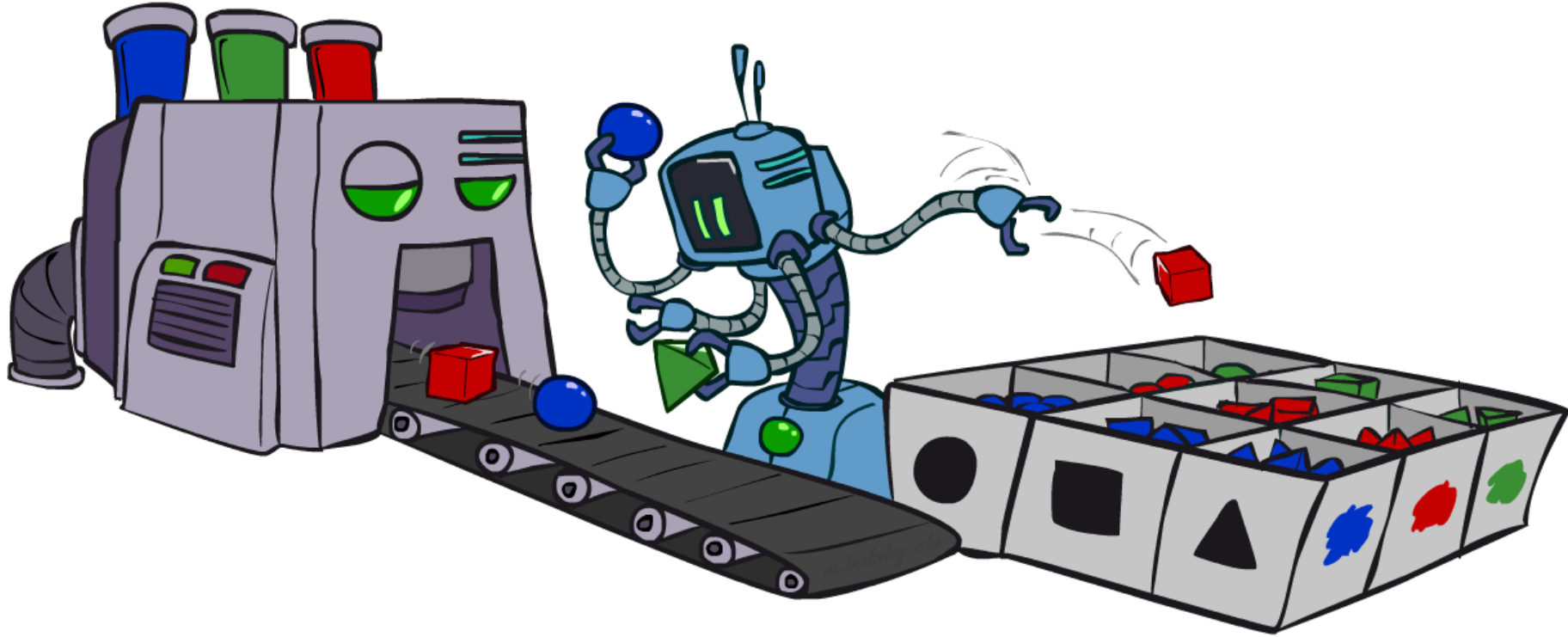


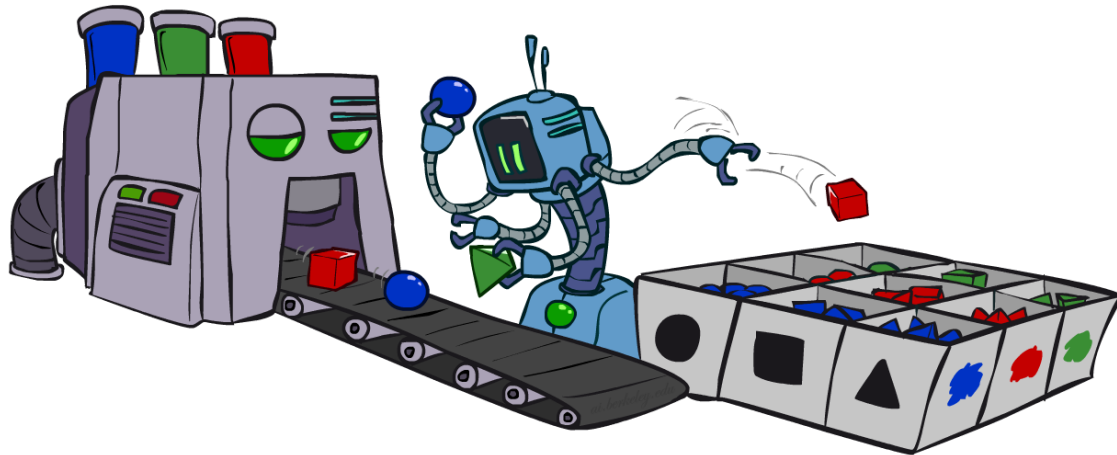
# Bayes Nets: Approximate Inference



AIMA Chapter 14.5, PRML Chapter 11

# Sampling

- Goal: probability  $P$
- Basic idea
  - Draw  $N$  samples from a sampling distribution  $S$
  - Compute some quantity from the samples
  - Show this converges to the true probability  $P$
- Why sample?
  - Often very fast to get a decent approximate answer
  - The algorithms are very simple and general (easy to apply to fancy models)
