

EIGENVALUE PROBLEMS

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Eigenvalue Problems. Introduction

Let A an $n \times n$ real nonsymmetric matrix. The eigenvalue problem:

$$Ax = \lambda x$$

$\lambda \in \mathbb{C}$: eigenvalue

$x \in \mathbb{C}^n$: eigenvector

Types of Problems:

- Compute a few λ_i 's with smallest or largest real parts;
- Compute all λ_i 's in a certain region of \mathbb{C} ;
- Compute a few of the dominant eigenvalues;
- Compute all λ_i 's.

Eigenvalue Problems. Their origins

- Structural Engineering [$Ku = \lambda Mu$]
- Stability analysis [e.g., electrical networks, mechanical system,...]
- Bifurcation analysis [e.g., in fluid flow]
- Electronic structure calculations [Schrödinger equation..]
- Application of new era: page ranking on the world-wide web.

Basic definitions and properties

A complex scalar λ is called an eigenvalue of a square matrix A if there exists a nonzero vector u in \mathbb{C}^n such that $Au = \lambda u$. The vector u is called an **eigenvector** of A associated with λ . The set of all eigenvalues of A is the 'spectrum' of A . Notation: $\Lambda(A)$.

- λ is an eigenvalue iff the columns of $A - \lambda I$ are linearly dependent.
- ... equivalent to saying that its rows are linearly dependent. So: there is a nonzero vector w such that

$$w^H(A - \lambda I) = 0$$

- w^H is a **left** eigenvector of A ($u =$ **right** eigenvector)
- λ is an eigenvalue iff $\det(A - \lambda I) = 0$

Basic definitions and properties (cont.)

- An eigenvalue is a root of the **Characteristic polynomial**:

$$p_A(\lambda) = \det(A - \lambda I)$$

- So there are n eigenvalues (counted with their multiplicities).
- The multiplicity of these eigenvalues as roots of p_A are called **algebraic multiplicities**.
- The **geometric multiplicity** of an eigenvalue λ_i is the number of linearly independent eigenvectors associated with λ_i .

- Geometric multiplicity is \leq algebraic multiplicity.
- An eigenvalue is **simple** if its (algebraic) multiplicity is one.
- It is **semi-simple** if its geometric and algebraic multiplicities are equal.

 Consider

$$A = \begin{pmatrix} 1 & 2 & -4 \\ 0 & 1 & 2 \\ 0 & 0 & 2 \end{pmatrix}$$

Eigenvalues of A ? their algebraic multiplicities? their geometric multiplicities? Is one a semi-simple eigenvalue?

 Same questions if a_{33} is replaced by one.

 Same questions if a_{12} is replaced by zero.

- Two matrices A and B are **similar** if there exists a nonsingular matrix X such that

$$B = XAX^{-1}$$

- Definition: A is **diagonalizable** if it is similar to a diagonal matrix







- THEOREM: A matrix is diagonalizable iff it has n linearly independent eigenvectors

- THEOREM (Schur form): Any matrix is unitarily similar to a triangular matrix, i.e., for any A there exists a unitary matrix Q and an upper triangular matrix R such that

$$A = QRQ^H$$

- Any Hermitian matrix is unitarily similar to a **real diagonal** matrix, (i.e. its Schur form is real diagonal).

Schur Form – Proof

-  Show that there is at least one eigenvalue and eigenvector of A : $Ax = \lambda x$, with $\|x\|_2 = 1$
-  There is a unitary transformation P such that $Px = e_1$. How do you define P ?
-  Show that $PA P^H = \left(\begin{array}{c|c} \lambda & ** \\ \hline 0 & A_2 \end{array} \right)$.
-  Apply process recursively to A_2 .
-  What happens if A is Hermitian?
-  Another proof altogether: use Jordan form of A and QR factorization

Perturbation analysis

- General questions: If A is perturbed how does an eigenvalue change? How about an eigenvector?
- Also: sensitivity of an eigenvalue to perturbations

THEOREM [Gerschgorin]

$$\forall \lambda \in \Lambda(A), \quad \exists i \text{ such that } |\lambda - a_{ii}| \leq \sum_{\substack{j=1 \\ j \neq i}}^{j=n} |a_{ij}| .$$

- In words: An eigenvalue λ of A is located in one of the closed discs of the complex plane centered at a_{ii} and with radius $\rho_i = \sum_{j \neq i} |a_{ij}|$.
- The proof is by contradiction.

Gerschgorin's theorem - example

 Find a region of the complex plane where the eigenvalues of the following matrix are located:

$$A = \begin{pmatrix} 1 & -1 & 0 & 0 \\ 0 & 2 & 0 & 1 \\ -1 & -2 & -3 & 1 \\ \frac{1}{2} & \frac{1}{2} & 0 & -4 \end{pmatrix}$$

- Refinement: if disks are all disjoint then each of them contains one eigenvalue
- Refinement: can combine row and column version of the theorem (column version obtained by applying theorem to A^H).

