
Algorithms for ℓ_1 minimization

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1 Problem formulation

Lasso

Consider the ℓ_1 -regularized problem

$$\min_x f_\mu(x) = g(x) + \mu h(x) := \frac{1}{2} \|Ax - b\|_2^2 + \mu \|x\|_1 \quad (1.1)$$

where $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$ and $\mu > 0$ are given.

2 CVX solutions

We can obtain and solutions directly from cvx mosek and cvx gurobi.

The ℓ_1 regularized problem (1.1) is equivalent to the following optimization problem

$$\begin{aligned} \min \quad & \frac{1}{2} \|A(x^+ - x^-) - b\|_2^2 + \mu \mathbb{1}^\top (x^+ + x^-) \\ \text{s.t.} \quad & x^+, x^- \geq 0 \end{aligned} \quad (2.1)$$

which can be rewritten into

$$\begin{aligned} \min \quad & \frac{1}{2} \begin{pmatrix} x^+ \\ x^- \end{pmatrix}^\top \begin{pmatrix} A^\top A & -A^\top A \\ -A^\top A & A^\top A \end{pmatrix} \begin{pmatrix} x^+ \\ x^- \end{pmatrix} + \begin{pmatrix} \mu \mathbb{1} - A^\top b \\ \mu \mathbb{1} + A^\top b \end{pmatrix}^\top \begin{pmatrix} x^+ \\ x^- \end{pmatrix} + \frac{1}{2} b^\top b \\ \text{s.t.} \quad & x^+, x^- \geq 0. \end{aligned} \quad (2.2)$$

The problem (2.1) can be solved by mosek and gurobi.

We plot the exact solution and solutions from cvx mosek, cvx gurobi, mosek and gurobi.

3 Various algorithms

3.1 Projection gradient method by reformulating the primal problem as a quadratic program with box constraints

According the the problem (2.1), define

$$f_\mu(x^+, x^-) = \frac{1}{2} (x^+ - x^-)^\top A^\top A (x^+ - x^-) + (\mu \mathbb{1} - A^\top b)^\top x^+ + (\mu \mathbb{1} + A^\top b)^\top x^- + \frac{1}{2} b^\top b \quad (3.1)$$

We aim to minimize $f_\mu(x^+, x^-)$ such that $x^+, x^- \geq 0$ by the projection gradient method. We have $\nabla_{x^+} f_\mu(x^+, x^-) = A^\top A (x^+ - x^-) + \mu \mathbb{1} - A^\top b$, $\nabla_{x^-} f_\mu(x^+, x^-) = A^\top A (x^- - x^+) + \mu \mathbb{1} + A^\top b$.

The projection gradient method can be summarized in Algorithm 1, where $\sigma(x) = \max\{x, 0\}$ is the projection operator.

Algorithm 1 Projection gradient method with continuation method

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1: Input: initial value  $x_0$ , step size  $\alpha$ , continuation parameter  $\gamma$ ,  $N$ , maximum iteration
   number for each stage  $M$ .
2: for  $i = 1, \dots, N$  do
3:    $\mu_i = \gamma^{N-i} \mu$ .
4:   for  $j = 1, \dots, M$  do
5:      $x^+ \leftarrow \sigma(x^+ - \alpha \nabla_{x^+} f_{\mu_i}(x^+, x^-)), x^- \leftarrow \sigma(x^- - \alpha \nabla_{x^-} f_{\mu_i}(x^+, x^-))$ 
6:   end for
7: end for
8: Output:  $x = x^+ - x^-$ .

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3.2 Subgradient method for the primal problem

The subgradient of f_μ is $\partial f_\mu(x) = A^\top(Ax - b) + \mu \cdot \text{sign}(x)$. The subgradient method can be summarized in Algorithm 2.

