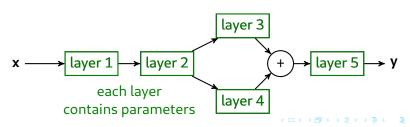
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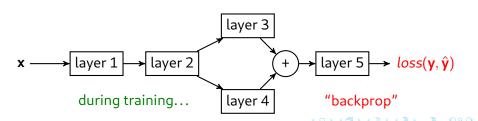
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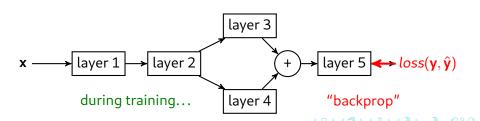
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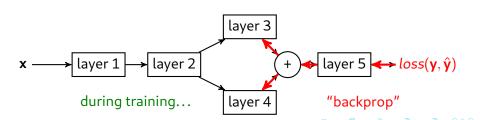
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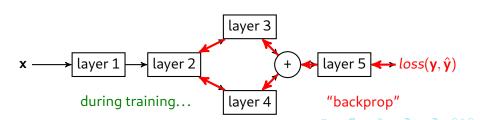
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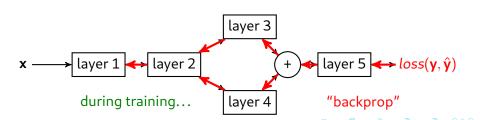
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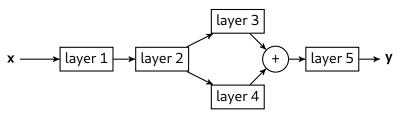


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Main idea

- Compositional Approach: Instead of directly mapping x to y, express solutions as an assembly of simple mathematical functions called layers
- End-to-end learning: Tune all atomic functions together
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Number of layers, choice of the architecture are hyperparameters

Layers

- $\mathbf{x} \mapsto h(\mathbf{W}\mathbf{x} + \mathbf{b}).$
 - h is a nonlinear parameterwise function (often without parameters)
 - W is a tensor:
 - Can be agnostic of the structure: fully-connected layers,Can be structure-dependent: convolutional layers.

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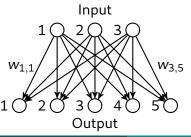
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Fully connected layer

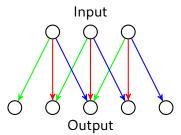


$$W_{3,1}$$
 $W_{3,2}$ $W_{3,3}$ $W_{3,4}$ $W_{3,5}$

Layers

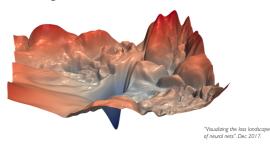
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Convolutional layer



$$\begin{pmatrix} \begin{pmatrix} w_{10} & w_{2} & w_{3} & w_{5} & 0 & 0 & 0 \\ w_{10} & w_{2} & w_{3} & 0 & 0 & 0 & 0 \\ 0 & w_{10} & w_{2} & w_{3} & 0 & w_{6} & 0 & 0 \\ 0 & 0 & w_{1} & w_{2} & w_{3} & 0 & w_{6} & 0 & 0 \\ 0 & 0 & w_{1} & w_{2} & w_{3} & 0 & w_{6} & 0 & 0 \\ \end{pmatrix}$$

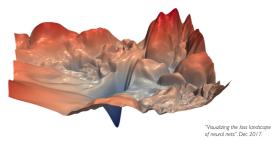
Training Neural Networks is Difficult



Optimization with Differentiable Algorithmic

- Learning rate $\eta: \mathbf{W} \leftarrow \mathbf{W} \eta \frac{\partial J(\mathbf{W})}{\partial \mathbf{W}}$
- Variants of the Stochastic Gradient Descent (SGD) algorithm are used:
 - Use of moments,
 - Use of regularizers.

Training Neural Networks is Difficult



Batches

■ To accelerate computations, inputs are often treated **concurrently** using small **batches**.

