

# CMP 334 (4/10/19)

## TOY processor redesign

- Single cycle instruction execution (review)

- Datapath (separate instruction & data memory)

- Control signals

- Pipeline instruction execution implementations

## Processor performance

- Performance equations (review)

- HW 13, HW 14

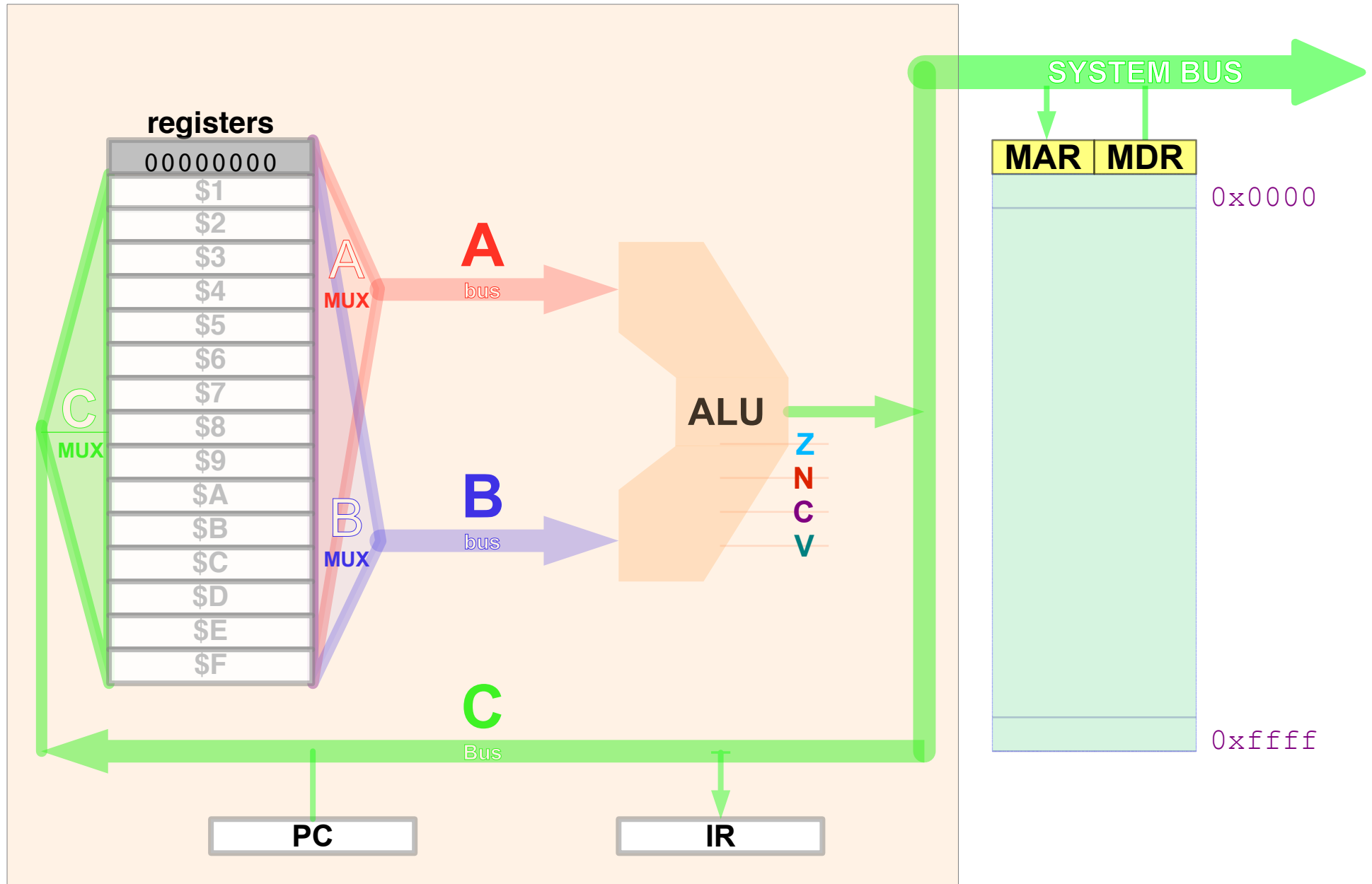
## Pipeline hazards

- Structural hazards

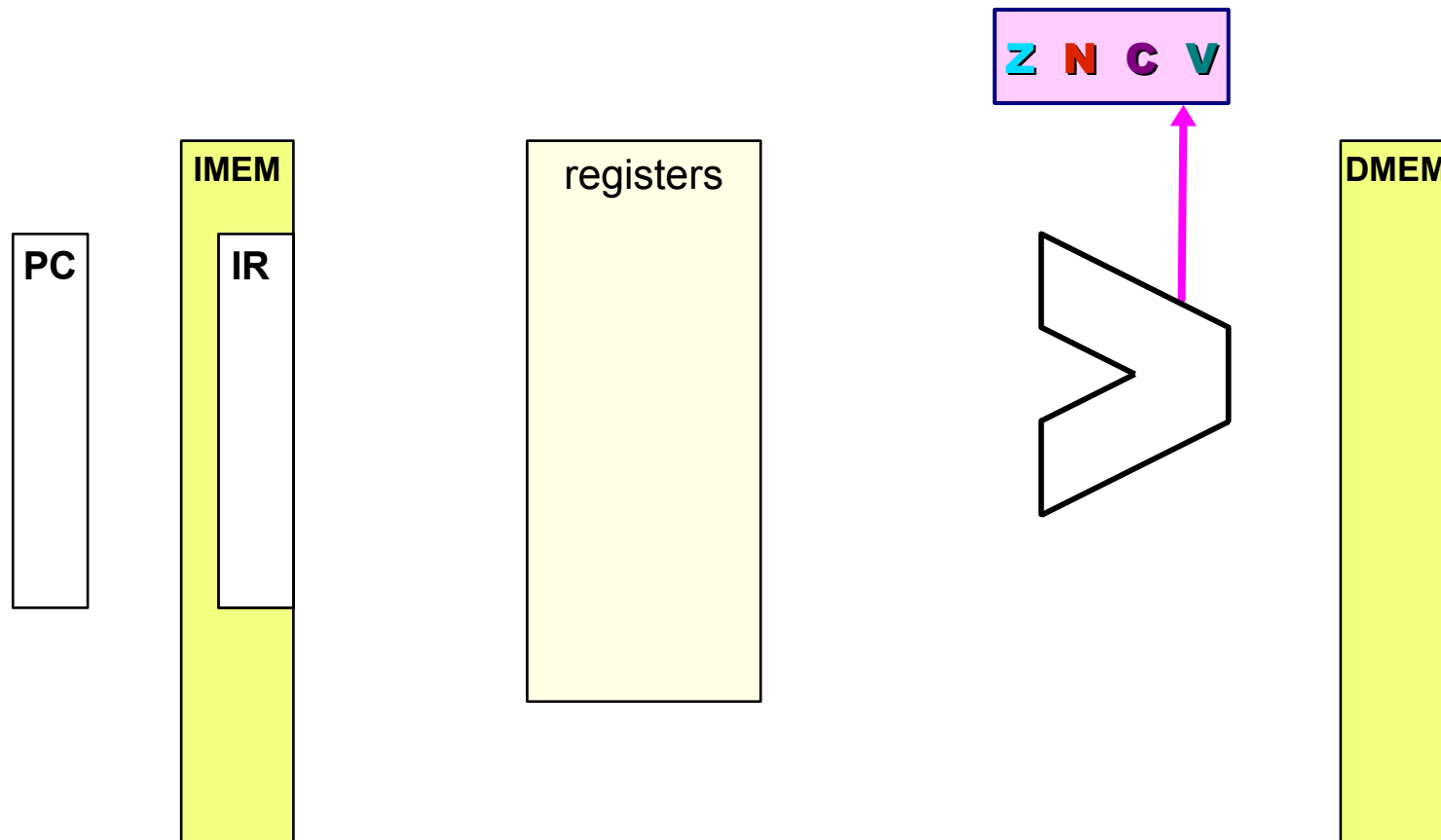
- Data hazards

