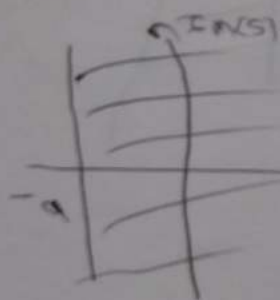


# Laplace transf. & ROC

ROC: The subset of the complex plane  $\mathbb{C}$  where the Laplace transf. integral conv. to a finite value

$$X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$$

Ex.  $x_1(t) = e^{-at} u(t)$   $a > 0$



ROC

$$X_1(s) = \int_0^{\infty} e^{-(s+a)t} dt = \frac{1}{s+a}$$

$\text{Re}(s+a) > 0$  for conv.

$\Rightarrow$  ROC:  $s \rightarrow \text{Re}(s) > -a$

$x_2(t) = e^{-at} u(t)$   $a < 0$

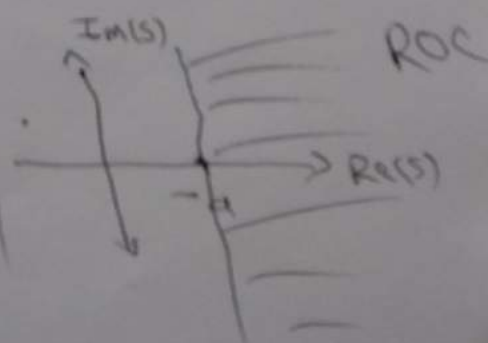
$$X_2(s) = \frac{1}{s-a}$$

let  $b = -a > 0$

$$X_2(s) = \int_0^{\infty} e^{-(s-b)t} dt$$

$\text{Re}(s-b) > 0$

$\Rightarrow \text{Re}(s) > b = -a$



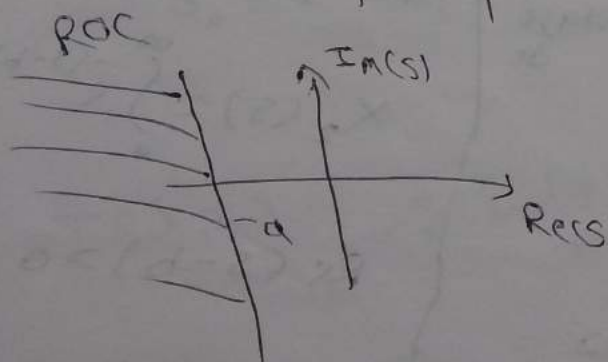
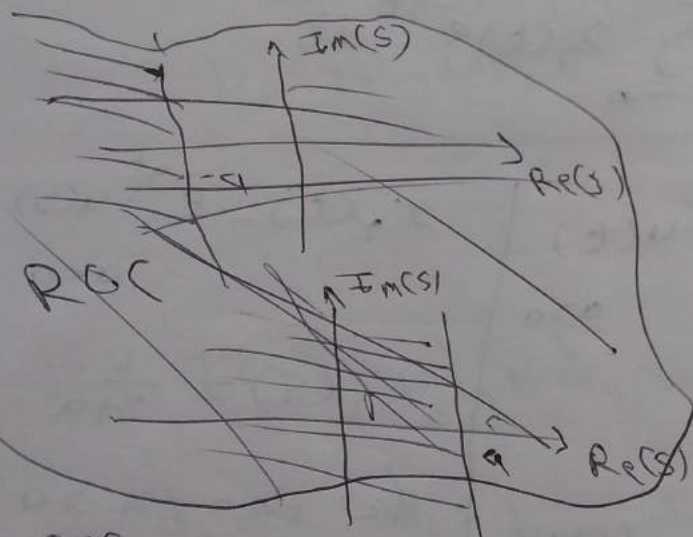
$$x_3(t) = e^{-at} u(-t), \quad a > 0$$

