Fibonacci Heaps

Outline for Today

Recap from Last Time

 Quick refresher on binomial heaps and lazy binomial heaps.

The Need for decrease-key

An important operation in many graph algorithms.

Fibonacci Heaps

 A data structure efficiently supporting decreasekey.

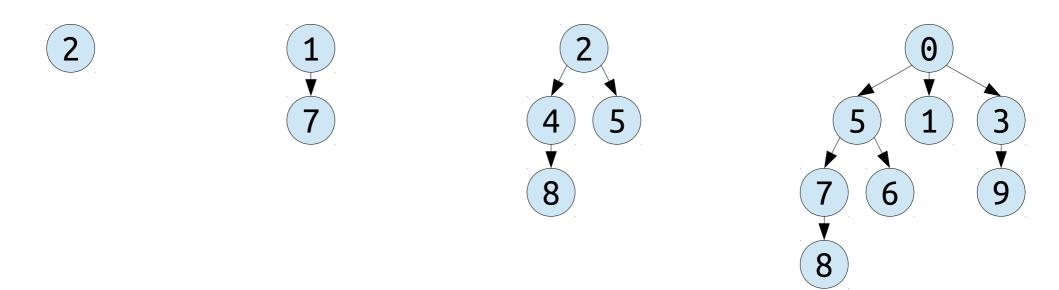
Representational Issues

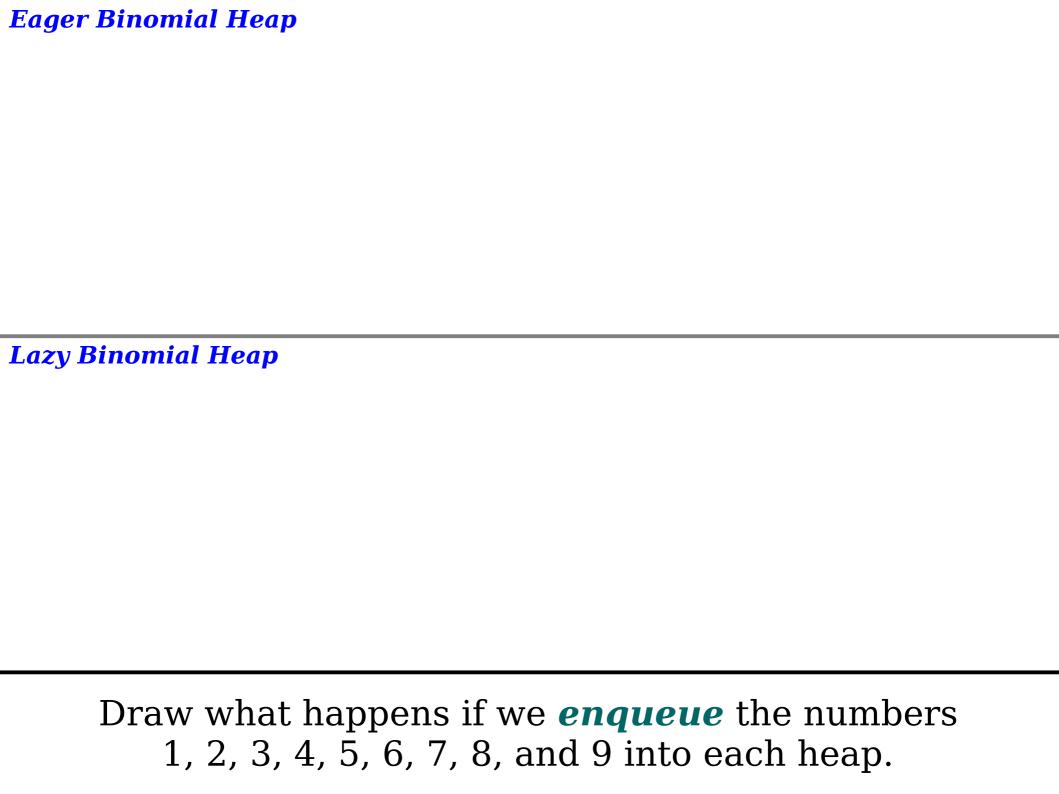
• Some of the challenges in Fibonacci heaps.

Recap from Last Time

(Lazy) Binomial Heaps

- Last time, we covered the **binomial heap** and a variant called the **lazy binomial heap**.
- These are priority queue structures designed to support efficient *meld*ing.
- Elements are stored in a collection of **binomial trees**.





Lazy Binomial Heap

Eager Binomial Heap Lazy Binomial Heap

1 7 2

Lazy Binomial Heap

1 3 v 2

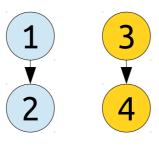
Lazy Binomial Heap

1 3 x 2 2

Lazy Binomial Heap

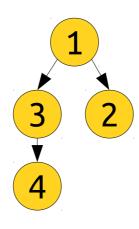
1 3

Lazy Binomial Heap

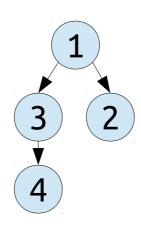


Lazy Binomial Heap

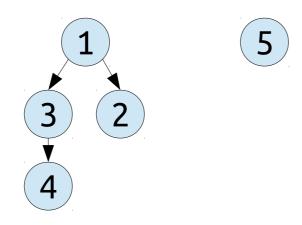
Lazy Binomial Heap



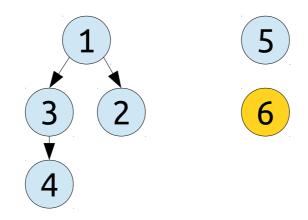
Lazy Binomial Heap



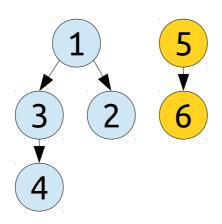
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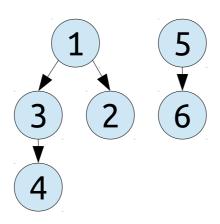
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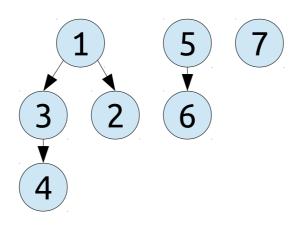
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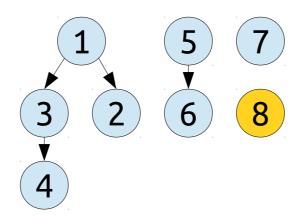
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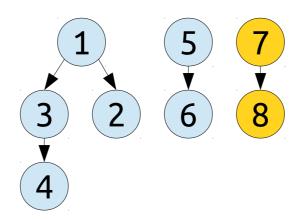
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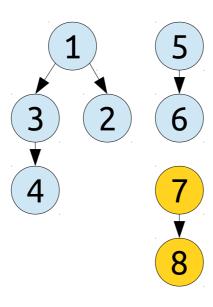
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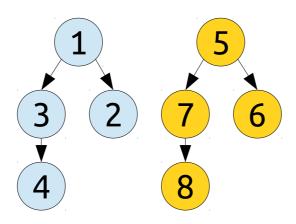
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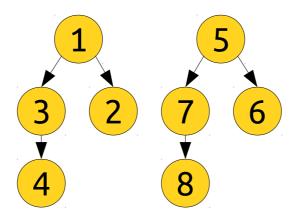
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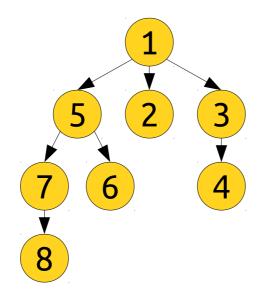
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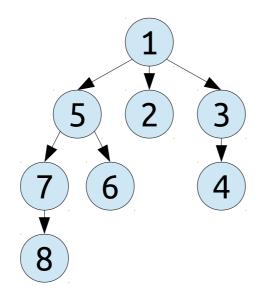
Lazy Binomial Heap



Lazy Binomial Heap

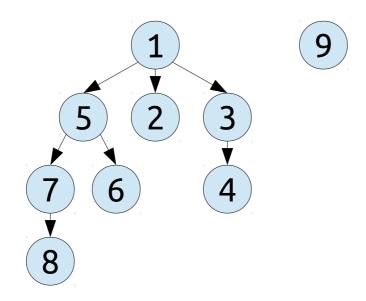


Lazy Binomial Heap



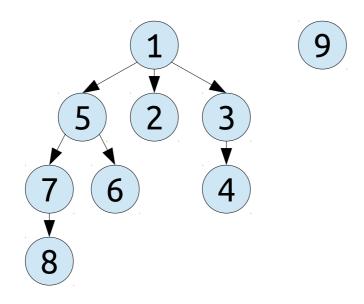
Lazy Binomial Heap

Eager Binomial Heap



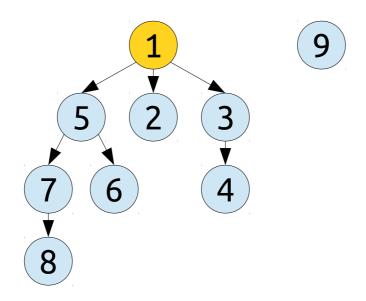
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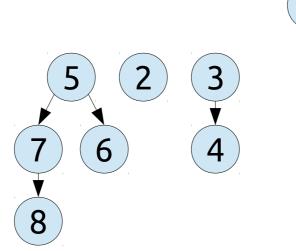
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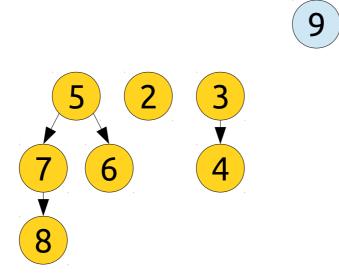
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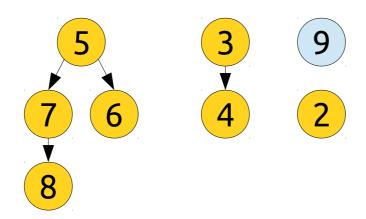
Lazy Binomial Heap

1 2 3 4 5 6 7 8 9



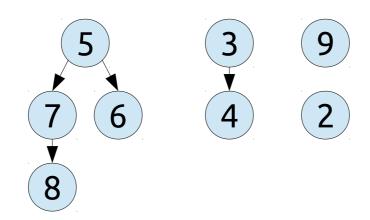
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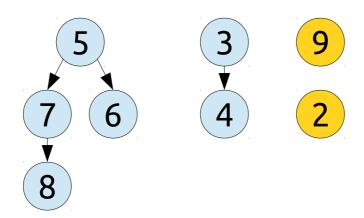
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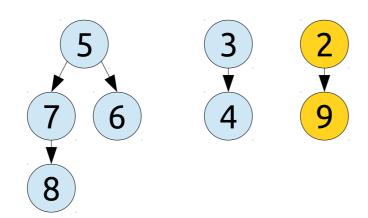
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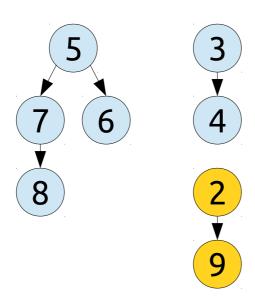
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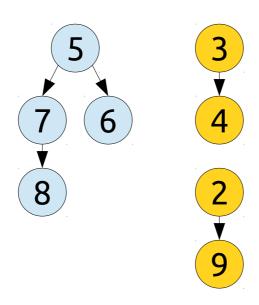
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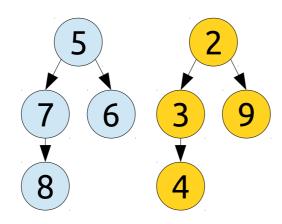
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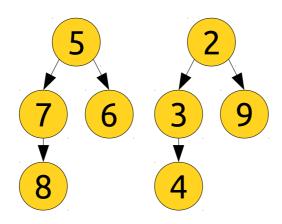
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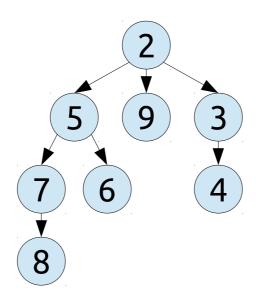
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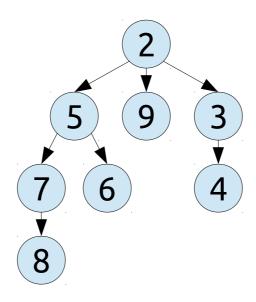
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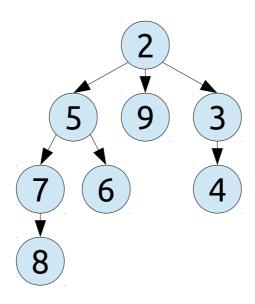
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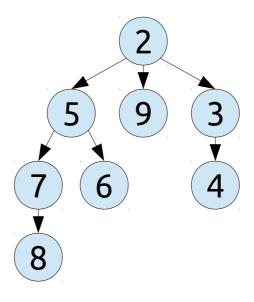
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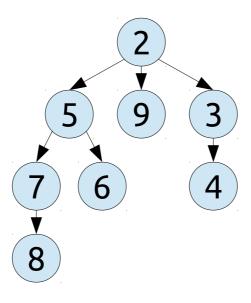


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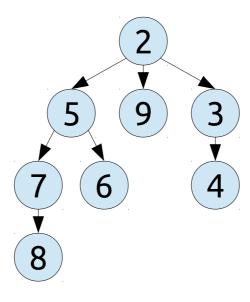




Lazy Binomial Heap		
Order 2	Order 1	Order 0
		2 3 4 5 6 7 8 9

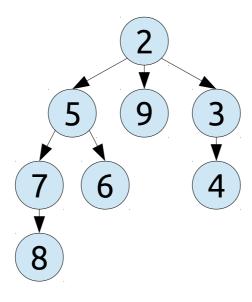


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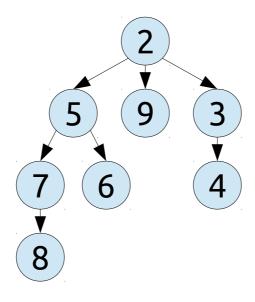


Lazy Binomial Heap			
Order 2	Order 1		Order 0
		2 3 4	5 6 7 8 9

Eager Binomial Heap

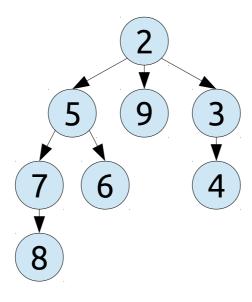


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Order 2	Order 1		Order 0	
	3 4	2	5 6 7 8 9	



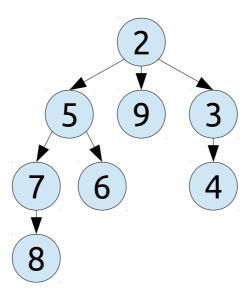
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Order 2	Order 1		Order 0	
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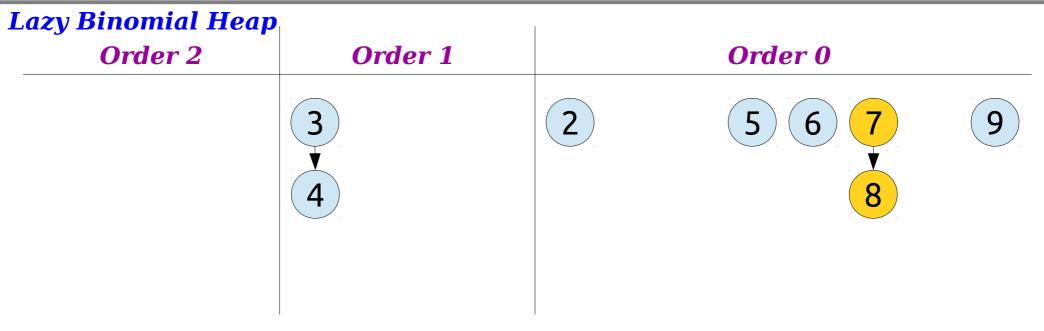
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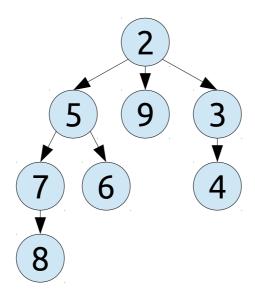
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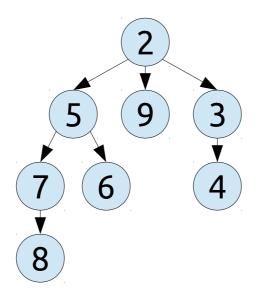


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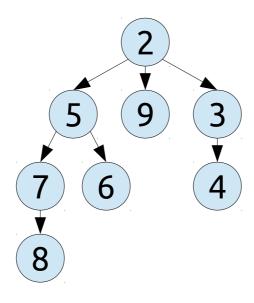
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Order 2	Order 1		Order 0		
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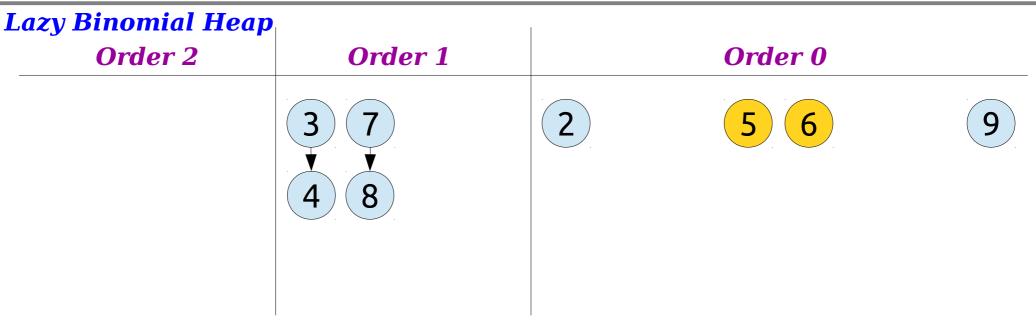
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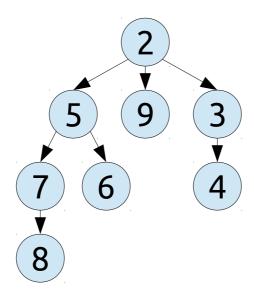
Lazy Binomial Heap					
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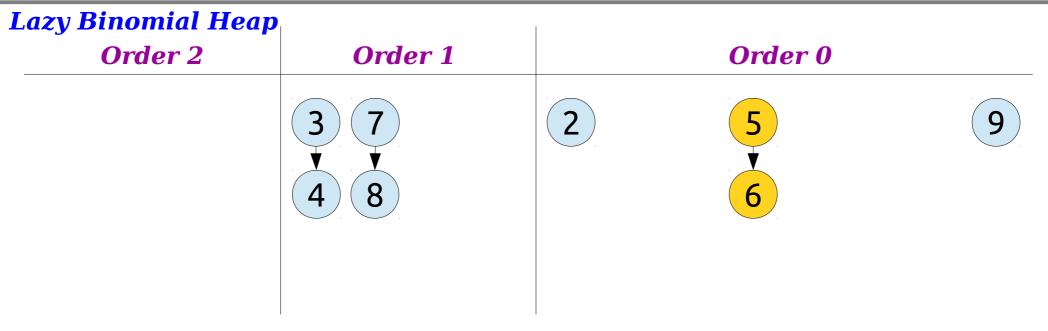
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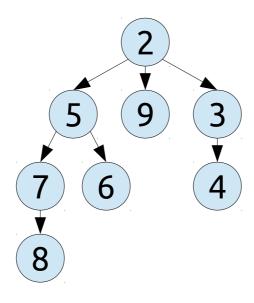


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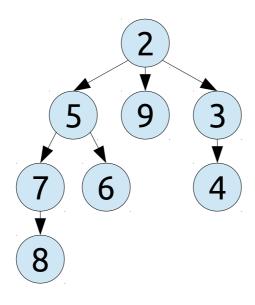




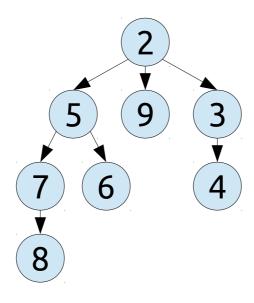
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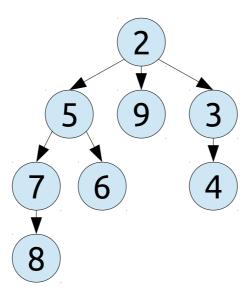
Lazy Binomial Heap	<u> </u>			
Order 2	Order 1		Order 0	
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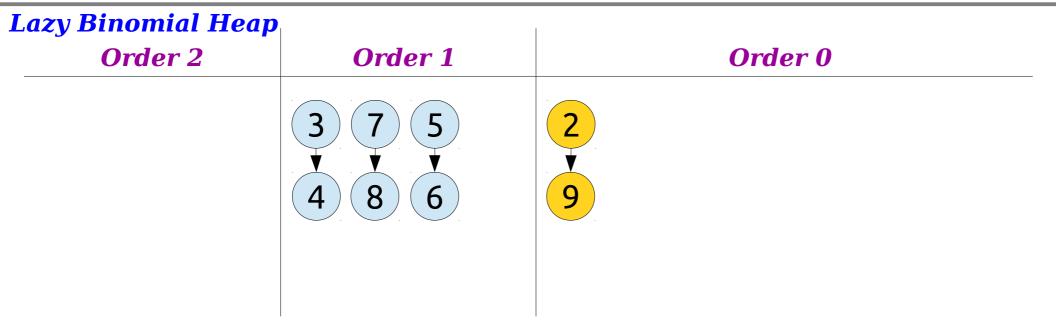


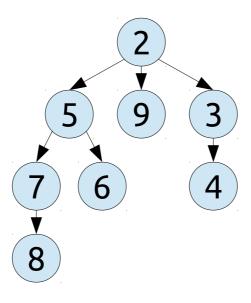
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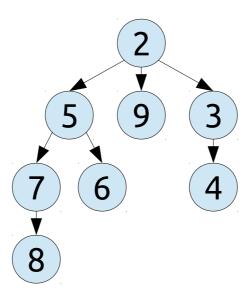
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Order 2	Order 1		Order 0	
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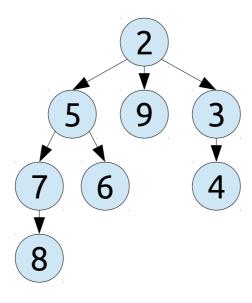


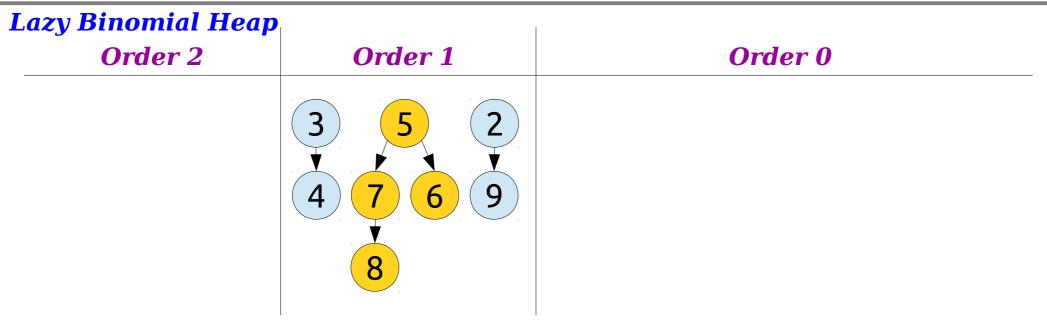
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Order 2	Order 1	Order 0			
	3 7 5 2				



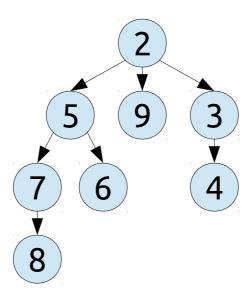
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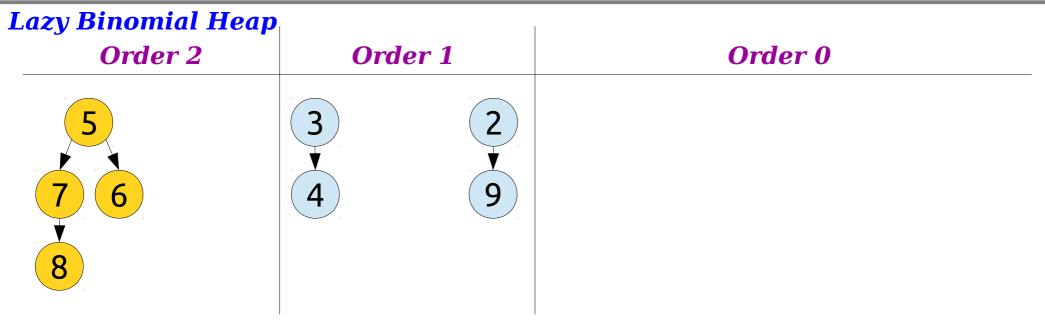
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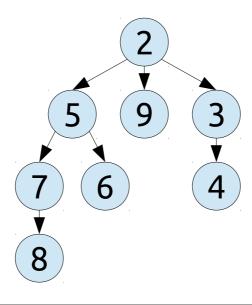


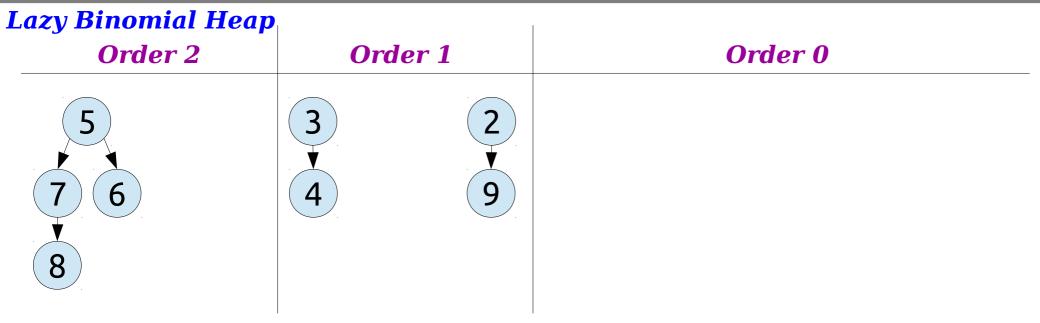
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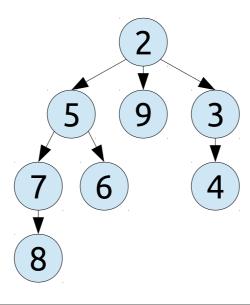


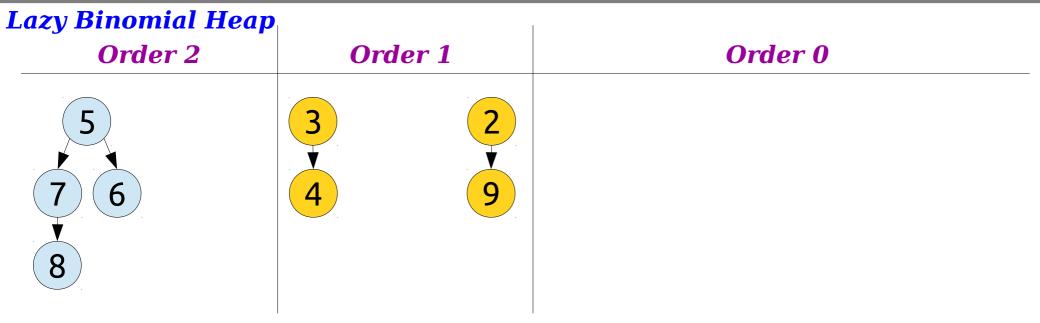
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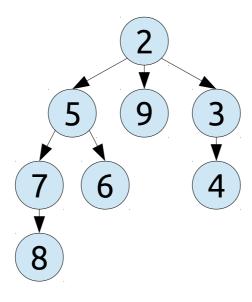


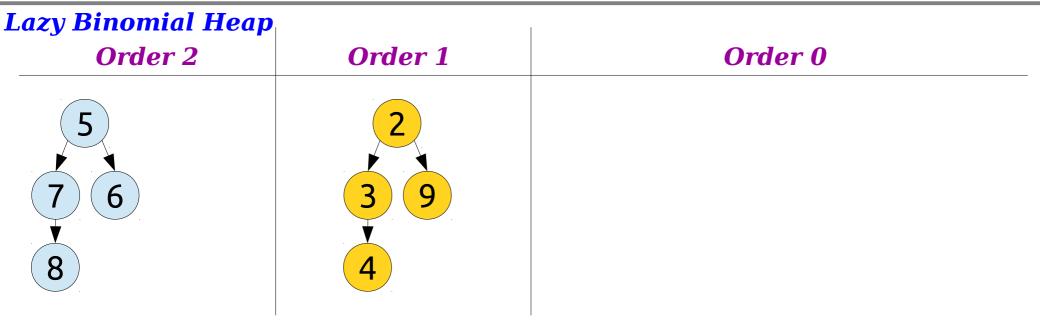
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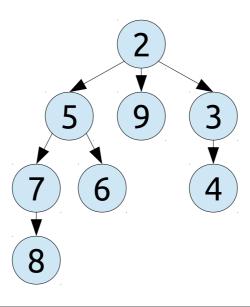


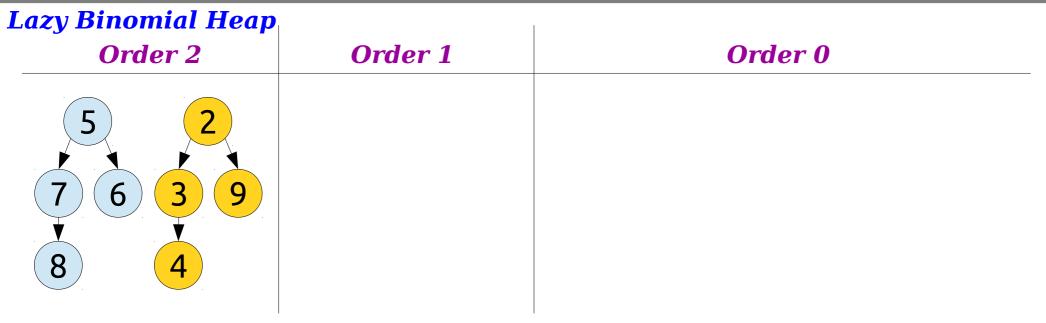
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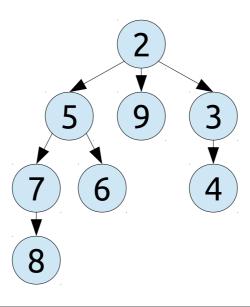


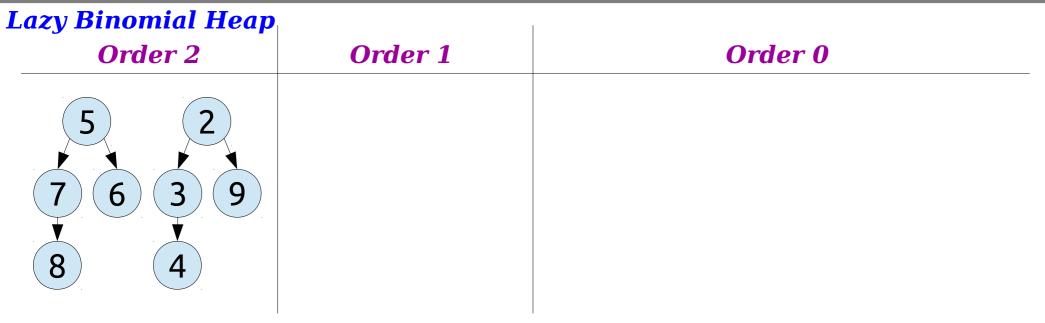
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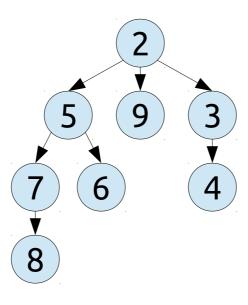


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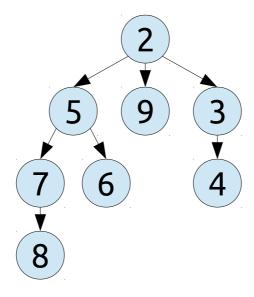




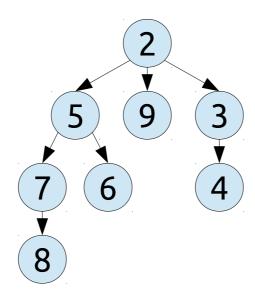
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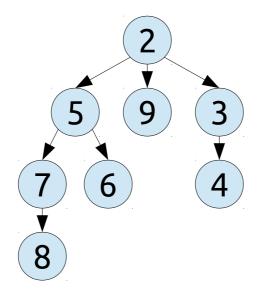


Lazy Binomial Heap			
Order 2	Order 1	Order 0	
7 6 3 9 8 4			

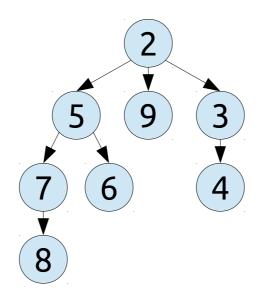


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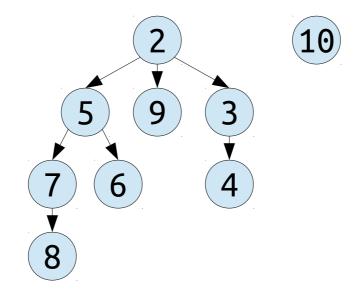




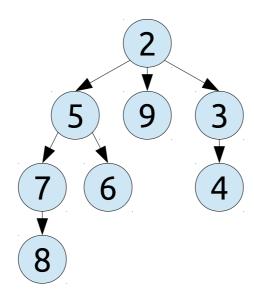
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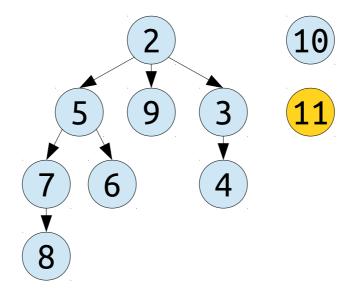
Let's *enqueue* 10, 11, and 12 into both heaps.



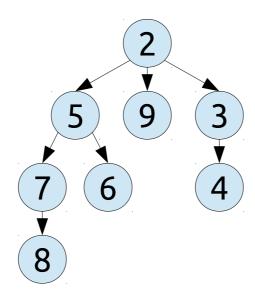
Lazy Binomial Heap



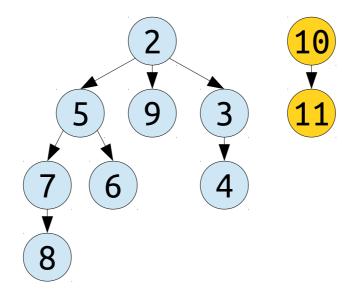
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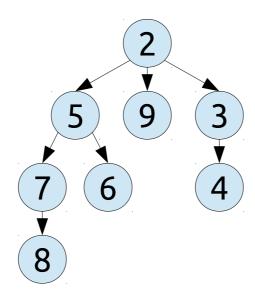
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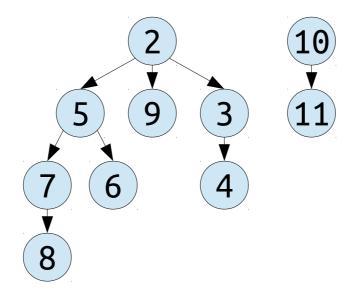


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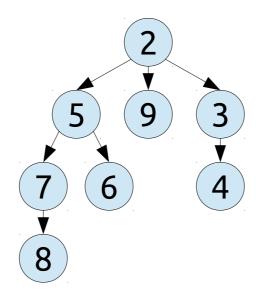


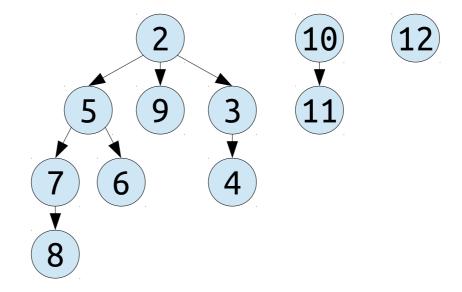
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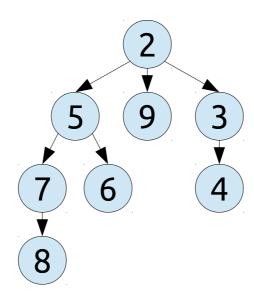


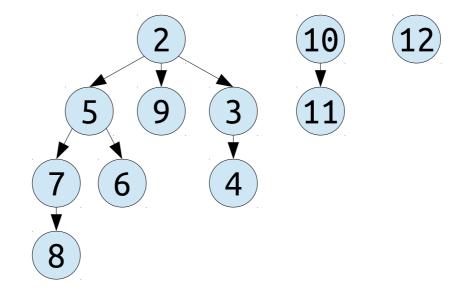
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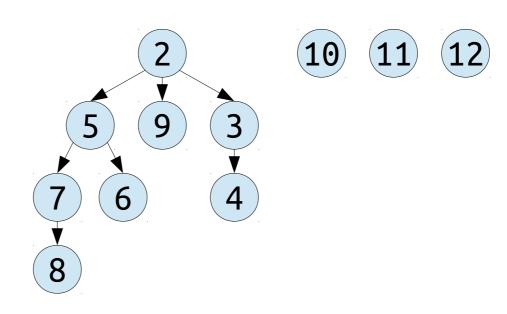


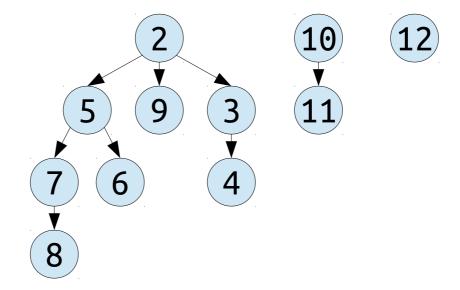
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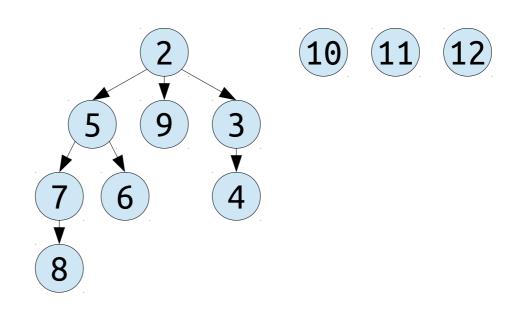


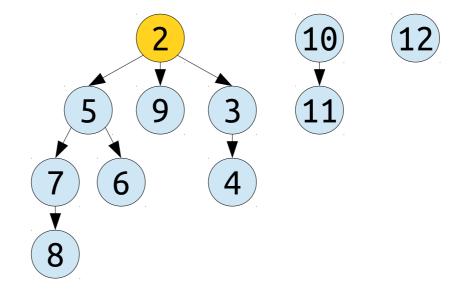
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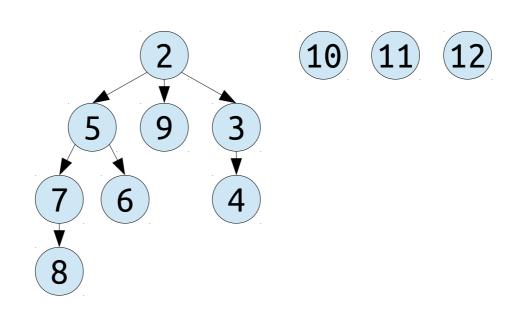


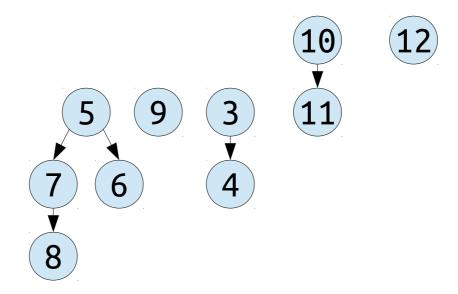
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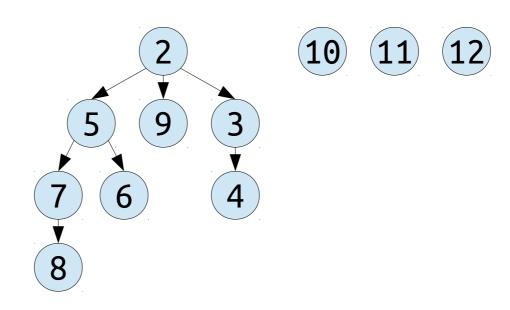


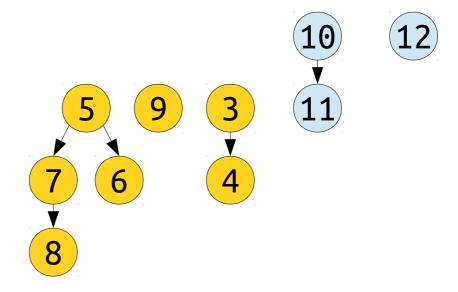
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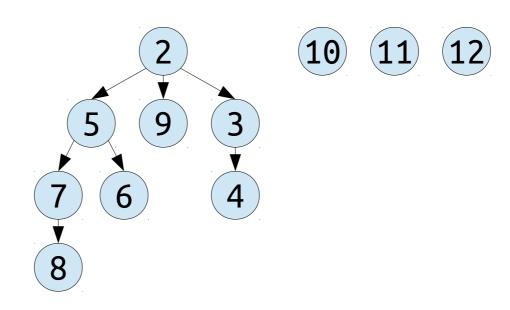