  - They require very little memory ( $O(n)$ )



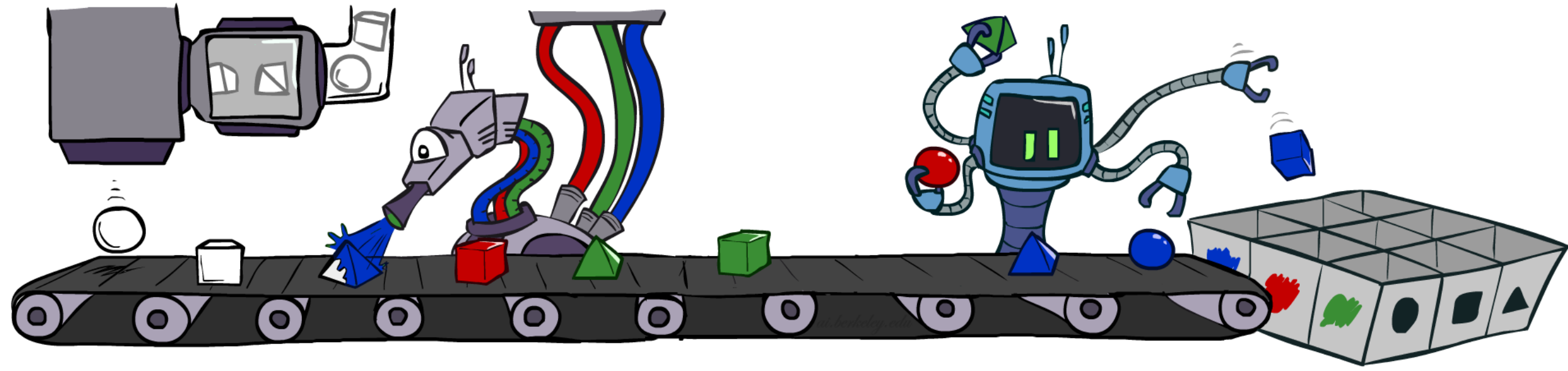
# Sampling in Bayes Nets

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- Prior Sampling
- Rejection Sampling
- Likelihood Weighting
- Gibbs Sampling

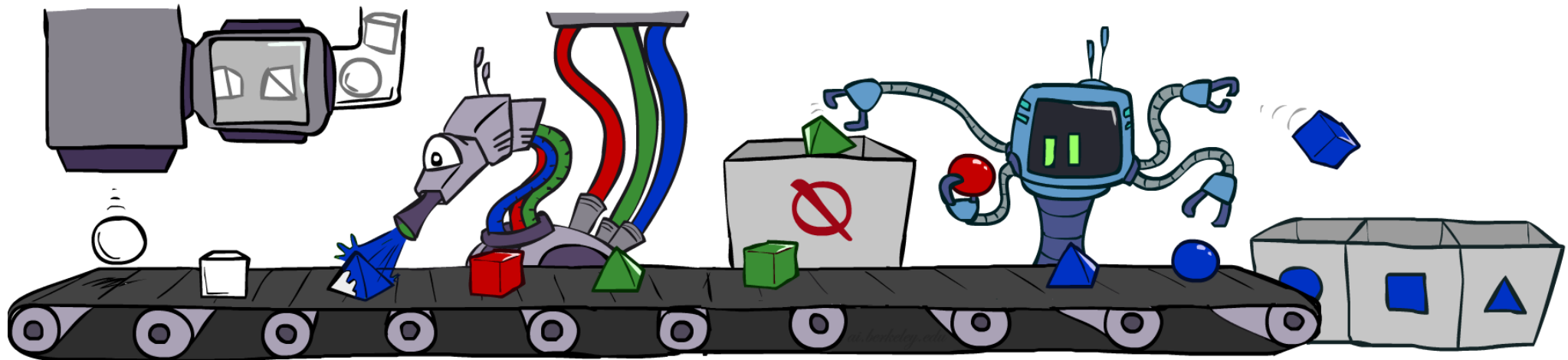
# Prior Sampling

- For  $i=1, 2, \dots, n$  (in topological order)
  - Sample  $X_i$  from  $P(X_i \mid \text{parents}(X_i))$
- Return  $(x_1, x_2, \dots, x_n)$

