

Quantum Workforce Development

Brian Rashap

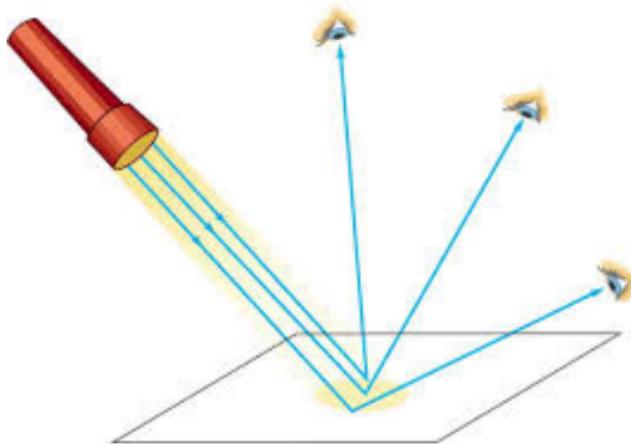
July 2023

Geometric Optics



Ray Nature of Light

The word "ray" means a straight line that originates at some point.

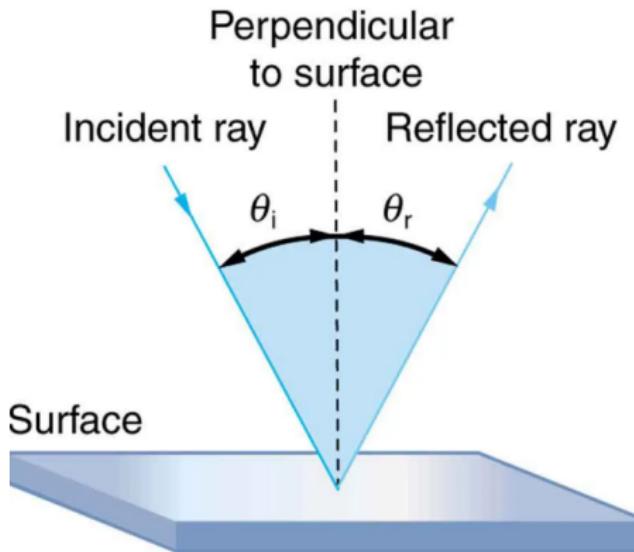


The part of optics dealing with the ray aspect of light is called "geometric optics."



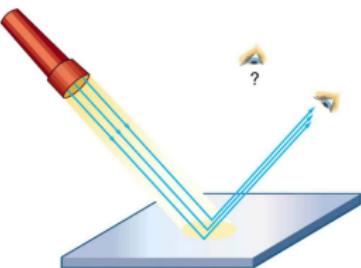
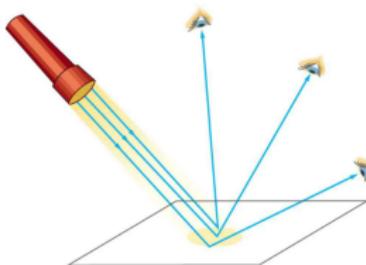
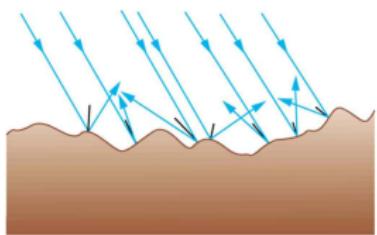
Reflection

The angle of reflection equals the angle of incidence





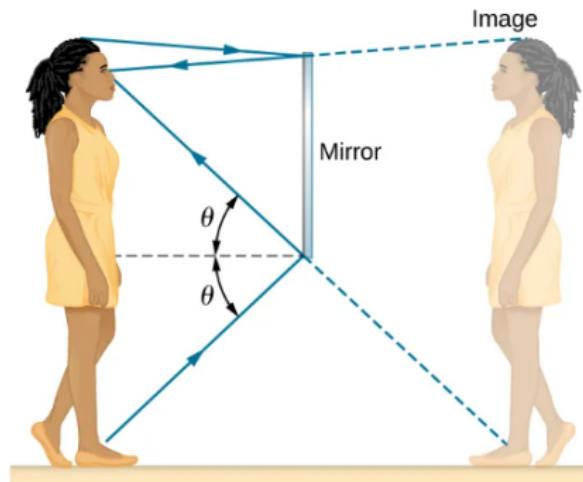
Rough vs Smooth Surfaces





Mirrors and Virtual Images

When we see ourselves in a mirror, it appears that our image is actually behind the mirror.

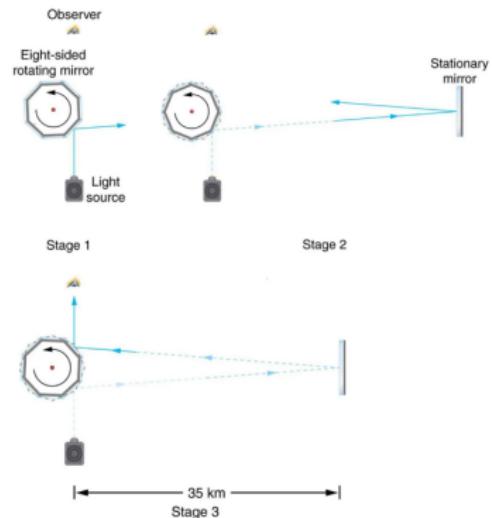




Speed of Light

- In 1676, Danish astronomer Ole Roemer noted the change in orbital period of Jupiter's moons depending on if the earth was moving towards or away from Jupiter. He was able to calculate speed of light to be $2.26 \times 10^8 (\frac{m}{s})$.
- In 1887, American physicist Albert Michelson used a rotating mirror to get a more precise measurement of the speed of light.
- Today, the speed of light is known as:

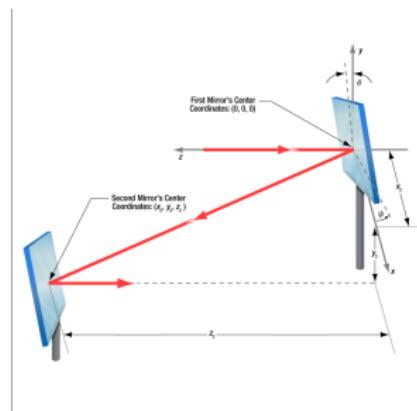
$$c = 2.9979245810^8 (\frac{m}{s}).$$





Two Mirror Walk

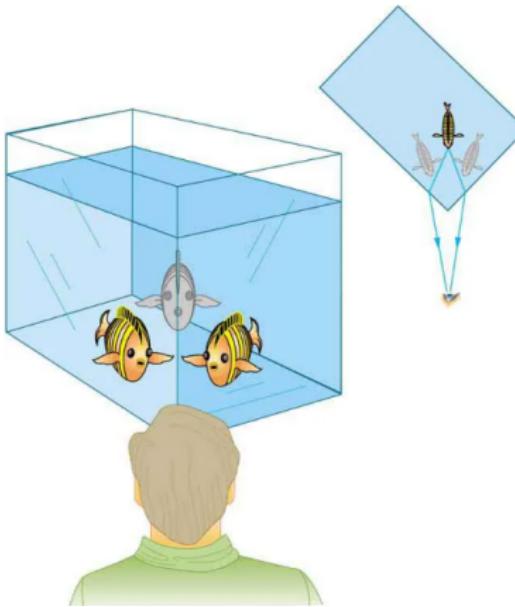
- Center of first mirror should match incoming height of incoming beam path and the second mirror set to the height of the target beam path.
- Set alignment target at height of target.
- Course adjust both mirrors by hand.
- Place the alignment target along the beampath to the target
- Fine tune the beampath by using the adjusters on both mirrors. Note: adjusting the first mirror affects the placement of the second mirror.
- Move the alignment target along the output beampath to endure it is level





Refraction

The changing of a light ray's direction (loosely called bending) when it passes through variations in matter is called refraction.





