## Mid-semester Examination (2024-25 Spring)

## Computational Geometry (CS60064)

Answer all. Duration = 2 hours. Full marks = 60.

Note: Unless mentioned, the following should be assumed about an input.

- Points are all distinct, no three being collinear, and no four being concyclic.
- A polygon is simple, i.e., edges intersect each other only at their endpoints, and it is described as clockwise or counter-clockwise sequence of its vertices, starting from an arbitrary vertex.
- 1. Write the worst-case time complexities of the best-known algorithms for the following problems. Just write the complexities, no explanation required.  $1\frac{1}{2} \times 10 = 15$  marks
  - (i) Given a set S of n points, construct a polygon with S as the vertex set.  $O(n \log n)$
  - (ii) Given a polygon with n vertices, check whether it is convex. O(n)
  - (iii) Given a polygon with n vertices, check whether it is monotone w.r.t. x-axis. O(n)
  - (iv) Given a convex polygon P with n vertices and a query point q, check whether q lies in P.
  - (v) Given a set S of n line segments, construct its convex hull.  $O(n \log n)$
  - (vi) Given two non-intersecting convex polygons P and Q with m and n vertices respectively, compute their joint convex hull. O(m+n)
  - (vii) Given a convex polygon P with n vertices and a point q inside P, check whether q lies on a diameter of P.
  - (viii) Given two convex polygons P and Q with n vertices each, check whether P contains Q.
  - (ix) Make a triangulation of a polygon with n vertices.  $O(n \log n) \text{ [conventional] or } O(n) \text{ [unconventional, no implementation is found].}$ You get credit for writing either one.
  - (x) Given a polygon P with n vertices and two vertices s and t of P, compute the Euclidean shortest path from s to t, contained in P.  $O(n \log n)$
  - **Sol.:** Triangulate P, construct its dual graph G = (V, E), then compute the shortest path (Dijkstra's algorithm) from the triangle of s to that of t. As G is planar, |V| = |E| = O(n), and so the runtime will be  $O(|E| + |V| \log |V|) = O(n \log n)$ .

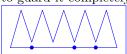
2. Answer in brief.

 $2\frac{1}{2} \times 6 = 15$  marks

(i) Draw a set of 8 points such that its convex hull has exactly 3 vertices.

Easy

- (ii) Draw a polygon with 8 vertices such that it is both x-monotone and y-monotone. Convex polygon
- (iii) Draw an art gallery (polygon) with at most 11 vertices such that 3 cameras are necessary to guard it completely.



- (iv) Recall the algorithm for computing intersection points among n given line segments. Mention the data structures used in the algorithm, and state the total time complexity for all operations performed on each of them.
- Sol.: Event queue Q as a balanced BST:

Initial construction:  $O(n \log n)$  time for 2n endpoints;  $|Q| \le 2n + O(n^2) = O(n^2) \implies$  any search / delete / insert time is  $O(\log n) \implies$  total time is  $O(k \log n)$ , where k = #intersections.

Sweep-line data structure  $T_{\lambda}$  as a balanced BST:

At most n segments when any event is processed.

O(n+k) event points in total. Any operation takes log time. So, total time for search + delete + insert is  $O((n+k)\log n)$ .

- (v) Is subdivision of a polygon into x-monotone polygons unique? Justify. No, easy to show.
- (vi) How many different triangulations are possible for a convex hexagon? Hint: A convex quadrilateral ABCD has two different triangulations:  $\{\triangle ABD, \triangle BCD\}$  and  $\{\triangle ABC, \triangle ACD\}$ . A convex pentagon has 5 different triangulations.
- **Sol.:** Consider vertex 1. Denote by ij the line segment joining the vertices i and j. Denote by f(D) the number of triangulations when D is a mandatory list of diagonals. Two cases:
  - i.  $D = \{26\} \implies f(26) = 5$ .
  - ii.  $26 \not\in D$ , i.e., vertex 1 is an endpoint of a diagonal. Applying principle of inclusion-exclusion,  $f(26 \not\in D) = f(13) + f(14) + f(15) f(13,14) f(14,15) f(13,15) + f(13,14,15) = 5 + 4 + 5 2 2 2 + 1 = 9$ .

So, total count = 5 + 9 = 14.

**3.** Given a set S of n points on the plane, suggest an efficient algorithm to find a farthest pair of points in S.

Justify its correctness and deduce its time complexity.

 $5+3+2=10~\mathrm{marks}$ 

- **Sol.:** Find the convex hull of S and then find its diagonal in linear time using the algorithm given in Assignment 3. Total time  $= O(n \log n)$ .
  - **4.** Suppose P is a polygon with  $n \geq 4$  vertices, and let T(P) be any triangulation of P. A triangle uvw in T(P) is called a *pendant triangle* if its vertices u, v, w are consecutive along the boundary of P.

Prove or disprove: Every triangulation T(P) contains at least two pendant triangles. 10 marks

**Sol.:** For i = 0, 1, 2, let  $n_i$  denote the number of triangles in T(P), such that for each of them, each exactly i edges are edges of P and the rest are diagonals. If P has n vertices, then

number of triangles in 
$$T(P) = n_0 + n_1 + n_2 = n - 2$$
.

Each diagonal is shared by exactly two triangles, and hence,

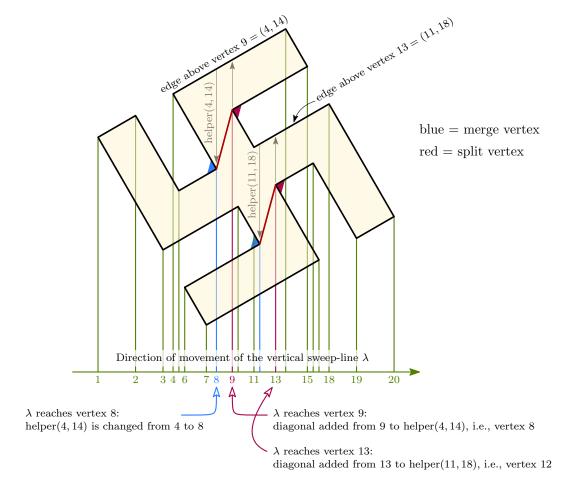
$$3n_0 + 2n_1 + n_2 = 2 \cdot \#\text{diagonals} = 2(n-3) = 2n-6.$$

Multiplying the first equation by 2 and subtracting the second from that,

$$-n_0 + n_2 = 2 \implies n_2 = n_0 + 2 \implies n_2 \ge 2.$$

5. Determine the diagonals in the x-monotone subdivision of the polygon given below, as per the algorithm discussed in the class. For clarity, vertex indices are shown below their projections on the x-axis in the diagram, with some omitted. These indices are according to their order of processing as the sweep-line moves from left to right.

You need not redraw the polygon on your answer sheet if it is time-consuming. Instead, list each diagonal as (i, j), where i and j are vertex indices, and justify its inclusion. Also explain how and from where the necessary information is obtained.



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