

Homework 3 for “Algorithms for Big-Data Analysis”

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“EE236C - Optimization Methods for Large-Scale Systems (Spring 2013-14)”

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1. For each of the following function on \mathbb{R}^n , explain how to calculate a subgradient at a given x .

A reference on subgradients is

<http://bicmr.pku.edu.cn/~wenzw/bigdata/subgradients.pdf>

(a) $f(x) = \|Ax - b\|_2 + \|x\|_2$ where $A \in \mathbb{R}^{m \times n}$ and $x \in \mathbb{R}^n$.

(b) $f(x) = \inf_y \|Ay - x\|_\infty$ where $A \in \mathbb{R}^{n \times m}$ and $x \in \mathbb{R}^n$.

2. Give a formula or simple algorithm for evaluating the proximal operator

$$\text{prox}_f(x) = \arg \min_u \left(f(u) + \frac{1}{2} \|u - x\|_2^2 \right).$$

(a) $f(x) = \|x\|_1$ with domain $\text{dom}(f) = \{x \mid \|x\|_\infty \leq 1\}$

(b) $f(x) = \max_k x_k$

(c) $f(x) = \|Ax - b\|_1$ where $AA^\top = D$ and D is a diagonal matrix whose diagonal elements are positive.

3. Given $w \in \mathbb{R}^n$, $\alpha, \sigma > 0$, write down an algorithm for solving the problem

$$\min_{t, y} \phi(t, y),$$

where

$$\phi(t, y) := t + \frac{1}{(1 - \alpha)n} \sum_{i=1}^n (y_i - t)_+ + \frac{\sigma}{2} \|y - w\|_2^2,$$

where $x_+ := \max(x, 0)$.

4. Let $S^n = \{X \in \mathbb{R}^{n \times n} \mid X^\top = X\}$ and $S_{++}^n = \{X \in \mathbb{R}^{n \times n} \mid X^\top = X, X \text{ is positive definite}\}$. Find the proximal operator of the function $f(X) = -\log \det X$ where $X \in S^n$ and $\text{dom } f = S_{++}^n$. Here, the proximal operator is defined as

$$\text{prox}_f(X) = \arg \min_U \left(f(U) + \frac{1}{2} \|U - X\|_F^2 \right),$$

where $\|\cdot\|_F$ is the Frobenius norm.

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1 Problem 1

1.1 (a)

Due to the chain rule, as well as $f(x)$ is a nonnegative combination

$$\partial f(x) = A^\top \partial \|Ax - b\|_2 + \partial \|x\|_2$$

Obviously, when $x \neq 0$, $\partial \|x\|_2 = \frac{x}{\|x\|_2}$. When $x = 0$, by definition, we have

$$\|y\|_2 \geq g^\top y, \forall y \in \mathbb{R}^n$$

which leads to $\|g\|_2 \leq 1$. Hence, $\partial \|x\|_2 = \{g \mid \|g\|_2 \leq 1\}$.

Hence,

$$\partial f(x) = \begin{cases} A^\top (Ax - b) / \|Ax - b\|_2 + x / \|x\|_2, & \text{if } x \neq 0, Ax - b \neq 0 \\ \{-A^\top b / \|b\|_2 + g \mid \|g\|_2 \leq 1\}, & \text{if } x = 0, b \neq 0 \\ \{A^\top g + x / \|x\|_2 \mid \|g\|_2 \leq 1\}, & \text{if } x \neq 0, Ax - b = 0 \\ \{A^\top g_1 + g_2 \mid \|g_1\|_2, \|g_2\|_2 \leq 1\}, & \text{if } x = 0, b = 0 \end{cases}$$

1.2 (b)