Index of Refraction

The speed of light depends strongly on the type of material. We define the index of refraction (n) as

$$n = \frac{c}{v}$$

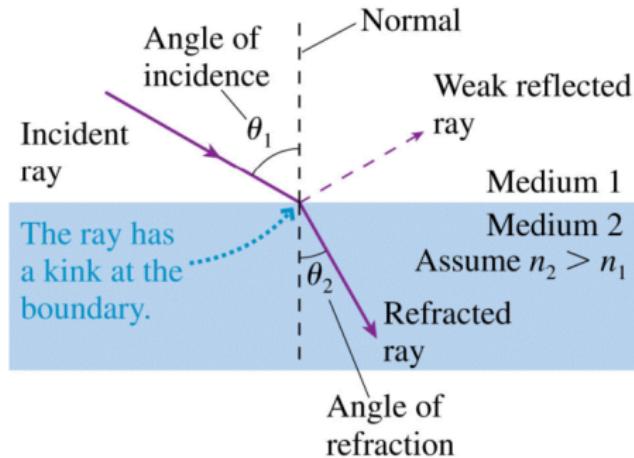
where v is the speed of light in the material and c is the speed of light in a vacuum.

Medium	n
Vacuum	1.00 exactly
Air (actual)	1.0003
Air (accepted)	1.00
Water	1.33
Ethyl alcohol	1.36
Oil	1.46
Glass (typical)	1.50
Polystyrene plastic	1.59
Cubic zirconia	2.18
Diamond	2.41
Silicon (infrared)	3.50



Law of Refraction - Snell's Law

The law of refraction is also called Snell's law after the Dutch mathematician Willebrord Snell (1591–1626).



$$\text{Snell's Law: } n_1 \sin \theta_1 = n_2 \sin \theta_2$$



Finding Index of Refraction

Snells Law:

$$n_1 \sin \theta_1 = n_2 \sin \theta_2 \quad (1)$$

Rearranging to isolate n_2 :

$$n_2 = n_1 \frac{\sin \theta_1}{\sin \theta_2} \quad (2)$$

For example, if the initial medium is air, $\theta_1 = 30^\circ$ and $\theta_2 = 22^\circ$

$$n_2 = (1.00) \cdot \frac{\sin 30^\circ}{\sin 22^\circ} = \frac{0.500}{0.375} = 1.33 \quad (3)$$



Total Internal Reflection

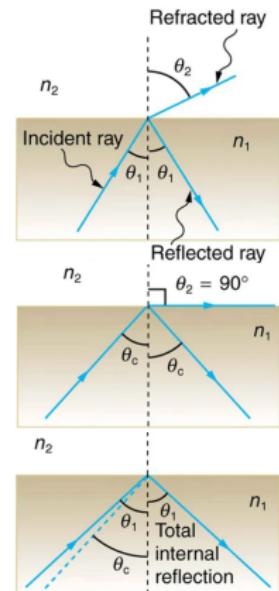
Good mirrors reflect > 90% of the light; however, total reflection can be produced via refraction.

If the index of refraction of the second medium is less than that of the first medium, the rays are refracted away from the perpendicular.

- Since $n_1 > n_2$, the angle of refraction is greater than the angle of incidence: $\theta_2 > \theta_1$.
- Increasing θ_1 causes θ_2 to increase.
- The critical angle (θ_c) is defined to be the incident angle (θ_1) that produces a $\theta_2 = 90^\circ$

The critical angle is given by:

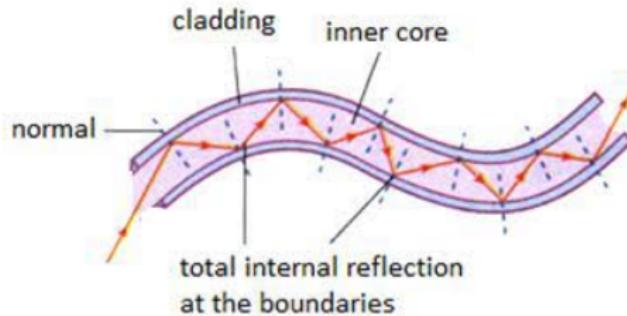
$$\theta_c = \sin^{-1}\left(\frac{n_2}{n_1}\right), \quad \text{for } n_1 > n_2 \quad (4)$$





Fiber Optic Cable

The fiber optic cable takes advantage of the core having a high index of refraction than the cladding.





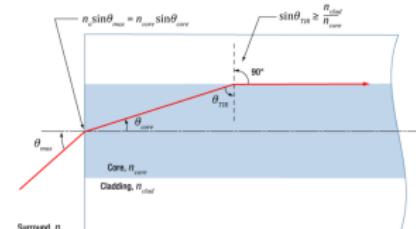
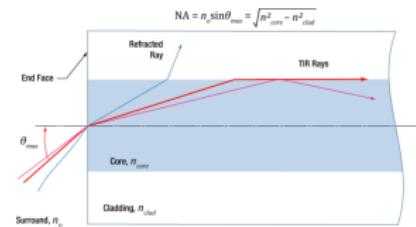
Fiber: Acceptance Angle

For multi-mode fibers, the numerical aperture (NA) provides a good estimate of the maximum acceptance angle.

- The cutoff angle is the maximum acceptance angle (θ_{max}), which is related to NA:

$$NA = n_0 \sin(\theta_{max}) = \sqrt{n_{core}^2 + n_{clad}^2}$$

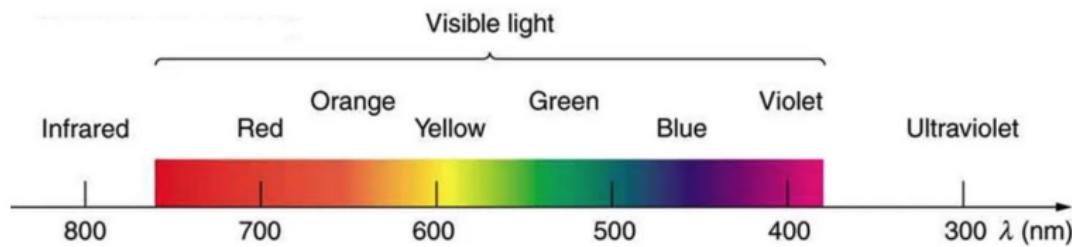
- Rays with an angle of incidence $\leq \theta_{max}$ are totally internally reflected (TIR) at the fiber core/cladding boundary.
- Rays with an angle of incidence $> \theta_{max}$ refract at and pass through the boundary.





Dispersion

Dispersion is defined to be the spreading of white light into its full spectrum of wavelengths.



- The angle of refraction depends on the index of refraction.
- The index of refraction (n) depends on the properties of the medium.
- However, for a given medium, n also depends on the optical wavelength.