Algorithm 2 Subgradient method for the primal problem with continuation method

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1: Input: initial value  $x_0$ , step size  $\alpha$ , continuation parameter  $\gamma$ ,  $N$ , maximum iteration
   number for each stage  $M$ .
2: for  $i = 1, \dots, N$  do
3:    $\mu_i = \gamma^{N-i} \mu$ .
4:   for  $j = 1, \dots, M$  do
5:      $x \leftarrow x - \alpha \partial f_{\mu_i}(x)$ .
6:   end for
7: end for
8: Output:  $x$ .

```

3.3 Gradient method for the smoothed primal problem

We consider the Huber penalty approximation of $\|x\|_1$:

$$h_\lambda(x) = \sum_{i=1}^n h_\lambda^i(x) \quad (3.2)$$

$$\text{where } h_\lambda^l(x) = \begin{cases} x_l^2/(2\lambda), & |x_l| \leq \lambda \\ |x_l| - \lambda/2, & |x_l| > \lambda \end{cases}$$

We choose an additional parameter β for the decay of λ . The define $f_{i,j}(x) = \frac{1}{2}\|Ax - b\|_2^2 + \mu_i h_{\lambda_j}(x)$. The gradient can be computed as

$$\nabla f_{i,j}(x)_k = \begin{cases} (A^\top Ax - A^\top b)_k + \mu_i x_k / \lambda_j, & |x_k| \leq \lambda_j \\ (A^\top Ax - A^\top b)_k + \mu_i \text{sign}(x_k), & |x_k| > \lambda_j \end{cases} \quad (3.3)$$

In $(k+1)$ -th iteration, if $k = 0$, we use the initial step size α . Otherwise, we use the BB step size α_k :

$$\alpha_k = \frac{(x_k - x_{k-1})^\top (x_k - x_{k-1})}{(x_k - x_{k-1})^\top (\nabla f_{i,j}(x_k) - \nabla f_{i,j}(x_{k-1}))} \quad (3.4)$$

Then we can update x_{k+1} by $x_{k+1} = x_k - \alpha_k \nabla f_{i,j}(x_k)$.

Similarly, we use the continuation strategy. We have three parameters γ, M_1, M_2 for continuation, and set $\mu_0 = \mu_{\max} = \max\{\gamma \|A^\top b\|_\infty, \mu\}$. While $\mu_i > \mu$ or $\lambda_j > \lambda$, we update μ_{i+1}, λ_{i+1} by

$$\mu_{i+1} = \max\{\mu, \gamma \min\{\|\nabla g(x_k)\|_\infty, \mu_i\}\}, \quad \lambda_{j+1} = \max\{\beta \lambda_j, \lambda\} \quad (3.5)$$

Algorithm 3 Gradient method for smoothed primal problem with continuation strategy

1: **Input:** initial value x_0 , step size α , continuation parameter $\gamma, M_1, M_2, \lambda$ decay parameter β .
2: $\mu_0 = \mu_{\max} = \max\{\gamma\|A^\top b\|_\infty, \mu\}, \alpha_0 = \alpha, k = 0$.
3: **while** $\mu_i > \mu$ or $\lambda_j > \lambda$ **do**
4: **for** $l = 1, 2, \dots, M_1$ **do**
5: Calculate BB step size α_k , and update x_{k+1} .
6: **end for**
7: $\mu_{i+1} = \max\{\mu, \gamma \min\{\|\nabla g(x_k)\|_\infty, \mu_i\}\}, \lambda_{j+1} = \max\{\beta\lambda_j, \lambda\}, i = i + 1, j = j + 1$.
8: Set $x_0 := x_k$ and $k = 0$. Update $\alpha_k = \min\{\alpha, \lambda_j\}$.
9: **end while**
10: **for** $l = 1, 2, \dots, M_2$ **do**
11: Calculate BB step size α_k , and update x_{k+1} .
12: **end for**

3.4 Fast (Nesterov/accelerated) gradient method for the smoothed primal problem

We still apply the continuation strategy with only a slight modification of the Algorithm 3. Specifically, we set $x_{-1} = x_0$. In $(k + 1)$ -th iteration, we update x_{k+1} by

$$\begin{cases} y &= x_k + \frac{k-1}{k+2}(x_k - x_{k-1}) \\ x_{k+1} &= y - \alpha_k \nabla f_{i,j}(x_k) \end{cases} \quad (3.6)$$

Algorithm 4 Fast gradient method for smoothed primal problem with continuation strategy

1: **Input:** initial value x_0 , step size α , continuation parameter $\gamma, M_1, M_2, \lambda$ decay parameter β .
2: $\mu_0 = \mu_{\max} = \max\{\gamma\|A^\top b\|_\infty, \mu\}, \alpha_0 = \alpha, k = 0$.
3: **while** $\mu_i > \mu$ or $\lambda_j > \lambda$ **do**
4: **for** $l = 1, 2, \dots, M_1$ **do**
5: Update x_{k+1} by (3.6), $\alpha_{k+1} = \alpha_k, k = k + 1$.
6: **end for**
