

Brandon Pollack

Lab 5 report

All ASM files including the includes

EBI_INIT.asm

```
/* A collection of inits for the EBI and stack init at the bottom */
.set IOPORT = 0x5000
.set SRAMPORT = 0x370000

.macro TRIPORT_ALE_ONE_INIT

    ldi R16, 0b00110111
    sts PORTH_DIR, R16 //set port pins as outputs for RE and ALE and WE CS1 and CS0

    ldi R16, 0b00110011
    sts PORTH_OUTSET, R16 //WE and RE and CS pins are active low so it must be set

    ldi R16, 0xFF
    sts PORTJ_DIR, R16 //set datalines as outputs (manual says so)
    sts PORTK_DIR, R16 //set address lines as outputs

    ldi R16, 0x01
    sts EBI_CTRL, R16 //turn on 3 port SRAM ALE1 EBI
.endmacro

.macro CS0_INIT

    ldi ZH, HIGH(EBI_CS0_BASEADDR) //all the set up for CS0, since EBI won't work without
it
    ldi ZL, LOW(EBI_CS0_BASEADDR)

    ldi R16, ((IOPORT>>8) & 0xF0)
    st Z+, R16

    ldi R16, ((IOPORT>>16) & 0xFF)
    st Z, R16

    ldi R16, 0x11
    sts EBI_CS0_CTRLA, R16
.endmacro

.macro CS1_INIT
.equ SRAMPORT = 370000
```

```

ldi ZH, HIGH(EBI_CS1_BASEADDR) //set up CS1 for the SRAM
ldi ZL, LOW(EBI_CS1_BASEADDR)

ldi R16, ((SRAMPOR>>8) & 0xF0)
st Z+, R16

ldi R16, ((SRAMPOR>>16) & 0xFF)
st Z, R16

ldi R16, 0b00011101
sts EBI_CS1_CTRLA, R16
.endmacro

```

```

.macro STACK_INIT
ldi R16, 0xFF
out CPU_SPL, R16
ldi R16, 0x3F
out CPU_SPH, R16 //init stack pointer
.endmacro

```

UART_INITS

```

/* Brandon Pollack
* HW4
* SCI Subroutines
*/

```

```

.macro SCI_C_INIT

.equ BSEL = 51
.equ BSCL = -2

ldi R16, 0x18
sts USARTC0_CTRLB, R16 ;this butts a one in RXEN and TXEN, enabling
transmission and receive

ldi R16, 0x03
sts USARTC0_CTRLA, R16 ;No parity, 8 bit data, a single stop bit

ldi R16, BSEL
sts USARTC0_BAUDCTRLA, R16 ;setting baud to 9600 HZ involves some calculation from
the manual

```

```

        ldi R16, ((BSCL << 4) & 0xF0) | ((BSEL >> 8) & 0x0F)

        sts USARTC0_BAUDCTRLB, R16      ;set the scale to -2 as per the formula to get 9600 HZ
from the Fper and BSCL, upper 4 bits of BSEL stay the same

        ; now begins the set up of the PORTC to output and input serial

        ldi R16, 0x08
        sts PORTC_DIR, R16
        sts PORTC_OUT, R16 ; set the direction of the TX line as out and default as 1 as per
docs
.endmacro
/*SPI_C_INIT:
    .macro
    .equ BSEL = 51
    .equ BSCL = -2

        ldi R16, 0x18
        sts USARTC0_CTRLB, R16          ;this butts a one in RXEN and TXEN, enabling
transmission and receive

        ldi R16, 0b01000011
        sts USARTC0_CTRLA, R16          ;No parity, 8 bit data, a single stop bit, synchronous
transmission

        ldi R16, BSEL
        sts USARTC0_BAUDCTRLA, R16      ;setting baud to 9600 HZ involves some calculation from
the manual

        ldi R16, ((BSCL << 4) & 0xF0) | ((BSEL >> 8) & 0x0F)

        sts USARTC0_BAUDCTRLB, R16      ;set the scale to -2 as per the formula to get 9600 HZ
from the Fper and BSCL, upper 4 bits of BSEL stay the same

        ; now begins the set up of the PORTC to output and input serial

        ldi R16, 0x08
        sts PORTC_DIR, R16
        sts PORTC_OUT, R16 ; set the direction of the TX line as out and default as 1 as per
docs
    .endmacro
*/

OUT_CHAR:
    .org 0x200
    push R17 ;save this value

    isdatasent:

