

Assignment 1 - ME 562 - Brandon Lampe

Constitutive Equations and Associated Numerical Algorithms

```
In [224]: from __future__ import division
from IPython.display import display_latex
from IPython.core.display import Math
import sys
sys.path.append('/Users/Lampe/PyScripts')
# print sys.path
from scipy import linalg as LA
import math
import numpy as np
import blfunc as bl
from sympy import *
init_printing()
np.set_printoptions(precision=3)
```

Problem 1

Function for creating orthonormal basis is contained in "blfunc", which is shown seperately.

```
In [225]: # transformation matrix
a_eE = bl.orth_basis()
a_Ee = np.transpose(a_eE)
print a_eE
```

```
[[ 0.132  0.778  0.614]
 [ 0.898  0.168 -0.406]
 [-0.419  0.605 -0.677]]
```

```
In [226]: # verify the transformation matrix is orthonormal
i = np.dot(a_Ee, a_eE)
print i
```

```
[[ 1.000e+00  5.551e-17  1.110e-16]
 [ 5.551e-17  1.000e+00  0.000e+00]
 [ 1.110e-16  0.000e+00  1.000e+00]]
```

```
In [227]: # verify the transformation matrix is nonsingular
print LA.det(a_Ee)
```

```
1.0
```

Problem 2

2.(i)

```
In [228]: T_EE = np.array([[7, 2, 11],
                           [2, 4, 5],
                           [11, 5, 6]])
print T_EE
```

```
[[ 7  2 11]
 [ 2  4  5]
 [11  5  6]]
```

```
In [229]: # Transform T to the e-e basis
T_ee = a_eE.dot(T_EE).dot(a_Ee)
print T_ee
```

```
[[ 11.773  5.714 -6.079]
 [ 5.714 -1.348 -6.251]
 [-6.079 -6.251  6.575]]
```

```
In [230]: # Transform T back to the E-E basis
T_EE_ck = a_Ee.dot(T_ee).dot(a_eE)
print T_EE_ck

[[ 7.  2. 11.]
 [ 2.  4.  5.]
 [11.  5.  6.]]
```

My algorithm appears correct because I am able to transform T from the E-E basis to the e-e basis then back to the E-E basis and obtain my original components in the E-basis.

2(ii)

```
In [231]: # spherical components of T in the E-E basis
T_EE_sp = np.multiply(np.trace(T_EE) / 3, np.eye(3, 3))
print T_EE_sp

[[ 5.667  0.  0. ]
 [ 0.  5.667  0. ]
 [ 0.  0.  5.667]]
```

```
In [232]: # deviatoric components of T in the E-E basis
T_EE_dev = T_EE - T_EE_sp
print T_EE_dev

[[ 1.333  2.  11. ]
 [ 2. -1.667  5. ]
 [11.  5.  0.333]]
```

Problem 3

3(i)

```
In [233]: eigval, eigvec = LA.eig(T_EE)

l1_EE, l2_EE, l3_EE = eigval
print 'Eigenvalue 1 = %G + %Gi' % (l1_EE.real, l1_EE.imag)
print 'Eigenvalue 2 = %G + %Gi' % (l2_EE.real, l2_EE.imag)
print 'Eigenvalue 3 = %G + %Gi' % (l3_EE.real, l3_EE.imag)

Eigenvalue 1 = 19.1218 + 0i
Eigenvalue 2 = -5.12943 + 0i
Eigenvalue 3 = 3.00763 + 0i

In [234]: P1_E, P2_E, P3_E = eigvec[:, 0], eigvec[:, 1], eigvec[:, 2]

print 'Principal Vector 1 in E basis => %G, %G, %G' % (P1_E[0], P1_E[1], P1_E[2])
print 'Principal Vector 2 in E basis => %G, %G, %G' % (P2_E[0], P2_E[1], P2_E[2])
print 'Principal Vector 3 in E basis => %G, %G, %G' % (P3_E[0], P3_E[1], P3_E[2])

Principal Vector 1 in E basis => -0.66617, -0.312077, -0.677366
Principal Vector 2 in E basis => -0.623059, -0.266296, 0.735449
Principal Vector 3 in E basis => 0.409896, -0.911973, 0.0170443
```

3(ii)

```
In [235]: # orthonormal Principal basis wrt E-E:
P_EE = eigvec
print P_EE

[[-0.666 -0.623  0.41 ]
 [-0.312 -0.266 -0.912]
 [-0.677  0.735  0.017]]
```

```
In [236]: # check that P basis is orthonormal (transpose = inverse)
P_EE.dot(np.transpose(P_EE))
```

```
Out[236]: array([[ 1.000e+00,  2.220e-16,  1.266e-16],
 [ 2.220e-16,  1.000e+00, -2.134e-16],
 [ 1.266e-16, -2.134e-16,  1.000e+00]])
```

