

ASSIGNMENT 5

Brandon Lampe
ME 512 - Continuum Mechanics

September 25, 2014

1 Find the derivatives with respect to components of the independent variable with the bases assumed constant.

(i) Show that for $\phi = (\mathbf{v} \cdot \mathbf{v})^{3/2}$; $(\phi)\overset{\leftarrow}{\nabla}_{\mathbf{v}} = \frac{3}{2}(\mathbf{v} \cdot \mathbf{v})^{1/2}\mathbf{v}$

- $\phi = (v_j v_j)^{3/2}$
- $(\phi)\overset{\leftarrow}{\nabla}_{\mathbf{v}} = \frac{\partial \phi}{\partial v_i} \Rightarrow \frac{d\phi}{dv_i} = \frac{3}{2}(v_j v_j)^{1/2} \frac{d(v_k v_k)}{dv_i}$
- $\frac{d(v_k v_k)}{dv_i} = 2v_l \frac{\partial v_l}{\partial v_i} = 2v_l \delta_{il} = 2v_i$
- $(\phi)\overset{\leftarrow}{\nabla}_{\mathbf{v}} = \frac{3}{2}(v_j v_j)^{1/2} 2v_i = 3(v_j v_j)^{1/2} v_i = 3(\mathbf{v} \cdot \mathbf{v})^{1/2} \mathbf{v}$

(ii) Show that for $\phi = \text{tr}(\mathbf{T}) + \text{tr}(\mathbf{T}^2) + (\mathbf{T} \cdot \mathbf{T})^{1/2}$; $(\phi)\overset{\leftarrow}{\nabla}_{\mathbf{T}} = \mathbf{I} + 2\mathbf{T}^T + \frac{\mathbf{T}}{(\mathbf{T} \cdot \mathbf{T})^{1/2}}$

- $\phi = T_{pp} + T_{pq} T_{qp} + (T_{pq} T_{qp})^{1/2}$
-

$$\begin{aligned} (\phi)\overset{\leftarrow}{\nabla}_{\mathbf{T}} &= \frac{\partial \phi}{\partial T} \\ &= \frac{\partial T_{pp}}{\partial T_{ij}} + \left(T_{pq} \frac{\partial T_{qp}}{\partial T_{ij}} + T_{qp} \frac{\partial T_{pq}}{\partial T_{ij}} \right) + \frac{1}{2} (T_{pq} T_{qp})^{-1/2} \frac{\partial (T_{rs} T_{sr})}{\partial T_{ij}} \\ &= \delta_{pi} \delta_{pj} + 2T_{pq} \delta_{pi} \delta_{qj} + \frac{1}{2(T_{pq} T_{qp})^{1/2}} 2T_{rs} \delta_{ri} \delta_{sj} \\ &= \delta_{ij} + 2T_{ij} + \frac{T_{ij}}{(T_{pq} T_{qp})^{1/2}} \Rightarrow \mathbf{I} + 2\mathbf{T}^T + \frac{\mathbf{T}}{(\mathbf{T} \cdot \mathbf{T})^{1/2}} \end{aligned}$$

(iii) Show that for $\phi = \mathbf{v}(\mathbf{v} \cdot \mathbf{v})^{3/2}$; $(\phi)\overset{\leftarrow}{\nabla}_{\mathbf{v}} = \left[\mathbf{I}(\mathbf{v} \cdot \mathbf{v})^{3/2} + 3(\mathbf{v} \cdot \mathbf{v})^{1/2}(\mathbf{v} \otimes \mathbf{v}) \right]$

- Postulate: $(\phi)\overset{\leftarrow}{\nabla}_{\mathbf{v}} = \frac{\partial \phi}{\partial v_i} \otimes \mathbf{e}_i$
- $\phi = v_k \mathbf{e}_k (v_l v_l)^{3/2}$
-

$$\begin{aligned} \frac{\partial \phi}{\partial v_i} &= \frac{\partial v_k}{\partial v_i} \mathbf{e}_k (v_l v_l)^{3/2} + v_k \mathbf{e}_k \frac{\partial (v_l v_l)}{\partial v_i} \\ &= \delta_{ki} \mathbf{e}_k (v_l v_l)^{3/2} + v_k \mathbf{e}_k (3/2)(v_l v_l)^{1/2} \left(v_m \frac{\partial v_m}{\partial v_i} + \frac{\partial v_m}{\partial v_i} v_m \right) \\ &= \delta_{ki} \mathbf{e}_k (v_l v_l)^{3/2} + v_k \mathbf{e}_k (3/2)(v_l v_l)^{1/2} (2v_m \delta_{mi}) \\ &= (\mathbf{v} \cdot \mathbf{v})^{3/2} \mathbf{e}_i + 3(\mathbf{v} \cdot \mathbf{v})^{1/2} v_k \mathbf{e}_k v_i \end{aligned}$$