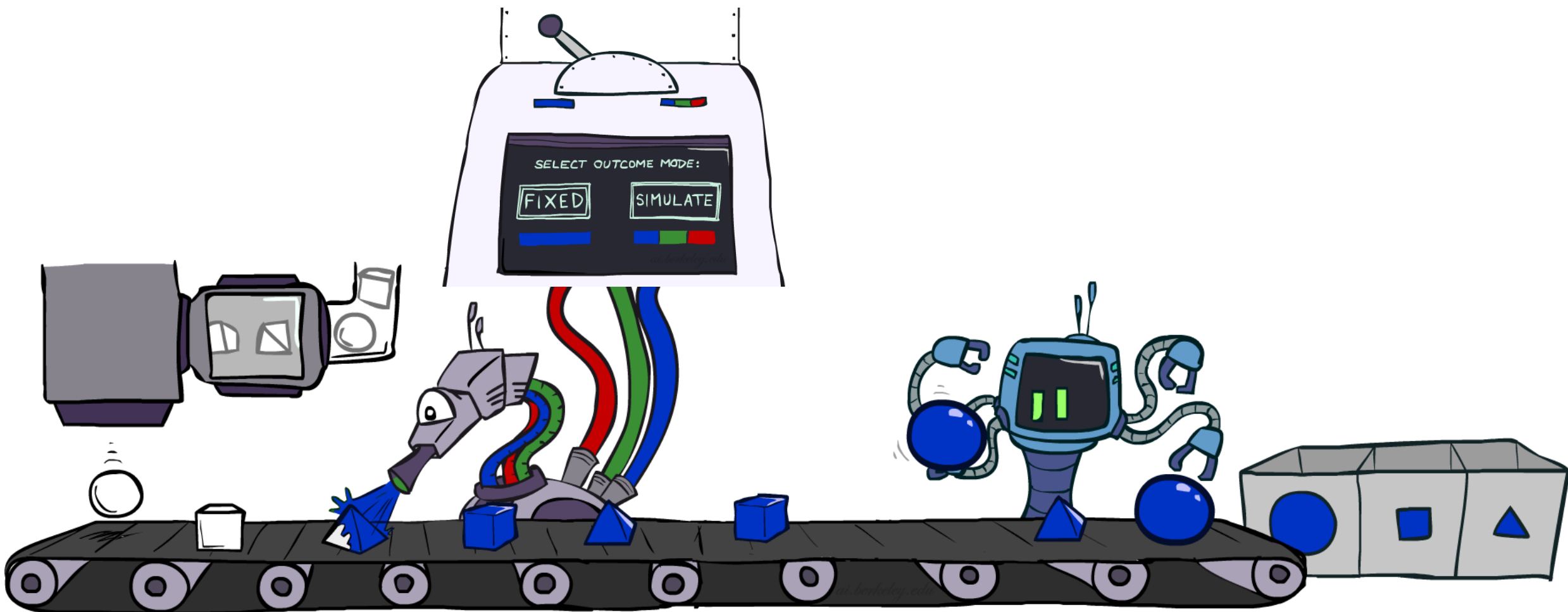


# Rejection Sampling

- Input: evidence  $e_1, \dots, e_k$
- For  $i=1, 2, \dots, n$ 
  - Sample  $x_i$  from  $P(x_i \mid \text{parents}(x_i))$
  - If  $x_i$  not consistent with evidence
    - Reject: Return, and no sample is generated in this cycle
- Return  $(x_1, x_2, \dots, x_n)$

