

## Math, Problem Set #3, Spectral Theory

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### Exercise 2

From the previous homework ], we know that we can represent the derivative operator as matrix

$$D = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}.$$

Therefore, the roots (eigenvalues) of the characteristic polynomial of  $D$  are given by

$$\det(D - \lambda I) = \det \begin{bmatrix} -\lambda & 1 & 0 \\ 0 & -\lambda & 2 \\ 0 & 0 & -\lambda \end{bmatrix} = 0$$

that is  $-\lambda^3 = 0$ . Hence, the unique eigenvalue of  $D$  is  $\lambda = 0$ , with algebraic multiplicity three and geometric multiplicity given by  $\dim(\text{Null}(D))$ . Since the matrix representation of the derivative operator maps vectors of the form  $\begin{bmatrix} a & b & c \end{bmatrix}$  (where  $a, b, c \in \mathbb{R}$ ) to vectors of the form  $\begin{bmatrix} b & 2c & 0 \end{bmatrix}$ ,  $p = \begin{bmatrix} a & b & c \end{bmatrix} \in \text{Null}(D) \iff b = c = 0$ . Thus,  $\text{Null}(D) = \text{Span}(e_1)$  and  $\dim(\text{Null}(D)) = 1$ .

### Exercise 4

(i)

Let  $A$  be an Hermitian matrix, i.e.,

$$\begin{bmatrix} a & x + iy \\ x - iy & b \end{bmatrix}.$$

By (4.3) we obtain that the characteristic polynomial of  $A$  is given by

$$p(\lambda) = \lambda^2 - (a + b)\lambda + ab - x^2 - y^2.$$

Therefore,

$$\Delta(p(\lambda)) = (a+b)^2 - 4(ab - x^2 - y^2) = a^2 + b^2 + 2ab - 4ab + 4x^2 + 4y^2 = (a-b)^2 + 4x^2 + 4y^2 \geq 0,$$

i.e., the discriminant is positive and the roots of the characteristic polynomial are all real.

(ii)

Let  $A$  be an Hermitian matrix, i.e.,

$$\begin{bmatrix} ix & a+ib \\ -a+ib & iy \end{bmatrix}.$$

By (4.3) we obtain that the characteristic polynomial of  $A$  is given by

$$p(\lambda) = \lambda^2 - (ix + iy)\lambda - xy + a^2 + b^2$$

Therefore,

$$\Delta(p(\lambda)) = -x^2 - y^2 + 2xy - 4a^2 - 4b^2 = -(x - y)^2 - 4(a^2 + b^2) < 0$$

i.e., the discriminant is negative and the roots of the characteristic polynomial are all imaginary.

## Exercise 6

Let  $A$  be an upper triangular matrix, i.e.,

$$A = \begin{bmatrix} \lambda_1 & * & * & \dots & * \\ 0 & \lambda_2 & * & \dots & * \\ 0 & 0 & \lambda_3 & \dots & * \\ 0 & 0 & 0 & \dots & * \\ 0 & 0 & \dots & 0 & \lambda_n \end{bmatrix}$$

Then,  $\lambda$  is an eigenvalue of  $A \iff (A - \lambda I)$  is singular. Thus,

$$A - \lambda I = \begin{bmatrix} \lambda_1 - \lambda & * & * & \dots & * \\ 0 & \lambda_2 - \lambda & * & \dots & * \\ 0 & 0 & \lambda_3 - \lambda & \dots & * \\ 0 & 0 & 0 & \dots & * \\ 0 & 0 & \dots & 0 & \lambda_n - \lambda \end{bmatrix}$$

This matrix is again upper triangular. An upper triangular matrices is singular if and only if the product of its diagonal entries equals zero. Hence,  $\lambda$  is an eigenvalue of  $A$  if and only if it satisfies

$$(\lambda_1 - \lambda)(\lambda_2 - \lambda)\dots(\lambda_n - \lambda) = 0.$$

Each root of this equation is an eigenvalue of  $A$ . This implies that  $\lambda = \lambda_i$  for all  $i = 1, 2, 3, \dots, n$ .

## Exercise 8

(i)

We know that every orthonormal set is also linearly independent. We showed in Exercise (3.8) that the set  $S$  is orthonormal, and hence linearly independent. Since  $V = \text{Span}(S)$ , we have that  $S$  is a basis for  $V$ .

(ii)

The matrix representation  $D$  of the derivative operator is completely determined by the map it operates on the basis  $S$ . In particular, it has to map the vector of coefficients  $[a, \ b, \ c, \ d]$  into the vector  $[-b, \ a, \ -2d, \ 2c]$ . Thus,

$$D = \begin{bmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -2 \\ 0 & 0 & 2 & 0 \end{bmatrix}$$

(iii)

Clearly, we can pick  $\text{Span}\{\sin(x), \cos(x)\}$  and  $\text{Span}\{\sin(2x), \cos(2x)\}$ .