7: $\mu_{i+1} = \max\{\mu, \gamma \min\{\|\nabla g(x_k)\|_\infty, \mu_i\}\}, \lambda_{j+1} = \max\{\beta\lambda_j, \lambda\}, i = i + 1, j = j + 1$.
8: Set $x_{-1} = x_0 := x_k$ and $k = 0$. Update $\alpha_k = \min\{\alpha, \lambda_j\}$.
9: **end while**
10: **for** $l = 1, 2, \dots, M_2$ **do**
11: Update x_{k+1} by (3.6), $\alpha_{k+1} = \alpha_k, k = k + 1$.
12: **end for**

3.5 Proximal gradient method for the primal problem

Define the proximal operator $\text{prox}_{\alpha_k \mu h}(x) = \arg \min_z \frac{1}{2}\|z - x\|_2^2 + \alpha_k \mu h(z)$. When $h(x) = \|x\|_1$, the proximal operator can be computed explicitly as $\text{prox}_{\alpha_k \mu h}(x) = S_{\alpha_k \mu}(x)$, where S is the soft thresholding operator. Define $f_i = g + \mu_i h$, in $(k + 1)$ -th iteration, we use the BB step size

$$\alpha_k = \frac{(x_k - x_{k-1})^\top (x_k - x_{k-1})}{(x_k - x_{k-1})^\top (\nabla g(x_k) - \nabla g(x_{k-1}))} \quad (3.7)$$

Then, we update x_{k+1} by

$$x_{k+1} = S_{\alpha_k \mu_i}(x_k - \alpha_k \nabla g(x_k)) \quad (3.8)$$

3.6 Fast proximal gradient method for the primal problem

In this part, we update x_{k+1} by

$$\begin{cases} y_k &= x_k + \frac{k-1}{k+2}(x_k - x_{k-1}) \\ x_{k+1} &= S_{\alpha_k \mu_i}(y_k - \alpha_k \nabla g(y_k)) \end{cases} \quad (3.9)$$

Algorithm 5 Proximal gradient method with continuation strategy

1: **Input:** initial value x_0 , step size α , continuation parameter $\gamma, \varepsilon_1, \varepsilon_2$.
2: $\mu_0 = \mu_{\max} = \max\{\gamma\|A^\top b\|_\infty, \mu\}$, $\alpha_0 = \alpha, i = k = 0$.
3: Update x_{k+1} by (3.8), $k = k + 1$.
4: **while** $\mu_i > \mu$ **do**
5: **for** $k = 1, 2, \dots, M_1$ **do**
6: Calculate BB step size s_k by (3.7), update x_{k+1} by (3.8).
7: **end for**
8: $\mu_{i+1} = \max\{\mu, \gamma \min\{\|\nabla g(x_k)\|_\infty, \mu_i\}\}$, $i = i + 1$.
9: Set $\alpha_k = \alpha$, update x_{k+1} by (3.8), $k = k + 1$.
10: **end while**
11: **for** $k = 1, 2, \dots, M_2$ **do**
12: Calculate BB step size s_k by (3.7), update x_{k+1} by (3.8).
13: **end for**

Algorithm 6 Fast proximal gradient method with continuation strategy

1: **Input:** initial value x_0 , step size α , continuation parameter $\gamma, \varepsilon_1, \varepsilon_2$.
2: $\mu_0 = \mu_{\max} = \max\{\gamma\|A^\top b\|_\infty, \mu\}$, $\alpha_0 = \alpha, i = k = 0$.
3: Update x_{k+1} by (3.9), $k = k + 1$.
4: **while** $\mu_i > \mu$ **do**
5: **for** $k = 1, 2, \dots, M_1$ **do**
6: Calculate BB step size s_k by (3.7), update x_{k+1} by (3.9).
7: **end for**
8: $\mu_{i+1} = \max\{\mu, \gamma \min\{\|\nabla g(x_k)\|_\infty, \mu_i\}\}$, $i = i + 1$.
9: Set $\alpha_k = \alpha$, update x_{k+1} by (3.9), $k = k + 1$.
10: **end while**
11: **for** $k = 1, 2, \dots, M_2$ **do**
12: Calculate BB step size s_k by (3.7), update x_{k+1} by (3.9).
13: **end for**

3.7 Augmented Lagrangian method for the dual problem

The original problem (1.1) is equivalent to the following problem:

$$\min_x \frac{1}{2}\|y\|_2^2 + \mu\|x\|_1 \quad \text{s.t.} \quad Ax - b = y \quad (3.10)$$

The corresponding Lagrangian is

$$L(x, y, z) = \frac{1}{2}\|y\|_2^2 + \mu\|x\|_1 + z^\top (Ax - b - y) \quad (3.11)$$

where $z \in \mathbb{R}^m$. By minimizing L , we have

$$\begin{aligned} \min_{x,y} L(x, y, z) &= -b^\top z + \min_y \left(\frac{1}{2}\|y\|_2^2 - z^\top y \right) + \min_x (\mu h(x) + (A^\top z)^\top x) \\ &= -b^\top z - g_0^*(z) - \mu h^*(A^\top z / \mu) \end{aligned} \quad (3.12)$$

where the g_0^* and h^* are the conjugate of the function $g_0 = \frac{1}{2}\|\cdot\|_2^2$ and h , which can be directly computed by $g_0^*(z) = \frac{1}{2}\|z\|^2$, $h^*(z) = \begin{cases} 0, & \|z\|_\infty \leq 1 \\ +\infty, & \|z\|_\infty > 1 \end{cases}$