•

$$\begin{aligned}\frac{\partial \phi}{\partial v_i} \otimes \mathbf{e}_i &= (\mathbf{v} \cdot \mathbf{v})^{3/2} \mathbf{e}_i \otimes \mathbf{e}_i + 3(\mathbf{v} \cdot \mathbf{v})^{1/2} v_k \mathbf{e}_k v_i \otimes \mathbf{e}_i \\ &= (\mathbf{v} \cdot \mathbf{v})^{3/2} \mathbf{e}_i \otimes \mathbf{e}_i + 3(\mathbf{v} \cdot \mathbf{v})^{1/2} (\mathbf{v} \otimes \mathbf{v}) \\ &= \mathbf{I}(\mathbf{v} \cdot \mathbf{v})^{3/2} + 3(\mathbf{v} \cdot \mathbf{v})^{1/2} (\mathbf{v} \otimes \mathbf{v})\end{aligned}$$

2 if F and ϕ are scalars, use indicial notation to show:

- (i) $(F\mathbf{v}) \cdot \hat{\nabla} = \mathbf{v} \cdot (F\hat{\nabla}) + F(\mathbf{v} \cdot \hat{\nabla}) \Rightarrow \frac{\partial(Fv_i)}{\partial x_i} = \left(\frac{\partial F}{\partial x_i}\right)v_i + F\left(\frac{\partial v_i}{\partial x_i}\right) = F_{,i}v_i + Fv_{i,i}$
- (ii) $(F\hat{\nabla}) \times \hat{\nabla} = \mathcal{E}_{ijk} \frac{\partial(F/\partial x_k)}{\partial x_j} = \mathcal{E}_{ijk} \frac{\partial^2 F}{\partial x_j \partial x_k} = \mathcal{E}_{ijk} F_{,jk} = \mathbf{0}$
- (iii) $(\mathbf{v} \times \hat{\nabla}) \cdot \hat{\nabla} = \frac{\partial}{\partial x_i} \left(\mathcal{E}_{ijk} \frac{\partial v_k}{\partial x_j} \right) = \mathcal{E}_{ijk} \frac{\partial^2 v_k}{\partial x_i \partial x_j} = \mathcal{E}_{ijk} v_{k,ij}$
- (iv) $(\mathbf{v} \times \hat{\nabla}) \times \hat{\nabla} = \mathcal{E}_{mni} \mathcal{E}_{ijk} v_{k,jn} = (\delta_{mj} \delta_{nk} - \delta_{mk} \delta_{jn}) v_{k,jn} = \delta_{mj} \delta_{nk} v_{k,jn} - \delta_{mk} \delta_{jn} v_{k,jn} = v_{k,mk} - v_{m,nn}$
 $(\mathbf{v} \cdot \hat{\nabla}) \hat{\nabla} = v_{k,mk}$
 $\mathbf{v} \hat{\nabla}^2 = \text{Laplacian} = v_{m,nn}$
 $(\mathbf{v} \times \hat{\nabla}) \times \hat{\nabla} = (\mathbf{v} \cdot \hat{\nabla}) \hat{\nabla} - \mathbf{v} \hat{\nabla}^2$
- (v) $(\mathbf{u} \otimes \mathbf{v}) \cdot \hat{\nabla} = (\mathbf{u} \hat{\nabla}) \cdot \mathbf{v} + \mathbf{u}(\mathbf{v} \cdot \hat{\nabla})$
Product rule: $\frac{\partial(\mathbf{u}\mathbf{v})}{\partial x_i} = \frac{\partial(\mathbf{u})}{\partial x_i} \mathbf{v} + \frac{\partial(\mathbf{v})}{\partial x_i} \mathbf{u}$
 $\mathbf{u}\mathbf{v} \Rightarrow T_{ij}$ then $T_{ij,j} = u_{j,j}v_i + v_{j,j}u_i$
- (vi) $\text{curl}(\text{grad}\phi) \Rightarrow \mathcal{E}_{ijk} \phi_{,jk} = \mathbf{0}$