### Exercise 13

We need to find an eigenbasis of  $A$ . Thus,

$$\det(A - \lambda I) = (0.8 - \lambda)(0.6 - \lambda) - 0.08 = \lambda^2 - 1.4\lambda + 0.4 = 0$$

The eigenvalues of  $A$  are  $\{1, 0.4\}$ , and with some calculations we also find that the corresponding eigenvectors are  $[1, \ 2]^T$  and  $[1, -1]^T$ . Thus, let  $P = \begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix}$ . Then,

$$P^{-1}AP = D = \begin{bmatrix} 1 & 0 \\ 0 & 0.4 \end{bmatrix}$$

where  $P^{-1} = \begin{bmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{2}{3} & -\frac{1}{3} \end{bmatrix}$ .

### Exercise 15

Since  $A$  is semisimple it is also diagonalizable. Hence  $A = PDP^{-1}$ , where  $D$  is diagonal. Then,

$$f(A) = P^{-1}(a_0 + a_1D + \dots + a_nD^n)P = P^{-1}D^nP$$

where  $D^n$  is still diagonal with entries  $f(\lambda_i)$ , i.e.,  $f(\lambda_i)$  are the eigenvalues of  $f(A)$ .

### Exercise 16

(i), (ii)

Using proposition (4.3.10), we know that

$$\begin{aligned} \lim_{n \rightarrow \infty} A^n &= \lim_{n \rightarrow \infty} PD^nP^{-1} = \lim_{n \rightarrow \infty} \begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 1^n & 0 \\ 0 & 0.4^n \end{bmatrix} \begin{bmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{2}{3} & -\frac{1}{3} \end{bmatrix} \\ &= \begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{2}{3} & -\frac{1}{3} \end{bmatrix} = \begin{bmatrix} \frac{1}{3} & \frac{1}{3} \\ \frac{2}{3} & \frac{2}{3} \end{bmatrix} \end{aligned}$$

The answer is not dependent on the type of norm that we use.

(iii)

Using Theorem (4.3.12) we know that the eigenvalues of  $f(A) = 3I + 5A + A^3$  are  $f(1) = 9$  and  $f(0.4) = 1.2 + 2 + 0.064 = 3.264$ .

### Exercise 18

We know that  $\lambda$  is an eigenvalue of  $A \iff$  there exist a non-zero column vector  $x$  such that  $Ax = \lambda x$ , or (since  $A$  and  $A^T$  have the same characteristic polynomial)  $A^T x = \lambda x$ . Taking the transpose of both sides in the last equation, we get  $x^T A = \lambda x^T$ . Thus,  $\lambda$  is an eigenvalue of  $A \iff$  there exist a non-zero row vector  $x$  such that  $x^T A = \lambda x^T$ .

### Exercise 20

By assumption, we have that  $A$  is Hermitian, i.e.,  $A^H = A$  and that  $A$  is orthonormally similar to  $B$ , i.e., there exists an orthonormal matrix  $Q$  such that  $A = Q^H B Q \iff B = Q A Q^H$ . Then,

$$B^H = [(Q A) Q^H]^H = Q (Q A)^H = Q A^H Q^H = Q A Q^H = B$$

Therefore,  $B$  is also Hermitian.

### Exercise 24

If  $A$  is an Hermitian matrix, then by the First Spectral Theorem (and Corollary) we know that  $A$  is orthonormally diagonalizable and has all real eigenvalues, i.e.,  $D = Q^H A Q$ , where  $D$  is a real diagonal matrix of eigenvalues of  $A$ . Let the vector  $x = Qc$ , where  $Q$  is an eigenbasis for  $C^n$ . Then,

$$\rho(x) = \frac{\langle x, Ax \rangle}{\|x\|^2} = \frac{c^H Q^H A Q c}{c^H c} = \frac{c^H D c}{c^H c} = \frac{\sum \lambda_i c_i^2}{\sum c_i^2}$$

which is real, since all the eigenvalues of  $A$  Hermitian matrix are real. Given that all eigenvalues of a Skew Hermitian matrix are all imaginary, we can go over the same proof for  $A$  Skew Hermitian to show that in this case the Rayleigh Quotient takes only imaginary values.

**Exercise 25**

**Exercise 27**

**Exercise 28**

**Exercise 31**

**Exercise 32**

**Exercisen 33**

**Exercise 36**

**Exercise 38**