

A fast and effective heuristic for the feedback arc set problem

Peter Eades

Department of Computer Science, University of Newcastle, Callaghan 2308, NSW, Australia

Xuemin Lin

Department of Computer Science, University of Queensland, Brisbane 4067, Qld, Australia

W.F. Smyth

Department of Computer Science and Systems, McMaster University, Hamilton, Ontario, Canada L8S 4L8 and School of Computing Science, Curtin University of Technology, Bentley 6102, WA, Australia

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Abstract

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Let $G = (V, A)$ denote a simple connected directed graph, and let $n = |V|$, $m = |A|$, where $n - 1 \leq m \leq \binom{n}{2}$. A *feedback arc set* (FAS) of G , denoted $R(G)$, is a (possibly empty) set of arcs whose reversal makes G acyclic. A *minimum feedback arc set* of G , denoted $R^*(G)$, is a FAS of minimum cardinality $r^*(G)$; the computation of $R^*(G)$ is called the *FAS problem*. Berger and Shor have recently published an algorithm which, for a given digraph G , computes a FAS whose cardinality is at most $m/2 - c_1 m / \Delta^{1/2}$ where Δ is the maximum degree of G and c_1 is a constant. Further, they exhibited an infinite class \mathcal{G} of graphs with the property that for every $G \in \mathcal{G}$ and some constant c_2 , $r^*(G) \geq m/2 - c_2 m / \Delta^{1/2}$. Thus the Berger–Shor algorithm provides, in a certain asymptotic sense, an optimal solution to the FAS problem. Unfortunately, the Berger–Shor algorithm is complicated and requires running time $O(mn)$. In this paper we present a simple FAS algorithm which guarantees a good (though not optimal) performance bound and executes in time $O(m)$. Further, for the sparse graphs which arise frequently in graph drawing and other applications, our algorithm achieves the same asymptotic performance bound that Berger–Shor does.

Keywords: Algorithms; analysis of algorithms; combinatorial problems; data structures; design of algorithms; digraphs; feedback arc set

1. Introduction

Correspondence to: P. Eades, Department of Computer Science, University of Newcastle, University Drive, Callaghan 2308, NSW, Australia. Email: dce@cs.newcastle.edu.au.

The FAS problem defined in the Abstract was apparently first studied by Slater [9] in the special

case $m = \binom{n}{2}$ that G is a *tournament*. Interpreting the direction of each arc xy as a “win” for x over y in a round-robin tournament of n players, Slater looked for a minimum set of results (arcs) whose reversal would make the tournament consistent (acyclic). For every n , let $\rho(n)$ denote the maximum, over all digraphs G of order n , of $|R^*(G)|$. Much of the subsequent research was devoted to estimating $\rho_T(n)$, the restriction of $\rho(n)$ to tournaments T . Then

$$\rho_T(n) = \binom{n}{2} / 2 - \phi_T(n) \leq \rho(n),$$

where $\phi_T(n) \in O(n^2)$.

In 1965 Erdős and Moon [4] showed that

$$\phi_T(n) \in \Omega(n), \quad \phi_T(n) \in O(n^{3/2} \log^{1/2} n).$$

The lower bound was sharpened to $\phi_T(n) \in \Omega(n \log n)$ by Jung [5], and Spencer [10,11] was able to improve both bounds by showing that $\phi_T(n) \in \Theta(n^{3/2})$. Then the upper bound was further refined by de la Vega [2], who proved that

$$\text{prob}[\phi_T(n) \leq 1.73n^{3/2}] \rightarrow 1$$

as $n \rightarrow \infty$, where all labelled tournaments on n vertices are regarded as equally likely.