3 Determine the gradient, divergence, and curl of \mathbf{u}

- $\mathbf{u} = x_1 x_2 x_3 \mathbf{e}_1 + x_1 x_2 \mathbf{e}_2 + x_1 \mathbf{e}_3$
- Gradient: $\mathbf{u} \hat{\nabla} = u_{i,j} \mathbf{e}_i \otimes \mathbf{e}_j \Rightarrow \begin{bmatrix} \frac{\partial u_1}{\partial x_1} & \frac{\partial u_1}{\partial x_2} & \frac{\partial u_1}{\partial x_3} \\ \frac{\partial u_2}{\partial x_1} & \frac{\partial u_2}{\partial x_2} & \frac{\partial u_2}{\partial x_3} \\ \frac{\partial u_3}{\partial x_1} & \frac{\partial u_3}{\partial x_2} & \frac{\partial u_3}{\partial x_3} \end{bmatrix} = \begin{bmatrix} x_2 x_3 & x_2 & 1 \\ x_1 x_3 & x_1 & 0 \\ x_1 x_2 & 0 & 0 \end{bmatrix}$
- Divergence: $\mathbf{u} \cdot \hat{\nabla} = u_{i,i} = \frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} = x_2 x_3 + x_1 + 0$
- Curl: $\mathbf{u} \times \hat{\nabla} = u_{i,i} = \mathcal{E}_{ijk} u_{j,k} \mathbf{e}_i \Rightarrow \begin{bmatrix} \frac{\partial u_2}{\partial x_3} - \frac{\partial u_3}{\partial x_2} \\ \frac{\partial u_3}{\partial x_1} - \frac{\partial u_1}{\partial x_3} \\ \frac{\partial u_1}{\partial x_2} - \frac{\partial u_2}{\partial x_1} \end{bmatrix} = \begin{bmatrix} 0 - 0 \\ 1 - x_1 x_2 \\ x_1 x_2 - x_2 \end{bmatrix}$
- Verify that (iv) of Problem 2 is satisfied:

4 Express in terms of components and base vectors.

- (i) $\mathbf{T} \times \hat{\nabla} \Rightarrow \mathcal{E}_{jkl} T_{ij,k} \mathbf{e}_i \otimes \mathbf{e}_l \Rightarrow \begin{bmatrix} \left(\frac{\partial T_{12}}{\partial x_3} - \frac{\partial T_{13}}{\partial x_2} \right) \mathbf{e}_1 \otimes \mathbf{e}_1 & \left(\frac{\partial T_{13}}{\partial x_1} - \frac{\partial T_{11}}{\partial x_3} \right) \mathbf{e}_1 \otimes \mathbf{e}_2 & \left(\frac{\partial T_{11}}{\partial x_2} - \frac{\partial T_{12}}{\partial x_1} \right) \mathbf{e}_1 \otimes \mathbf{e}_3 \\ \left(\frac{\partial T_{22}}{\partial x_3} - \frac{\partial T_{23}}{\partial x_2} \right) \mathbf{e}_2 \otimes \mathbf{e}_1 & \left(\frac{\partial T_{23}}{\partial x_1} - \frac{\partial T_{21}}{\partial x_3} \right) \mathbf{e}_2 \otimes \mathbf{e}_2 & \left(\frac{\partial T_{21}}{\partial x_2} - \frac{\partial T_{22}}{\partial x_1} \right) \mathbf{e}_2 \otimes \mathbf{e}_3 \\ \left(\frac{\partial T_{32}}{\partial x_3} - \frac{\partial T_{33}}{\partial x_2} \right) \mathbf{e}_3 \otimes \mathbf{e}_1 & \left(\frac{\partial T_{33}}{\partial x_1} - \frac{\partial T_{31}}{\partial x_3} \right) \mathbf{e}_3 \otimes \mathbf{e}_2 & \left(\frac{\partial T_{31}}{\partial x_2} - \frac{\partial T_{32}}{\partial x_1} \right) \mathbf{e}_3 \otimes \mathbf{e}_3 \end{bmatrix}$
- (ii) $C_{13}(\mathbf{I} \times \mathbf{T})$???

5 Express in indicial form and longhand.

- $\mathbf{T} \cdot \hat{\nabla} + \mathbf{f} = \mathbf{0} \Rightarrow T_{ij,j} \mathbf{e}_i + f_i \mathbf{e}_i$
- $\mathbf{T} \cdot \hat{\nabla} + \mathbf{f} = \mathbf{0} \Rightarrow \begin{pmatrix} \frac{\partial T_{11}}{\partial x_1} + \frac{\partial T_{12}}{\partial x_2} + \frac{\partial T_{13}}{\partial x_3} \\ \frac{\partial T_{21}}{\partial x_1} + \frac{\partial T_{22}}{\partial x_2} + \frac{\partial T_{23}}{\partial x_3} \\ \frac{\partial T_{31}}{\partial x_1} + \frac{\partial T_{32}}{\partial x_2} + \frac{\partial T_{33}}{\partial x_3} \end{pmatrix} + \begin{pmatrix} f_1 \\ f_2 \\ f_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$