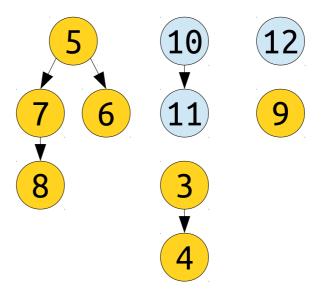
Lazy Binomial Heap



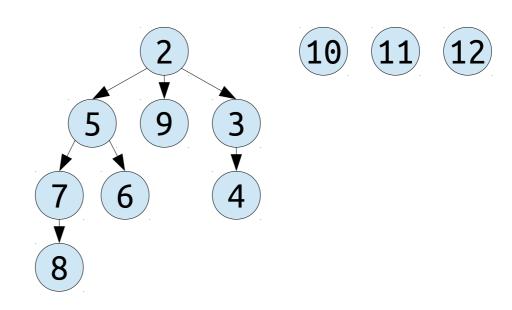


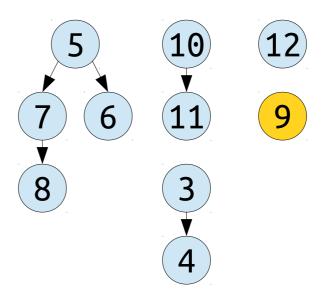
Lazy Binomial Heap



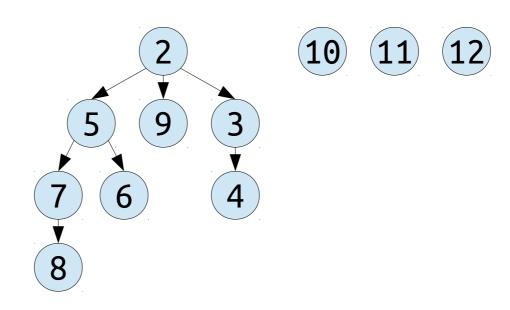


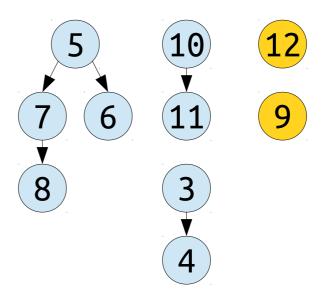
Lazy Binomial Heap



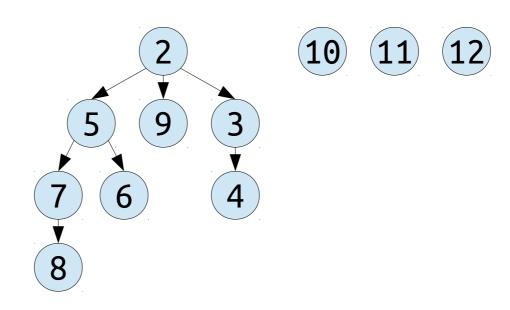


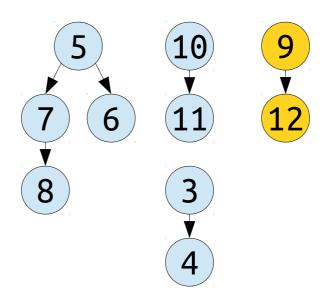
Lazy Binomial Heap



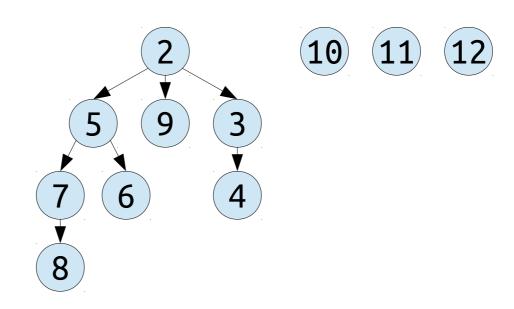


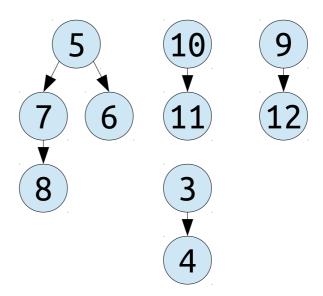
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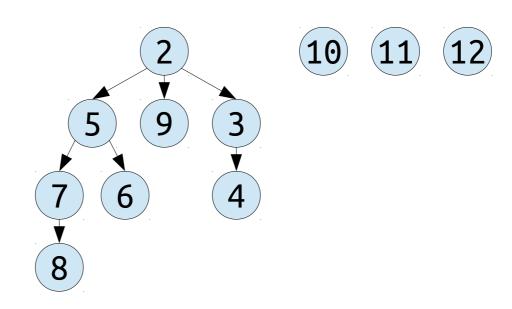


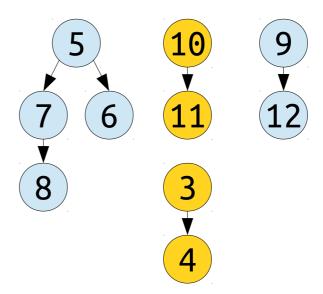
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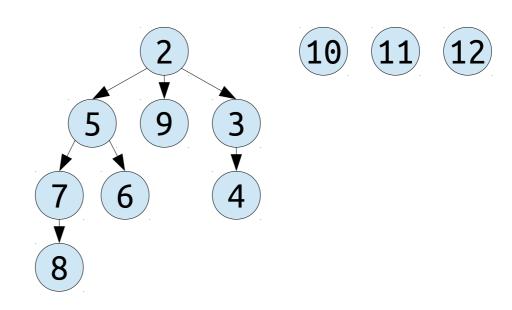


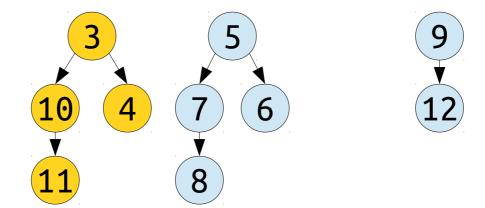
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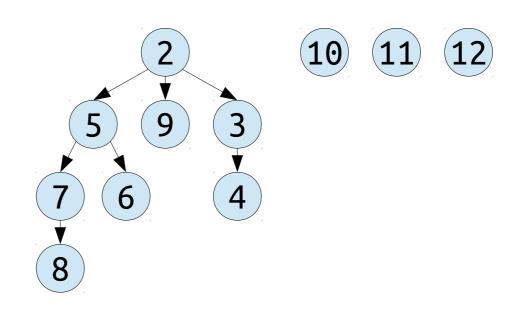


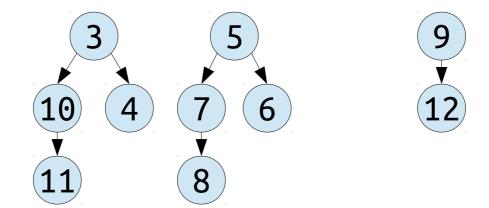
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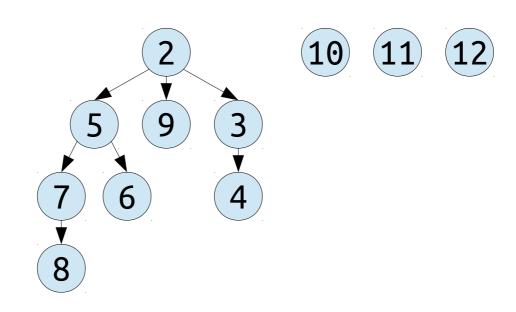


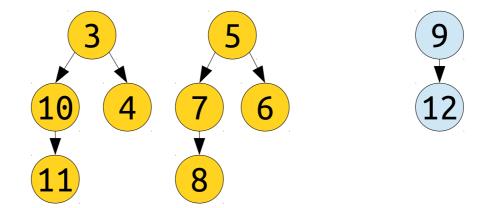
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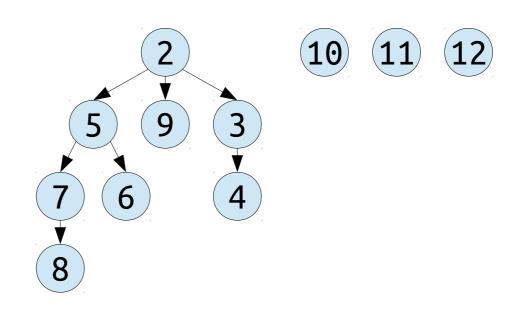


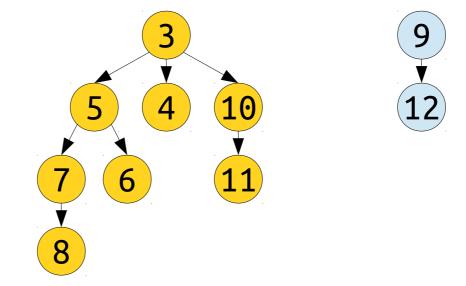
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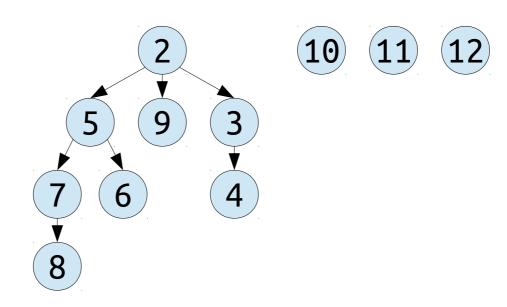


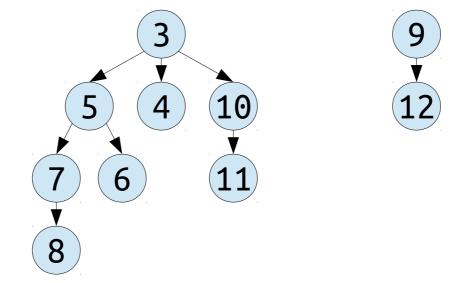
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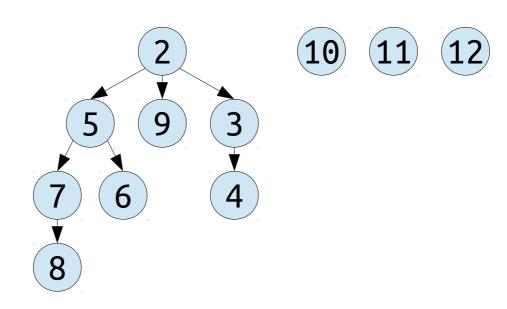


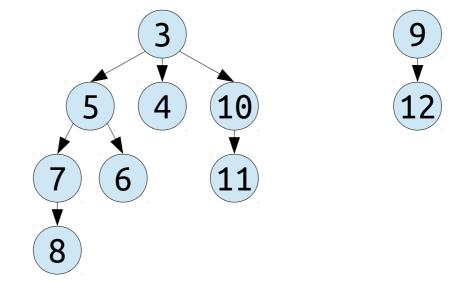
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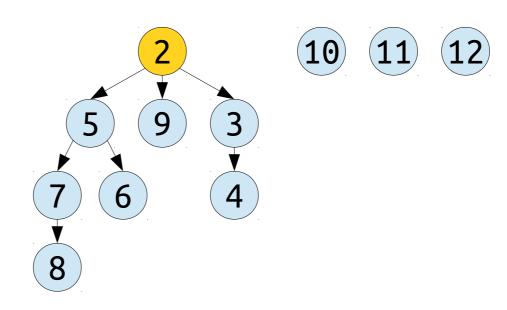


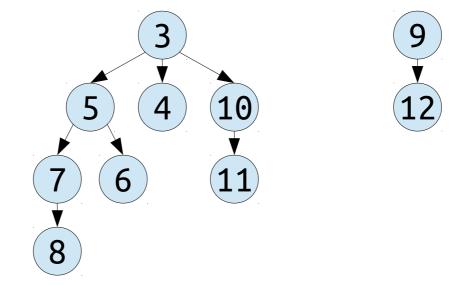
Lazy Binomial Heap



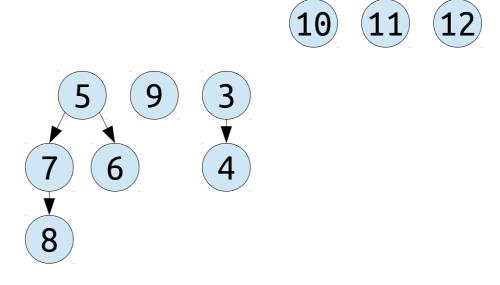


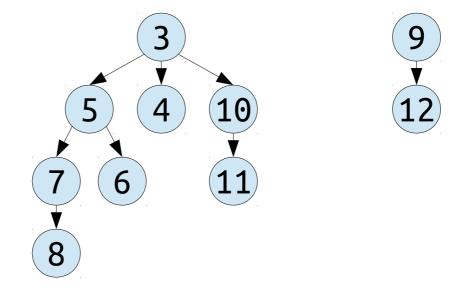
Lazy Binomial Heap



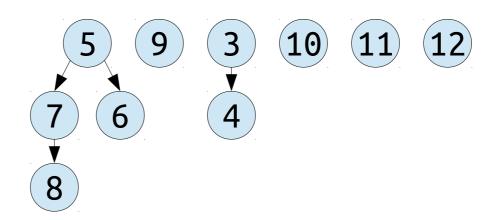


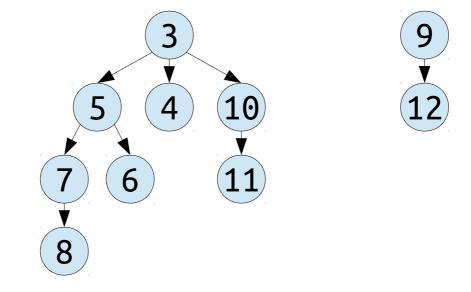
Lazy Binomial Heap



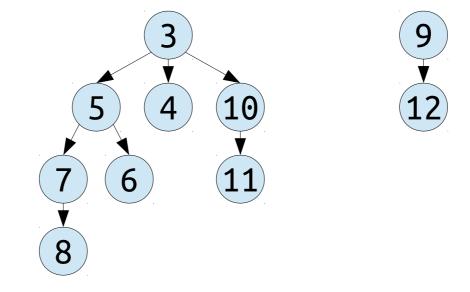


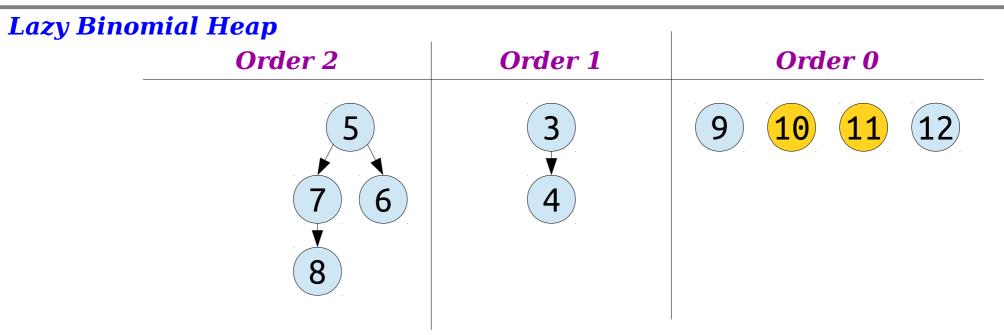
Lazy Binomial Heap

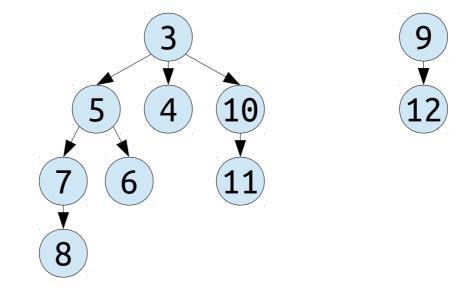


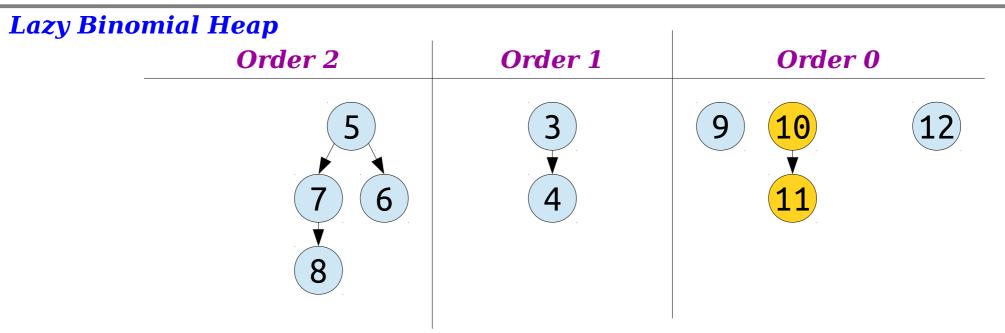


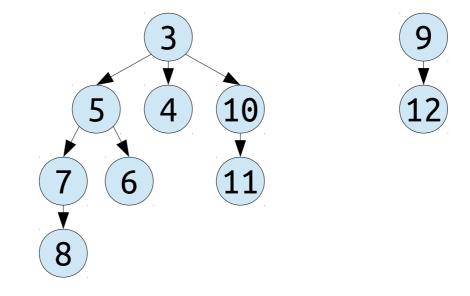
Lazy Binomial Heap		
Order 2	Order 1	Order 0
5768	3	9 10 11 12

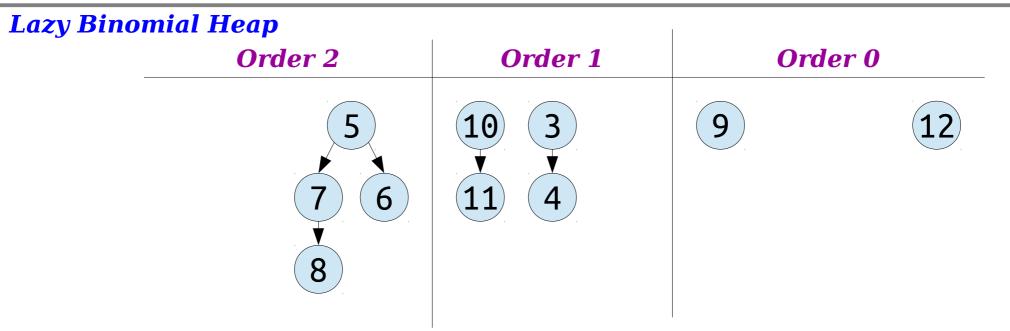


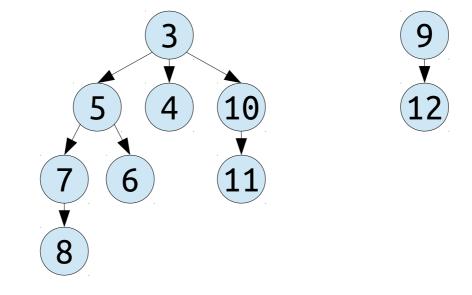


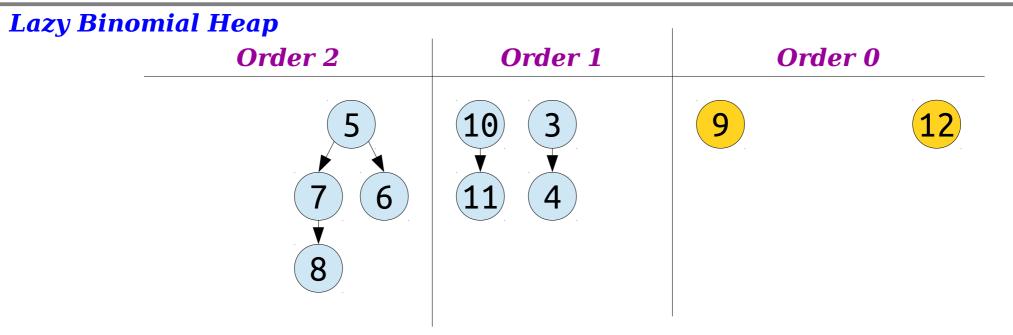


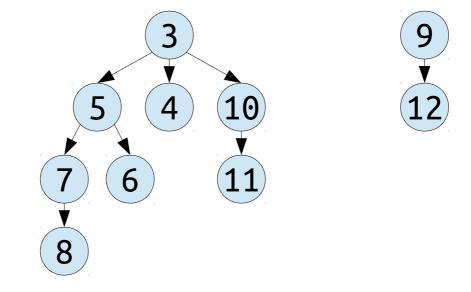


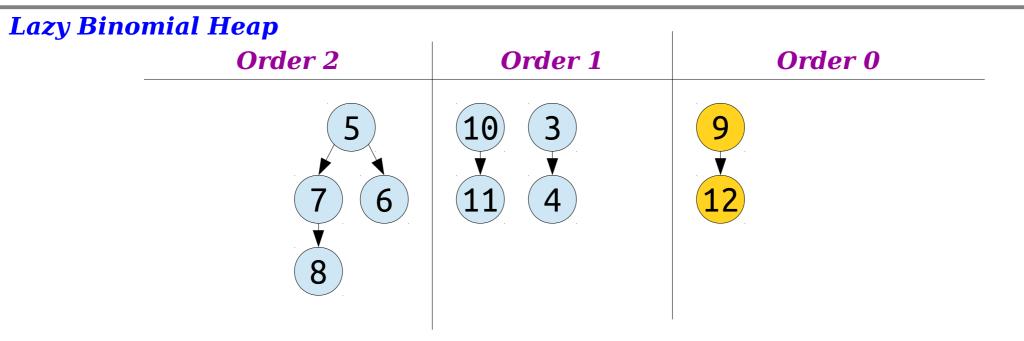


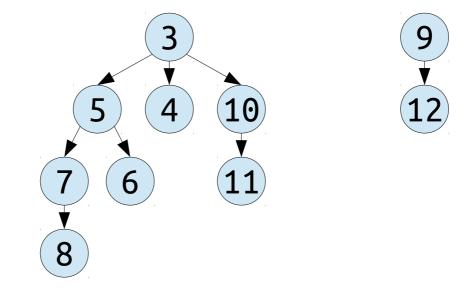


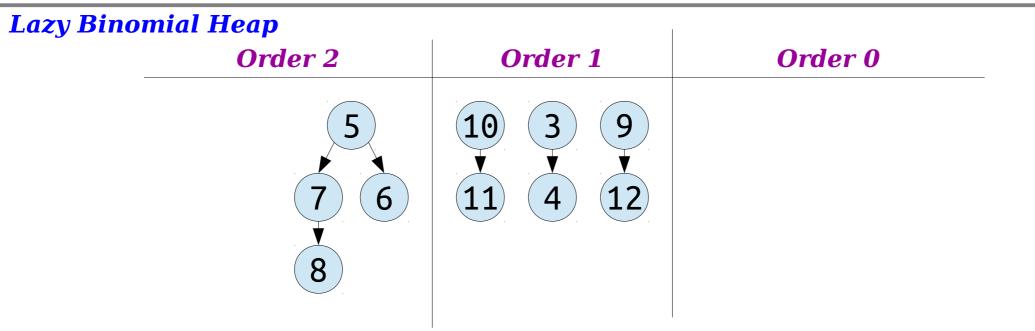


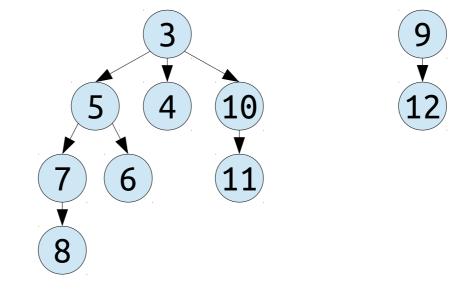


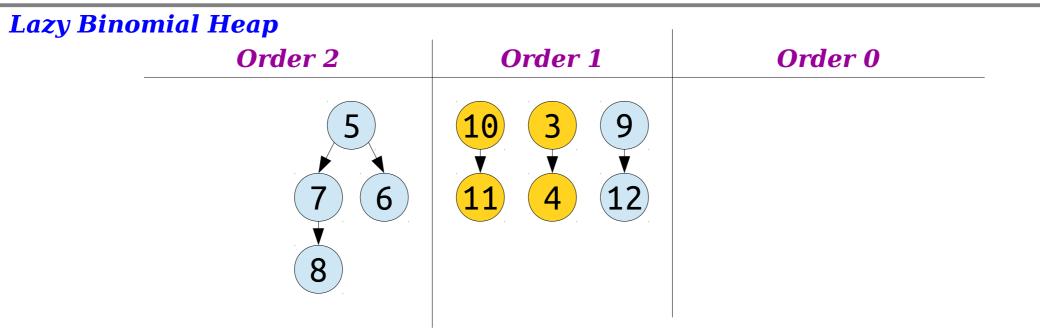


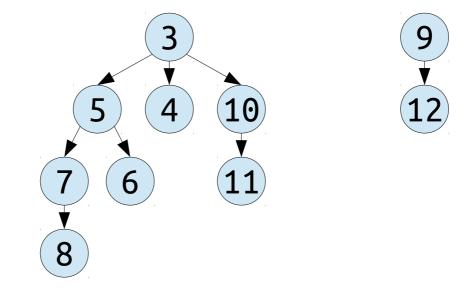


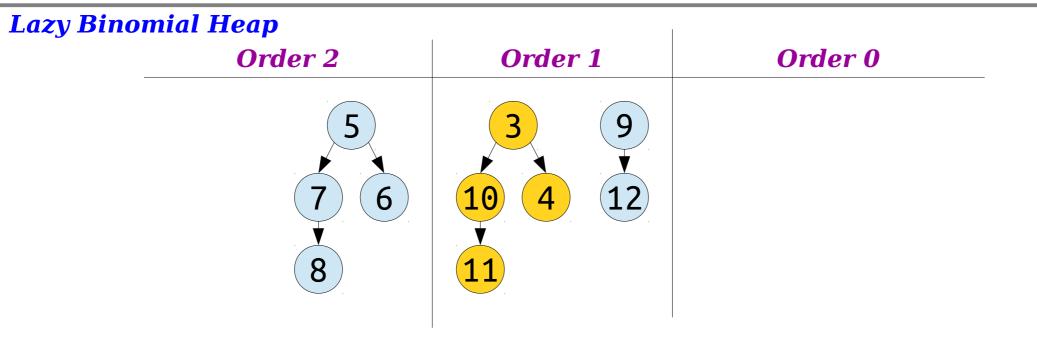


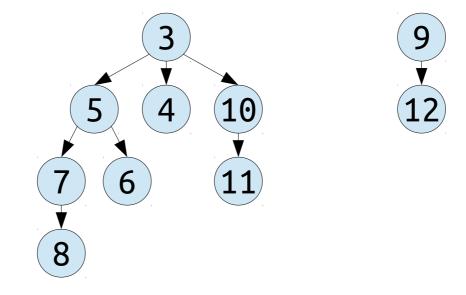


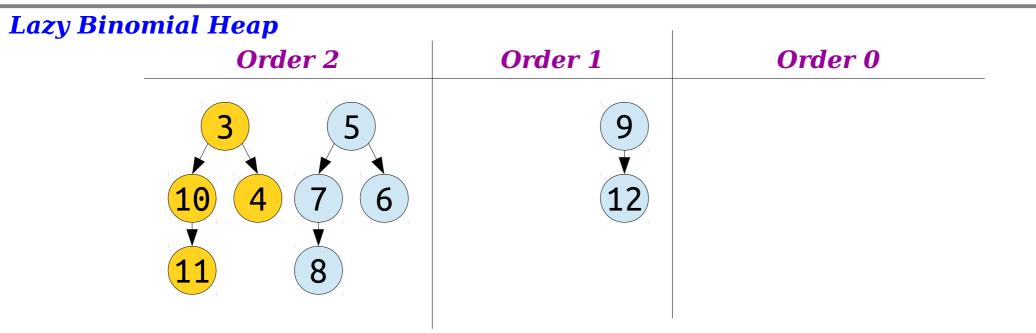


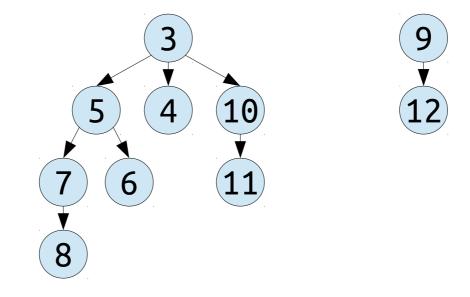


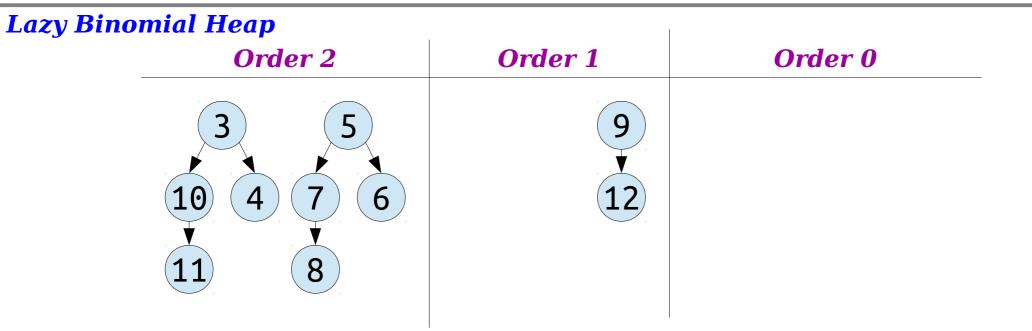


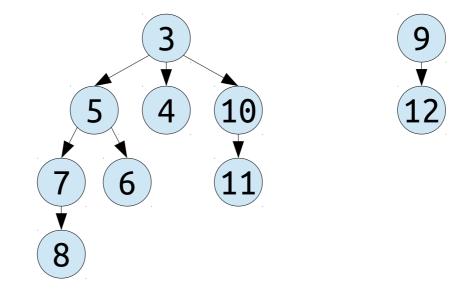


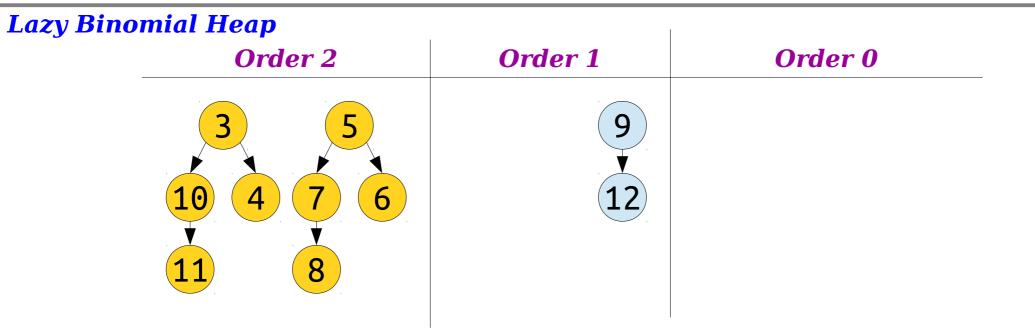


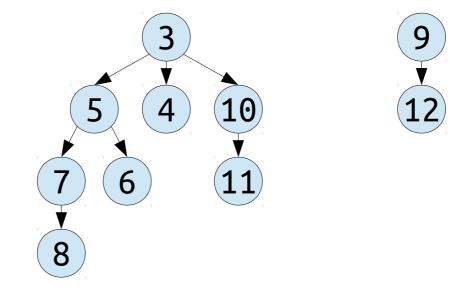


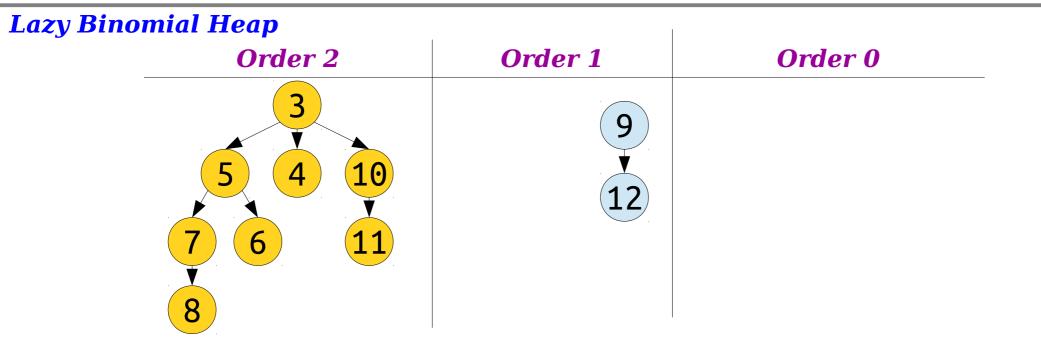


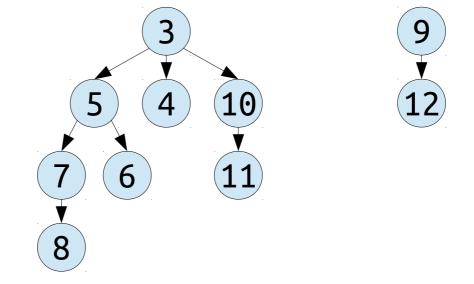




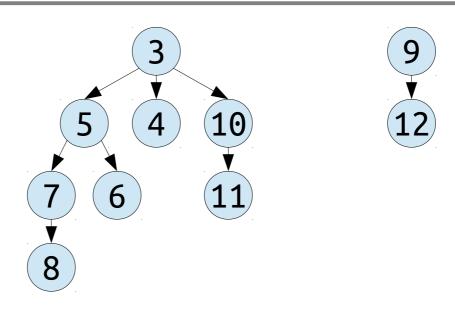








Lazy Binomial Heap



Operation Costs

- Eager Binomial Heap:
 - **enqueue**: O(log *n*)
 - *meld*: O(log *n*)
 - *find-min*: O(log *n*)
 - *extract-min*: O(log *n*)

- Lazy Binomial Heap:
 - **enqueue**: O(1)
 - **meld**: O(1)
 - **find-min**: O(1)
 - extract-min: $O(\log n)^*$
- *amortized

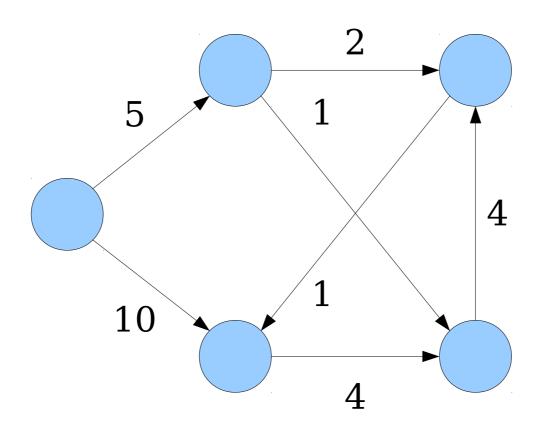
Intuition: Each extract-min has to do a bunch of cleanup for the earlier enqueue operations, but then leaves us with few trees.

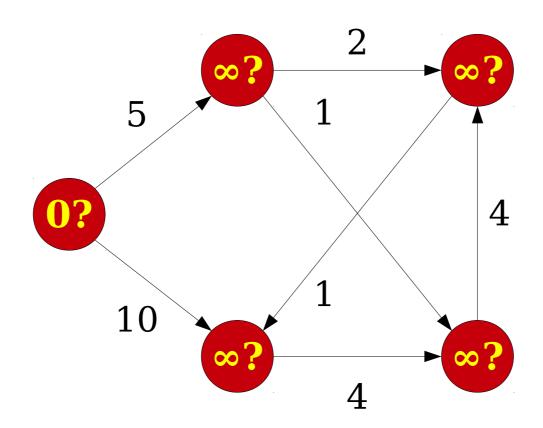
New Stuff!

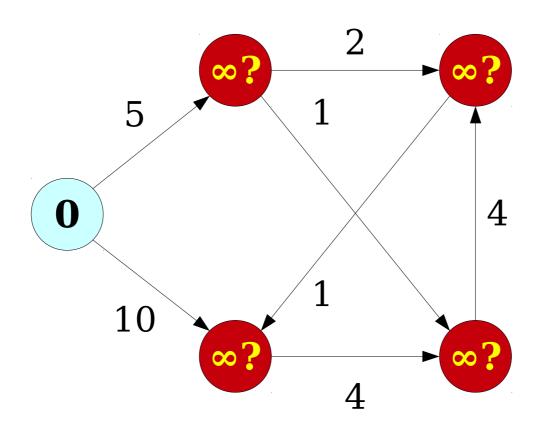
The Need for *decrease-key*

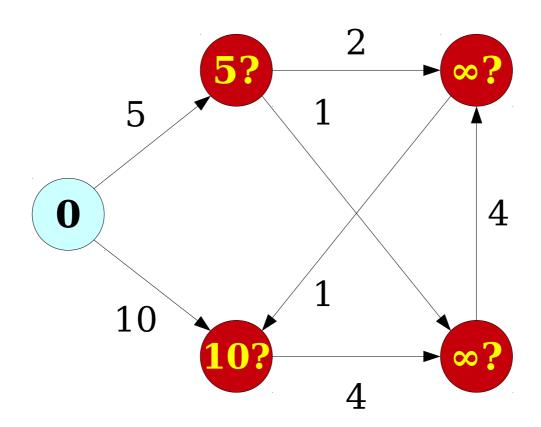
The decrease-key Operation

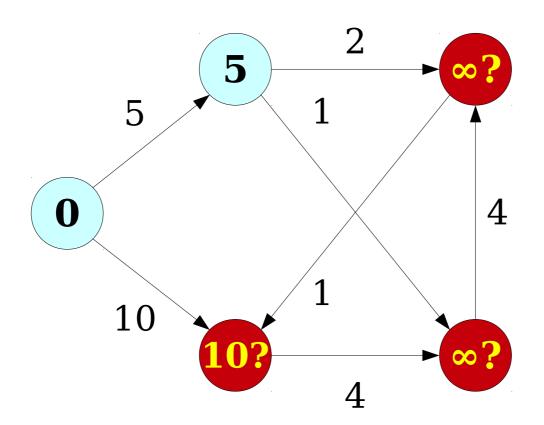
- Some priority queues support the operation decrease-key(v, k), which works as follows:
 - Given a pointer to an element v, lower its key (priority) to k. It is assumed that k is less than the current priority of v.
- This operation is crucial in efficient implementations of Dijkstra's algorithm and Prim's MST algorithm.

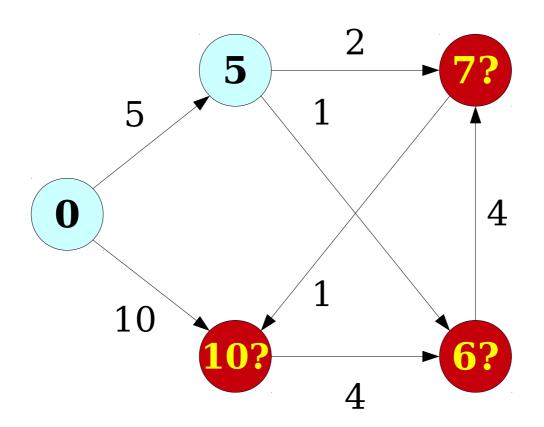


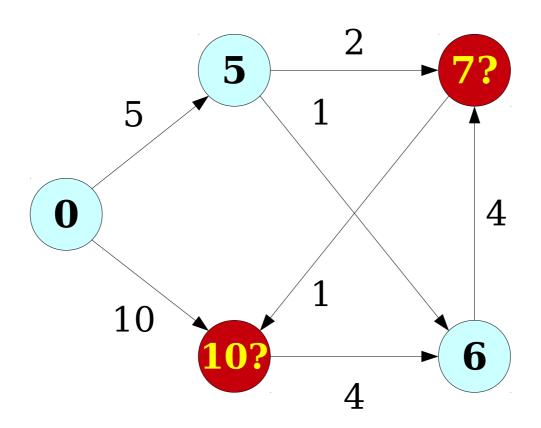


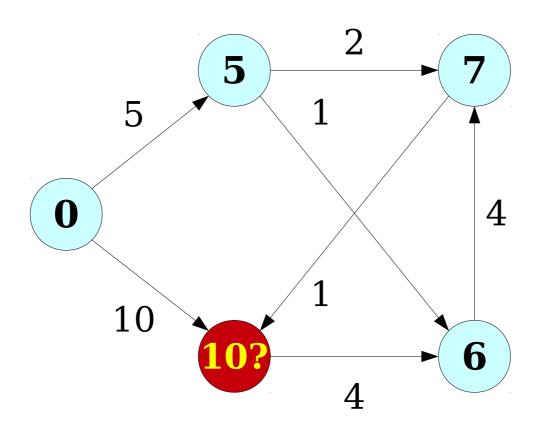


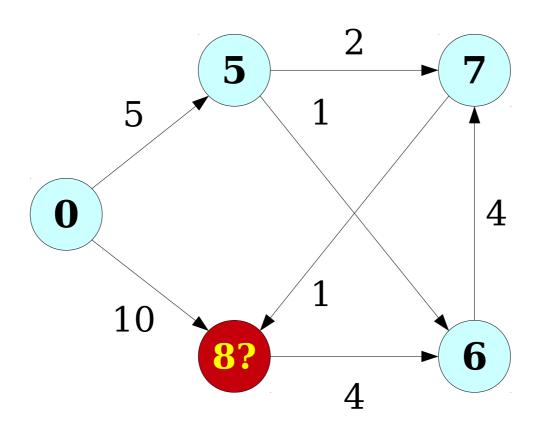


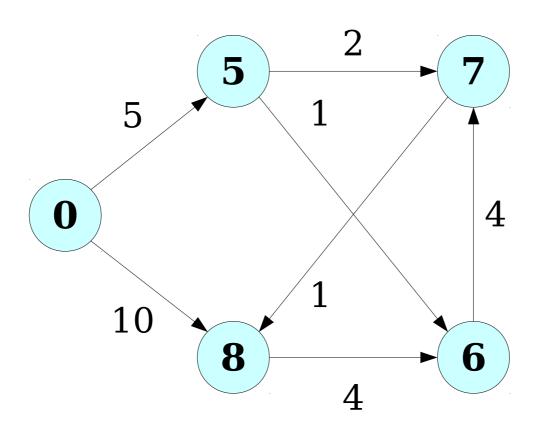






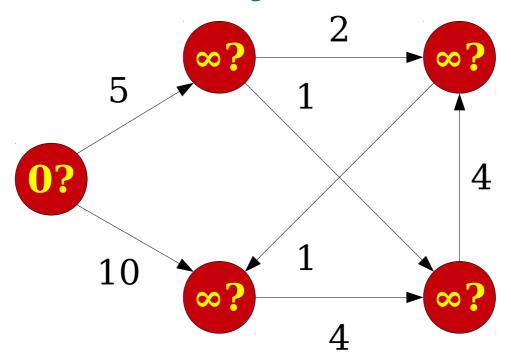




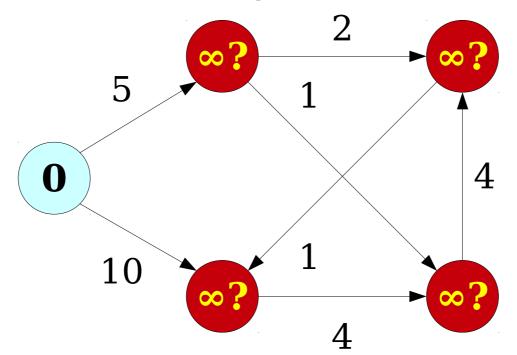


- Dijkstra's algorithm can be implemented with a priority queue using
 - O(n) total **enqueue**s,
 - O(n) total *extract-mins*, and
 - O(m) total **decrease-keys**.