Berger and Shor [1] provide a basis for both strengthening and generalizing these results. Given a digraph G of maximum degree Δ , their algorithm computes $R(G)$ of cardinality $r(G)$ satisfying

$$r^*(G) \leq r(G) \leq m/2 - c_1 m / \Delta^{1/2},$$

where c_1 is a positive constant. On the other hand, they exhibit an infinite class \mathcal{G} of digraphs with the property that for every $G \in \mathcal{G}$,

$$r^*(G) \geq m/2 - c_2 m / \Delta^{1/2},$$

for some positive constant c_2 . It follows that the upper bound $m/2 - c_1 m / \Delta^{1/2}$ is tight. When G is a tournament ($m = \binom{n}{2}$, $\Delta = n - 1$), this reduces to the form established by Spencer for $\rho_T(n)$.

Since the FAS problem is NP-hard [6], it is likely that no polynomial-time algorithm computes $r^*(G)$ exactly; hence the asymptotic performance bound of the Berger-Shor algorithm can be regarded as best possible. At the same

time, Berger-Shor requires $O(mn)$ execution time, and it may be that, in many circumstances (for example, for on-line processing), a much faster algorithm with a suboptimal but good performance bound would be preferred. Such an algorithm, with performance bound

$$r(G) \leq m/2 - n/6$$

and $O(m)$ execution time, is presented in Section 2 of this paper. Observe that, over digraphs satisfying $m \in O(n)$, this performance bound is at least as good as that of Berger and Shor, and is in fact better over digraphs for which, in addition, $\Delta \notin O(1)$.

Section 3 briefly discusses other FAS algorithms and makes suggestions for future work.

2. A new FAS algorithm

Suppose that the vertices of G are arranged in some order on a horizontal line and labelled v_1, v_2, \dots, v_n from left to right. We call such an arrangement a *vertex sequence* and denote it by $s = v_1 v_2 \dots v_n$. Clearly each vertex sequence s induces a feedback arc set $R(s)$ consisting of all the leftward arcs $v_j v_i$, $j > i$; moreover, every feedback arc set corresponds to some vertex sequence. Thus the FAS problem is equivalent to the problem of determining a vertex sequence s^* such that $R(s^*) = R^*(G)$.

In this section we present a greedy algorithm, called Algorithm GR, which computes a “good” vertex sequence s (one corresponding to a “small” feedback arc set $R(s)$). The algorithm greedily removes from G vertices (and their incident arcs) which are sinks or sources, or which satisfy a property that we now specify. For any vertex $u \in V$, let $d(u)$ denote the degree of u , $d^+(u)$ its outdegree, and $d^-(u)$ its indegree: then $d(u) = d^+(u) + d^-(u)$. At each step of Algorithm GR, after sinks and sources have been removed, a single vertex u is removed for which $\delta(u) = d^+(u) - d^-(u)$ is currently a maximum. If a vertex u removed from G is a sink, it is concatenated with a vertex sequence s_2 ; otherwise, u is concatenated with a vertex sequence s_1 . When G has been reduced to an empty graph by successive removals, the output vertex sequence s is

computed by forming the concatenation $s = s_1 s_2$. A formal statement of the new algorithm is given below:

Procedure GR

(G : DiGraph; **var** s : VertexSequence);

$s_1 \leftarrow \emptyset$; $s_2 \leftarrow \emptyset$;

while $G \neq \emptyset$ **do**

while G contains a sink **do**

 {choose a sink u ; $s_2 \leftarrow us_2$; $G \leftarrow G - u$ };

while G contains a source **do**

 {choose a source u ; $s_1 \leftarrow s_1 u$; $G \leftarrow G - u$ };

if $G \neq \emptyset$ **then**

 {choose a vertex u for which $\delta(u)$ is a maximum; $s_1 \leftarrow s_1 u$; $G \leftarrow G - u$ };

$s \leftarrow s_1 s_2$.

We consider first the performance of this algorithm.

