## **Project Timeline**

## Project Delieverables

ACTIVITY	PLAN START	PLAN DURATION	PLAN END	3-Sep 10-Sep 17-Sep 17-Sep 17-Sep 1-Oct 8-Oct 15-Oct 15-Oct 15-Oct 17-Dec 17-De
Project Proposal (Draft)	10-Ѕер	8	18-Sep	
Progress Report	23-Nov	15	8-Dec	
Oral Presentation	4-Jan	14	18-Jan	
Final Report (Draft)	22-Feb	21	14-Mar	
Poster Fair	4-Mar	14	18-Mar	
Final Report	19-Mar	20	8-Apr	
3D Print Hand/Arm	3-Sep	22	25-Sep	
Hand Assembly	11-Ѕер	14	25-Sep	
Forearm Assembly	25-Sep	7	2-Oct	
Test Hand/Forearm Range of Motion	2-Oct	7	9-Oct	
[Milestone 1 - Hardware Complete]		9-0	ct	
Hand Control using Microcontroller	24-Sep	22	16-Oct	
Interface Leap Motion with Microcontroller	1-Oct	43	13-Nov	
Test Wired control from Leap Motion to Hand	13-Nov	14	27-Nov	
[Milestone 2 - Interface Established]		27-N	ov	
Remote Control Over Internet	4-Jan	31	4-Feb	
Test Latency of Remote Control over IP	26-Jan	17	12-Feb	
Fingertip Sensors for Closed Loop System	4-Jan	31	4-Feb	
Test Arm Movement and Closed Loop System				
(Pick up Egg test)	4-Feb	8	12-Feb	
[Milestone 3 - Remote Control]		12-F	eb	
Record Motion Feature	1-Feb	17	18-Feb	
Test Entire Integrated System	13-Feb	16	29-Feb	
[Milestone 4 - Verify Entire System]		29-F	eb	