



NPTEL ONLINE CERTIFICATION COURSES

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**Lecture 27: State Machine Replication as Distributed
Consensus**

CONCEPTS COVERED

- State Machine Replication as a Consensus
- Synchronous vs Asynchronous Consensus with Crash Faults



KEYWORDS

- Crash Fault Tolerance
- Paxos



State Machine Replication as Consensus

- There is a natural reason to use state machine replication-based consensus over permissioned blockchains
 - The network is closed, the nodes know each other, so state replication is possible among the known nodes
 - Avoid the overhead of mining - do not need to spend anything (like power, time, bitcoin) other than message passing
 - However, consensus is still required - machines can be faulty or behave maliciously



State Machine Replication as Consensus

- There is a natural reason to use state machine replication:
 - ...er, so
 - ...des
 - ...pend
 - ...essage
 - ...can be
 - faulty or be maliciously

But, we need a bit redesign !



State Machine Replication as Consensus

- There is a problem with state machine replication as consensus. The problem is that the nodes are not trusted. They can be faulty or behave maliciously. Therefore, we need a bit redesign !
 - **Crypto is the saver**
 - **Crypto + Distributed Consensus = Consensus for Permissioned Blockchain**
- If the nodes are not trusted, then the nodes can be faulty or behave maliciously.



State Machine Replication as Consensus

- Classical Distributed Consensus Algorithms (**Paxos**, **RAFT**, **Byzantine Agreement**) are based on State Machine Replication
 - Let us (re)visit those algorithms



Faults in a Distributed Systems

- **Crash Faults**: The node stops operating – hardware or software faults
 - In an asynchronous system: You do not know whether messages have been delayed or the node is not responding
 - Rely on majority voting – progress as and when you have received the confirmation from the majority
 - Propagation of the consensus information – nodes on a slow network will receive it eventually



Faults in a Distributed Systems

- **Byzantine Faults**: Nodes misbehave – send different information to different peers (partition the network)
 - More difficult to handle
 - More suitable for blockchains



Asynchronous Consensus with Crash Faults

- Remember the **FLP Impossibility**
 - Give priority to safety over liveness
- Guarantees the followings --
 - **Validity**: If all correct process proposes the same value v , then any correct process decides v
 - **Agreement**: No two correct processes decide differently
 - **Termination**: Every correct process eventually decides



Asynchronous Consensus with Crash Faults

- Guarantees the followings --
 - **Validity**: If all correct process proposes the same value v , then any correct process decides v (**Unlikely to happen in PoW**)
 - **Agreement**: No two correct processes decide differently (**Safety – Not in PoW**)
 - **Termination**: Every correct process eventually decides (**Liveness – Priority in PoW**)



CFT Consensus

- CFT Consensus
 - **Paxos** (Proposed by Lamport, the most fundamental CFT) -- used in DynamoDB
 - **RAFT** (Much simpler than Paxos) -- Used in Fabric Transaction Ordering