Bauer-Fike theorem

THEOREM [Bauer-Fike] Let $\tilde{\lambda}, \tilde{u}$ be an approximate eigenpair with $\|\tilde{u}\|_2 = 1$, and let $r = A\tilde{u} - \tilde{\lambda}\tilde{u}$ ('residual vector'). Assume A is diagonalizable: $A = XDX^{-1}$, with D diagonal. Then

$$\exists \lambda \in \Lambda(A) \quad \text{such that} \quad |\lambda - \tilde{\lambda}| \leq \text{cond}_2(X) \|r\|_2 .$$

- Very restrictive result - also not too sharp in general.
- Alternative formulation. If E is a perturbation to A then for any eigenvalue $\tilde{\lambda}$ of $A + E$ there is an eigenvalue λ of A such that:

$$|\lambda - \tilde{\lambda}| \leq \text{cond}_2(X) \|E\|_2 .$$



Prove this result from the previous one.

Conditioning of Eigenvalues

- Assume that λ is a simple eigenvalue with right and left eigenvectors u and w^H respectively. Consider the matrices:

$$A(t) = A + tE$$

- Eigenvalue $\lambda(t)$, eigenvector $u(t)$.
- Conditioning of λ of A relative to E is $\left| \frac{d\lambda(t)}{dt} \right|_{t=0}$.

- Write $A(t)u(t) = \lambda(t)u(t)$

- Then multiply both sides to the left by w^H

$$w^H(A + tE)u(t) = \lambda(t)w^H u(t) \rightarrow$$

$$\begin{aligned} \lambda(t)w^H u(t) &= w^H A u(t) + t w^H E u(t) \\ &= \lambda w^H u(t) + t w^H E u(t). \end{aligned}$$

$$\rightarrow \frac{\lambda(t) - \lambda}{t} w^H u(t) = w^H E u(t)$$

- Take the limit at $t = 0$,

$$\lambda'(0) = \frac{w^H E u}{w^H u}$$

- Note: the left and right eigenvectors associated with a simple eigenvalue cannot be orthogonal to each other.
- Actual conditioning of an eigenvalue, given a perturbation “in the direction of E ” is $|\lambda'(0)|$.
- In practice only estimate of $\|E\|$ is available, so

$$|\lambda'(0)| \leq \frac{\|Eu\|_2 \|w\|_2}{|(u, w)|} \leq \|E\|_2 \frac{\|u\|_2 \|w\|_2}{|(u, w)|}$$

Definition. The condition number of a simple eigenvalue λ of an arbitrary matrix A is defined by

$$\text{cond}(\lambda) = \frac{1}{\cos \theta(u, w)}$$

in which u and w^H are the right and left eigenvectors, respectively, associated with λ .

Example: Consider the matrix

$$A = \begin{pmatrix} -149 & -50 & -154 \\ 537 & 180 & 546 \\ -27 & -9 & -25 \end{pmatrix}$$

- $\Lambda(A) = \{1, 2, 3\}$. Right and left eigenvectors associated with $\lambda_1 = 1$:

$$u = \begin{pmatrix} 0.3162 \\ -0.9487 \\ 0.0 \end{pmatrix} \quad \text{and} \quad w = \begin{pmatrix} 0.6810 \\ 0.2253 \\ 0.6967 \end{pmatrix}$$

So:

$$\text{cond}(\lambda_1) \approx 603.64$$

- Perturbing a_{11} to -149.01 yields the spectrum:
 $\{0.2287, 3.2878, 2.4735\}$.
- as expected..
- For Hermitian (also normal matrices) every simple eigenvalue is well-conditioned, since $\text{cond}(\lambda) = 1$.

Perturbations with Multiple Eigenvalues - Example

- $A = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 2 \\ \textcolor{red}{0} & 0 & 1 \end{pmatrix} = I_3 + \begin{pmatrix} 0 & 2 & 0 \\ 0 & 0 & 2 \\ \textcolor{red}{0} & 0 & 0 \end{pmatrix} = I + 2J$
- Worst case perturbation is in 3,1 position: set $J_{31} = \epsilon$.
- Eigenvalues of perturbed J are the roots of
$$p(\mu) = \mu^3 - 2 \cdot 2 \cdot \epsilon.$$
- Hence eigenvalues of perturbed A are $1 + O(\sqrt[3]{\epsilon})$.
- In general, if index of eigenvalue (dimension of largest Jordan block) is k , then an $O(\epsilon)$ perturbation to A can lead to $O(\sqrt[k]{\epsilon})$ change in eigenvalue. Simple eigenvalue case corresponds to $k = 1$.

The power method

- Basic idea is to generate the sequence of vectors $A^k v_0$ where $v_0 \neq 0$ – then normalize.
- Most commonly used normalization: ensure that the largest component of the approximation is equal to one.