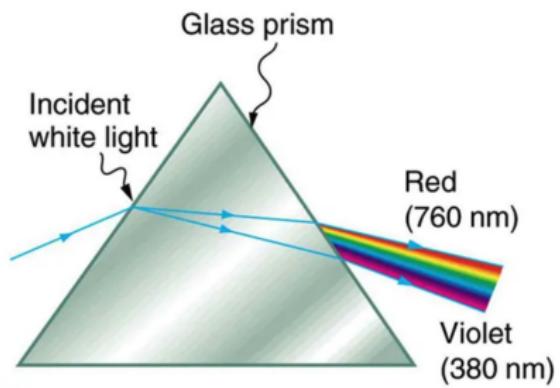
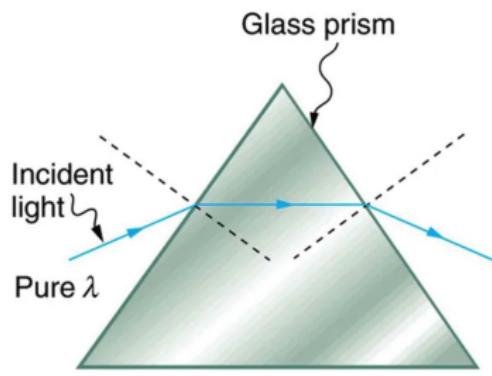
Index of Refraction by Wavelength

Index of refraction (n) by wavelength (λ):

Medium	Red (660 nm)	Orange (610 nm)	Yellow (580 nm)	Green (550 nm)	Blue (470 nm)	Violet (410 nm)
Water	1.331	1.332	1.333	1.335	1.338	1.342
Diamond	2.410	2.415	2.417	2.426	2.444	2.458
Glass, crown	1.512	1.514	1.518	1.519	1.524	1.530
Glass, flint	1.662	1.665	1.667	1.674	1.684	1.698
Polystyrene	1.488	1.490	1.492	1.493	1.499	1.506
Quartz, fused	1.455	1.456	1.458	1.459	1.462	1.468

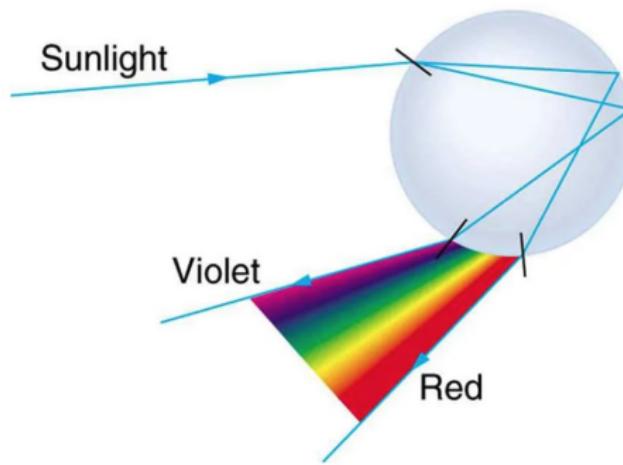


Glass Prism





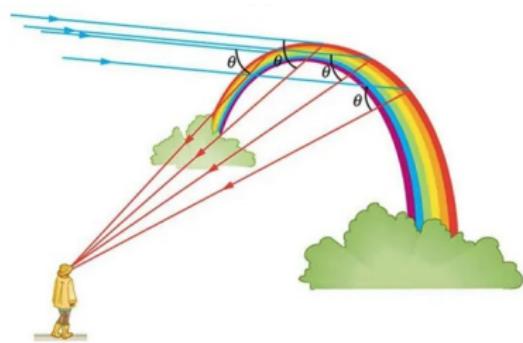
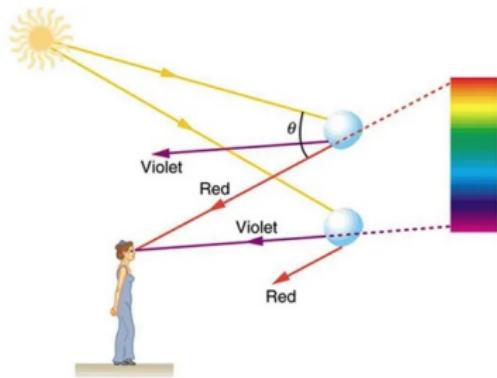
Rainbow



Rainbows are produced by a combination of refraction and reflection. You may have noticed that you see a rainbow only when you look away from the sun. Light enters a drop of water and is reflected from the back of the drop. The light is refracted both as it enters and as it leaves the drop. Since the index of refraction of water varies with wavelength, the light is dispersed, and a rainbow is observed.



Rainbow as an Arc



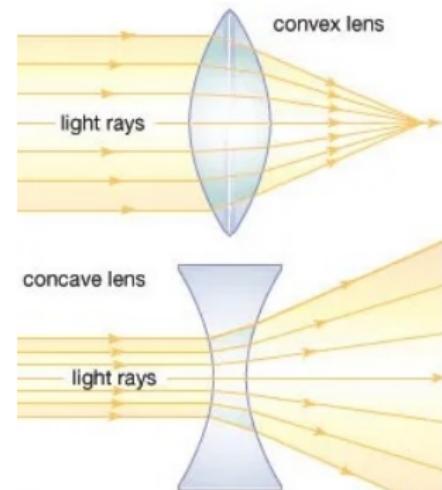
Lens



Lens

With the Law of Refraction, we can explore the properties of lens and how images are formed.

- The word lens comes from the Latin word for lentil bean, the shape of which is similar to a convex lens.
- Convex Lens: all light rays that enter parallel to the axis cross one another at a single point on the opposite side of the lens, i.e., they converge.
- Concave Lens: all light rays that enter parallel to the axis diverge (bend away) from the lens axis.

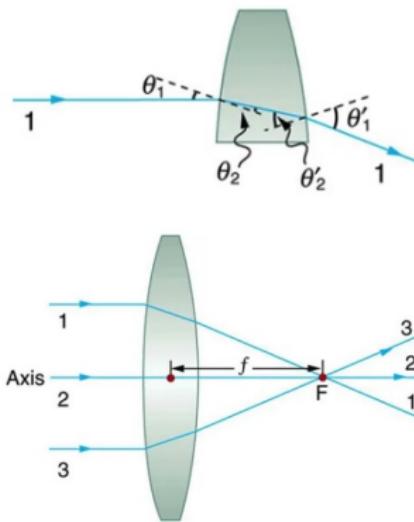




Convex Lens

With the Law of Refraction, we can explore the properties of lens and how images are formed.

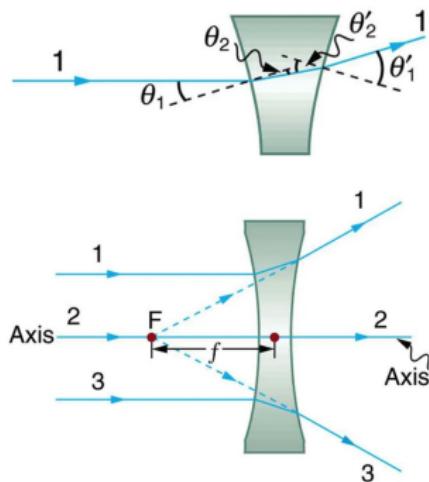
- A ray of light bends (refracts) at both interface, and for convex lens converge.
- The point at which the rays crossed is defined as the Focal point (F) of the lens.
- The distance from the center of the lens to its focal point is called the focal length (f).
- The Power of the lens, measuring in Diopters ($P = \frac{1}{f}$) where f is measured in meters.