Hence the dual problem for problem (1.1) is

$$\min \frac{1}{2}\|z\|_2^2 + b^\top z, \quad \text{s.t.} \quad A^\top z = w, \quad \|w\|_\infty \leq \mu. \quad (3.13)$$

whose augmented Lagrangian is

$$L_a(z, w, \lambda) = \frac{1}{2}\|z\|_2^2 + b^\top z + \lambda^\top (A^\top z - w) + \frac{a}{2}\|A^\top z - w\|_2^2. \quad (3.14)$$

If we set $z^0 = 0, w^0, \lambda^0 = 0$. Given (z^k, w^k, λ^k) , the relationship between w^{k+1} and z^{k+1}

$$w^{k+1} = \lambda^k / a + A^\top z^{k+1} - S_\mu(\lambda^k / a + A^\top z^{k+1}). \quad (3.15)$$

where the soft thresholding function S_μ is defined as

$$S_\mu(w) = \text{sign}(w) \cdot (|w| - \mu)^+ \quad (3.16)$$

Then, we have the following problem:

$$\arg \min_z \frac{1}{2} \|z\|_2^2 + b^\top z + \frac{a}{2} \|S_\mu(\lambda^k / t + A^\top z)\|_2^2 \quad (3.17)$$

We consider to use the Newton's method to solve the minimization (3.17). We define $z^{k,0} = z^k$, the update can be written as

$$\begin{aligned} z^{k,j+1} &= z^{k,j} - H(z^{k,j})^{-1} d(z^{k,j}) \\ &= z^{k,j} - (z^{k,j} + b + a \sum_{|v_i^{k,j}| > \mu} A_i S_\mu(v_i^{k,j})^{-1} (I + a \sum_{|v_i^{k,j}| > \mu} A_i A_i^\top) \end{aligned} \quad (3.18)$$

where $v^{k,j} = \lambda^k / a + A^\top z^{k,j}$. We perform the update until $\|d(z^{k,j})\|_2 / \|d(z^{k,0})\|_2 \leq \epsilon_3$, assuming we terminate the iteration at the M_2 -th step.

Since the computational cost of solving $H(z^{k,j})^{-1} d(z^{k,j})$ is large when $H(z^{k,j})$ varies, we approximate $H(z^{k,j}) \approx I + aAA^\top = LDL^\top$ in advance. Empirically, we find approximate $d(z^{k,j}) \approx z^{k,j} + b + aAS_\mu(v^{k,j})$ does not impair the performance and improve the efficiency.

In all, we can update $(z^{k+1}, w^{k+1}, \lambda^{k+1})$:

$$\begin{cases} z^{k+1} = z^{k,M_3} \\ w^{k+1} = \lambda^k / a + A^\top z^{k+1} - S_\mu(\lambda^k / a + A^\top z^{k+1}) \\ \lambda^{k+1} = \lambda^k + a(A^\top z^{k+1} - w^{k+1}) \end{cases} \quad (3.19)$$

Algorithm 7 Augmented Lagrangian method for the dual problem with continuation strategy.

- 1: **Input:** Augmented Lagrangian parameter a , continuation parameter γ , M_1, M_2 , Newton's method parameter M_3 . Calculate $\mu_0 = \max\{\gamma \|A^\top b\|_\infty, \mu\}$. Initialize variables $i = k = 0, z^0 = 0, \lambda^0 = 0$.
 - 2: **while** $\mu_i > \mu$ **do**
 - 3: **for** $k = 1, 2, \dots, M_1$ **do**
 - 3: Update $(z^{k+1}, w^{k+1}, \lambda^{k+1})$ by (3.19), $k = k + 1$.
 - 4: **end for**
 - 4: $\mu_{i+1} = \max\{\mu, \gamma \mu_i\}, i = i + 1, z^0 = z^k, \lambda^0 = \lambda^k, k = 0$.
 - 5: **end while**
 - 6: **for** $k = 1, 2, \dots, M_2$ **do**
 - 6: Update $(z^{k+1}, w^{k+1}, \lambda^{k+1})$ by (3.19), $k = k + 1$.
 - 7: **end for**
 - 8: $x = -\lambda^k$.
-

3.8 Alternating direction method of multipliers for the dual problem

Similarity we obtain the augmented Lagrangian (3.14), while we minimize this Lagrangian with alternating direction strategy. First we minimize $L_a(z^k, w, \lambda^k)$ w.r.t. w , we have $w^{k+1} = \lambda^k / a + A^\top z^k - S_\mu(\lambda^k / a + A^\top z^k)$. Then we minimize $L_a(w^{k+1}, z, \lambda^k)$ w.r.t. z . Therefore we can update $(z^{k+1}, w^{k+1}, \lambda^{k+1})$:

$$\begin{cases} w^{k+1} = \lambda^k / a + A^\top z^k - S_\mu(\lambda^k / a + A^\top z^k) \\ z^{k+1} = (I + aAA^\top)^{-1} (-b - A\lambda^k + aAw^{k+1}) \\ \lambda^{k+1} = \lambda^k + a(A^\top z^{k+1} - w^{k+1}) \end{cases} \quad (3.20)$$

Algorithm 8 ADMM for the dual problem with continuation strategy