- Control hazards

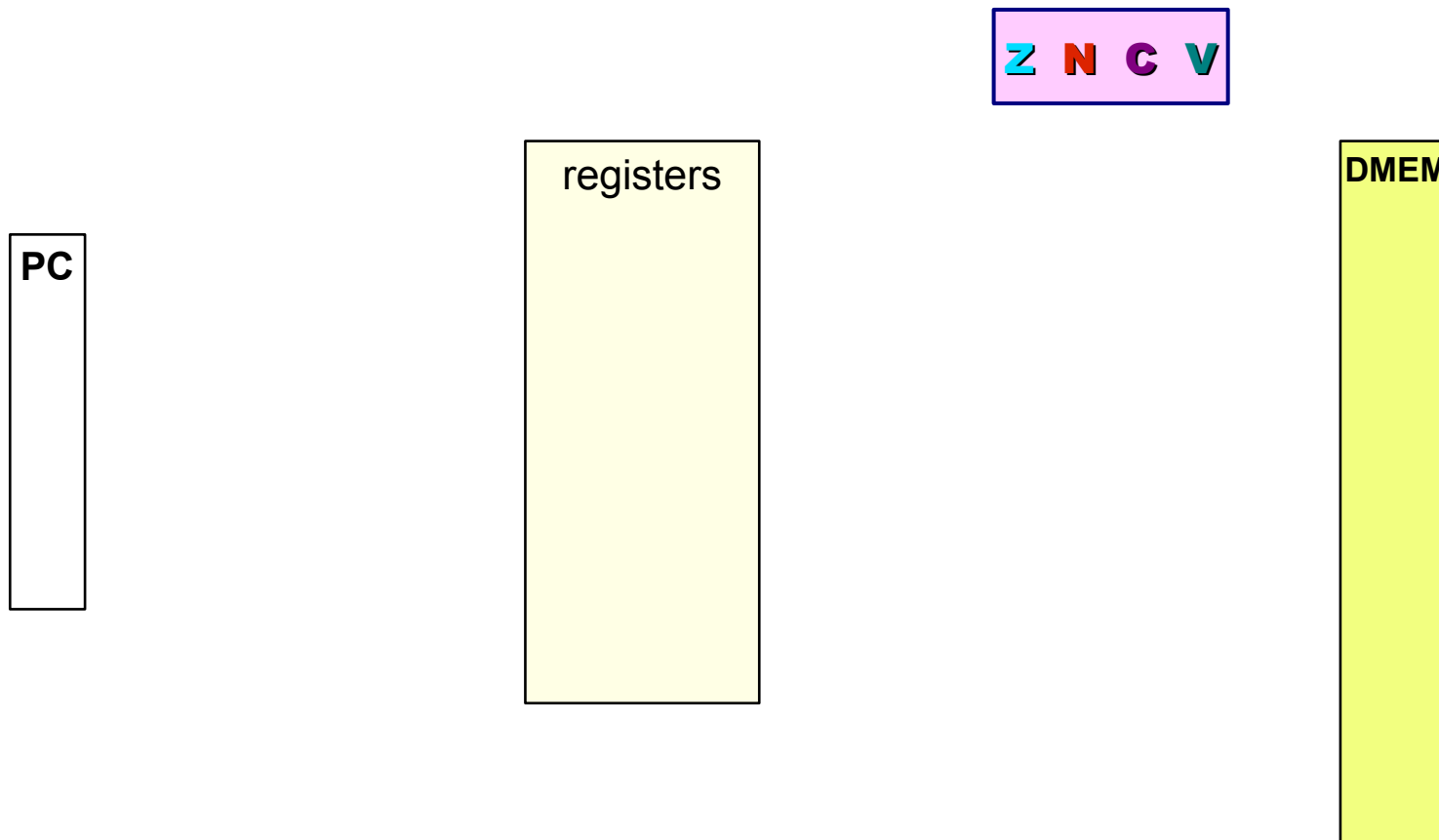
# TOY ISA Simple Implementation



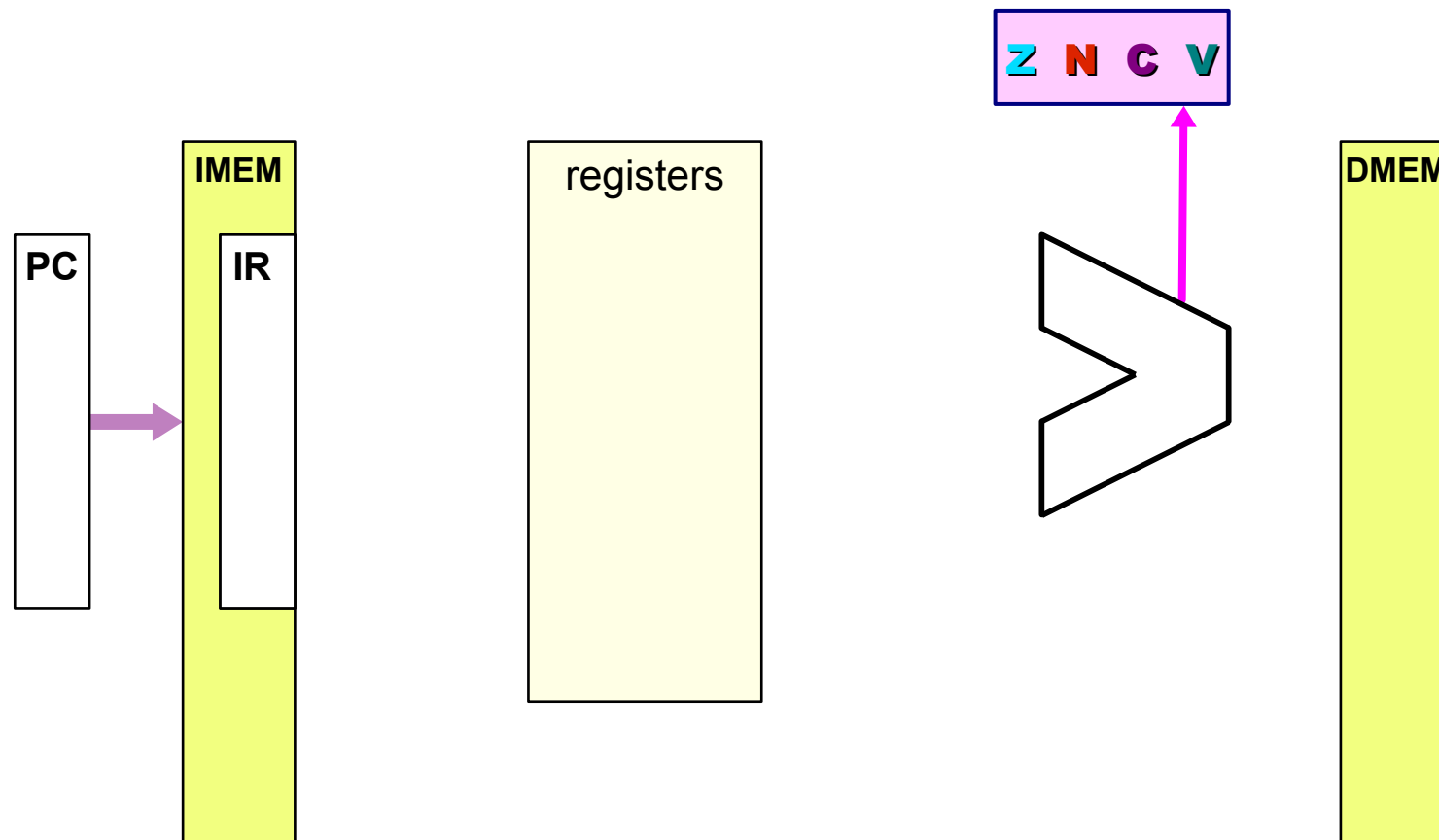
# TOY Processor Redesign



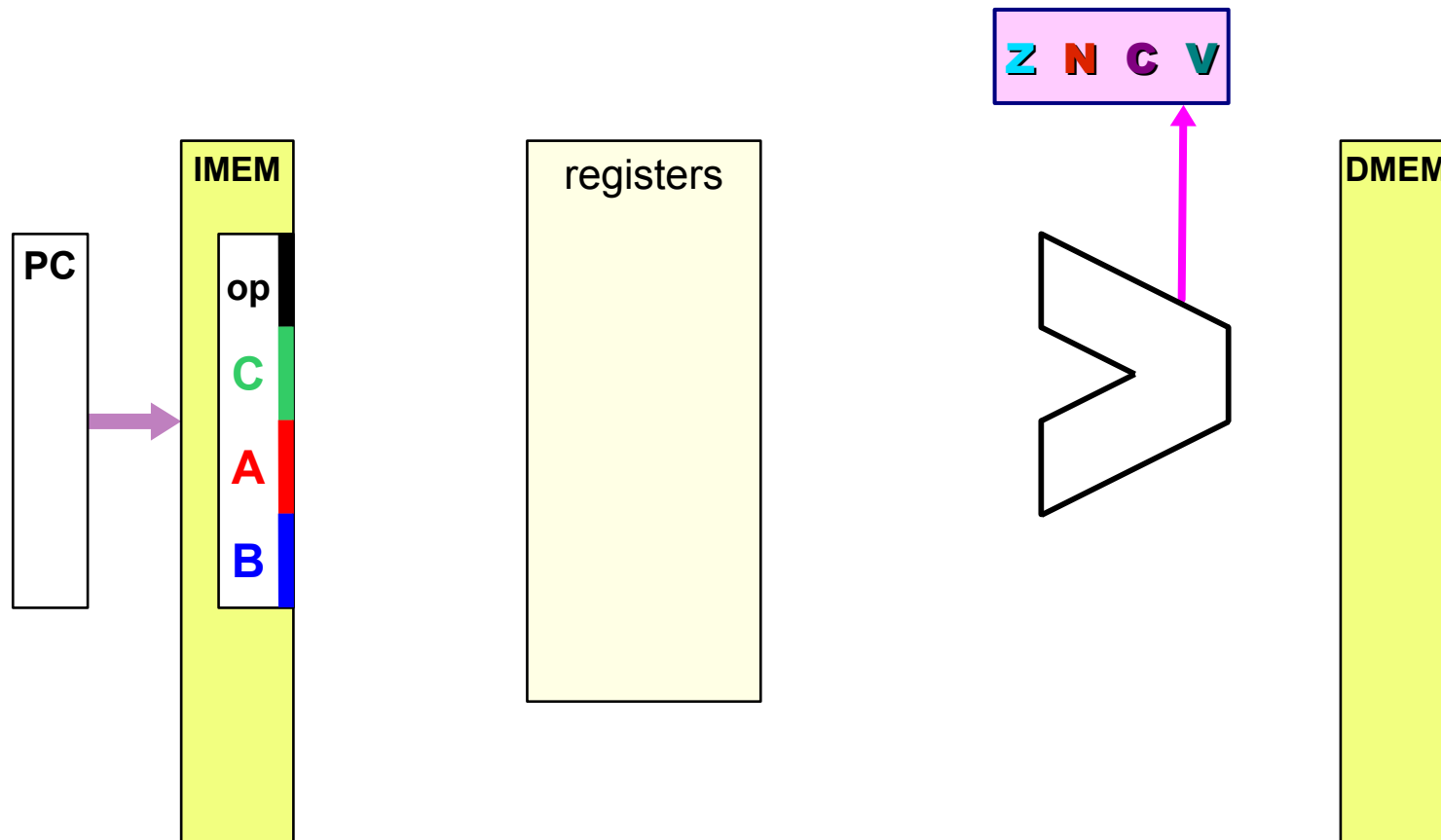
# Redesign Memory Elements



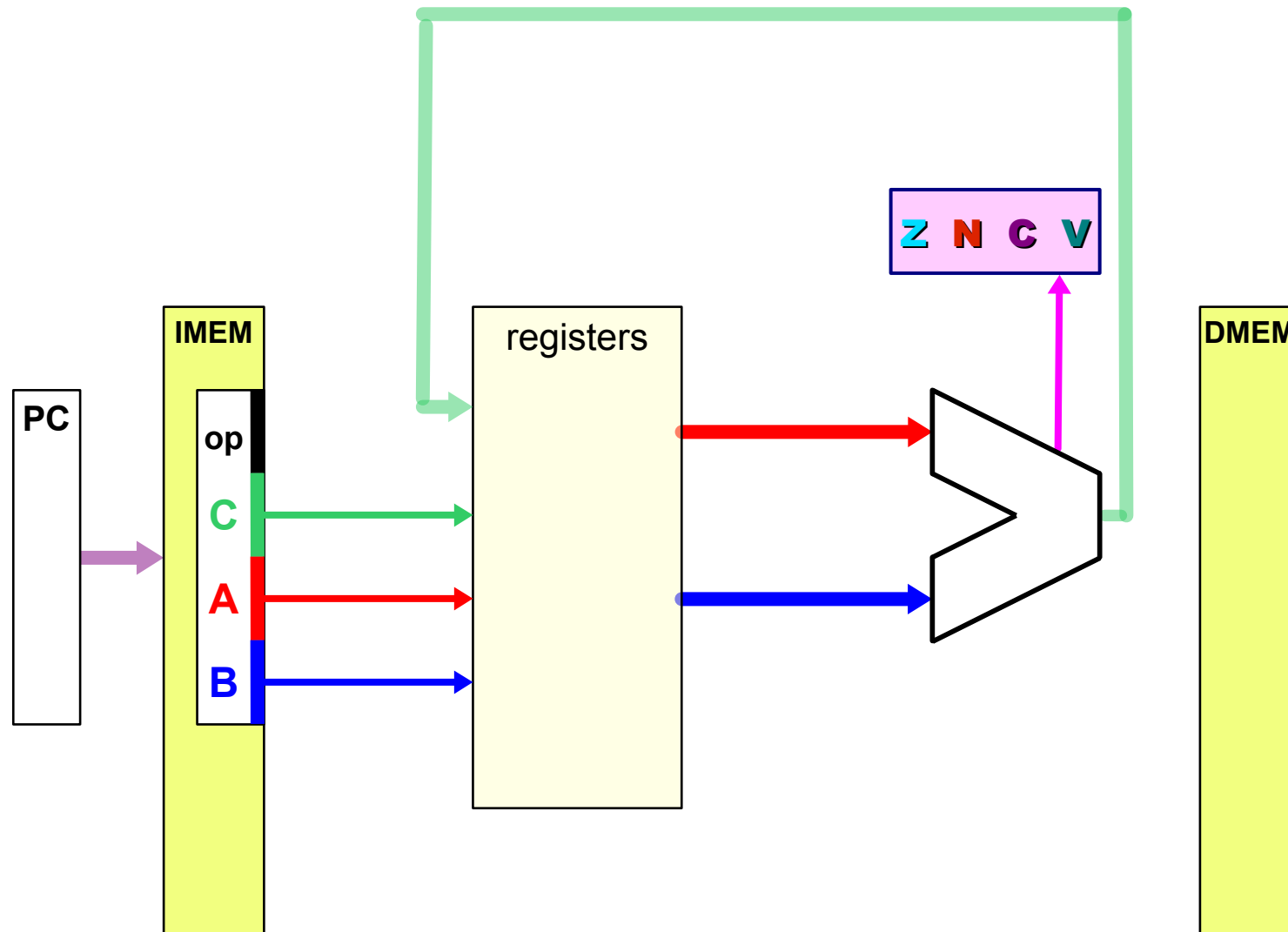
# Support for Instruction fetch



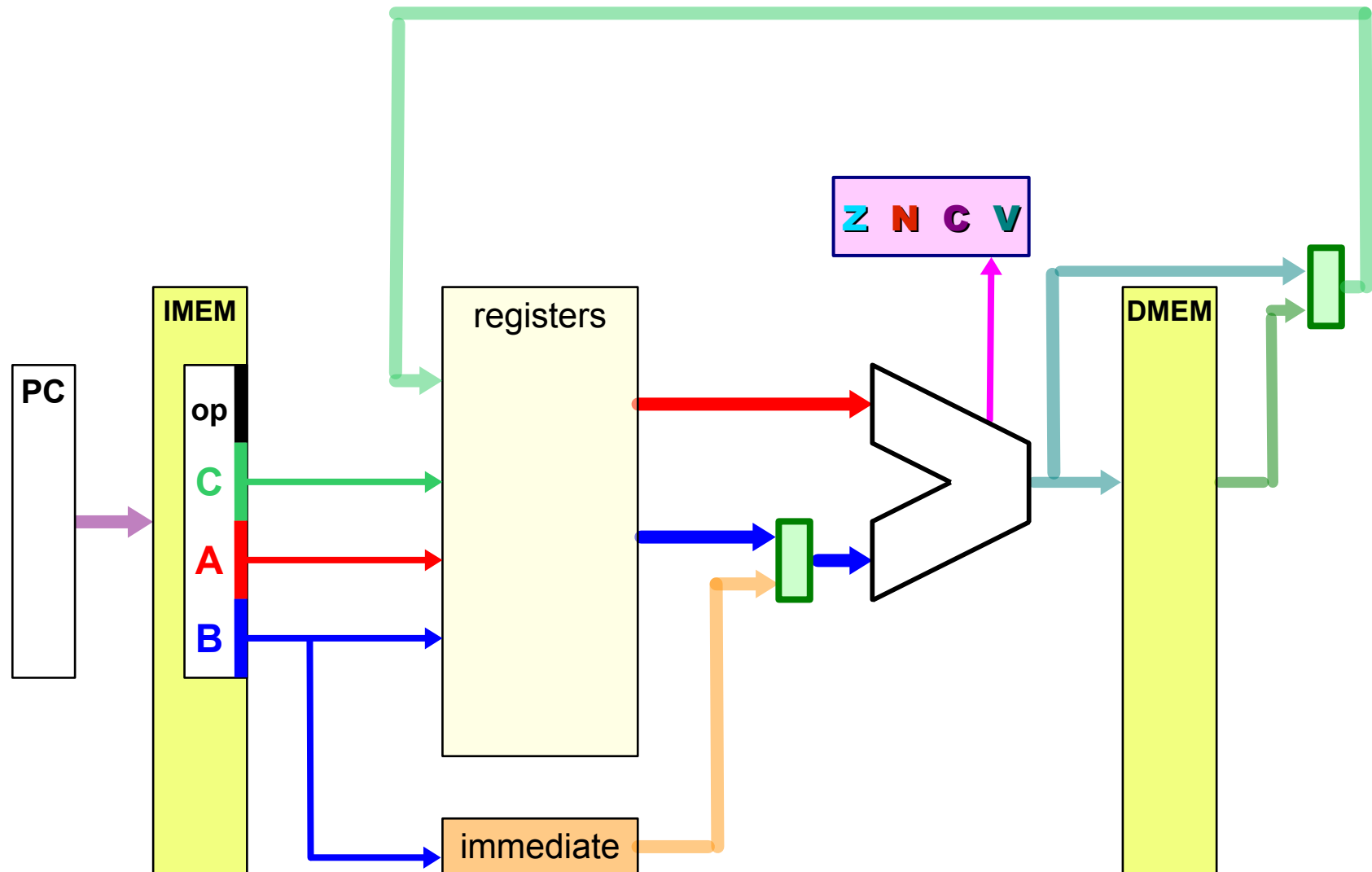
# TOY Redesign IR



# Support for ALU Instructions

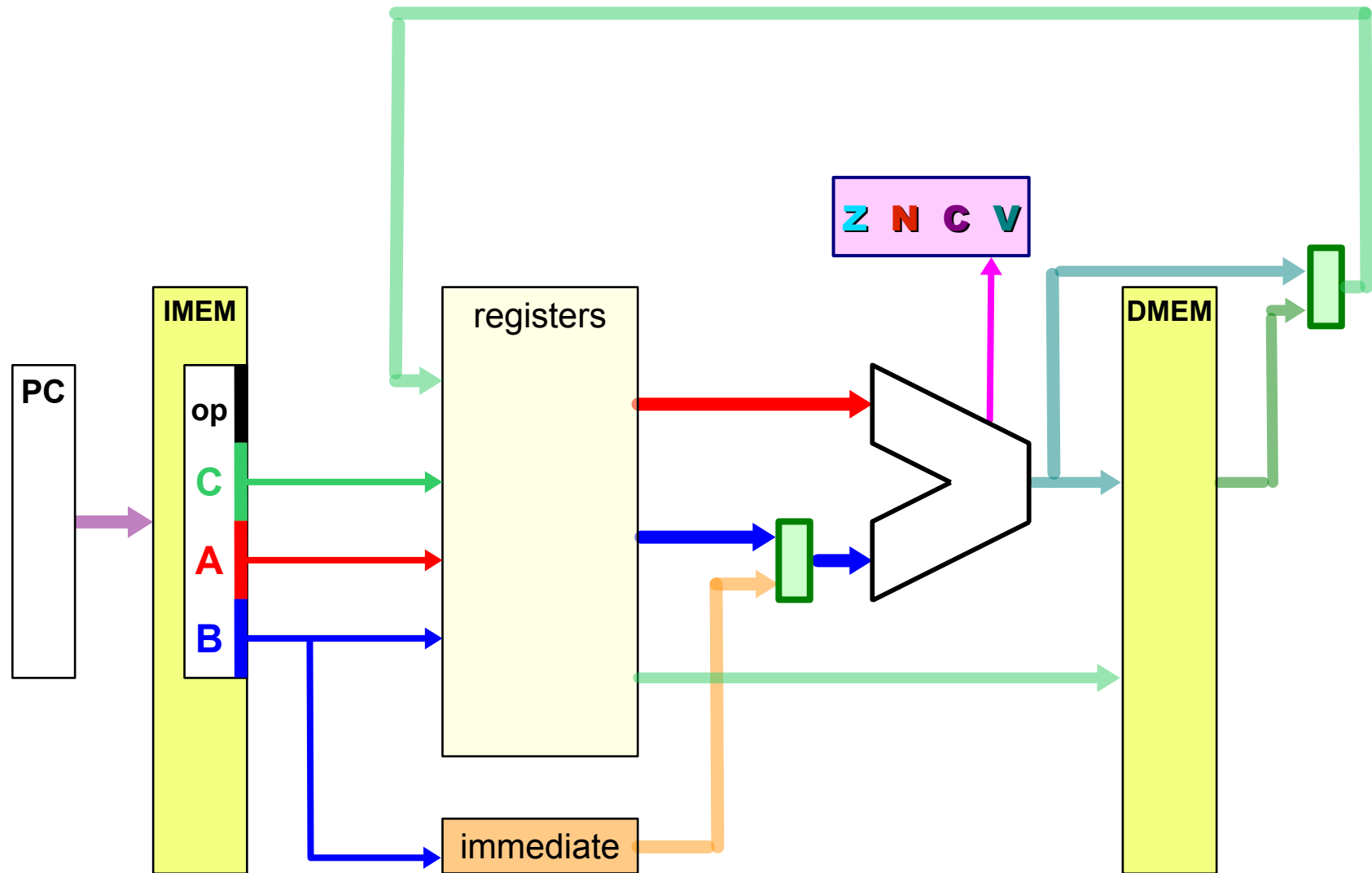