3(iii)

```
In [237]: # transformation matrix between the E-P basis(a_EP):
```

```
a_EP = P_EE
print a_EP

[[-0.666 -0.623  0.41 ]
 [-0.312 -0.266 -0.912]
 [-0.677  0.735  0.017]]
```

```
In [238]: # transpose of a_EP
```

```
a_PE = np.transpose(a_EP)
print a_PE

[[-0.666 -0.312 -0.677]
 [-0.623 -0.266  0.735]
 [ 0.41  -0.912  0.017]]
```

```
In [239]: # components of T in the Principal basis
```

```
T_PP = a_PE.dot(T_EE).dot(a_EP)
print T_PP

[[ 1.912e+01  2.665e-15 -1.776e-15]
 [ 2.220e-15 -5.129e+00  6.661e-16]
 [-1.332e-15  2.220e-16  3.008e+00]]
```

Yes, the diagonal components should be the eigenvalues with all other components equal zero.

3(iv)

```
In [240]: T_PP_inv = LA.inv(T_PP)
```

```
print T_PP_inv

[[ 5.230e-02  2.717e-17  3.089e-17]
 [ 2.264e-17 -1.950e-01  4.318e-17]
 [ 2.317e-17  1.439e-17  3.325e-01]]
```

```
In [241]: T_EE_inv = a_EP.dot(T_PP_inv).dot(a_PE)
```

```
print T_EE_inv

[[ 0.003 -0.146  0.115]
 [-0.146  0.268  0.044]
 [ 0.115  0.044 -0.081]]
```

```
In [242]: #check if inverse is correct -> should get Identity matrix"
```

```
print np.dot(T_EE, T_EE_inv)

[[ 1.000e+00  5.551e-17 -1.110e-16]
 [ 0.000e+00  1.000e+00 -8.327e-17]
 [ 0.000e+00  0.000e+00  1.000e+00]]
```

Yes, my result is correct.

3(v)

```
In [243]: eigval, eigvec = LA.eig(T_ee)
```

```
l1_ee, l2_ee, l3_ee = eigval
print 'Eigenvalue 1 = %G + %Gi' % (l1_ee.real, l1_ee.imag)
print 'Eigenvalue 2 = %G + %Gi' % (l2_ee.real, l2_ee.imag)
print 'Eigenvalue 3 = %G + %Gi' % (l3_ee.real, l3_ee.imag)
```

```
Eigenvalue 1 = 19.1218 + 0i
Eigenvalue 2 = 3.00763 + 0i
Eigenvalue 3 = -5.12943 + 0i
```

```
In [244]: P1_e, P2_e, P3_e = eigvec[:, 0], eigvec[:, 1], eigvec[:, 2]

print 'Principal Vector 1 in e basis => %G, %G, %G' % (P1_e[0], P1_e[1], P1_e[2])
print 'Principal Vector 2 in e basis => %G, %G, %G' % (P2_e[0], P2_e[1], P2_e[2])
print 'Principal Vector 3 in e basis => %G, %G, %G' % (P3_e[0], P3_e[1], P3_e[2])
P_ee = eigvec

Principal Vector 1 in e basis => 0.746479, 0.376013, -0.548983
Principal Vector 2 in e basis => 0.645372, -0.208187, 0.734951
Principal Vector 3 in e basis => -0.16206, 0.902924, 0.398076
```

The eigenvectors vary as they should. P_ee is the principal basis wrt the e-e basis, while P_EE is the principal basis wrt the E-E basis.

Problem 4

```
In [245]: # bl.tran_3x3_vm -> located in "blfunc"
T_E_vm = bl.tran_3x3_vm(T_EE)
print T_E_vm

[[ 7.   ]
 [ 4.   ]
 [ 6.   ]
 [ 2.828]
 [ 7.071]
 [ 15.556]]
```

```
In [246]: T_e_vm = bl.tran_3x3_vm(T_ee)
print T_e_vm

[[ 11.773]
 [ -1.348]
 [ 6.575]
 [ 8.08 ]
 [ -8.84 ]
 [ -8.597]]
```

Problem 5

5(i) bl.tran_a_A() -> located in "blfunc"

