SPECIAL LINEAR SYSTEMS OF EQUATIONS

- Symmetric positive definite matrices.
- ullet The LDL^T decomposition; The Cholesky factorization
- Banded systems

Positive-Definite Matrices

> A real matrix is said to be positive definite if

$$(Au,u)>0$$
 for all $u
eq 0$ $u\in~\mathbb{R}^n$

▶ Let A be a real positive definite matrix. Then there is a scalar $\alpha > 0$ such that

$$(Au,u) \geq lpha \|u\|_2^2,$$

- ➤ Consider now the case of Symmetric Positive Definite (SPD) matrices.
- ➤ Consequence 1: A is nonsingular
- ➤ Consequence 2: the eigenvalues of A are (real) positive

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A few properties of SPD matrices

- ➤ Diagonal entries of A are positive
- ightharpoonup Each principal submatrix (A(1:k,1:k) in matlab notation) is SPD
- For any $n \times k$ matrix X of rank k, the matrix X^TAX is SPD.
- ➤ The mapping :

$$x,y \rightarrow (x,y)_A \equiv (Ax,y)$$

is a proper inner product on \mathbb{R}^n . The associated norm, denoted by $\|.\|_A$, is called the energy norm:

$$||x||_A = (Ax, x)^{1/2} = \sqrt{x^T A x}$$

More terminology

➤ A matrix is Positive Semi-Definite if

$$(Au,u)\geq 0$$
 for all $u\in \mathbb{R}^n$

- ➤ Eigenvalues of symmetric positive semi-definite matrices are real nonnegative, i.e., ...
- \blacktriangleright ... A can be singular [If not, A is SPD]
- ➤ A matrix is said to be Negative Definite if -A is positive definite. Similar definition for Negative Semi-Definite
- ➤ A matrix that is neither positive semi-definite nor negative semi-definite is indefinite
- Show that if $A^T = A$ and $(Ax, x) = 0 \forall x$ then A = 0
- **Show:** A is indefinite iff $\exists x,y:(Ax,x)(Ay,y)<0$

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The LDL^T and Cholesky factorizations

Consider the LU factorization of an SPD matrix A. Let D=diag(U).

$$A = LU = LD \underbrace{(D^{-1}U)}_{M^T} \equiv LDM^T$$

- \blacktriangleright Both L and M are unit lower triangular
- ► Consider $L^{-1}AL^{-T} = DM^TL^{-T}$
- Matrix on the right is upper triangular. But it is also symmetric. Therefore $M^TL^{-T}=I$ and so M=L
- ▶ The diagonal entries of D are positive [Proof: consider $L^{-1}AL^{-T}=D$]. In the end:

$$A = LDL^T = GG^T$$
 where $G = LD^{1/2}$

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Row-Cholesky (outer product form)

Scale the rows as the algorithm proceeds. Line 4 becomes

$$a(i,:) := a(i,:) - [a(k,i)/\sqrt{a(k,k)}] * \left[a(k,:)/\sqrt{a(k,k)}
ight]$$

ALGORITHM : 1. Outer product Cholesky

- 1. For k = 1 : n Do:
- 2. $A(k, k:n) = A(k, k:n) / \sqrt{A(k,k)}$;
- 3. For i := k + 1 : n Do :
- 4. A(i, i:n) = A(i, i:n) A(k, i) * A(k, i:n);
- 5. **End**
- 6. End
- Result: Upper triangular matrix U such $A = U^T U$.

➤ Cholesky factorization is a specialization of the LU factorization for the SPD case. Several variants exist.

First algorithm: row-oriented LDLT

Adapted from Gaussian Elimination [Work only on upper triang. part]

- 1. For k = 1 : n 1 Do:
- 2. For i = k + 1 : n Do:
- 3. piv := a(k,i)/a(k,k)
- 4. a(i,i:n) := a(i,i:n) piv * a(k,i:n)
- 5. End
- 6. End
- ➤ This will give the U matrix of the LU factorization. Therefore D = diag(U), $L = D^{-1}U$.

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Example:

$$A = \left(egin{array}{ccc} 1 & -1 & 2 \ -1 & 5 & 0 \ 2 & 0 & 9 \end{array}
ight)$$

- \triangle Is A symmetric positive definite?
- ightharpoonup What is the LDL^T factorization of A?
- lacktriangle What is the Cholesky factorization of A?

Column Cholesky.

Let $A = GG^T$ with G = lower triangular. Then equate j-th columns:

$$a(i,j) = \sum_{k=1}^j g(j,k) g^T(k,i)
ightarrow$$

$$egin{aligned} A(:,j) &= \sum_{k=1}^{j} G(j,k) G(:,k) \ &= G(j,j) G(:,j) + \sum_{k=1}^{j-1} G(j,k) G(:,k)
ightarrow \ G(j,j) G(:,j) &= A(:,j) - \sum_{k=1}^{j-1} G(j,k) G(:,k) \end{aligned}$$

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▶ Assume that first i-1 columns of G already known.

➤ Compute unscaled column-vector:

$$v = A(:,j) - \sum_{k=1}^{j-1} G(j,k) G(:,k)$$

- ► Notice that $v(j) \equiv G(j, j)^2$.
- ► Compute $\sqrt{v(j)}$ scale v to get j-th column of G.

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ALGORITHM: 2. Column Cholesky

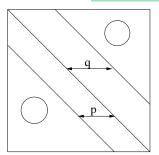
- 1. For j = 1 : n do
- 2. For k = 1 : j 1 do
- 3. A(j:n,j) = A(j:n,j) A(j,k) * A(j:n,k)
- 4. EndDo
- 5. If $A(j,j) \leq 0$ ExitError("Matrix not SPD")
- $6. \qquad A(j,j) = \sqrt{A(j,j)}$
- 7. A(j+1:n,j) = A(j+1:n,j)/A(j,j)
- 8. EndDo

Example:

$$A = \left(egin{array}{ccc} 1 & -1 & 2 \ -1 & 5 & 0 \ 2 & 0 & 9 \end{array}
ight)$$

Banded matrices

- **▶** Banded matrices arise in many applications
- lacksquare A has upper bandwidth q if $a_{ij}=0$ for j-i>q
- ▶ A has lower bandwidth p if $a_{ij} = 0$ for i j > p



➤ Simplest case: tridiagonal $\blacktriangleright p = q = 1$.

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➤ First observation: Gaussian elimination (no pivoting) preserves the initial banded form. Consider first step of Gaussian elimination:

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2. For i=2:n Do:

3. a_{i1}:=a_{i1}/a_{11} (pivots)

4. For j:=2:n Do:

5. a_{ij}:=a_{ij}-a_{i1}*a_{1j}

6. End

7. End
```

▶ If A has upper bandwidth q and lower bandwidth p then so is the resulting [L/U] matrix. ▶ Band form is preserved (induction)

Operation count?

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What happens when partial pivoting is used?

If A has lower bandwidth p, upper bandwidth q, and if Gaussian elimination with partial pivoting is used, then the resulting U has upper bandwidth p+q. L has at most p+1 nonzero elements per column (bandedness is lost).

> Simplest case: tridiagonal **>** p = q = 1.

Example:

$$A = egin{pmatrix} 1 & 1 & 0 & 0 & 0 \ 2 & 1 & 1 & 0 & 0 \ 0 & 2 & 1 & 1 & 0 \ 0 & 0 & 2 & 1 & 1 \ 0 & 0 & 0 & 2 & 1 \end{pmatrix}$$

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