# Support for `load` Instruction

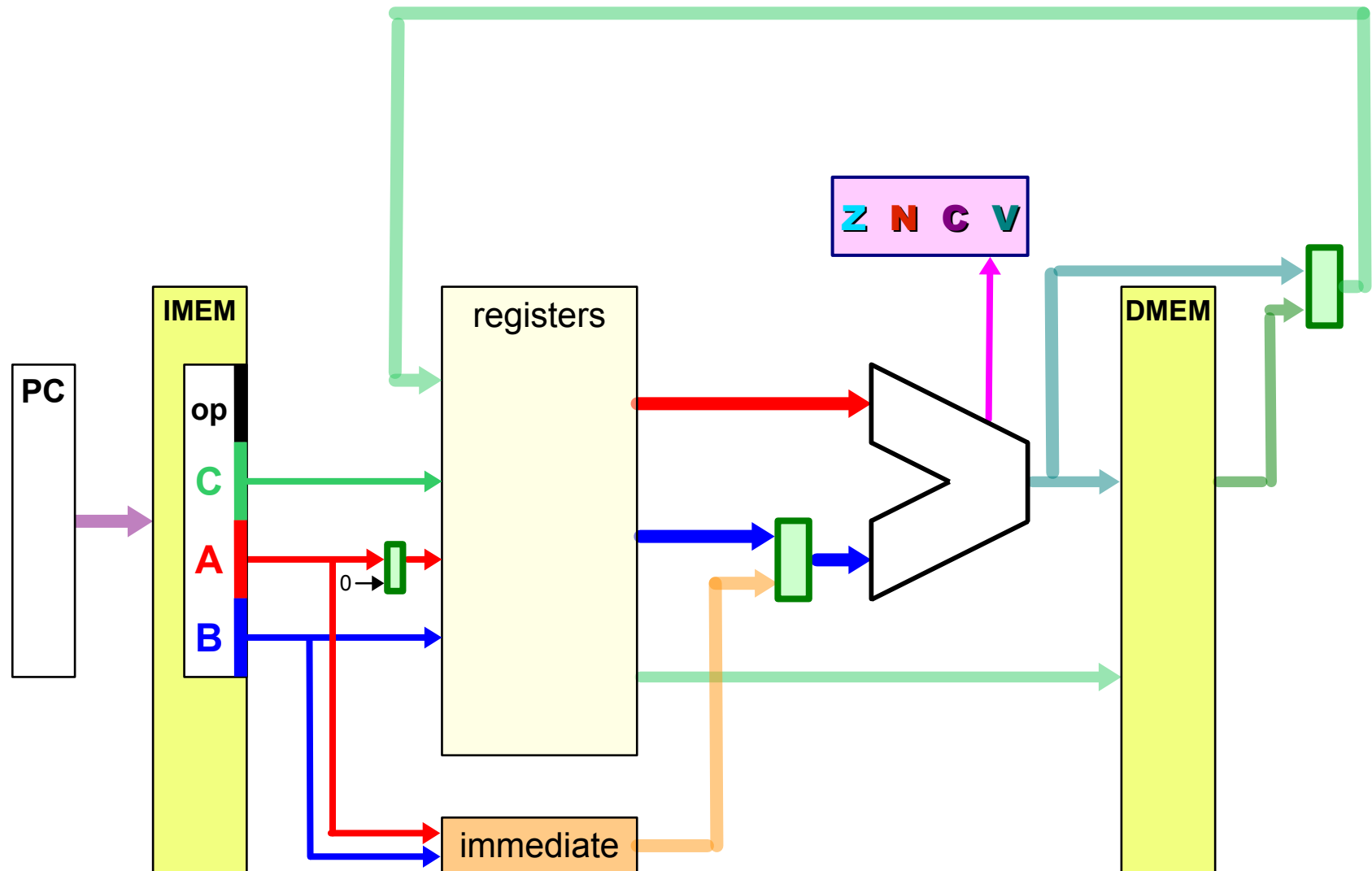




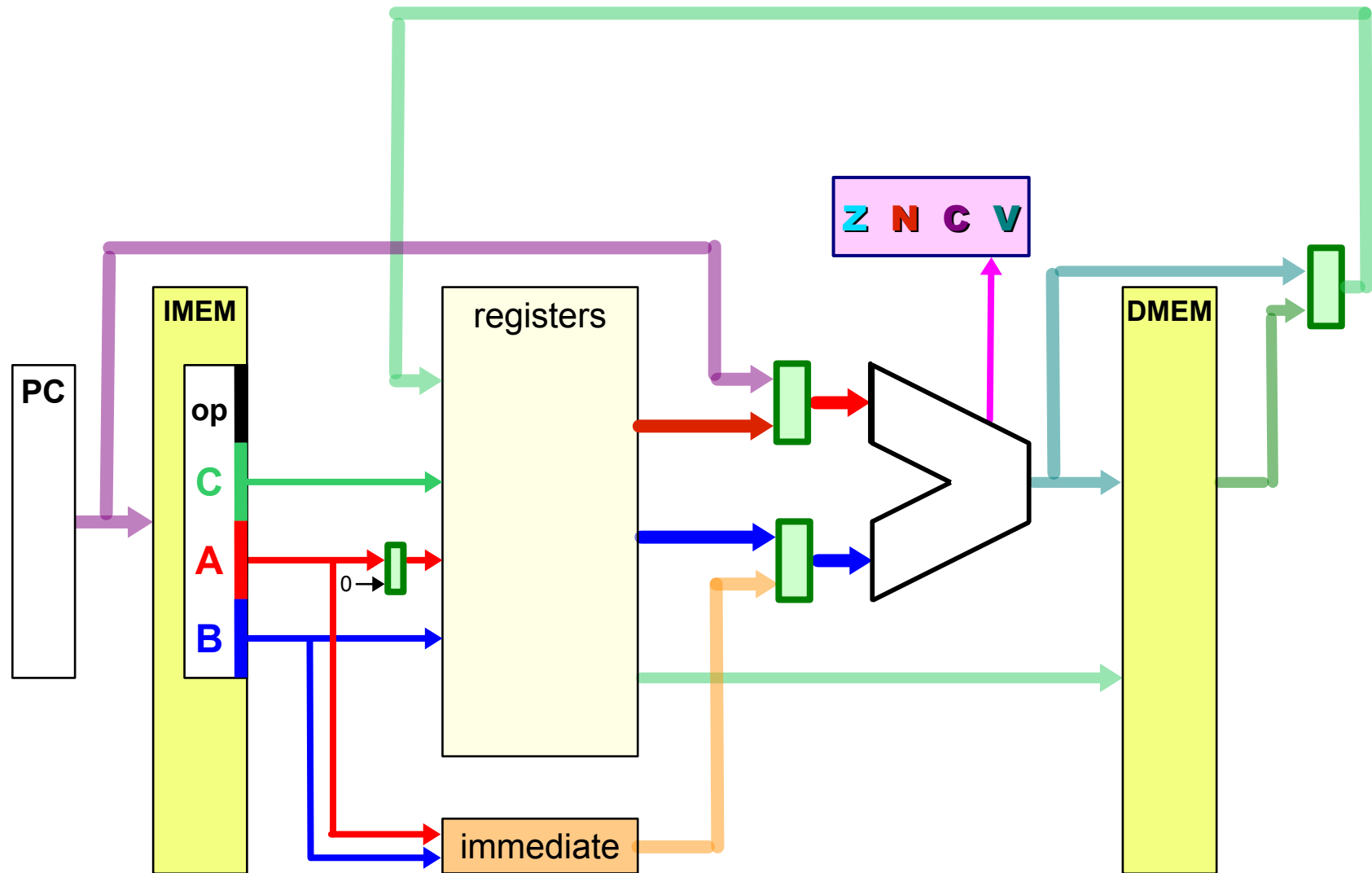
# Support for `store` Instruction



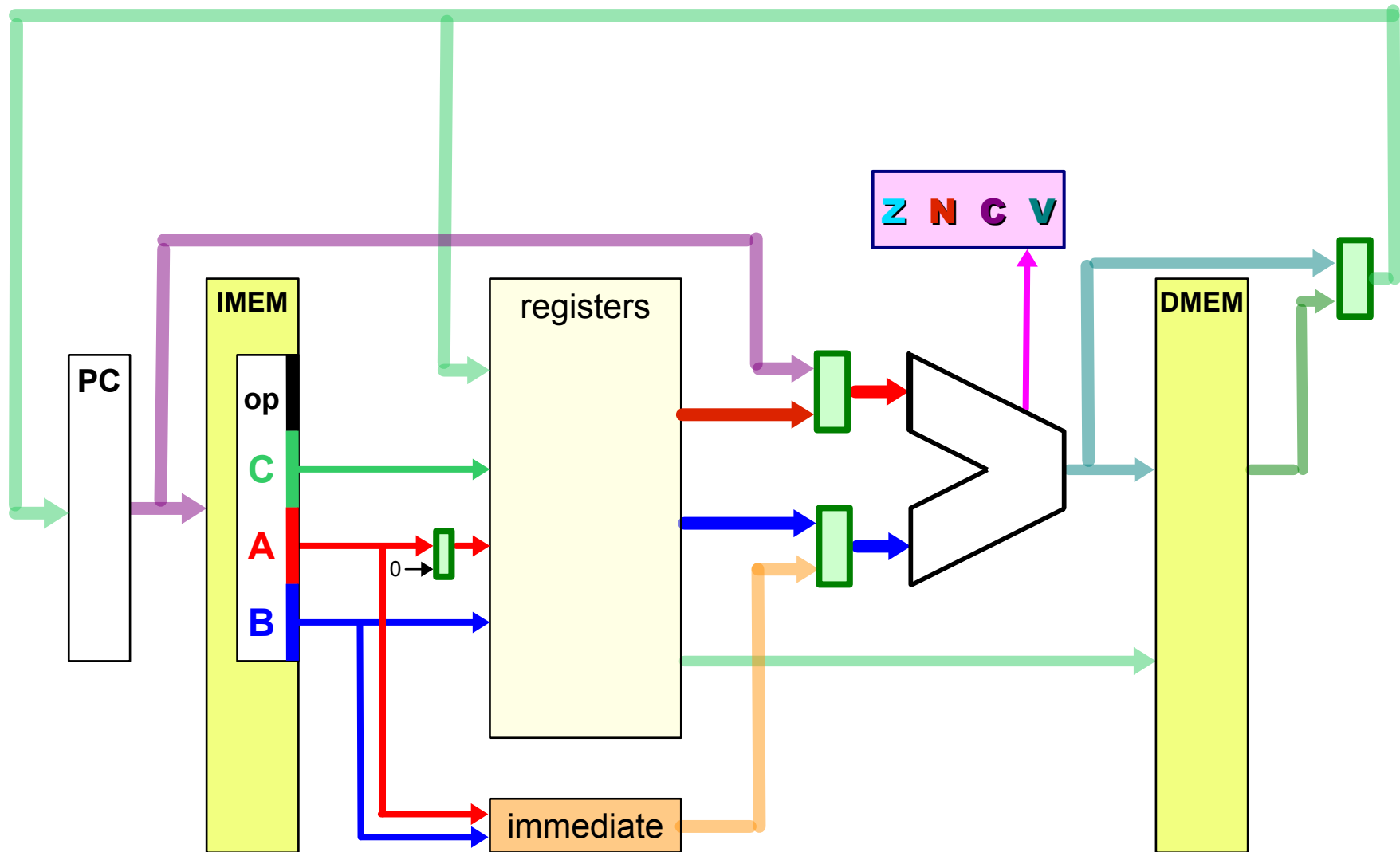
# Support for `lis` Instruction



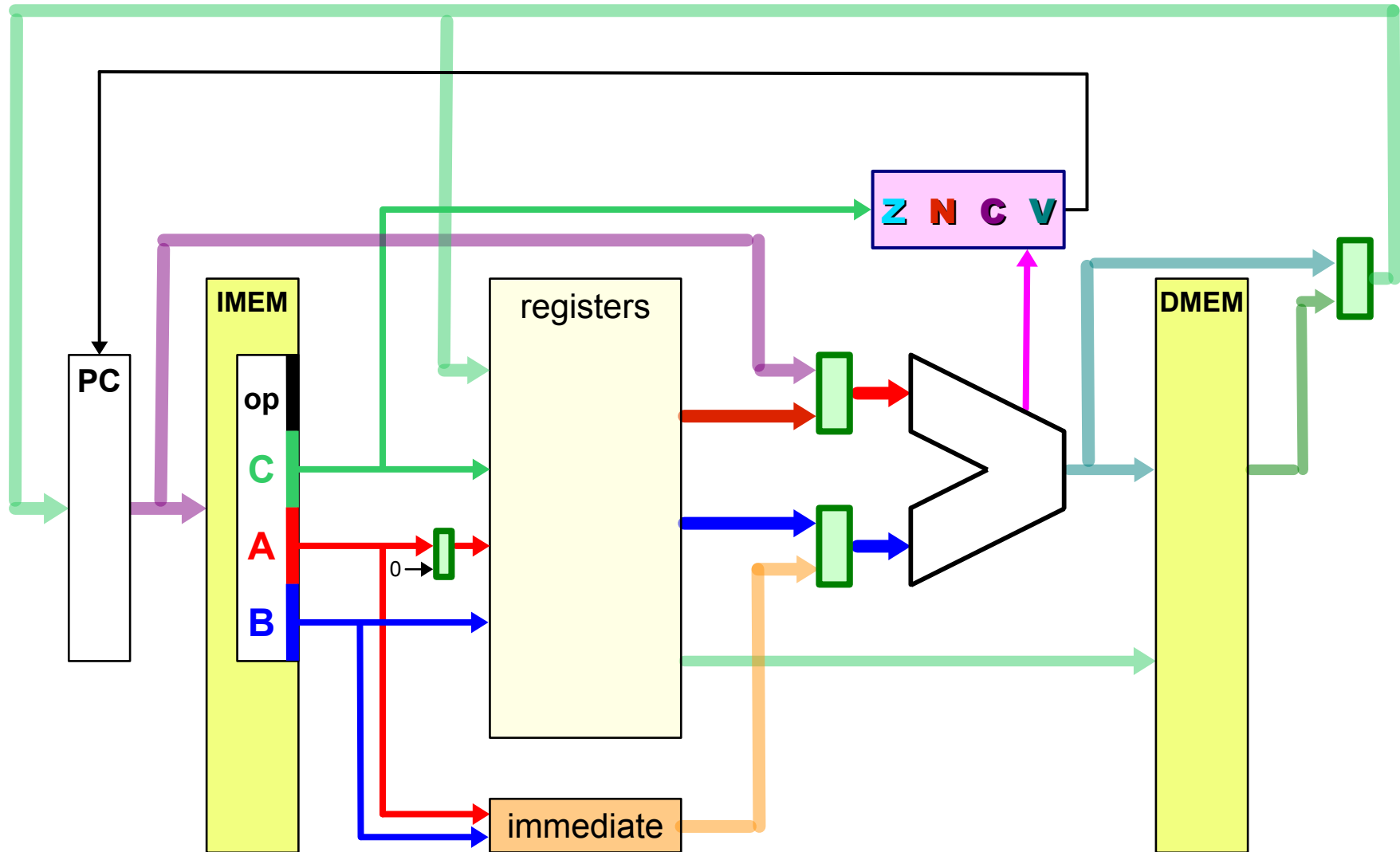
# Support for **bc** Instruction (1)



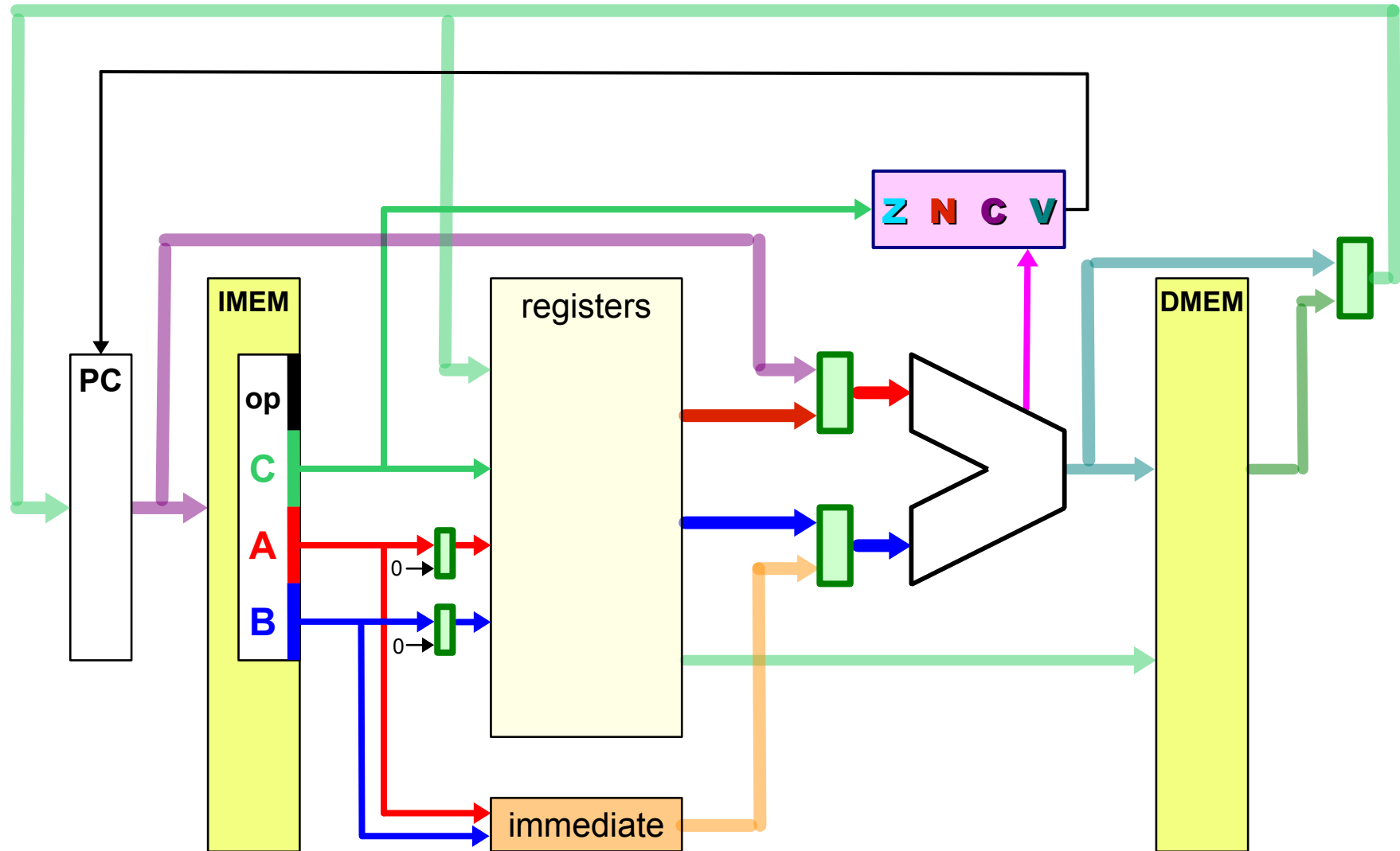
# Support for **bc** Instruction (2)