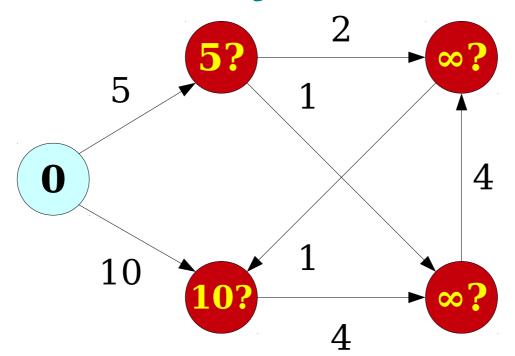
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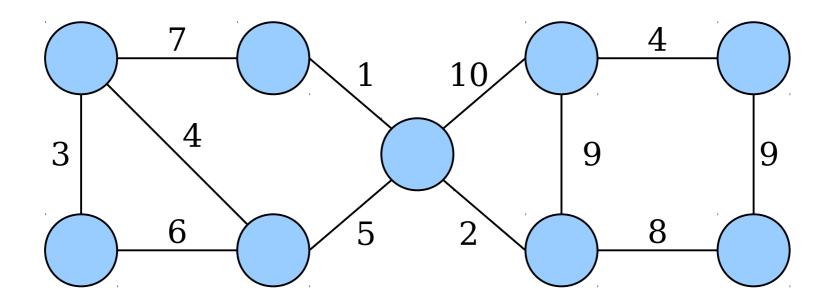


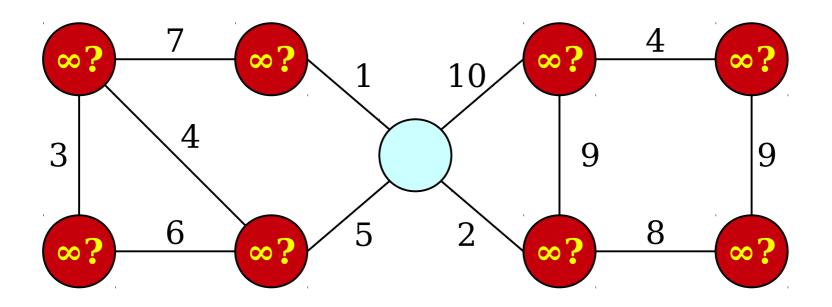
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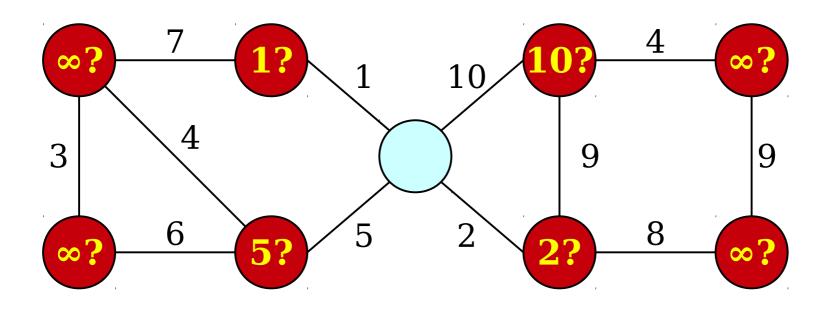


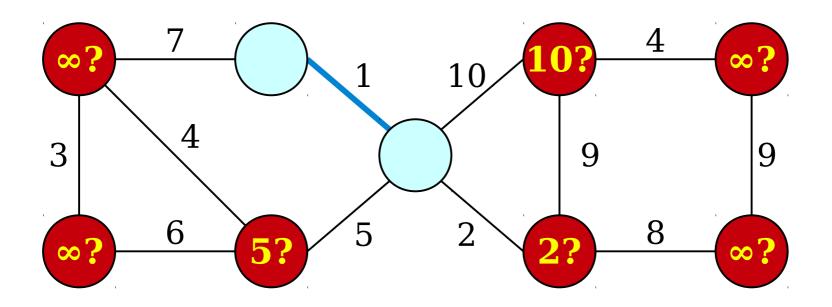
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- Dijkstra's algorithm runtime is

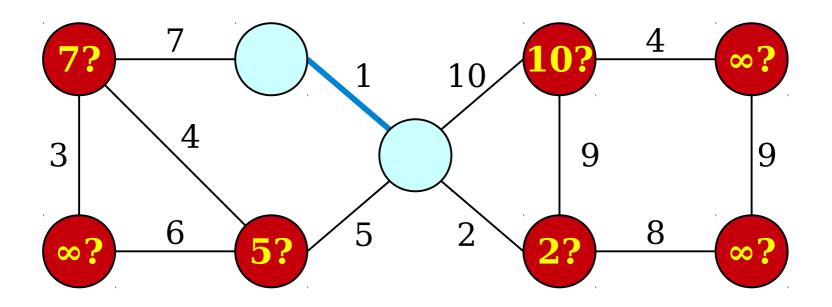
$$O(n T_{eng} + n T_{ext} + m T_{dec})$$

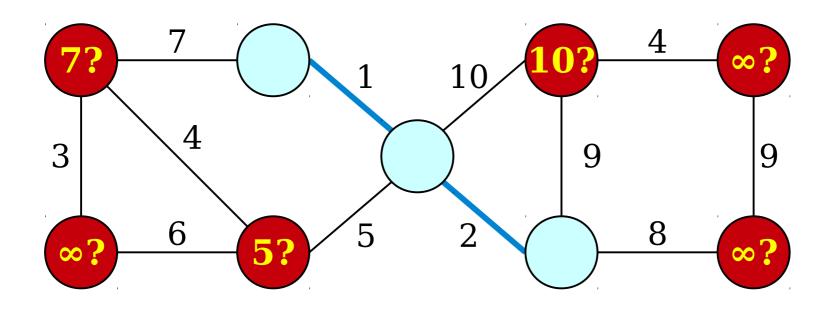


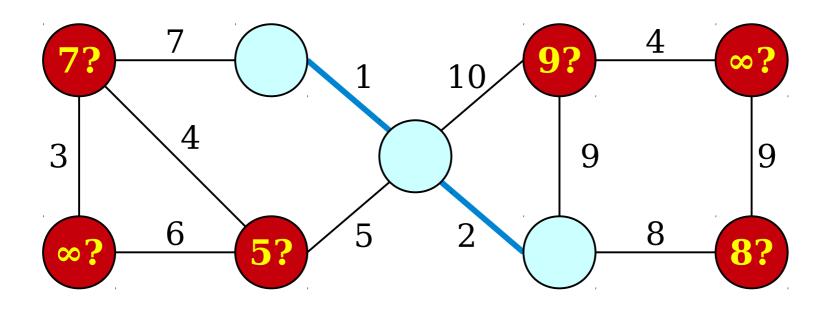


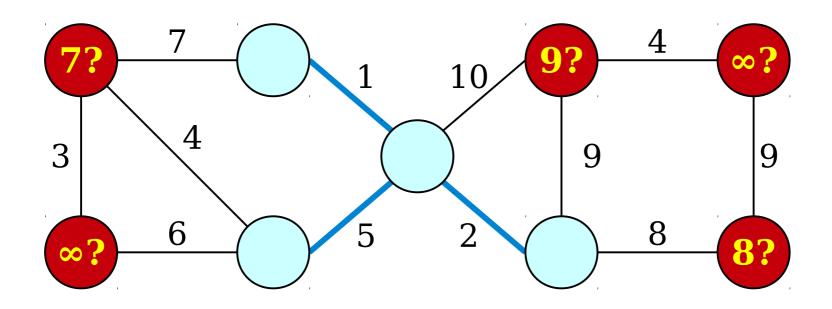


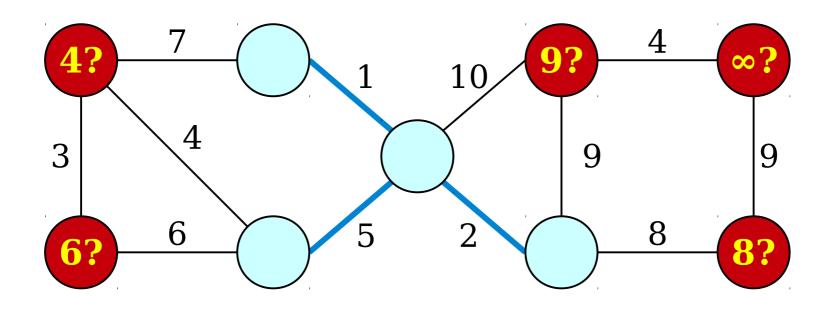


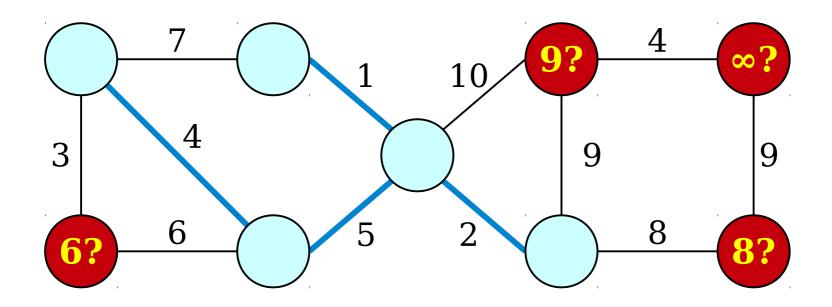


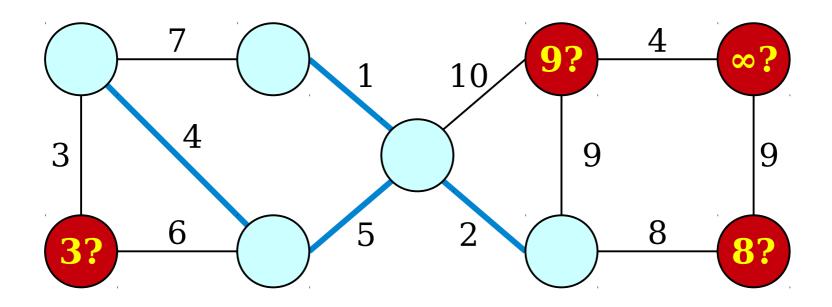


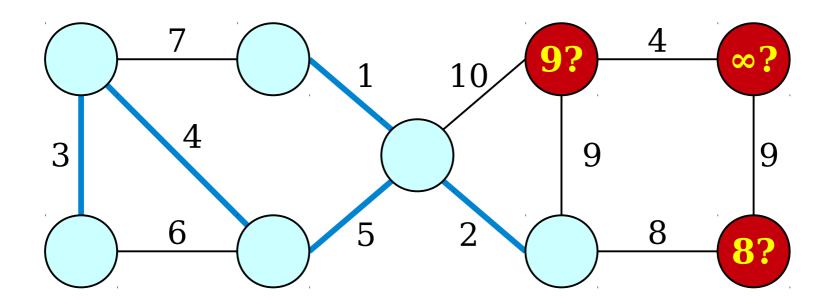


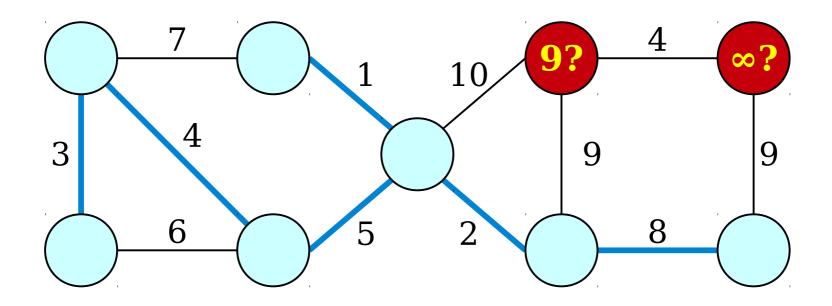


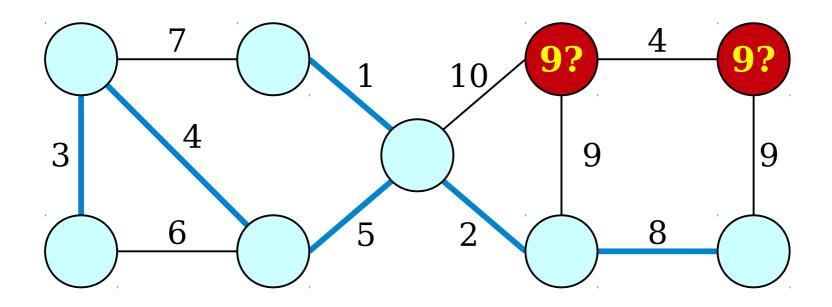


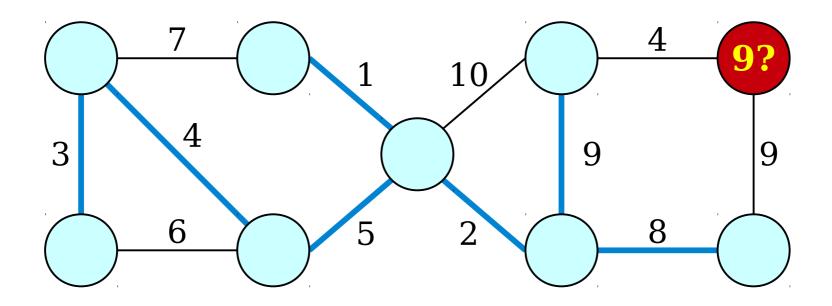


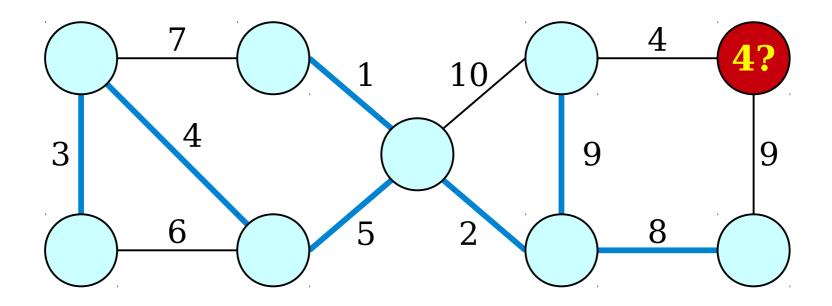


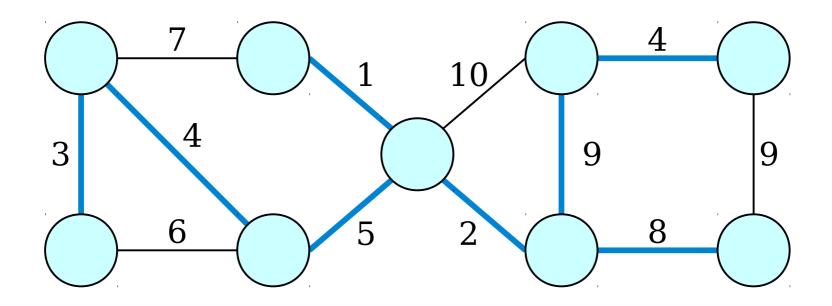






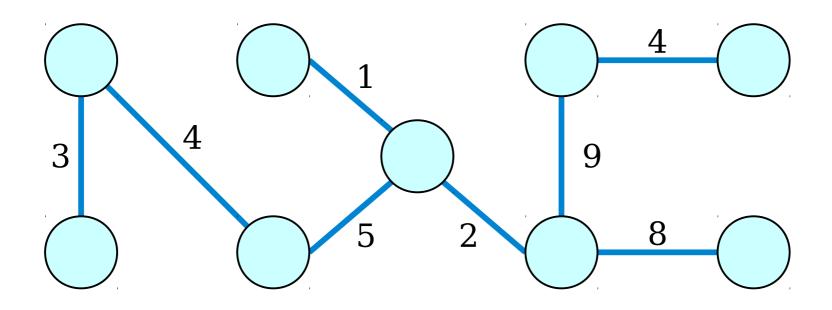






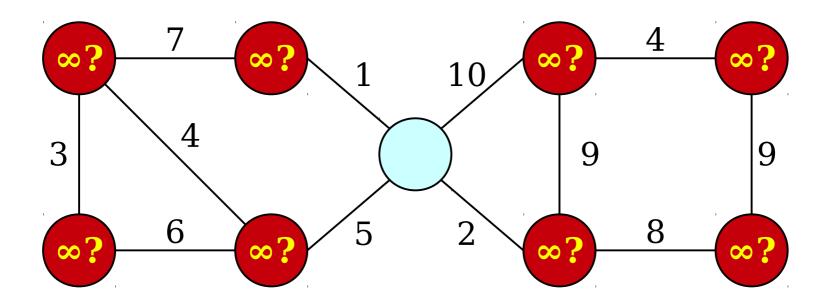
Review: Prim's Algorithm

• Prim's algorithm solves the minimum spanning tree (MST) problem in undirected graphs.

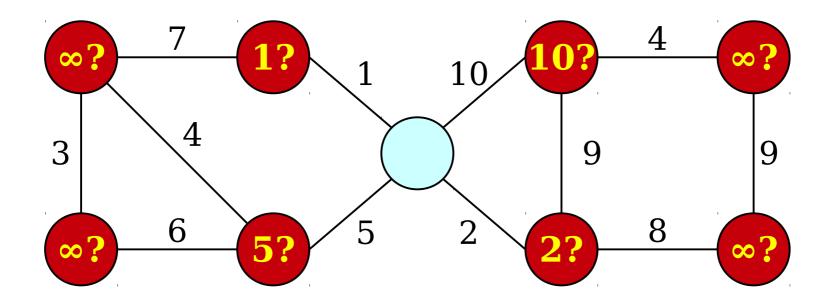


- Prim's algorithm can be implemented with a priority queue using
 - O(n) total **enqueue**s,
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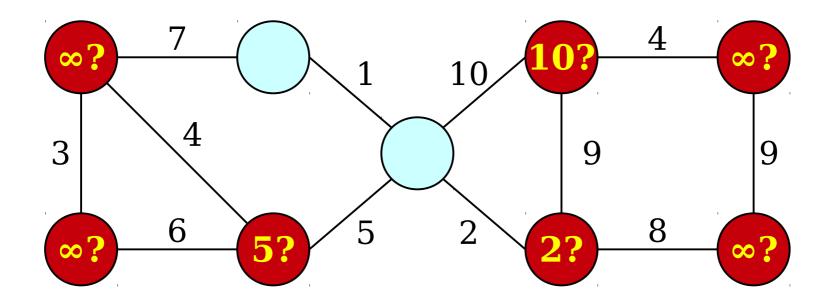
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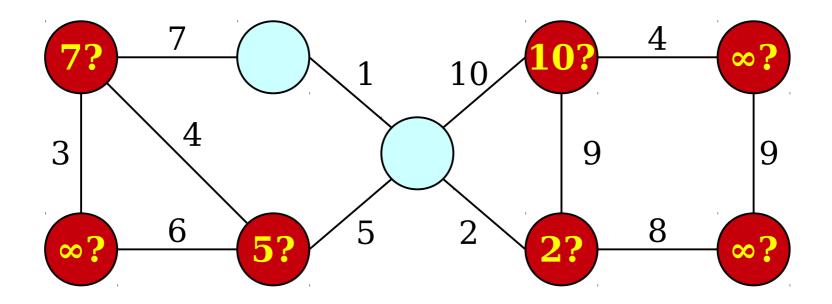
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 - O(m) total **decrease-keys**.
- Prim's algorithm runtime is

$$O(n T_{eng} + n T_{ext} + m T_{dec})$$

Standard Approaches

- In a binary heap, enqueue, extract-min, and decrease-key can be made to work in time O(log n) time each.
- Cost of Dijkstra's / Prim's algorithm:

$$O(n T_{enq} + n T_{ext} + m T_{dec})$$

- $= O(n \log n + n \log n + m \log n)$
- $= O(m \log n)$

Standard Approaches

- In a lazy binomial heap, *enqueue* takes amortized time O(1), and *extract-min* and *decrease-key* take amortized time $O(\log n)$.
- Cost of Dijkstra's / Prim's algorithm:

$$O(n T_{enq} + n T_{ext} + m T_{dec})$$

- $= O(n + n \log n + m \log n)$
- $= O(m \log n)$

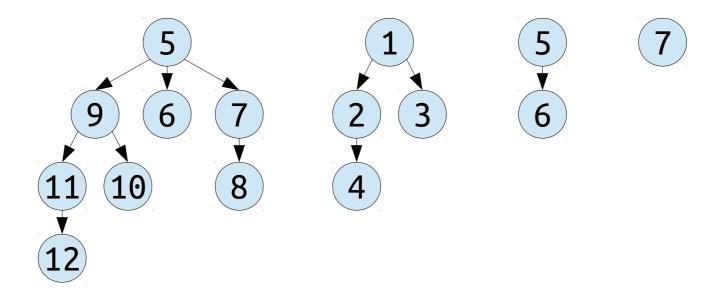
Where We're Going

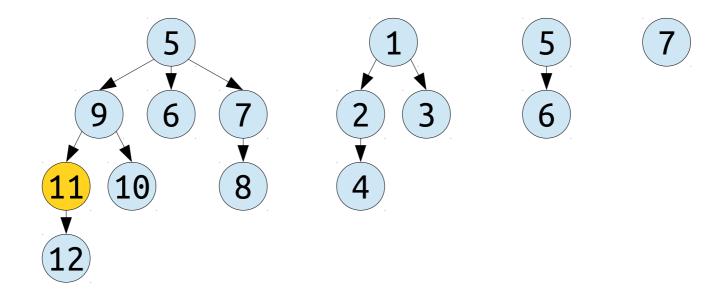
- The *Fibonacci heap* has these amortized runtimes:
 - **enqueue**: O(1)
 - *extract-min*: O(log *n*).
 - *decrease-key*: O(1).
- Cost of Prim's or Dijkstra's algorithm:

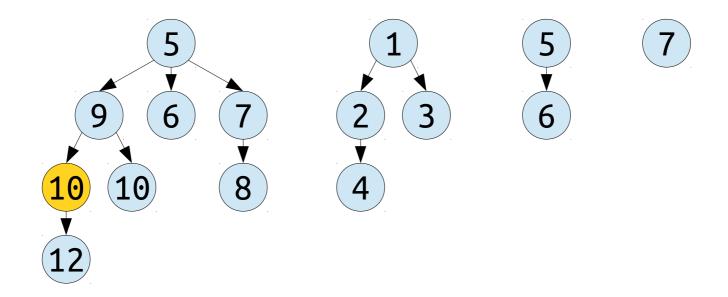
$$O(n T_{enq} + n T_{ext} + m T_{dec})$$

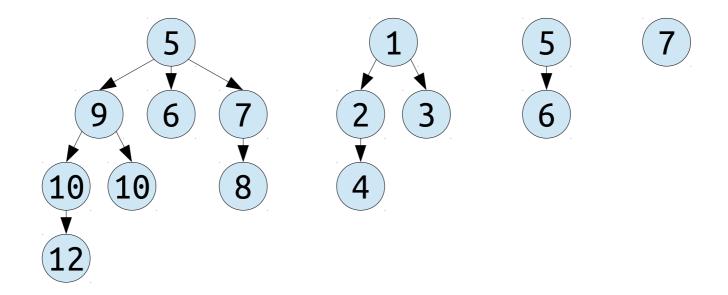
- $= O(n + n \log n + m)$
- $= O(m + n \log n)$
- This is theoretically optimal for a comparison-based priority queue in Dijkstra's or Prim's algorithms.

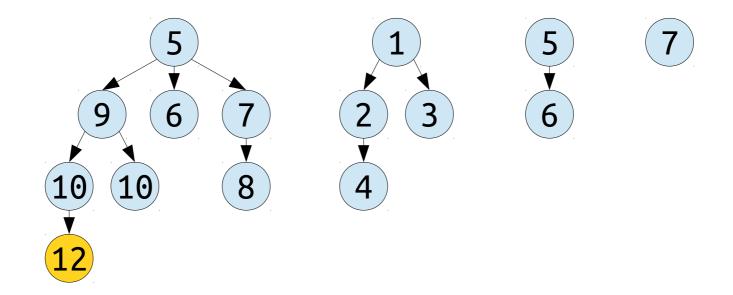
The Challenge of *decrease-key*

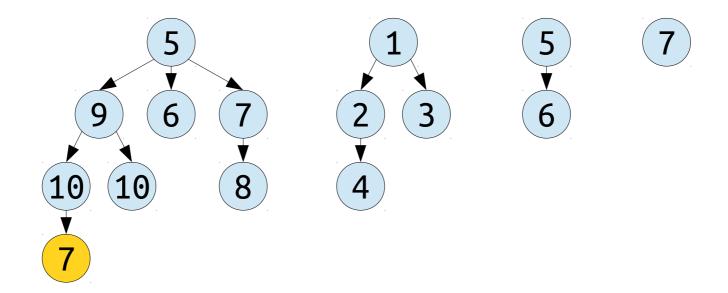


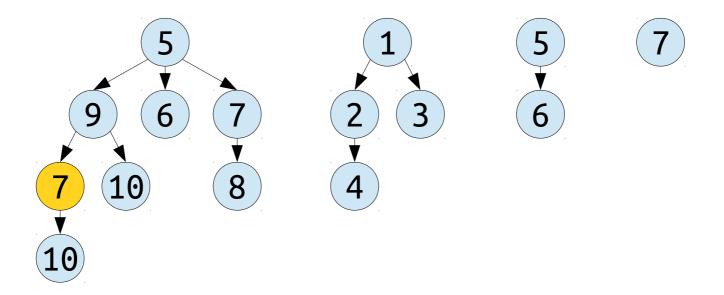


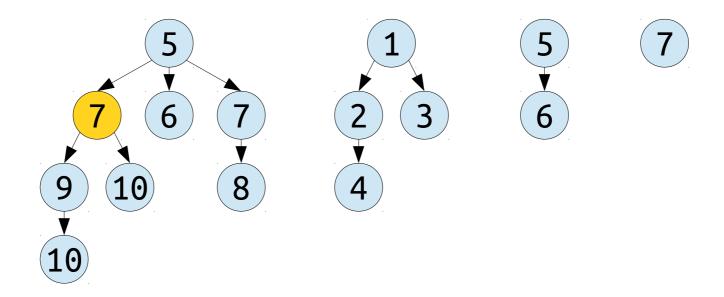


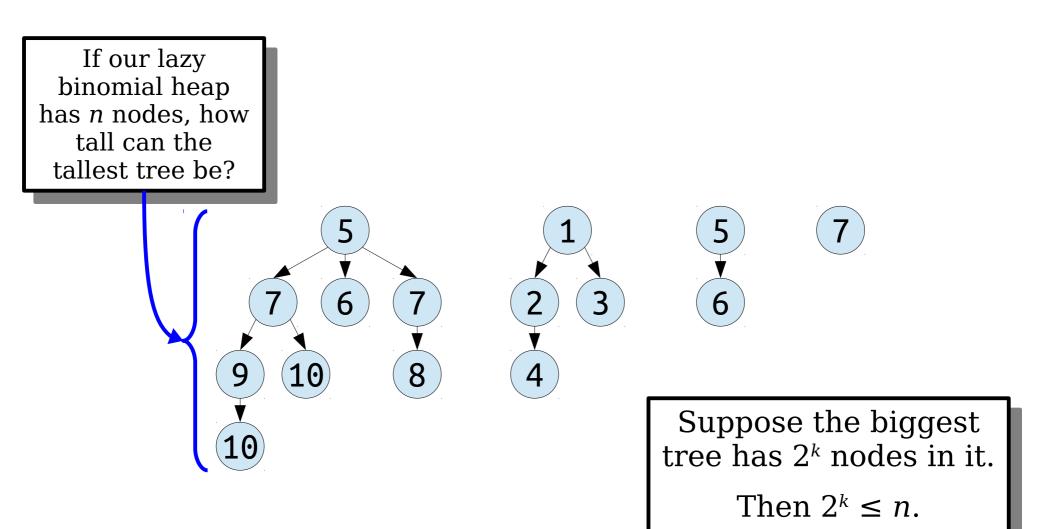




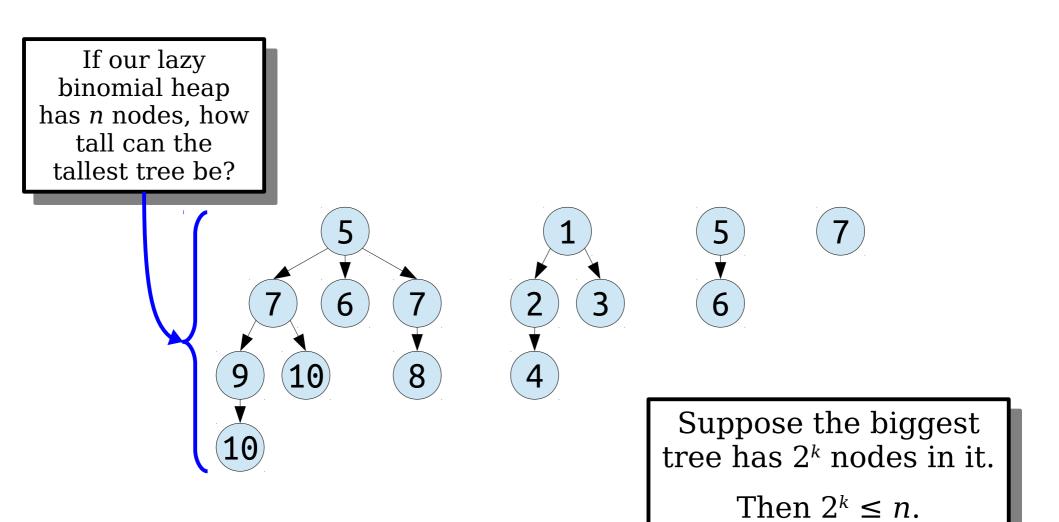






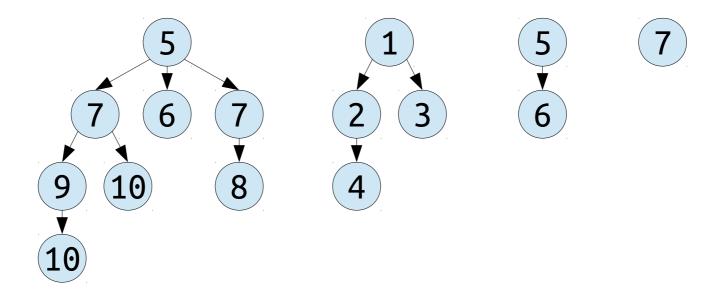


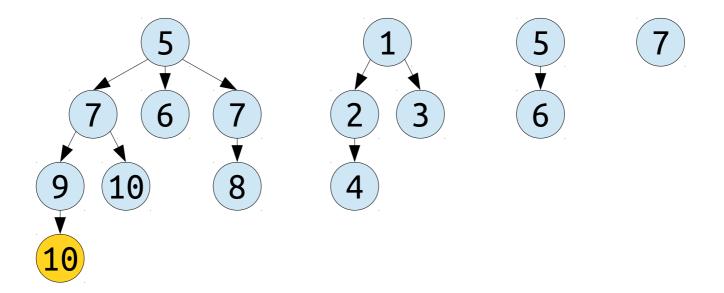
So $k = O(\log n)$.

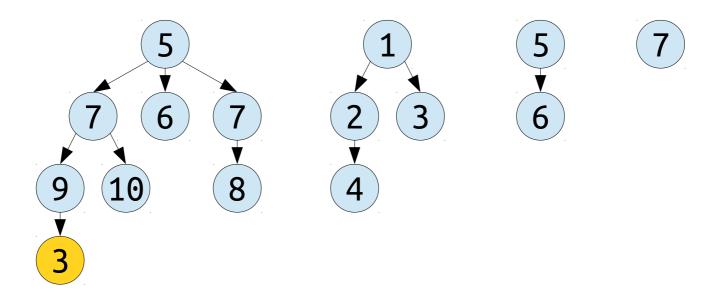


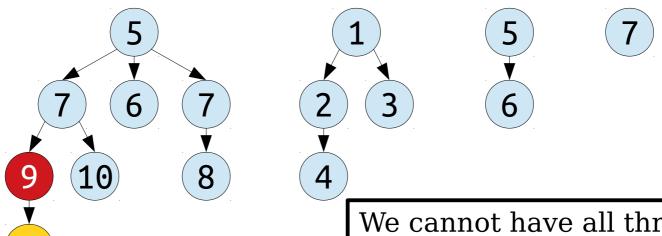
Challenge: Support **decrease-key** in (amortized) time O(1).

So $k = O(\log n)$.





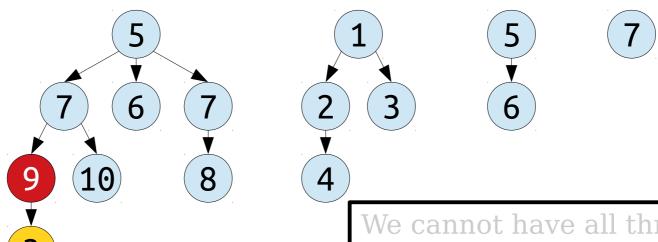




We cannot have all three of these nice properties at once:

- 1. decrease-key takes time O(1).
- 2. Our trees are heap-ordered.
- 3. Our trees are binomial trees.

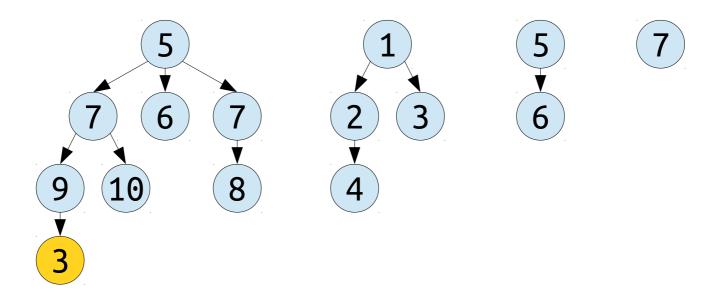
Challenge: Support **decrease-key** in (amortized) time O(1).

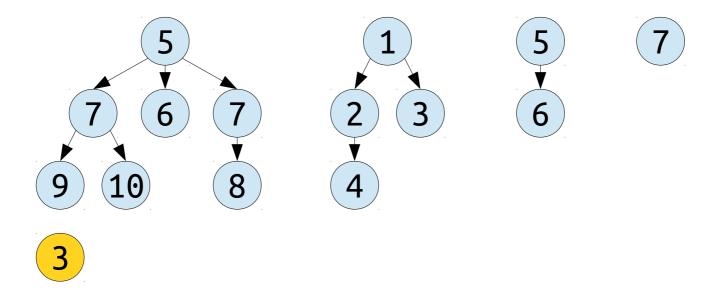


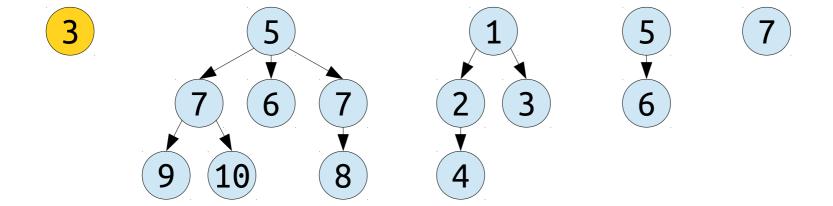
We cannot have all three of these nice properties at once:

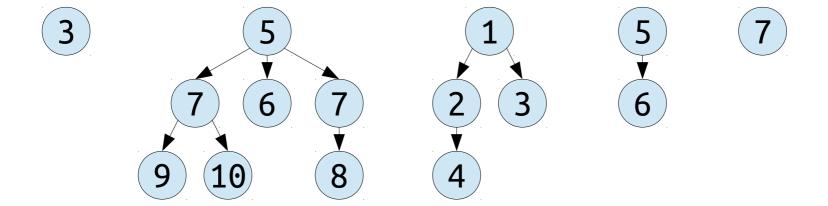
- 1. decrease-key takes time O(1).
- 2. Our trees are heap-ordered.
- 3. Our trees are binomial trees.

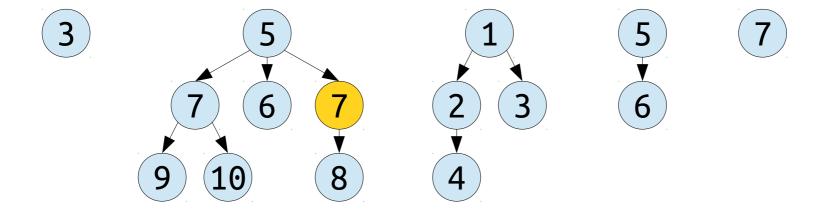
Challenge: Support **decrease-key** in (amortized) time O(1).

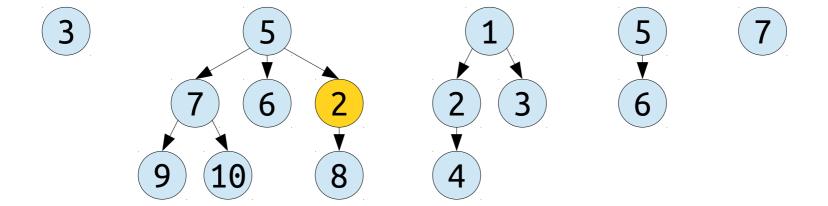


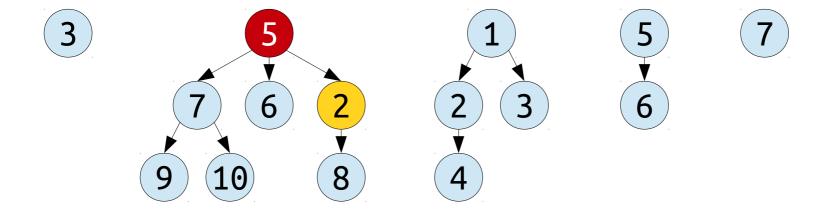


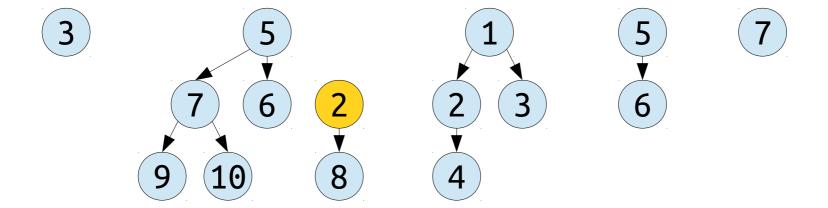


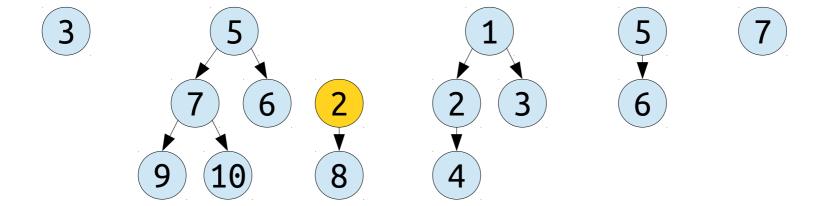


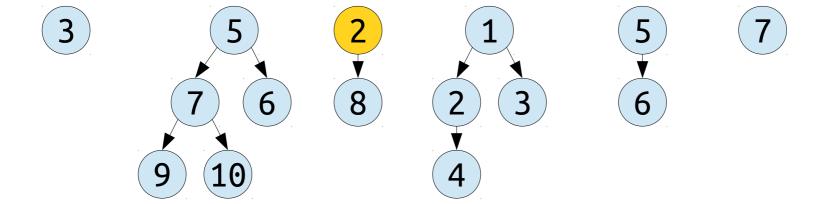


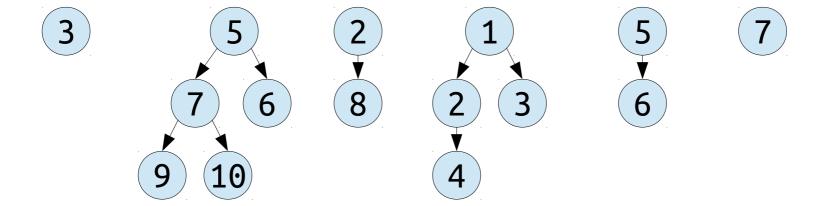


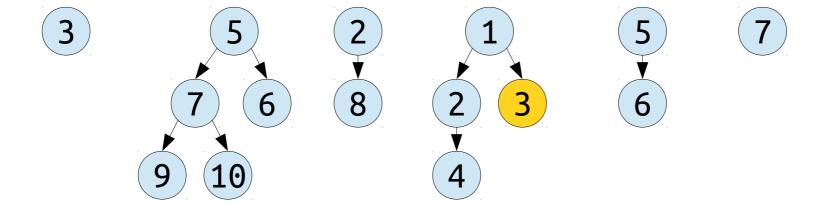


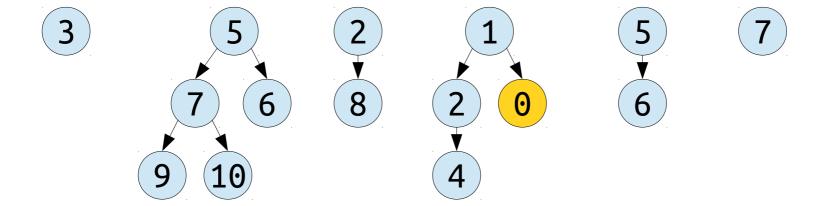


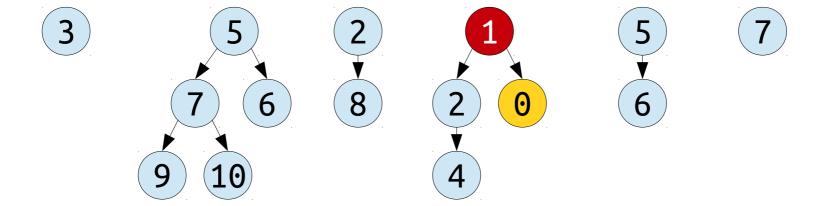


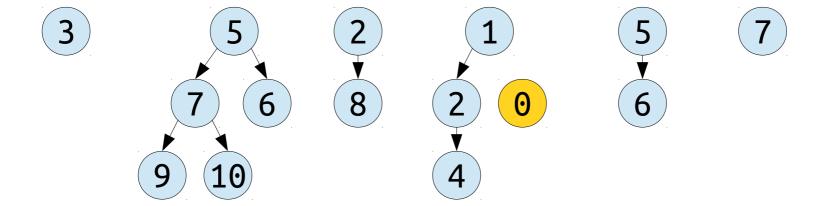


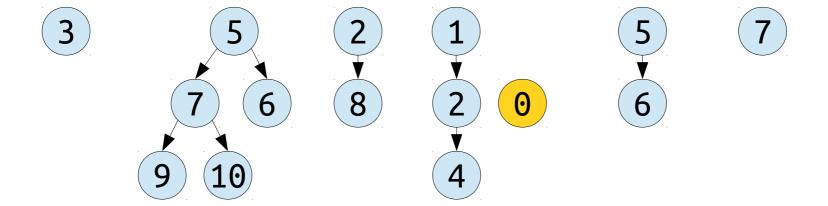


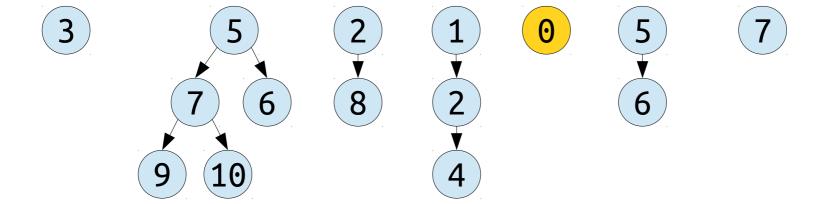


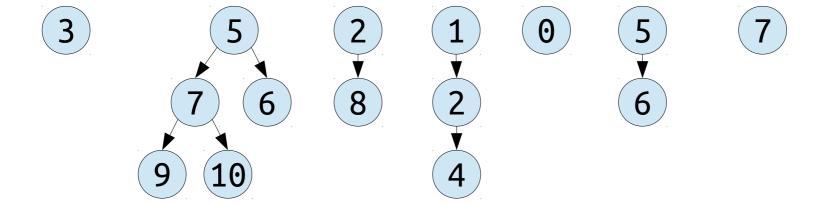


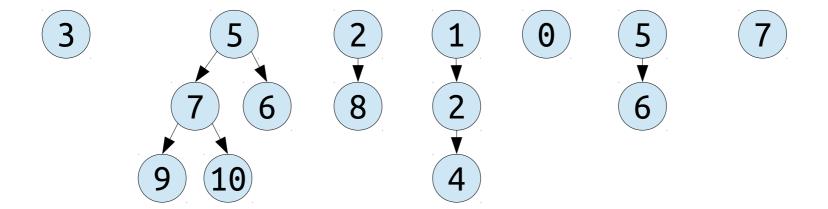


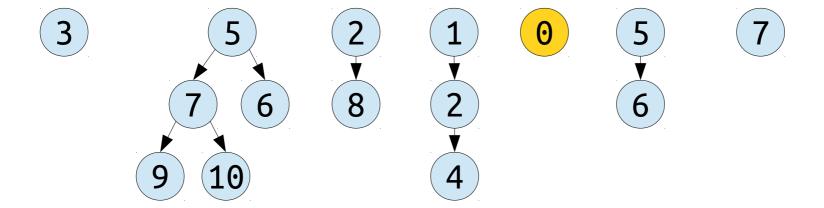


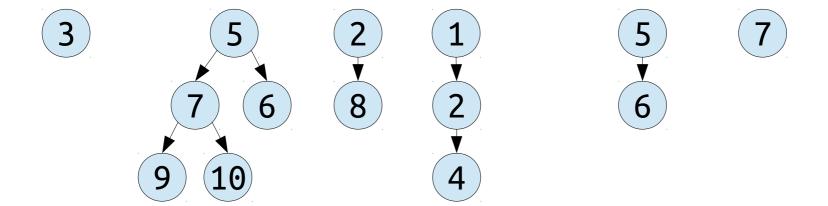


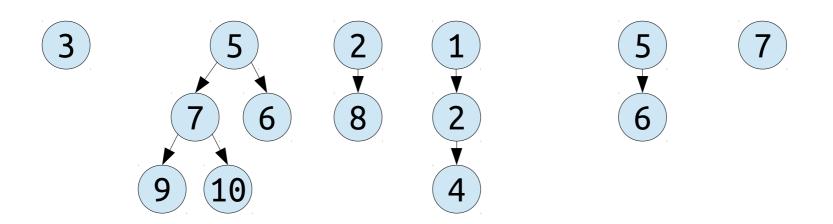


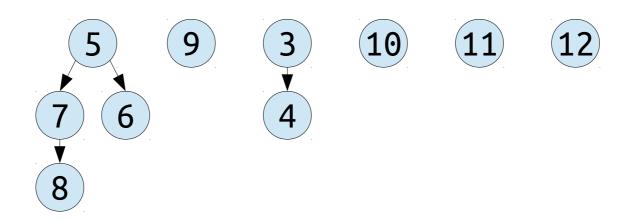


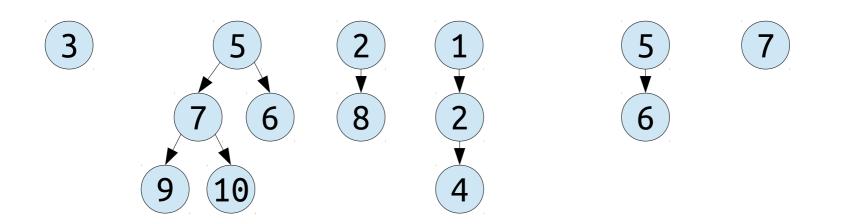




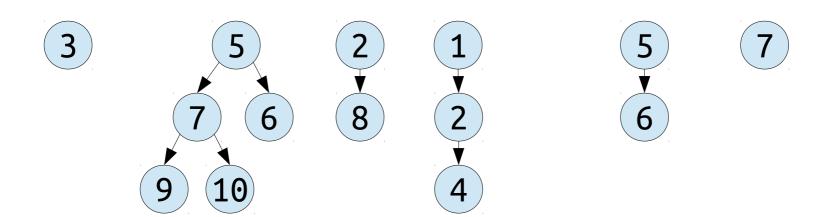




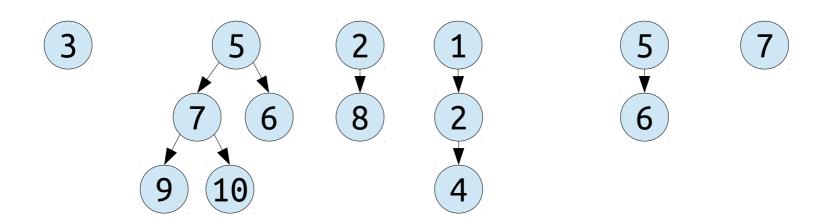




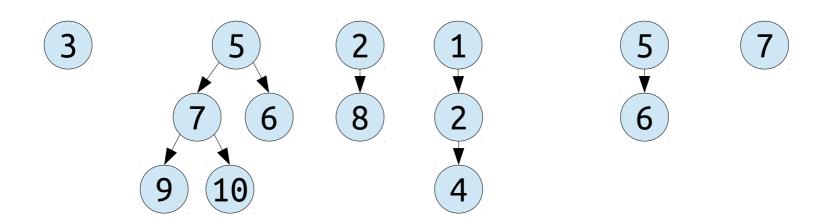
Order 2	Order 1	Order 0
5 7 6	3	9 10 11 12