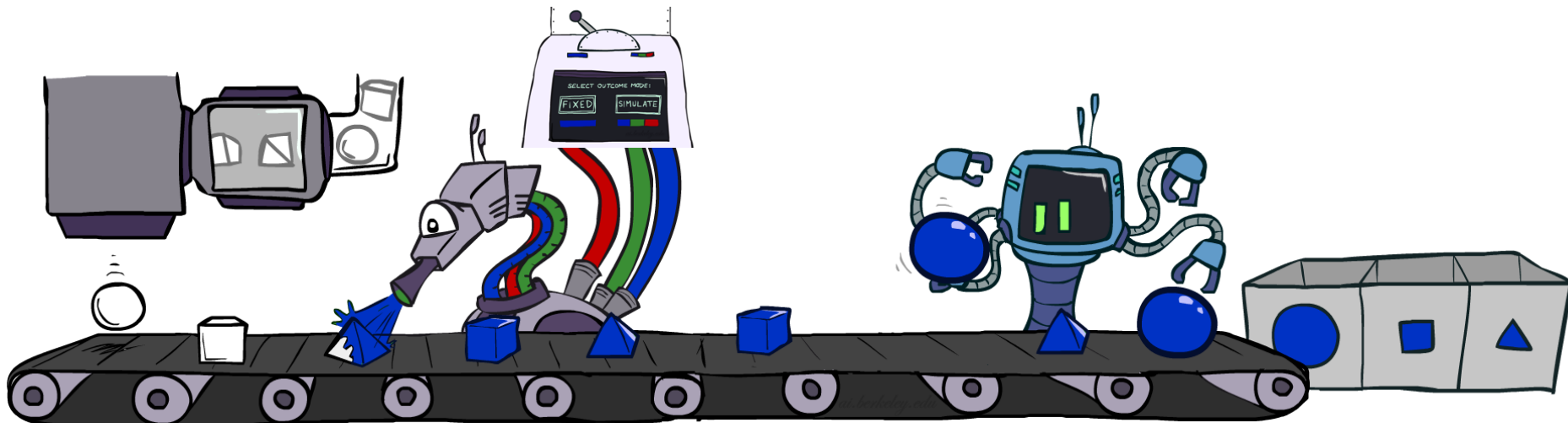


# Likelihood Weighting



# Likelihood Weighting

- Input: evidence  $e_1, \dots, e_k$
- $w = 1.0$
- for  $i=1, 2, \dots, n$ 
  - if  $X_i$  is an evidence variable
    - $x_i = \text{observed value}_i \text{ for } X_i$
    - Set  $w = w * P(x_i \mid \text{Parents}(X_i))$
  - else
    - Sample  $x_i$  from  $P(X_i \mid \text{Parents}(X_i))$
- return  $(x_1, x_2, \dots, x_n), w$



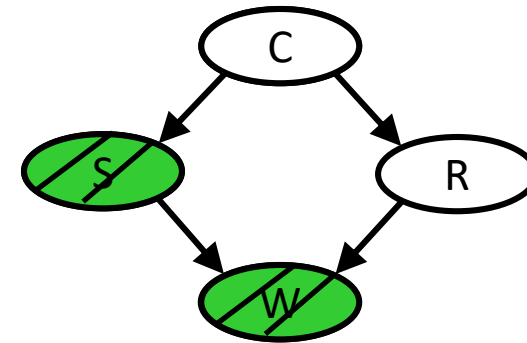
# Likelihood Weighting

- Sampling distribution ( $z$  is sampled and  $e$  is fixed evidence)

$$S_{WS}(z, e) = \prod_{i=1}^l P(z_i | \text{Parents}(Z_i))$$

- Now, samples have weights

$$w(z, e) = \prod_{i=1}^m P(e_i | \text{Parents}(E_i))$$



- Together, weighted sampling distribution is consistent

$$\begin{aligned} S_{WS}(z, e) \cdot w(z, e) &= \prod_{i=1}^l P(z_i | \text{Parents}(z_i)) \prod_{i=1}^m P(e_i | \text{Parents}(e_i)) \\ &= P(z, e) \end{aligned}$$