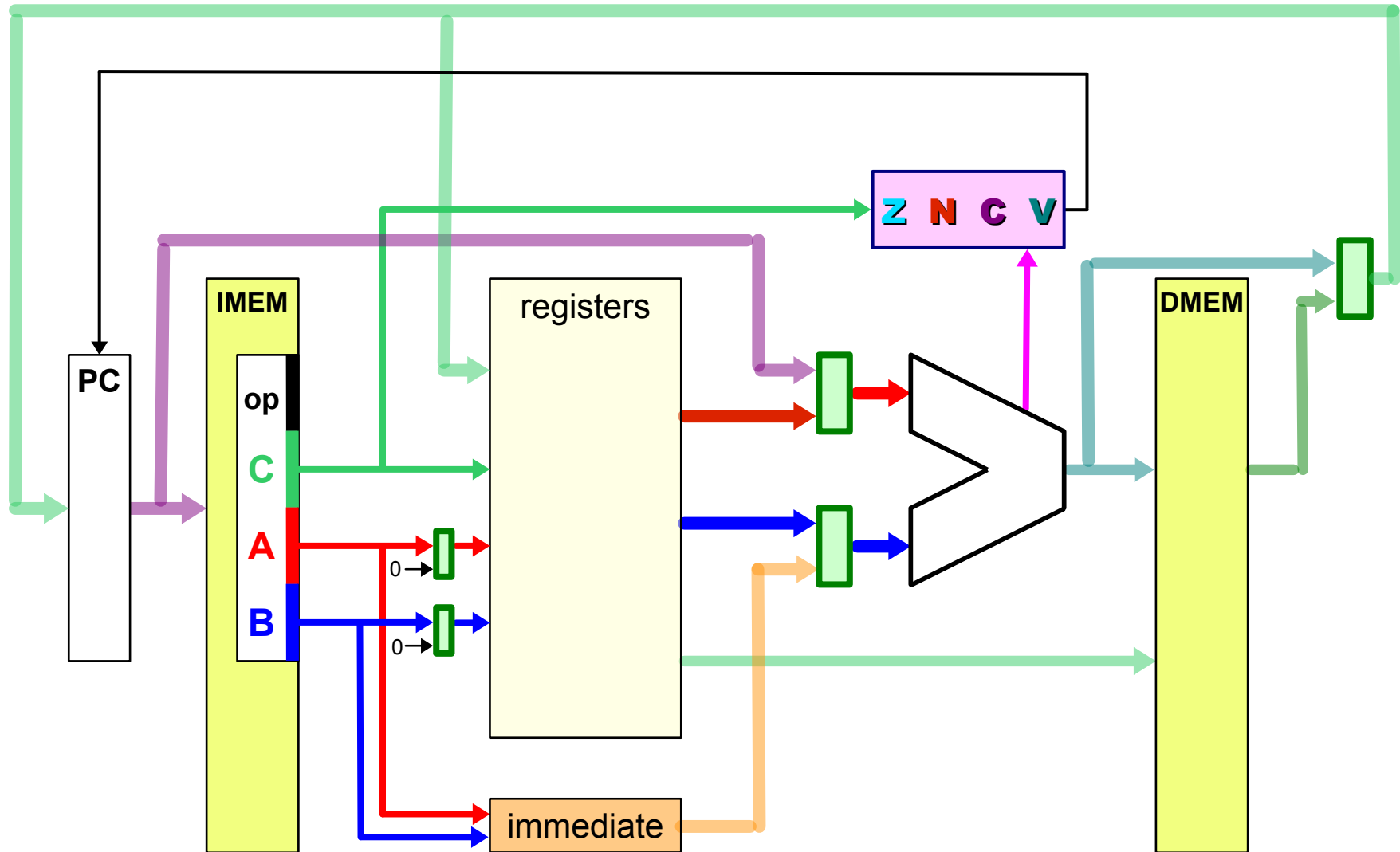
# Support for bc Instruction



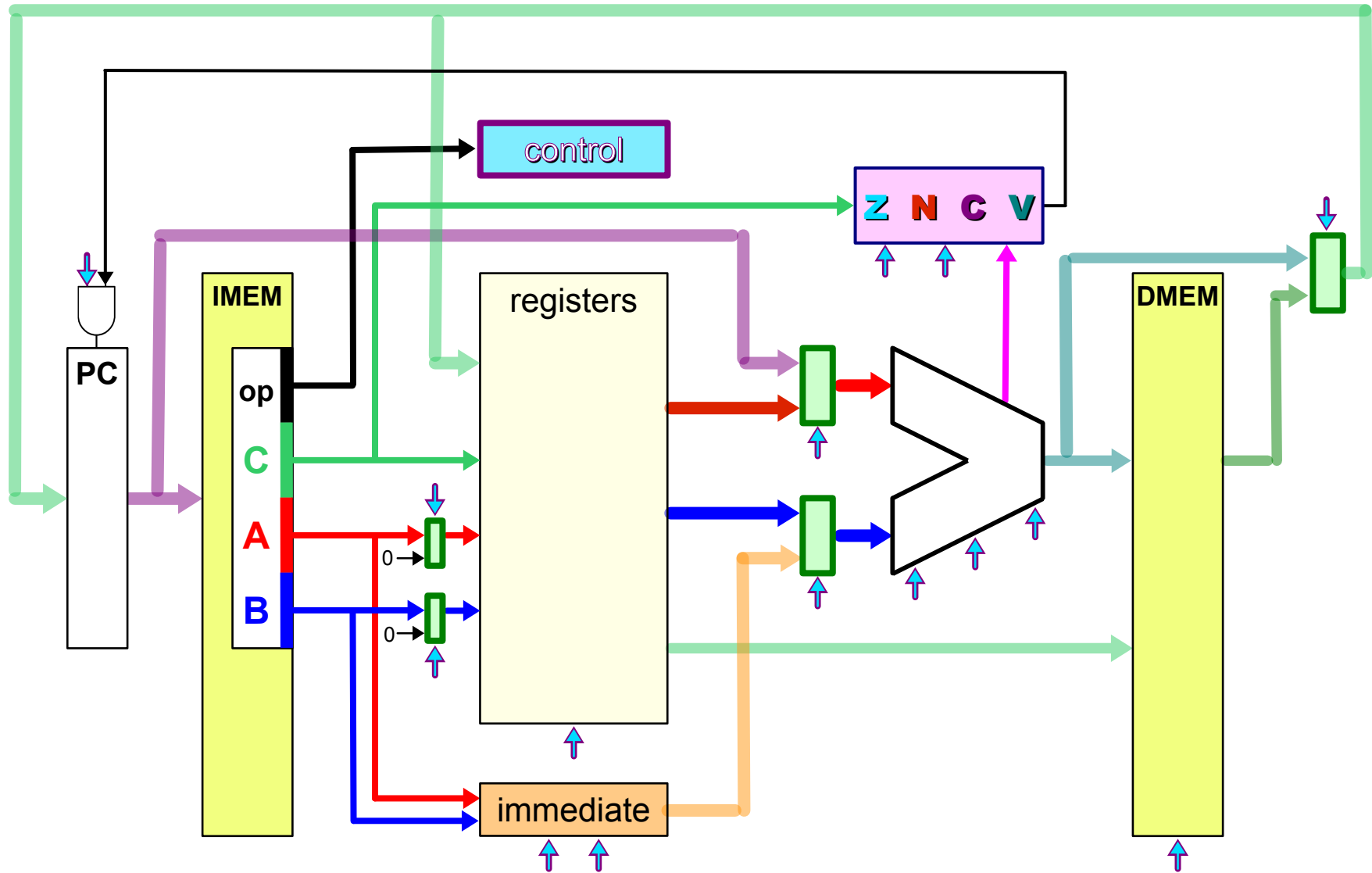
# *Partial* Support for b1c Instruction



# TOY Redesign *Datapath*

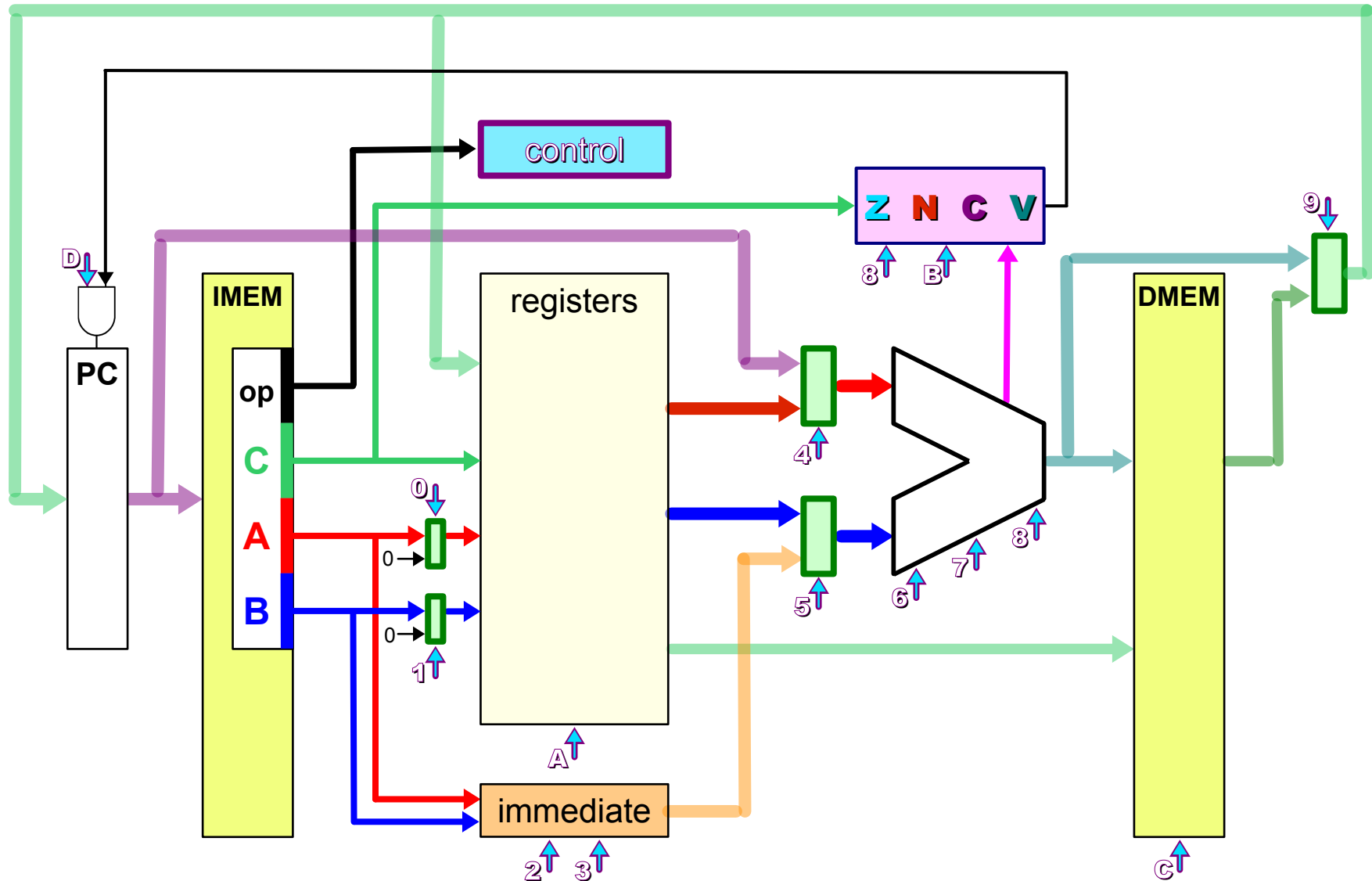


# TOY Redesign with **Control**





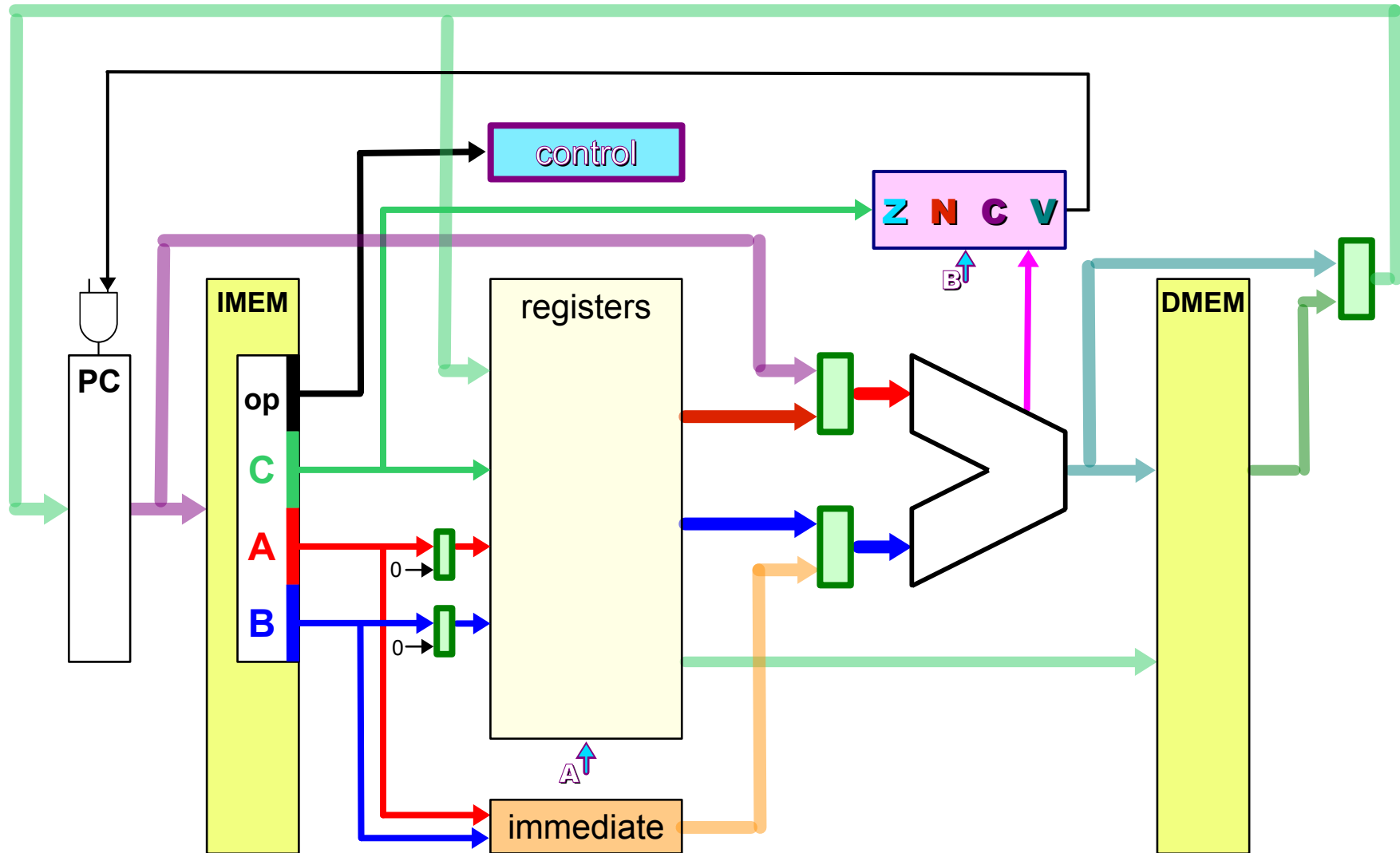
# TOY Redesign with Control



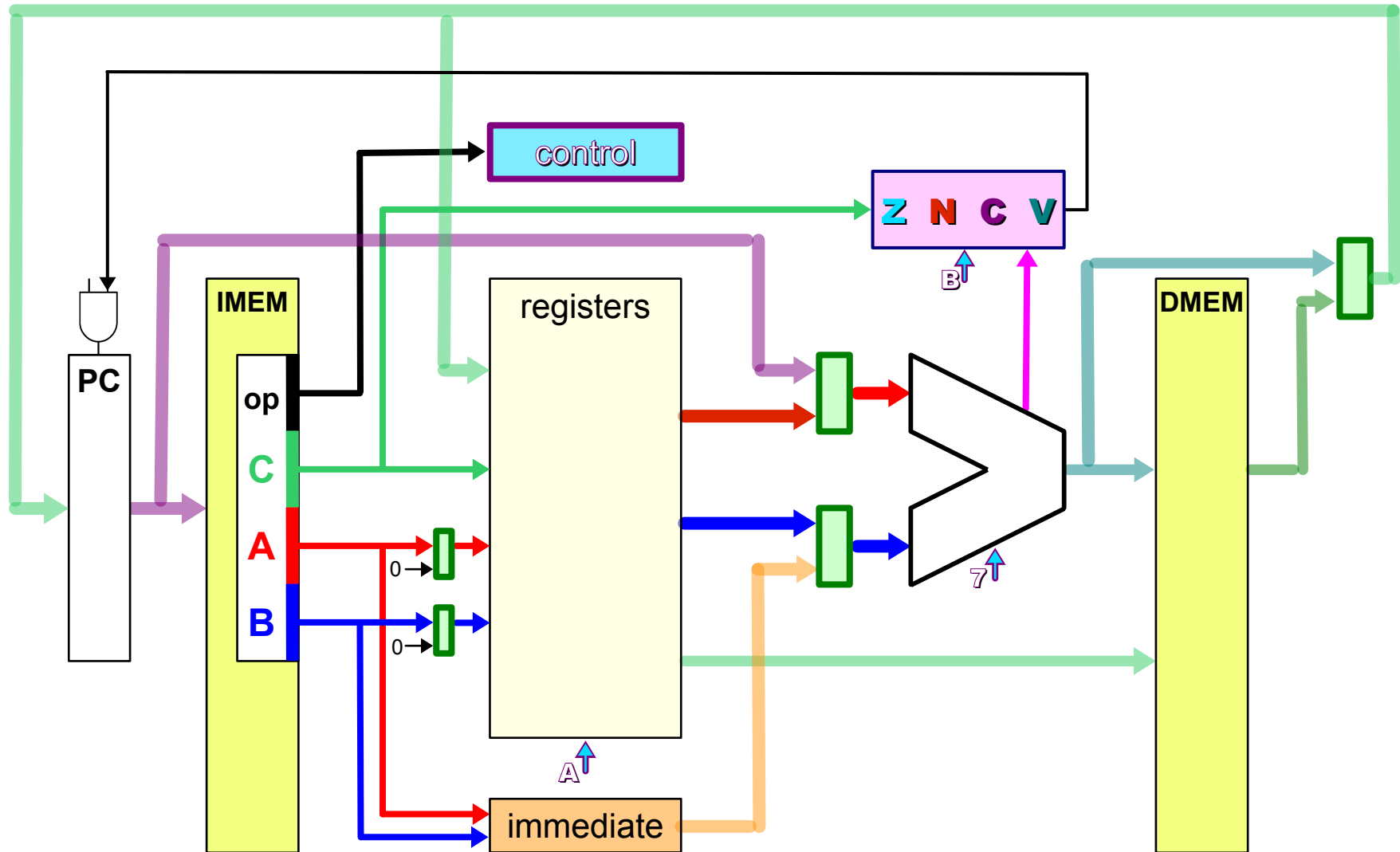
# TOY Redesign Control Signals

	?	0	1
0	<b>A</b> register address	IR[7..4]	0000
1	<b>B</b> register address	IR[3..0]	0000
2	Immediate input	IR[7..0]	0000 IR[3..0]
3	Immediate output	(sign extended) [7..0]	[F..8] 11111111
4	<b>B</b> bus source	<b>B</b> register	Immediate value
5	<b>A</b> bus source	<b>A</b> register	<b>PC</b>
6	Invert <b>A</b> bus	no	yes
7	Invert <b>B</b> bus	no	yes
8	ALU output	Arithmetic (full adder)	Logical (AND gate)
9	<b>C</b> bus source	<b>ALU</b>	Data memory
<b>A</b>	Register file write	no	yes
<b>B</b>	Condition write	no	<b>Z N C V</b> or <b>Z N</b>
<b>C</b>	Data memory write	no	yes
<b>D</b>	Possible branch?	no	yes