```

```

        lds R17, USARTCO_STATUS
        sbrs R17, 6 ;poll TXIF in status register, if it is clear we are not done
        rjmp isdatasent

    sts USARTCO_DATA, R16

    pop R17

    ret

OUT_STRING:
    push R16 ;I chose to use z so this sub works for program or data memory (remember to
    shift left if program memory)

    beginwritingstring:
        ld R16, Z+ ;at the end of this sub, z will point to one address past the end
    of the string
        breq donewritingstring
        call OUT_CHAR
        rjmp beginwritingstring

    donewritingstring:
        pop R16
        ret

IN_CHAR:
    push R17

    isdatarecieved:
        lds R17, USARTCO_STATUS
        sbrs R17, 7
        rjmp isdatarecieved

    lds R16, USARTCO_DATA

    pop R17
    ret

IN_STRING: ;be sure to have X point where you want this data to go
    push R16

    beginreadingstring:
        call IN_CHAR ;puts the character in R16
        cpi R16, 0
        breq donereadingstring
        st X+, R16
        rjmp beginreadingstring

    donereadingstring:

```

```
pop R16
ret
```

Lab5_part1_BRP

```
/*
 * Brandon Pollack
 * Ivan
 * 1524
 * A program that uses an input on a port as an interrupt
 */
#include "Atxmega128A1udef.inc"
#include "EBI_INITS.asm"
.org 0
    rjmp main

.org PORTC_INT0_VECT
    rjmp EXT_INT_countup

main:
.org 0x100
    ldi R16, 0x01
    sts PORTC_INTCTRL, R16 ;set this port as a low level interrupt

    ldi R16, 0x04
    sts PORTC_INTOMASK, R16 ;set pin 2 as the interrupt, since it is the only one with
full asynch support
    sts PORTC_DIRCLR, R16 ;make certain that pin is an input

    ldi R16, 0x02
    sts PORTC_PIN2CTRL, R16 ;set pin 2 to trigger an interrupt on only a falling edge

    ldi R16, 0x01
    sts PMIC_CTRL, R16 ;turn on low level interrupts

    sei ;turn on interrupts

    TRIPORT_ALE_ONE_INIT ;turn on EBI so I can write to my LEDs
    CS0_INIT ;not really needed but I think my CPLD uses it now so lets turn it on
    ldi R16, 0x0 ;set the init value of our count to 0
    sts IOPORT, R16

loopforever:
    rjmp loopforever

EXT_INT_countup:
```


Lab5_part2_1

```
/*
*Brandon Pollack
*Ivan
*1352
*UART Port C program to interface with a terminal
*/

.include "Atxmega128A1udef.inc"
.include "EBI_INITS.asm"

.equ CR = 0x0D
.equ LF = 0x0A
.equ stringlocation = 0x1000

.org stringlocation
.DB "My name is Brandon Pollack, my favourite movie is Pulp Fiction, my favourite
class is EEL4744, my favourite TV show is Star Trek." CR, LF, "Instructor: Dr. Eric M.
Schwartz, TA: IVAN", CR, LF, 0x00

.org 0x0
    rjmp main

main:
.org 0x100

    STACK_INIT

.equ BSEL = 144
.equ BSCL = -6

    ldi R16, 0x18
    sts USARTC0_CTRLB, R16      ;this butts a one in RXEN and TXEN, enabling
transmission and receive

    ldi R16, 0x03
    sts USARTC0_CTRLA, R16      ;No parity, 8 bit data, a single stop bit

    ldi R16, BSEL
    sts USARTC0_BAUDCTRLA, R16  ;setting baud to 9600 HZ involves some calculation from
the manual

    ldi R16, ((BSCL << 4) & 0xF0) | ((BSEL >> 8) & 0x0F)

    sts USARTC0_BAUDCTRLB, R16  ;set the scale to -2 as per the formula to get 9600 HZ
from the Fper and BSCL, upper 4 bits of BSEL stay the same
```

```

; now begins the set up of the PORTC to output and input serial

ldi R16, 0x08
sts PORTC_DIR, R16
sts PORTC_OUT, R16 ; set the direction of the TX line as out and default as 1 as per
docs

```

```

ldi ZL, low(stringlocation << 1)
ldi ZH, high(stringlocation << 1) ;string location shifted by one

```

```

call OUT_STRING

```

```

done: rjmp done

```

```

OUT_CHAR:

```

```

.org 0x200
push R17 ;save this value

isdatasent:
lds R17, USARTC_STATUS
sbrs R17, 5 ;poll TXIF in status register, if it is clear we are not done
rjmp isdatasent

