MATH 313: LINEAR ALGEBRA - HOMEWORK 5

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(1) Learn the precise definitions of the following:

- (a) Group
- (b) Abelian group
- (c) Ring
- (d) Commutative ring
- (e) Field
- (f) Vector space
- (2) Consider the matrices

$$C = \begin{pmatrix} 9 & -1 & 4 \\ 3 & 0 & 2 \end{pmatrix}$$
 and $D = \begin{pmatrix} 1 & -13 \\ -2 & 5 \\ 0 & 8 \end{pmatrix}$.

Compute the following matrix transposes:

$$C^t$$
, D^t , C^tD^t , $(CD)^t$, D^tC^t .

(3) Compute (if possible) the inverses of the following matrices:

$$\begin{pmatrix} 2 & 7 \\ 3 & 5 \end{pmatrix}, \quad \begin{pmatrix} 2 & 6 \\ 3 & 5 \end{pmatrix}, \quad \begin{pmatrix} 2 & 6 \\ 3 & 9 \end{pmatrix}$$

(4) The integer special linear group $SL_2(\mathbf{Z})$ is the set of all 2×2 matrices (a) Prove that if $A, B \in SL_2(\mathbf{Z})$, then $AB \in SL_2(\mathbf{Z})$. (b) Prove that if $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL_2(\mathbf{Z})$, then A is invertible and $A^{-1} \in SL_2(\mathbf{Z})$.

 $SL_2(\mathbf{Z})$. Compute A^{-1} .

(5) Let $SL_2(\mathbf{R})$ be the set of all 2×2 matrices $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \operatorname{Mat}_2(\mathbf{R})$ such that ad - bc = 1. For $\theta \in \mathbf{R}$, let

$$R(\theta) = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}.$$

- (a) Prove that $R(\theta) \in SL_2(\mathbf{R})$.
- (b) Prove that, for all $\theta_1, \theta_2, \theta \in \mathbf{R}$,

$$R(\theta_1)R(\theta_2) = R(\theta_1 + \theta_2)$$

and

$$R(\theta)^{-1} = R(-\theta).$$

The rotation group SO(2) is the set of matrices $\{R(\theta): \theta \in \mathbf{R}\}$.

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- (6) The affine group $\mathcal{A}(\mathbf{R})$ is the set of all matrices of the form $\begin{pmatrix} r & x \\ 0 & 1 \end{pmatrix}$ with $r \in \mathbf{R} \setminus \{0\}$ and $x \in \mathbf{R}$.
 - (a) Prove that if $A, B \in \mathcal{A}(\mathbf{R})$, then $AB \in \mathcal{A}$.
 - (b) Prove that if $A = \begin{pmatrix} r & x \\ 0 & 1 \end{pmatrix} \in \mathcal{A}(\mathbf{R})$, then A is invertible and $A^{-1} \in \mathcal{A}(\mathbf{R})$. Compute A^{-1} .
- (7) The Heisenberg group $H_3(\mathbf{R})$ is the set of all 3×3 matrices of the form

$$\begin{pmatrix} 1 & a & c \\ 0 & 1 & b \\ 0 & 0 & 1 \end{pmatrix} \text{ with } a, b, c \in \mathbf{R}.$$

- (a) Prove that if $A, B \in H_3(\mathbf{R})$, then $AB \in H_3(\mathbf{R})$.
- (b) Prove that if $A \in H_3(\mathbf{R})$, then A is invertible and $A^{-1} \in H_3(\mathbf{R})$. Compute A^{-1} .
- (8) Solve the following systems of linear equations by using elementary row operations to put the augmented matrix into reduced row echelon form.

 (a)

(9) Compute the reduced row echelon form of the matrix

$$A = \begin{pmatrix} 2 & 0 & 5 & -1 \\ 1 & -1 & 10 & 5 \\ 3 & 1 & 0 & -7 \end{pmatrix}$$

(10) Let A be an $n\times n$ matrix. Let k and ℓ be postive integers. Use mathematical induction to prove that

$$A^k A^\ell = A^{k+\ell}$$
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