We first compute $\partial \|z\|_\infty$. Since $\|z\|_\infty = \sup_{\|w\|_1 \leq 1} z^\top w$, by the **Danskin-Bertseka's Theorem for subdifferentials**, since $\{w : \|w\|_1 \leq 1\}$ is compact, and $w^\top z$ is convex in z for every w , we have

$$\begin{aligned} \partial \|z\|_\infty &= \text{conv}\{w : \|w\|_1 \leq 1, z^\top w = \|z\|_\infty\} \\ &= \{w : \|w\|_1 \leq 1, z^\top w = \|z\|_\infty\} \end{aligned}$$

For given x , we minimize $\|Ay - x\|_\infty$ w.r.t. y , which is a LP problem. Then

$$\partial_{x,y} \|Ay - x\|_\infty = \partial_{x,y} \left(-I \quad A \right) \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -I \\ A^\top \end{pmatrix} = \left\{ \begin{pmatrix} -I \\ A^\top \end{pmatrix} w : \|w\|_1 \leq 1, w^\top (Ay - x) = \|Ay - x\|_\infty \right\}$$

Since we set $A^\top w = 0$, hence the subgradient is

$$\{w : A^\top w = 0, \|w\|_1 \leq 1, w^\top \hat{x} = \|A\hat{y} - \hat{x}\|_\infty\}$$

at point \hat{x} .

Now we need to prove that such w exist. We need first find \hat{y} to minimize $\|Ay - x\|_\infty$. If $\|\hat{x} - A\hat{y}\|_\infty = 0$, we set $w = 0$. Otherwise, the problem can be reformulated as

$$\begin{aligned} \min_{t,y} \quad & t \\ \text{s.t.} \quad & -t\mathbb{1} \preceq Ay - \hat{x} \preceq t\mathbb{1} \end{aligned} \tag{1.1}$$

whose Lagrangian can be written as

$$L(t, y, a, b) = t + a^\top (Ay - \hat{x} - t\mathbb{1}) + b^\top (-t\mathbb{1} - Ay + \hat{x}) \tag{1.2}$$

where $a, b \succeq 0$.

The dual problem is

$$\min_{a,b} \quad \hat{x}^\top (a - b) \quad (1.3a)$$

$$\text{s.t.} \quad A^\top (a - b) = 0, \quad \mathbb{1}^\top (a + b) = 1 \quad (1.3b)$$

$$a, b \succeq 0 \quad (1.3c)$$

Assuming the optimal solution is t^*, y^*, a^*, b^* , then the KKT condition amounts to

$$A^\top (a^* - b^*) = 0 \quad (1.4a)$$

$$\mathbb{1}^\top (a^* + b^*) = 1 \quad (1.4b)$$

$$(a^*)^\top (Ay^* - \hat{x} - t^* \mathbb{1}) = 0 \quad (1.4c)$$

$$(b^*)^\top (-t^* \mathbb{1} - Ay^* + \hat{x}) = 0 \quad (1.4d)$$

We claim that $w = a^* - b^*$ satisfy 1.2. According to 1.4a, $A^\top w = 0$; and from 1.4b, 1.4c and 1.4d, we have

$$w^\top \hat{x} = (a^* - b^*)^\top (Ay^* - \hat{x}) = (a^* + b^*)^\top \mathbb{1} t^* = t^*$$

Besides, if $a_i^* \neq 0$, then from 1.4c we have $(Ay^* - \hat{x})_i = t$, combined with 1.4d and $t > 0$, we have $b_i^* = 0$. Similarly, if $b_i^* \neq 0$, then $a_i^* = 0$. Hence,

$$\|w\|_1 = \|a^* - b^*\|_1 = \|a^*\|_1 + \|b^*\|_1 = \mathbb{1}^\top (a^* + b^*) = 1$$

Therefore, the existence is proved. Form the proof, we can easily find that by solving the dual 1.3, $\partial f(\hat{x})$ is naturally obtained by setting $w = a^* - b^*$.