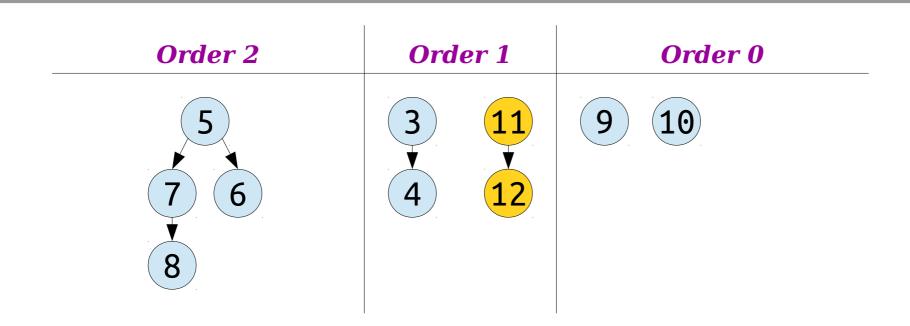


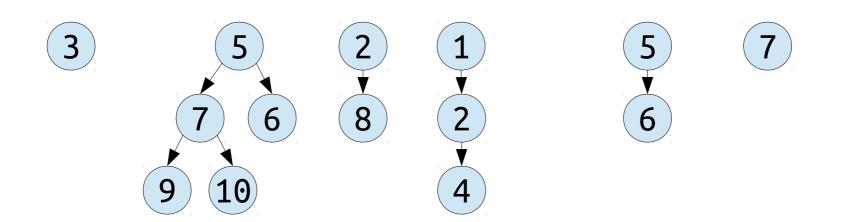
Order 2	Order 1	Order 0
5 7 6	3 4	9 10 11 12



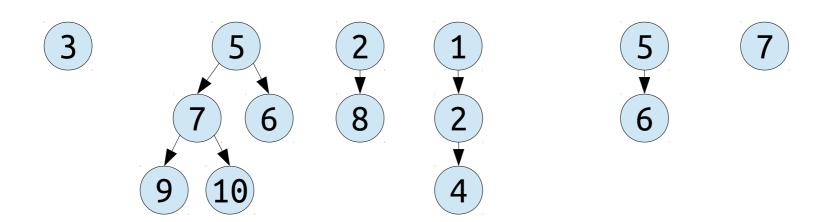
Order 2	Order 1	Order 0
5 7 6	4	9 10 11 12



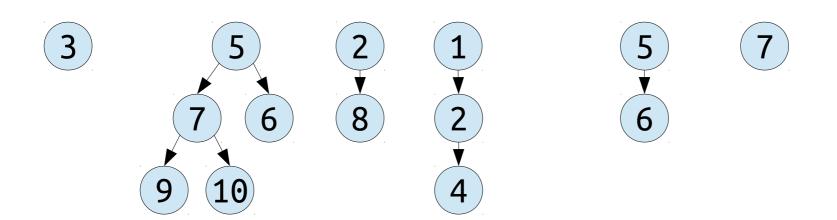


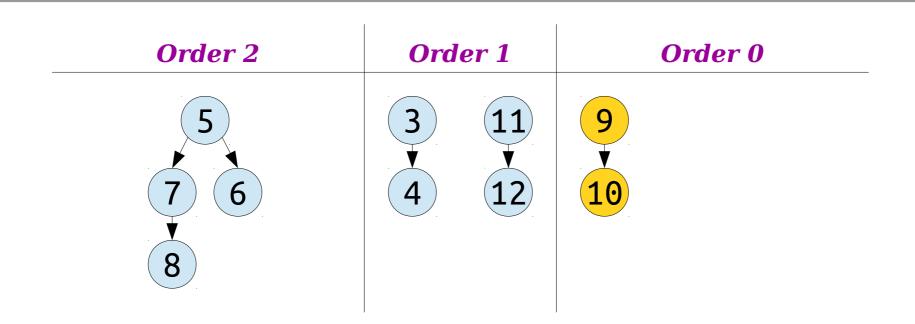


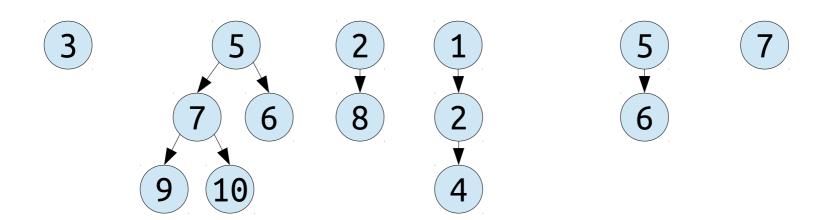
Order 2	Order 1	Order 0
5768	3 11 4 12	9 10

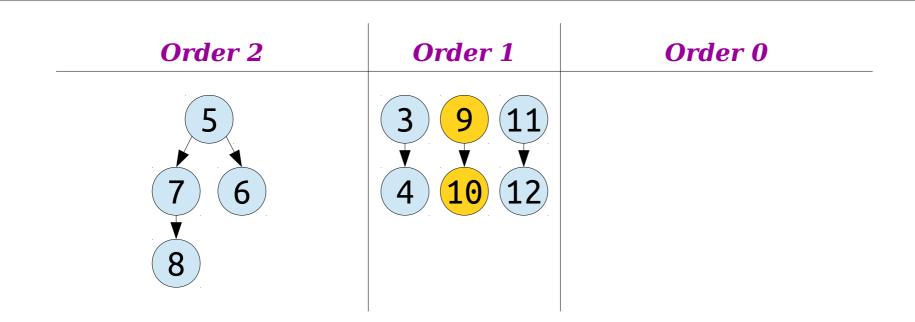


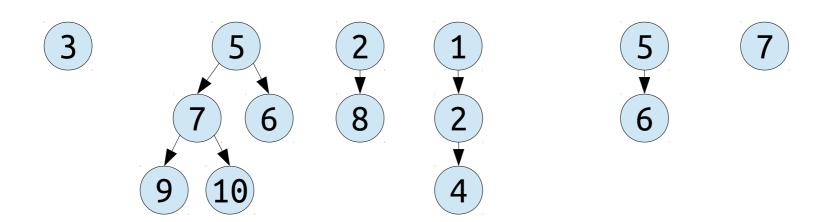
Order 2	Order 1	Order 0
5 7 6	3 11 4 12	9 10

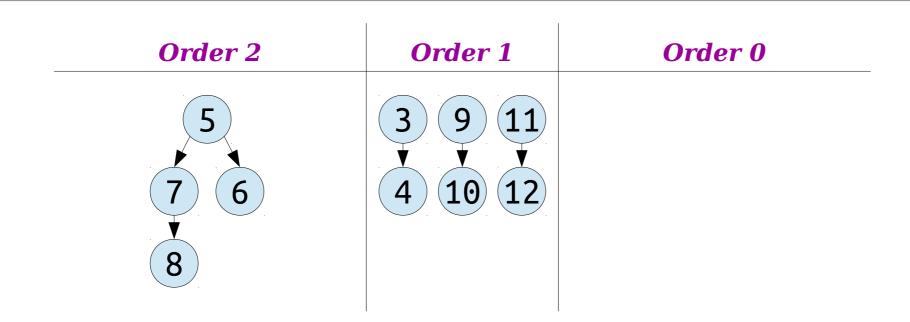


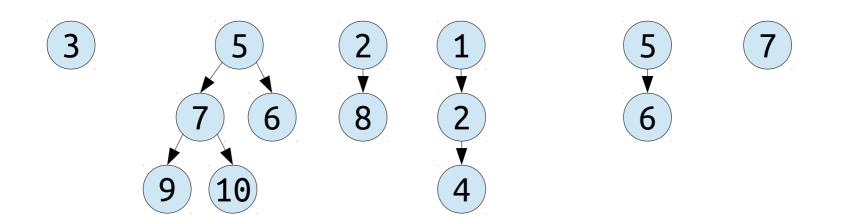


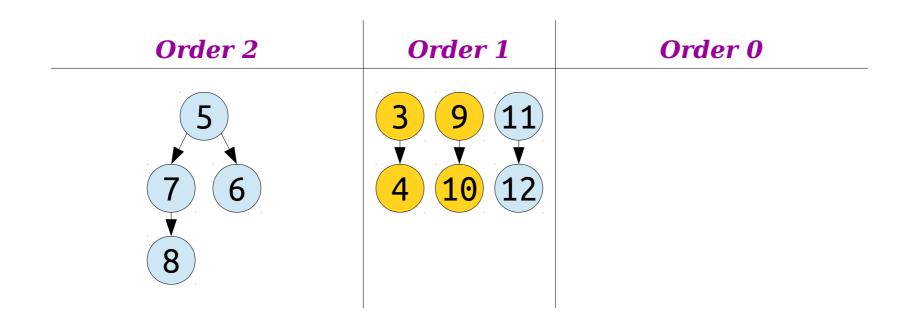


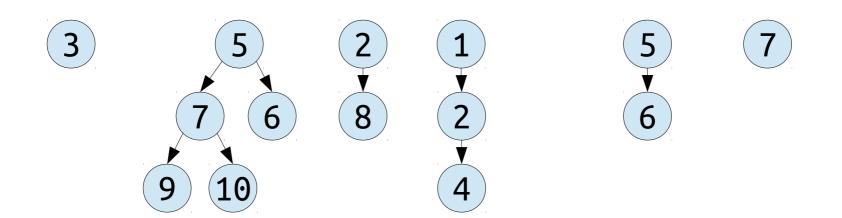


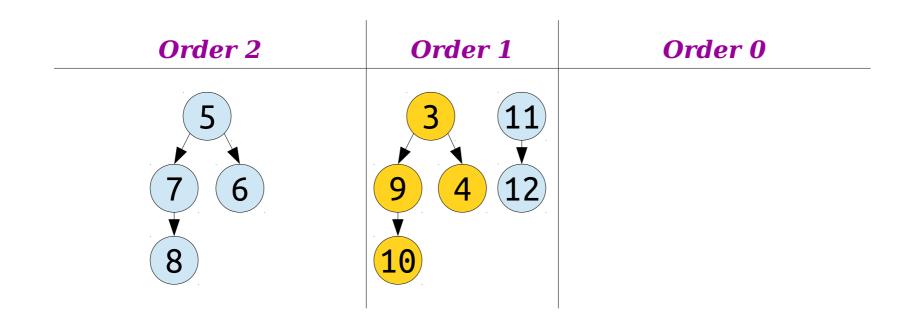


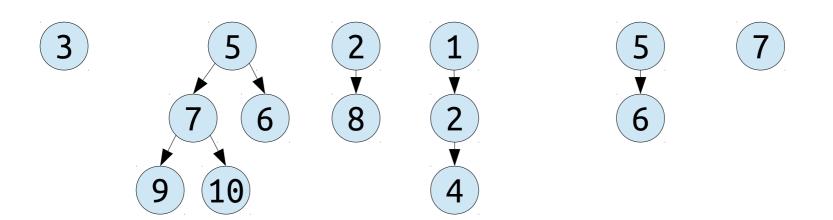


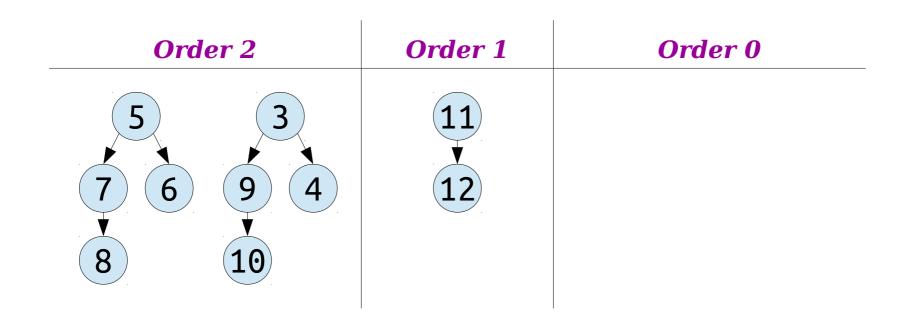


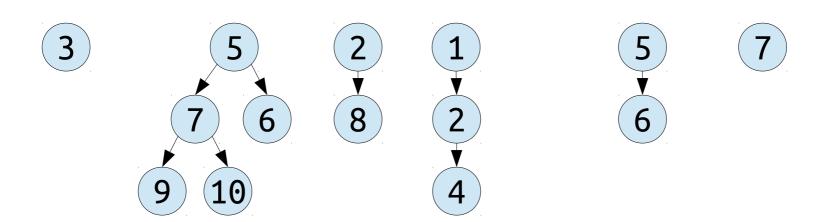


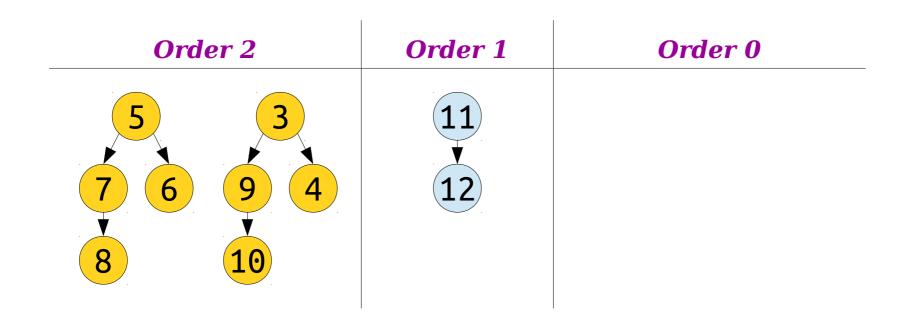


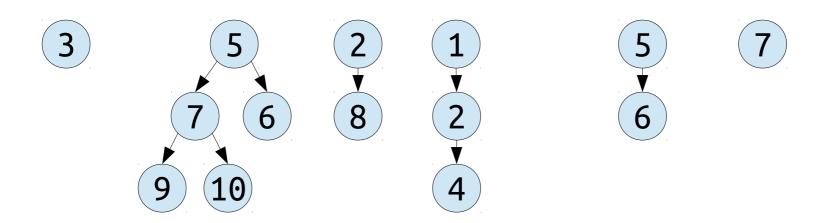


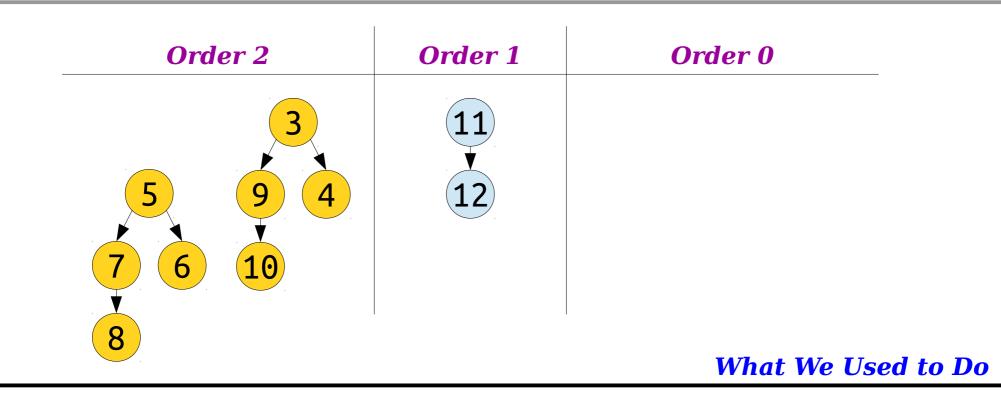


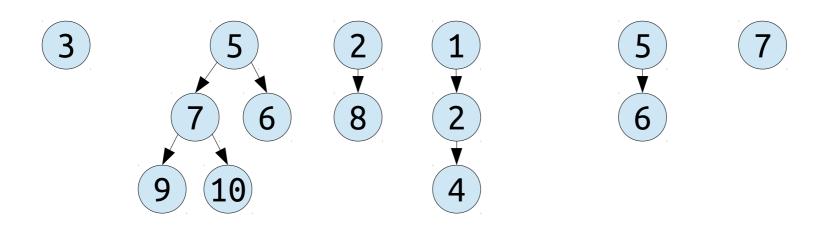


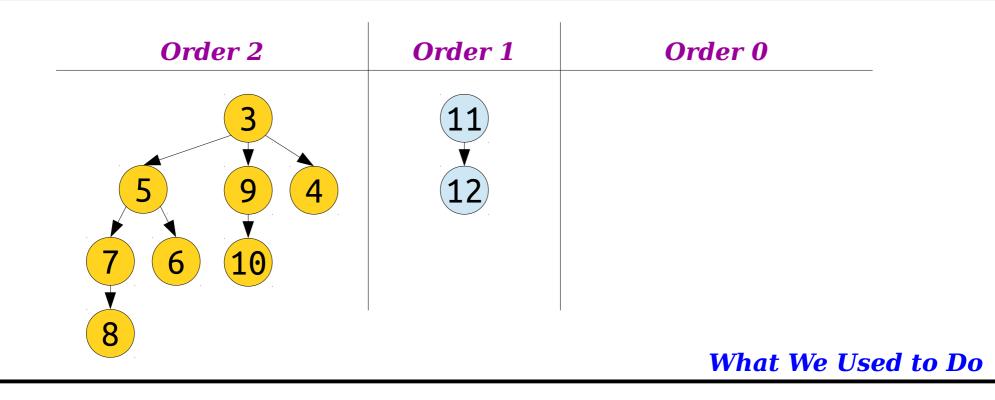


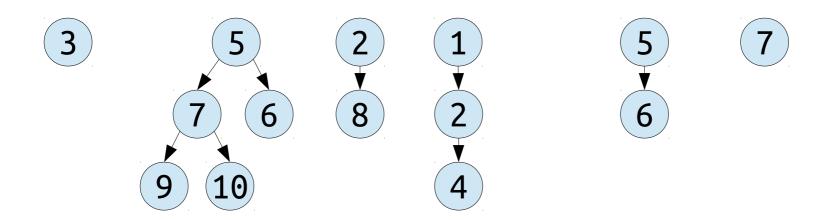


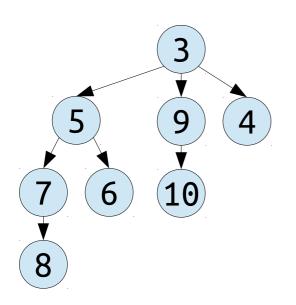


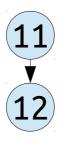












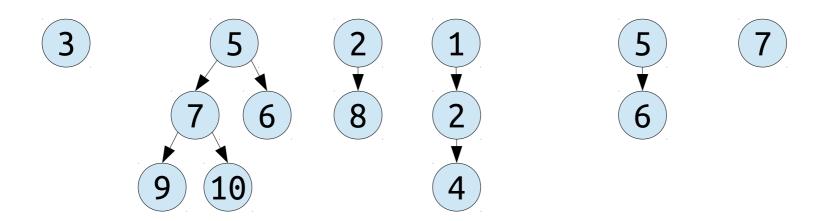
This system assumes we can assign an "order" to each tree.

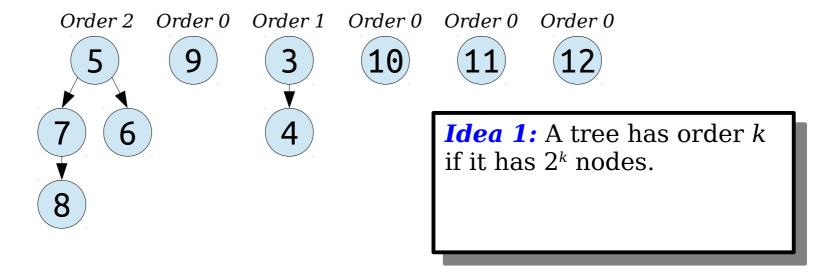
That's easy with binomial trees.

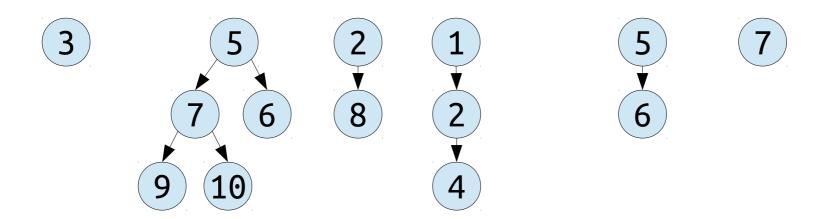
That's harder with our new trees.

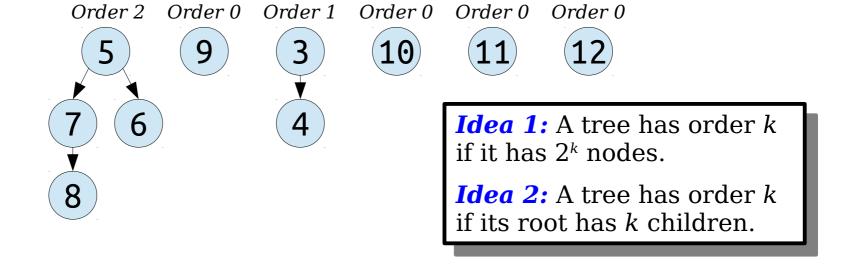
What should we do here?

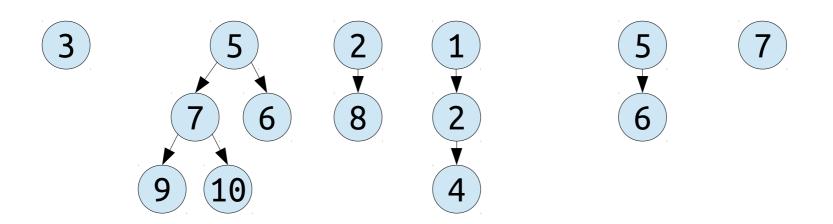
What We Used to Do

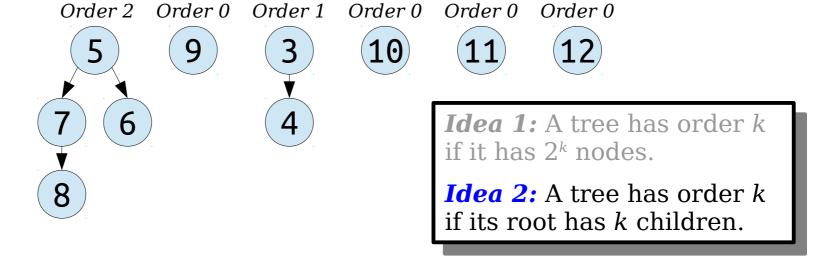


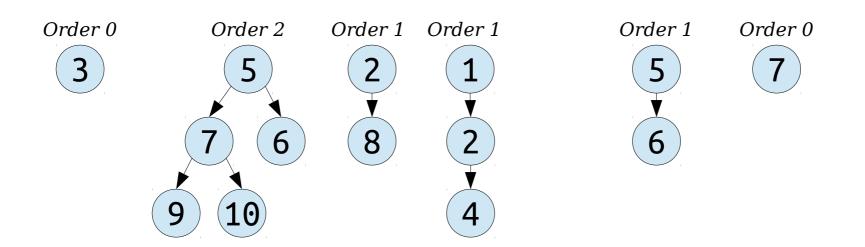


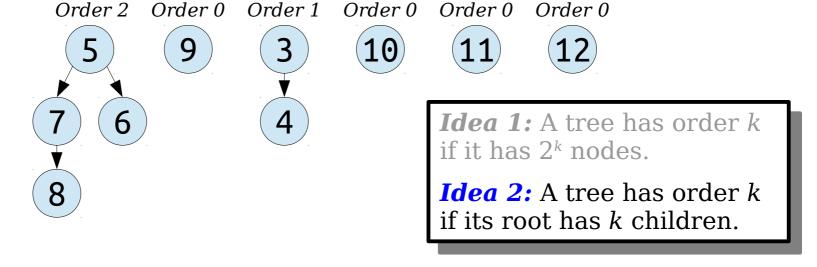


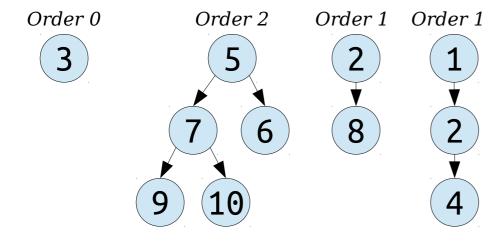


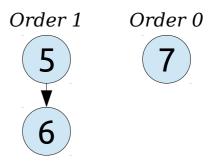






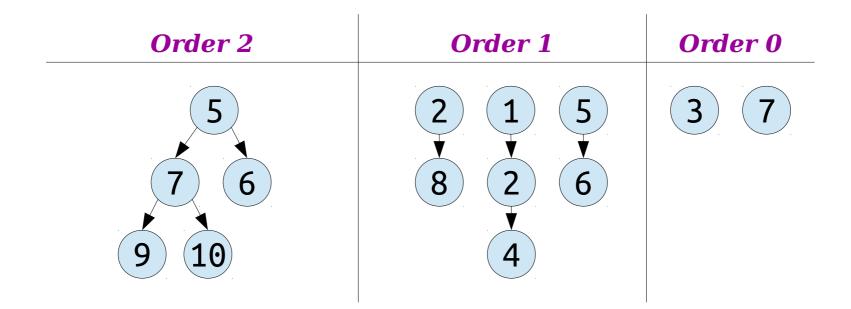


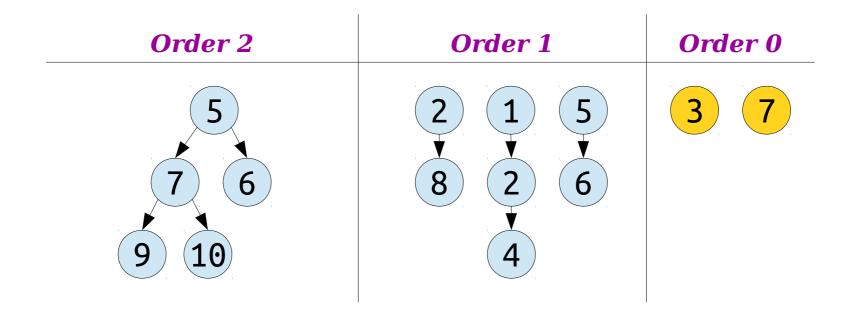


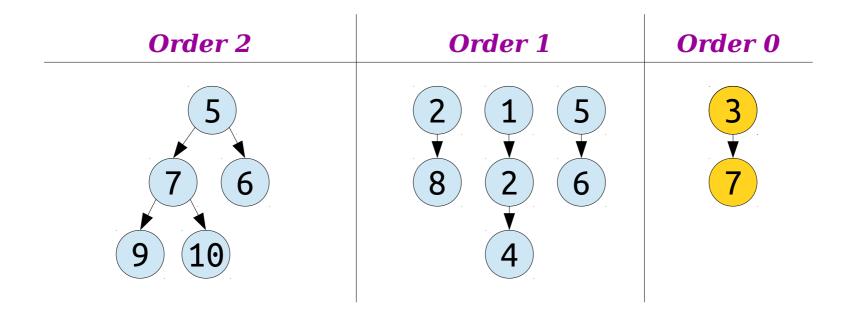


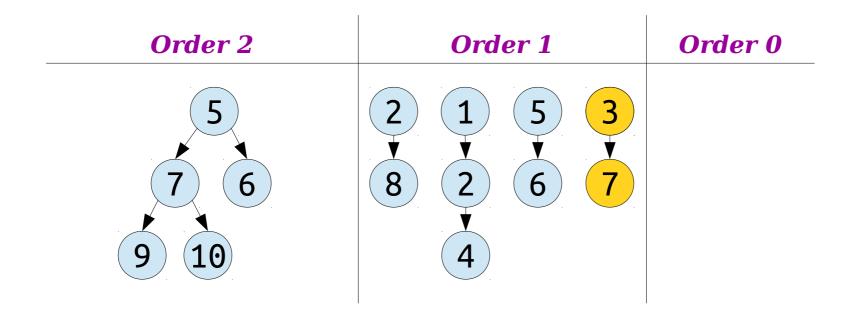
Idea 1: A tree has order k if it has 2^k nodes.

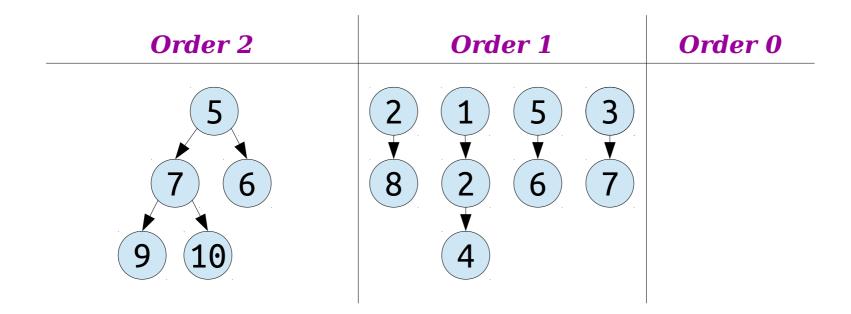
Idea 2: A tree has order *k* if its root has *k* children.

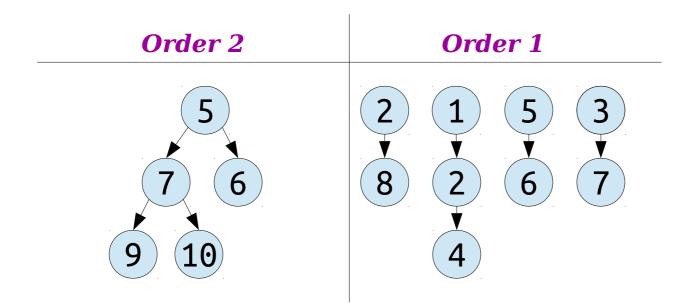


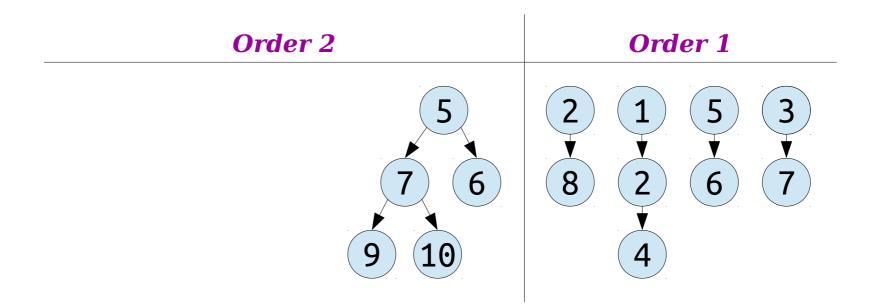


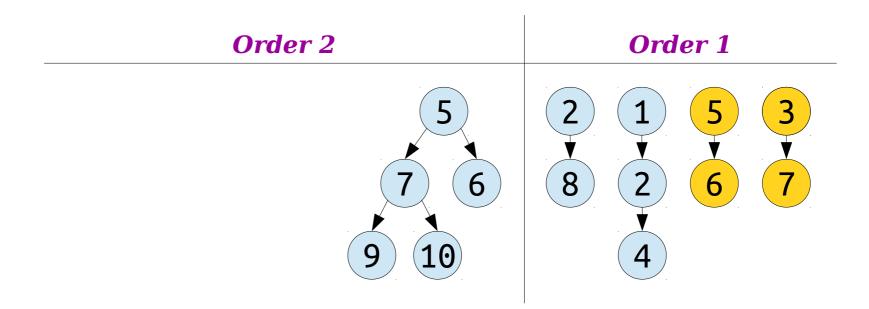


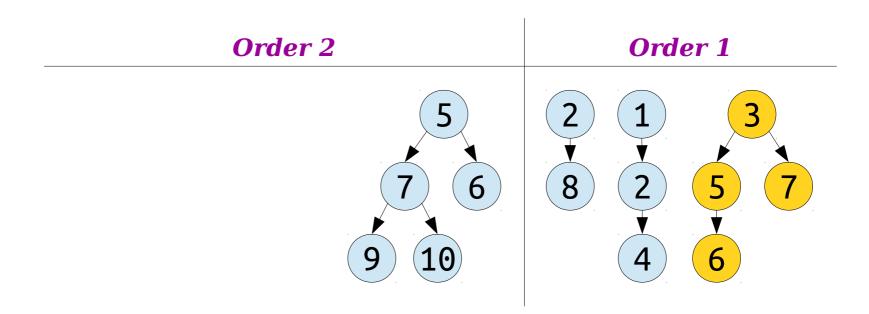


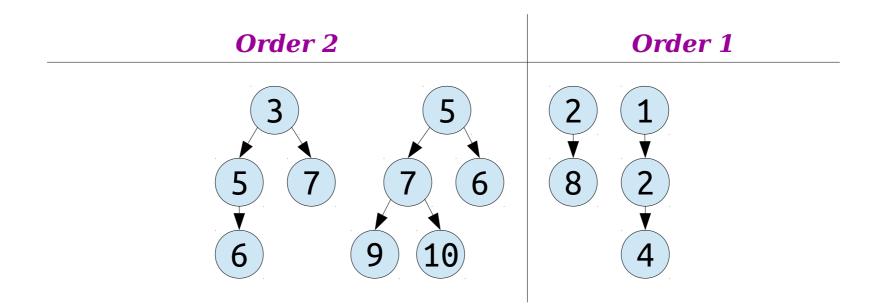


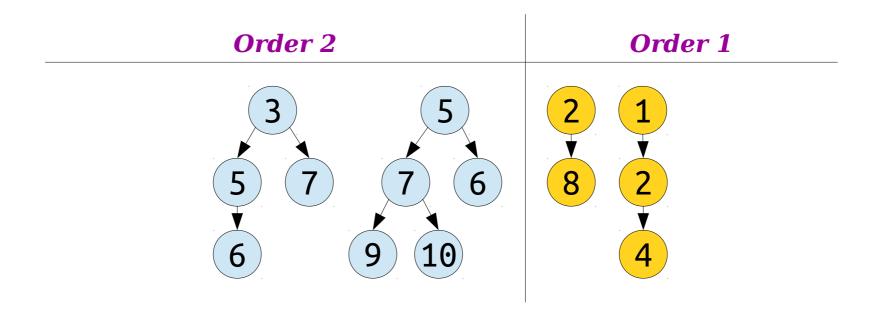


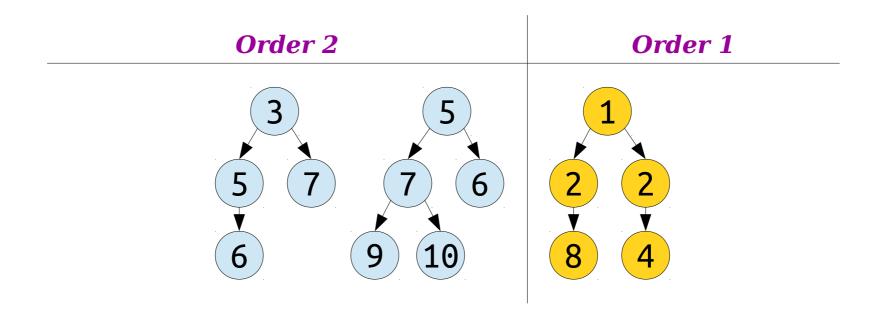


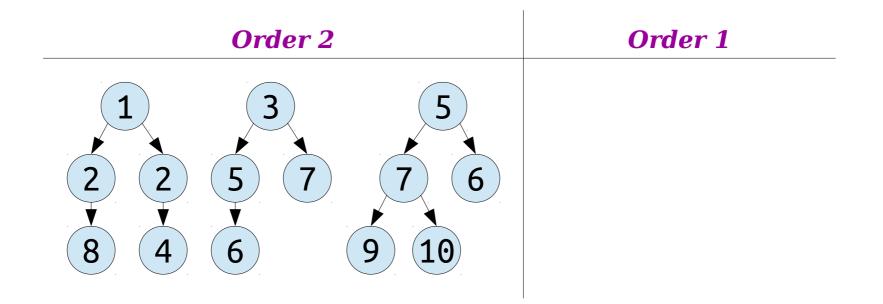




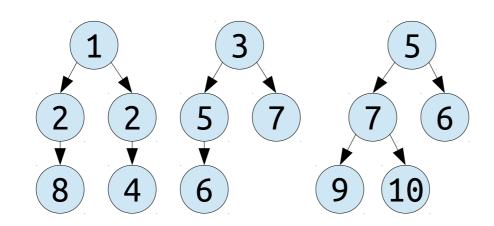


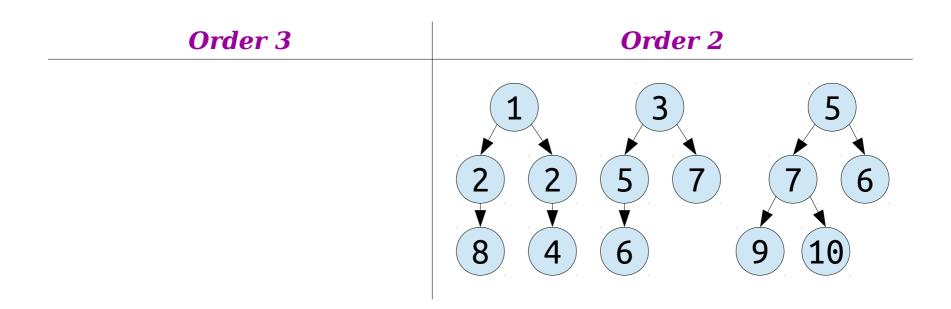


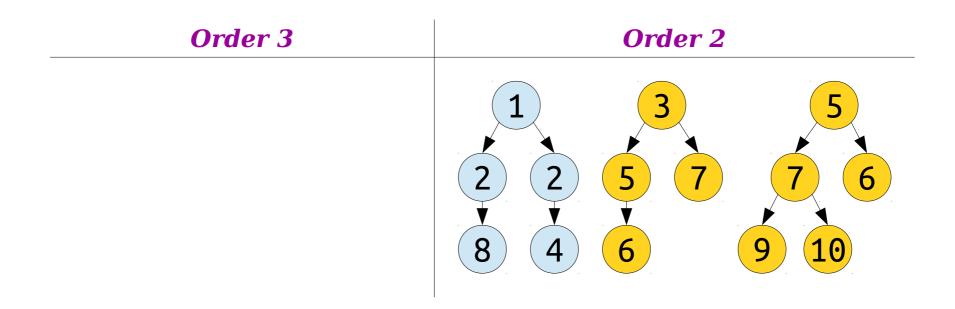


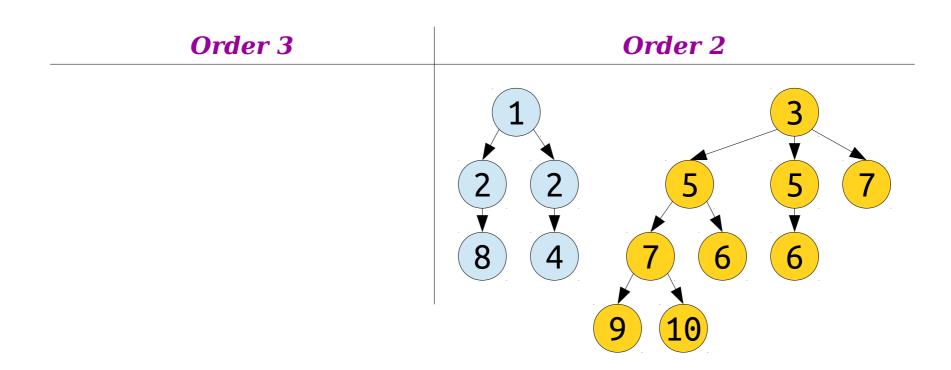


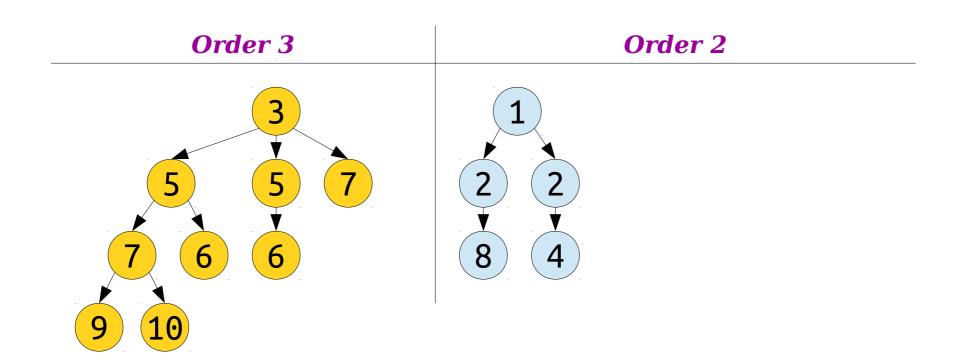
Order 2

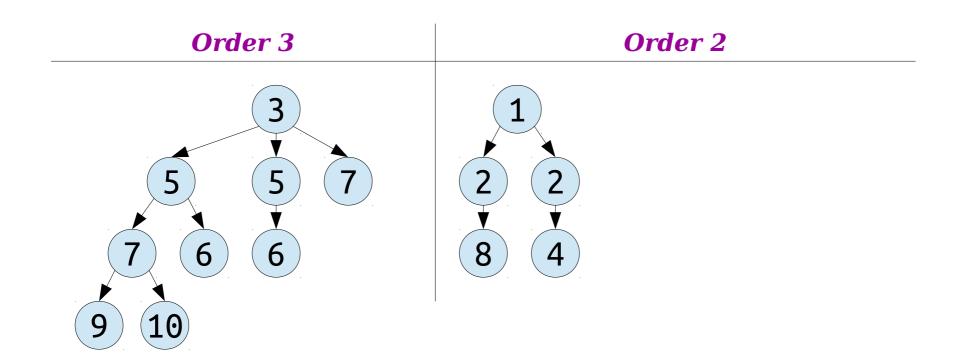


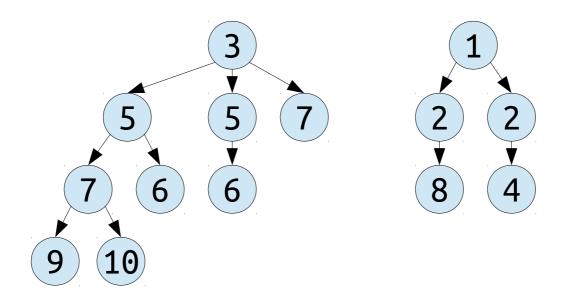


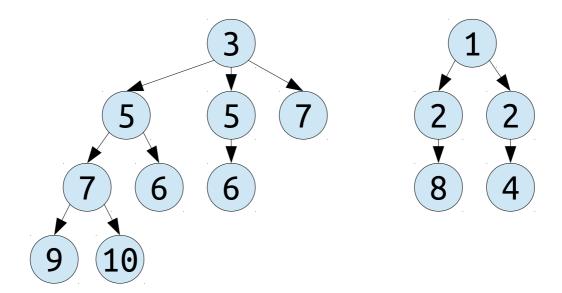






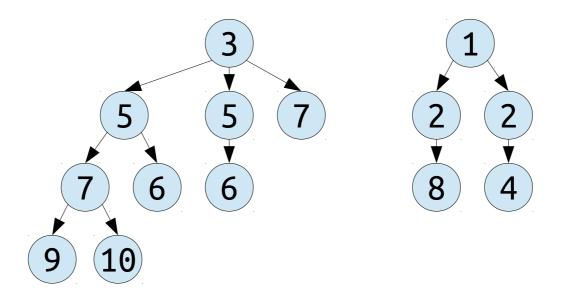




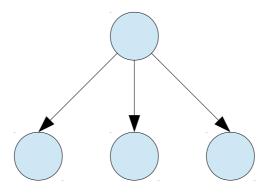


- (1) To do a *decrease-key*, cut the node from its parent.
- (2) Do extract-min as usual, using child count as order.

