Refinement types in Haskell: Exercise Sheet 1

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Exercise 1: Vectors

In the second lecture we introduced the following type of sized vectors:

We also introduced the idea of parametrising predicate synonyms over variables by introducing them in uppercase such as in predicate IsNotDivisibleBy M N. In Liquid Haskell, type synonyms and datatype refinements can similarly be parametrised (or *indexed*) over term variables. Consider the following alternative presentation of sized vectors:

```
\{-\mathbb{Q} \text{ data Vec a N} = \{xs : [a] \mid \text{len } xs = \mathbb{N}\} \mathbb{Q}-\}
```

To apply Vec a to a particular natural number in a refinement type definition we can write Vec a n. For example:

- Part 1. Try to define a function from Vec a N to Vector a, what problem arises?
- Part 2. Give a definition of non-empty sized vectors first using Vector a and then Vec a N.
- **Part 3.** Define the following functions on both Vector and Vec: concatenation, zip, dot product, concatMap.
- **Part 4.** In Liquid Haskell we can parametrise refinement type definitions over more than a single variable. With this in mind, define a type of sized matrices (note that there are analogous approaches to both the Vec and Vector definitions).

Exercise 2: Exercise 3: Balanced Binary Search Trees

In the second lecture, we defined a type of binary search trees as follows:

Part 1. Define the insertion operation on binary search trees from the lecture and then define the union operation for two trees.

Part 2. In lecture 3, we will learn more about measures in Liquid Haskell, and the following is an example on trees:

By adding this measure to our program, we can now include the depth function in predicates and Liquid Haskell can reason about it. Using depth, define a type of *balanced* binary search trees, whereby the depth of either branch can be at most one greater than the other.