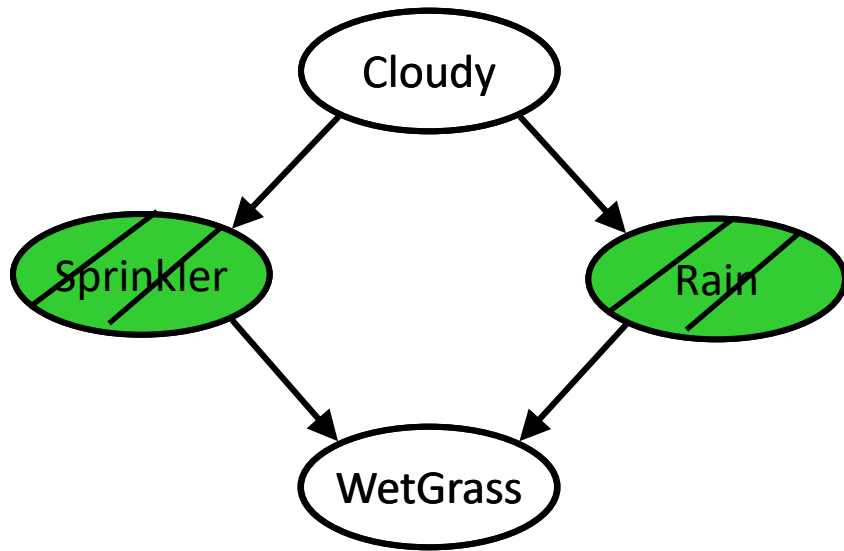
# Importance Sampling

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- Likelihood weighting is an instance of importance sampling
  - Suppose it is difficult to sample from  $p(x)$
  - Generate samples from a proposal distribution  $q(x)$ 
    - $q(x)$  is easy to draw samples from
  - Weight each sample by  $p(x)/q(x)$
- The choice of  $q(x)$  would greatly influence the speed of convergence
  - If you want to estimate the expectation of  $f(x)$
  - Then  $q(x)$  should be close to being proportional to  $|f(x)|p(x)$

# Likelihood Weighting

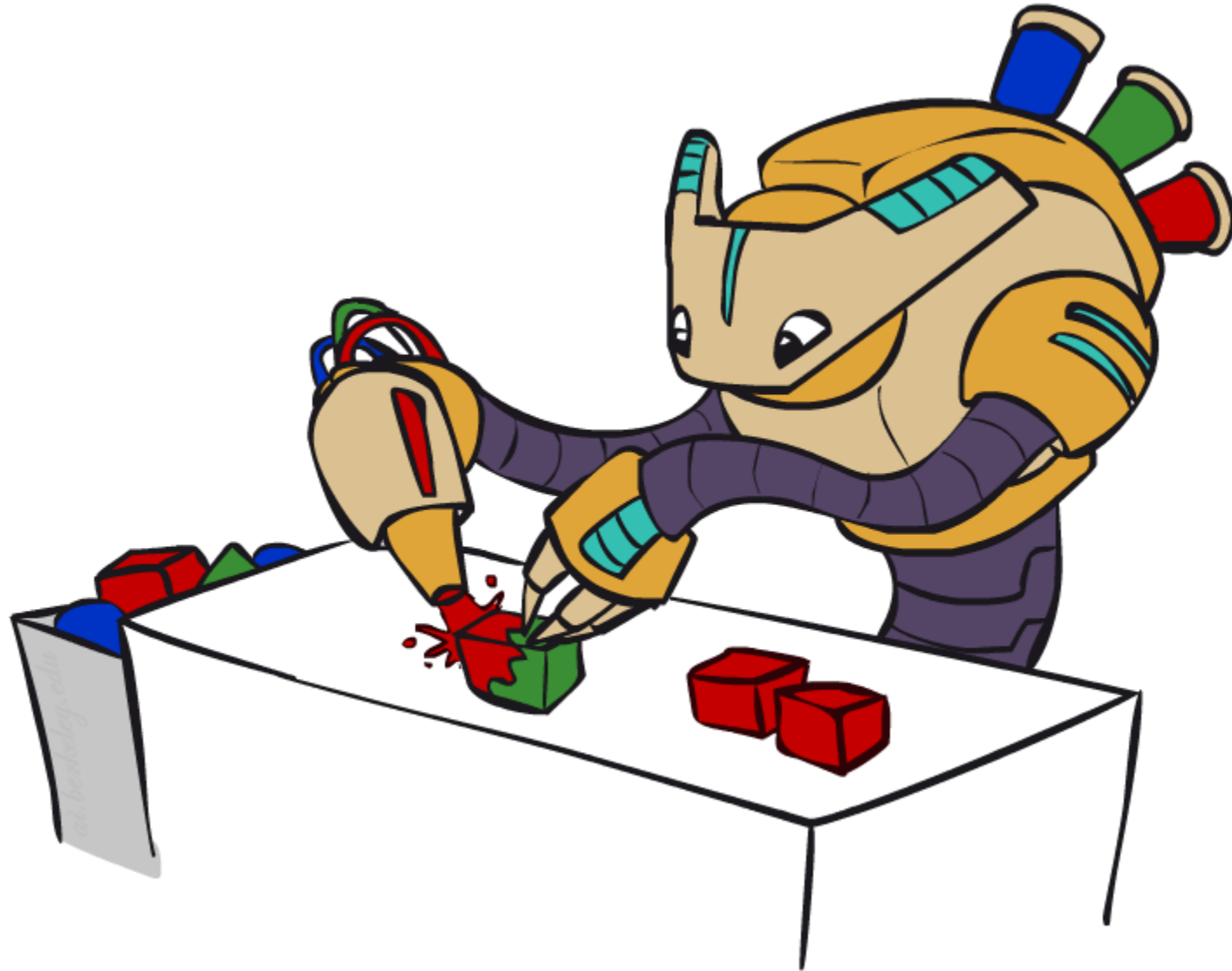
- Likelihood weighting is good
  - All samples are used
  - The values of **downstream** variables are influenced by **upstream** evidence