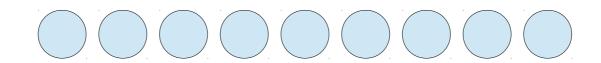
Question: How efficient is this?

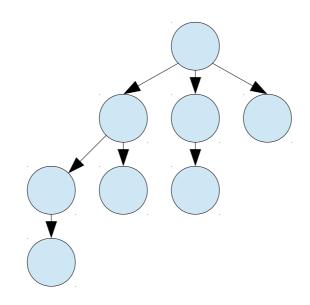


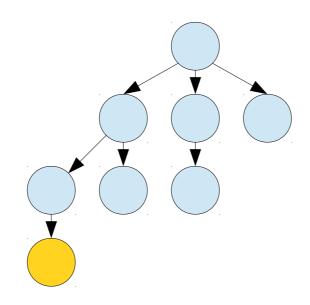
- (1) To do a *decrease-key*, cut the node from its parent.
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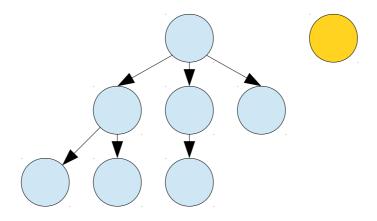


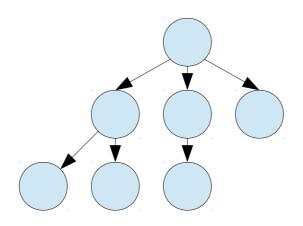
Find a series of operations that gives rise to a heap containing a single tree with this shape.

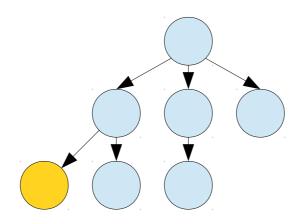


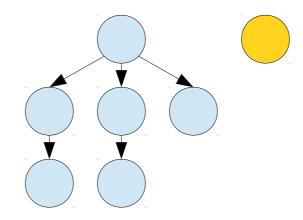


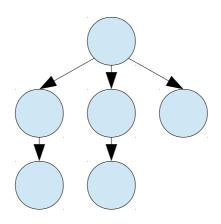


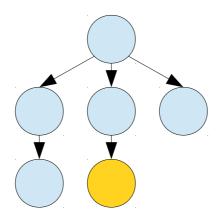


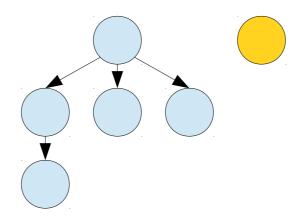


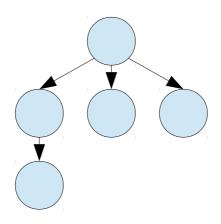


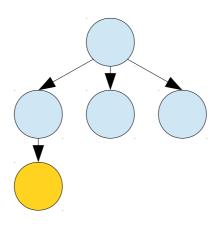


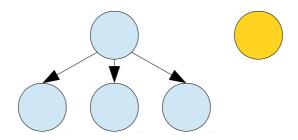


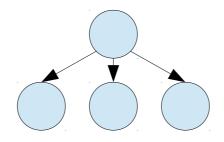


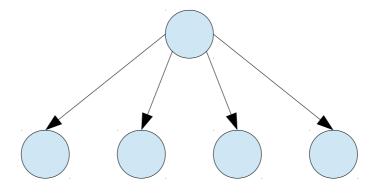




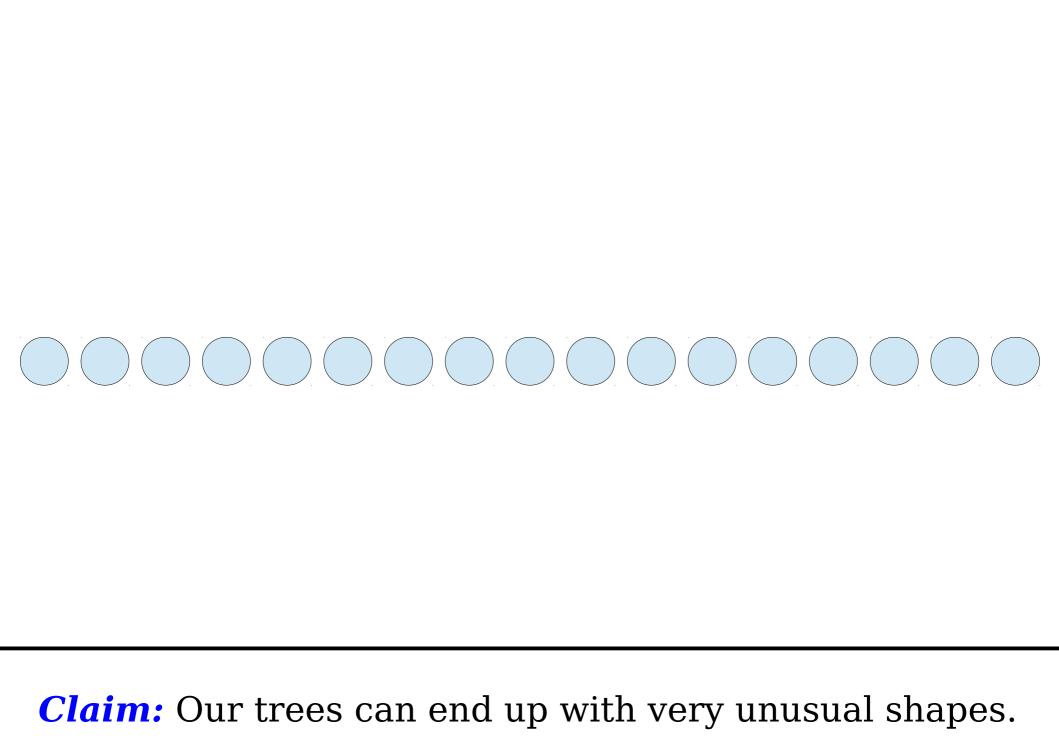


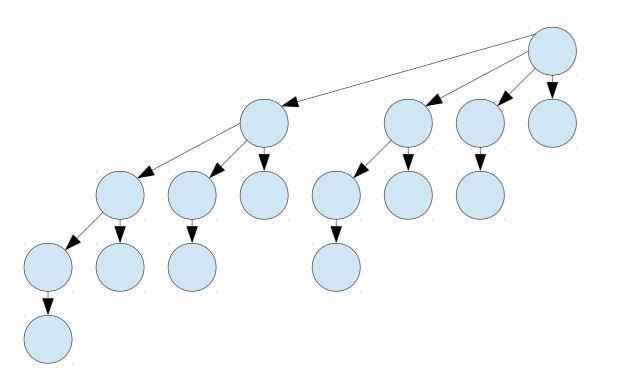


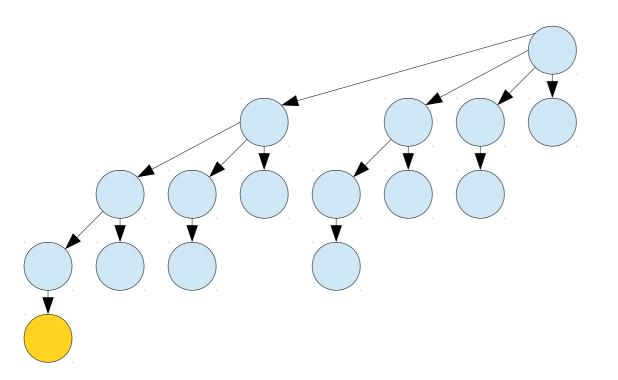


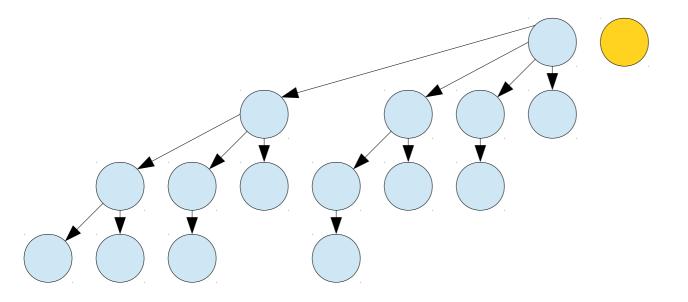


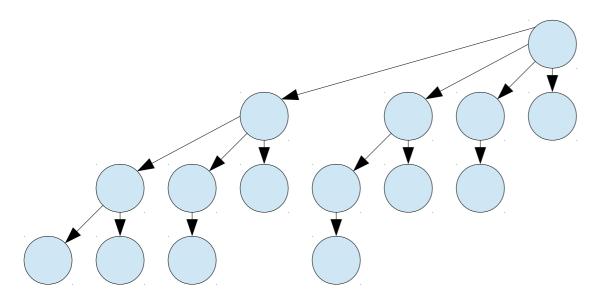
Find a series of operations that gives rise to a heap containing a single tree with this shape.

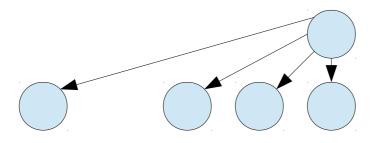


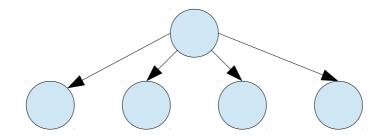








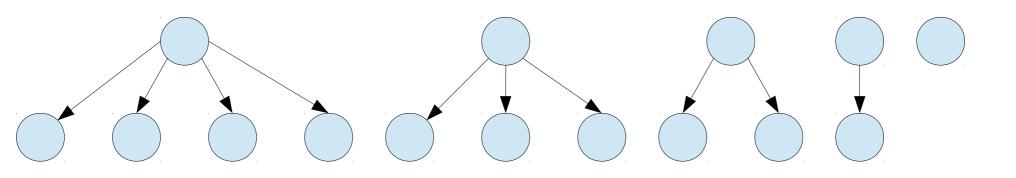




- 1. enqueue $2^k + 1$ nodes.
- 2. Do an *extract-min*.
- 3. Use *decrease-key* and *extract-min* to prune the tree.

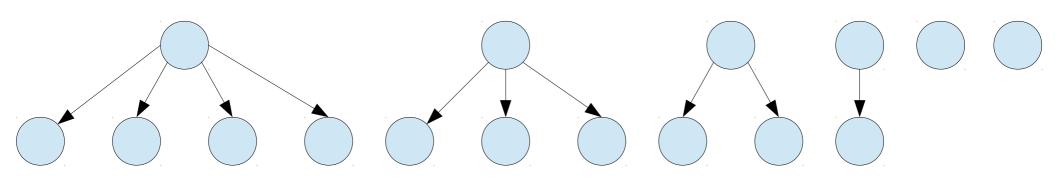
There are $\Theta(n^{1/2})$ trees here.

What happens if we repeatedly **enqueue** and **extract-min** a small value?



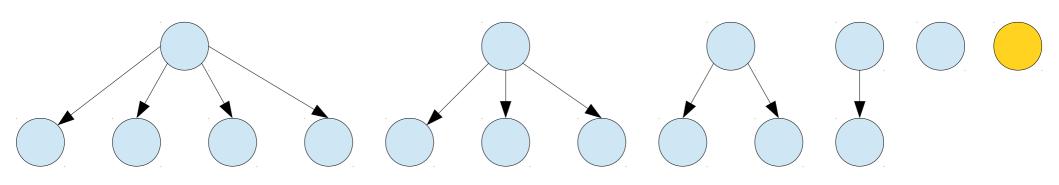
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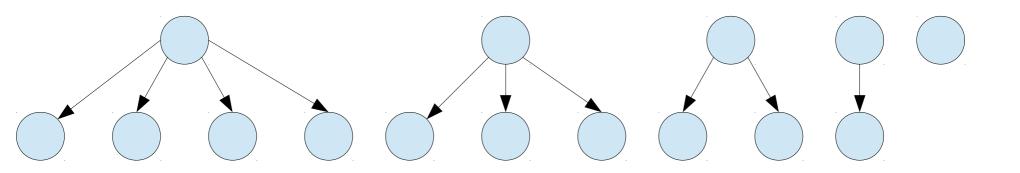
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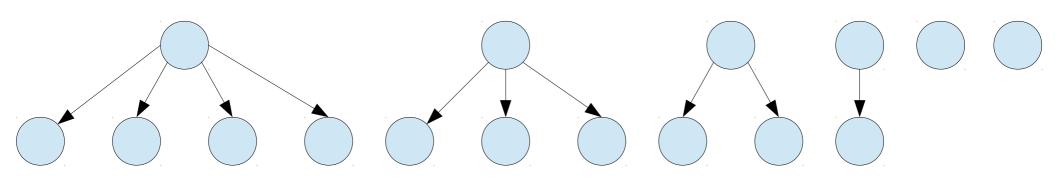
What happens if we repeatedly enqueue and extract-min a small value?



(Do a bunch of work to compact the trees, which doesn't accomplish anything.)

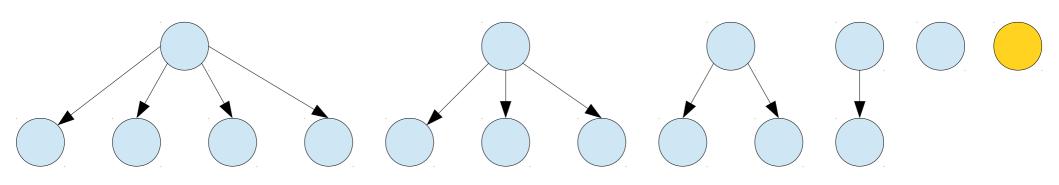
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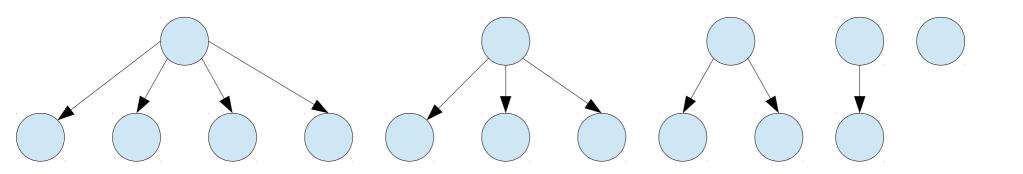
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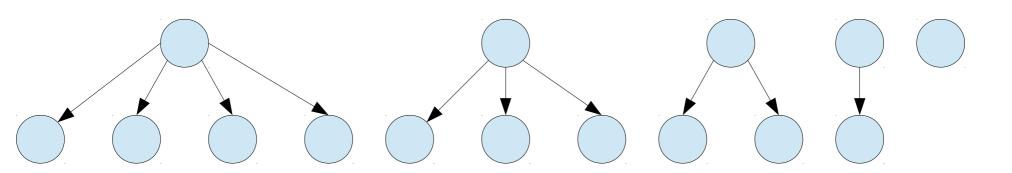
What happens if we repeatedly **enqueue** and **extract-min** a small value?



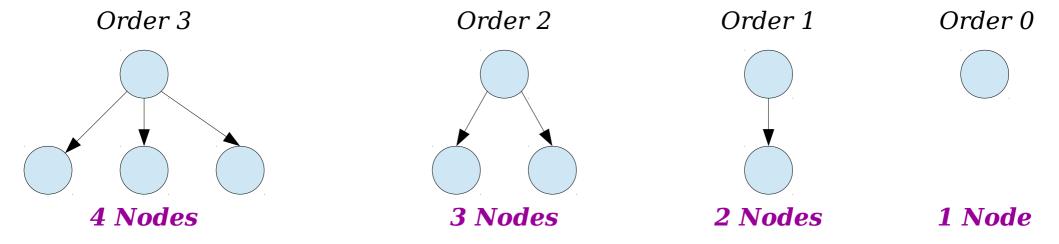
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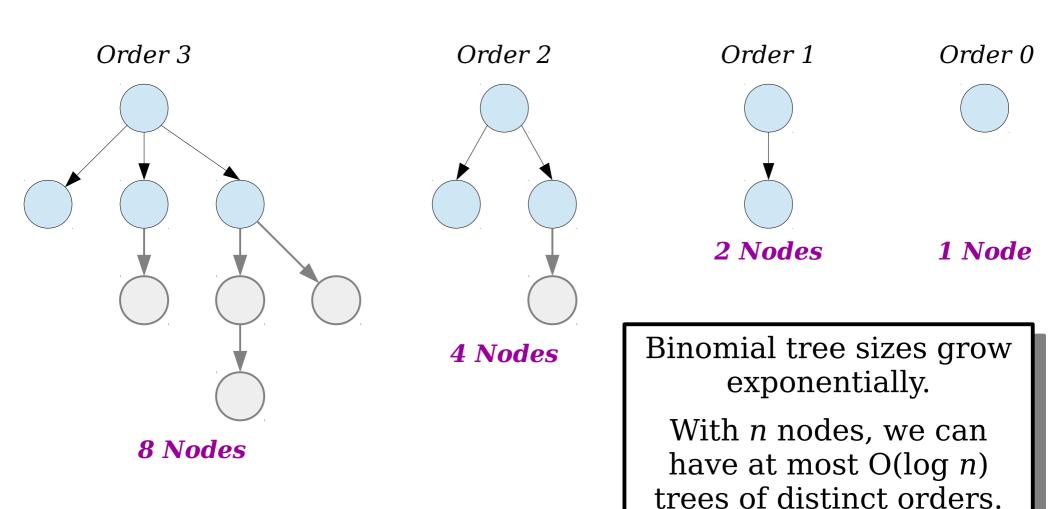


Each operation does $\Theta(n^{1/2})$ work, and doesn't make any future operations any better.



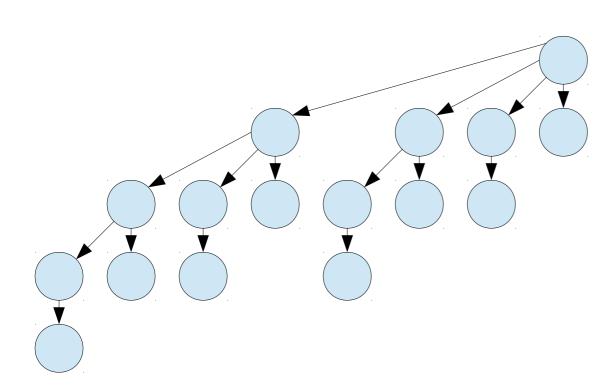
With n nodes, it's possible to have $\Omega(n^{1/2})$ trees of distinct orders.

Question: Why didn't this happen before?

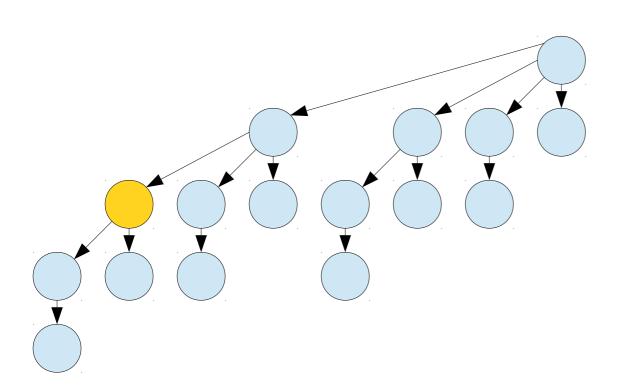


Question: Why didn't this happen before?

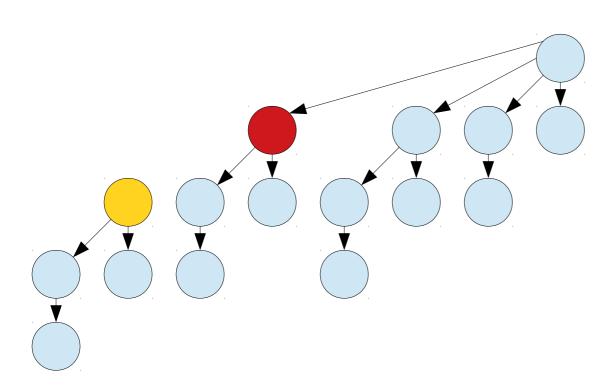
Rule: Nodes can lose at most one child. If a node loses two children, cut it from its parent.



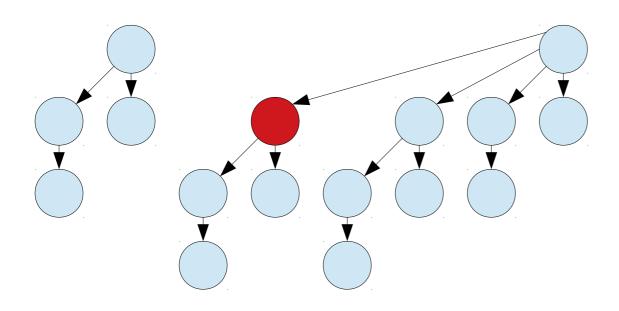
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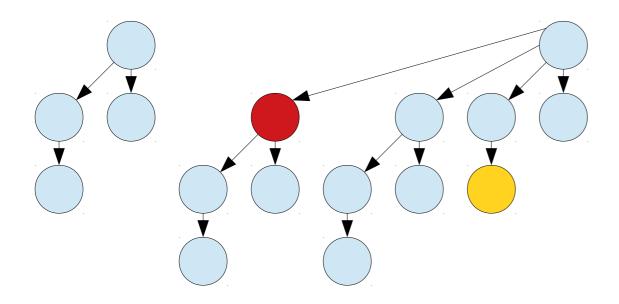
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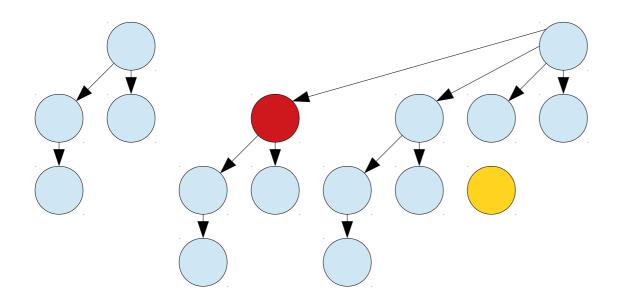
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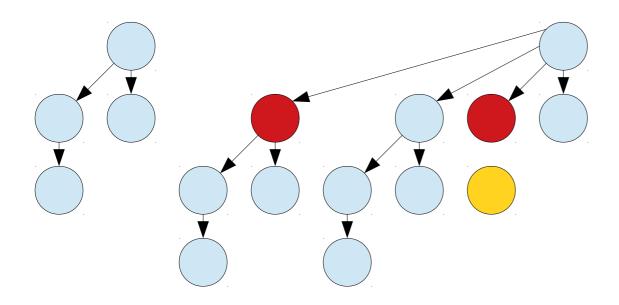
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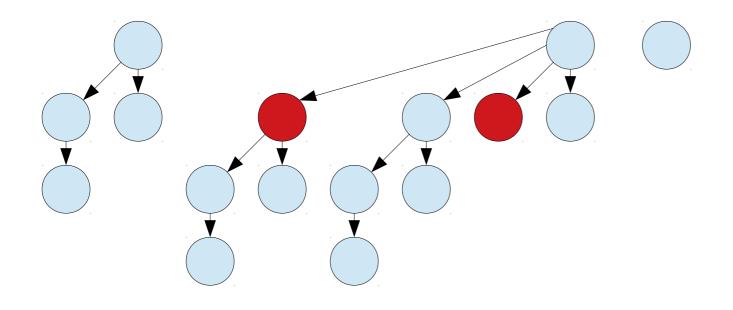
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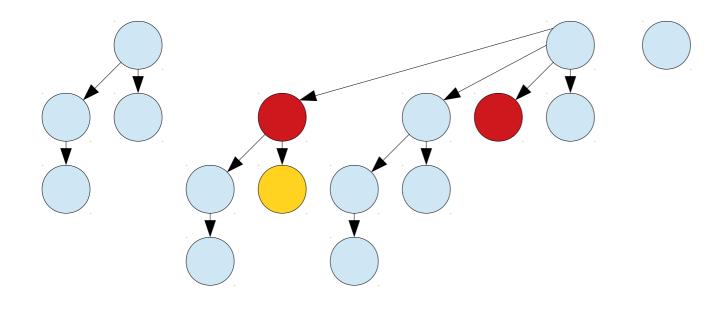
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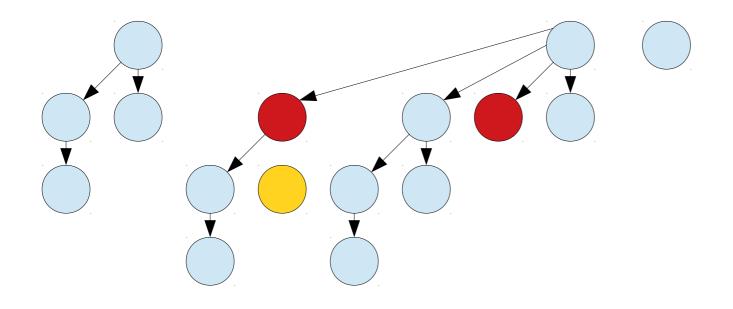
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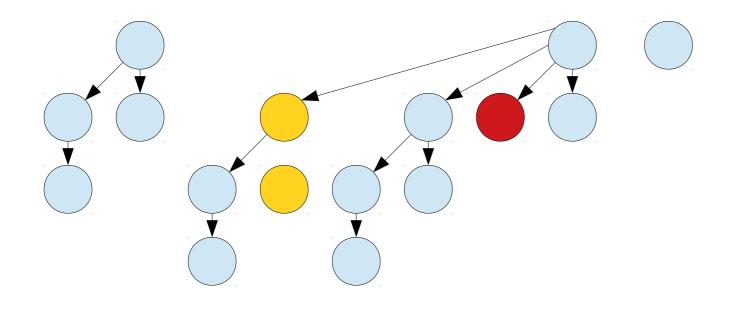
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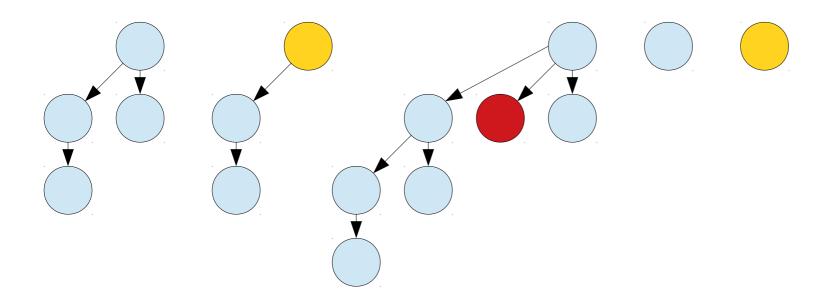
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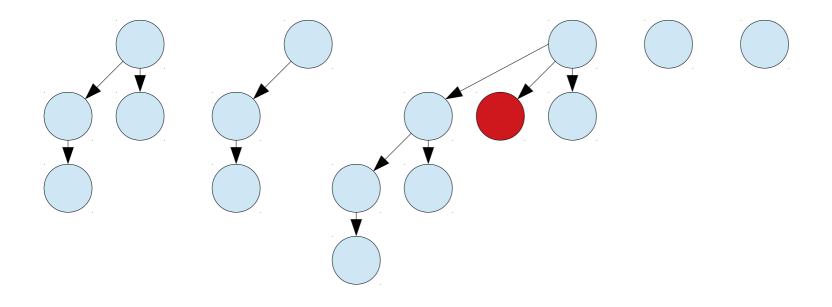
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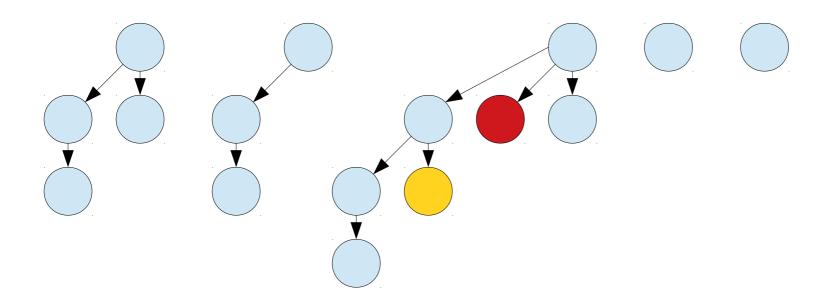
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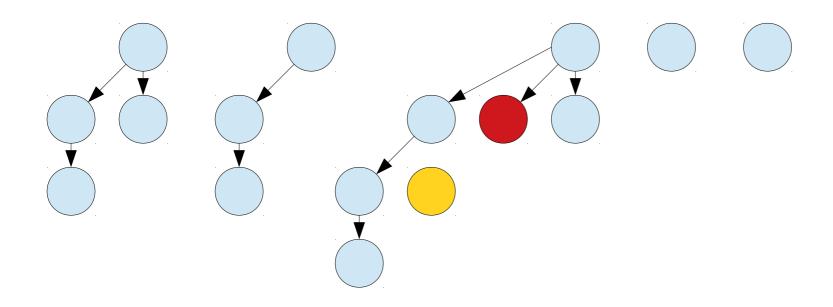
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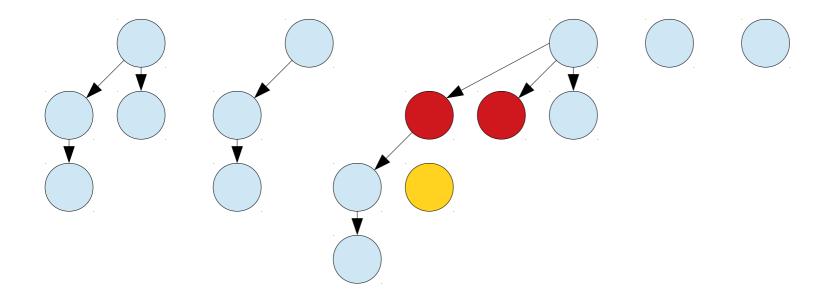
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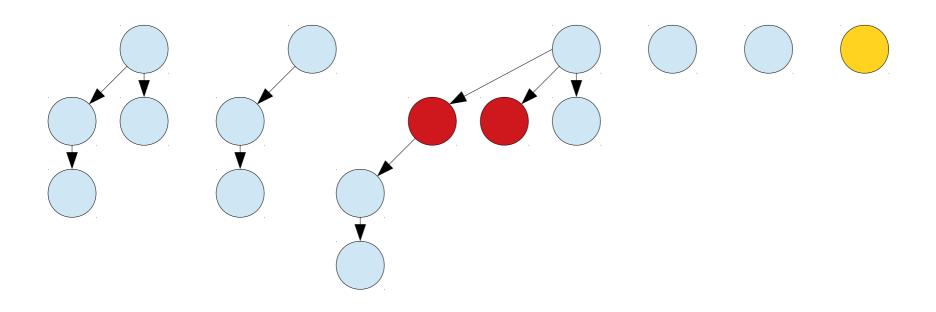
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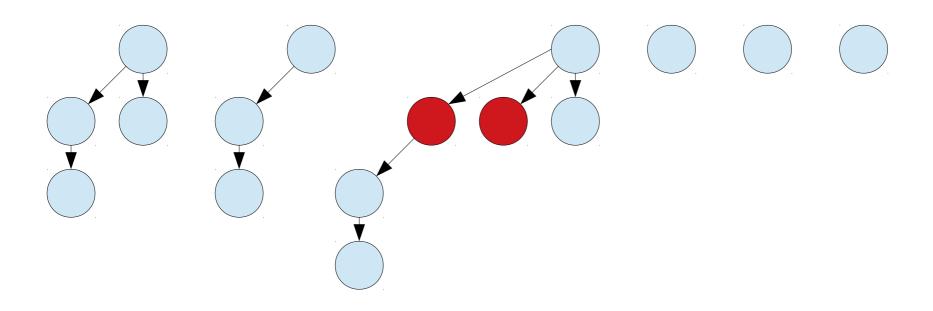
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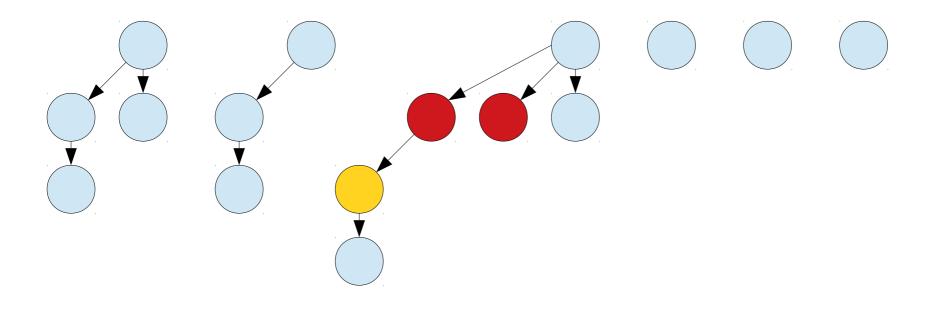
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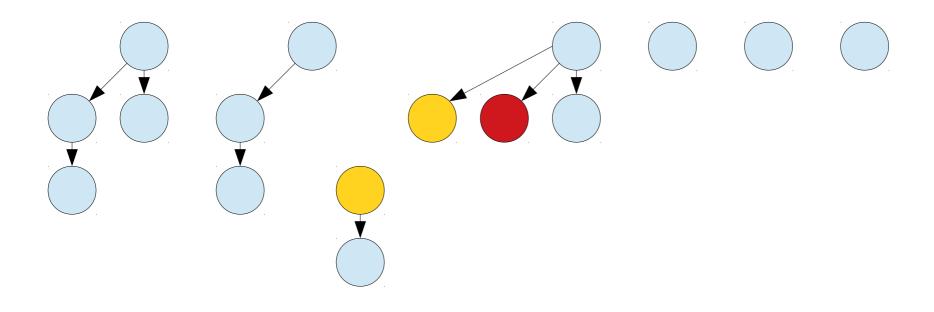
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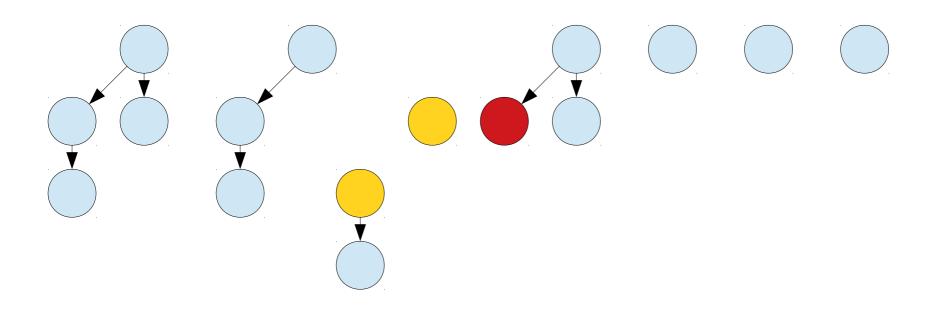
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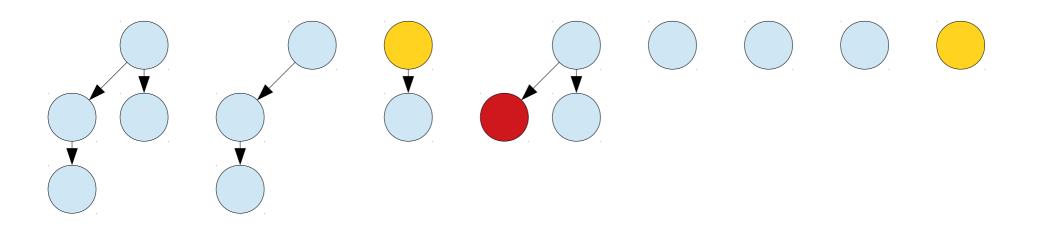


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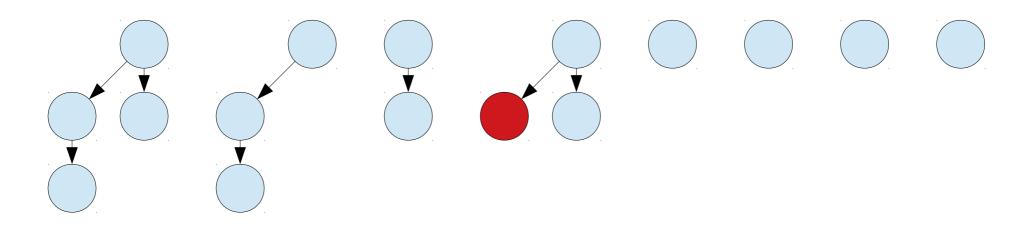
Goal: Make tree sizes grow exponentially with order, but still allow for subtrees to be cut out quickly.

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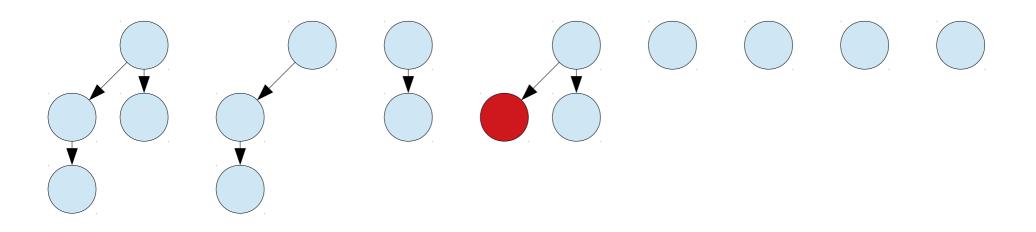
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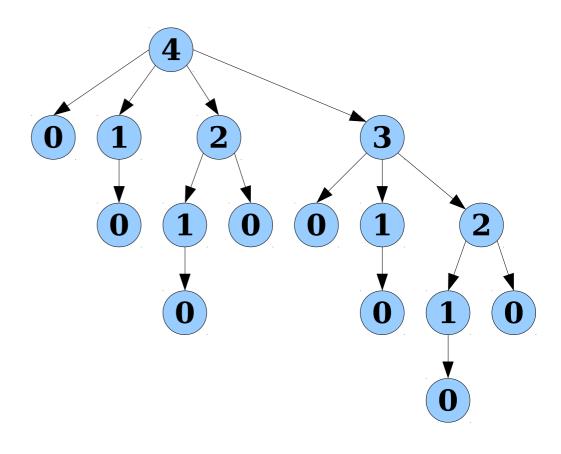
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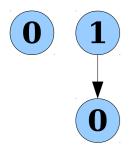


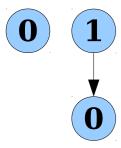
Question: Does this guarantee exponential tree size?