2 Problem 2

2.1 (a)

Define

$$\delta(x) = \begin{cases} 0, & \|x\|_\infty \leq 1 \\ +\infty, & \text{otherwise} \end{cases}$$

Hence, $f(x) = \|x\|_1 + \delta(x)$. If we optimize elementwisely, i.e.

$$\min_{u_i} \quad |u_i| + \delta(u_i) + \frac{1}{2}|u_i - x_i|^2$$

which means

$$\begin{aligned} \min_{u_i} \quad & |u_i| + \frac{1}{2}|u_i - x_i|^2 \\ \text{s.t.} \quad & -1 \leq u_i \leq 1 \end{aligned}$$

Taking the derivative w.r.t. u_i , we get

$$u_i - x_i + \partial|u_i| = 0$$

The solution is $u_i = \text{sign}(x_i) \max(|x_i| - 1, 0)$. Considering $|u_i| \leq 1$, since the problem is quadratic and have positive leading coefficient, the solution should be modified to $u_i = \text{sign}(x_i) \min(\max(|x_i| - 1, 0), 1)$.

Hence

$$\text{prox}_f(x)_i = \text{sign}(x_i) \min(\max(|x_i| - 1, 0), 1)$$

2.2 (b)

Take the subgradient, we have

$$\partial f(u) + u - x = 0$$

Assume e_i is the vector whose i -th item is 1 and the others are 0, according to the relation of taking maximum and subgradient, we have

$$\partial f(u) = \text{conv}\{e_i | u_i = f(u)\}$$

where the equality holds since each x_k is linear (differentiable). Hence, we have

$$u_j = \begin{cases} x_j, & u_j \neq f(u) \\ x_j - c_j & u_j = f(u) \end{cases}$$

where c_j satisfies $\sum_{j: u_j = f(u)} c_j = 1$.

Assuming the solution of $\sum_k \max(x_k - t, 0) = 1$ w.r.t. $t \in \mathbb{R}$ is \hat{t} . Clearly, \hat{t} exist and is unique. This equation can be solved by bisecting t with the initial interval $[\min_i x_i - \frac{1}{n}, \max_i x_i]$.

We thus have $\text{prox}_f(x)_i = \min(x_i, \hat{t})$.

2.3 (c)

Since

$$\text{prox}_f(x) = \min_u \left\{ \|Au - b\|_1 + \frac{1}{2} \|u - x\|_2^2 \right\}$$

which can be formulated as

$$\min_{u, z} \quad \|z\|_1 + \frac{1}{2} \|u - x\|_2^2 \tag{2.1a}$$

$$\text{s.t.} \quad z = Au - b \tag{2.1b}$$

Define the optimal solution of 2.2 by (\hat{z}, \hat{u}) . The existence of such solution follows from the fact that $\|x\|_1$ is convex and positive. Clearly $\hat{u} = \text{prox}_f(x)$, fixing $z = \hat{z}$, we have that \hat{u} is the optimal solution of

$$\begin{aligned} \min_{u, z} \quad & \frac{1}{2} \|u - x\|_2^2 \\ \text{s.t.} \quad & Au = \hat{z} + b \end{aligned}$$

Thanks to the strong duality, there exist w such that

$$\hat{u} \in \arg \min_u \left\{ \frac{1}{2} \|u - x\|_2^2 + \langle y, Au - \hat{z} - b \rangle \right\} \tag{2.3a}$$

$$A\hat{u} = \hat{z} + b \tag{2.3b}$$

By 2.3a, we have

$$\hat{u} = x - A^\top y \tag{2.4}$$

Substituting it into 2.3b, we have

$$A(x - A^\top y) = \hat{z} + b$$

Since $AA^\top = D$, and D is a diagonal matrix whose diagonal elements are positive,

$$y = D^{-1}(Ax - \hat{z} - b)$$

which combined with 2.4, we have

$$\hat{u} = x + A^\top D^{-1}(\hat{z} + b - Ax) \quad (2.5)$$

Substituting it into 2.2, we have

$$\hat{z} = \arg \min_z \left\{ \|z\|_1 + \frac{1}{2} \|A^\top D^{-1}(z + b - Ax)\|_2^2 \right\} \quad (2.6)$$