$$X_3(s) = \int_{-\infty}^0 e^{-(s+a)t} dt$$

$$\therefore \text{ROC: } \operatorname{Re}\{-s+a\} > 0$$

$$\Rightarrow \operatorname{Re}(-s) > -a$$

$$\Rightarrow \operatorname{Re}(s) < -a$$



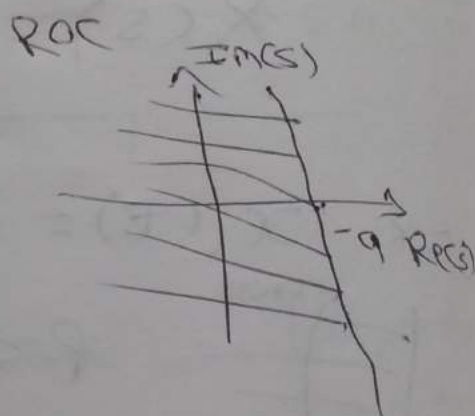
$$x_4(t) = e^{-at} u(t), \quad a < 0$$

$$X_4(s) = \int_0^{\infty} e^{-(s+a)t} dt$$

$$\therefore \text{ROC: } \operatorname{Re}\{-(s+a)\} > 0$$

$$\Rightarrow \operatorname{Re}\{-s\} > -a$$

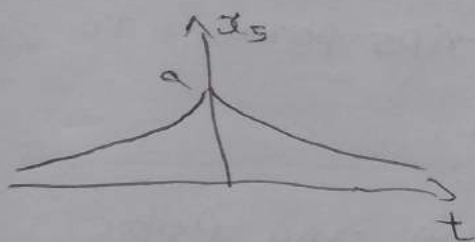
$$\Rightarrow \operatorname{Re}\{s\} < -a$$



$$x_5(t) = e^{-at} u(t) \quad t \geq 0$$

$$= e^{+at} u(-t) \quad t < 0$$

$$a > 0$$

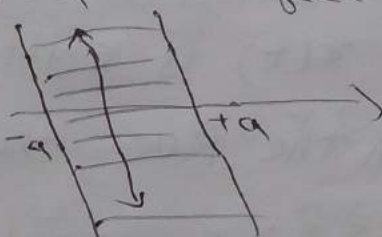


$$X_5(s) = \int_0^{\infty} e^{-(s+a)t} dt + \int_{-\infty}^0 e^{-(s+a)t} dt$$

$$\text{ROC: } \text{Re}\{s\} > -a$$

$$\text{Re}\{s\} < +a$$

$$\Rightarrow \text{ROC} = \emptyset$$



$$x_6(t) = e^{-at} u(t) - e^{+bt} u(-t) \quad a, b > 0$$

$$\text{ROC: } \text{Re}\{s\} > -a \quad \text{Re}\{s\} < -b$$

$$\text{ROC: } \emptyset \quad -a < \text{Re}\{s\} < a$$

## ROC prop.

1. ROC consists of strips parallel to  $j\omega$  axis in the  $s$ -plane.

2. ROC doesn't contain any poles

3. If  $x(t)$  is of finite durat.<sup>n</sup> & abs. integrable, ROC is entire  $s$ -plane

4. If  $x(t)$  is right sided & if  $\text{Re}(s) = \sigma_0$  is in the ROC, then  $\forall s \in \mathbb{C}$  such that  $\text{Re}(s) > \sigma_0$  is also in the ROC.

5. If  $x(t)$  is left sided . . .  
...  $\text{Re}(s) < \sigma_0$  is also in the ROC.

6. If  $x(t)$  is 2-sided & . . . , then the ROC consists of a strip in the  $s$ -plane that includes the line

7. If  $x$  poles

8. If  $\gamma$  the  $\gamma$  If of

LT

1. lie

2. time

3.  $s$ -

4. +

5.  $c$

6.  $c$

7.  $d$

8.  $d$

9.  $i$



7. If  $X(s)$  is rational, then ROC is bdd. by poles or extends to  $\infty$ .

8. If  $X(s)$  is rational &  $x(t)$  is rt. sided, then the ROC is the region in the  $s$ -plane to the rt. of the rightmost pole.

If  $x(t)$  is left sided, the ROC is to the left of the leftmost pole.