- Here's a binomial tree of order 4. That is, the root has four children.
- Question: Using our marking scheme, how many nodes can we remove without changing the order of the tree?
- Equivalently: how many nodes can we remove without removing any direct children of the root?

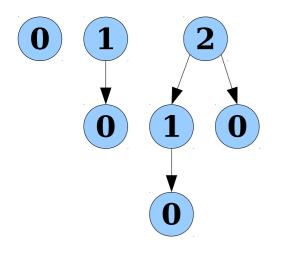


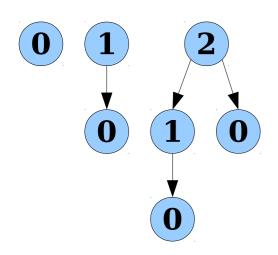




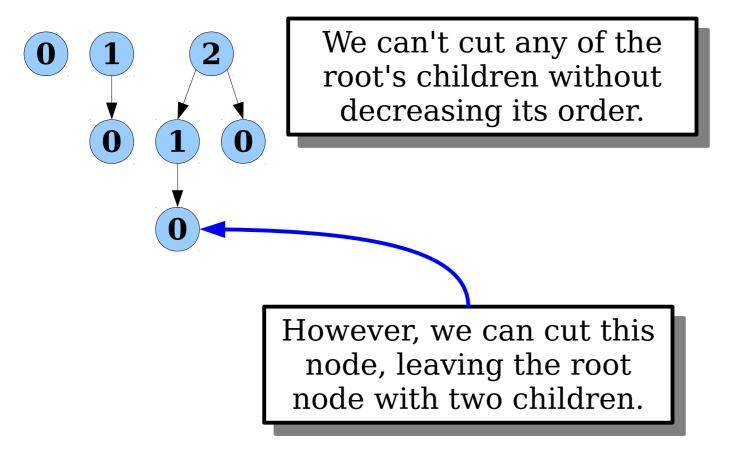


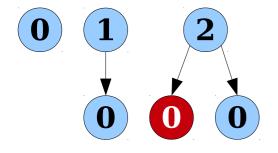
We can't cut any nodes from this tree without making the root node have order 0.

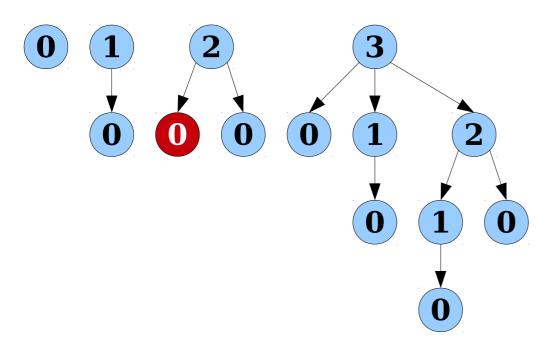


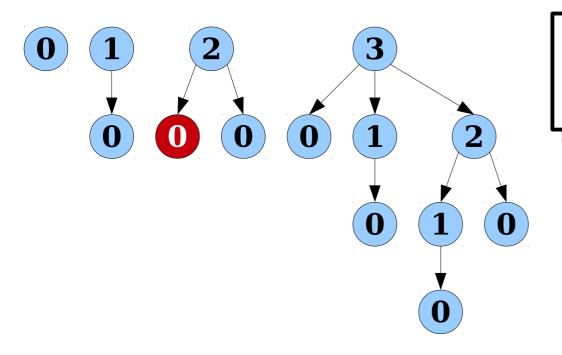


We can't cut any of the root's children without decreasing its order.

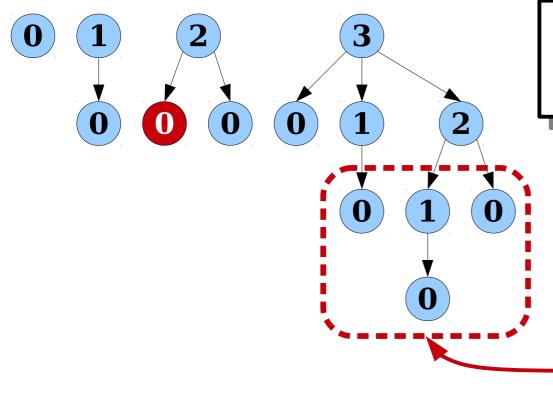






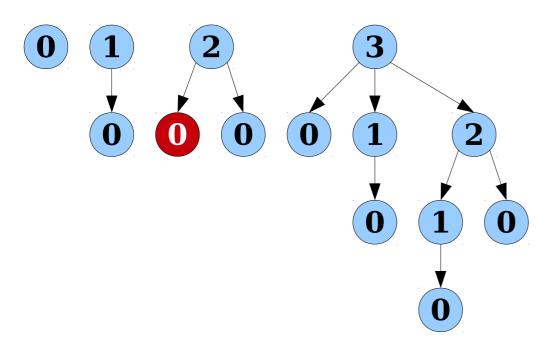


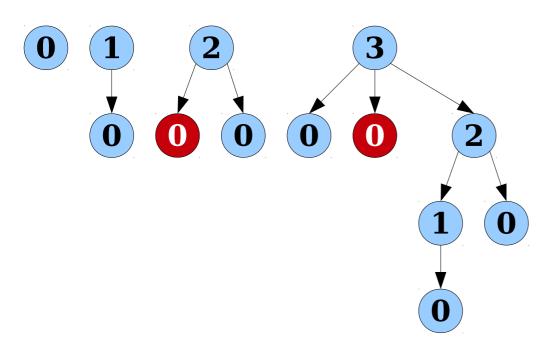
As before, we can't cut any of the root's children without decreasing its order.

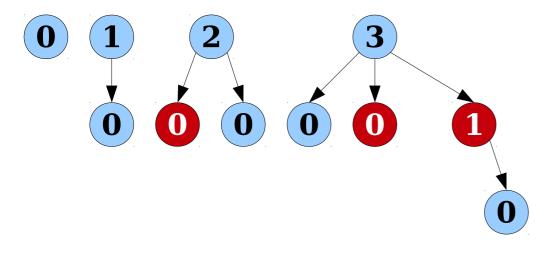


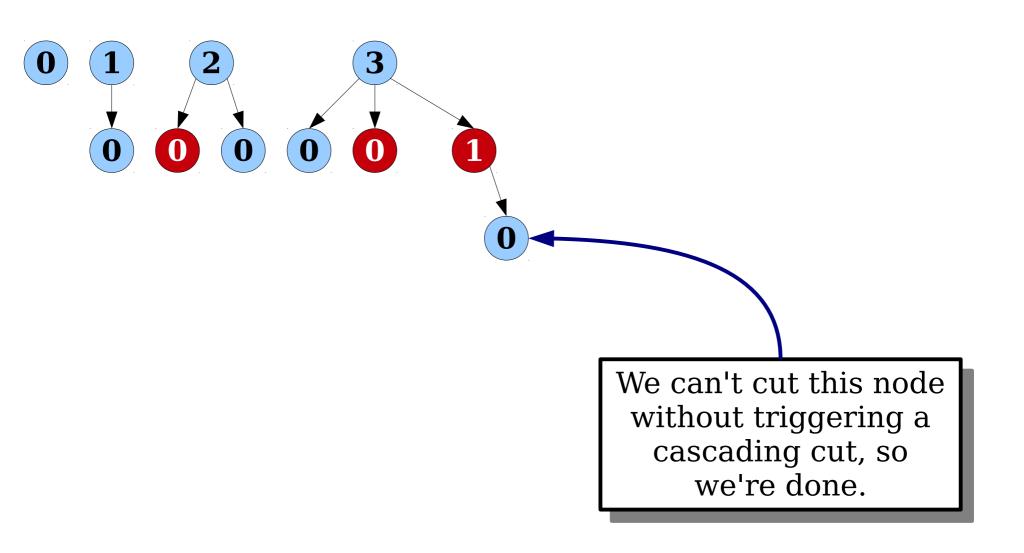
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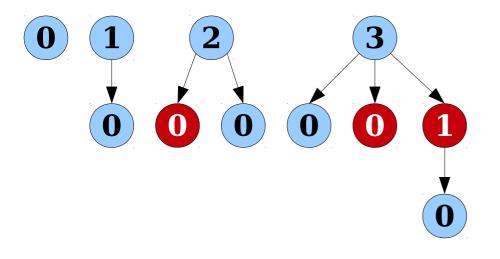
However, any nodes below the second layer are fair game to be eliminated.

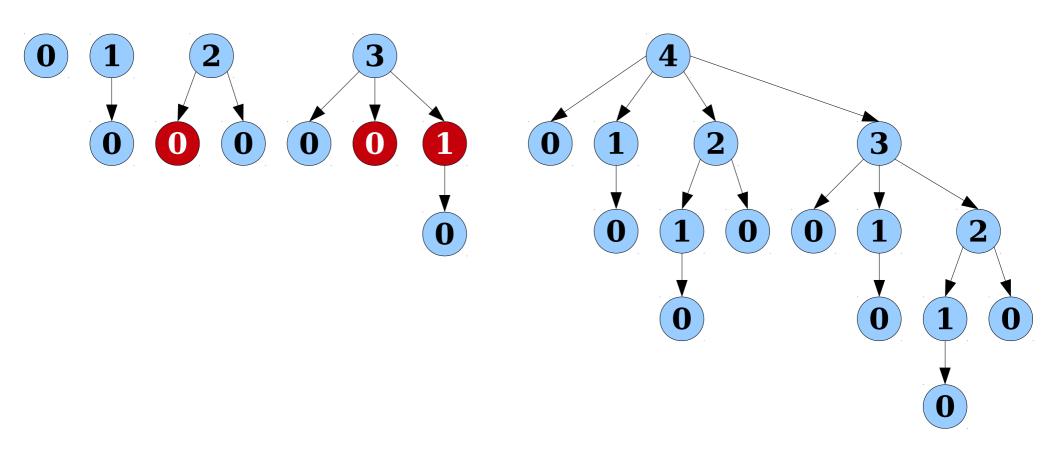


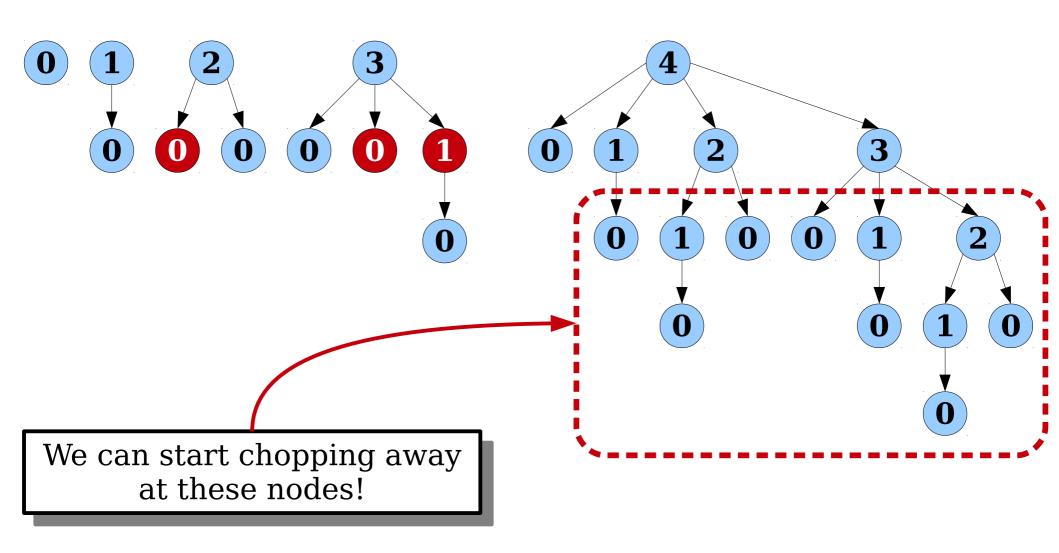


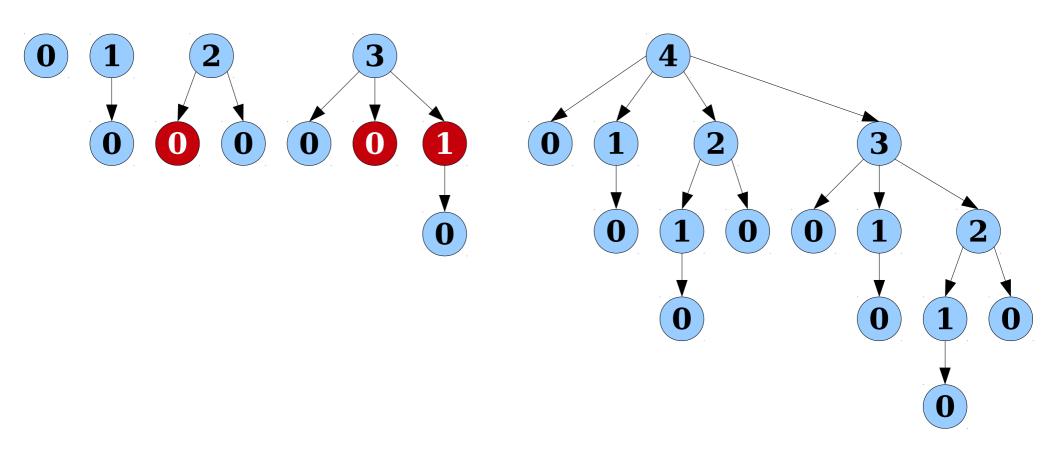


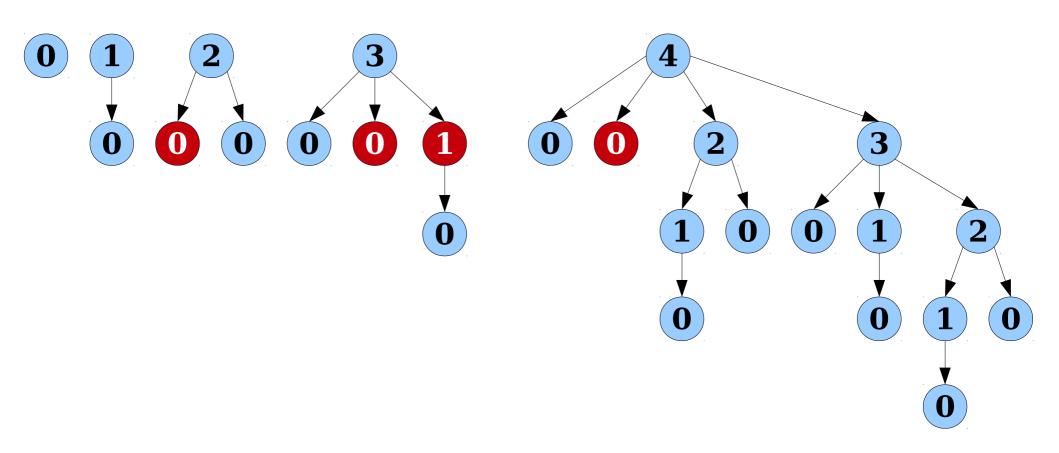


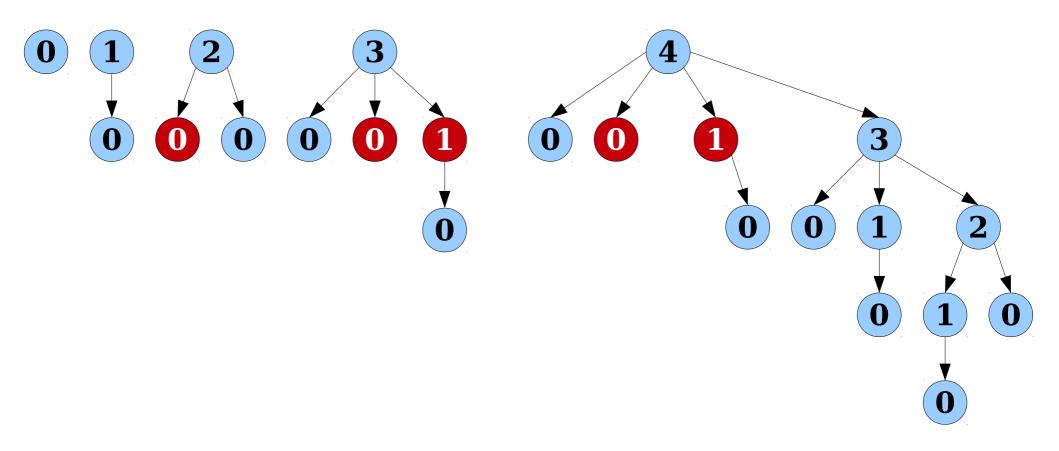


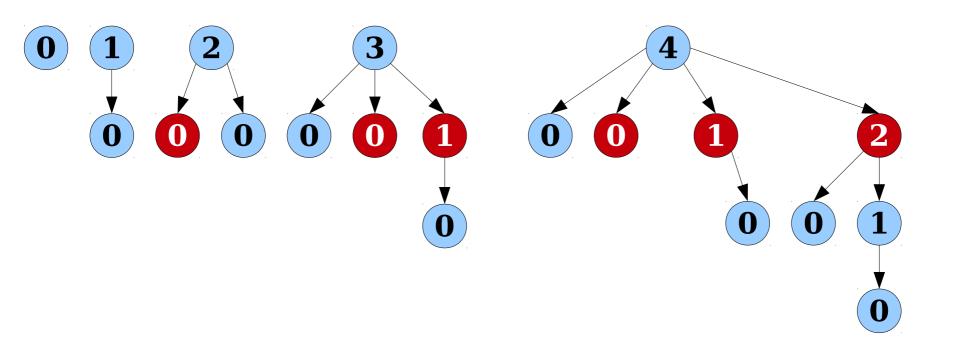


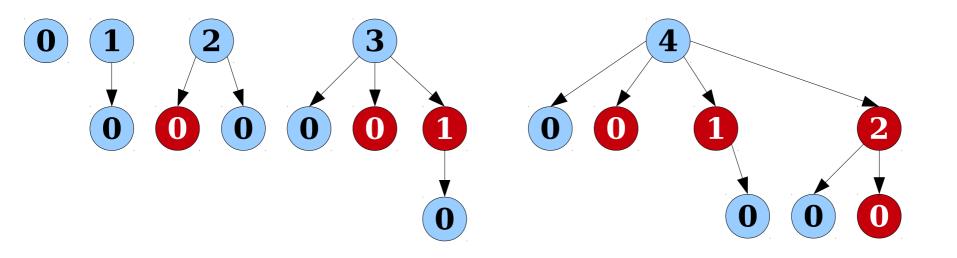


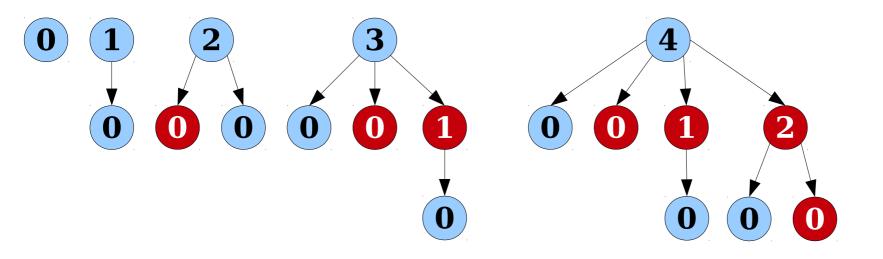


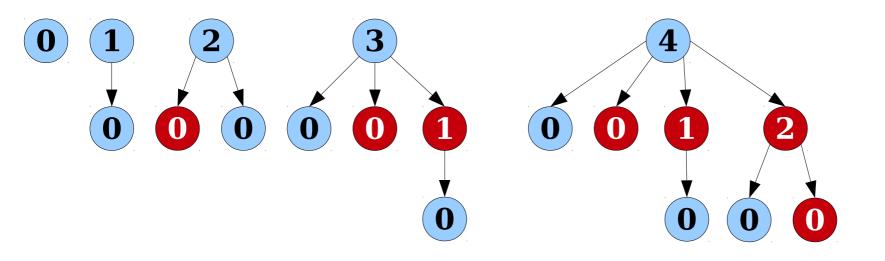


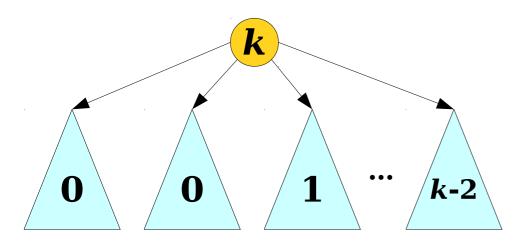


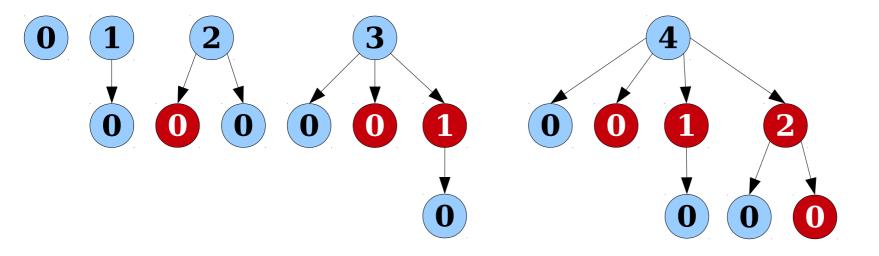


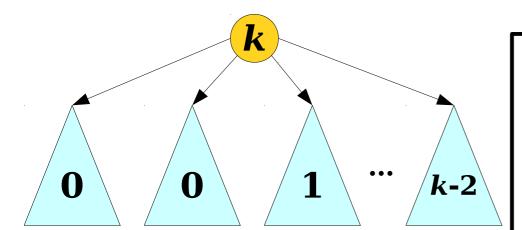






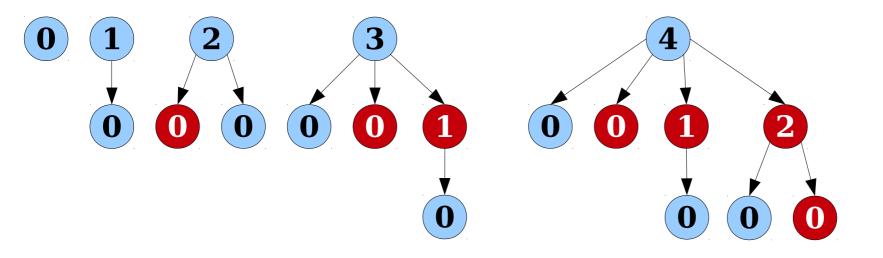


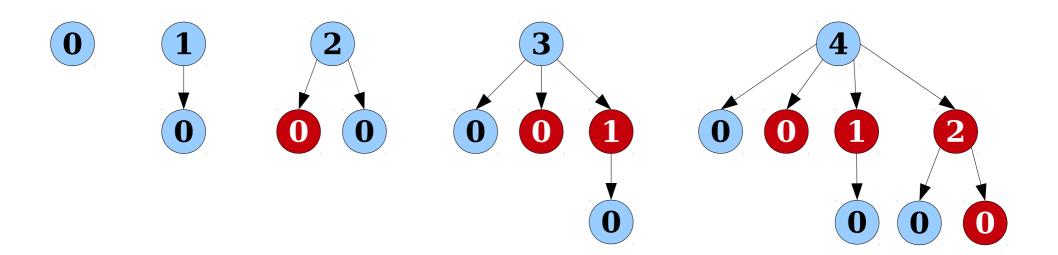


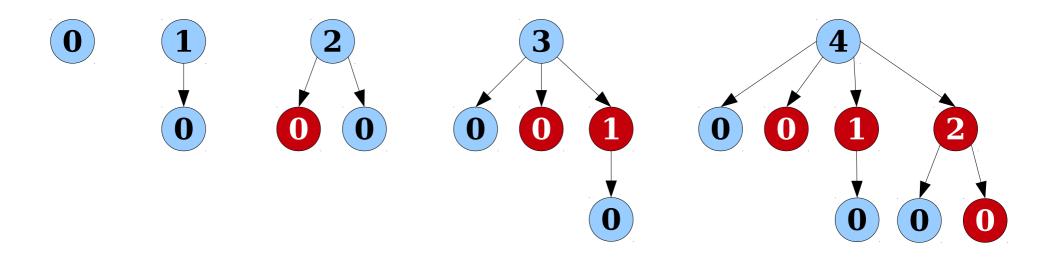


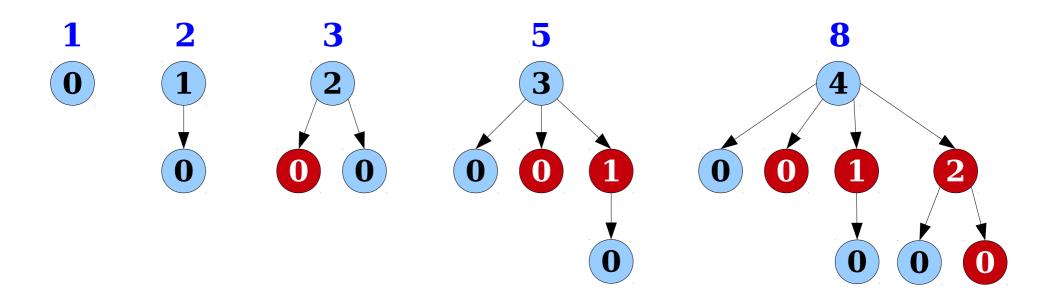
A maximally-damaged tree of order k is a node whose children are maximally-damaged trees of orders

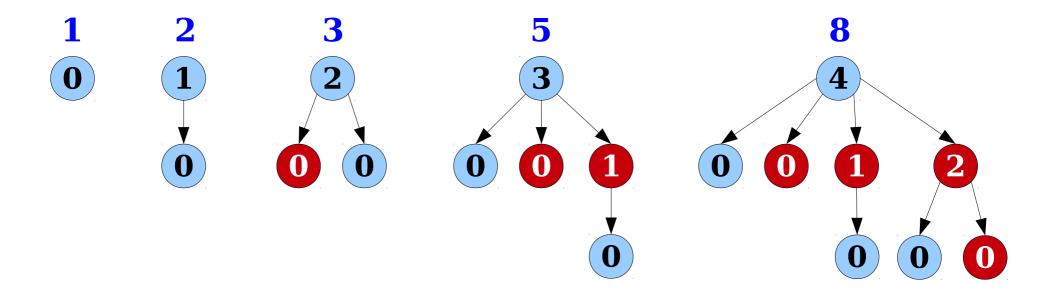
0, 0, 1, 2, 3, ..., k - 2.







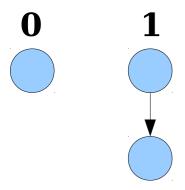




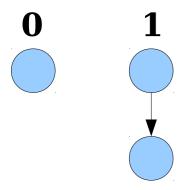
Claim: The minimum number of nodes in a tree of order k is F_{k+2}

- *Theorem*: The number of nodes in a maximally-damaged tree of order k is F_{k+2} .
- **Proof:** Induction.

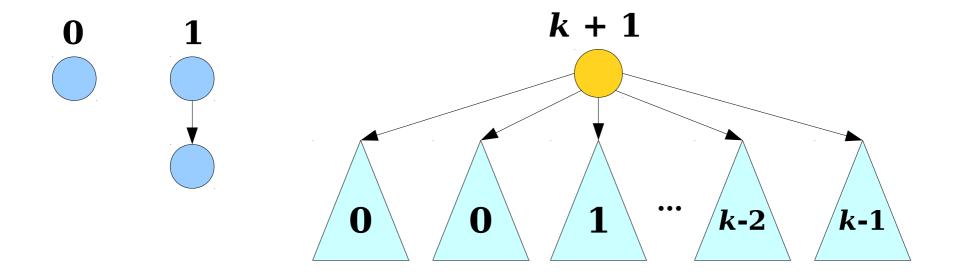
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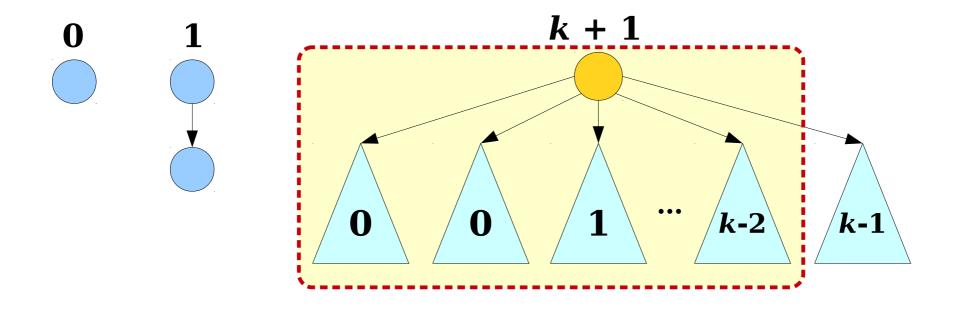
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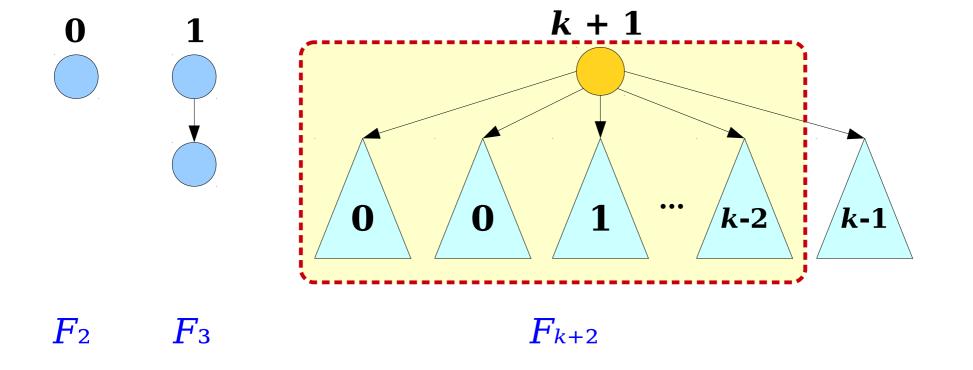
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 F_2

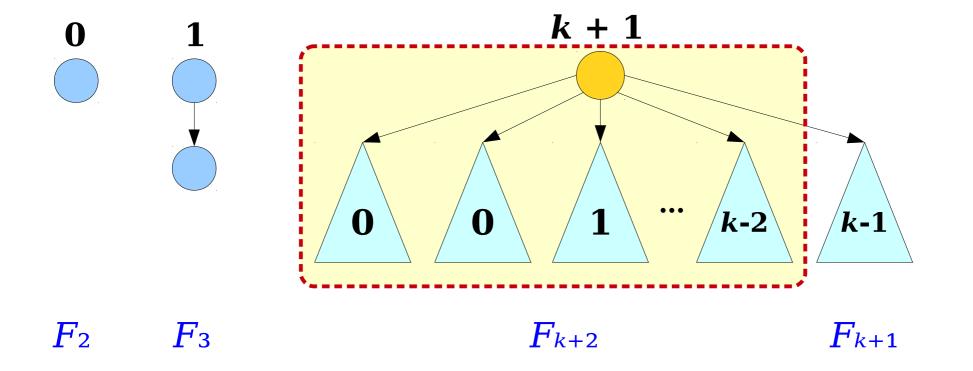
 F_3



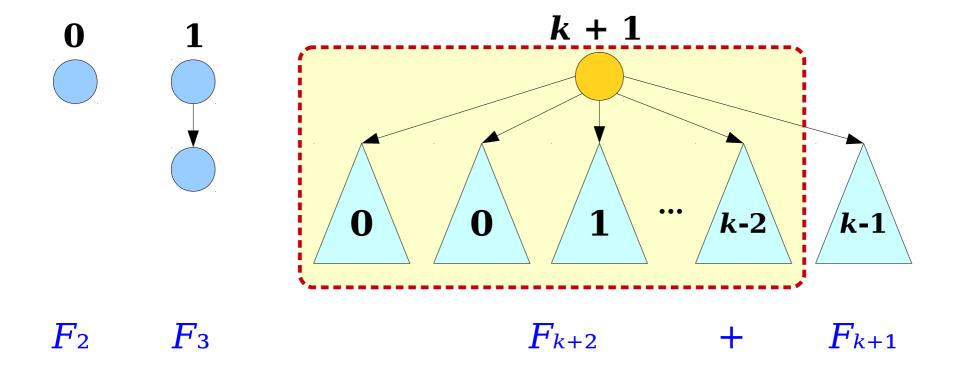
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- **Theorem:** The number of nodes in a maximally-damaged tree of order k is F_{k+2} .

 Recall: $F_k = \Theta(\varphi^k)$
- **Proof:** Induction.

 F_2

 F_3

k+1grows exponentially! 0 1 k-2 k-1

 F_{k+3}

The number of

nodes in a tree

A *Fibonacci heap* is a lazy binomial heap with *decrease-key* implemented using the marking scheme described earlier.

Time-Out for Announcements!

Project Proposals

- Project proposals were due at 2:30PM today.
- We're aiming to do matchmaking as soon as possible. Expect an email from us by tomorrow afternoon.
- Next milestone is the project checkpoint, and we'll give details in our emails.

Problem Set Three

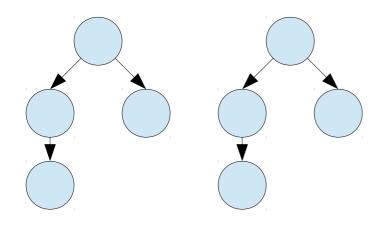
- Problem Set Three is due this upcoming Tuesday at 2:30PM.
- Have questions?
 - Ask on Piazza!
 - Stop by our office hours!

Back to CS166!

How fast are the operations on Fibonacci heaps?

$$\Phi = T$$

T is the number of trees.















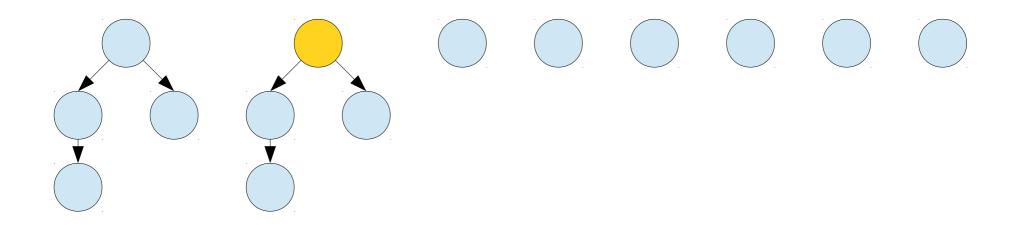
Actual cost: O(1)

 $\Delta\Phi$: +1

Amortized cost: O(1).

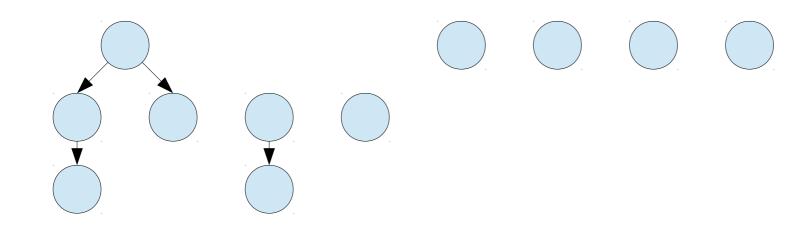
$$\Phi = T$$

T is the number of trees.



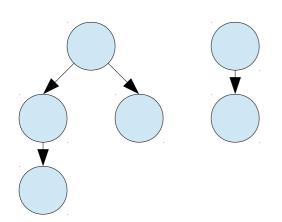
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T is the number of trees.



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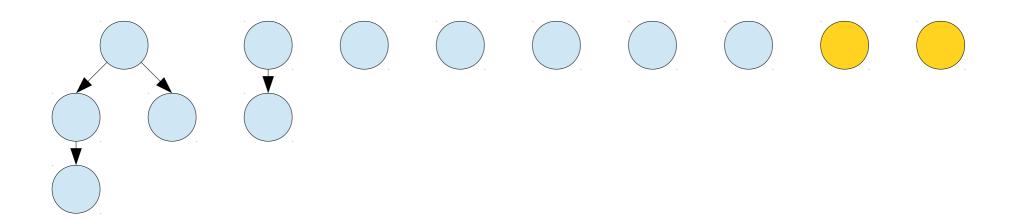


Deleting the node with the minimum value exposes up to $O(\log n)$ new trees.

Number of trees at this point: $T + O(\log n)$.

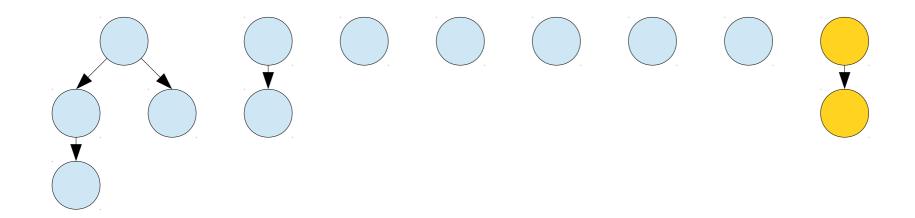
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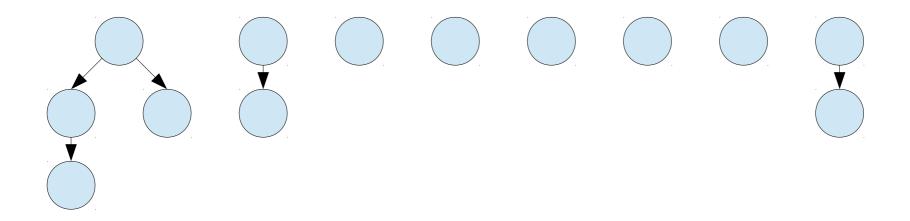
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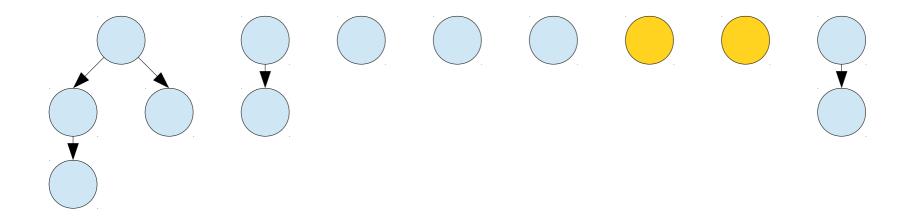
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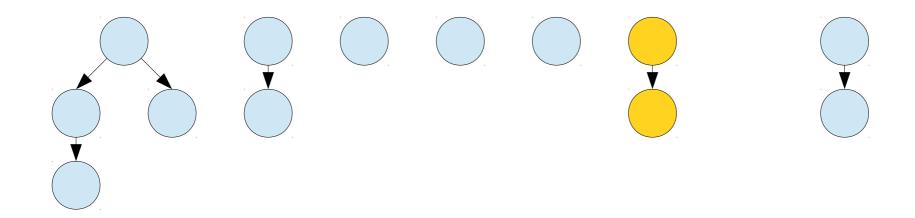
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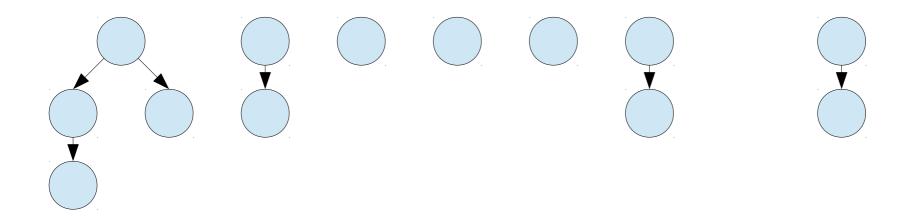
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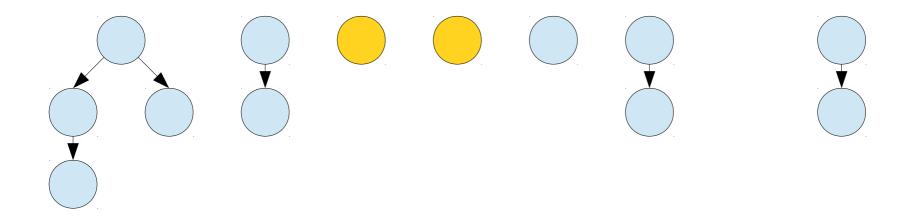
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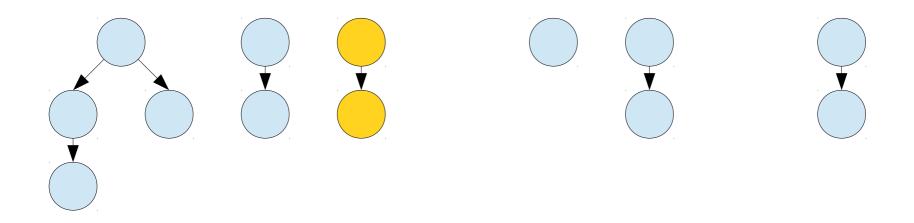
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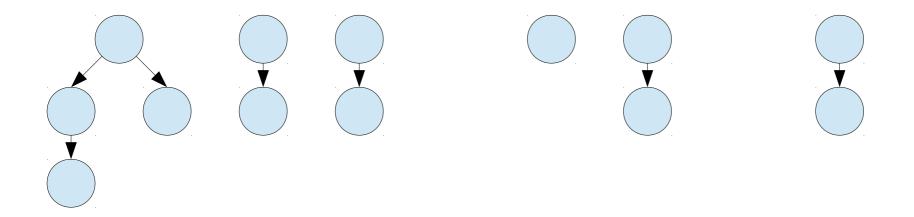
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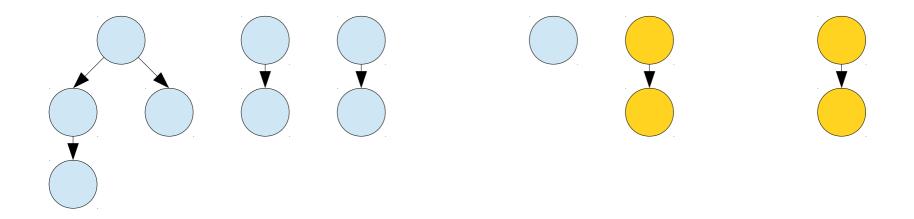
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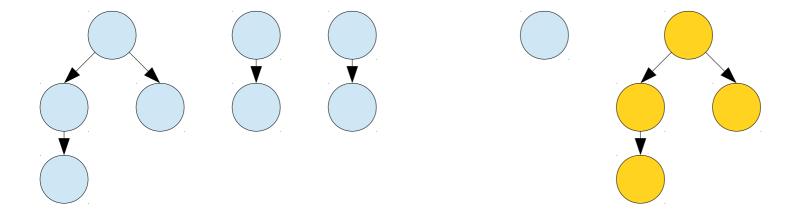
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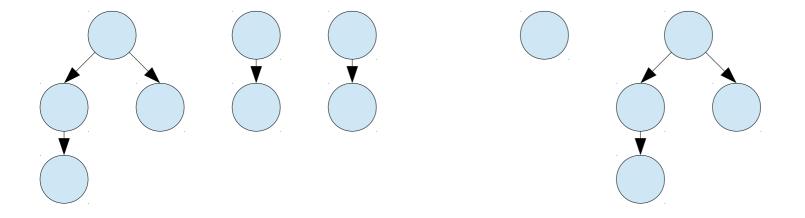
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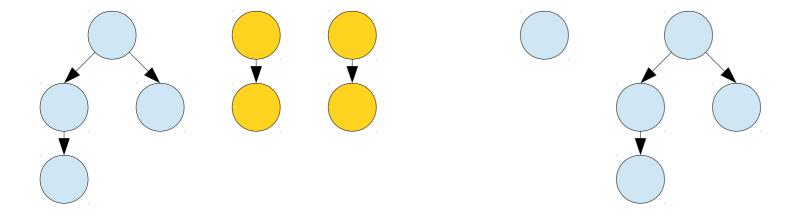
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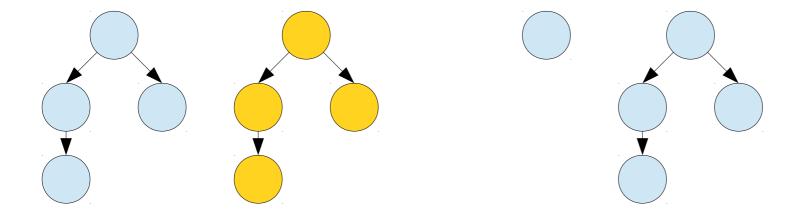
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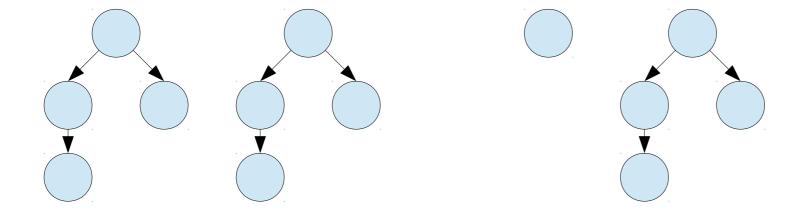
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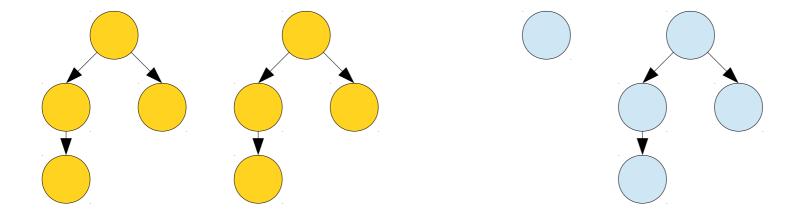
$$\Phi = T$$

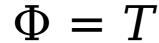
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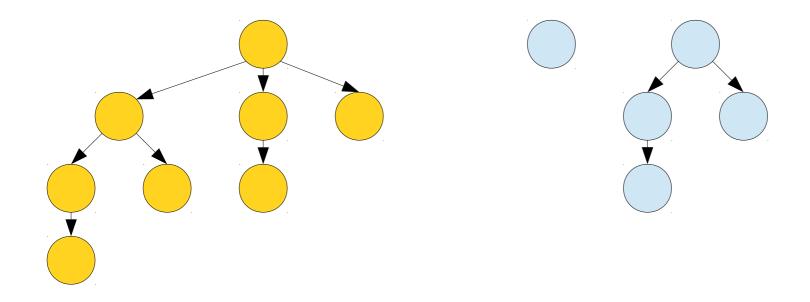
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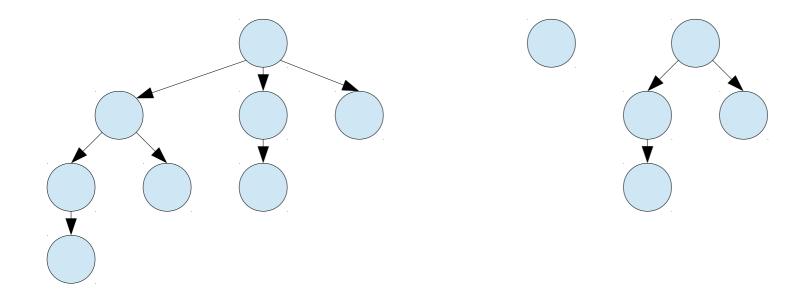


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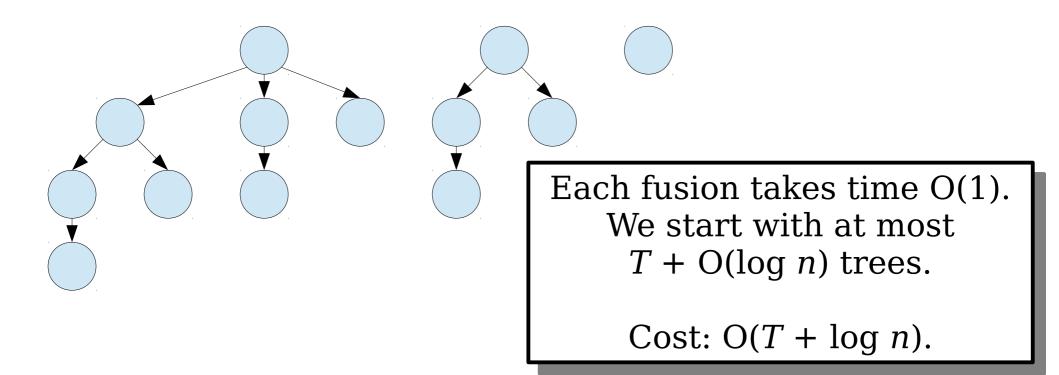
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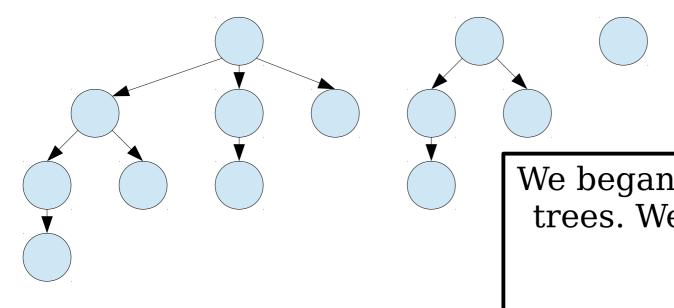
$$\Phi = T$$

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$$\Phi = T$$

T is the number of trees.

