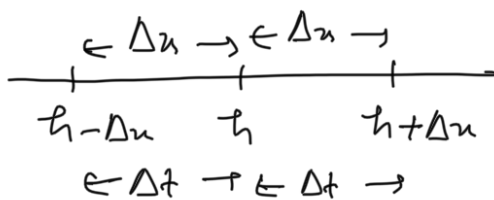


# Brownian Motion process:



$X(t)$ : position of particle at time  $t$

$$= \Delta x (X_1 + X_2 + \dots + X_{\lceil \frac{t}{\Delta t} \rceil}) = \Delta x \sum_{i=1}^{\lceil \frac{t}{\Delta t} \rceil} X_i$$

$$X_i = \begin{cases} +1 & \text{right } i\text{th step} \\ -1 & \text{left } i\text{th step} \end{cases}$$

$X_i$ 's are indep

$$P(X_i = +1) = P(X_i = -1) = \frac{1}{2}$$

$$E(X_i) = 0, V(X_i) = E(X_i^2) = 1$$

$$E(X(t)) = \Delta x \sum_{i=1}^{\lceil \frac{t}{\Delta t} \rceil} \underbrace{E(X_i)}_{=0} = 0$$

$$V(X(t)) = (\Delta x)^2 \sum_{i=1}^{\lceil \frac{t}{\Delta t} \rceil} \underbrace{V(X_i)}_{=1} = (\Delta x)^2 \left\lceil \frac{t}{\Delta t} \right\rceil$$

Let  $\Delta x \rightarrow 0, \Delta t \rightarrow 0$

Case I  $\Delta x = \Delta t$

$$E(X(t)) = 0, V(X(t)) \rightarrow 0$$

trivial case

Case II  $\Delta x = \sigma \sqrt{\Delta t}, \sigma > 0$

$$E(X(t)) = 0, V(X(t)) \rightarrow \sigma^2 t$$

Intuitive properties

$X(t)$  is a Brownian Motion (BM) process.

1.1.1) Brownian motion (BM) process

(i)  $X(t)$  has stationary & independent increments

(ii)  $X(t) \sim N(0, \sigma^2 t)$

(iii)  $X(0) = 0$

$W(t)$  standard BM process or Wiener process

(i)  $W(t)$  has stationary & indep. increment

(ii)  $W(t) \sim N(0, t)$

(iii)  $W(0) = 0$  —X—

$$W(t) = \frac{B(t)}{\sigma}$$

Wiener process

$$W(t) \sim N(0, t) \quad \text{pdf } f_t(x) = \frac{1}{\sqrt{2\pi t}} e^{-x^2/2t}, \quad -\infty < x < \infty$$

$$W(t_1) = x_1, \dots, W(t_n) = x_n \equiv W(t_1) = x_1, W(t_2) - W(t_1) = x_2 - x_1, \dots, W(t_n) - W(t_{n-1}) = x_n - x_{n-1}$$

Joint density of  $W(t_1), \dots, W(t_n)$

$$f_{t_1, \dots, t_n}(x_1, \dots, x_n) = f_{t_1}(x_1) f_{t_2-t_1}(x_2-x_1) \dots f_{t_n-t_{n-1}}(x_n-x_{n-1})$$

$$= \frac{\exp\left\{-\frac{1}{2}\left[\frac{x_1^2}{t_1} + \frac{(x_2-x_1)^2}{t_2-t_1} + \dots + \frac{(x_n-x_{n-1})^2}{t_n-t_{n-1}}\right]\right\}}{(2\pi)^{n/2} [t_1(t_2-t_1) \dots (t_n-t_{n-1})]^{1/2}}$$

$$[W(s) | W(t) = B], \quad s < t$$

$$\text{density } f_{s|t}(x|B) = \frac{f_{s,t}(x, B)}{f_t(B)} = \frac{f_s(x) f_{t-s}(B-x)}{f_t(B)}$$

$$f_{s|t}(x) \quad \text{or} \quad [W(s) | W(t) = B]$$

$$= k_1 \exp\left\{-\frac{1}{2}\left[\frac{x^2}{s} + \frac{(B-x)^2}{t-s}\right]\right\}$$

$$= k_2 \exp \left\{ -x^2 \left( \frac{1}{2s} + \frac{1}{2(t-s)} \right) + \frac{\beta x}{t-s} \right\}$$

$$= k_2 \exp \left\{ \frac{-t}{2s(t-s)} \left( x^2 - \frac{2\beta s x}{t} \right) \right\}$$

$$= k_3 \exp \left\{ - \frac{\left( x - \frac{\beta s}{t} \right)^2}{2s(t-s)/t} \right\}$$

$$\begin{array}{c} s < t \\ [W(s) | W(t) = \beta] \sim N \left( \underbrace{\frac{s}{t} \beta}_{E[W(s) | W(t) = \beta]}, \underbrace{\frac{s(t-s)}{t}}_{V[W(s) | W(t) = \beta]} \right) \end{array}$$

Example : In a bicycle race between two competitors, let  $Y(t)$  : amt of time (in secs) by which the racer that started in the inside position is ahead when 100% of the race has been completed,  $(Y(t), 0 \leq t \leq 1)$  BM process  
var. param  $\sigma^2$

(9) If the inside racer is leading the race by  $\sigma$  secs at the midpoint of the race, what is the prob. that she is the winner?