```

```

sts USARTC_DATA, R16

```

```

pop R17

```

```

ret

```

```

OUT_STRING:

```

```

push R16 ;I chose to use z so this sub works for program or data memory (remember to
shift left if program memory)

```

```

beginwritingstring:
lpm R16, Z+ ;at the end of this sub, z will point to one address past the end
of the string

```

```

cpi R16, 0x0
breq donewritingstring
call OUT_CHAR
rjmp beginwritingstring

```

```

donewritingstring:

```

```

pop R16
ret

```


Lab5_part2_2

```
/*
 * Brandon Pollack
 * Ivan
 * 1524
 * A program that uses interrupts to manage UART
 */
#include "Atmega128A1udef.inc"
#include "EBI_INITS.asm"

.org 0x0
rjmp main

.org USARTCO_RXC_vect
rjmp RX_ISR

.org 0x100
main:
    .equ BSEL = 144
    .equ BSCL = -6

    ldi R16, 0x18
    sts USARTCO_CTRLB, R16      ;this butts a one in RXEN and TXEN, enabling
transmission and receive

    ldi R16, 0x03
    sts USARTCO_CTRLC, R16      ;No parity, 8 bit data, a single stop bit

    ldi R16, BSEL
    sts USARTCO_BAUDCTRLA, R16  ;setting baud to involves some calculation from the
manual

    ldi R16, ((BSCL << 4) & 0xF0) | ((BSEL >> 8) & 0x0F)

    sts USARTCO_BAUDCTRLB, R16  ;set the scale and last 4 bits of BSEL

    ; now begins the set up of the PORTC to output and input serial

    ldi R16, 0x08
    sts PORTC_DIR, R16
    sts PORTC_OUT, R16 ; set the direction of the TX line as out and default as 1 as per
docs

    //done with UART setup (except Interrupt drives, whcih I will do after I initilize
    PMIC)

    ldi R16, 0x01
    sts PMIC_CTRL, R16 //globally enable low level interrupts
```

```
ldi R16, (0x01 << 4)
sts USARTC0_CTRLA, R16 //set RXINTLVL to a low level interrupt

sei //globally enable all interrupts
```

```
TRIPORT_ALE_ONE_INIT
CSO_INIT
STACK_INIT
ldi XL, low(IOPORT)
ldi XH, high(IOPORT)
ldi R16, 0xFF
st X, R16
```

```
loopforever:
    ldi R16, 0xFF
    st X, R16
    call DELAY500
    ldi R16, 0x00
    st X, R16
    call DELAY500
    rjmp loopforever
```

```
RX_ISR:
    push R17
    push R16
    lds R16, USARTC0_DATA
    isdatasent:
        lds R17, USARTC0_STATUS
        sbrs R17, 5 ;poll DATA in status register, if it is clear we are not done
        rjmp isdatasent

    sts USARTC0_DATA, R16
    pop R16
    pop R17
    reti
```

```
DELAY500:
    push R16
    push R17
```

```
ldi R16, 0
ldi R17, 0
```

```
AGAIN:
NOP
NOP
NOP
NOP
```

```
NOP
NOP
NOP
NOP
NOP
NOP
NOP
NOP
NOP
NOP
NOP
NOP
INC R16
CPI R16, 0
BREQ CARRY
```

```
BACK:
CPI R17, 0xFF
BRNE AGAIN
BREQ RETURN
```

```
CARRY:
INC R17
rjmp BACK
```

```
RETURN:
    pop R17
    pop R16
    RET
```