5(ii)

```
In [247]: A_eE = bl.tran_a_A(a_eE)
A_Ee = np.transpose(A_eE)

T_e_vm_ck = A_eE.dot(T_E_vm)
T_E_vm_ck = A_Ee.dot(T_e_vm)

# verify T_e is correct
print T_e_vm_ck

[[ 11.773]
 [ -1.348]
 [ 6.575]
 [ 8.08 ]
 [ -8.84 ]
 [ -8.597]]
```

```
In [248]: # T_E_vm in V-m notation (check)
print T_E_vm_ck

[[ 7.   ]
 [ 4.   ]
 [ 6.   ]
 [ 2.828]
 [ 7.071]
 [ 15.556]]
```

```
In [249]: # Check that A_eE (6x6) is orthogonal
orthogonal_ck = A_eE.dot(A_Ee)
print orthogonal_ck

[[ 1.000e+00 -4.550e-18  8.990e-18  1.252e-16  6.939e-17  6.939e-18]
 [-4.550e-18  1.000e+00 -4.322e-17  1.003e-16  8.327e-17  2.776e-17]
 [ 8.990e-18 -4.322e-17  1.000e+00 -3.823e-17  0.000e+00 -1.110e-16]
 [ 1.252e-16  1.003e-16 -3.823e-17  1.000e+00 -5.551e-17 -8.327e-17]
 [ 6.939e-17  8.327e-17  0.000e+00 -5.551e-17  1.000e+00  2.776e-17]
 [ 6.939e-18  2.776e-17 -1.110e-16 -8.327e-17  2.776e-17  1.000e+00]]
```

Problem 6

functions for calculating the deviatoric and spherical projects are shown in "bl.func"

```
In [250]: # P spherical: componenets of the V-M version of the fourth -order spherical projection
P_dv = P_dv()
P_sp = P_sp()
```

```
In [251]: # T_dev in VM notation
T_E_dv = P_dv.dot(T_E_vm)
print T_E_dv
```

```
[[ 1.333]
 [-1.667]
 [ 0.333]
 [ 2.828]
 [ 7.071]
 [15.556]]
```

```
In [252]: # T_dev in 3x3 form
bl.tran_vm_3x3(T_E_dv)
```

```
Out[252]: array([[ 1.333,  2.   , 11.   ],
 [ 2.   , -1.667,  5.   ],
 [11.   ,  5.   ,  0.333]])
```

```
In [219]: T_E_sp = P_sp.dot(T_E_vm)
bl.tran_vm_3x3(T_E_sp)
```

```
Out[219]: array([[ 5.667,  0.   ,  0.   ],
 [ 0.   ,  5.667,  0.   ],
 [ 0.   ,  0.   ,  5.667]])
```

Problem 7

The deviatoric and spherical projectors are isotropic; therefore, the components of the two tensors are the same in any basis.

```
In [223]: # deviatoric projector components in the e-e basis (VM)
P_dv_ck = A_eE.dot(P_dv).dot(A_Ee)
print P_dv_ck
```

```
[[ 6.667e-01 -3.333e-01 -3.333e-01  1.110e-16  2.776e-17  2.776e-17]
 [-3.333e-01  6.667e-01 -3.333e-01  8.327e-17  5.551e-17  2.776e-17]
 [-3.333e-01 -3.333e-01  6.667e-01 -1.110e-16  0.000e+00 -8.327e-17]
 [ 1.110e-16  6.939e-17 -8.327e-17  1.000e+00 -1.110e-16 -5.551e-17]
 [ 4.163e-17  0.000e+00  0.000e+00 -8.327e-17  1.000e+00 -5.551e-17]
 [ 0.000e+00  0.000e+00 -1.110e-16 -1.110e-16  2.776e-17  1.000e+00]]
```

```
In [221]: # spherical projector componenets in the e-e basis (VM)
P_sp_ck = A_eE.dot(P_sp).dot(A_Ee)
print P_sp_ck
```

```
[[ 3.333e-01  3.333e-01  3.333e-01  2.082e-17  3.469e-17  0.000e+00]
 [ 3.333e-01  3.333e-01  3.333e-01  2.776e-17  1.388e-17  0.000e+00]
 [ 3.333e-01  3.333e-01  3.333e-01  2.082e-17  3.469e-17  0.000e+00]
 [ 2.776e-17  2.776e-17  2.776e-17  2.311e-33  1.541e-33  0.000e+00]
 [ 2.776e-17  2.776e-17  2.776e-17  2.311e-33  1.541e-33  0.000e+00]
 [ 0.000e+00  0.000e+00  0.000e+00  0.000e+00  0.000e+00  0.000e+00]]
```