Sol.  $P \left( Y(1) > 0 \mid Y\left(\frac{1}{2}\right) = \sigma \right) \quad \underline{Y(t) \sim N(0, \sigma^2 t)}$

$$= P \left( Y(1) - Y\left(\frac{1}{2}\right) > 0 - \sigma \mid Y\left(\frac{1}{2}\right) = \sigma \right)$$

$$= P \left( Y(1) - Y\left(\frac{1}{2}\right) > -\sigma \right)$$

$$= P(Y(\frac{1}{2}) > -\sigma) = P\left(\frac{Y(\frac{1}{2}) - 0}{\sigma \frac{1}{\sqrt{2}}} > \frac{-\sigma - 0}{\sigma/\sqrt{2}}\right)$$

$$= P(Z > -\sqrt{2}) \quad ; Z \sim N(0,1)$$

$$= 1 - P(Z \leq -\sqrt{2}) = 1 - \Phi(-\sqrt{2})$$

$$= \Phi(\sqrt{2}) \approx 0.9213 \quad \left( \text{from standard normal distn table} \right)$$

(b) If the inside racer wins the race by a margin of  $\sigma$  sec's, what is the prob. that she was ahead at the midpoint?

$$P(Y(\frac{1}{2}) > 0 \mid Y(1) = \sigma)$$

$$s < t; [W(s) \mid W(t) = B] \sim N\left(\frac{s}{t} B, \frac{s(t-s)}{t}\right)$$

$$\sigma W(t) = Y(t)$$

$$[\sigma W(s) \mid Y(t) = \sigma B] \sim N\left(\sigma \frac{s}{t} B, \frac{s(t-s)}{t} \sigma^2\right)$$

$$[Y(s) \mid Y(t) = \sigma B] \sim N\left(\frac{s}{t} \sigma B, \frac{s(t-s)}{t} \sigma^2\right)$$

$$U = \left(Y\left(\frac{1}{2}\right) \mid Y(1) = \sigma\right) \sim N\left(\frac{1}{2}\sigma, \frac{1}{4}\sigma^2\right)$$

$$P(U > 0) = P\left(\frac{U - \sigma/2}{\sqrt{\sigma^2/4}} > \frac{-\sigma/2}{\sqrt{\sigma^2/4}}\right)$$

$$= P(Z > -1)$$

$$Z = \frac{U - \sigma/2}{\sqrt{\sigma^2/4}} \sim N(0,1)$$

1 0/2, 1/4

$$\begin{aligned}
 &= 1 - \Phi(-1) \\
 &= 1 - \Phi(-1) \\
 &= \Phi(1) \approx 0.8413
 \end{aligned}$$

Geometric BM :

$Y(t)$  BM process with drift parameter  $\mu$  and variance parameter  $\sigma^2$ ,  $Y(t) \sim N(\mu t, \sigma^2 t)$ .

$$X(t) = e^{Y(t)}$$

↳ Geometric BM.

$$E(X(t) | X(u), 0 \leq u \leq s)$$

$$= E(e^{Y(t)} | Y(u), 0 \leq u \leq s)$$

$$= E(e^{Y(t)-Y(s)+Y(s)} | Y(u), 0 \leq u \leq s)$$

$$= e^{Y(s)} E(e^{Y(t)-Y(s)} | Y(u), 0 \leq u \leq s)$$

$$= e^{Y(s)} E(e^{Y(t)-Y(s)}) \quad \left. \vphantom{E(e^{Y(t)-Y(s)})} \right\} \because Y(t) \text{ has indep. increments}$$

$$\begin{aligned}
 U &= Y(t) - Y(s) \stackrel{d}{=} Y(t-s) \\
 &\sim N(\mu(t-s), \sigma^2(t-s)) \\
 \text{msf } E(e^{aU}) &= e^{\mu(t-s)a + \frac{1}{2}\sigma^2(t-s)a^2}
 \end{aligned}$$

$$1 - u = 1$$

$$= e^{y(s)} e^{\mu(t-s) + \frac{1}{2}\sigma^2(t-s)}$$

$$= X(s) e^{(t-s)(\mu + \sigma^2/2)}$$

$$E(X(t) | X(u), 0 \leq u \leq s) = X(s) e^{(t-s)(\mu + \sigma^2/2)}$$

$$E(X(t)) = E(E(X(t) | X(u), 0 \leq u \leq s)) = E(X(s)) e^{(t-s)(\mu + \sigma^2/2)}$$