- Likelihood weighting still has weaknesses
  - The values of **upstream** variables are unaffected by **downstream** evidence
  - With many downstream evidence, we may
    - mostly get samples that are inconsistent with the evidence and thus have very small weights
    - get a few lucky samples with very large weights, which dominate the result
- We would like each variable to “see” **all** the evidence!

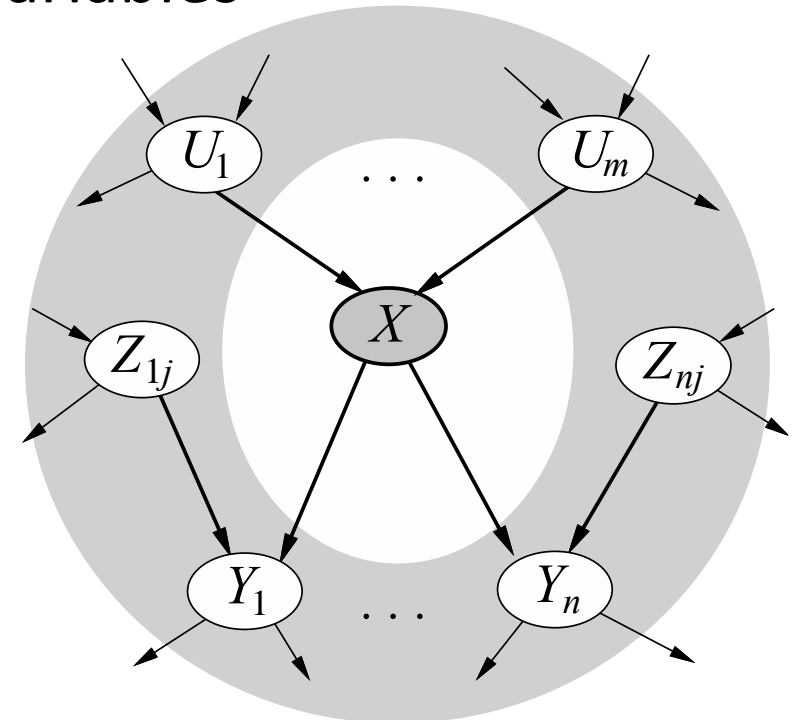
# Gibbs Sampling

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# Gibbs Sampling

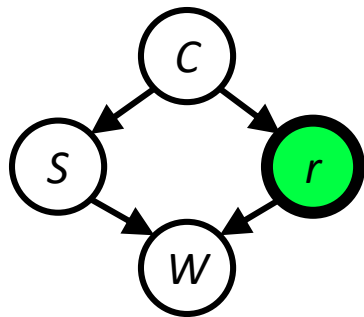
- Generate each sample by making a random change to the preceding sample
  - Evidence variables remain fixed. For each of the non-evidence variable, sample its value conditioned on all the other variables
  - $X_i' \sim P(X_i \mid x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_n)$
  - In a Bayes net
$$P(X_i \mid x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_n)$$
$$= P(X_i \mid \text{markov\_blanket}(X_i))$$
$$= \alpha P(X_i \mid u_1, \dots, u_m) \prod_j P(y_j \mid \text{parents}(Y_j))$$



# Gibbs Sampling Example: $P(S | r)$

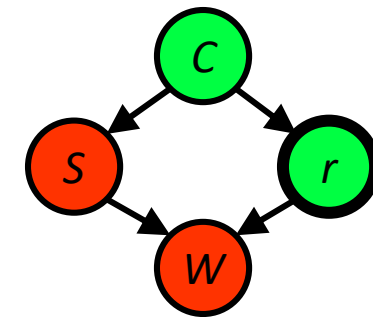
- Step 1: Fix evidence

- $R = \text{true}$



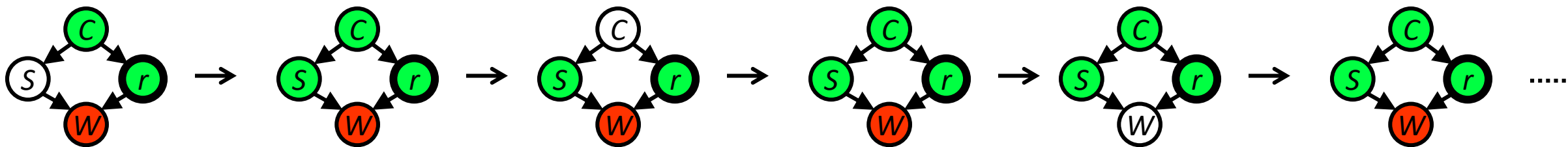
- Step 2: Initialize other variables

- Randomly



- Step 3: Repeat

- Choose an arbitrary non-evidence variable  $X$
- Resample  $X$  from  $P(X | \text{markov\_blanket}(X))$