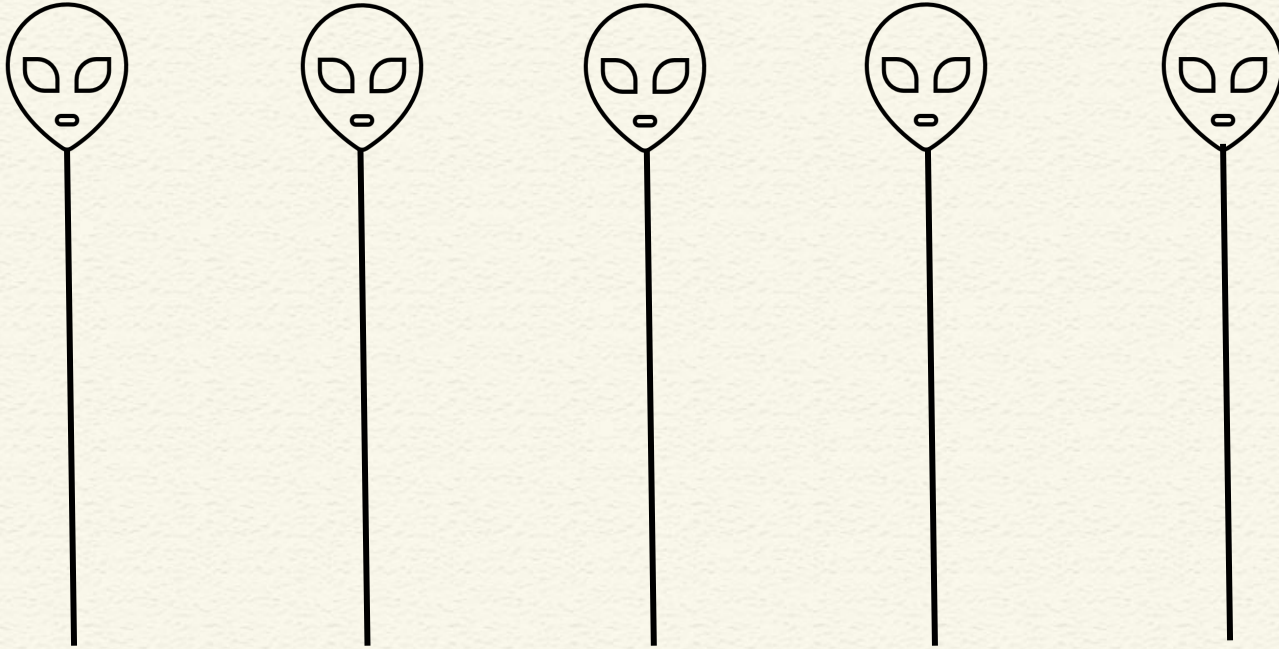
CFT Consensus

We'll see how Paxos works

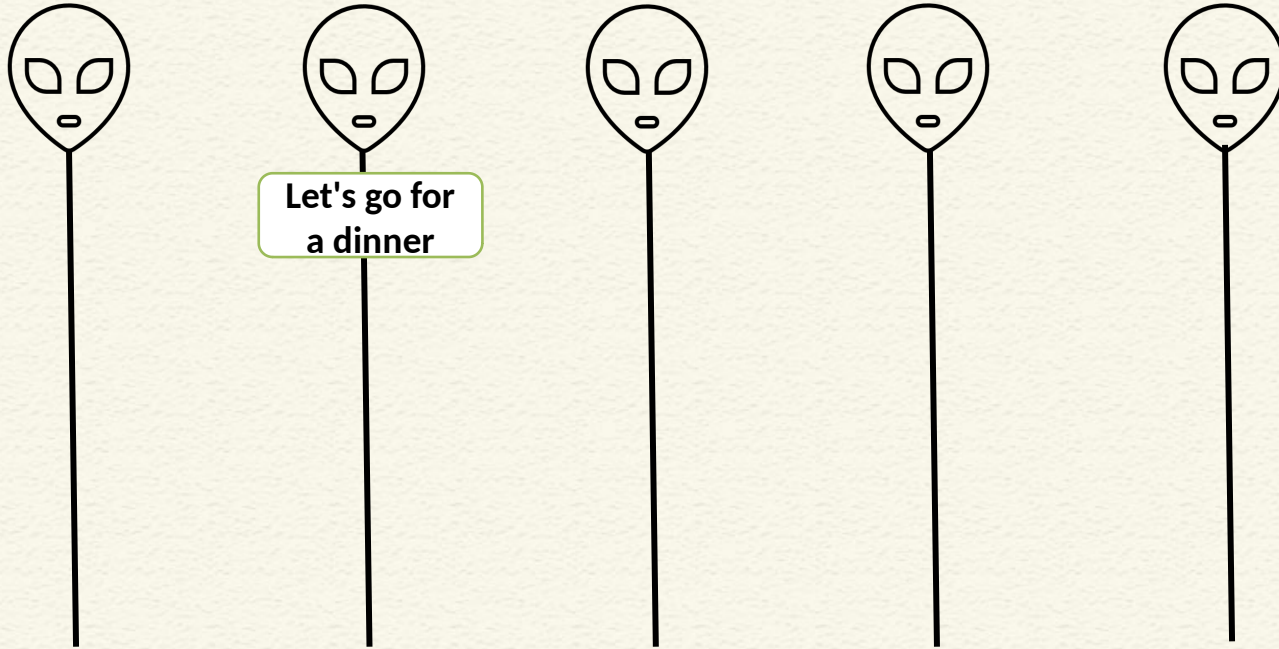
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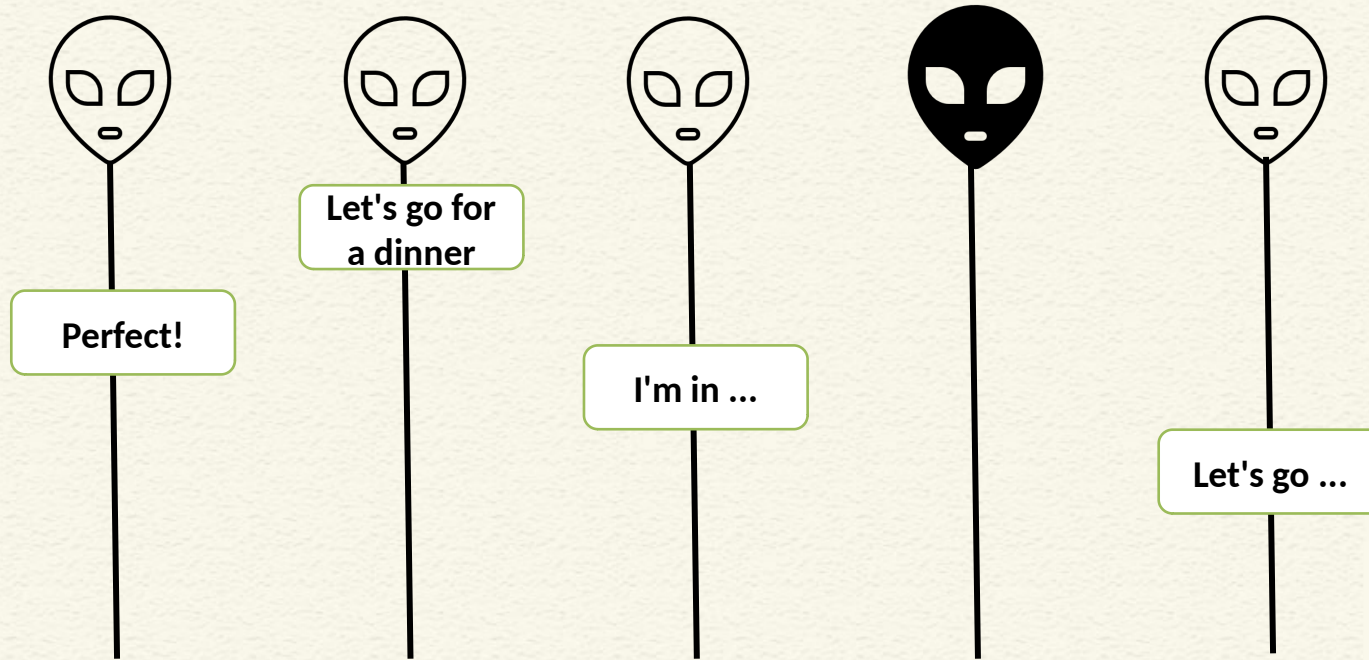
CFT in a Synchronous System