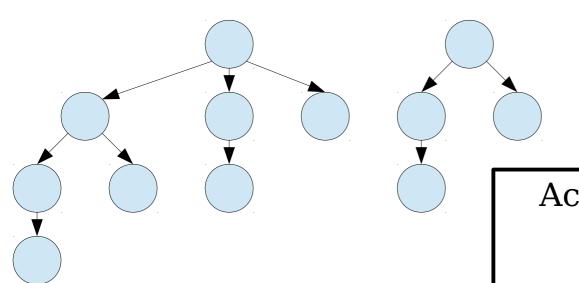


We began this process with T trees. We end with $O(\log n)$ trees.

 $\Delta\Phi$: $-T + O(\log n)$.

$$\Phi = T$$

T is the number of trees.



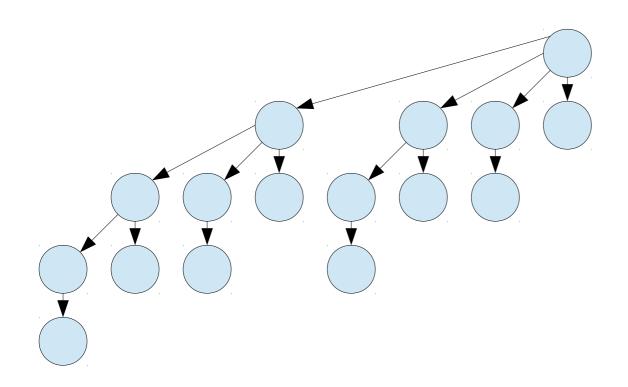
Actual cost: $O(T + \log n)$.

 $\Delta\Phi$: $-T + \log n$.

Amortized cost: $O(\log n)$.

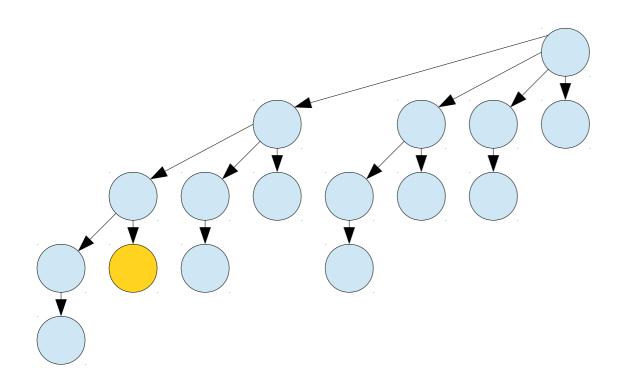
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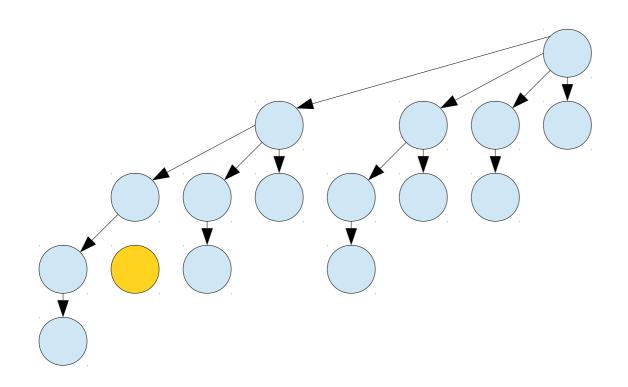
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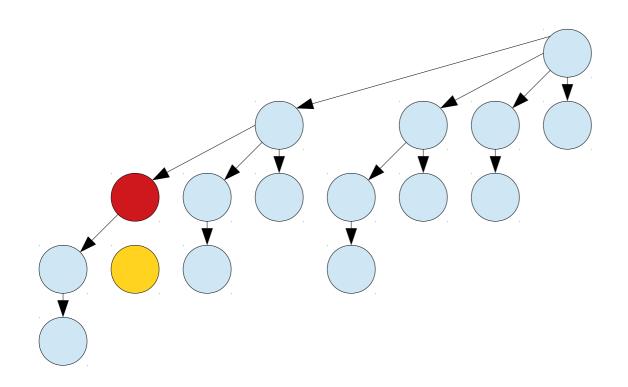
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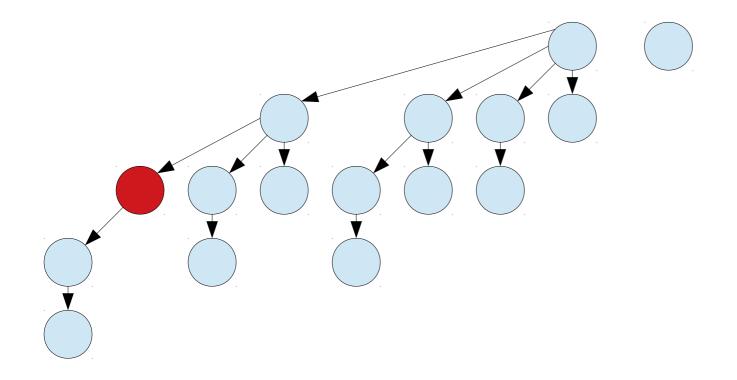
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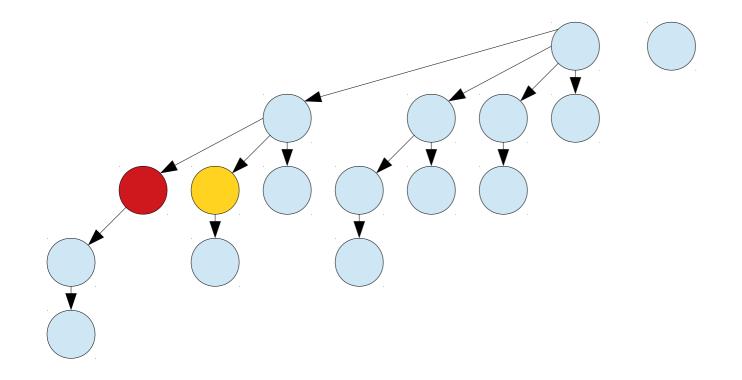
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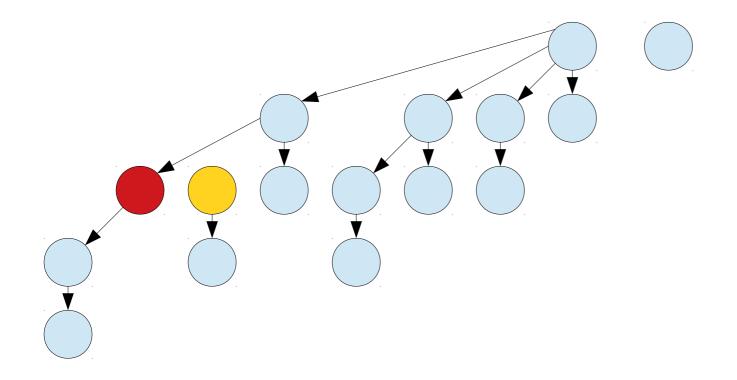
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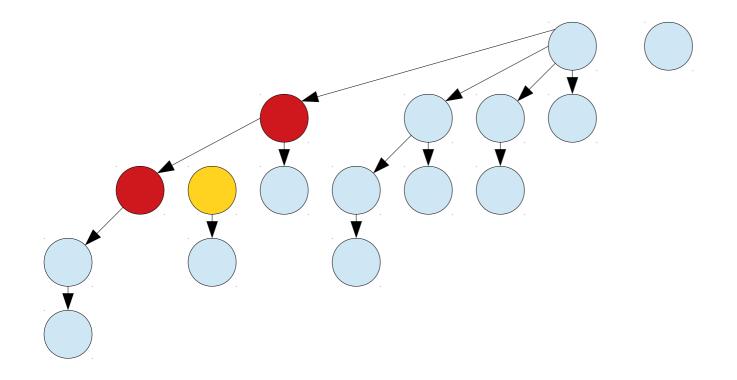
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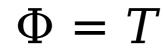
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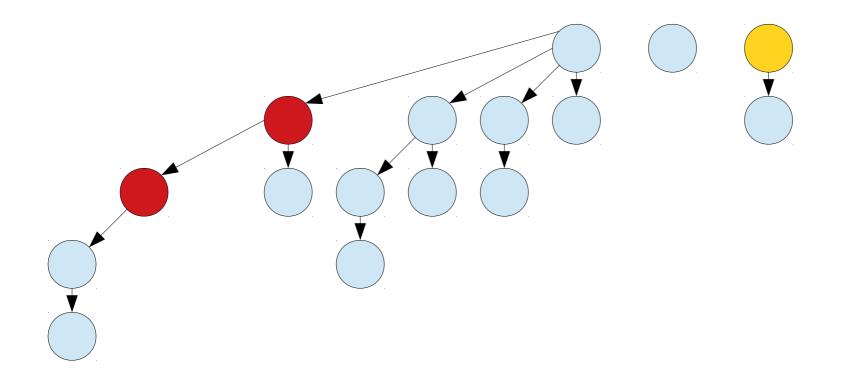
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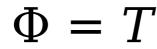
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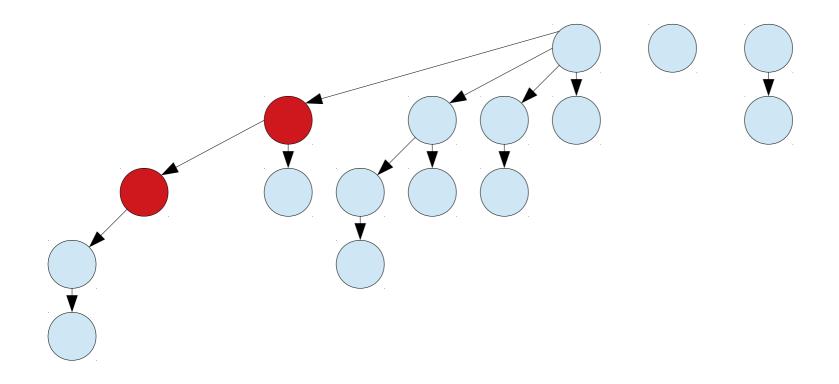


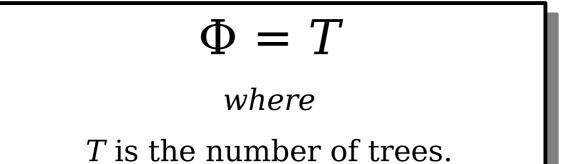
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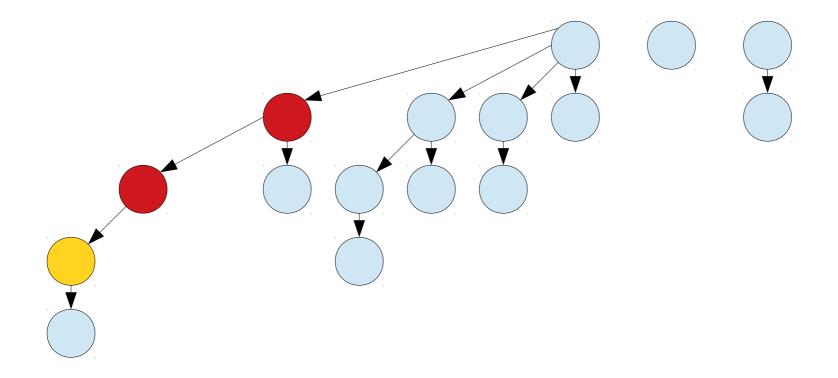


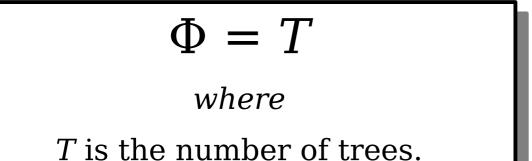


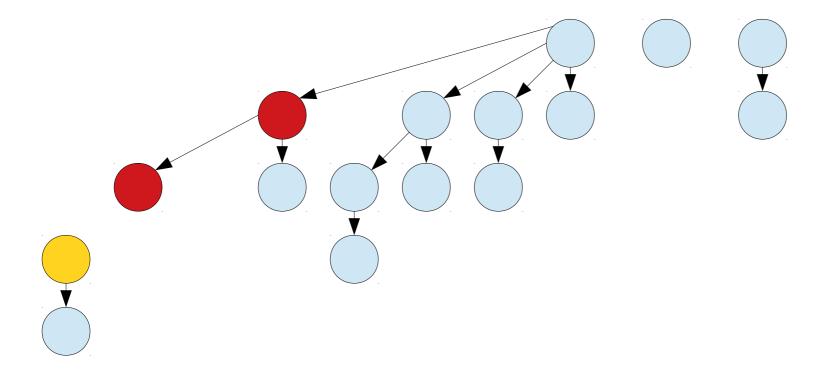
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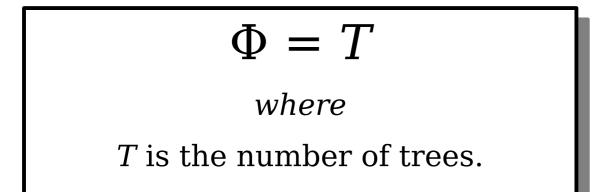


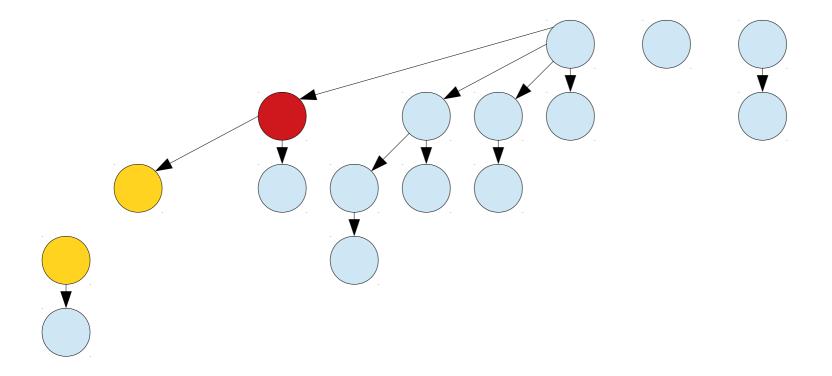


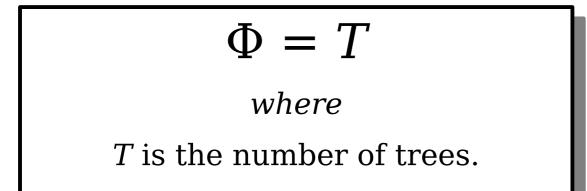


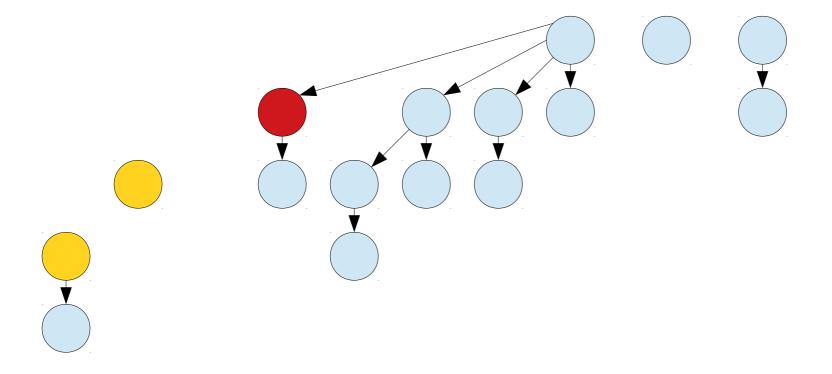


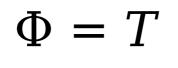




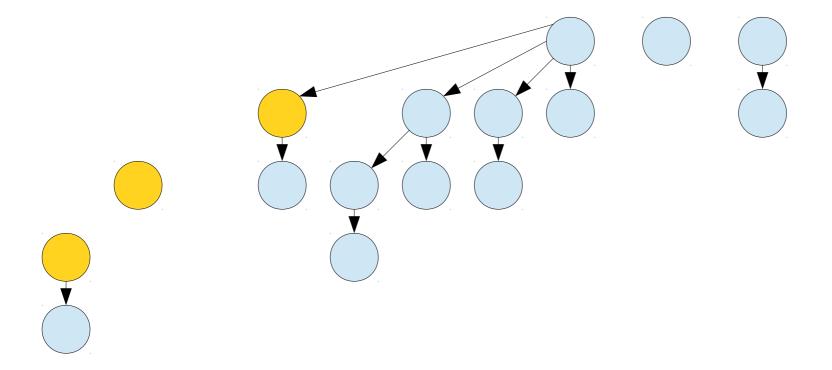


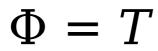




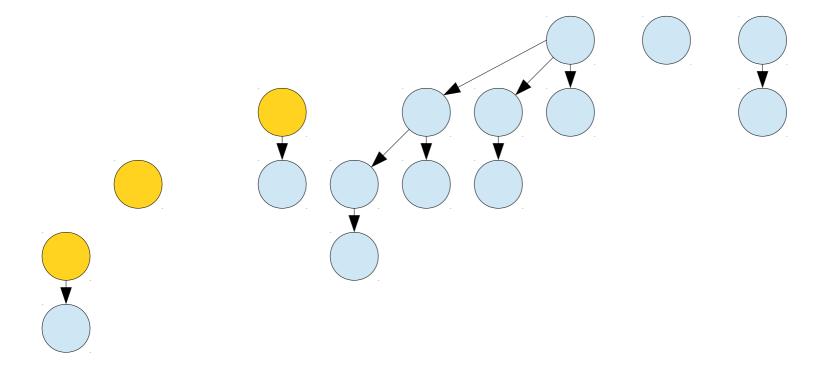


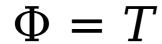
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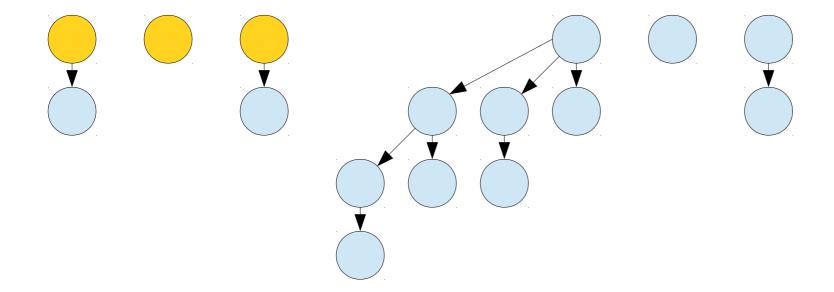


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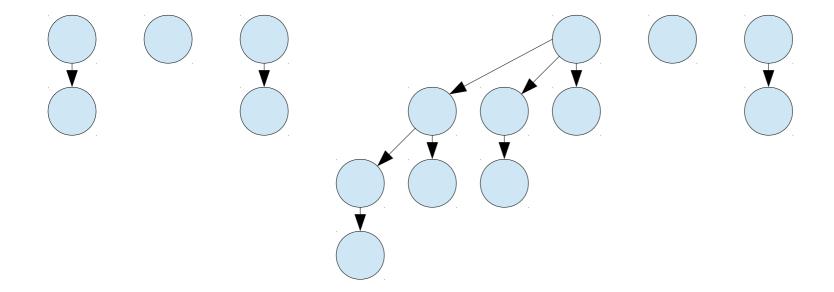


T is the number of trees.



$$\Phi = T$$

T is the number of trees.

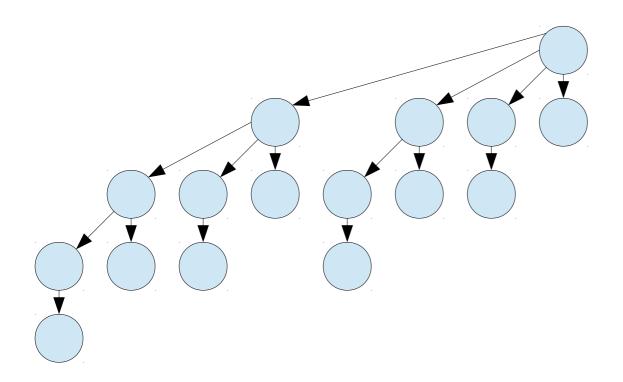


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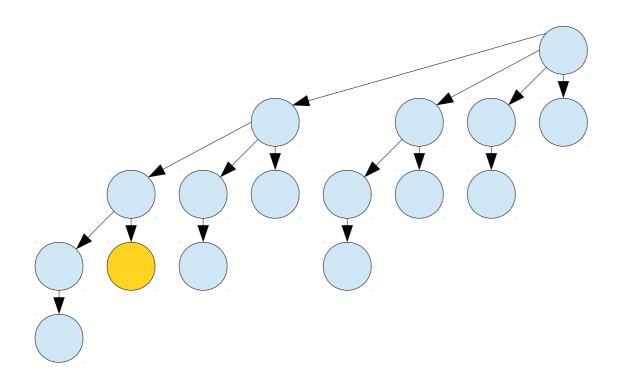
$$\Phi = T + M$$

T is the number of trees and *M* is the number of marked nodes.



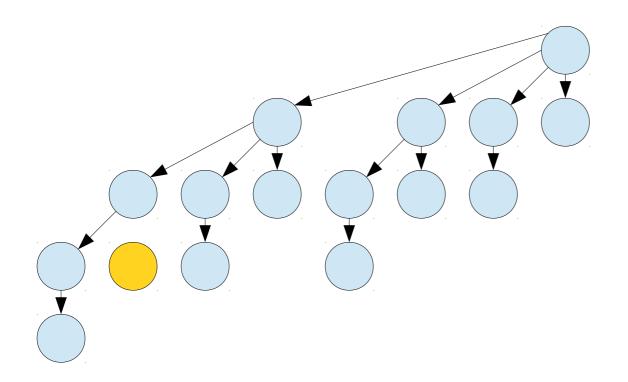
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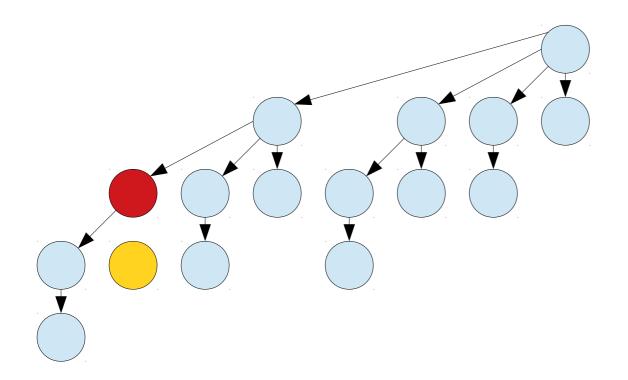
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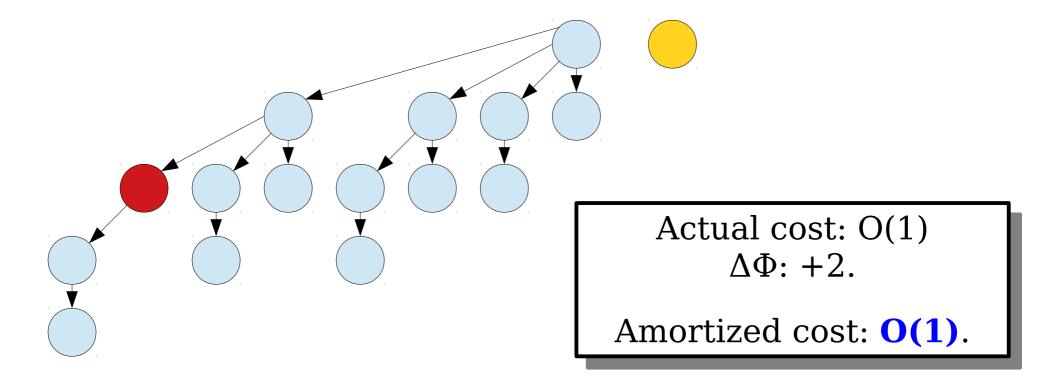
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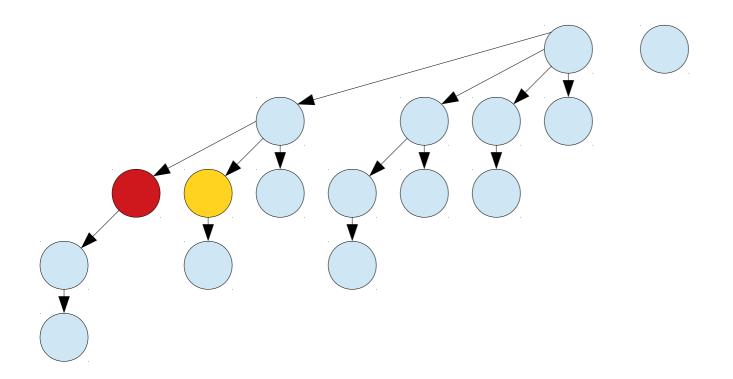
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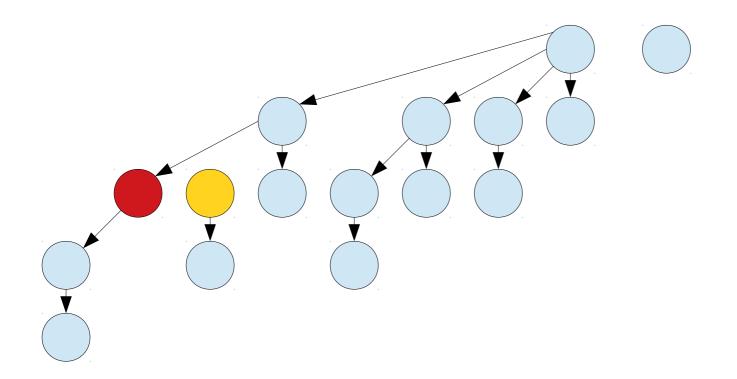
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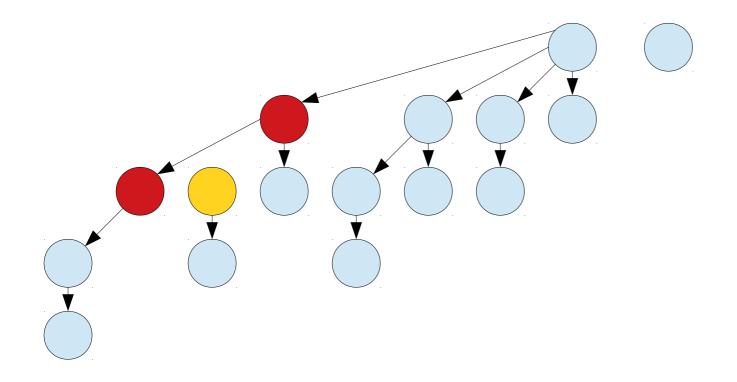
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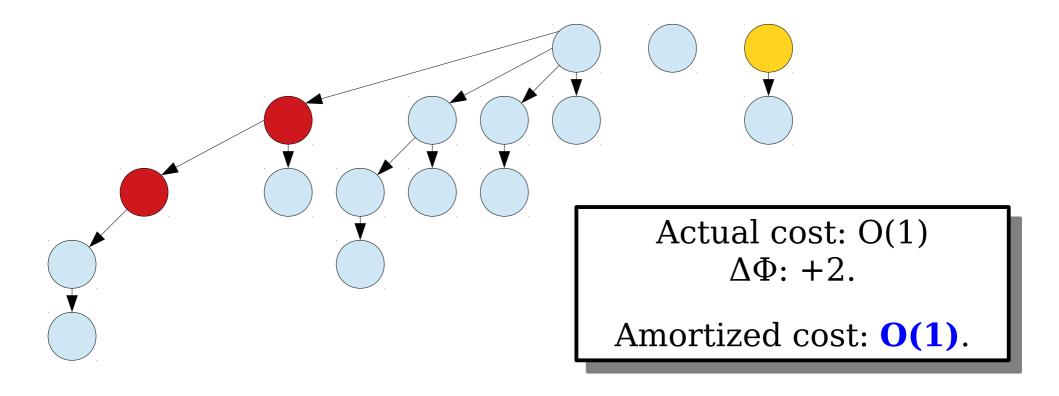
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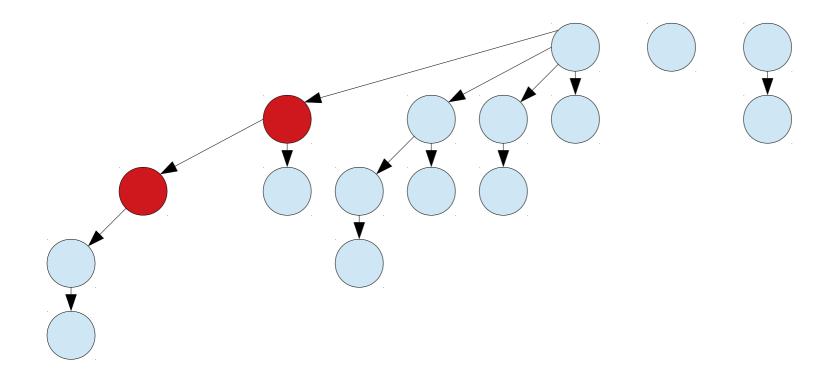
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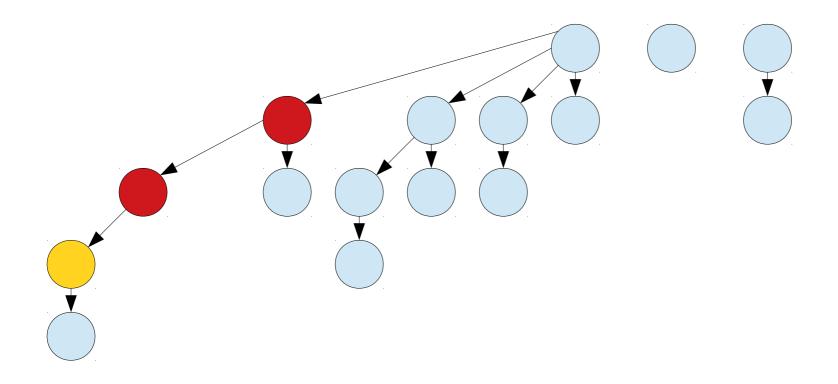
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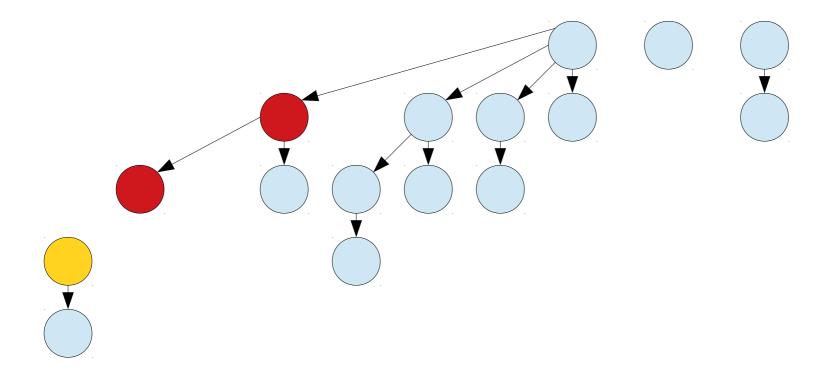
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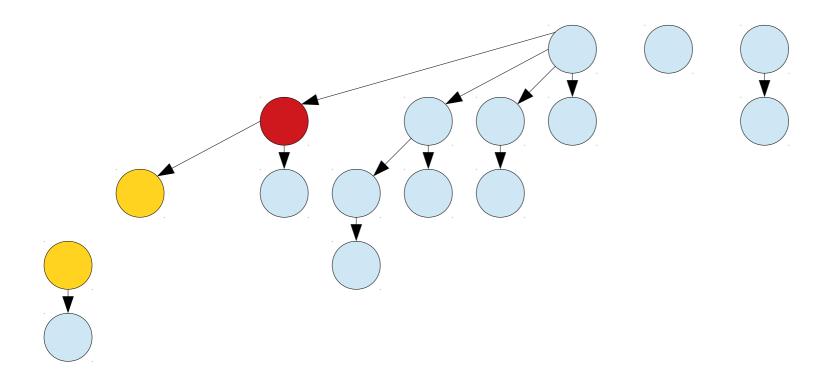
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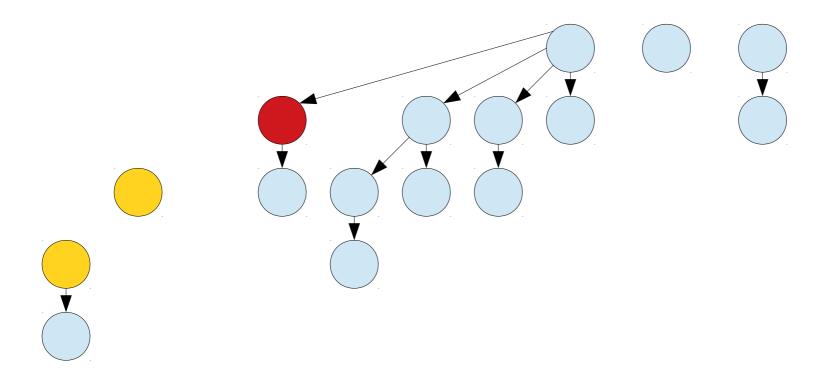
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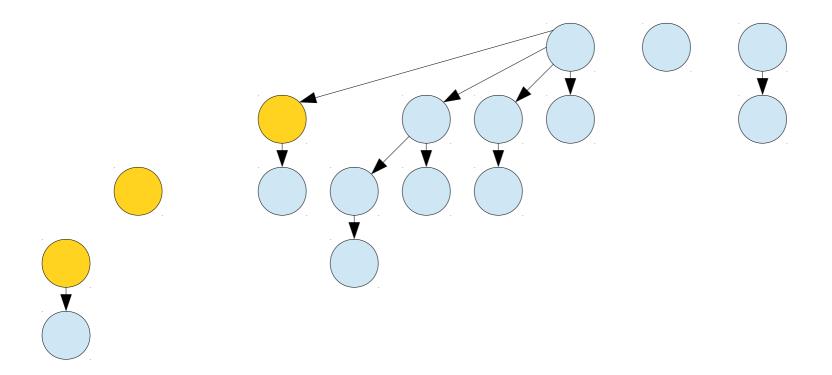
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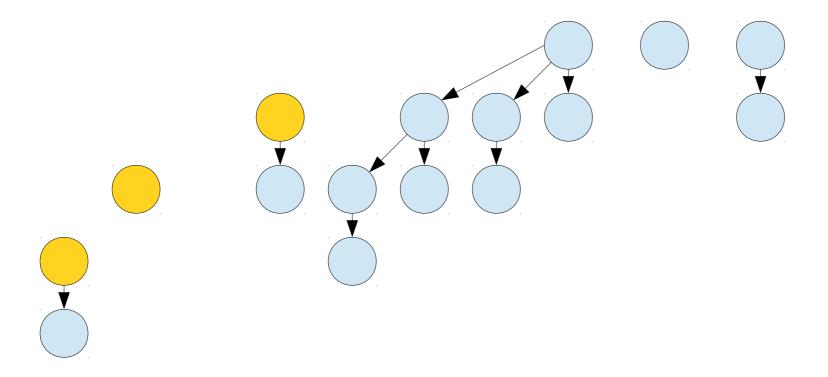
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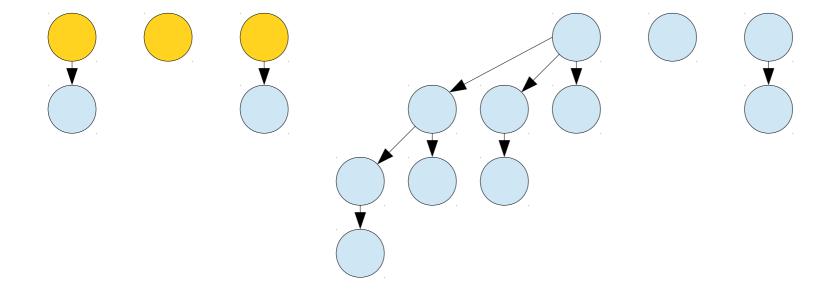
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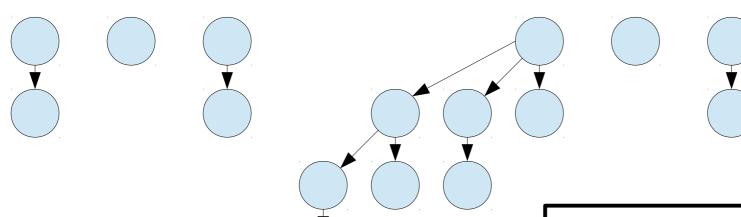
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T is the number of trees and M is the number of marked nodes.



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T is the number of trees and M is the number of marked nodes.



Suppose this operation did *C* total cuts.

Actual cost: O(C) $\Delta\Phi$: +1

Amortized cost: O(C).

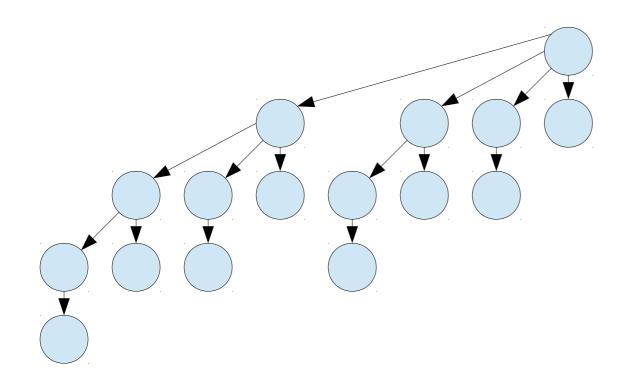
$$\Phi = T + M$$

T is the number of trees and M is the number of marked nodes.