Theorem 2.1. *Algorithm GR computes either an empty vertex sequence or a vertex sequence s for which $|R(s)| \leq m/2 - n/6$.*

Proof. For $n \leq 1$, GR computes $R(s) = \emptyset$. Otherwise, GR induces a partitioning $V = \cup_{i=1}^5 V_i$ where

- V_1 consists of removed vertices u which at the time of removal were sinks of indegree $d^-(u) > 0$,
- V_2 consists of removed vertices u which were isolated ($d(u) = 0$),
- V_3 consists of removed vertices u which were sources of outdegree $d^+(u) > 0$;
- V_4 consists of removed vertices u such that $d^+(u) = d^-(u) > 0$,
- V_5 consists of removed vertices u such that $d^+(u) > d^-(u) > 0$.

For $1 \leq i \leq 5$, let $n_i = |V_i|$ and let m_i denote the number of arcs removed from G as a result of the removal of the vertices of V_i . The $n = \sum_{i=1}^5 n_i$, $m = \sum_{i=1}^5 m_i$, and $m_2 = 0$.

Since G is connected and $n > 1$, there is initially no isolated vertex. Suppose that removal of a vertex $u \in V_4 \cup V_5$ induces an isolated vertex v . Then v must result from removal of either uv or vu , but not both. Hence v would have been

either a sink before the removal of uv or a source before the removal of vu . In either case v would already have been removed, and so removal of u cannot give rise to a vertex $v \in V_2$. A similar argument shows that removal of $u \in V_3$ cannot induce an isolated vertex v , and we seen then that v can only be induced by prior removal of a sink u and an incident arc vu . It follows that the isolated vertices are induced by the removal of the vertices in V_1 . Thus,

$$n_2 \leq m_1. \quad (2.1)$$

Note that when GR removes a vertex $u \in V_4$, all other vertices have indegree equal to outdegree. Thus, after u is removed, the resulting digraph $G - u$ contains exactly $d^+(u)$ vertices v for which $d^+(v) = d^-(v) + 1$ and exactly $d^+(u)$ vertices w for which $d^-(w) = d^+(w) + 1$. Since as we have seen $G - u$ contains no isolated vertex, it follows that the next removed vertex $x \in V_1 \cup V_3 \cup V_5$. That is,

$$n_4 \leq n_1 + n_3 + n_5,$$

which, by substitution for n_4 , becomes

$$n \leq 2n_1 + n_2 + 2n_3 + 2n_5$$

$$\leq 2n_1 + n_2 + 3n_3 + 3n_5,$$

so that, applying (2.1) and observing that $n_1 \leq m_1$, we find

$$n \leq 3(m_1 + n_3 + n_5). \quad (2.2)$$

Consider now the number of leftward arcs induced by the removal from G of a vertex u and its insertion in the vertex sequence s . If $u \in V_4$, then the number of leftward arcs to u at the time of its removal is exactly $d(u)/2$; if $u \in V_5$, then the number of leftward arcs to u at the time of its removal is at most $(d(u) - 1)/2$. A removed vertex $u \in V_1 \cup V_2 \cup V_3$ contributes no leftward arcs. Thus,

$$\begin{aligned} r(s) &= |R(s)| \leq m_4/2 + (m_5 - n_5)/2 \\ &= m/2 - (m_1 + m_3 + n_5)/2 \\ &\leq m/2 - (m_1 + n_3 + n_5)/2, \end{aligned}$$

since $n_3 \leq m_3$. Applying (2.2), we obtain the desired result. \square

Though only connected graphs are considered in this paper, Theorem 2.1 is easily extended to graphs which are not connected. The upper bound is sharp, since it is attained when G is a collection of directed cycles of length 3. However, for tournaments, a slightly better bound can be stated, as follows:

Theorem 2.2. *Given a tournament G , Algorithm GR computes a vertex sequence s for $|R(s)| \leq m/2 - \lfloor n/2 \rfloor/2$.*