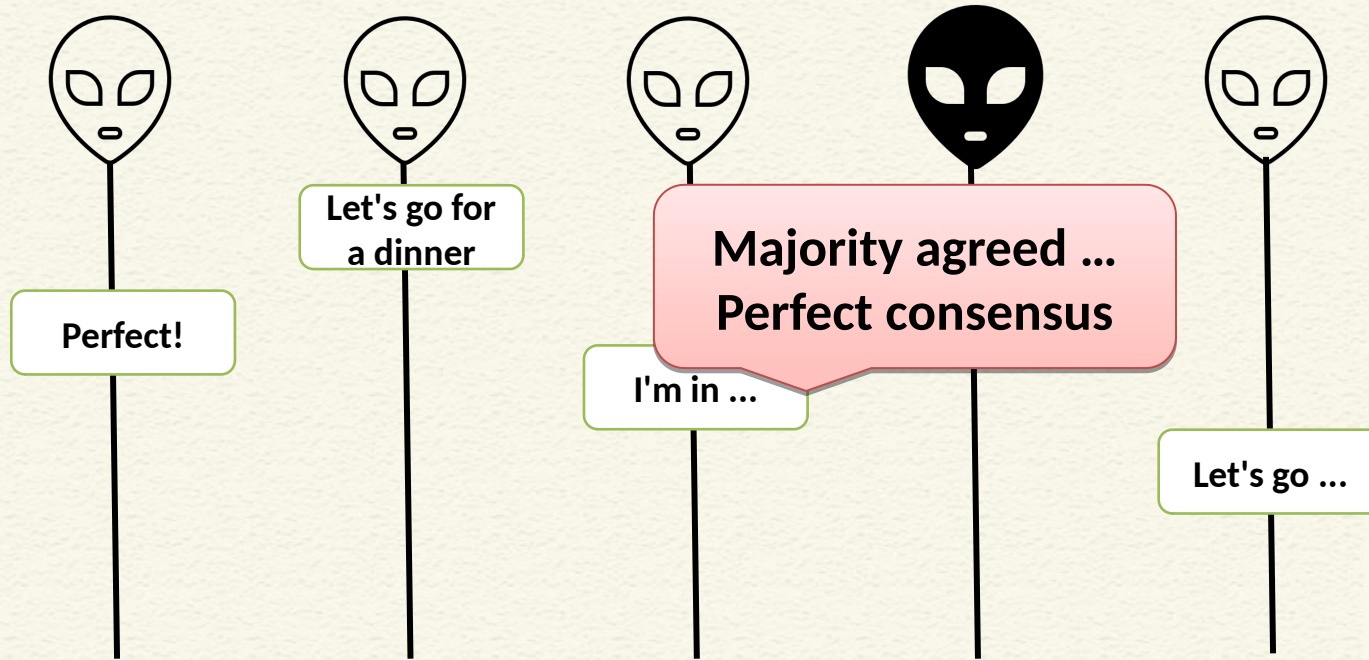
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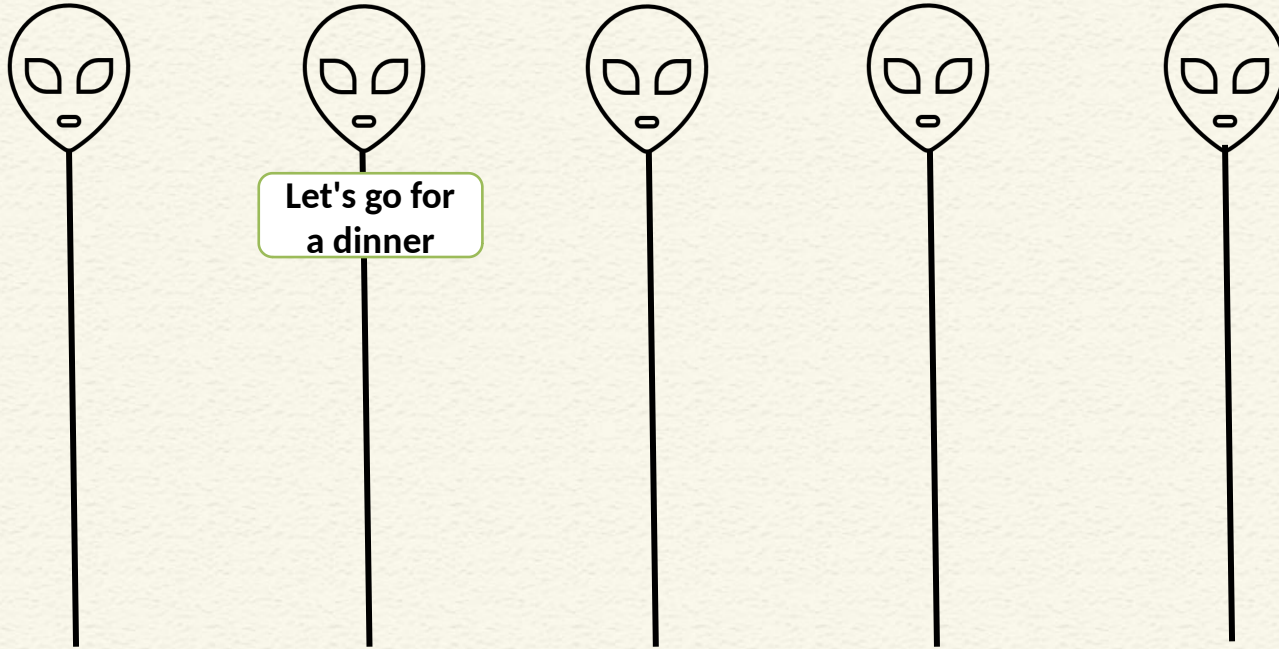
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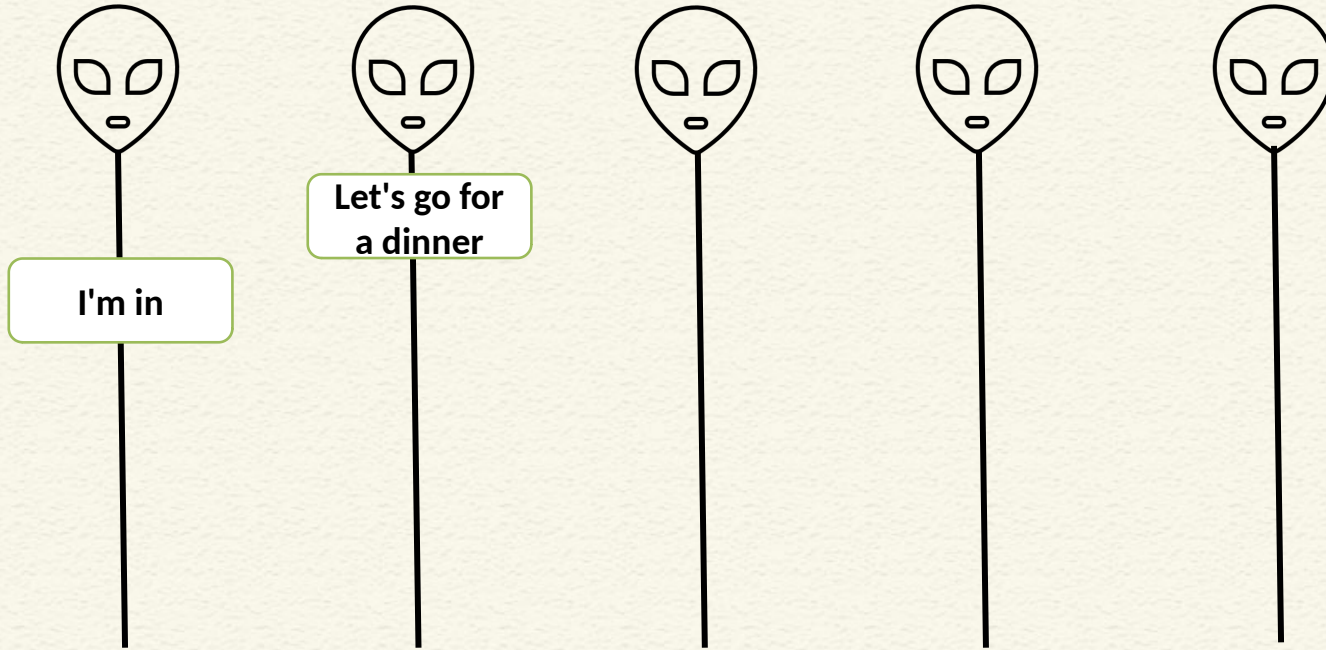
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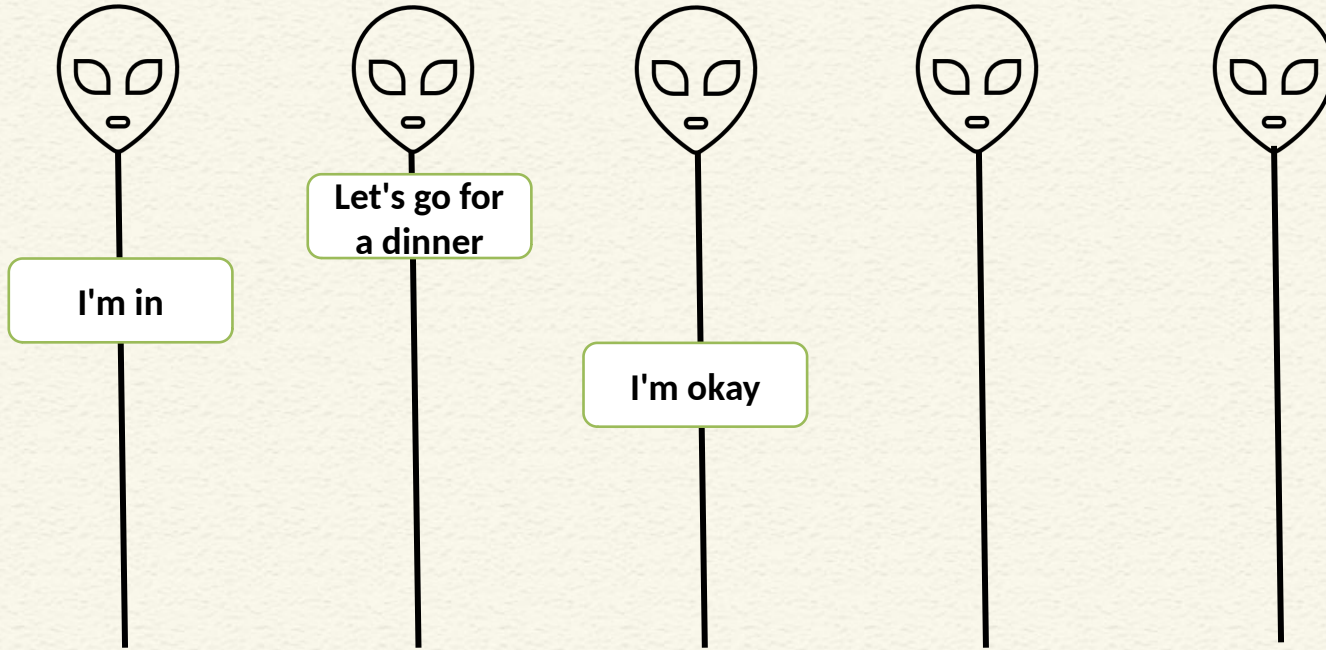
