

CSCI 405: Algorithm Analysis II
Homework 6: Polygon Decomposition

Code

```
#include <errno.h>
#include <math.h>
#include <stdarg.h>
#include <stdio.h>
#include <string.h>
#include <stdexcept>
#include <vector>

using std::vector;
using std::logic_error;
void LogicError(const char* format, ...) {
    char buffer[4096];
    va_list args;
    va_start(args, format);
    vsprintf(buffer, format, args);
    va_end(args);
    throw logic_error(buffer);
}

class Vertex {
private:
    double x_;
    double y_;
    size_t index_;

public:
    Vertex(const double x, const double y, const size_t index)
        : x_(x), y_(y), index_(index) { }
    double x() const {
```

```

        return x_;
    }
    double y() const {
        return y_;
    }
    size_t index() const {
        return index_;
    }
    static double distance(const Vertex& a, const Vertex& b) {
        double dx = a.x_ - b.x_;
        double dy = a.y_ - b.y_;
        return sqrt(dx * dx + dy * dy);
    }
} ;

```

```

class Chord {
private:
    const Vertex* one_;
    const Vertex* two_;
    double dist_;

public:
    Chord() : one_(NULL), two_(NULL), dist_(INFINITY) { }
    Chord(const Vertex& one, const Vertex& two)
        : one_((one.index() < two.index()) ? (&one) : (&two)),
          two_((one.index() < two.index()) ? (&two) : (&one)),
          dist_(Vertex::distance(one, two)) { }
    double dist() const {
        return dist_;
    }
    const Vertex* one() const {
        return one_;
    }
    const Vertex* two() const {
        return two_;
    }
}

```

```

}

void print() const {
    printf("%3lu:(%12.4f,%12.4f) => %3lu:(%12.4f,%12.4f) dist: %12.4f\n",
        one_>index(), one_>x(), one_>y(),
        two_>index(), two_>x(), two_>y(),
        dist_);
}

bool operator ==(const Chord& other) const {
    return (one_>index() == other.one_>index() &&
        two_>index() == other.two_>index());
}
} ;

class Polygon {
private:
    const char*    path_;
    vector<Vertex> points_;
    vector<Chord>  chords_;
    double**       value_matrix_;
    double**       dists_matrix_;
    vector<Chord>** chord_matrix_;
    void read() {
        FILE* file;
        if ((file = fopen(path_, "r")) == NULL)
            LogicError("fopen('%s', 'r') error: %s", path_, strerror(errno));
        double x, y;
        while (fscanf(file, "%lf%lf", &x, &y) == 2)
            points_.push_back(Vertex(x, y, points_.size()));
        fclose(file);
    }
    void add_chord(const Chord& c, vector<Chord> * const out) {
        // Don't add if edge.
        if ((c.one_>index() + 1) % points_.size() == c.two_>index() ||
            (c.two_>index() + 1) % points_.size() == c.one_>index())
            return;
    }
};

```

```

    // Don't add if chord exists in chords_
    for (auto i = out->begin(); i != out->end(); ++i)
        if (c == *i) return;
    out->push_back(c);
}

static void copy_to(vector<Chord> * const src, vector<Chord> * const dst) {
    for (auto i = src->begin(); i != src->end(); ++i)
        dst->push_back(*i);
}

double triangle_perim(size_t i, size_t j, size_t k) {
    return dists_matrix_[i][j] + dists_matrix_[j][k] +
        dists_matrix_[k][i];
}

double decompose(const size_t i, const size_t j, vector<Chord>* const out) {
    if (value_matrix_[i][j] >= 0) {
        copy_to(&chord_matrix_[i][j], out);
        return value_matrix_[i][j];
    } else if (j == i + 1) {
        return value_matrix_[i][j] = 0;
    } else {
        double min = INFINITY;
        size_t best_k;
        vector<Chord> best_out;
        for (size_t k = i + 1; k < j; ++k) {
            vector<Chord> new_out;
            double v = decompose(i, k, &new_out)
                + decompose(k, j, &new_out)
                + triangle_perim(i, j, k);
            if (v < min) {
                min = v;
                best_k = k;
                best_out = new_out;
            }
        }
        add_chord(Chord(points_[i], points_[j]), &best_out);
    }
}