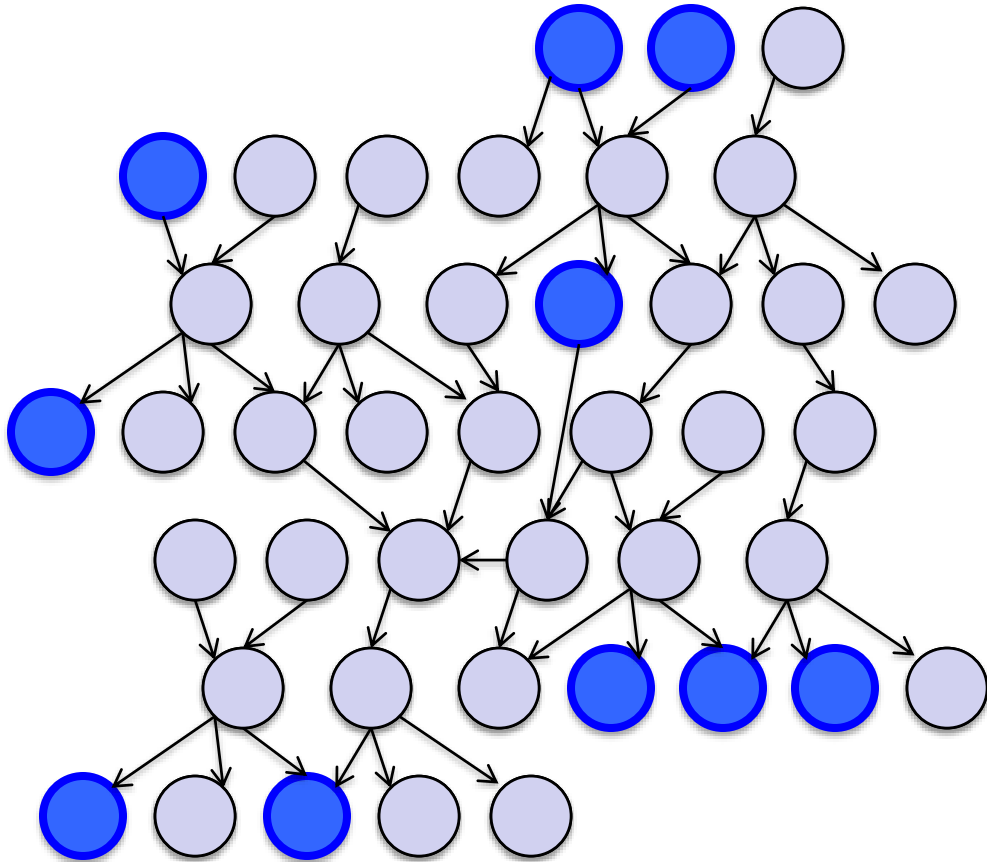


Sample  $S \sim P(S | c, r, \neg w)$

Sample  $C \sim P(C | s, r)$

Sample  $W \sim P(W | s, r)$

# Why doing this?



- Samples soon begin to reflect all the evidence in the network
- Eventually they are being drawn from the true posterior!
- Theorem: Gibbs sampling is consistent

# Why does it work? (see AIMA 14.5.2 for details)

- Suppose we run it for a long time and predict the probability of reaching any given state at time  $t$ :  $\pi_t(x_1, \dots, x_n)$  or  $\pi_t(\underline{x})$
- Each Gibbs sampling step (pick a variable, resample its value) applied to a state  $\underline{x}$  has a probability  $q(\underline{x}' \mid \underline{x})$  of reaching a next state  $\underline{x}'$
- So  $\pi_{t+1}(\underline{x}') = \sum_{\underline{x}} q(\underline{x}' \mid \underline{x}) \pi_t(\underline{x})$  or, in matrix/vector form  $\pi_{t+1} = Q\pi_t$
- When the process is in equilibrium  $\pi_{t+1} = \pi_t$  so  $Q\pi_t = \pi_t$
- This has a unique solution  $\pi_t = P(x_1, \dots, x_n \mid e_1, \dots, e_k)$
- So for large enough  $t$  the next sample will be drawn from the true posterior