Concave Lens

- A concave lens is a diverging lens, it causes light rays to bend away from the axis.
- In the case of all rays entering parallel to its axis, the light appears to originate at the same point F .
- The distance from the center of the lens to its focal point is called the focal length (f) and is defined to be negative.





Thin Lens

A thin lens is defined to be one whose thickness allows rays to refract but does not allow properties such as dispersion and aberrations.



Ray Tracing

- ① A ray entering a converging lens parallel to its axis passes through the focal point F of the lens on the other side.
- ② A ray entering a diverging lens parallel to its axis seems to come from the focal point F.
- ③ A ray passing through the center of either a converging or a diverging lens does not change direction.
- ④ A ray entering a converging lens through its focal point exits parallel to its axis.
- ⑤ A ray that enters a diverging lens by heading toward the focal point on the opposite side exits parallel to the axis.

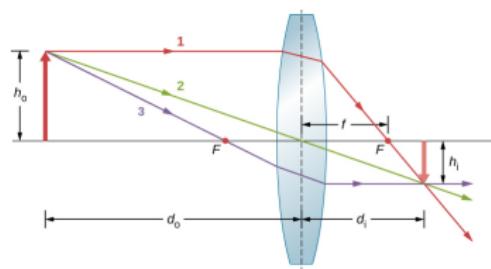
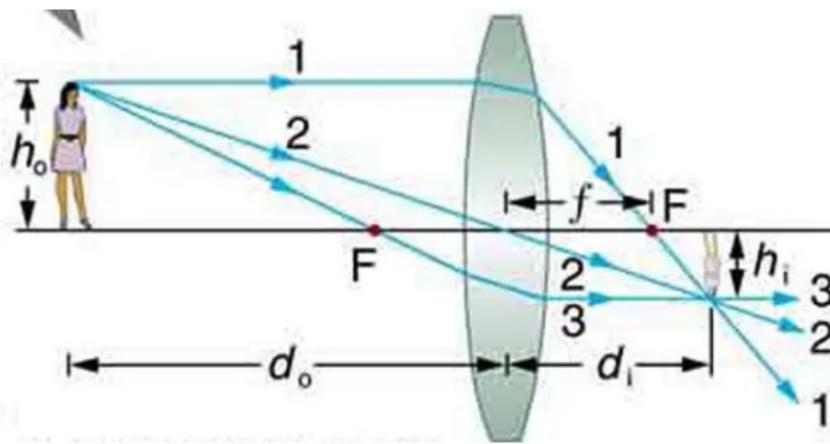




Image Formation



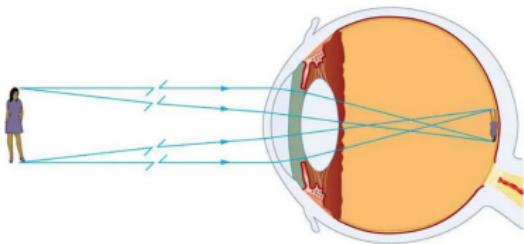
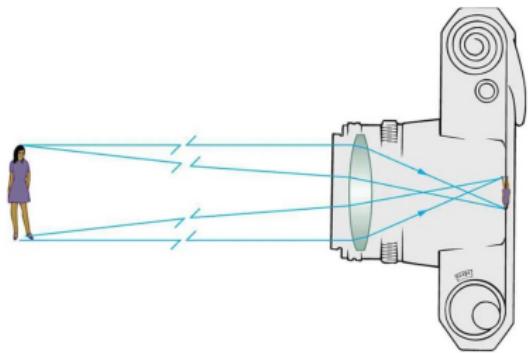
Thin Lens equations:

$$\frac{1}{d_o} + \frac{1}{d_i} = \frac{1}{f}$$

$$\frac{h_i}{h_o} = -\frac{d_i}{d_o} = m$$



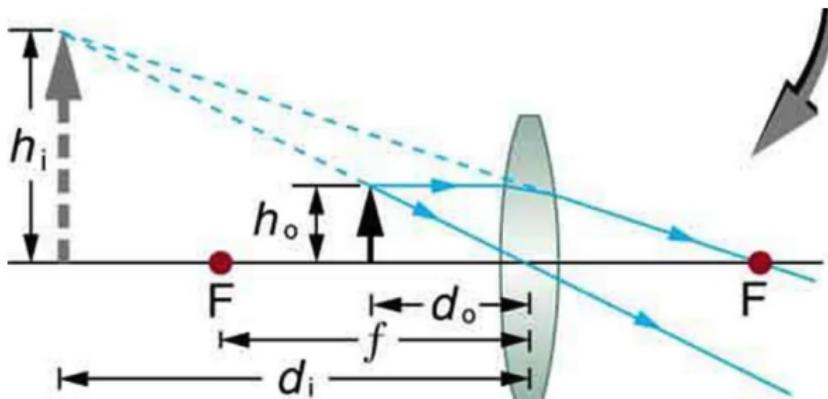
Image Formation - Real Image



The image in which light rays from one point on the object actually cross at the location of the image and can be projected onto a screen, a piece of film, or the retina of an eye is called a real image.



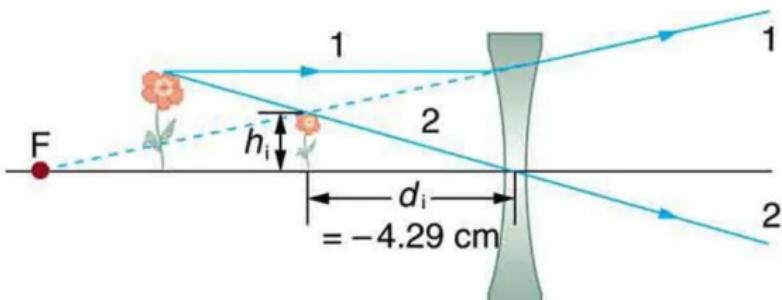
Image Formation - Virtual Image



If an object is held closer to the converging lens than its focal length (f), then the rays from a common point continue to diverge after passing through the lens. They all appear to originate from a point at the location of the image, on the same side of the lens as the object. This is a virtual image.