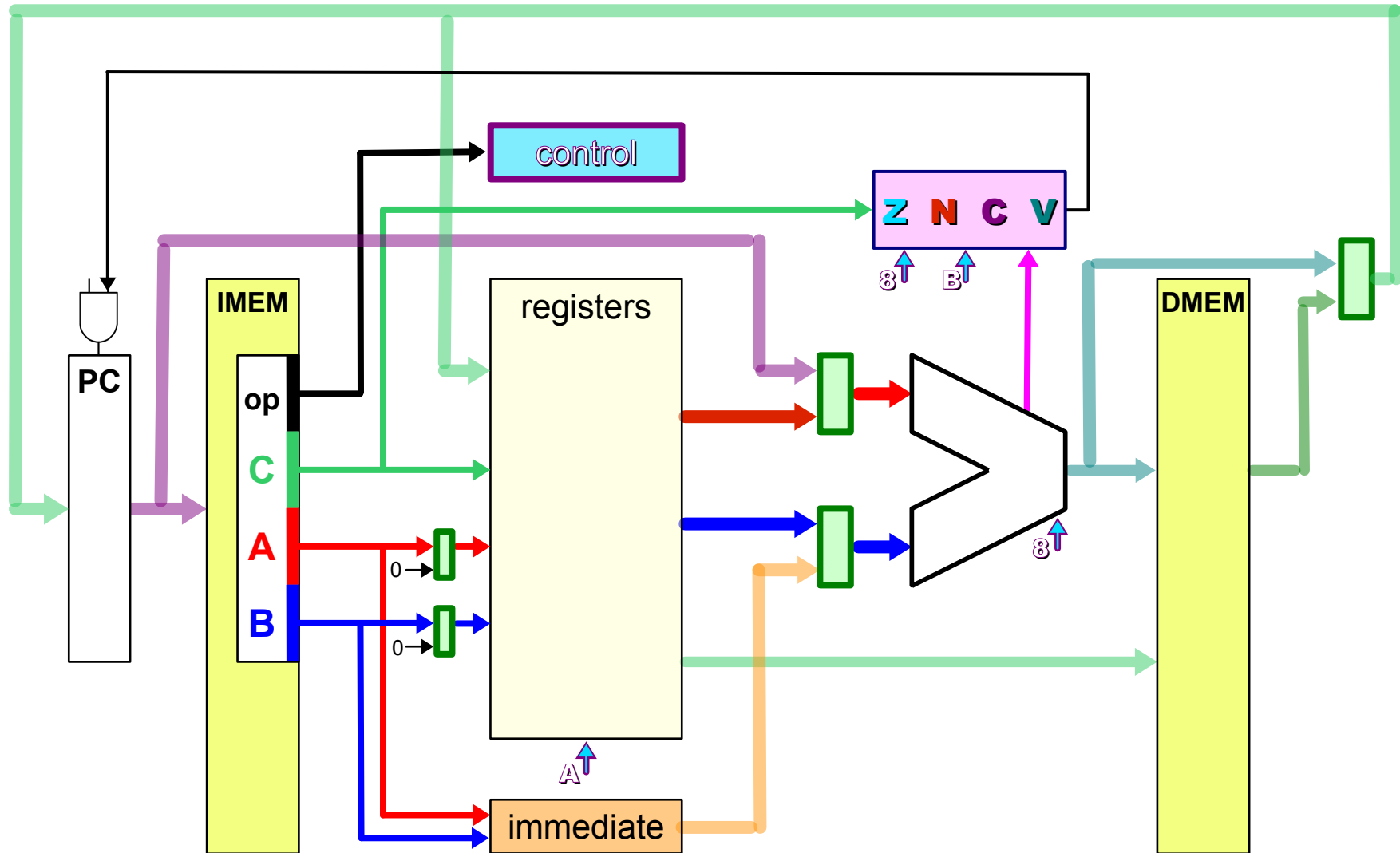
# Control = 1: add instruction



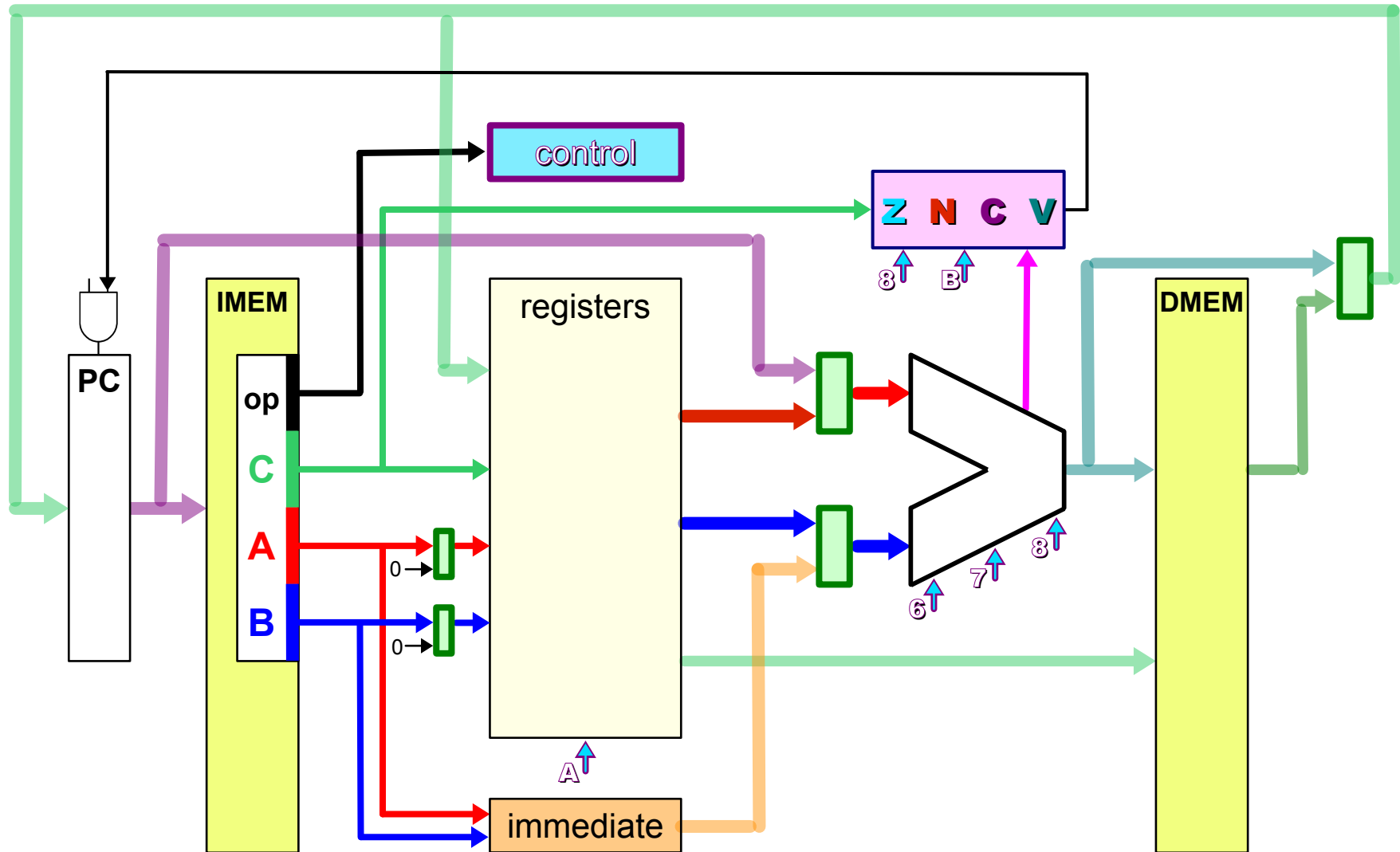
# Control = 1: sub instruction



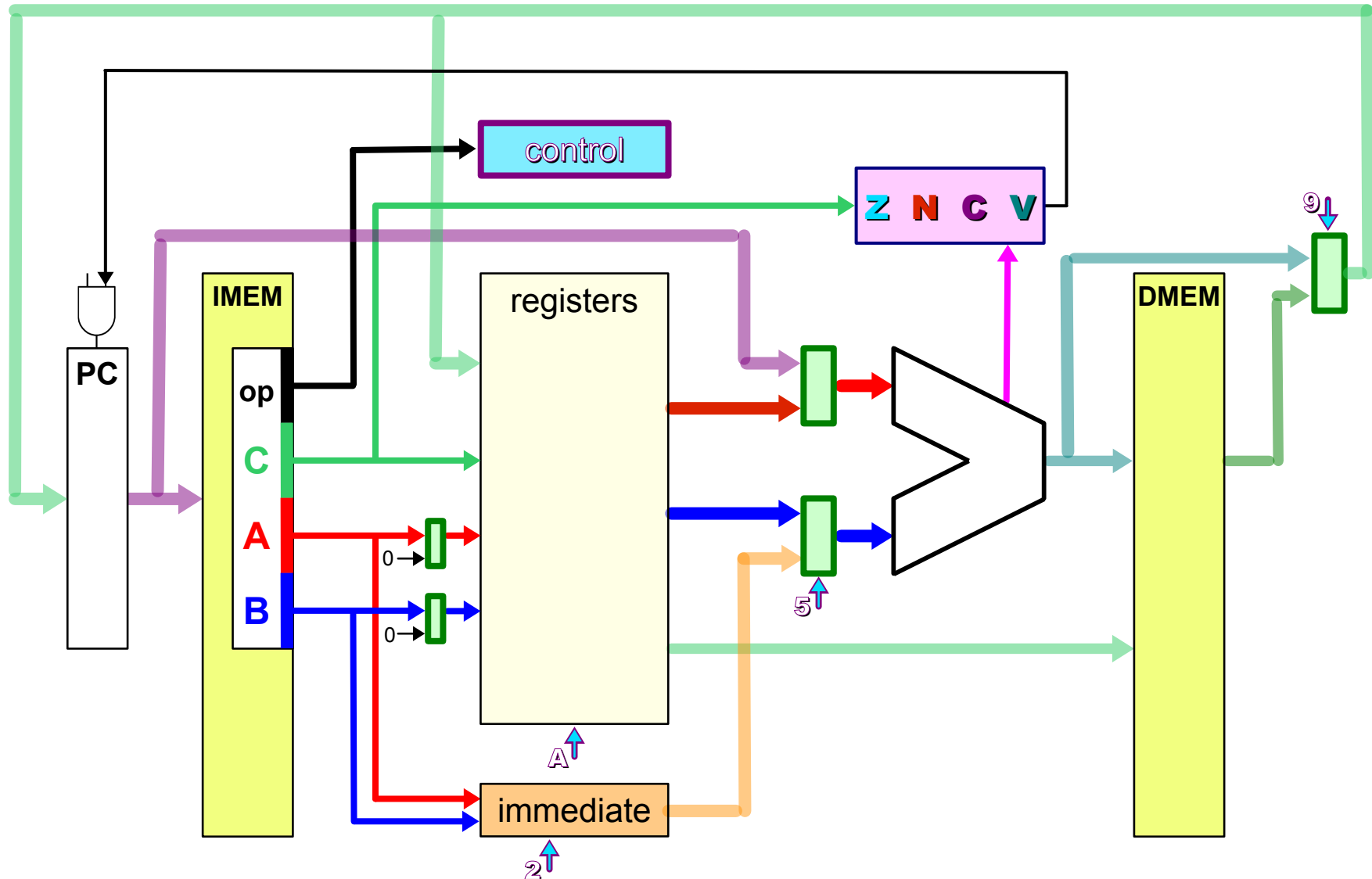
# Control = 1: and instruction



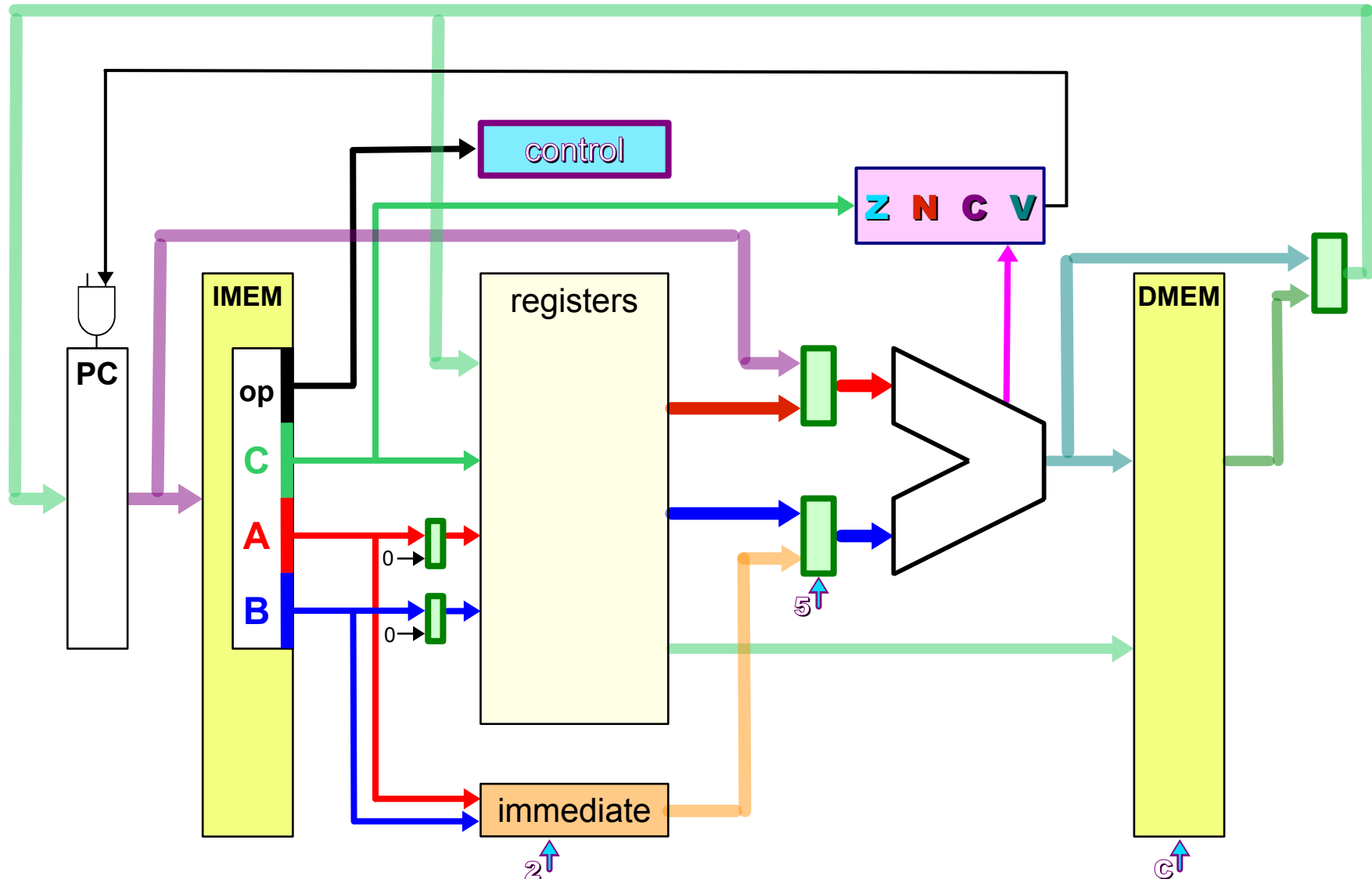
# Control = 1: nor instruction



# Control = 1: load instruction

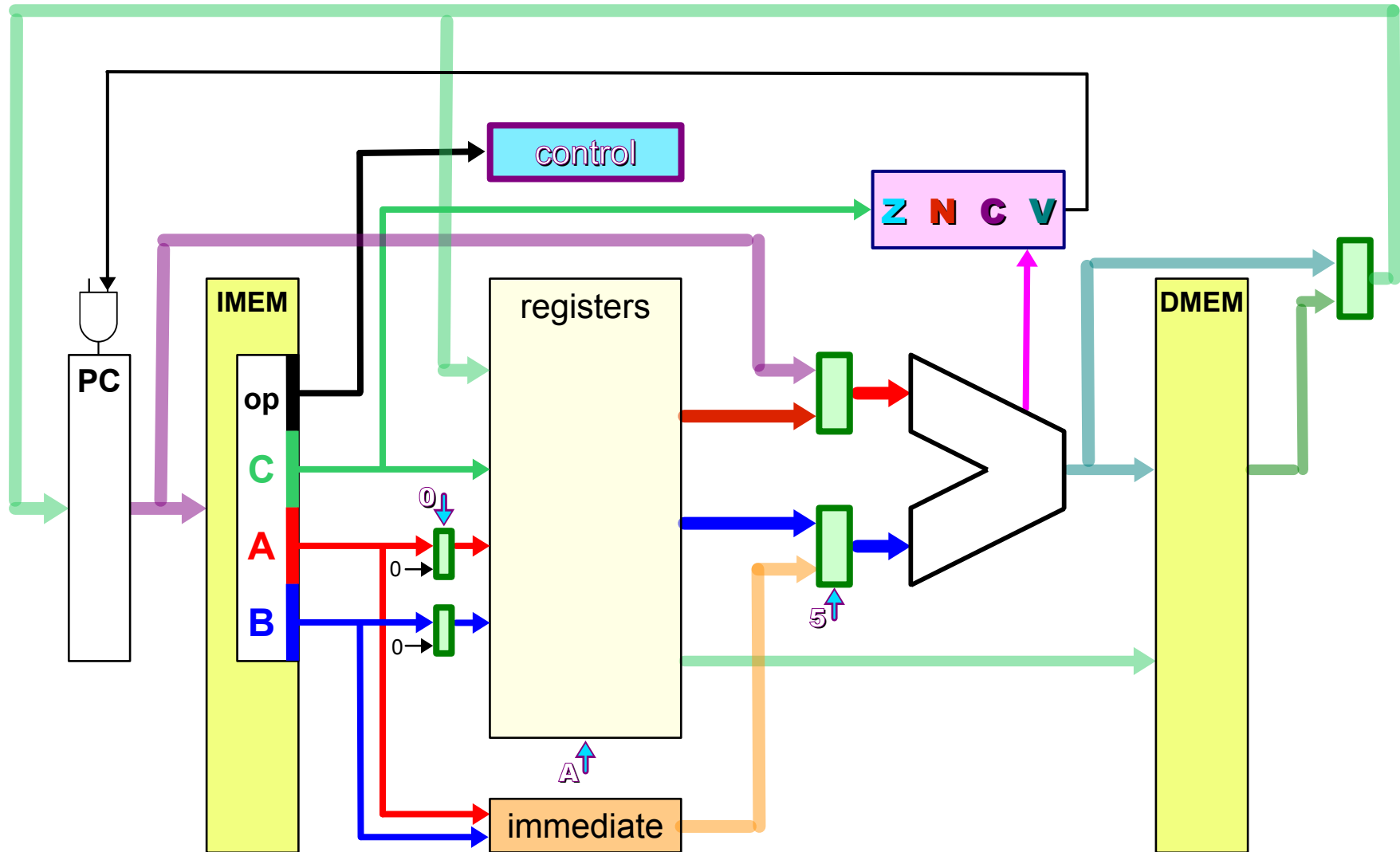


# Control = 1: store instruction

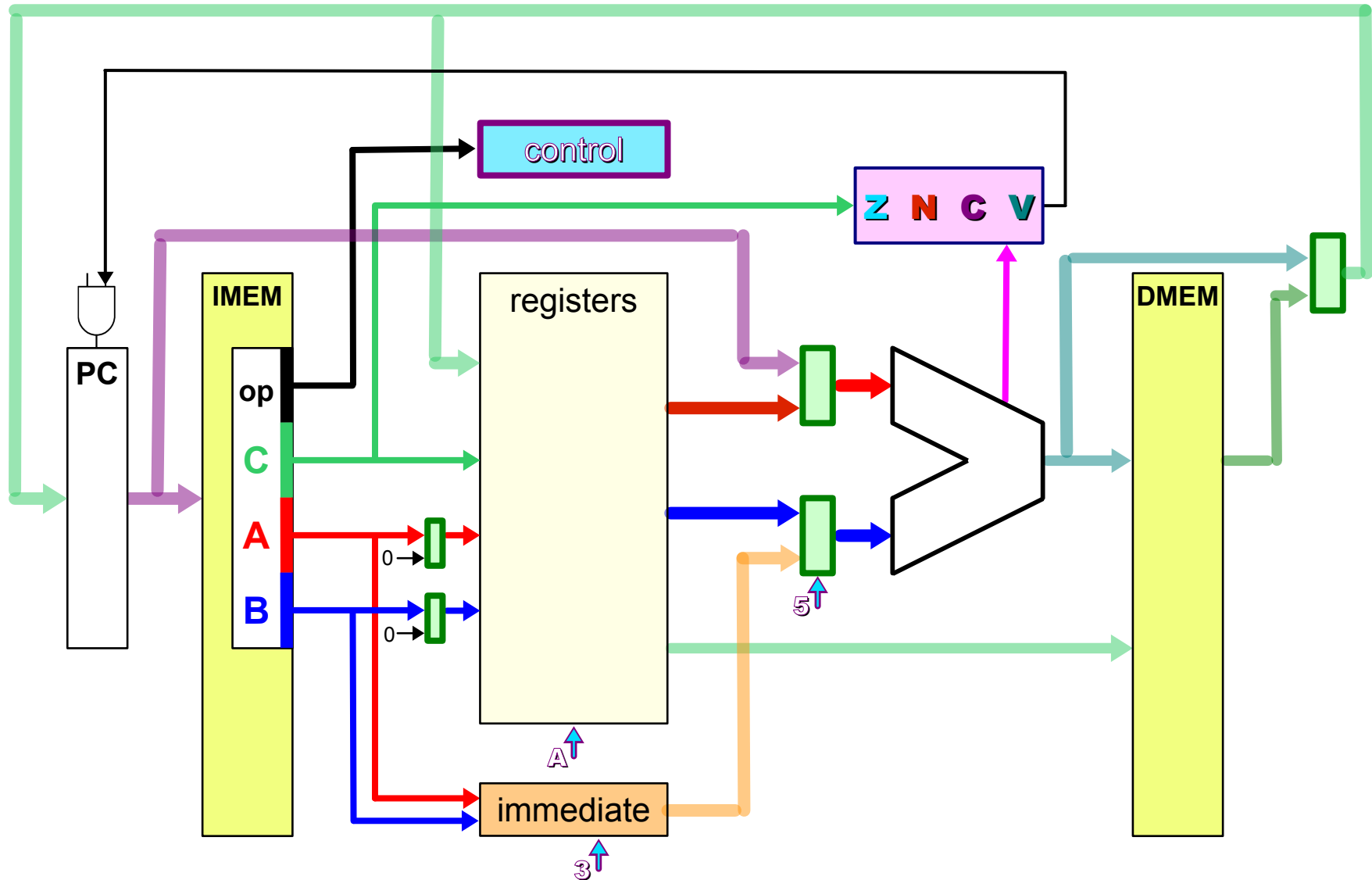




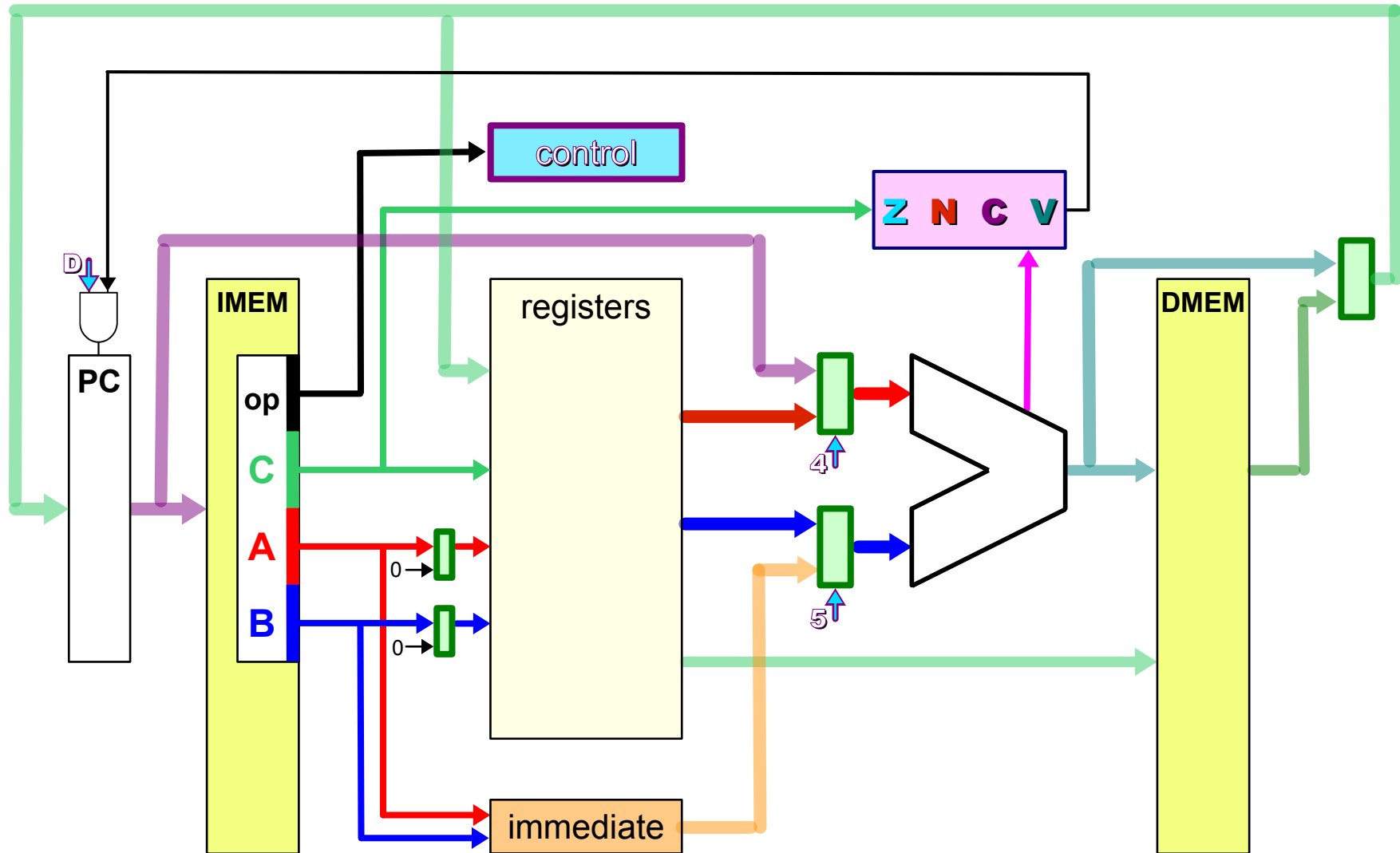
# Control = 1: `lis` instruction



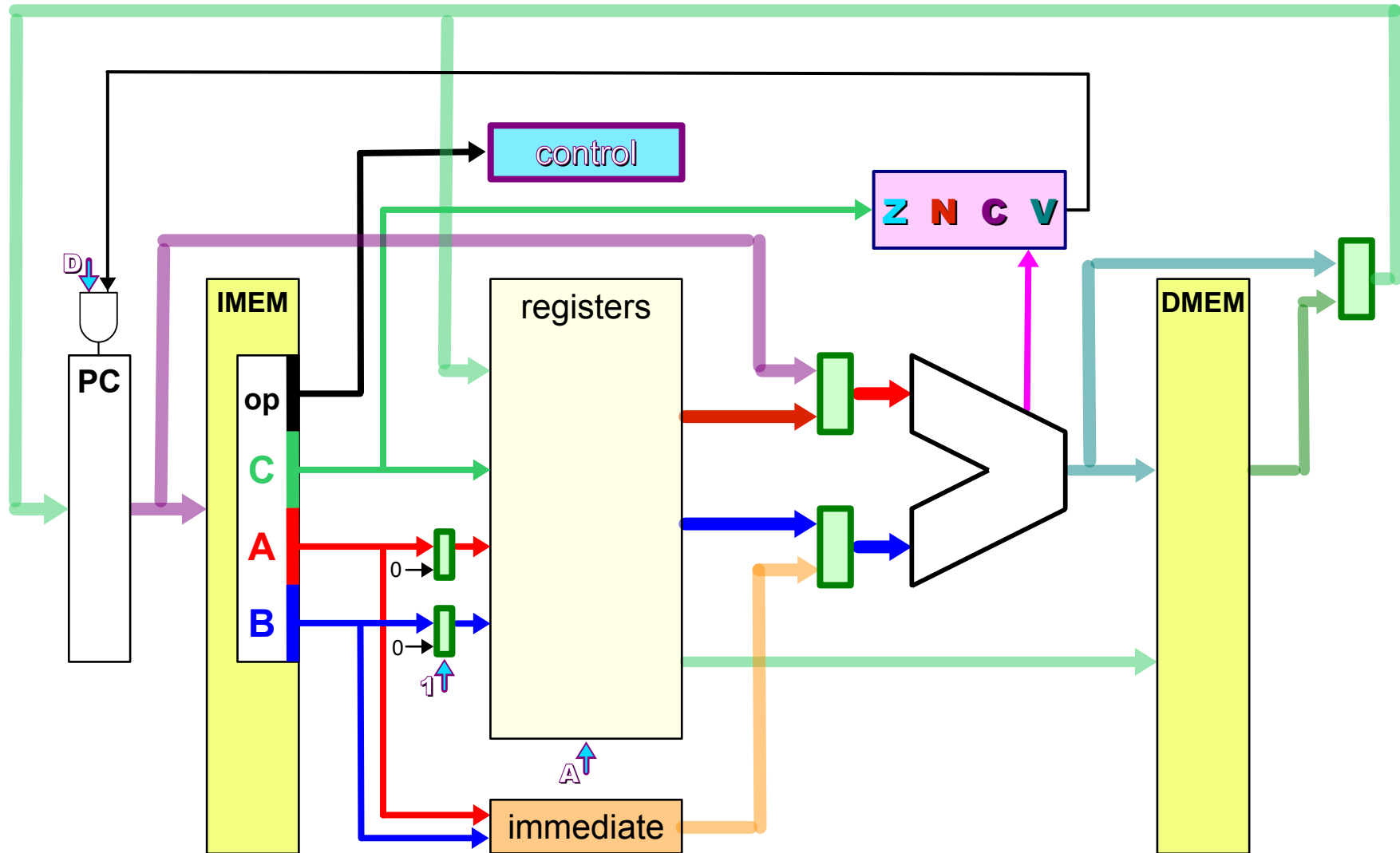
# Control = 1: 1ih instruction



# Control = 1: bc instruction



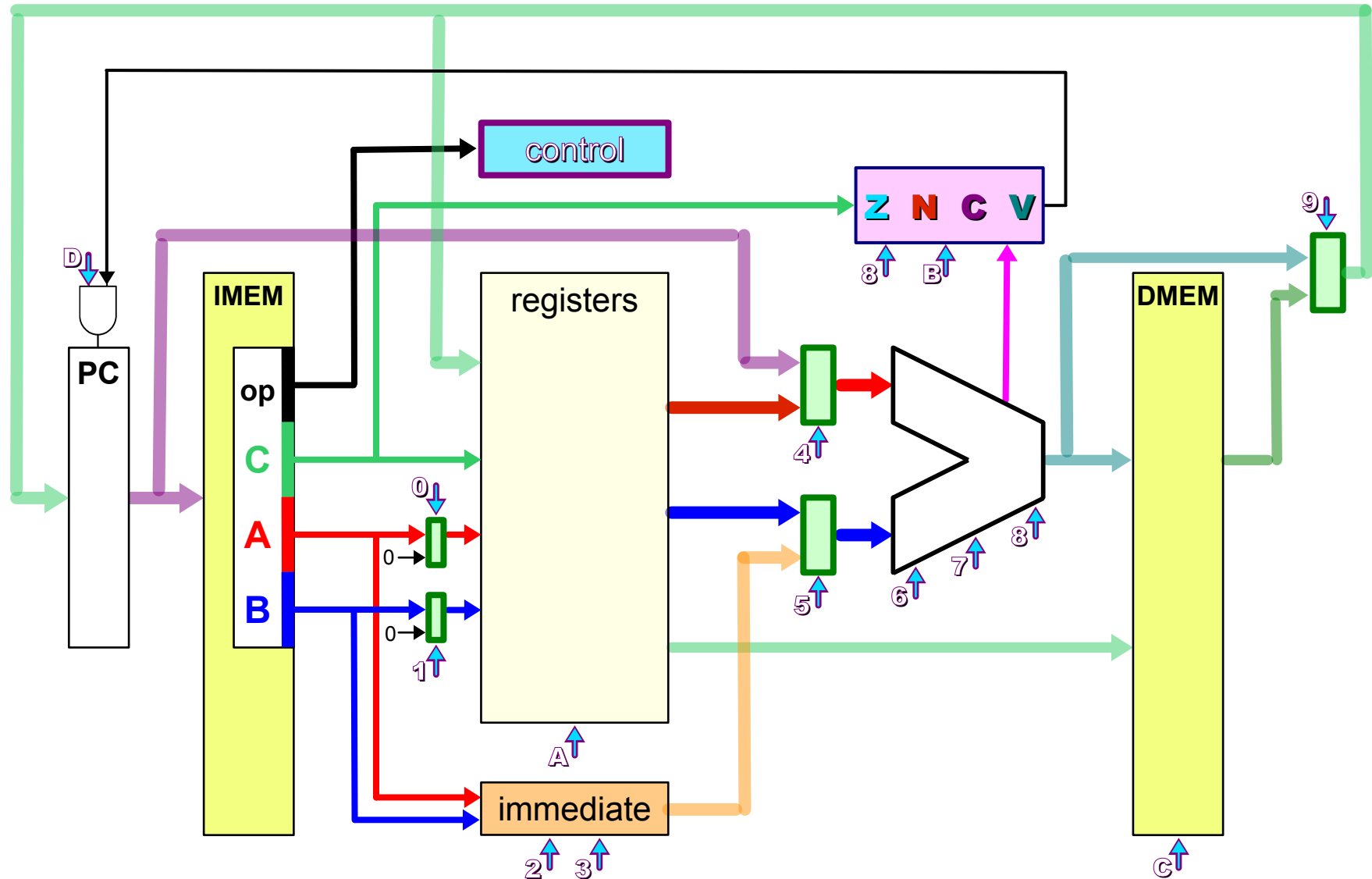