Proof. Suppose that n is odd and observe that removing the first vertex u from G contributes at most $(n-1)/2$ arc reversals to $r(s)$. $G-u$ will then be a tournament of even order $n-1$, and removing a vertex v from $G-u$ contributes at most $\lfloor (n-2)/2 \rfloor$ arc reversals. In general,

$$\begin{aligned} r(s) &\leq (n-1)/2 + \lfloor (n-2)/2 \rfloor \\ &\quad + \cdots + 4/2 + \lfloor 3/2 \rfloor + 2/2 \\ &= (n-1)^2/4. \end{aligned}$$

A similar calculation yields

$$r(s) \leq n(n-2)/4$$

when n is even. Both these inequalities reduce to the required form. \square

We now consider the implementation of Algorithm GR. For this, it is convenient to partition the vertex set of G into sources, sinks, and δ -classes, as follows:

$$\begin{aligned} V_d &= \{u \in V \mid d = \delta(u); d^+(u) > 0; d^-(u) > 0\}, \\ &\quad -n+3 \leq d \leq n-3; \\ V_{-n+2} &= \{u \in V \mid d^+(u) = 0\}; \\ V_{n-2} &= \{u \in V \mid d^-(u) = 0; d^+(u) > 0\}. \end{aligned}$$

It is clear that every vertex $u \in V$ falls into exactly one of these $2n-3$ classes. To compute these classes for a given digraph G , Algorithm GR needs to perform a bin sort as an initialization phase. The bin sort implements each vertex class as a bin, with the vertices in each class

linked together by a doubly linked list. This structure can be formed in $O(m)$ time and uses $O(m)$ space.

Using the bins, it becomes trivial to recognize a sink u , a source u , or a vertex u for which $\delta(u)$ is a maximum. Furthermore, having determined u , it becomes trivial to compute s_1 or s_2 and, at the same time, to output the leftward arcs, if any, currently incident at u .

It remains only to be seen how to form $G-u$. The vertex u itself can be removed in $O(1)$ time by eliminating it from its bin list. As a result, every vertex v adjacent to u will either become a sink, a source, or an element of an adjacent bin: to perform these updates requires $O(1)$ time for each arc incident at u . We have proved the following theorem:

Theorem 2.3. *Algorithm GR can be implemented in $O(m)$ time and $O(m)$ space.*

3. Remarks

In Section 2 we described Algorithm GR, a simple new FAS algorithm with a good (though not optimal) performance bound and $O(m)$ (linear) execution time. For sparse digraphs this performance bound is at least as good as that of Berger and Shor, whose algorithm requires execution time $O(mn)$. However, for dense digraphs, the Berger-Shor algorithm has a performance bound which is, in a certain sense, optimal.

Our new algorithm is the only known FAS algorithm which executes in linear time and has a performance bound strictly less than $m/2$ for all digraphs. Trivial linear algorithms [3,7] have been known for some time, but these do not even guarantee good performance bounds for tournaments. [3] describes new greedy and divide-and-conquer algorithms which execute in linear time and guarantee good performance bounds for tournaments; but, as shown in [7], there nevertheless exist digraphs for which these algorithms yield feedback arc sets of cardinality greater than $m/2$. ([7] also describes an $O(mn)$ FAS algorithm (a greedier version of Algorithm GR) whose performance bound is not as good as Berger-Shor in

general, but which nevertheless yields slightly better results when applied to oriented cubic graphs.)

In a practical context, the real challenge is to find a technique for expressing performance bounds, not just in terms of $\rho(n)$, but rather in terms of $r^*(G)$. For many digraphs G , $r^*(G)$ is much smaller than $\rho(n)$, and in such cases there is persuasive computational evidence [3] that even simple linear algorithms will “usually” yield feedback arc sets of cardinality not much greater than $r^*(G)$. On the other hand, there is some theoretical evidence ([8], see also [1]) that a polynomial time algorithm which obtains a feedback arc set of cardinality at most a constant times $r^*(G)$ may be impossible. In any case, to find a means of expressing performance bounds of certain algorithms (such as Algorithm GR and the Berger–Shor algorithm) in terms of $r^*(G)$ would provide a much sounder basis of evaluating their practical effectiveness.

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