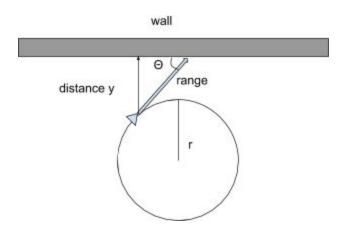
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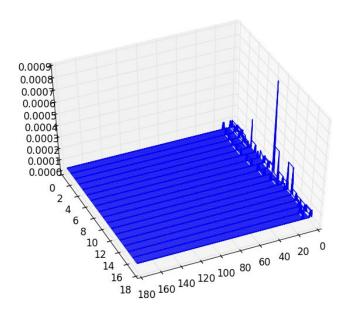
varunshi - 50244968

Question 1:



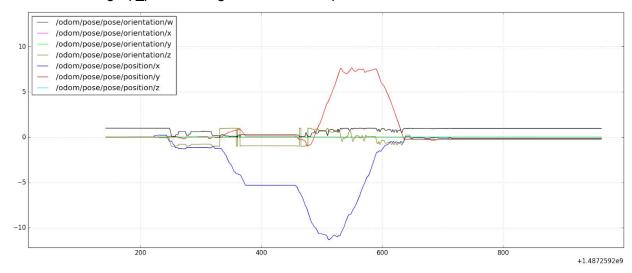
Using a state space of y vs theta since there are no landmarks along the wall to localize along x

Result at t = 1s for space of theta ranging from 0-180 degrees, distance ranging from 0-18 and probability on the vertical axis after running *question1.py* (*Python 2*).



Question 3:

Result of running rqt_plot listening on the /odom topic



Result of running *reorder.py* to order the messages in the bag followed by running *question3.py* to plot locations of tag data after clustering alongwith odometry data from corresponding timestamps.