# Control = 1: bc1 instruction



# TOY Redesign Control Signals

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0	<b>A</b> register address	IR[7..4]	0000
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<b>C</b>	Data memory write	no	yes
<b>D</b>	Possible branch?	no	yes

# TOY Single Cycle Implementation



# TOY Single Cycle Implementation

Single cycle instruction execution

Combinational circuit with

Memory elements constant til the end of a cycle

**PC**, register file, **Z N C V**, **DMEM**

**lwh** instruction not fully implemented

Need to channel **C** address to **A MUX**

Need 3<sup>rd</sup> input to **4 MUX** (top 8 bits only)

**1111 1111** → **A** bus [F..8]

**bcl** instruction not fully implemented

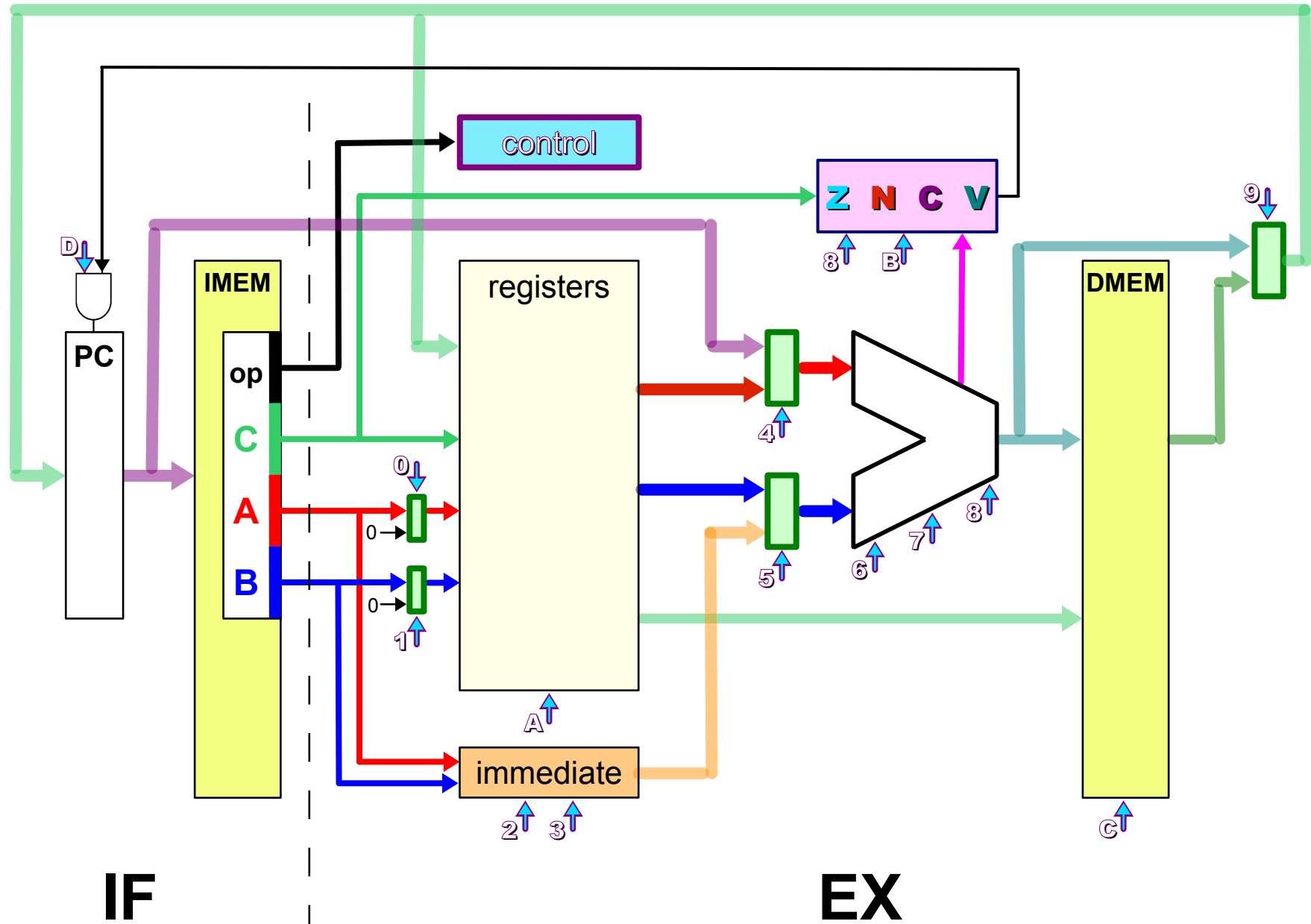
Need to channel **B** address to **C** decoder

