

# Brandon Ho

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## EDUCATION

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### University of California San Diego

GPA: 3.97/4.00

*B.S. Computer Engineering, M.S. Intelligent Systems, Robotics & Control, Regents Scholar (~1%) exp. Dec 2024*

- **Relevant Coursework:** Algorithms, Digital Systems, Software Engineering, Deep Learning, Operating Systems, Autonomous Vehicles, Computer Vision, Computer Architecture, Robot Systems Design & Implementation

## EXPERIENCE

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### Relativity Space

Long Beach, CA

*Robotics Software Engineer Intern*

*June 2023 - Present*

- Exposing **OPC-UA** interface on Fronius welders to real-time context for Wire Arc Additive Manufacturing
- **RTOS:** Integrated **RTnet** kernel module on network interface for real-time TCP comms on **Xenomai** RT framework
- **ROS2 Driver:** Wrote an OPC-UA driver in **C++** to read and write over RT (shared memory) and non-RT contexts
- **UI Dev:** Created web interface for weld engineers to interact with OPC-UA parameters in **TypeScript**

### Garmin

Brea, CA

*Software Engineer Intern*

*June 2022 - December 2022*

- Automating release processes and mock radio UI layer on the Tuner Team (Garmin AutoOEM Radio)
- **Process Automation:** Utilized Python REST APIs to automate page generation with user-configurable metadata
- **UI Automation:** Automated mock UI creation and deployment using MQTT & Node-RED for **214 D-Bus services**

### Yonder Dynamics

La Jolla, CA

*Software Lead*

*October 2020 - Present*

- Lead software dev for rover to autonomously path and perform tasks in the University Rover Competition
- **Project Management:** Leading a team of **10+ SWE w/ SCRUM** and spearheading documentation on Notion
- **Autonomous Exploration:** Implementing AR-tag detection with computer vision and researching RRT\* search algorithm to update a live AR-tag probability map in C++, **increasing rover exploration speed by ~10x**
- **Sensor Fusion:** Fusing GPS with local position from IMU and stereo camera for a **~20% increase in accuracy**
- **Obstacle Avoidance:** Created a **ROS** obstacle detection and avoidance pipeline in C++ with **RealSense** stereo camera to efficiently convert 3D pointclouds at 30Hz into occupancy grid and output avoidance waypoints

### InflammaSense

UCSD ECE

*Software Developer and Undergraduate Research Assistant*

*January 2021 - September 2022*

- Built medical device to record and analyze neural signals for early signs of sepsis, published **Scientific Reports** ([link](#))
- **Data Pipeline:** Designing a robust asynchronous network with the ZeroMQ Python API for the wireless display, transmission, storage (PostgreSQL), analysis of neural data for an array of **100+ medical devices (~155 Mbps)**
- **Project Management:** Documenting a comprehensive system model and **leading a team of 5+ SWE** with Asana
- **Web Development:** Developing a website to display high throughput (8 kHz) neural data with React.js & Node.js

## PROJECTS

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### SEMPPro

Bae Lab

*Using Explainable AI to Learn Structure-Property Insights from Hydrogel Microscopy Images*

*Spring 2021*

- **Web Scraping:** Developed NLP scraping algorithm (Selenium+BeautifulSoup), compiling data from **1100+ articles**
- **Deep Learning:** Optimized and trained a ResNext model in Pytorch to predict hydrogel modulus from dataset of microscopy images, able to predict within a range of 1 log Pa with **an accuracy of ~90%**
- **Explainable AI:** Implemented regression activation mapping on a CNN to expose learned structure-property insights

### Autow

Autonomous Vehicles

*Autonomous tow hitching using Computer Vision*

*Fall 2022*

- Led a team of two mechanical and one software engineer in programming an RC car to autonomously hitch to a trailer
- **ROS2:** Built an asynch callback system with **ROS2** for seamless cohesion between driver and autonomous control
- **Computer Vision:** Utilized **OpenCV** to perform ArUco tag detection and pose estimation to perform iterative localization and path planning, resulting in a **90% hitching accuracy**

## SKILLS

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**Programming Languages:** Python, C++, Java, SQL, JS, PHP, HTML/CSS, TypeScript

**Technologies:** AWS, Git, Jupyter Notebook, Linux, Docker, Confluence, Jira, Gerrit

**Frameworks:** ROS2, ROS, PyTorch, ZeroMQ, MQTT, D-Bus, TimescaleDB, NumPy, Pandas, SciKit, Ansible