LT prop. & ROC ( $X(s)$  has  $\text{ROC} = R$ )

1. lin.  $a_1 x_1(t) + a_2 x_2(t) \longleftrightarrow a_1 X_1(s) + a_2 X_2(s)$   
 $\text{ROC} \supseteq R_1 \cap R_2$

2. time-shift:  $x(t-t_0) \longleftrightarrow e^{-st_0} X(s)$   $\text{ROC} = R$

3.  $s$ -shift:  $e^{s_0 t} x(t) \longleftrightarrow X(s-s_0)$   $\text{ROC}: R + R_0(s_0)$

4. time scale:  $x(at) \longleftrightarrow \frac{1}{|a|} X\left(\frac{s}{a}\right)$   $\text{ROC}: aR$

5. conjug.<sup>n</sup>:  $x^*(t) \longleftrightarrow X^*(s^*)$   $\text{ROC} = R$

6. convol.<sup>n</sup>:  $x_1 * x_2 \longleftrightarrow X_1(s) X_2(s)$   $\text{ROC} \supseteq R_1 \cap R_2$

7. diff. in time:  $\frac{dx}{dt} \longleftrightarrow sX(s)$   $\text{ROC} \supseteq R$

8. diff. in freq.  $-tx(t) \longleftrightarrow \frac{dX(s)}{ds}$   $\text{ROC} = R$

9. integr.<sup>n</sup> in time:  $\int_{-\infty}^t x(\tau) d\tau \longleftrightarrow \frac{1}{s} X(s)$   $\text{ROC} \supseteq R \cap \text{Re}\{s\} > 0$

in prop. 1 (lin.) &  $G$  (conv.),

there could be a pole zero cancell.  
leading to  $\geq$  instead of  $=$  in the R

ex.  $X_1(s) = \frac{s+1}{s+2}$

$R_1 \rightarrow \operatorname{Re}(s) > -2$

$X_2(s) = \frac{s+2}{s+1}$

$R_2 \rightarrow \operatorname{Re}(s) > -1$

$R_1 \cap R_2 = R_2 \subset R = s\text{-plane}$

### Causality, stability & ROC

causality  $\leftrightarrow$  ROC = rt. half plane to the  
rt. of the rightmost pole

anticausal  $\leftrightarrow$  ROC = ? (left half ...)

stability  $\leftrightarrow$  ROC includes  $j\omega$ -axis



impulse resp. abs.

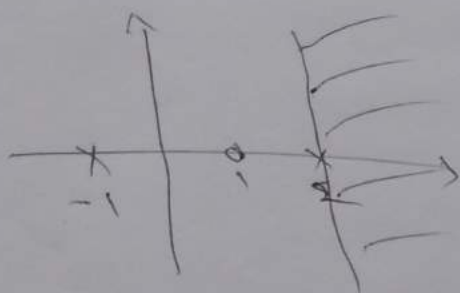
integr.  $\Rightarrow$  Four. transf.

converges  $\Rightarrow$  L.T. conv. on  $j\omega$ -axis

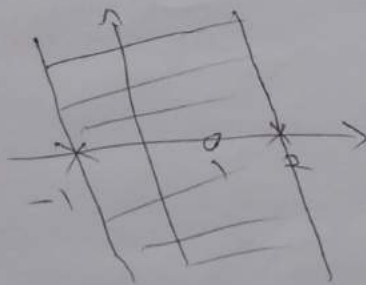
causal & stable  $\leftrightarrow$  poles in the LHP,  
 ROC includes  $j\omega$ -axis.

ex.  $H(s) = \frac{s-1}{(s+1)(s-2)}$

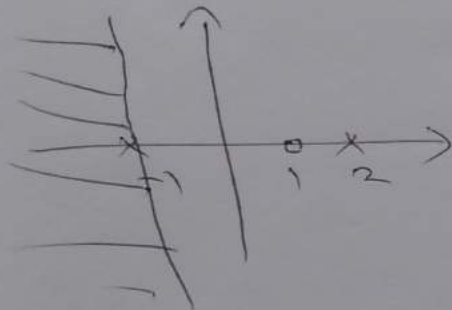
when  $h(t)$  is  
 stable/causal?



$R_1$



$R_2$



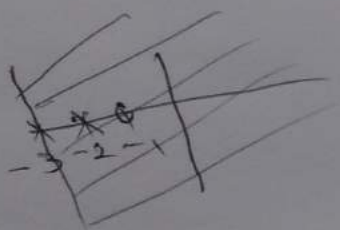
$R_3$

$R_1 \rightarrow$  causal, unstable

$R_2 \rightarrow$  non causal, stable

$R_3 \rightarrow$  anti causal,  
 unstable

ex.  $H(s) = \frac{s+1}{(s+2)(s+3)}$



$\rightarrow$  stable & causal