Taking the derivative w.r.t. z , assuming $d_i = D_{ii}$, we have

$$\partial \|z\|_1 + (z + b - Ax)_i / d_i = 0$$

which leads to

$$z_i = \text{sign}(Ax - b)_i \max(|(Ax - b)_i| - d_i, 0)$$

Substituting it into 2.5

$$\text{prox}_f(x) = \hat{u} = x + A^\top D^{-1}(b - Ax + \text{sign}(Ax - b) \odot \max(|Ax - b| - \text{diag}(D), 0))$$

3 Problem 3

Taking the derivative w.r.t. y , we have

$$y - w + \frac{1}{(1 - \alpha)\sigma n} \sum_{i=1}^n \partial(y_i - t)_+$$

where

$$\partial(x)_+ = \begin{cases} 1, & x > 0 \\ [0, 1], & x = 0 \\ 0, & x < 0 \end{cases}$$

WLOG, assuming $w_1 \leq w_2 \leq \dots, w_n$, and $w_0 = -\infty, w_{n+1} = \infty$. For each t , we can readily find u, v , such that $w_u \leq t < w_{u+1}, w_v \leq t + \frac{1}{(1-\alpha)\sigma n} < w_{v+1}$.

Then, for $i \leq u$, $y_i = w_i$; for $i \geq v + 1$, $y_i = w_i - \frac{1}{(1-\alpha)\sigma n} > t$; for $u + 1 \leq i \leq v$, y_i must be t . Substituting it into the original problem, we have

$$\min_t \quad t + \sum_{i=v+1}^n \frac{w_i - t}{(1 - \alpha)n} + \sum_{i=u+1}^v (w_i - t)^2 + \left(\frac{1}{(1 - \alpha)\sigma n} \right)^2 (n - v)$$

i.e. given u, v

$$\min_t \quad (v - u)t^2 + \left(1 - \frac{n - v}{(1 - \alpha)n} - 2 \sum_{i=u+1}^v w_i \right) t$$

Keeping u, v , it is a quadratic minimization. Denote $w'_i = w_i - \frac{1}{(1-\alpha)\sigma n}$. Then w_i, w'_i divide the real line into at most $2n + 1$ interval. Each interval corresponds to a set of (u, v) . For each set of (u, v) , we can minimize t by performing a quadratic function minimization.

If we precompute and store $\sum_{i=1}^m w_i$ for $m = 1, 2, \dots, n$, the algorithm's complexity can be $O(n)$.

4 Problem 4

Assuming $X = S\Lambda S^\top$, where Λ is diagonal, since

$$\log \det(X) = \log \det(S\Lambda S^\top) = \log \det \Lambda$$

$\log \det(X)$ is determined by the eigenvalues of X . A standard result shows that the optimal solution can be written as $U^* = SDS^\top$, where D is diagonal. Denote $d_i = D_{ii}$, $\lambda_i = \Lambda_{ii}$. We have

$$\begin{aligned} & f(U) + \frac{1}{2} \|U - X\|_F^2 \\ &= f(D) + \frac{1}{2} \|\Lambda - D\|_F^2 \\ &= \sum_{i=1}^n \left(-\log d_i + \frac{1}{2} |\lambda_i - d_i|^2 \right) \end{aligned}$$

For each i , we optimize separately. Note that since $X, U \in S_{++}^n$, $\lambda_i, d_i > 0$, taking the derivative w.r.t. d_i and setting it to 0, we have

$$-\frac{1}{d_i} + d_i - \lambda_i = 0$$

which leads to $d_i = \frac{\lambda_i + \sqrt{\lambda_i^2 + 4}}{2}$. (omit the negative root)

If we denote $g(X) = Sg(\Lambda)S^\top$ and operations are taken element-wise on Λ . Define $g(x) = \frac{x + \sqrt{x^2 + 4}}{2}$, $x \in \mathbb{R}$, then

$$\text{prox}_f(X) = g(X)$$