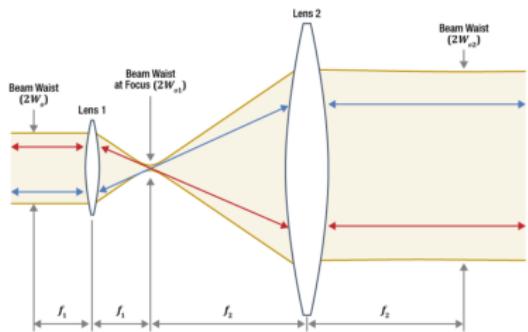


Image Formation - Concave Lens

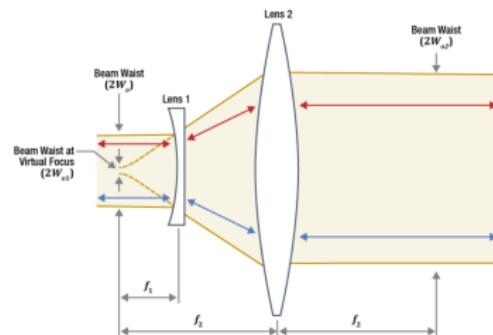




Beam Expander/Reducer - Telescope



Galilean Design



Galilean Design

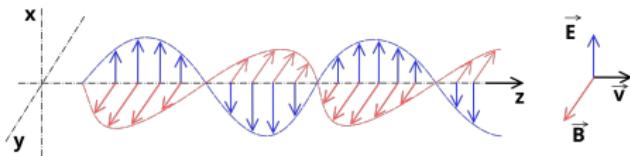
Both the beam's waist ($2W_0$) and the divergence angle (θ) are affected by the beam expanders and reducers. If Lens 2 is the output lens, then the beam expansion ratio (m_{12}) is:

$$m_{12} = \frac{f_2}{f_1} \quad (5)$$

Polarization



Electromagnetic Wave



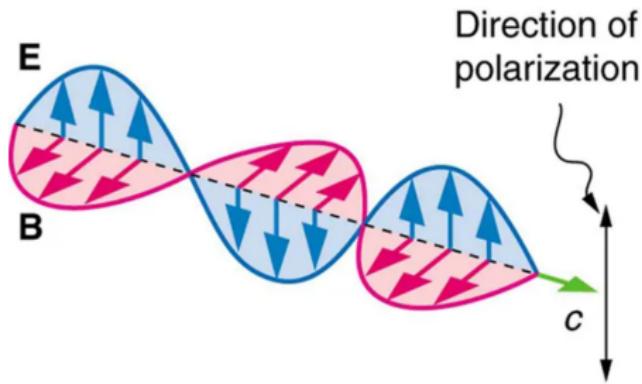
An Electromagnetic (EM) wave is a transverse wave where the electric and magnetic fields are perpendicular to each other and to the direction of propagation.

- Light is called unpolarized if the direction of this electric field fluctuates randomly in time.
- If the direction of the electric field of light is well defined, it is called polarized light.



Linear Polarization

We define the direction of polarization to be the direction parallel to the electric field.





Linear Polarizer

Natural light has polarizations in random directions, it is unpolarized.

Light Passing Through Crossed Polarizers

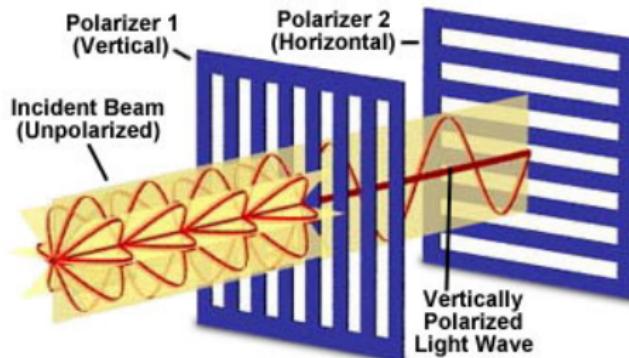


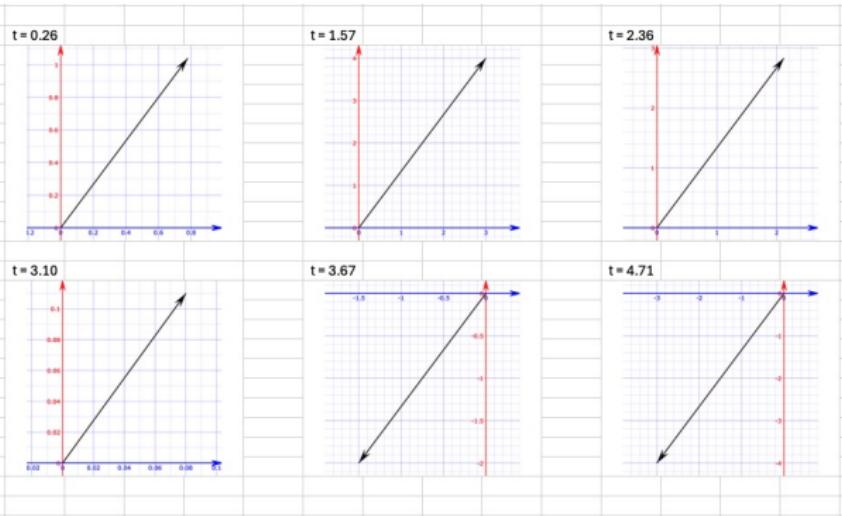
Figure 1



Linear Polarization - Off Axis

<https://www.mathsisfun.com/algebra/vector-calculator.html>

time	v	h	length	angle
0.00	0.00	0.00	0.00	53
0.26	1.04	0.78	1.29	53
0.52	2.00	1.50	2.50	53
0.79	2.83	2.12	3.54	53
1.05	3.46	2.60	4.33	53
1.31	3.86	2.90	4.83	53
1.57	4.00	3.00	5.00	53
1.83	3.86	2.90	4.83	53
2.09	3.46	2.60	4.33	53
2.36	2.83	2.12	3.54	53
2.62	2.00	1.50	2.50	53
2.88	1.04	0.78	1.29	53
3.14	0.00	0.00	0.00	53
3.40	-1.04	-0.78	1.29	-127
3.67	-2.00	-1.50	2.50	-127
3.93	-2.83	-2.12	3.54	-127
4.19	-3.46	-2.60	4.33	-127
4.45	-3.86	-2.90	4.83	-127
4.71	-4.00	-3.00	5.00	-127
4.97	-3.86	-2.90	4.83	-127
5.24	-3.46	-2.60	4.33	-127
5.50	-2.83	-2.12	3.54	-127
5.76	-2.00	-1.50	2.50	-127
6.02	-1.04	-0.78	1.29	-127
6.28	0.00	0.00	0.00	-127



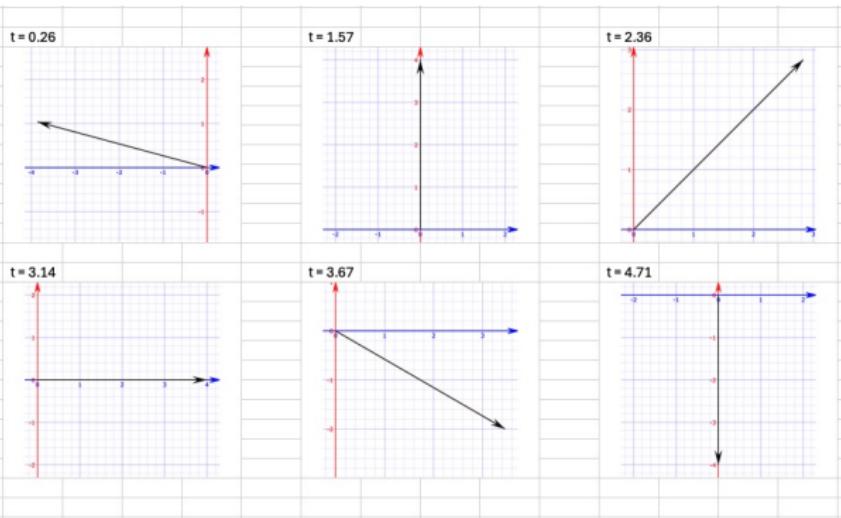
$$\vec{E} = 3 \sin(t) \vec{i} + 4 \sin(t) \vec{j} \quad (6)$$