Lab5_part2_3

```
/*
 * Lab5_part2_3.asm
 *
 * Created: 3/3/2013 3:41:22 PM
 * Author: Brandon
 *Brandon Pollack
 *Ivan
 *1352
 *UART Port C program to interface with a terminal, now taking input
 */

#include "Atxmega128A1udef.inc"
#include "EBI_INITS.asm"

.equ CR = 0x0D
.equ LF = 0x0A
.equ menulocation = 0x1000
.equ TAB = 0x09
.equ CC = 0x12

.org menulocation
    .db "Brandon's Favourite:", CR, LF, "0:", TAB, "Sport", CR, LF, "1:", TAB, "TV
Show", CR, LF, "2:", TAB, "Book", CR, LF, "3:", TAB, "Food", CR, LF, "4:", TAB, "Movie", CR, LF, "5:", TAB, "Disp
lay menu", CR, LF, "ESC: exit", CR, LF, 0x00

fsport:
    .db "Baseball", CR, LF, 0
fTV:
    .db "Star Trek", CR, LF, 0
fBook:
    .db "Ender's Game", CR, LF, 0
fFood:
    .db "Tonkotsu Ramen", CR, LF, 0
fMovie:
    .db "Pulp Fiction", CR, LF, 0
exitprint:
    .db "Done!", 0

.org 0x0
    rjmp main

main:
.org 0x100

    STACK_INIT
```

```

.equ BSEL = 144
.equ BSCL = -6

ldi R16, 0x18
sts USARTC0_CTRLB, R16      ;this butts a one in RXEN and TXEN, enabling
transmission and receive

ldi R16, 0x03
sts USARTC0_CTRLA, R16      ;No parity, 8 bit data, a single stop bit

ldi R16, BSEL
sts USARTC0_BAUDCTRLA, R16  ;setting baud to 9600 HZ involves some calculation from
the manual

ldi R16, ((BSCL << 4) & 0xF0) | ((BSEL >> 8) & 0x0F)

sts USARTC0_BAUDCTRLB, R16  ;set the scale to -2 as per the formula to get 9600 HZ
from the Fper and BSCL, upper 4 bits of BSEL stay the same

; now begins the set up of the PORTC to output and input serial

ldi R16, 0x08
sts PORTC_DIR, R16
sts PORTC_OUT, R16 ; set the direction of the TX line as out and default as 1 as per
docs

loop:
ldi ZL, low(menulocation << 1)
ldi ZH, high(menulocation << 1) ;string location shifted by one
call OUT_STRING
recieve newchar:
call IN_CHAR

cpi R16, 0x1B
breq exitroutine
cpi R16, '0'
breq sport
cpi R16, '1'
breq TVshow
cpi R16, '2'
breq book
cpi R16, '3'
breq food
cpi R16, '4'
breq movie

```

```
    cpi R16, '5'
    breq loop
    rjmp recievenewchar
```

exitroutine:

```
    ldi ZL, low(exitprint << 1)
    ldi ZH, high(exitprint << 1)
    call OUT_STRING
```

done:

```
    rjmp done
```

sport:

```
    ldi R16, CC
    call OUT_CHAR
    ldi ZL, low(fsport << 1)
    ldi ZH, high(fsport << 1)
    call OUT_STRING
    rjmp loop
```

TVshow:

```
    ldi R16, CC
    call OUT_CHAR
    ldi ZL, low(fTV << 1)
    ldi ZH, high(fTV << 1)
    call OUT_STRING
    rjmp loop
```

book:

```
    ldi R16, CC
    call OUT_CHAR
    ldi ZL, low(fbook << 1)
    ldi ZH, high(fbook << 1)
    call OUT_STRING
    rjmp loop
```

food:

```
    ldi R16, CC
    call OUT_CHAR
    ldi ZL, low(fFood << 1)
    ldi ZH, high(fFood << 1)
    call OUT_STRING
    rjmp loop
```

movie:

```
    ldi R16, CC
    call OUT_CHAR
    ldi ZL, low(fmovie << 1)
    ldi ZH, high(fmovie << 1)
    call OUT_STRING
    rjmp loop
```

IN_CHAR:

```
    push R17
```

```

isdatarecieved:
    lds R17, USARTC0_STATUS
    sbrs R17, 7
    rjmp isdatarecieved

    lds R16, USARTC0_DATA

    pop R17
    ret

OUT_CHAR:
    push R17 ;save this value

    isdatasent:
        lds R17, USARTC0_STATUS
        sbrs R17, 5 ;poll TXIF in status register, if it is clear we are not done
        rjmp isdatasent

    sts USARTC0_DATA, R16

    pop R17

    ret

OUT_STRING:
    push R16 ;I chose to use z so this sub works for program or data memory (remember to
shift left if program memory)

    beginwritestring:
        lpm R16, Z+ ;at the end of this sub, z will point to one address past the end
of the string
        cpi R16, 0x0
        breq donewritingstring
        call OUT_CHAR
        rjmp beginwritestring

    donewritingstring:
        pop R16
        ret