Idea 2: Each *decrease-key* hurts twice: once in a cascading cut, and once in an *extract-min*.

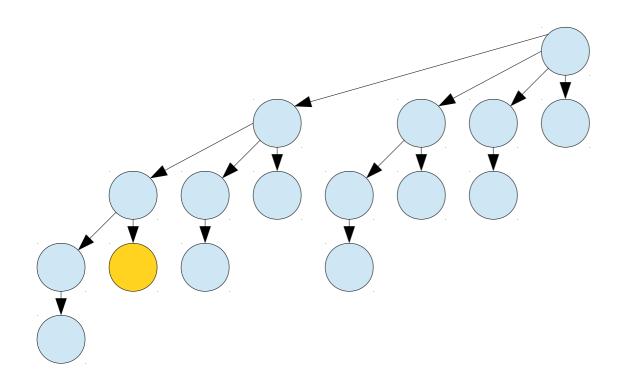
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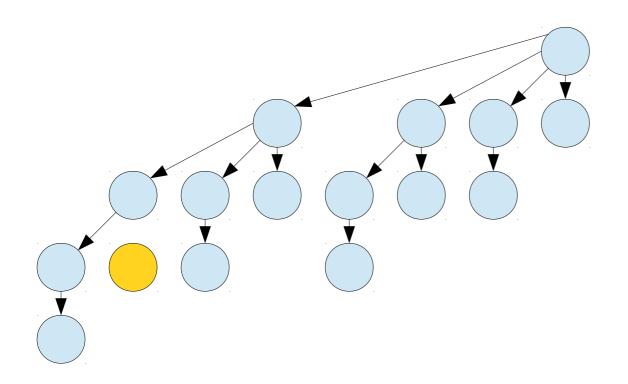
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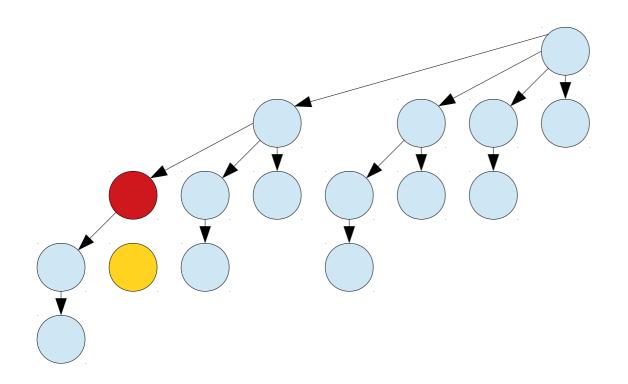
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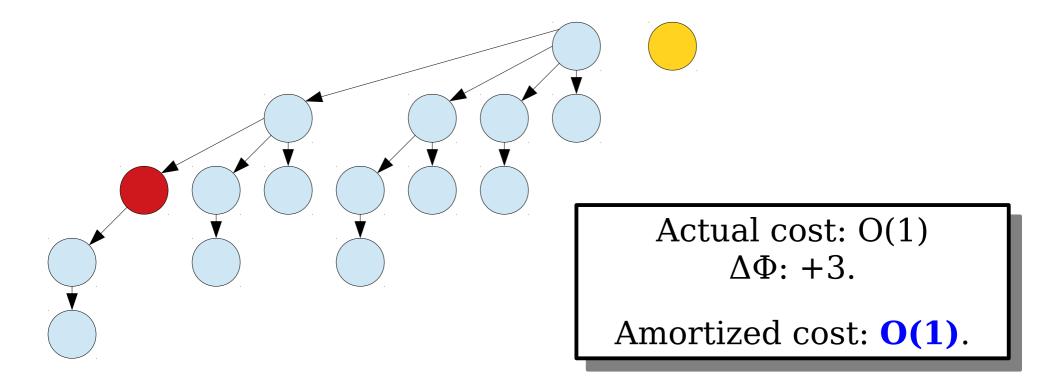
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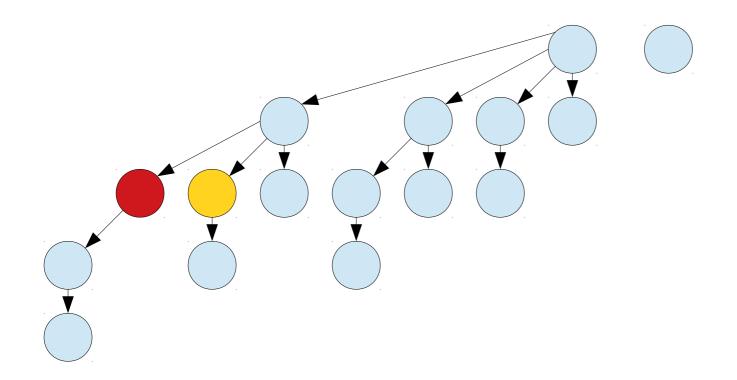
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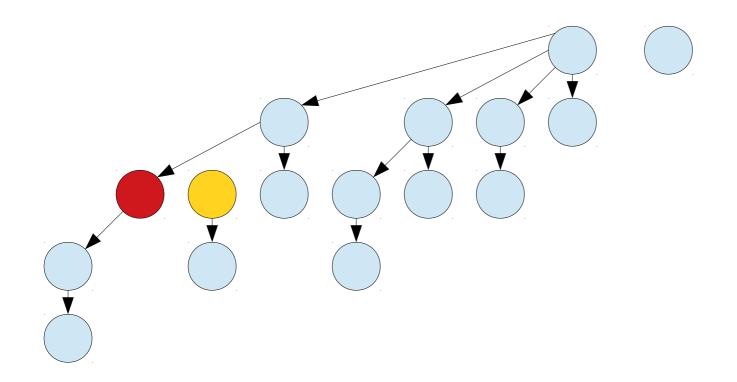
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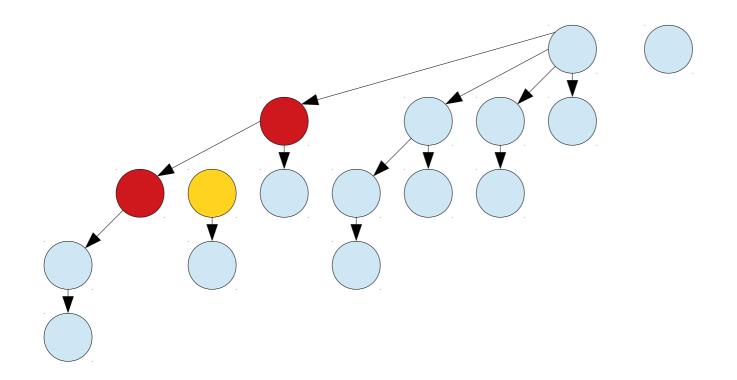
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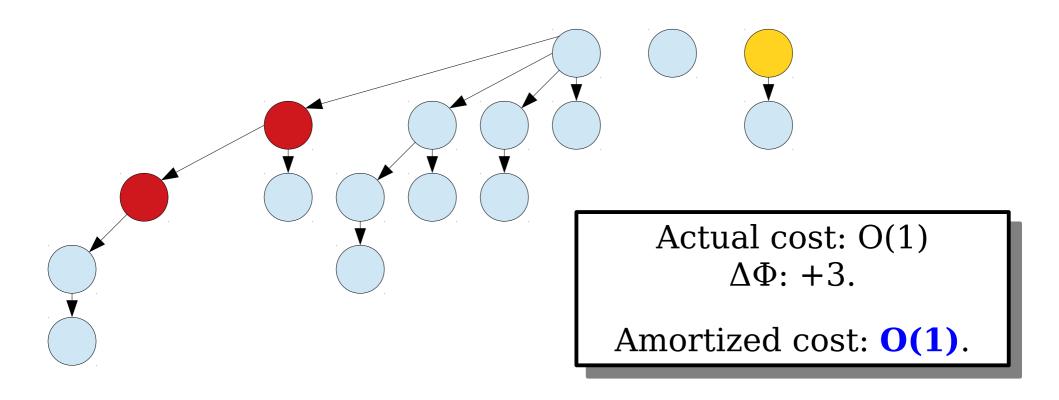
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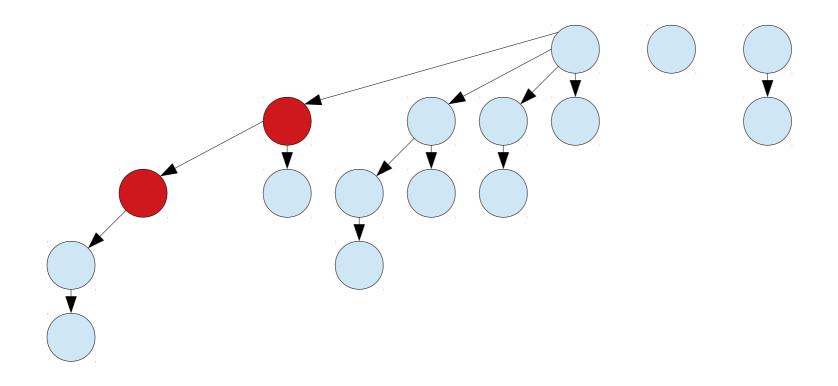
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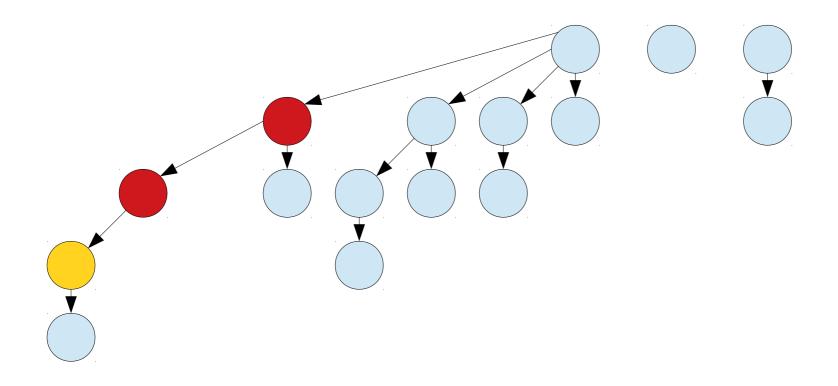
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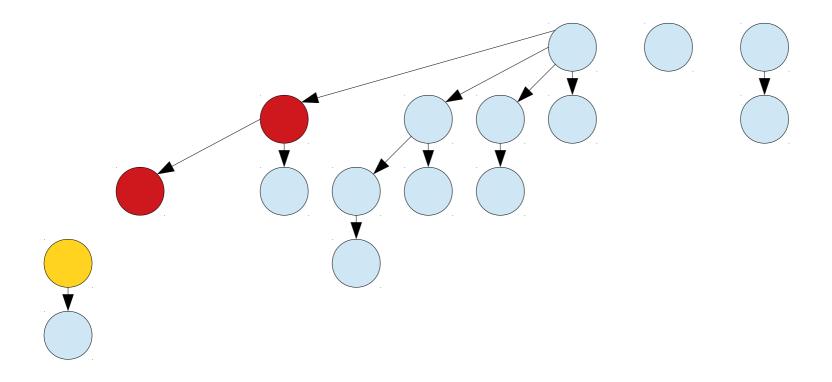
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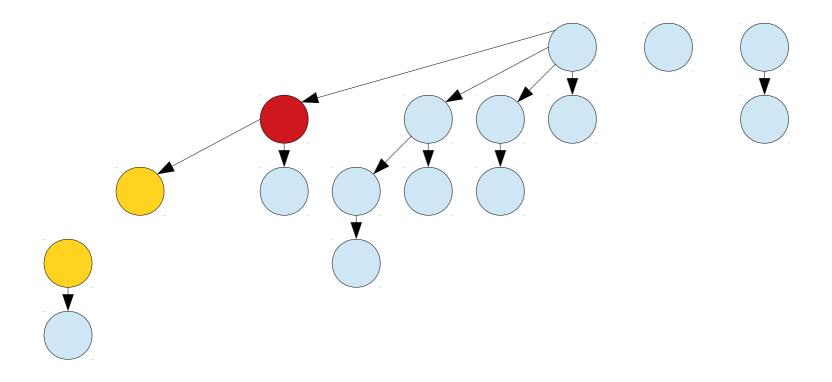
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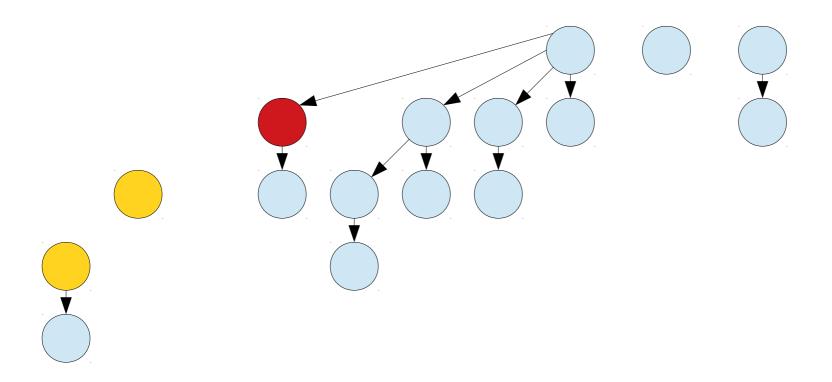
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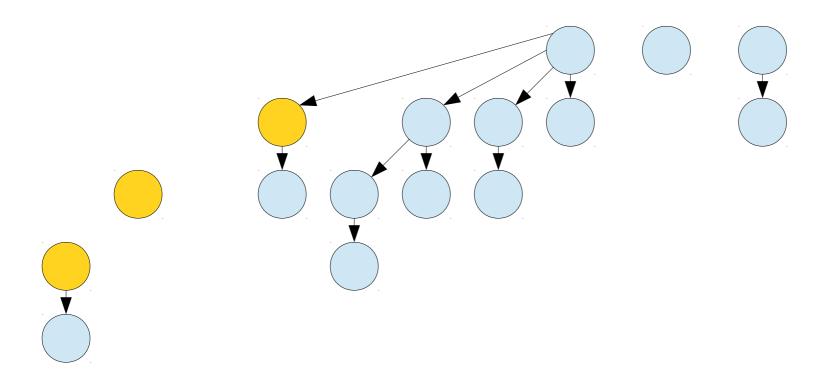
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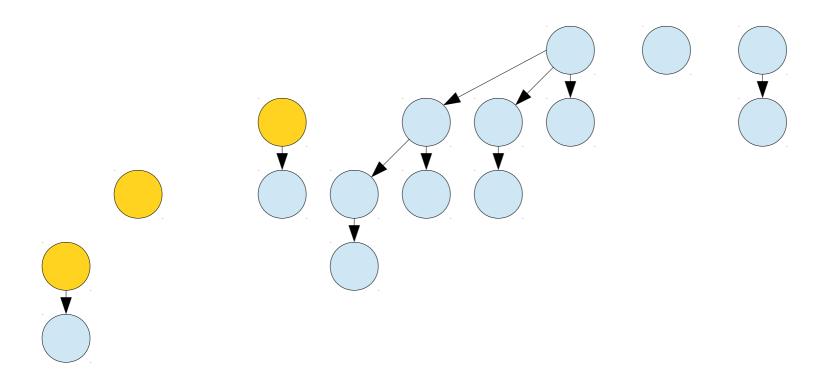
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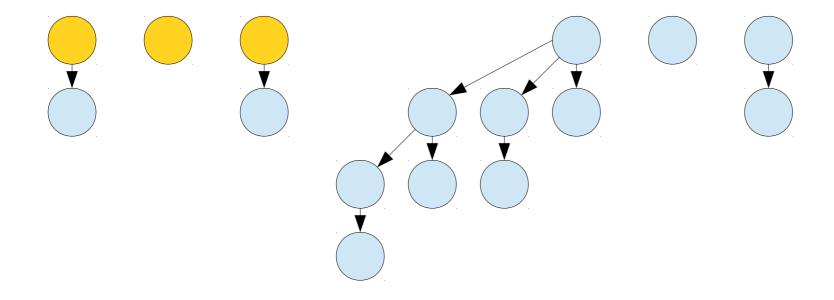
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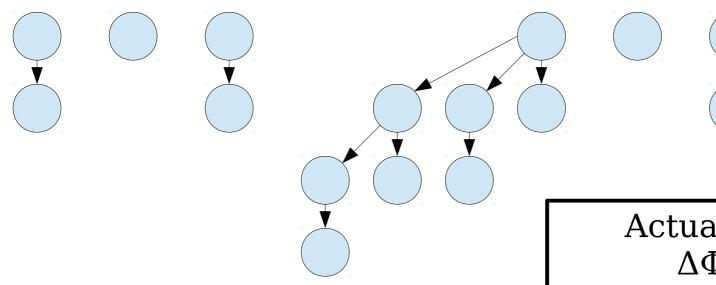
$$\Phi = T + 2M$$



Idea 2: Each *decrease-key* hurts twice: once in a cascading cut, and once in an *extract-min*.

$$\Phi = T + 2M$$

T is the number of trees and M is the number of marked nodes.



Actual cost: O(C)

 $\Delta\Phi$: -C + 1

Amortized cost: **O(1)**.

Idea 2: Each *decrease-key* hurts twice: once in a cascading cut, and once in an *extract-min*.

The Overall Analysis

- Here's the final scorecard for the Fibonacci heap.
- These are excellent theoretical runtimes. There's minimal room for improvement!
- Later work made all these operations worst-case efficient at a significant increase in both runtime and intellectual complexity.

enqueue: O(1)

find-min: O(1)

meld: O(1)

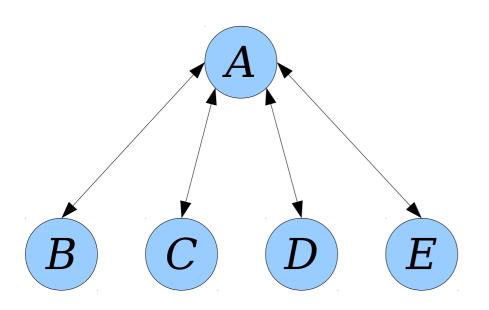
extract-min: $O(\log n)^*$

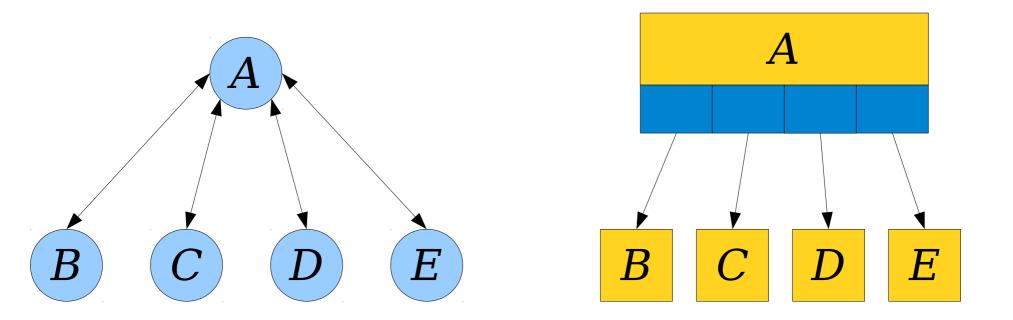
decrease-key: O(1)*

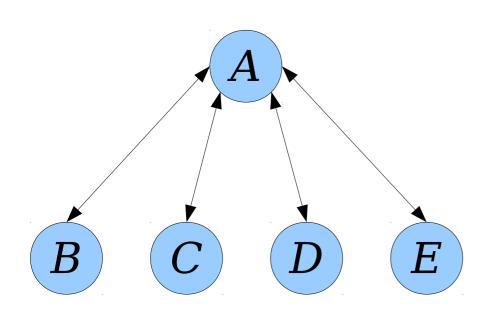
*amortized

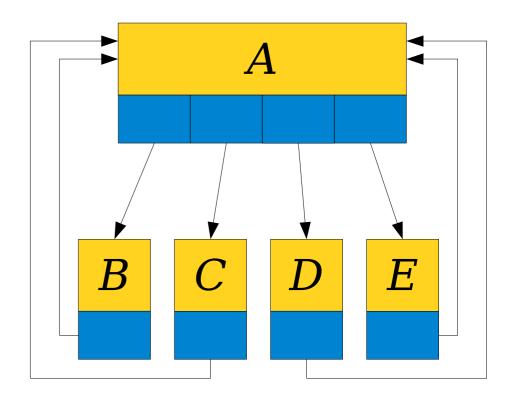
Representation Issues

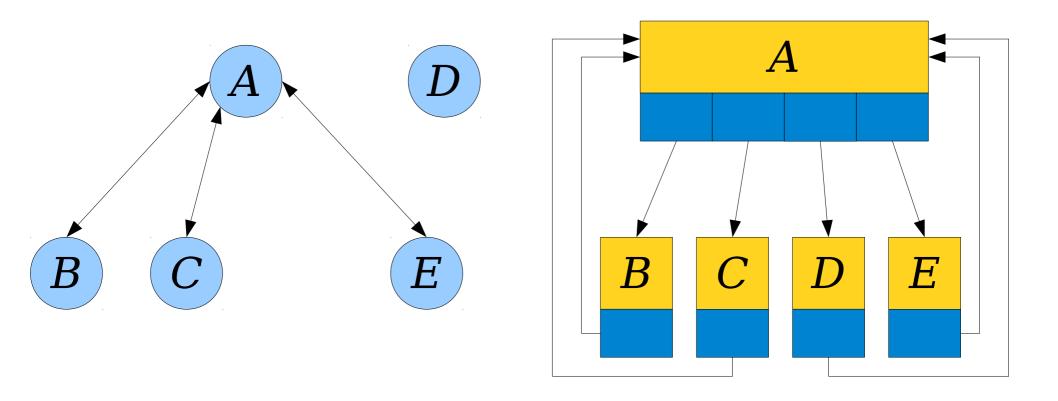
- The trees in a Fibonacci heap must be able to do the following:
 - During a merge: Add one tree as a child of the root of another tree.
 - During a cut: Cut a node from its parent in time O(1).
- *Claim:* This is trickier than it looks.

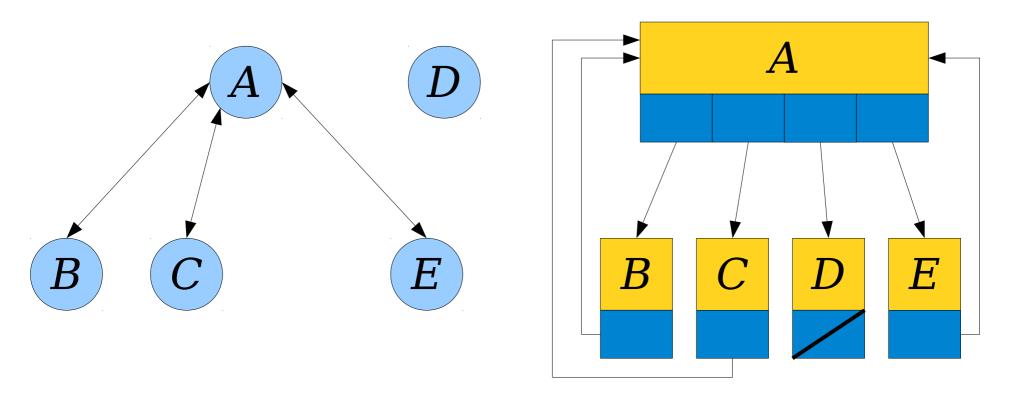


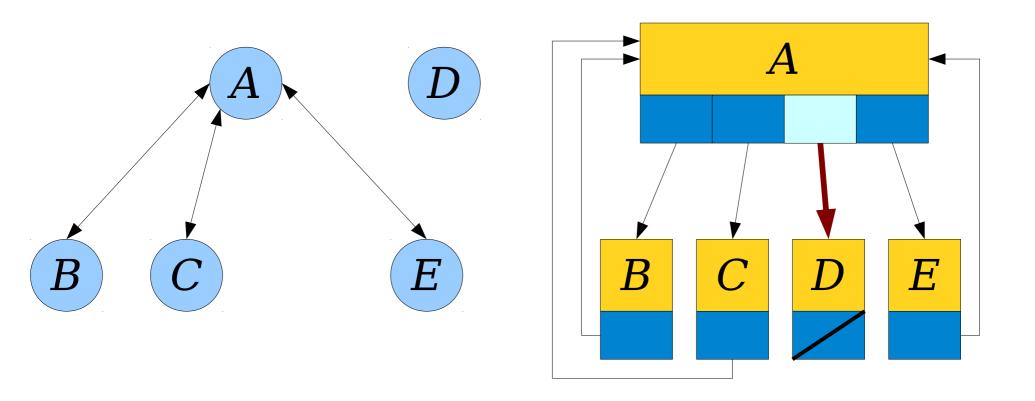


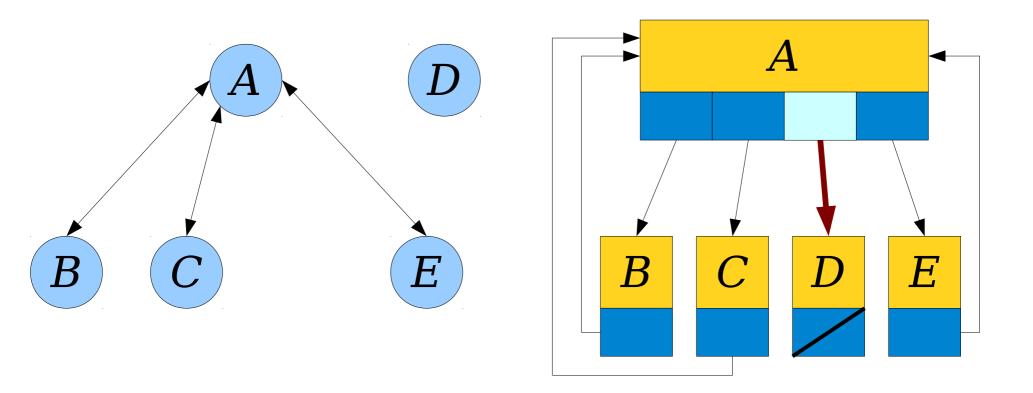












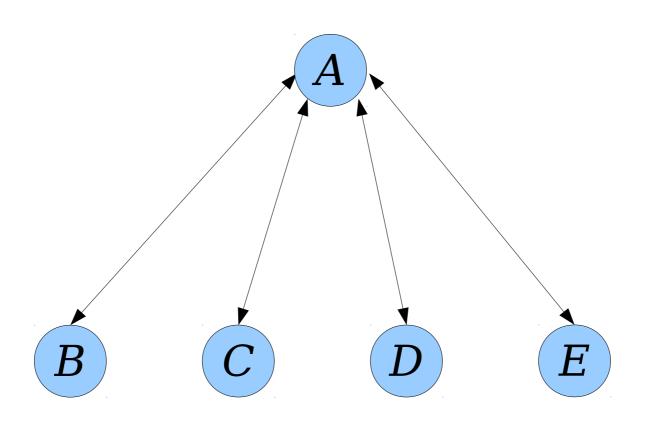
Finding this pointer might take time $\Theta(\log n)!$

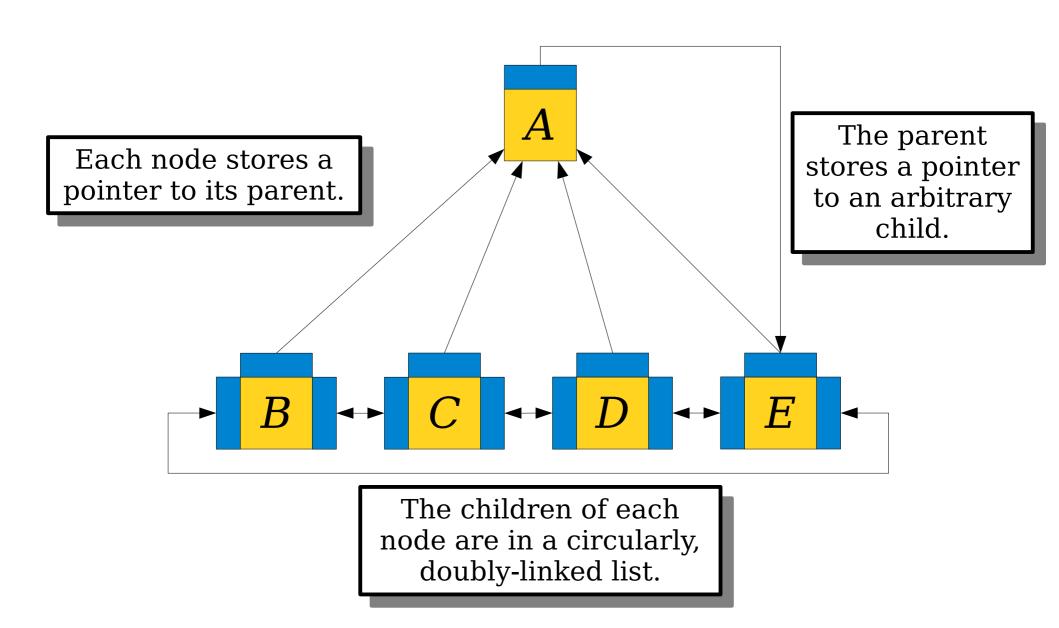
The Solution

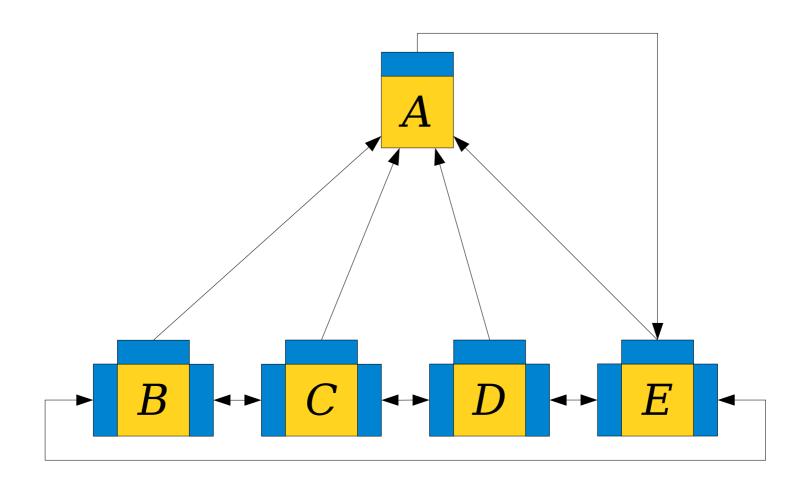
The Solution

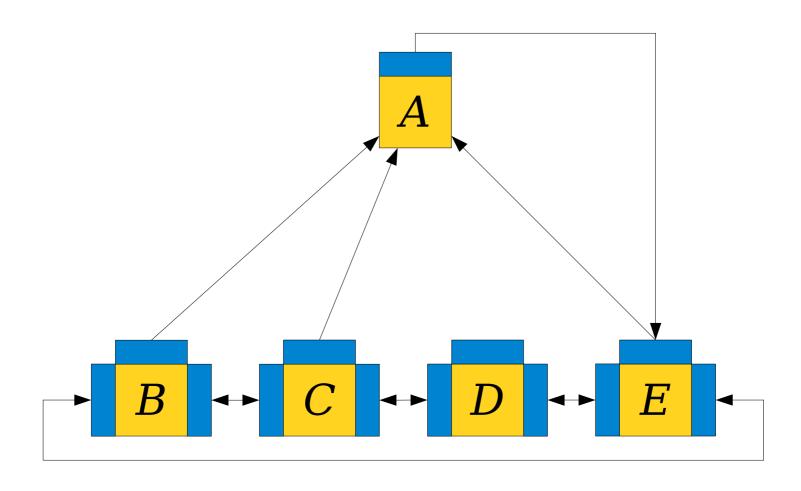
This is going to be weird.

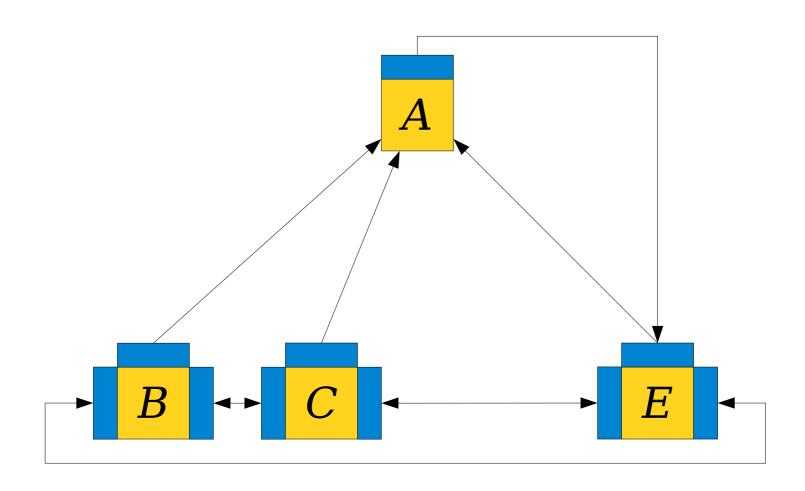
Sorry.

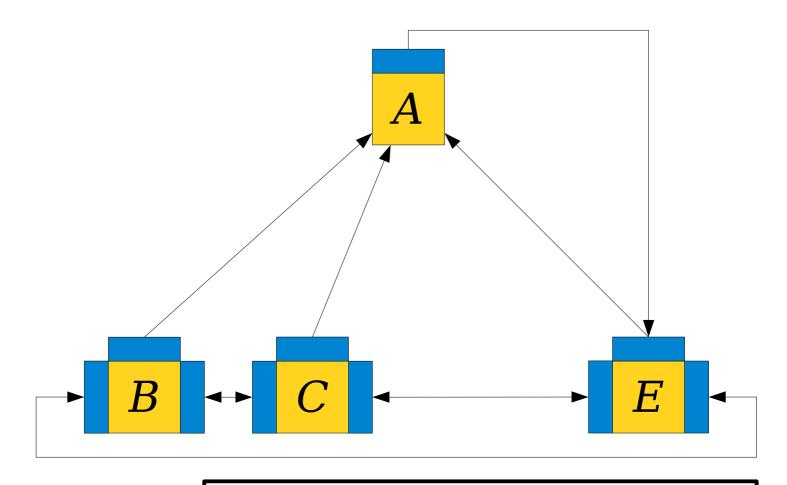




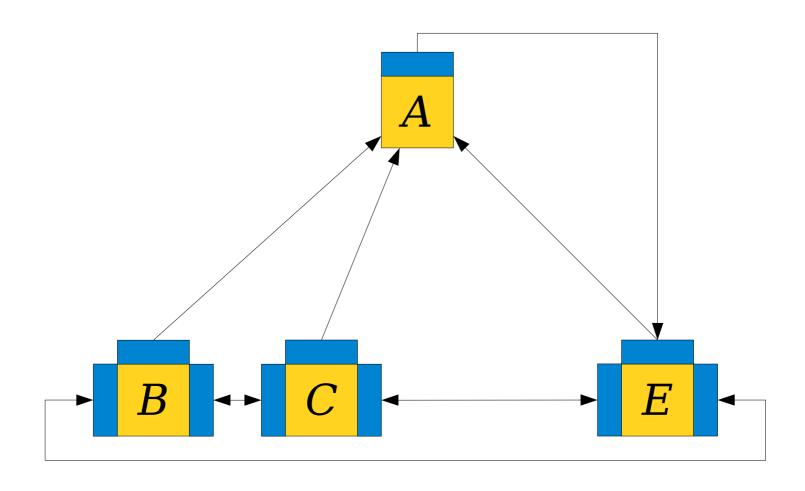


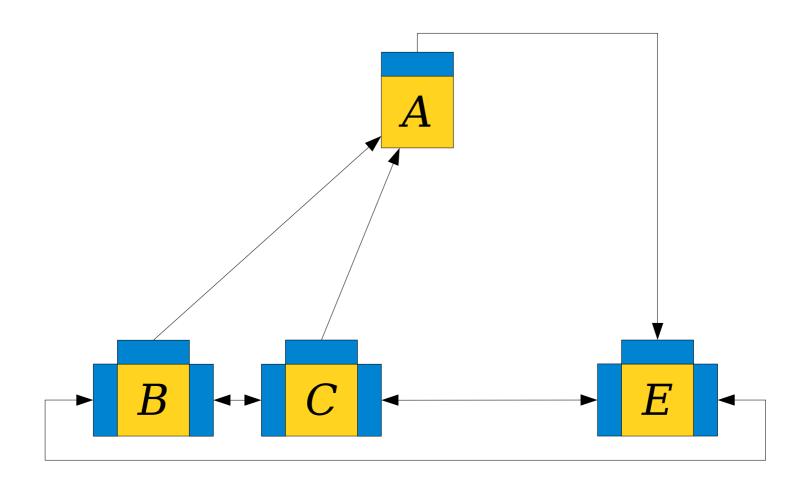


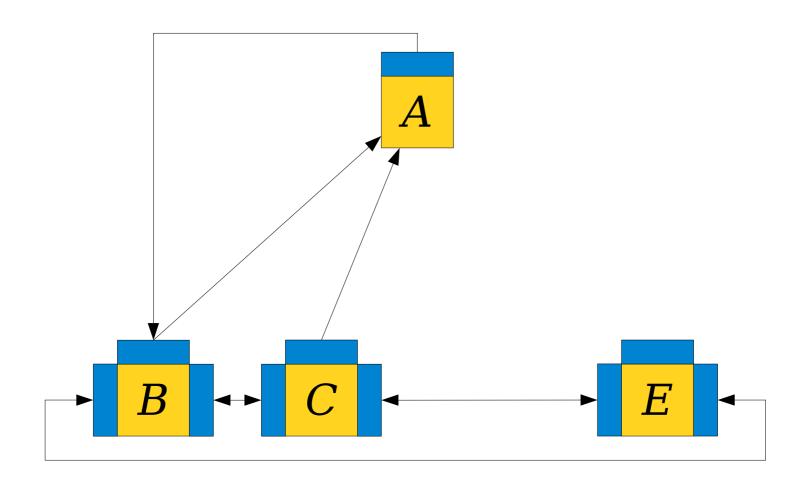


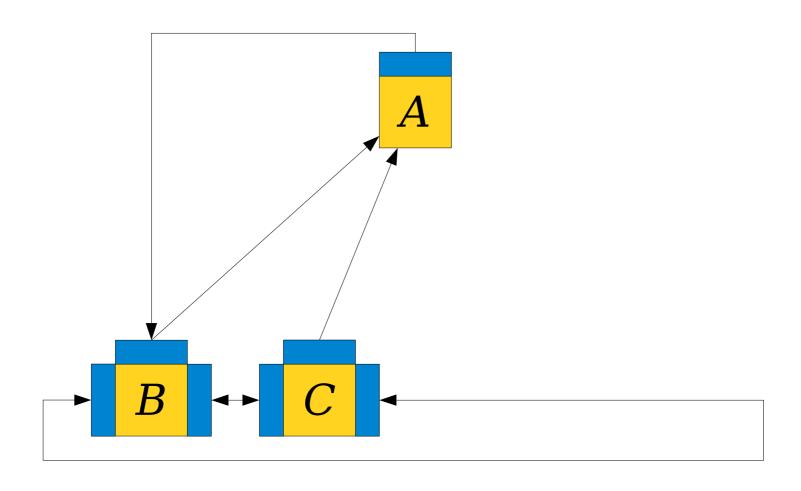


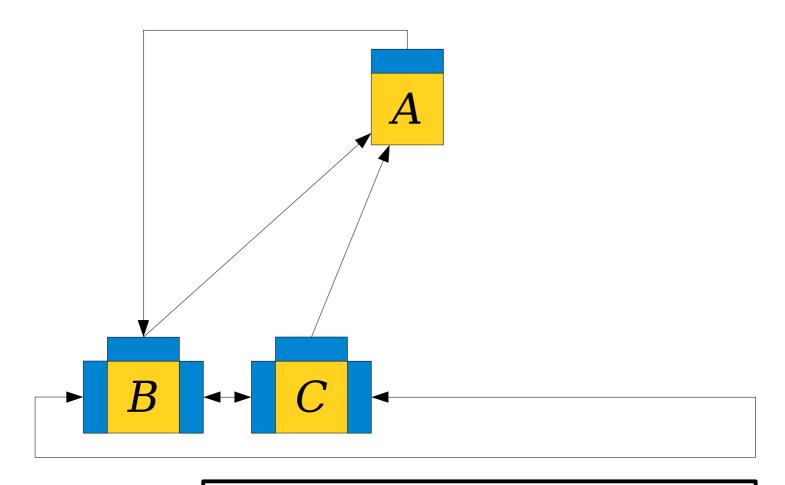
To cut a node from its parent, if it isn't the representative child, just splice it out of its linked list.











If it is the representative, change the parent's representative child to be one of the node's siblings.

Awful Linked Lists

- Trees are stored as follows:
 - Each node stores a pointer to some child.
 - Each node stores a pointer to its parent.
 - Each node is in a circularly-linked list of its siblings.
- The following possible are now possible in time O(1):
 - Cut a node from its parent.
 - Add another child node to a node.

Fibonacci Heap Nodes

- Each node in a Fibonacci heap stores
 - A pointer to its parent.
 - A pointer to the next sibling.
 - A pointer to the previous sibling.
 - A pointer to an arbitrary child.
 - A bit for whether it's marked.
 - Its order.
 - Its key.
 - Its element.

In Practice

• In practice, the constant factors on Fibonacci heaps make it slower than other heaps, except on huge graphs or workflows with tons of *decrease-key*s.

• Why?

- Huge memory requirements per node.
- High constant factors on all operations.
- Poor locality of reference and caching.

In Theory

- That said, Fibonacci heaps are worth knowing about for several reasons:
 - Clever use of a two-tiered potential function shows up in lots of data structures.
 - Implementation of *decrease-key* forms the basis for many other advanced priority queues.
 - Gives the theoretically optimal comparisonbased implementation of Prim's and Dijkstra's algorithms.

More to Explore

- Since the development of Fibonacci heaps, there have been a number of other priority queues with similar runtimes.
 - In 1986, a powerhouse team (Fredman, Sedgewick, Sleator, and Tarjan) invented the *pairing heap*. It's much simpler than a Fibonacci heap, is fast in practice, but its runtime bounds are unknown!
 - In 2012, Brodal et al. invented the *strict Fibonacci heap*. It has the same time bounds as a Fibonacci heap, but in a *worst-case* rather than *amortized* sense.
 - In 2013, Chan invented the *quake heap*. It matches the asymptotic bounds of a Fibonacci heap but uses a totally different strategy.
- Also interesting to explore: if the weights on the edges in a graph are chosen from a continuous distribution, the expected number of *decrease-key*s in Dijkstra's algorithm is $O(n \log (m / n))$. That might counsel another heap structure!

Next Time

Static Optimality

Can we outperform a balanced BST?
 (Answer: yes, in some cases!)

Splay Trees

Reshaping trees in response to queries.

• Dynamic Optimality

• Is there a single best binary search tree data structure?