The Power Method

1. Choose a nonzero initial vector $v^{(0)}$.
2. For $k = 1, 2, \dots$, until convergence, Do:
3. $v^{(k)} = \frac{1}{\alpha_k} A v^{(k-1)}$ where
4. $\alpha_k = \operatorname{argmax}_{i=1, \dots, n} |(A v^{(k-1)})_i|$
5. EndDo

- $\operatorname{argmax}_{i=1, \dots, n} |x_i| \equiv$ the component x_i with largest modulus

Convergence of the power method

THEOREM Assume there is one eigenvalue λ_1 of A , s.t. $\lambda_1 = \max_j |\lambda_j|$, and that λ_1 is semi-simple. Then either the initial vector $v^{(0)}$ has no component in $\text{Null}(A - \lambda_1 I)$ or $v^{(k)}$ converges to an eigenvector associated with λ_1 and $\alpha_k \rightarrow \lambda_1$.

Proof in the diagonalizable case.

➤ $v^{(k)}$ is = vector $A^k v^{(0)}$ normalized by a certain scalar $\hat{\alpha}_k$ in such a way that its largest component is 1.

➤ Decompose initial vector $v^{(0)}$ in the eigenbasis as:

$$v^{(0)} = \sum_{i=1}^n \gamma_i u_i$$

➤ Each u_i is an eigenvector associated with λ_i .

- Note that $A^k u_i = \lambda_i^k u_i$

$$\begin{aligned} v^{(k)} &= \frac{1}{\text{scaling}} \times \sum_{i=1}^n \lambda_i^k \gamma_i u_i \\ &= \frac{1}{\text{scaling}} \times \left[\lambda_1^k \gamma_1 u_1 + \sum_{i=2}^n \lambda_i^k \gamma_i u_i \right] \\ &= \frac{1}{\text{scaling}'} \times \left[u_1 + \sum_{i=2}^n \left(\frac{\lambda_i}{\lambda_1} \right)^k \frac{\gamma_i}{\gamma_1} u_i \right] \end{aligned}$$

- Second term inside bracket converges to zero. QED
- Proof suggests that the convergence factor is given by

$$\rho_D = \frac{|\lambda_2|}{|\lambda_1|}$$

where λ_2 is the second largest eigenvalue in modulus.

Example: Consider a 'Markov Chain' matrix of size $n = 55$. Dominant eigenvalues are $\lambda = 1$ and $\lambda = -1$ ➤ the power method applied directly to A fails. (Why?)

➤ We can consider instead the matrix $I + A$ The eigenvalue $\lambda = 1$ is then transformed into the (only) dominant eigenvalue $\lambda = 2$

Iteration	Norm of diff.	Res. norm	Eigenvalue
20	0.639D-01	0.276D-01	1.02591636
40	0.129D-01	0.513D-02	1.00680780
60	0.192D-02	0.808D-03	1.00102145
80	0.280D-03	0.121D-03	1.00014720
100	0.400D-04	0.174D-04	1.00002078
120	0.562D-05	0.247D-05	1.00000289
140	0.781D-06	0.344D-06	1.00000040
161	0.973D-07	0.430D-07	1.00000005

The Shifted Power Method

➤ In previous example shifted A into $B = A + I$ before applying power method. We could also iterate with $B(\sigma) = A + \sigma I$ for any positive σ

Example: With $\sigma = 0.1$ we get the following improvement.

Iteration	Norm of diff.	Res. Norm	Eigenvalue
20	0.273D-01	0.794D-02	1.00524001
40	0.729D-03	0.210D-03	1.00016755
60	0.183D-04	0.509D-05	1.00000446
80	0.437D-06	0.118D-06	1.00000011
88	0.971D-07	0.261D-07	1.00000002

- **Question:** What is the best **shift-of-origin** σ to use?
- Easy to answer the question when all eigenvalues are real.


Assume all eigenvalues are real and labeled decreasingly:

$$\lambda_1 > \lambda_2 \geq \lambda_2 \geq \cdots \geq \lambda_n,$$

Then:

The value of σ which yields the best convergence factor is:

$$\sigma_{opt} = \frac{\lambda_2 + \lambda_n}{2}$$

 Plot a typical function $\phi(\sigma) = \rho(A - \sigma I)$ as a function of σ . Determine the minimum value and prove the above result.

Inverse Iteration

Observation: The eigenvectors of A and A^{-1} are identical.

- Idea: use the power method on A^{-1} .
- Will compute the eigenvalues closest to zero.
- **Shift-and-invert** Use power method on $(A - \sigma I)^{-1}$. ➤ will compute eigenvalues closest to σ .
- Advantages: fast convergence in general.
- Drawbacks: need to factor A (or $A - \sigma I$) into LU.