Need to resolve structural hazard for the **C** bus

**PC** → register file write data input

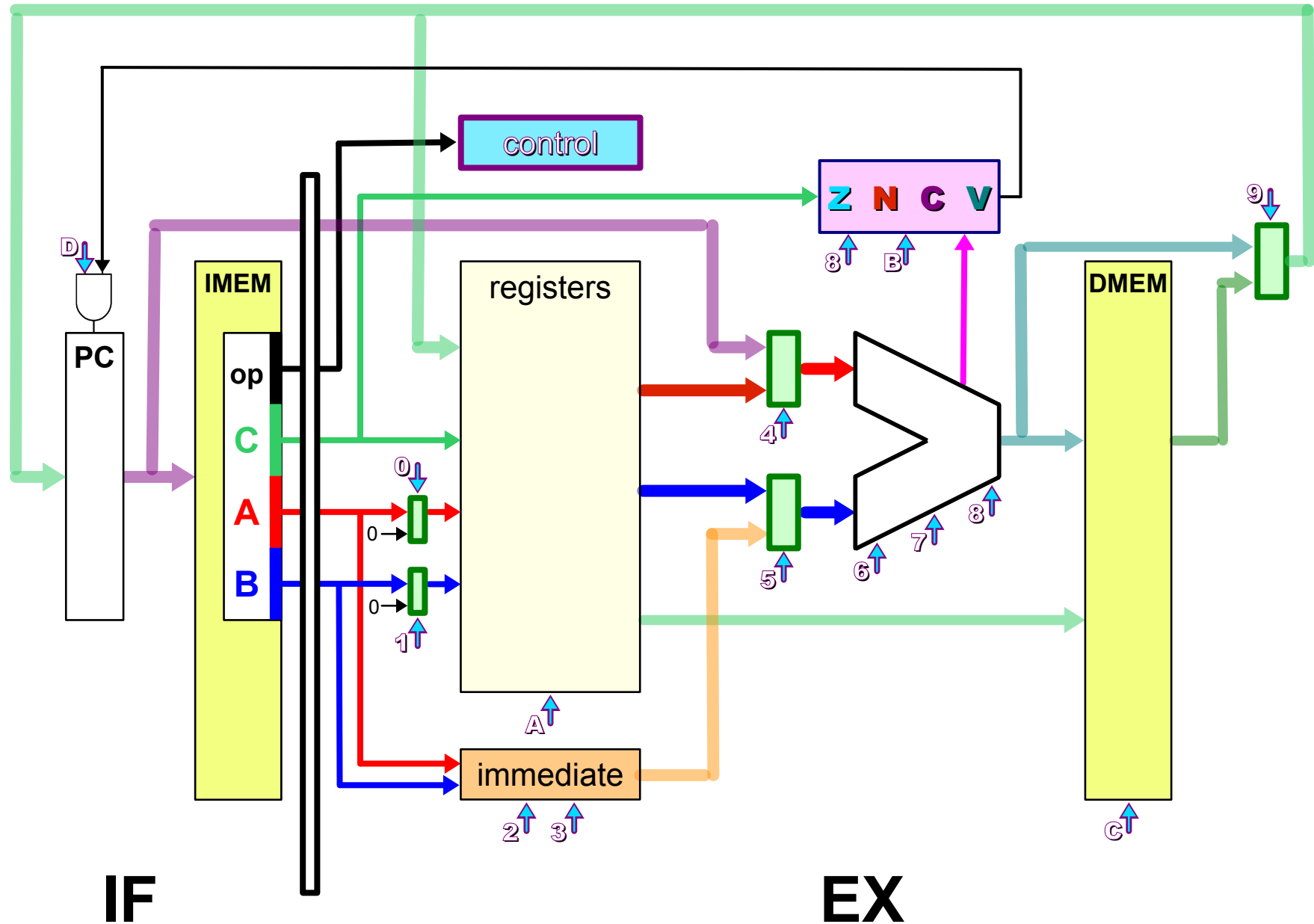
Register **A** + 0 → **PC**

# TOY Pipeline Implementation?

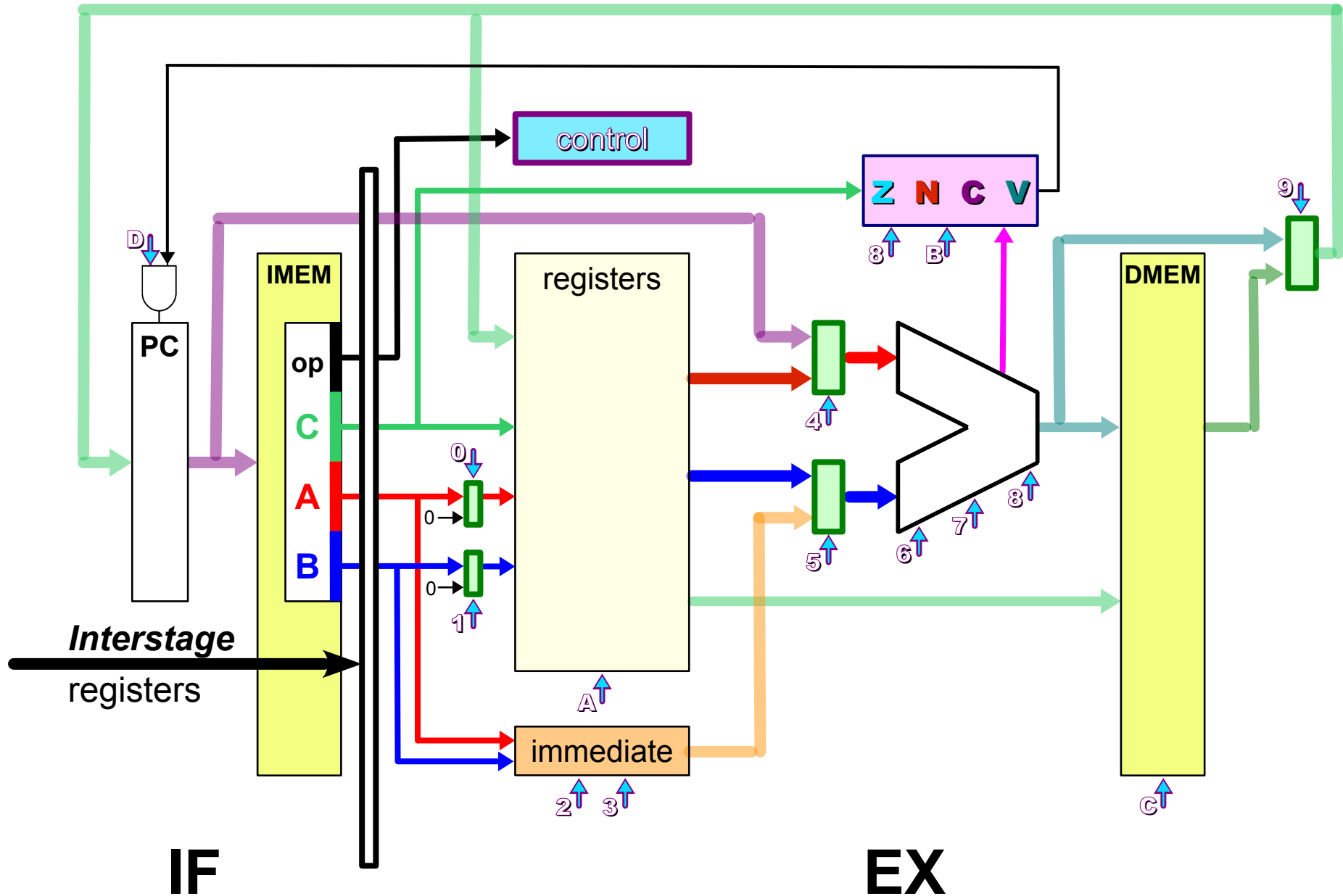




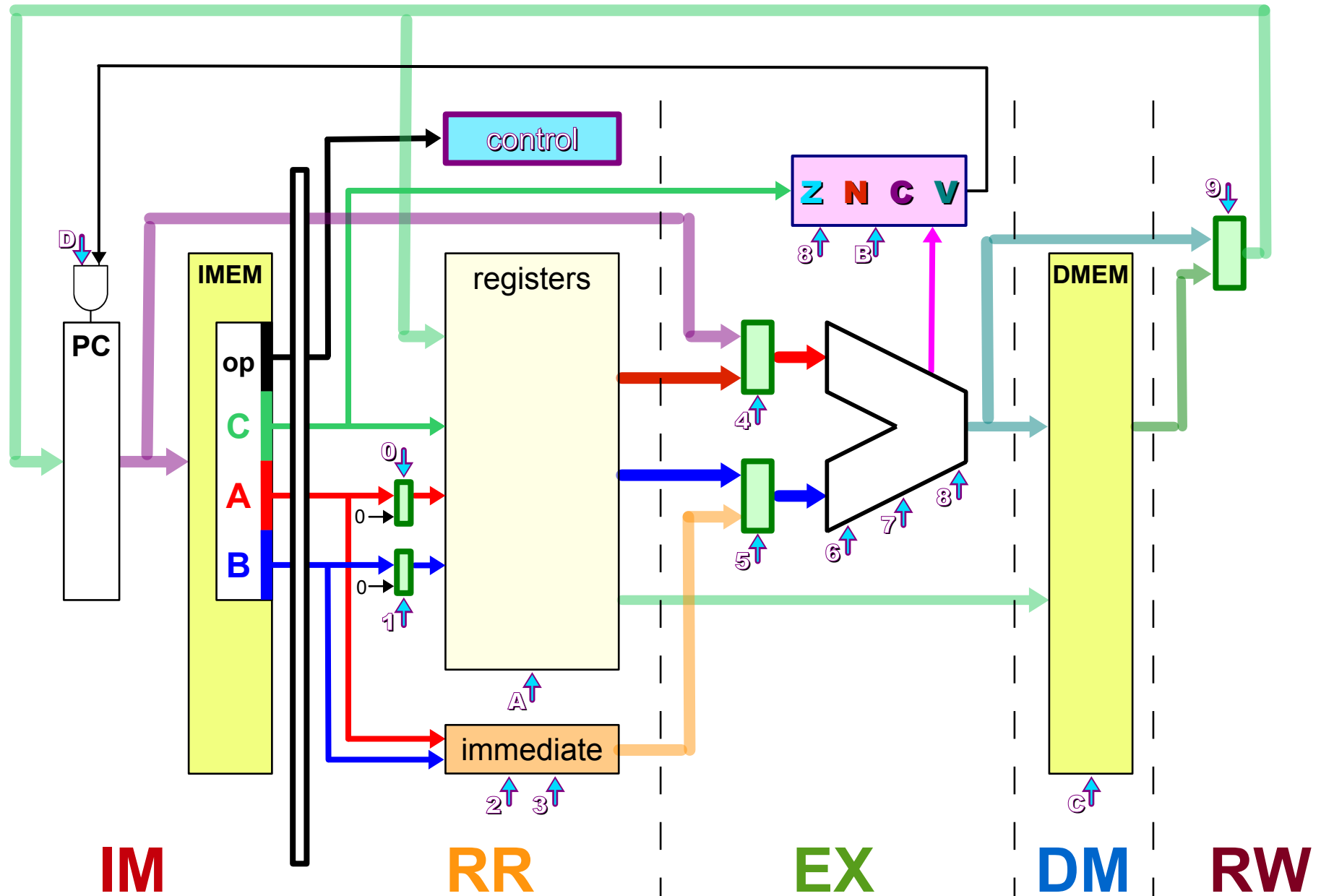