```

```

        add_chord(Chord(points_[j],      points_[best_k]), &best_out);
        add_chord(Chord(points_[best_k], points_[i]),      &best_out);
        copy_to(&best_out, out);
        chord_matrix_[i][j] = best_out;
        return value_matrix_[i][j] = min;
    }
}

public:
    explicit Polygon(const char* path) : path_(path) {
        read();
        value_matrix_ = new double*[points_.size()];
        dists_matrix_ = new double*[points_.size()];
        chord_matrix_ = new vector<Chord>*[points_.size()];
        for (size_t i = 0; i < points_.size(); ++i) {
            value_matrix_[i] = new double[points_.size()];
            dists_matrix_[i] = new double[points_.size()];
            chord_matrix_[i] = new vector<Chord>[points_.size()];
            for (size_t j = 0; j < points_.size(); ++j) {
                value_matrix_[i][j] = -1;
                dists_matrix_[i][j] = Vertex::distance(points_[i], points_[j]);
            }
        }
    }

    double decompose() {
        return decompose(0, points_.size() - 1, &chords_);
    }

    void print_chords() {
        for (auto i = chords_.begin(); i != chords_.end(); ++i)
            i->print();
    }
};

int main() {
    Polygon p("polygon2.txt");
    printf("size: %f\n", p.decompose());
}

```

```

    p.print_chords();
}

```

Results

size: 8328.604014

| | | |
|----------------------------|--------------------------------|----------|
| 0:(397.2494, 204.0564) => | 2:(375.8121, 295.3134) dist: | 93.7411 |
| 3:(340.3170, 338.5171) => | 5:(260.6411, 384.6494) dist: | 92.0676 |
| 2:(375.8121, 295.3134) => | 5:(260.6411, 384.6494) dist: | 145.7576 |
| 5:(260.6411, 384.6494) => | 7:(163.0483, 394.1319) dist: | 98.0524 |
| 7:(163.0483, 394.1319) => | 9:(76.2607, 352.6056) dist: | 96.2108 |
| 5:(260.6411, 384.6494) => | 9:(76.2607, 352.6056) dist: | 187.1442 |
| 9:(76.2607, 352.6056) => | 11:(8.0842, 273.5640) dist: | 104.3820 |
| 11:(8.0842, 273.5640) => | 13:(8.6748, 173.7644) dist: | 99.8013 |
| 9:(76.2607, 352.6056) => | 13:(8.6748, 173.7644) dist: | 191.1858 |
| 5:(260.6411, 384.6494) => | 13:(8.6748, 173.7644) dist: | 328.5719 |
| 13:(8.6748, 173.7644) => | 15:(34.3564, 87.0327) dist: | 90.4540 |
| 13:(8.6748, 173.7644) => | 16:(72.7005, 46.8978) dist: | 142.1071 |
| 17:(117.8008, 12.5129) => | 19:(210.7204, 2.7835) dist: | 93.4276 |
| 16:(72.7005, 46.8978) => | 19:(210.7204, 2.7835) dist: | 144.8985 |
| 13:(8.6748, 173.7644) => | 19:(210.7204, 2.7835) dist: | 264.6826 |
| 19:(210.7204, 2.7835) => | 21:(309.2761, 27.5857) dist: | 101.6286 |
| 21:(309.2761, 27.5857) => | 23:(377.3673, 108.9847) dist: | 106.1236 |
| 19:(210.7204, 2.7835) => | 23:(377.3673, 108.9847) dist: | 197.6104 |
| 13:(8.6748, 173.7644) => | 23:(377.3673, 108.9847) dist: | 374.3402 |
| 5:(260.6411, 384.6494) => | 23:(377.3673, 108.9847) dist: | 299.3594 |
| 2:(375.8121, 295.3134) => | 23:(377.3673, 108.9847) dist: | 186.3352 |
| 0:(397.2494, 204.0564) => | 23:(377.3673, 108.9847) dist: | 97.1284 |

Justification of approx. $\Theta(n^3)$ running time

The algorithm builds a tableau of the best polygon decompositions for as it runs, which takes linear time to fill each of the entries. Since there are n^2 entries, it should take $\Theta(n^3)$ running time.