

# Special Topics in Applications (AIL861)

## Artificial Intelligence for Earth Observation

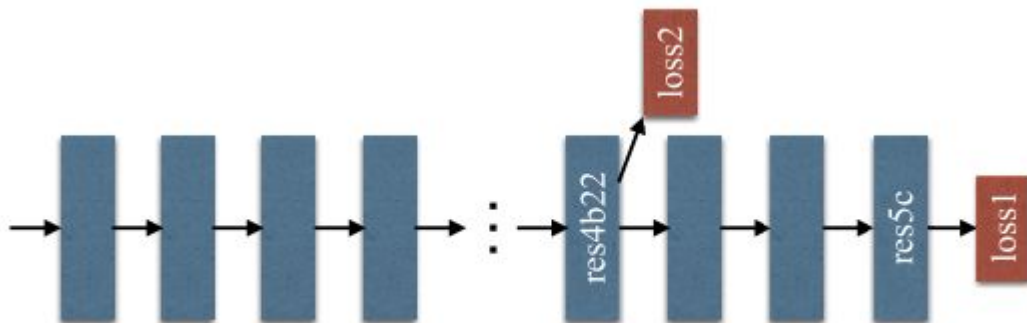
### Lecture 12

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# Deep Supervision

“Deep pretrained networks lead to good performance [17, 33, 13]. However, increasing depth of the network may introduce additional optimization difficulty as shown in [32, 19] for image classification. ResNet solves this problem with skip connection in each block. Latter layers of deep ResNet mainly learn residues based on previous ones. We contrarily propose generating initial results by supervision with an additional loss, and learning the residue afterwards with the final loss. Thus, optimization of the deep network is decomposed into two, each is simpler to solve.

An example of our deeply supervised ResNet101 [13] model is illustrated in Fig. 4. Apart from the main branch using softmax loss to train the final classifier, another classifier is applied after the fourth stage, i.e., the res4b22 residue block.”



Source: Pyramid Scene Parsing Network, 2017

<https://github.com/kazuto1011/pspnet-pytorch/blob/master/libs/models/pspnet.py>

See line 118, 122, 95-111

# Channel Attention

```
class SELayer(nn.Module):  
    def __init__(self, channel, reduction=16):  
        super(SELayer, self).__init__()  
        self.avg_pool = nn.AdaptiveAvgPool2d(1)  
        self.fc = nn.Sequential(  
            nn.Linear(channel, channel // reduction, bias=False),  
            nn.ReLU(inplace=True),  
            nn.Linear(channel // reduction, channel, bias=False),  
            nn.Sigmoid()  
        )  
  
    def forward(self, x):  
        b, c, _, _ = x.size()  
        y = self.avg_pool(x).view(b, c)  
        y = self.fc(y).view(b, c, 1, 1)  
        return x * y.expand_as(x)
```

[https://github.com/moskomule/senet.pytorch/blob/master/senet/se\\_module.py#L4](https://github.com/moskomule/senet.pytorch/blob/master/senet/se_module.py#L4)

# Channel Attention (Alternate Implementation)

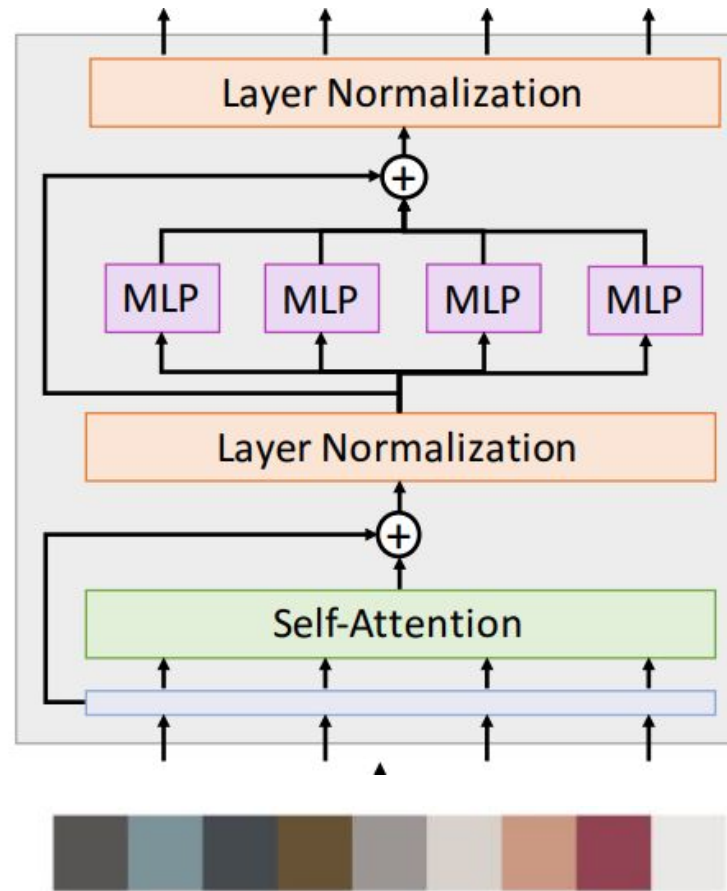
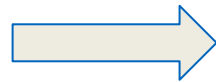
```
class ChannelAttention(nn.Module):  
    def __init__(self, in_channels, ratio = 16):  
        super(ChannelAttention, self).__init__()  
        self.avg_pool = nn.AdaptiveAvgPool2d(1)  
        self.max_pool = nn.AdaptiveMaxPool2d(1)  
        self.fc1 = nn.Conv2d(in_channels, in_channels//ratio, 1, bias=False)  
        self.relu1 = nn.ReLU()  
        self.fc2 = nn.Conv2d(in_channels//ratio, in_channels, 1, bias=False)  
        self.sigmod = nn.Sigmoid()  
    def forward(self, x):  
        avg_out = self.fc2(self.relu1(self.fc1(self.avg_pool(x))))  
        max_out = self.fc2(self.relu1(self.fc1(self.max_pool(x))))  
        out = avg_out + max_out  
        return self.sigmod(out)
```

