

Data Structures. General Observations

- The use of a proper data structures is critical to achieving good performance.
- Generate a symmetric sparse matrix A in matlab and time the operations of accessing (only) all entries by columns and then by rows. Observations?
- Many data structures; sometimes unnecessary variants.
- These variants are more useful in the context of iterative methods
- ➤ Basic linear algebra kernels (e.g., matrix-vector products) depend on data structures.

Some Common Data Structures (from SPARSKIT)

DNSDenseELLEllpack-ItpackBNDLinpack BandedDIADiagonalCOOCoordinateBSRBlock Sparse RowCSRCompressed Sparse RowSSKSymmetric SkylineCSCCompressed Sparse ColumnNSKNonsymmetric SkylineMSRModified CSRJADJagged Diagonal

Most common (and important): CSR (/ CSC), COO

The coordinate format (COO)

$$A = egin{pmatrix} 1. & 0. & 0. & 2. & 0. \ 3. & 4. & 0. & 5. & 0. \ 6. & 0. & 7. & 8. & 9. \ 0. & 0. & 10. & 11. & 0. \ 0. & 0. & 0. & 0. & 12. \end{pmatrix}$$

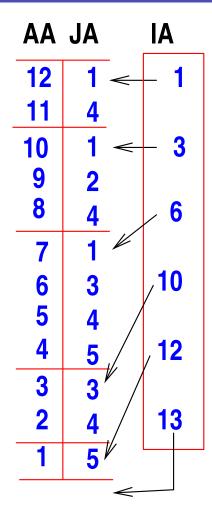
- Simplest data structure -
- Often used as 'entry' format in packages
- Variant used in matlab and matrix market
- Also known as 'triplet format'

AA	JR	JC
12.	5	5
9.	3	5
7.	3	3
5.	2	4
1.	1	1
2.	1	4
11.	4	4
3.	2	1
6.	3	1
4.	2	2
8.	3	4
10.	4	3

Compressed Sparse Row (CSR) format

$$A = egin{pmatrix} 12. & 0. & 0. & 11. & 0. \ 10. & 9. & 0. & 8. & 0. \ 7. & 0. & 6. & 5. & 4. \ 0. & 0. & 3. & 2. & 0. \ 0. & 0. & 0. & 0. & 1. \ \end{pmatrix}$$

- ➤ IA(j) points to beginning or row j in arrays AA, JA
- Related formats: Compressed Sparse Column format, Modified Sparse Row format (MSR).



➤ Used predominantly in Fortran & portable codes [e.g. Metis] — what about C?

CSR (CSC) format - C-style

* CSR: Collection of pointers of rows & array of row lengths

```
typedef struct SpaFmt {
 C-style CSR format - used internally
 for all matrices in CSR/CSC format
  int n; /* size of matrix
  int *nzcount; /* length of each row
  int **ja; /* to store column indices
 double **ma; /* to store nonzero entries
} SparMat;
aa[i][*] == entries of i-th row (col.);
ja[i][*] == col. (row) indices,
nzcount[i] == number of nonzero elmts in row (col.) i
```

Data structure used in Csparse [T. Davis' code, U. Florida]

```
typedef struct cs_sparse
{/* matrix in compressed-column or triplet form */
 int nzmax; /* maximum number of entries */
 int m ; /* number of rows */
 int n; /* number of columns */
 int *p; /* column pointers (size n+1) or
               col indices (size nzmax) */
 int *i;  /* row indices, size nzmax */
 double *x ; /* numerical values, size nzmax */
 int nz; /* # of entries in triplet matrix,
               -1 for compressed-col */
} cs ;
```

- ➤ Can be used for CSR, CSC, and COO (triplet) storage
- Easy to use from Fortran

The Diagonal (DIA) format

$$A = egin{pmatrix} 1. & 0. & 2. & 0. & 0. \ 3. & 4. & 0. & 5. & 0. \ 0. & 6. & 7. & 0. & 8. \ 0. & 0. & 9. & 10. & 0. \ 0. & 0. & 0. & 11. & 12. \end{pmatrix}$$

DA =
$$\begin{bmatrix} 1. & 2. \\ 3. & 4. & 5. \\ 6. & 7. & 8. \\ 9. & 10. & * \\ 11 & 12. & * \end{bmatrix}$$

$$IOFF = \begin{bmatrix} -1 & 0 & 2 \end{bmatrix}$$

The Ellpack-Itpack format

$$A = egin{pmatrix} 1. & 0. & 2. & 0. & 0. \ 3. & 4. & 0. & 5. & 0. \ 0. & 6. & 7. & 0. & 8. \ 0. & 0. & 9. & 10. & 0. \ 0. & 0. & 0. & 11. & 12. \end{pmatrix}$$

AC =
$$\begin{bmatrix} 1. & 2. & 0. \\ 3. & 4. & 5. \\ 6. & 7. & 8. \\ 9. & 10. & 0. \\ 11 & 12. & 0. \end{bmatrix}$$