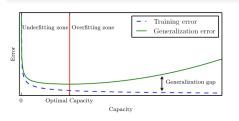
Generalization vs Overfitting

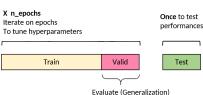
Learning Objectives

- Reduce the training error AND reduce the gap between training and generalization error (error on new inputs)
- Avoid overfitting, increase generalization for better performances on test set

Validation Set

 Examples from the training distribution NOT observed during training (e.g. 20%, 80% sp lit) to check model generalization





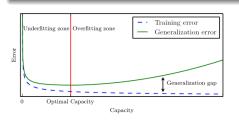
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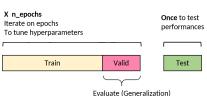
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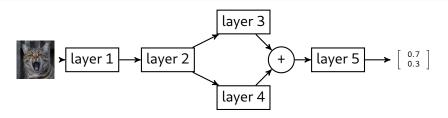
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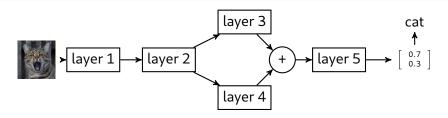
Inputs/outputs

- Often: inputs are raw signals or feature vectors,
- Often: outputs are vectors which highest value indicate the category of the input.



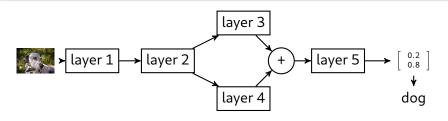
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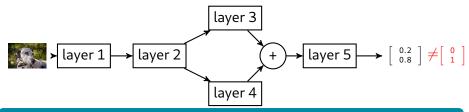
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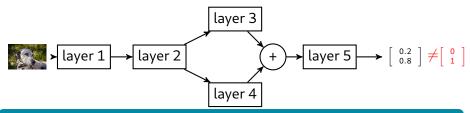


Loss and targets

- Labels are encoded as one-hot-bit vectors and called targets,
- Outputs are **softmaxed**: $\mathbf{y}_i \leftarrow \exp(\mathbf{y}_i) / \sum_j \exp(\mathbf{y}_j)$,
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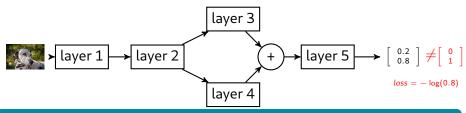


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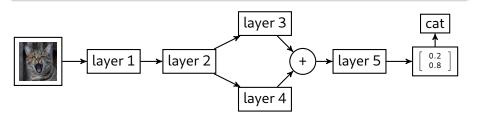


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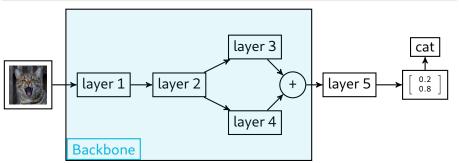
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- Fine-tuning: both the backbone and downstream networks are trained,
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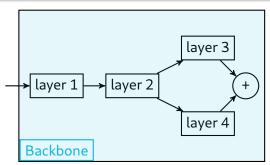
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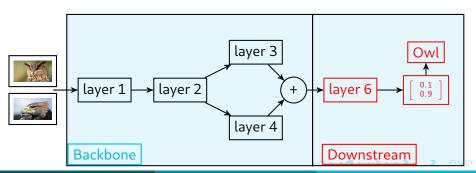
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Hyperparameters

Architecture

- Number of layers
- Architecture choice (e.g. ResNet, DenseNet, VGG, ...)

Training

- Learning rate and scheduling
- Regularization (e.g. weight decay)
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Lab Session 1 and assignment

Introduction to Deep Learning

- Introduction to Deep Learning in Pytorch
- Train a full DL model from scratch
- Train a downstream model using transfer learning

Project 1 (oral presentation)

Explore one of the following architectures: ResNet, DenseNet, PreActResNet, VGG.

You have to prepare a 10 minutes (+5 min Q&A) presentation for session 2, in which you explain:

- Description of the architecture
- Hyperparameter search and results
- Study the compromise between architecture size, performance and training time.