```

Lab5_part3

```
/*
 * Brandon Pollack
 * Ivan
 * 1524
 * A program that uses interrupts to manage UART
 */
#include "Atmega128A1defs.inc"
#include "EBI_INITS.asm"

.org 0x0
rjmp main

.org USART0_RXC_vect
rjmp RX_ISR

.org 0x100
main:
    .equ BSEL = 144
    .equ BSCL = -6

    ldi R16, 0x18
    sts USART0_CTRLB, R16      ;this puts a one in RXEN and TXEN, enabling
transmission and receive

    ldi R16, 0x03
    sts USART0_CTRLA, R16      ;No parity, 8 bit data, a single stop bit

    ldi R16, BSEL
    sts USART0_BAUDCTRLA, R16  ;setting baud to involves some calculation from the
manual

    ldi R16, ((BSCL << 4) & 0xF0) | ((BSEL >> 8) & 0x0F)

    sts USART0_BAUDCTRLB, R16  ;set the scale and last 4 bits of BSEL

    ; now begins the set up of the PORTC to output and input serial

    ldi R16, 0x08
    sts PORTC_DIR, R16
    sts PORTC_OUT, R16 ; set the direction of the TX line as out and default as 1 as per
docs

    //done with UART setup (except Interrupt drives, which I will do after I initialize
    PMIC)

    ldi R16, 0x01
    sts PMIC_CTRL, R16 //globally enable low level interrupts
```



```

ldi R16, (0x01 << 4)
sts USARTC0_CTRLA, R16 //set RXINTLVL to a low level interrupt

sei //globally enable all interrupts

```

```

TRIPORT_ALE_ONE_INIT
CSO_INIT
STACK_INIT
ldi XL, low(IOPORT)
ldi XH, high(IOPORT)
ldi R16, 0xFF
st X, R16

```

```

loopforever:
    ldi R16, 0xFF
    st X, R16
    call DELAY500
    ldi R16, 0x00
    st X, R16
    call DELAY500
    rjmp loopforever

```

```

RX_ISR:
    push R17
    push R16
    lds R16, USARTC0_DATA
    isdatasent:
        lds R17, USARTC0_STATUS
        sbrc R17, 5 ;poll DATA in status register, if it is clear we are not done
        rjmp isdatasent

    sts USARTC0_DATA, R16
    pop R16
    pop R17
    reti

```

```

DELAY500:
    push R16
    push R17

```

```

ldi R16, 0
ldi R17, 0

```

```

AGAIN:
NOP
NOP
NOP
NOP

```

```
NOP
NOP
NOP
NOP
NOP
NOP
NOP
NOP
NOP
NOP
NOP
NOP
INC R16
CPI R16, 0
BREQ CARRY
```

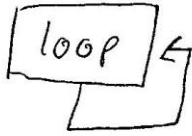
```
BACK:
CPI R17, 0xFF
BRNE AGAIN
BREQ RETURN
```

```
CARRY:
INC R17
rjmp BACK
```

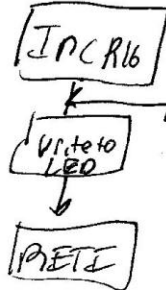
```
RETURN:
    pop R17
    pop R16
    RET
```