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# Markov Chain Monte Carlo (MCMC)

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- MCMC is a family of randomized algorithms for approximating some quantity of interest over a very large state space
  - Markov chain = a sequence of randomly chosen states (“random walk”), where each state is chosen conditioned on the previous state
  - ~~Monte Carlo = a very expensive city in Monaco with a famous casino~~
  - Monte Carlo = an algorithm (usually based on sampling) that is likely to find a correct answer
- MCMC = sampling by constructing a Markov chain
- Gibbs, Metropolis-Hastings, Hamiltonian, Slice, etc.

# Metropolis-Hastings

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- Repeat

1. Draw a sample from a proposal distribution  $g(x'|x)$

- $g(x'|x)$  is typically easy to sample from

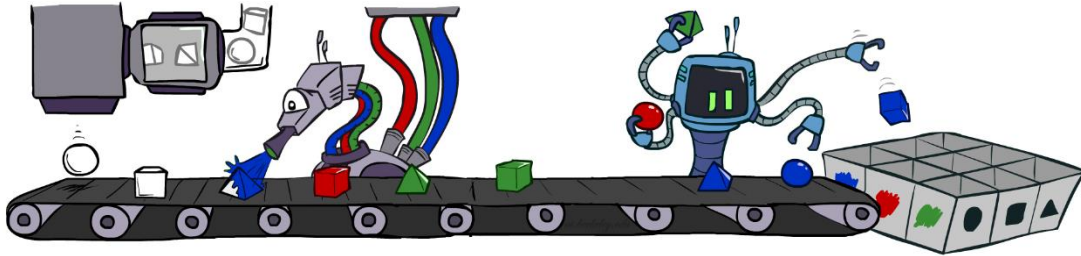
2. Accept this sample with probability

$$\min\left(1, \frac{P(x')g(x|x')}{P(x)g(x'|x)}\right)$$

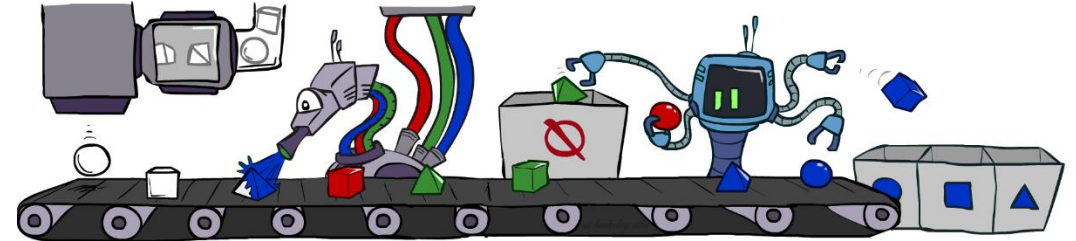
- Gibbs is a special case of Metropolis-Hastings in which the acceptance rate is always 1

# Summary

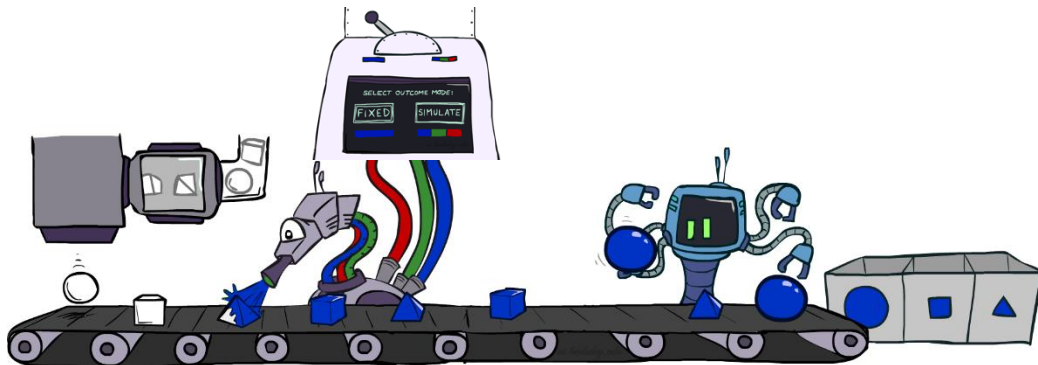
- Prior Sampling  $P$



- Rejection Sampling  $P(Q | e)$



- Likelihood Weighting  $P(Q | e)$



- Gibbs Sampling  $P(Q | e)$