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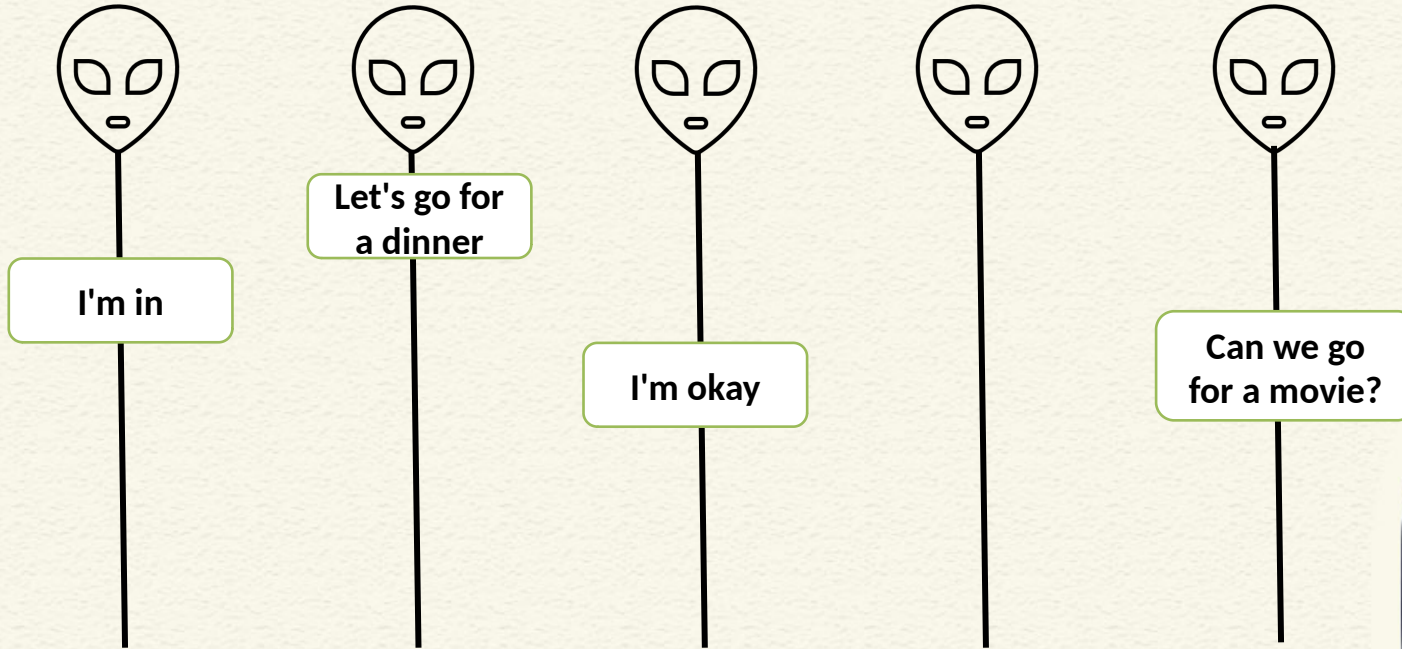
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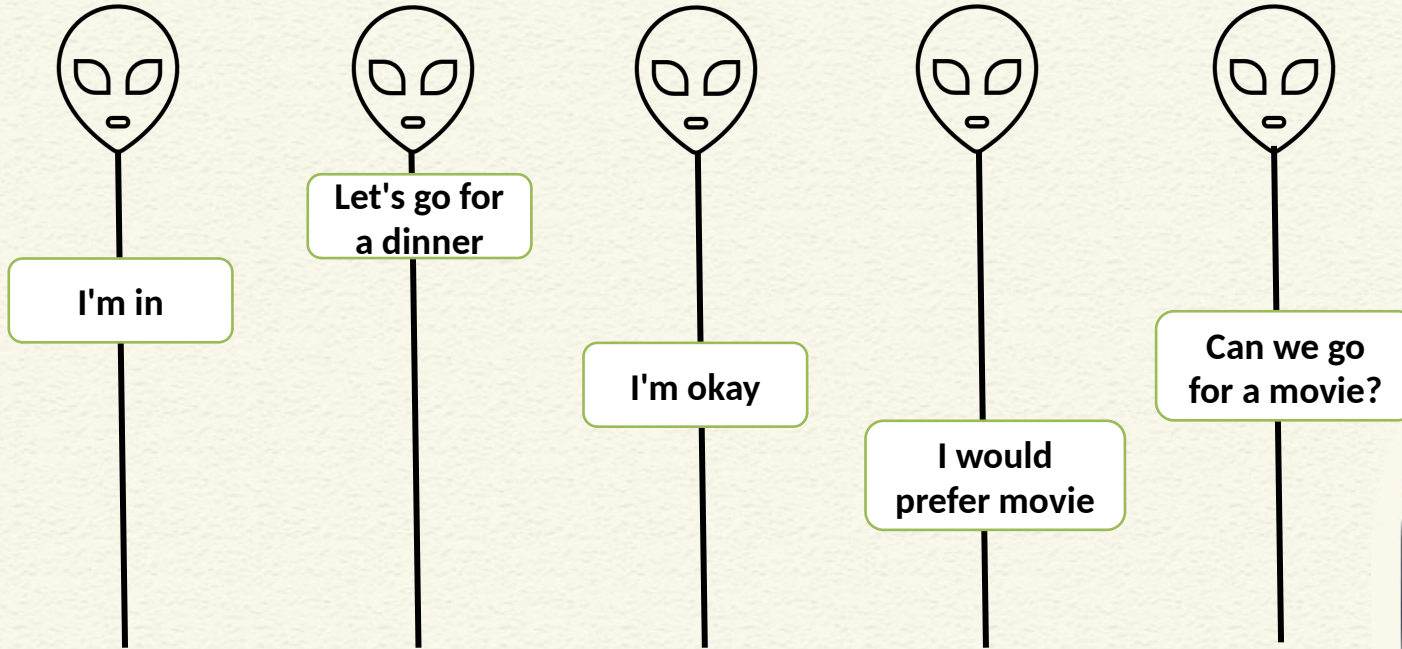
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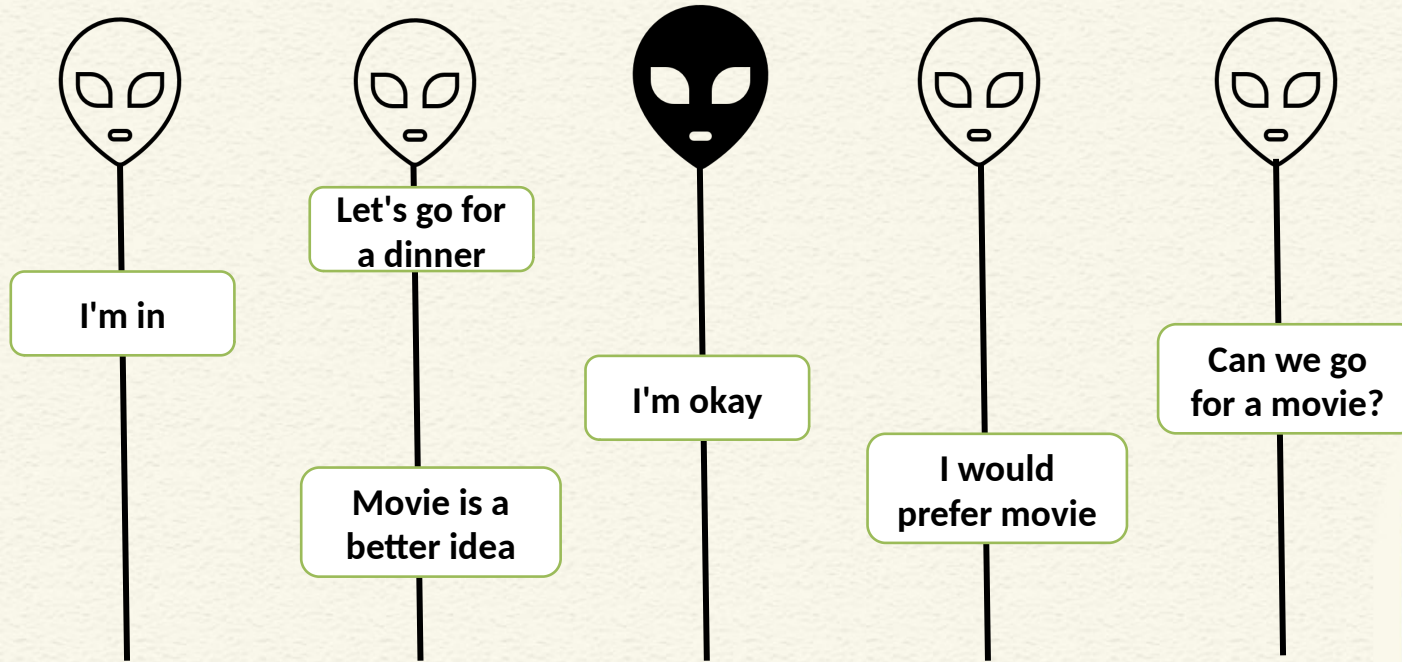
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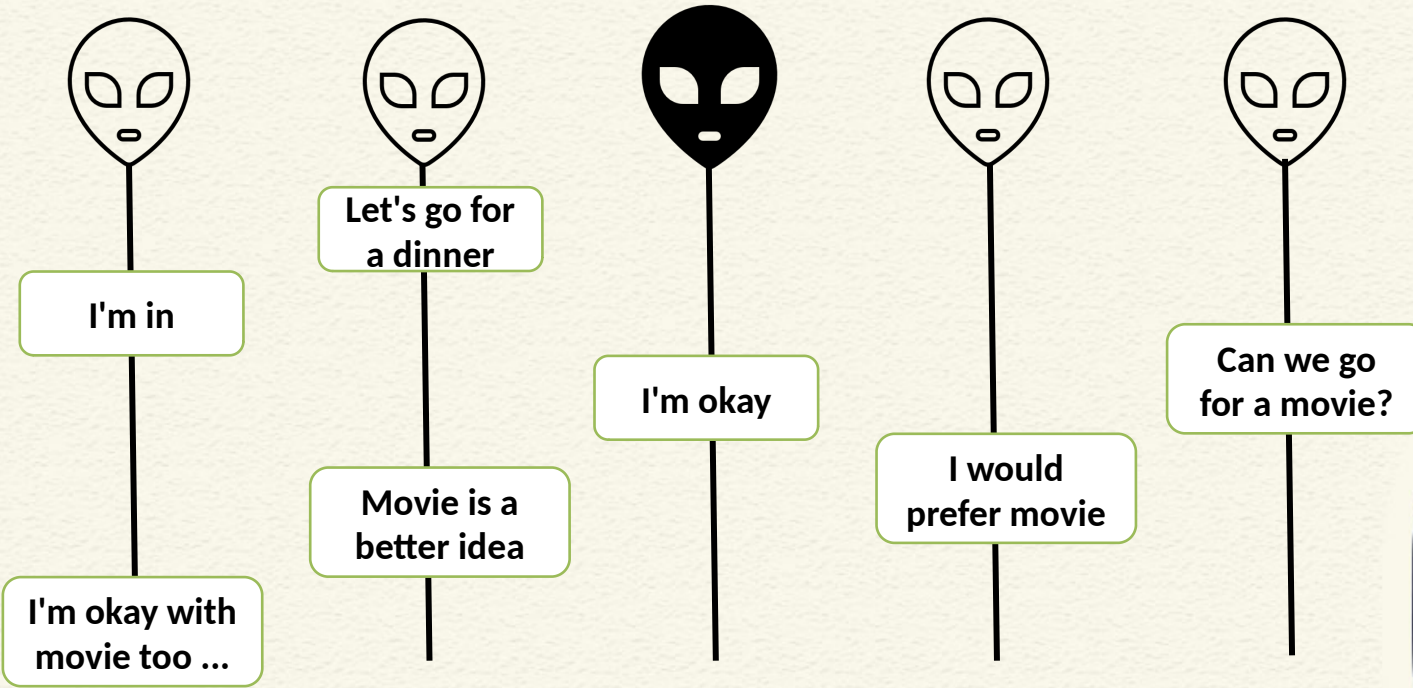