Circular Polarization

<https://www.mathsisfun.com/algebra/vector-calculator.html>

time	v	h	length	angle
0.00	0.00	-4.00	4.00	180
0.26	1.04	-3.86	4.00	165
0.52	2.00	-3.46	4.00	150
0.79	2.83	-2.83	4.00	135
1.05	3.46	-2.00	4.00	120
1.31	3.86	-1.04	4.00	105
1.57	4.00	0.00	4.00	90
1.83	3.86	1.04	4.00	75
2.09	3.46	2.00	4.00	60
2.36	2.83	2.83	4.00	45
2.62	2.00	3.46	4.00	30
2.88	1.04	3.86	4.00	15
3.14	0.00	4.00	4.00	0
3.40	-1.04	3.86	4.00	-15
3.67	-2.00	3.46	4.00	-30
3.93	-2.83	2.83	4.00	-45
4.19	-3.46	2.00	4.00	-60
4.45	-3.86	1.04	4.00	-75
4.71	-4.00	0.00	4.00	-90
4.97	-3.86	-1.04	4.00	-105
5.24	-3.46	-2.00	4.00	-120
5.50	-2.83	-2.83	4.00	-135
5.76	-2.00	-3.46	4.00	-150
6.02	-1.04	-3.86	4.00	-165
6.28	0.00	-4.00	4.00	-180



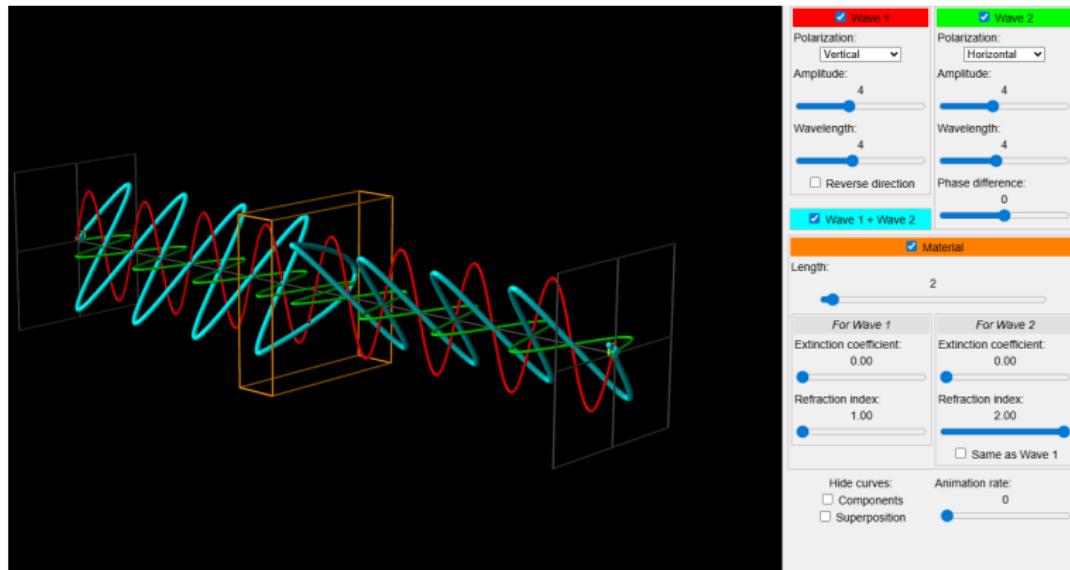
X lags Y by $\frac{\pi}{2}$:

$$\vec{E} = 4 \sin(t + \frac{\pi}{2}) \vec{i} + 4 \sin(t) \vec{j} \quad (7)$$



Incoming 45° with Half-Wave Plate

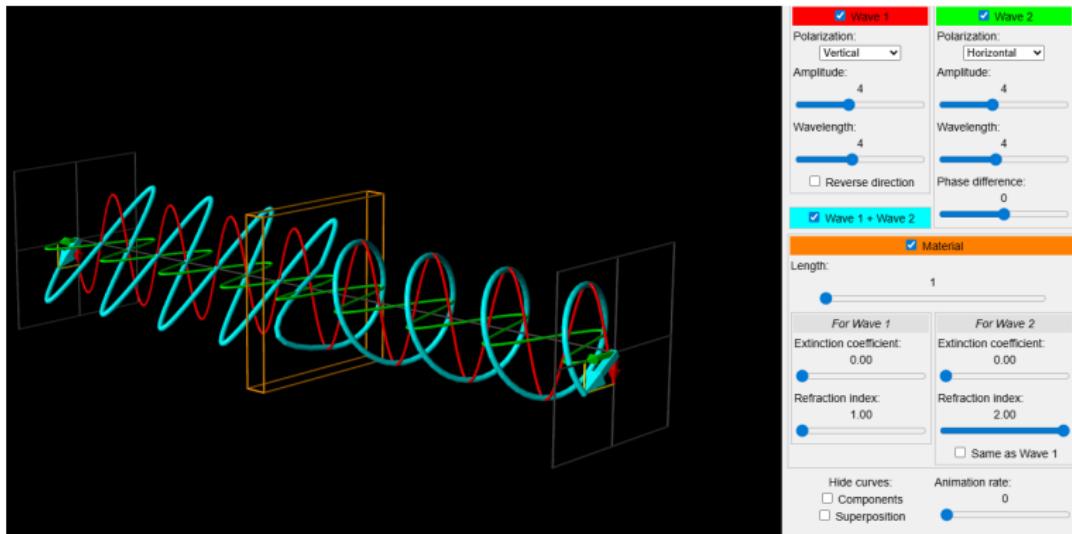
From <https://emanim.szialab.org/>





Incoming 45° with Quarter-Wave Plate

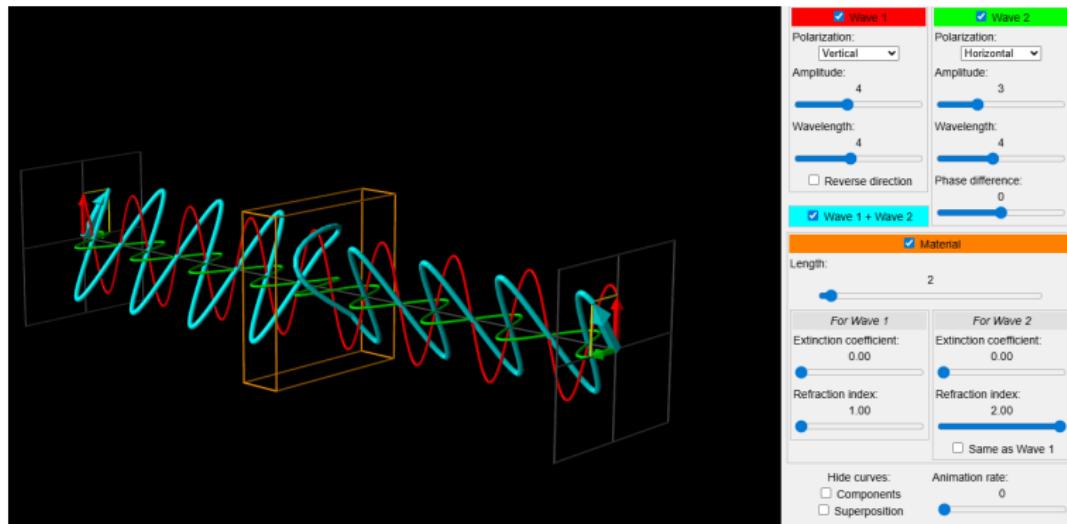
From <https://emanim.szialab.org/>





Incoming 37° with Half-Wave Plate

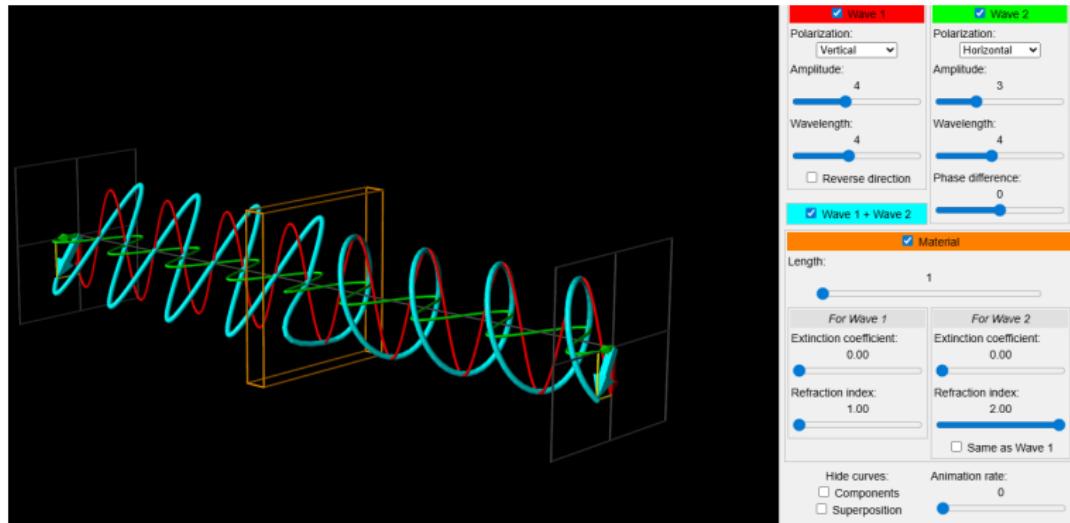
From <https://emanim.szialab.org/>





Incoming 37° with Quarter-Wave Plate

From <https://emanim.szialab.org/>

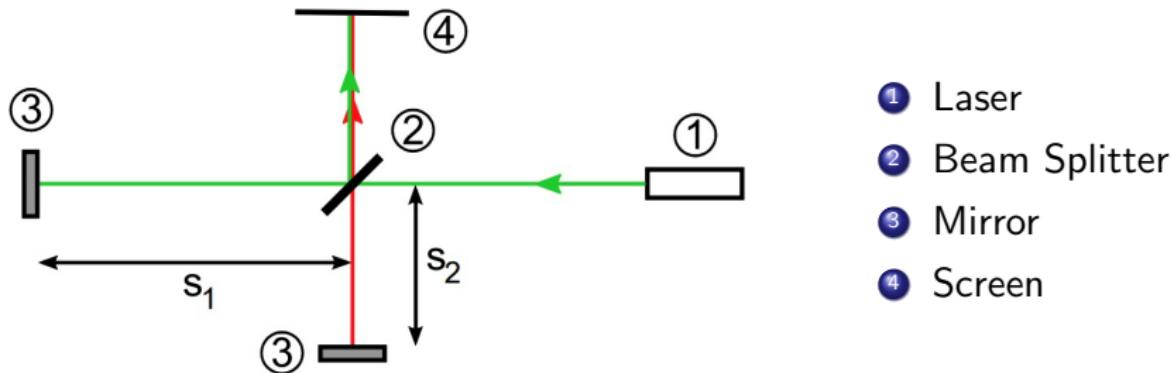


Interferometry



Michelson Interferometer

Invented by the American physicist Albert Abraham Michelson in 1887.



- Laser light is divided by the beamsplitter, the partial beams are reflected by the mirrors and overlap again at the beamsplitter.
- The light intensity on the screen is dependent on the path length difference (Δs) between the two paths s_1 and s_2 .



Interferometer Math

- The Electric Field (E_i) is given by

$$|E_i| = \sqrt{R \cdot T} \cos(\omega t + \phi_i) \quad (8)$$

where T is the transmission capacity of the beamsplitter, R is the reflection capacity, and ϕ_i is the phase which value is defined by the actual optical path.

- Intensity (I) on the screen is given by

$$I = c\epsilon_0 |E_1 + E_2|^2 \quad (9)$$

- If we assume that the transmission and reflection capacity are 0.5 then the average intensity (\bar{I}) is given by

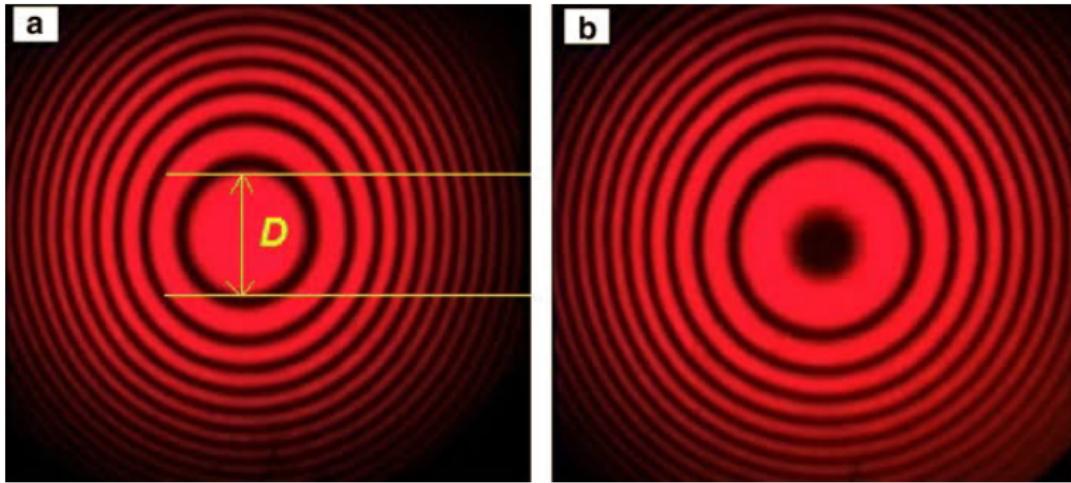
$$\bar{I} = \frac{1}{4}c\epsilon_0 E_0^2(1 + \cos(\Delta\phi)) \quad (10)$$

where $\Delta\phi = \frac{2\pi}{\lambda}\Delta s$ and λ is the wavelength



Interferometer Math - what does it mean

Compare the centers:



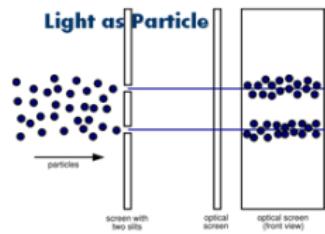
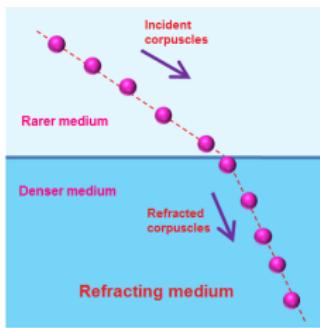
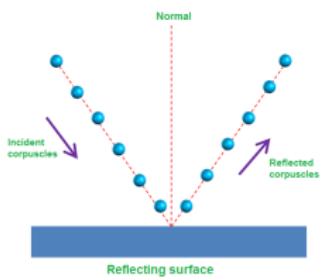
Why are there alternating concentric circles?