Part 1

MAIN

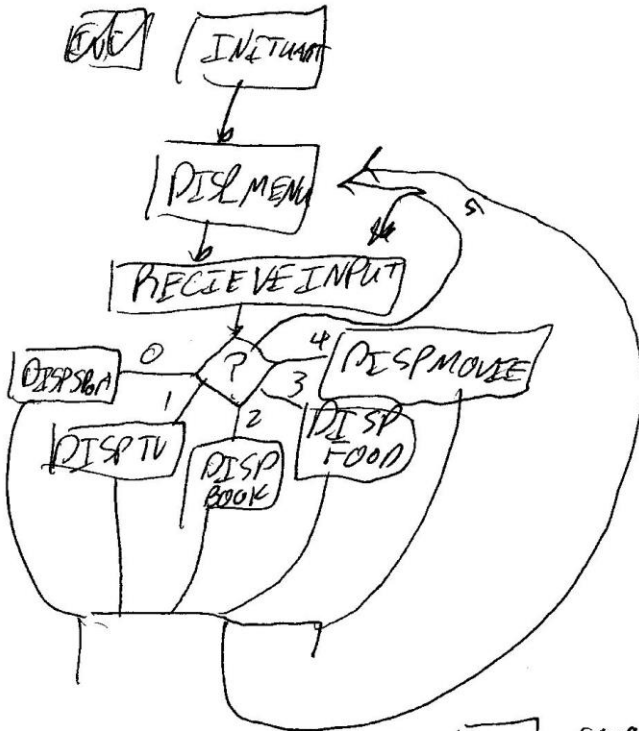


ISR



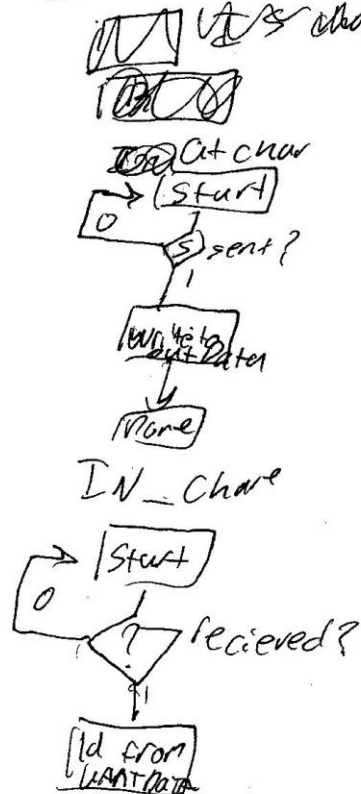
// this is to compensate for bounce

Part 2-2

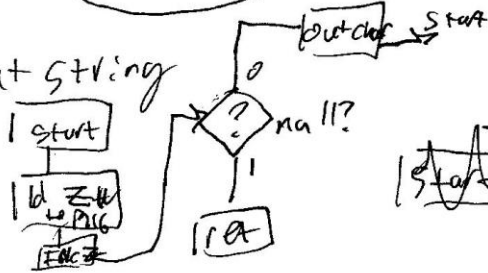


PART 2-1

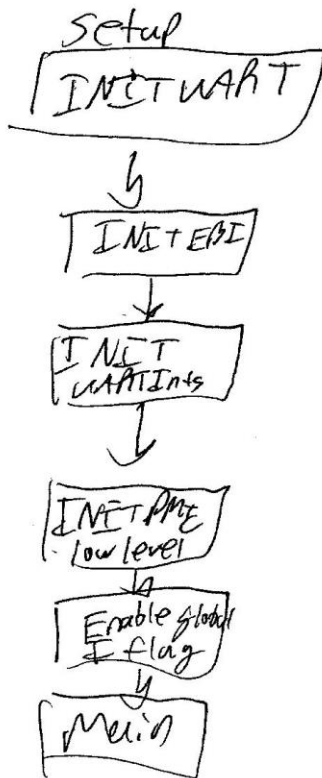
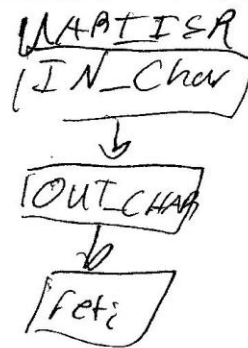
IN-char

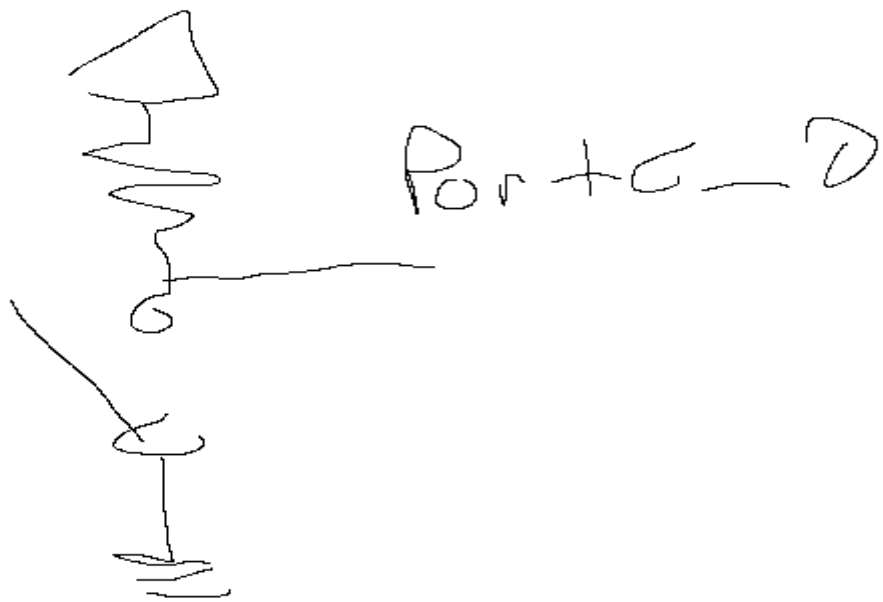


Out string



start string





Interrupt port