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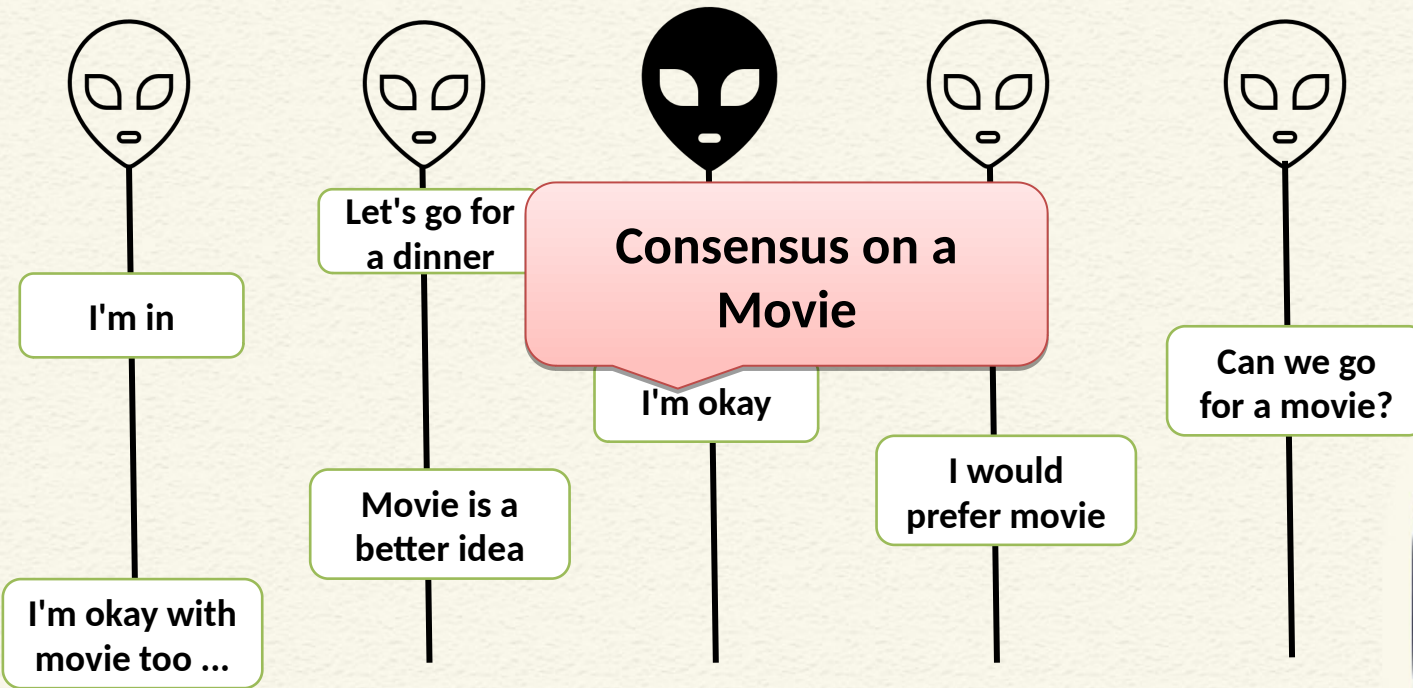
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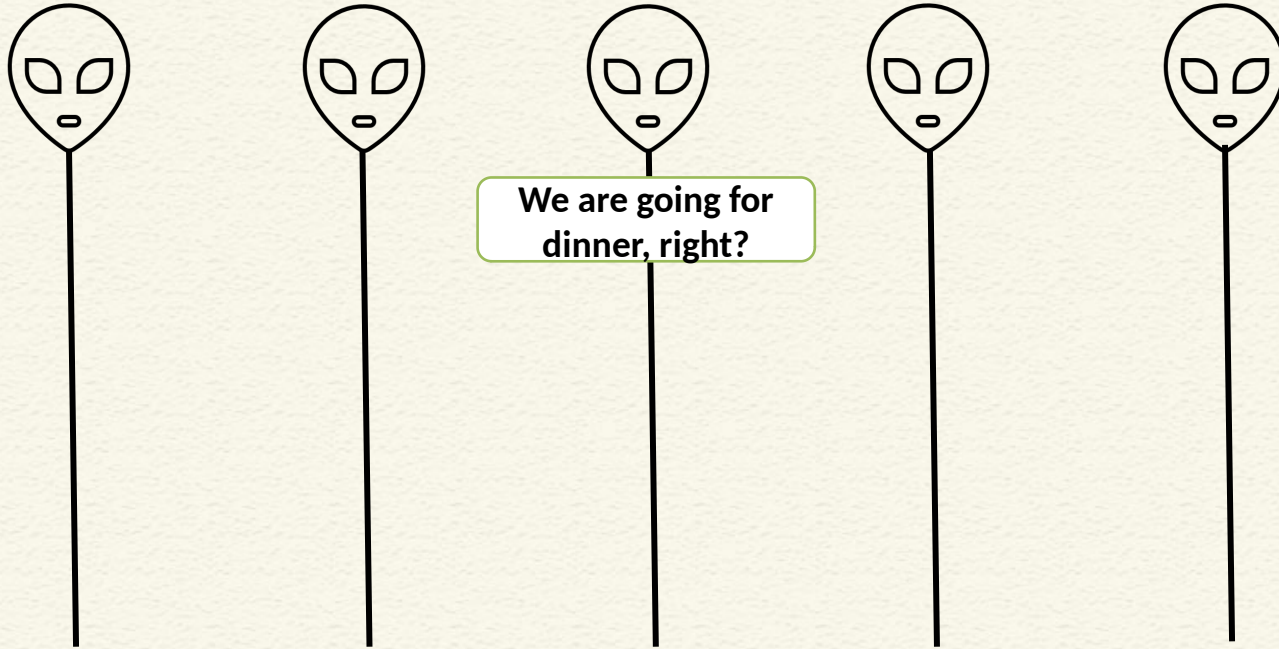
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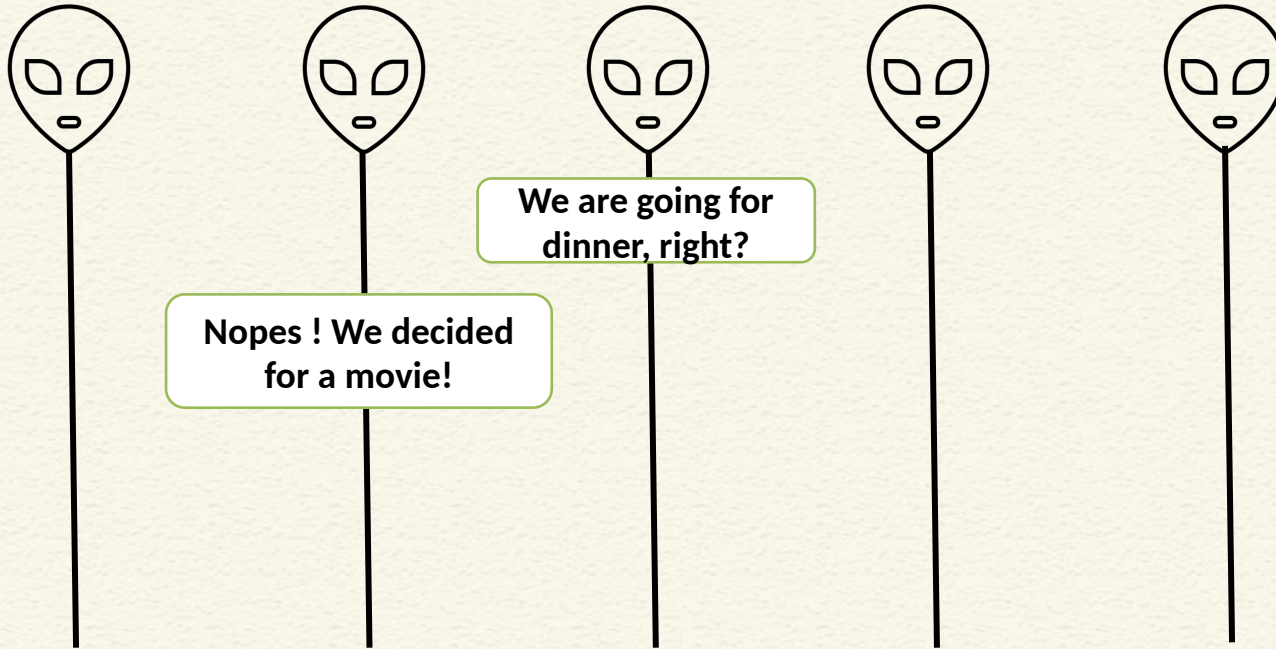
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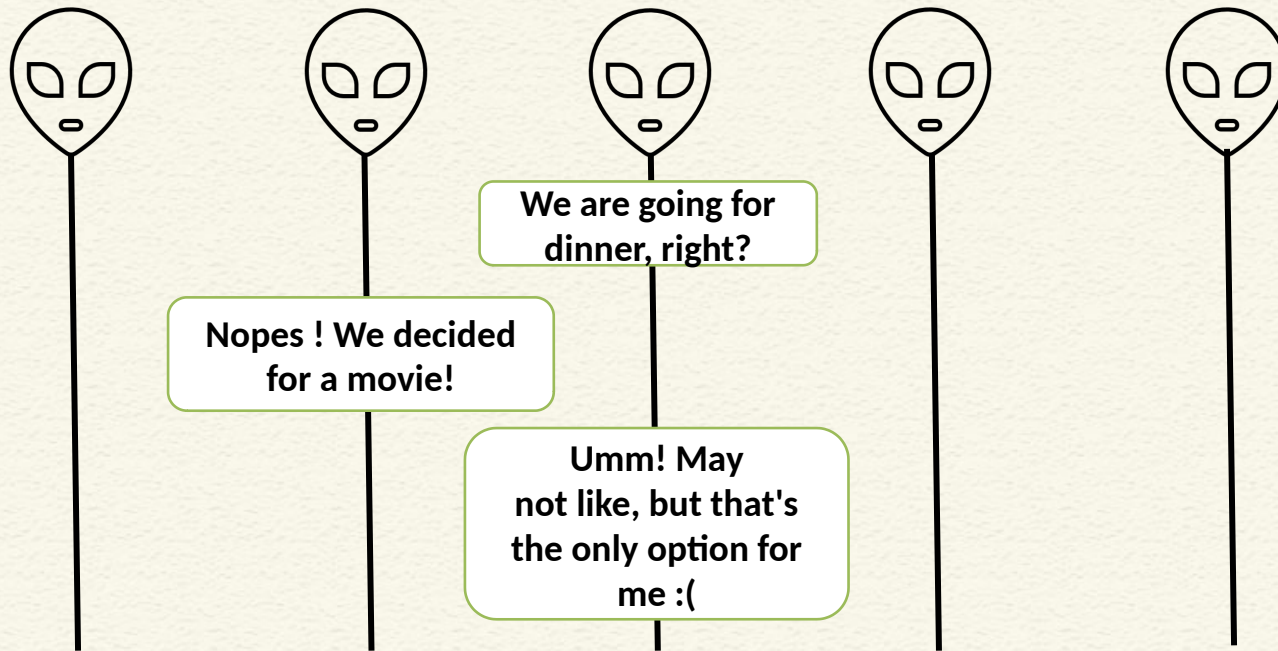