Light - a particle or a wave



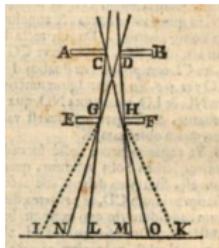
Corpuscular Theory of Light

In 1675, Sir Isaac Newton hypothesized that light was made up corpuscles (small particles) with the size/mass of the corresponding to different colors.

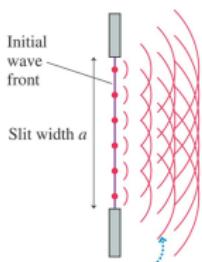




Huygens Principle

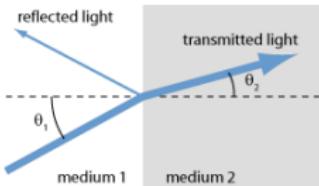


- Francesco Maria Grimaldi (mid-1600's) made accurate observations of the diffraction of light.
- In 1678, Christian Huygens, in order to explain the diffraction of light, proposed that every point on a wavefront (of light) is a wavelet that spreads.

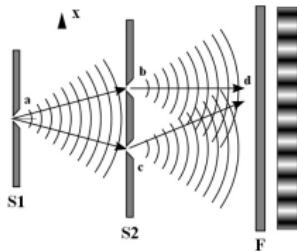




Fresnel and Young



- In 1815, Augustin Jean Fresnel developed the laws of reflection and refraction.



- And, in 1817, Thomas Young calculated the wavelength of light



Maxwell's Equations: Electric \vec{E} and Magnetic \vec{B} Fields

In 1864, James Clerk Maxwell predicted electromagnetic waves

- Gauss's Law: $\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$, where ρ is enclosed charge
- Guass's Law for Magnets: $\nabla \cdot \vec{B} = 0$
- Faraday's Law: $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$
- Ampere's Law: $\nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$

where

$$\mu_0 = 4\pi * 10^{-7} \frac{N}{A^2 m} \text{ and } \epsilon_0 = 8.85 * 10^{-12} \frac{Nm^2}{C^2}$$

Maxwell noted that the speed of the electromagnetic wave is equal to the speed of light:

$$\frac{1}{\sqrt{\mu_0 \epsilon_0}} = \frac{1}{\sqrt{4\pi * 10^{-7} * 8.85 * 10^{-12}}} = 2.99 * 10^8 \frac{m}{s} = c$$

Intro to Quantum Phenomenon

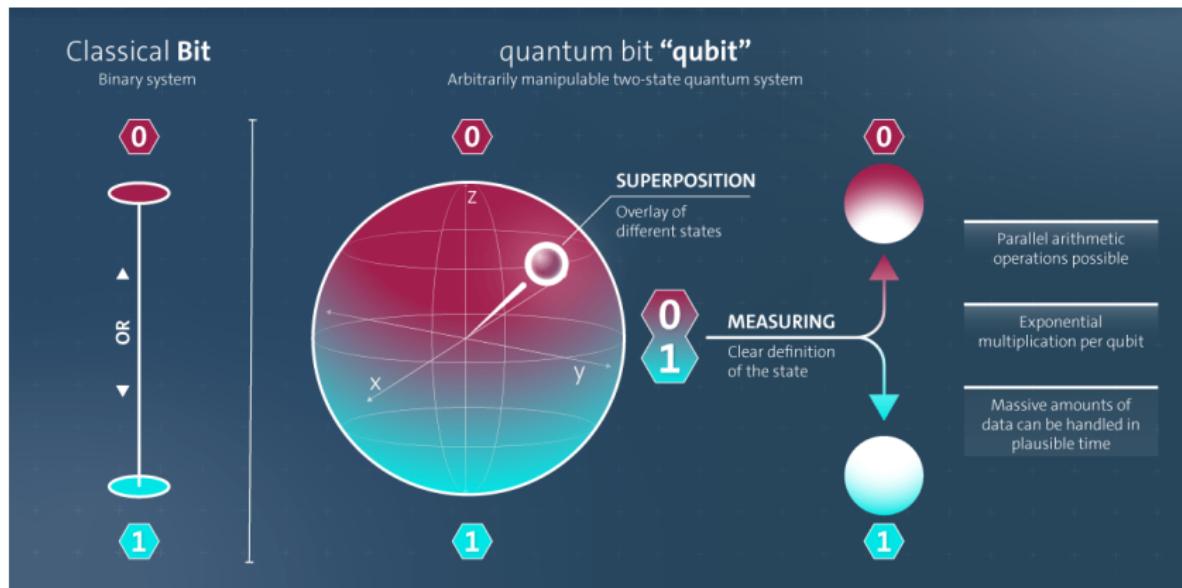


Let there be light

What is a Qubit



Bit vs Qubit



Quantum Computing



Types of Quantum Computers

- Superconducting
- Photonic
- Neutral Atom
- Trapped Ion
- Quantum Dots
- Diamond Nitrogen Vacancies



Quantum Computing: Superconducting

One of the most popular types of quantum computers is a superconducting qubit quantum computer. Usually made from superconducting materials, these quantum computers utilize tiny electrical circuits to produce and manipulate qubits. When using superconducting qubits, gate operations can be performed quickly.

Companies actively researching and manufacturing superconducting quantum computers include Google, IBM, IQM and Rigetti Computing to name just a few.



Quantum Computing: Photonics

These types of quantum computers use photons (particles of light) to carry and process quantum information. For large-scale quantum computers, photonic qubits are a promising alternative to trapped ions and neutral atoms that require cryogenic or laser cooling.



Quantum Computing: Neutral Atom

Quantum computing based on neutral atoms involves atoms suspended in an ultrahigh vacuum by arrays of tightly focused laser beams called optical tweezers, though not all neutral atom companies use optical tweezers. Neutral atom quantum computers are less sensitive to stray electric fields, which makes them a good option for quantum processors.



Trapped Ions



A trapped ion quantum computer involves using atoms or molecules with a net electrical charge known as “ions” that are trapped and manipulated using electric and magnetic fields to store and process quantum information. As trapped ions can be isolated from their environment, they are useful for precision measurements and other applications requiring high levels of stability and control. Also, the qubits can remain in a superposition state for a long time before becoming decoherent. Representing the trapped ions community of companies in the quantum space, we have Quantinuum (a company that came out of the merger between Cambridge Quantum Computing and Honeywell Quantum.



Quantum Computing: Quantum Dots

A quantum dot quantum computer uses silicon qubits made up of pairs of quantum dots. In theory for quantum computers, such 'coupled' quantum dots could be used as robust quantum bits, or qubits.

Companies focused on this area include Diraq, Siquance and Quantum Motion.



Quantum Computing: NV Diamond