<https://github.com/likyoo/Siam-NestedUNet/blob/master/models/Models.py>

# Transformer: Global Context

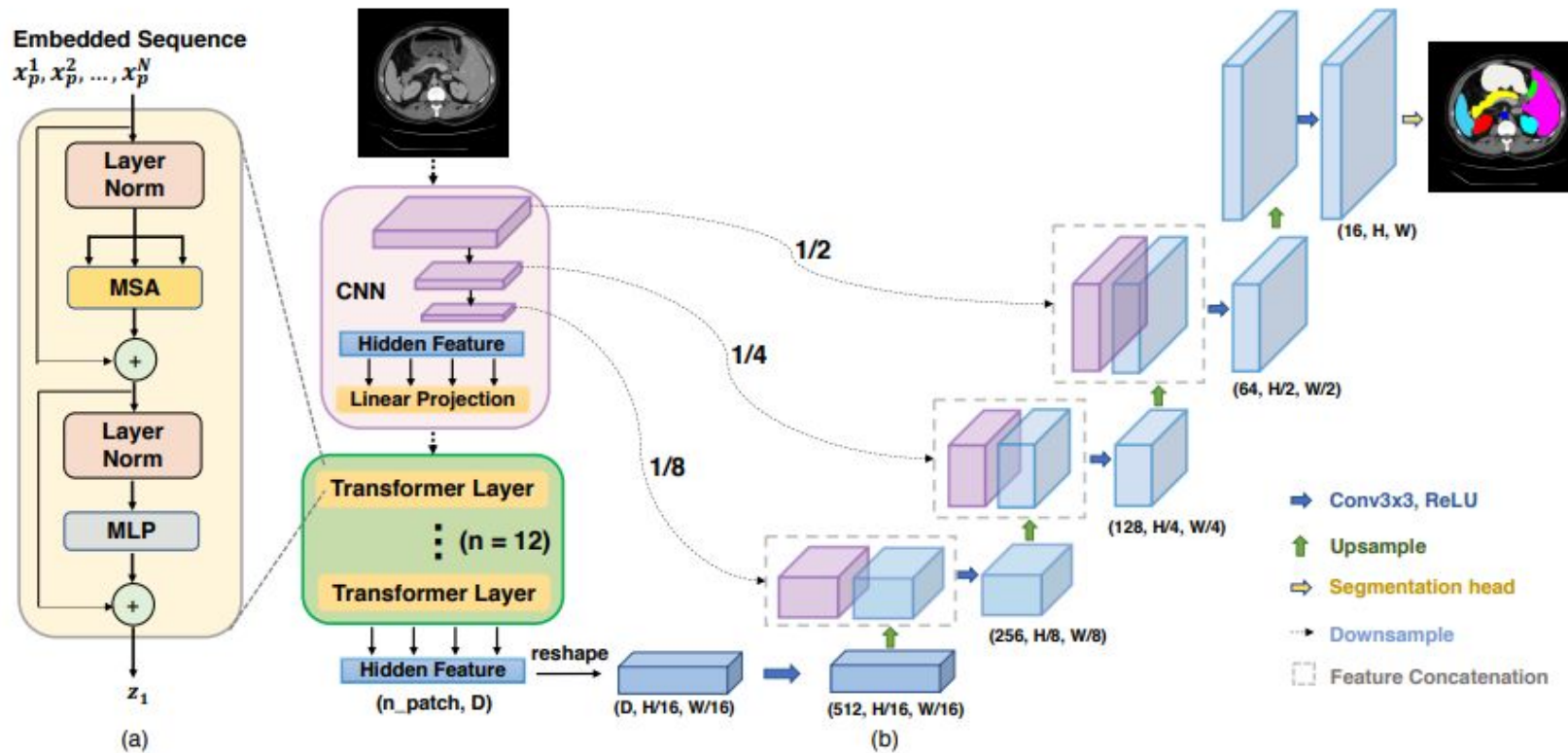
- Initially introduced in NLP
- Sentences are processed as a whole, instead of word by word
- Since sentence is processed as a whole, it does not “forget”
- Parallelism