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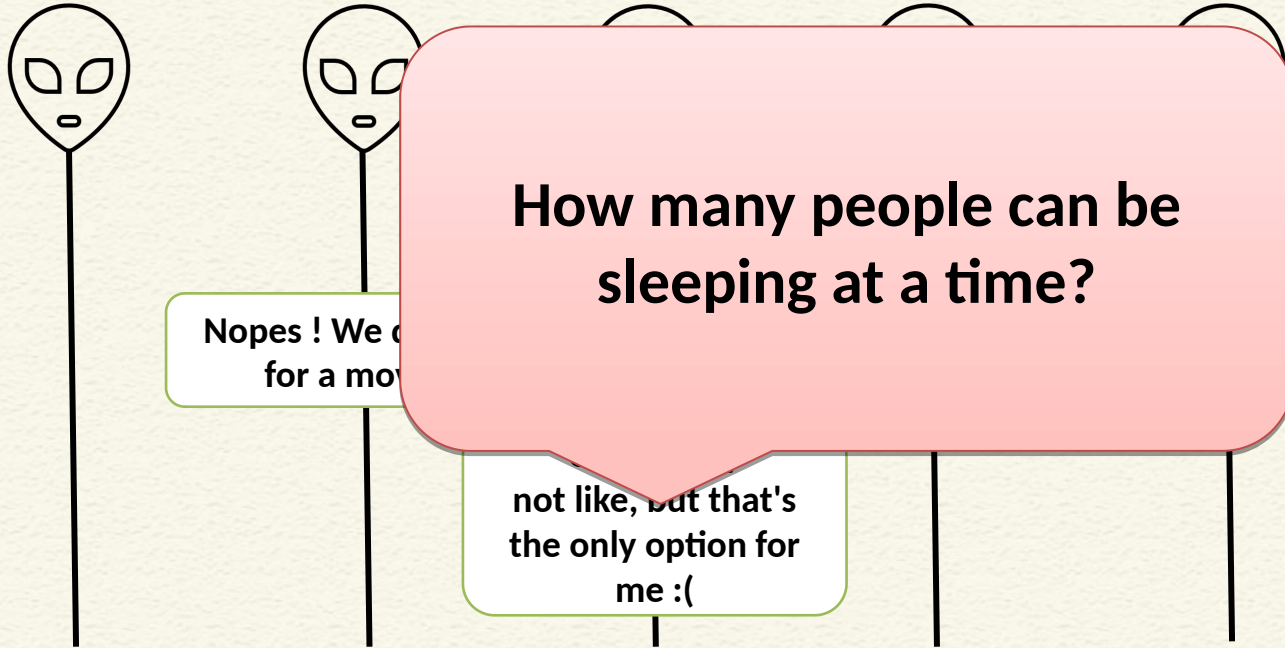
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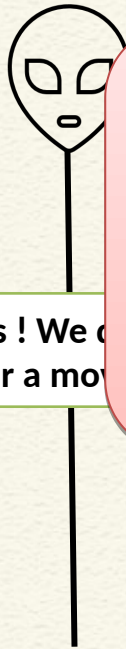
CFT in an Asynchronous System



CFT in an Asynchronous System



CFT in an Asynchronous System



Nopes ! We c
for a mo

How many people can be
sleeping at a time?

2

not like, but that's
the only option for
me :(



Asynchronous CFT

- If there are F faulty nodes (crash fault), we need at least $2F+1$ nodes to reach consensus
- **Paxos:** A family of distributed algorithms to reach consensus in an asynchronous CFT



What is Paxos?

- We'll discuss vanilla Paxos
- Proposed by Lamport in 1989
- Received a lot of criticism about its proof of correctness
- Accepted in ACM Transactions on Computer Systems in 1998, titled "*The Part-time Parliament*"
- Lamport received the Turing award in 2013



Conclusion

- Consensus is harder on asynchronous environment
- For asynchronous CFT, we need $2F+1$ nodes with F crash faults only
- Let's explore Paxos in the next class



*Thank
you*