Block matrices

$$A = egin{pmatrix} 1. & 2. & 0. & 0. & 3. & 4. \ 5. & 6. & 0. & 0. & 7. & 8. \ \hline 0. & 0. & 9. & 10. & 11. & 12. \ 0. & 0. & 13. & 14. & 15. & 16. \ \hline 17. & 18. & 0. & 0. & 20. & 21. \ 22. & 23. & 0. & 0. & 24. & 25. \ \end{pmatrix}$$

$$\mathsf{AA} = \begin{bmatrix} 1. & 3. & 9. & 11. & 17. & 20. \\ 5. & 7. & 15. & 13. & 22. & 24. \\ 2. & 4. & 10. & 12. & 18. & 21. \\ 6. & 8. & 14. & 16. & 23. & 25. \end{bmatrix}$$

$$\mathsf{AA} = \begin{bmatrix} 1. & 3. & 9. & 11. & 17. & 20. \\ \mathsf{JA} = \begin{bmatrix} 1 & 5 & 3 & 5 & 1 \\ 1 & 3 & 5 & 7 \end{bmatrix}$$

$$\mathsf{IA} = \begin{bmatrix} 1 & 3 & 5 & 7 \end{bmatrix}$$

Columns of AA hold 2×2 blocks. JA(k) = col. index of (1,1) entries of k-th block. FORTRAN: declare as AA(2,2,6)

Can also store the blocks row-wise in AA.

AA =
$$\begin{array}{r}
1. & 5. & 2. & 0. \\
3. & 7. & 4. & 8. \\
9. & 15. & 10. & 14. \\
11. & 13. & 12. & 16. \\
17. & 22. & 18. & 23. \\
20. & 24. & 21. & 25.
\end{array}$$

$$JA = \begin{bmatrix} 1 & 5 & 3 & 5 & 1 & 5 \\ 1 & 3 & 5 & 7 \end{bmatrix}$$
 $IA = \begin{bmatrix} 1 & 3 & 5 & 7 \end{bmatrix}$

- \blacktriangleright In other words AA is simply transposed
- What are the advantages and disadvantages of each scheme?
- ➤ Block formats are important in many applications..
- Also valuable: block structure with variable block size.

$\overline{Sparse\ matrices-data\ structure\ in\ C}$

➤ Recall:

- Can store rows of a matrix (CSR)
- or its columns (CSC)
- \blacktriangleright How to perform the operation y=A*x in each case?

$Matvec-row\ version$

```
void matvec( csptr mata, double *x, double *y )
{
   int i, k, *ki;
   double *kr;
   for (i=0; i<mata->n; i++) {
      y[i] = 0.0;
      kr = mata->ma[i];
      ki = mata->ja[i];
      for (k=0; k<mata->nzcount[i]; k++)
           y[i] += kr[k] * x[ki[k]];
   }
}
```

- Uses sparse dot products (sparse SDOTS)
- Operation count

$Matvec\ -\ Column\ version$

```
void matvecC( csptr mata, double *x, double *y )
{
  int n = mata->n, i, k, *ki;
  double *kr;
  for (i=0; i<n; i++)
    y[i] = 0.0;
  for (i=0; i<n; i++) {
    kr = mata->ma[i];
    ki = mata->ja[i];
    for (k=0; k<mata->nzcount[i]; k++)
        y[ki[k]] += kr[k] * x[i];
}
```

- Uses sparse vector combinations (sparse SAXPY)
- Operation count

$Matvec-row\ version$ - FORTRAN

```
subroutine amux (n, x, y, a, ja, ia)
      real*8 x(*), y(*), a(*), t
      integer n, ja(*), ia(*), i, k
c---- row loop
     do 100 i = 1, n
      inner product of row i with vector x
         t = 0.0d0
         do 99 k=ia(i), ia(i+1)-1
            t = t + a(k)*x(ja(k))
  99
         continue
         y(i) = t
      continue
 100
      return
      end
```

Matvec - column version - FORTRAN

```
subroutine atmux (n, x, y, a, ja, ia)
      real *8 x(*), y(*), a(*)
      integer n, ia(*), ja(*)
      integer i, k
 ---- set y to zero
      do 1 i=1,n
         y(i) = 0.0
   continue
c---- column loop
    do 100 i = \bar{1}, n
 ---- sparse saxpy
         do 99 k=ia(i), ia(i+1)-1
            y(ja(k)) = y(ja(k)) + x(i)*a(k)
 99
         continue
100 continue
      return
      end
```

$Sparse\ matrices\ in\ matlab$

- ru| Generate a tridiagonal matrix $m{T}$
- lacktriangle Convert $oldsymbol{T}$ to sparse format
- See how you can generate this sparse matrix directly using sparse
- See how you can use spconvert to achieve the same result
- What can you observe about the way the triplets of a sparse matrix are ordered?
- Important for performance: spalloc. See the difference between

$$A = sparse(m,n)$$
 and $A = spalloc(m,n,nzmax)$