# Vision Transformer



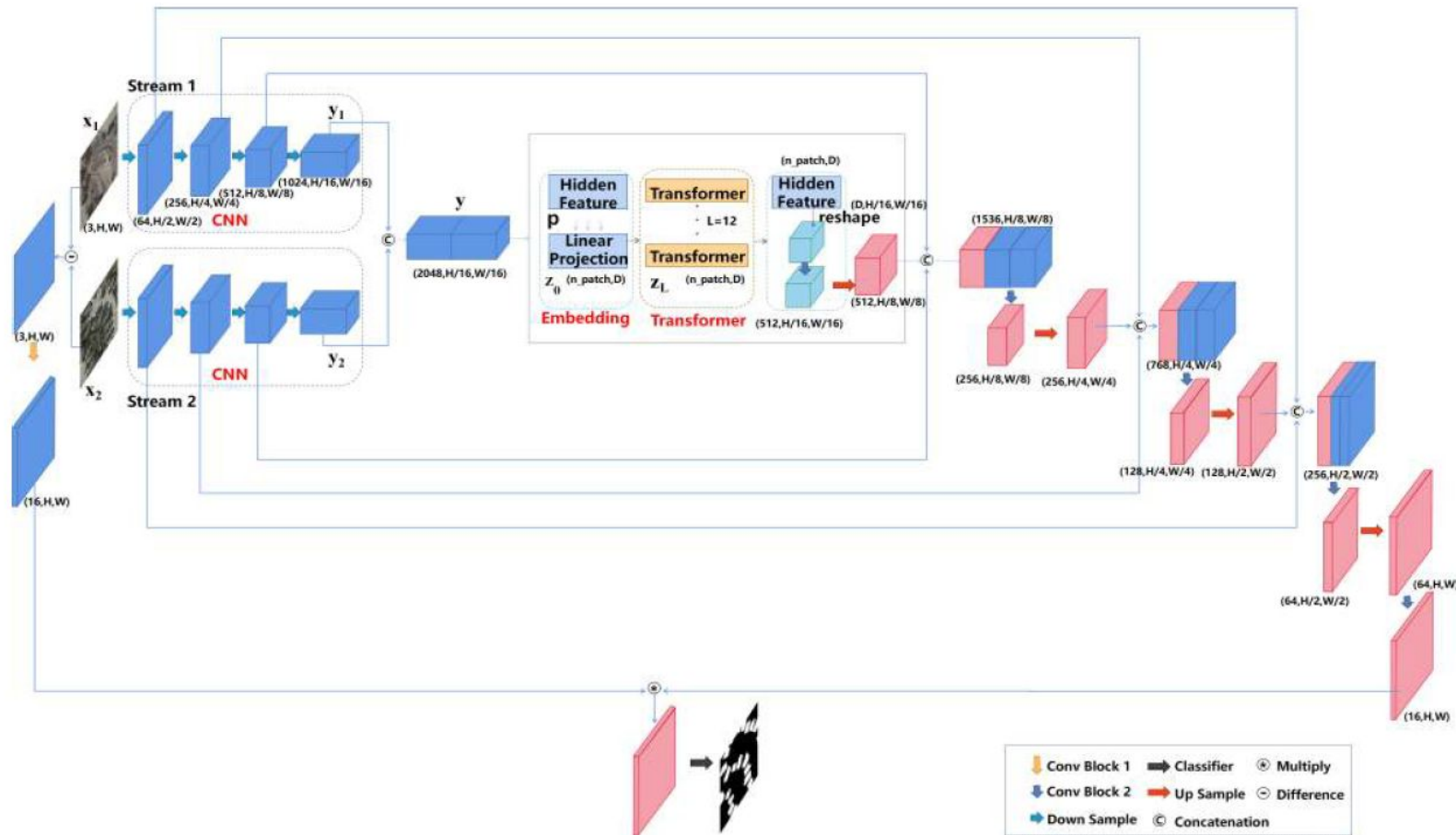
# Transformer-Based Segmentation or Change Detection

## TransUNet





# TransUNet for CD



TransUNetCD: A Hybrid Transformer Network for Change Detection in Optical Remote-Sensing Images