

## B9.5 (Homogenous Linear Systems with Linear Coefficients)

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- So, now do we actually go about finding a general solution to

$$x'(t) = Ax(t)$$

- Let  $A = [a_{ij}]$  be an  $n \times n$  constant matrix. The eigenvalues of  $A$  are those numbers (real or complex) numbers  $r$  for which  $(A - rI)u = 0$  has at least one nontrivial (real or complex) solution to  $u$ .
- The corresponding nontrivial solutions  $u$  are called the eigenvectors of  $A$  associated with  $r$ .
- Theorem 5: Suppose the  $n \times n$  constant matrix  $A$  has  $n$  linearly independent eigenvectors  $u_1, u_2, u_3, \dots, u_n$ , and let  $r_i$  be the eigenvalue corresponding to  $u_i$ . Then,  $\{e^{r_1 t} u_1, e^{r_2 t} u_2, e^{r_3 t} u_3, \dots, e^{r_n t} u_n\}$  is a fundamental solution set and  $X(t) = [e^{r_1 t} u_1 \ e^{r_2 t} u_2 \ \dots \ e^{r_n t} u_n]$  is a fundamental matrix on  $(-\infty, \infty)$  for homogenous system  $x' = Ax$ .

Thus, our general solution of  $x' = Ax$  is:  $x(t) = c_1 e^{r_1 t} u_1 + c_2 e^{r_2 t} u_2 + \dots + c_n e^{r_n t} u_n$

Theorem 6: If  $r_1, \dots, r_m$  are distinct eigenvalues of the matrix  $A$  and  $u_i$  is an eigenvector associated with  $r_i$ , then  $u_1, \dots, u_m$  are linearly independent.

- When solving for eigenvalues, always have left side "alone"