1.

(a) The signal  $\cos(\Pi n/2)$  can be broken up into a sum of two exponentials  $x_1[n] = (1/2)e^{j\pi n/2}$  and  $x_2[n] = (1/2)e^{-j\pi n/2}$ . From the given information, we know that  $x_1[n]$  passes through the given LTI system, it experiences a delay of 2 samples the system has a real impulse response, it has an even group delay function. Then the complex exponential  $x_2[n]$  with frequency  $-w_0$  also experiences a group delay samples. The output y[n] of the LTI system when the input is  $x[n] = x_1[n] + x_2[n]$ .

Therefore

$$y[n] = 2x_1[n-2] + 2x_2[n-2] = 2\cos\left(\frac{\pi}{2}(n-2)\right) = 2\cos\left(\frac{\pi}{2}n - \pi\right)$$

(b) The signal  $x[n] = \sin(\frac{7\pi}{2}n + \frac{\pi}{4})$  is the same as  $-\sin(\frac{\pi}{2}n - \frac{\pi}{4})$ . This signal may again be broken up into complex exponentials of frequency  $\frac{\pi}{2}$  and  $-\frac{\pi}{2}$ . We then use an argument similar to the one used in part(a) to argue that the output is

$$y[n] = 2x[n-2] = 2\sin\left(\frac{7\pi}{2}(n-2) + \frac{\pi}{4}\right)$$
$$= 2\sin\left(\frac{7\pi}{2}n - 7\pi + \frac{\pi}{4}\right)$$
$$= 2\sin\left(\frac{7\pi}{2}n - \pi + \frac{\pi}{4}\right)$$
$$= 2\sin\left(\frac{7\pi}{2}n - \frac{3\pi}{4}\right)$$

2.

Taking the Fourier transform of both sides of the h[n] difference equation of and simplifying, we obtain the frequency response  $H(e^{jw})$  of the first filter.

$$H(e^{jw}) = \frac{Y(e^{jw})}{X(e^{jw})} = \frac{\sum_{k=0}^{q} b_k e^{-jwk}}{1 + \sum_{k=1}^{p} a_k e^{-jwk}}$$

Taking the Fourier transform of both sides of the g[n] difference equation and simplifying, we obtain the frequency response  $H(e^{jw})$  of the first filter.

$$G(e^{jw}) = \frac{Y(e^{jw})}{X(e^{jw})} = \frac{\sum_{k=0}^{q} (-1)^k b_k e^{-jwk}}{1 + \sum_{k=1}^{p} (-1)^k a_k e^{-jwk}}$$

This may be also be written as

$$G(e^{jw}) = \frac{Y(e^{jw})}{X(e^{jw})} = \frac{\sum_{k=0}^{q} b_k e^{-j(w-\pi)k}}{1 + \sum_{k=1}^{p} a_k e^{-j(w-\pi)k}} = H (e^{j(w-\pi)})$$

Therefore, the frequency response of the g(n) filter is obtained shifting the frequency response of the first filter by  $\pi$ .

So it's a high-pass filter

3.

(1)

Let us first find the differential equation governing the input and output of this circuit.

Current through resistor and inductor=Current through capacitor= $C \frac{dy(t)}{dt}$ .

Voltage across resistor =  $RC \frac{dy(t)}{dt}$ .

Voltage across inductor =  $LC \frac{d^2y(t)}{dt^2}$ .

Total input voltage = Voltage across inductor + Voltage across resistor + Voltage across capacitor.

Therefore,

$$x(t) = LC \frac{d^2 y(t)}{dt^2} + RC \frac{dy(t)}{dt} + y(t).$$

The frequency response of this circuit is therefore

$$H(jw) = \frac{1}{LC(jw)^2 + RCjw + 1}$$

We may rewrite this to be

H(jw) = 
$$\frac{1}{(\frac{jw}{1/\sqrt{LC}})^2 + 2(R/2)\sqrt{C/L}\frac{jw}{1/\sqrt{LC}} + 1}$$

(2)

 $x(t) = \delta(t)$ , so y(t) = h(t).

H(jw) = 
$$\frac{1/LC}{(jw)^2 + 2(R/2)\sqrt{C/L}\frac{jw}{\sqrt{LC}} + 1/LC}$$

Compare H(jw) to the fraction  $H(j\omega) = \frac{{\omega_n}^2}{(j\omega-c_1)(j\omega-c_2)} = \frac{M_1}{(j\omega-c_1)} - \frac{M_2}{(j\omega-c_2)}$ 

( 
$$c_1, c_2$$
: roots of  $(j\omega)^2 + 2\zeta\omega_n(j\omega) + \omega_n^2 = 0$ ):

$$\omega_n = 1/\sqrt{LC}$$
$$\zeta = (R/2)\sqrt{C/L}$$

If  $\zeta \neq 1$ :

 $h(t) = M[e^{c_1 t} - e^{c_2 t}]u(t)$ , with:

$$\begin{split} c_1 &= -\zeta \omega_n + \omega_n \sqrt{\zeta^2 - 1} = -\frac{R}{2L} + \frac{1}{2L} \sqrt{\frac{R^2C - 4L}{C}}, \quad c_2 = -\zeta \omega_n - \omega_n \sqrt{\zeta^2 - 1} = -\frac{R}{2L} - \frac{1}{2L} \sqrt{\frac{R^2C - 4L}{C}} \\ M_1 &= M_2 = M = \frac{\omega_n}{2\sqrt{\zeta^2 - 1}} = \frac{1}{\sqrt{R^2C^2} - 4LC} \end{split}$$

if  $\zeta = 1$ :

$$h(t) = \omega_n^2 t e^{-\omega_n t} u(t)$$

(3)

The damping constant  $\zeta = (R/2)\sqrt{C/L}$ . In order for the step response to have no oscillations, we must have  $\zeta \geq 1$ . Therefore, we require

$$R \ge 2\sqrt{\frac{L}{C}}$$

4.

(1)

Using the Bode magnitude plot specified in figure 2, we may obtain an expression for H(jw). The figure shows that H(jw) has the break frequencies  $w_1$ =0.2,  $w_2$ =10,  $w_3$ =50. We can conclude that

$$H(jw) = \frac{A(jw + w_1)^2}{(jw + w_2)(jw + w_3)}$$

For w=0, we can calculate A=50000. Then

$$H(jw) = \frac{50000(jw + 0.2)^2}{(jw + 50)(jw + 10)}$$

(2)