```
1: Input: Augmented Lagrangian parameter  $a$ , continuation parameter  $\gamma, M_1, M_2$ . Calculate  
    $\mu_0 = \max\{\gamma\|A^\top b\|_\infty, \mu\}$ . Initialize variables  $i = k = 0, z^0 = 0, \lambda^0 = 0$ .  
2: while  $\mu_i > \mu$  do  
3:   for  $k = 1, 2, \dots, M_1$  do  
3:     Update  $(z^{k+1}, w^{k+1}, \lambda^{k+1})$  by (3.20).  
4:   end for  
4:    $\mu_{i+1} = \max\{\mu, \gamma\mu_i\}, i = i + 1, z^0 = z^k, \lambda^0 = \lambda^k, k = 0$ .  
5: end while  
6: for  $k = 1, 2, \dots, M_2$  do  
6:   Update  $(z^{k+1}, w^{k+1}, \lambda^{k+1})$  by (3.20).  
7: end for  
8:  $x = -\lambda^k$ .
```

3.9 Alternating direction method of multipliers with linearization for the primal problem

The primal problem can be reformulated as

$$\min \frac{1}{2}\|Ax - b\|_2^2 + \mu\|y\|_1 \quad \text{s.t. } x = y \quad (3.21)$$

The augmented Lagrangian is

$$L_a^p(x, y, z) = \frac{1}{2}\|Ax - b\|_2^2 + \mu\|y\|_1 + z^\top(x - y) + \frac{a}{2}\|x - y\|_2^2. \quad (3.22)$$

We first update x^{k+1} by direct minimization $x^{k+1} = \arg \min_x L_a(x^k, y^k, z^k) = (A^\top A + aI)^{-1}(A^\top b + ay^k - z^k)$; then we update $y^{k+1} = \arg \min_y L_a(x^{k+1}, y, z^k) = S_{\frac{\mu}{a}}(x^{k+1} + \frac{z^k}{a})$. The update can be summarized as

$$\begin{cases} x^{k+1} = (A^\top A + aI)^{-1}(A^\top b + ay^k - z^k) \\ y^{k+1} = S_{\frac{\mu}{a}}(x^{k+1} + \frac{z^k}{a}) \\ z^{k+1} = z^k + a(x^{k+1} - y^{k+1}) \end{cases} \quad (3.23)$$

Algorithm 9 ADMM with linearization for the primal problem with continuation strategy

```
1: Input: Augmented Lagrangian parameter  $a$ , continuation parameter  $\gamma, \varepsilon_1, \varepsilon_2$ . Calculate  
    $\mu_0 = \max\{\gamma\|A^\top b\|_\infty, \mu\}$ . Initialize variables  $i = k = 0, x^0 = y^0 = x_0, z^0 = 0$ .  
2: while  $\mu_i > \mu$  do  
3:   for  $k = 1, 2, \dots, M_1$  do  
3:     Update  $(x^{k+1}, y^{k+1}, z^{k+1})$  by (3.23),  $k = k + 1$ .  
4:   end for  
4:    $\mu_{i+1} = \max\{\mu, \gamma\mu_i\}, i = i + 1, x^0 = z^k, y^0 = y^k, z^0 = z^k, k = 0$ .  
5: end while  
6: for  $k = 1, 2, \dots, M_2$  do  
6:   Update  $(x^{k+1}, y^{k+1}, z^{k+1})$  by (3.23),  $k = k + 1$ .  
7: end for  
8:  $x = x^k$ .
```

References