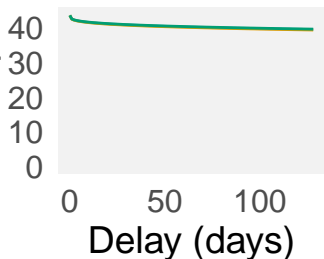


Indifference point (...)



frame

- neutral
- defer
- speedup

task: defer\_speedup  
pid: 064  
model: DDM  
pmz: time\_scaling\_t0