# TOY 2 Stage Pipeline



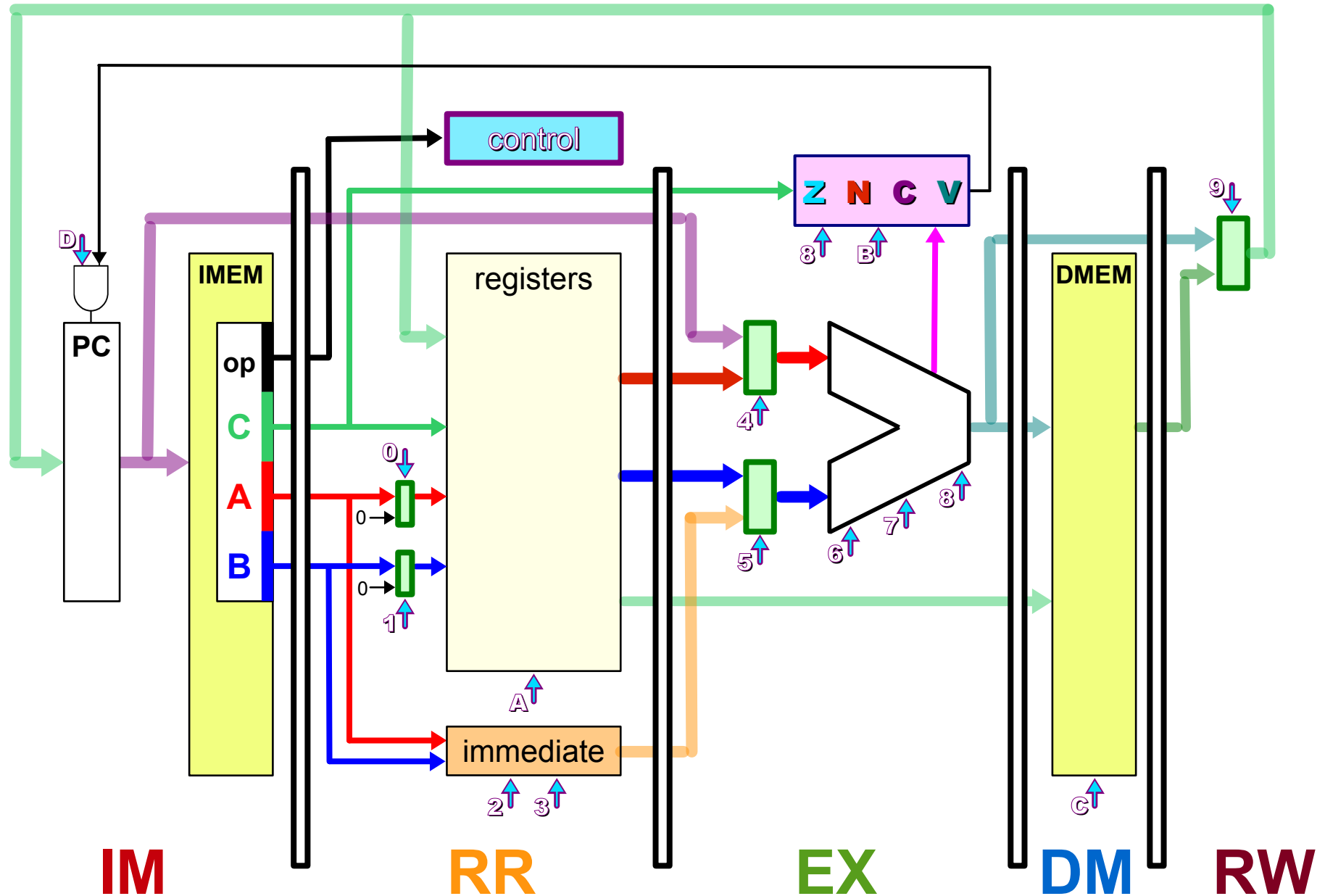
# TOY 2 Stage Pipeline



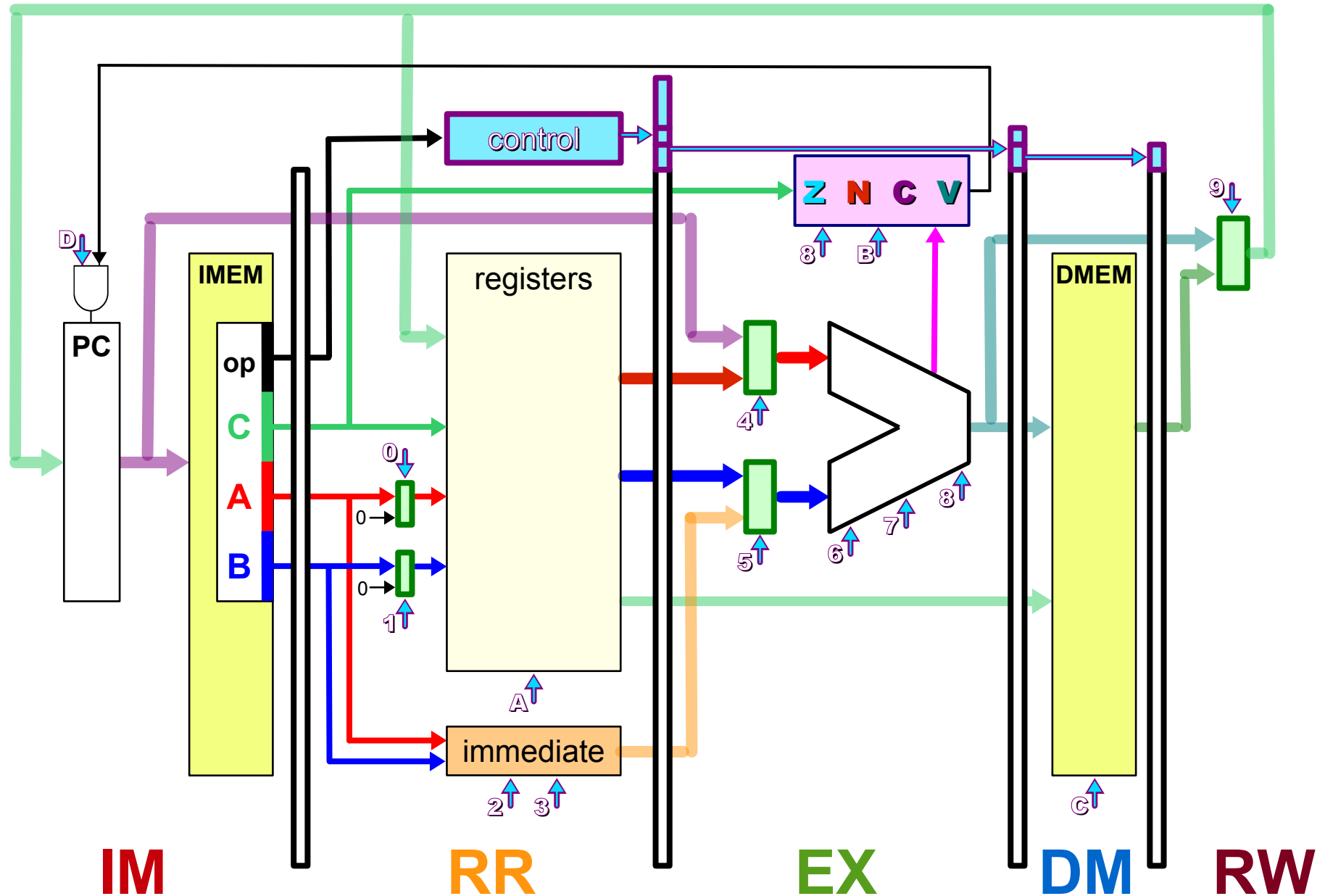
# TOY 5 Stage Pipeline ??



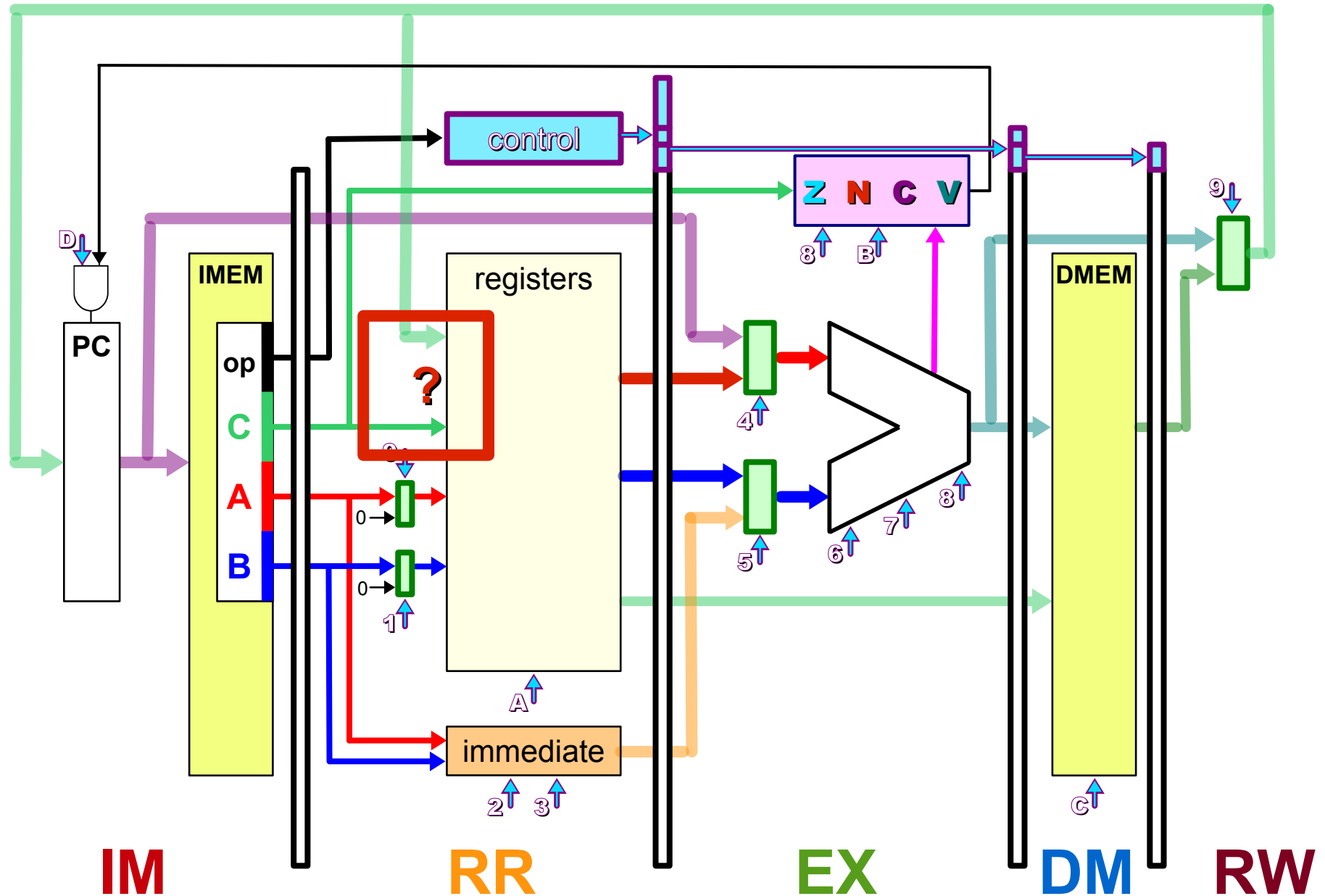
# TOY 5 Stage Pipeline ?



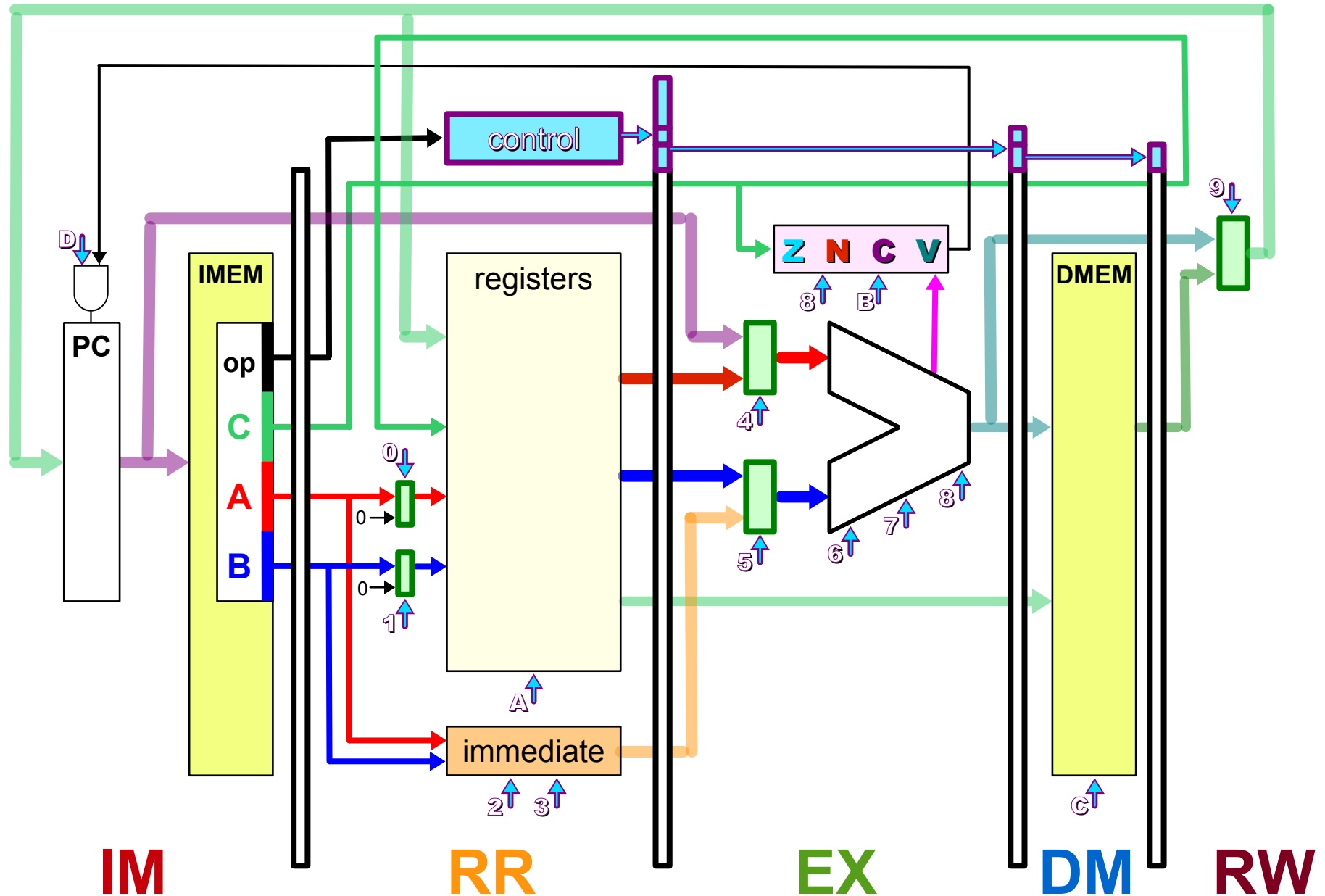
# TOY 5 Stage Pipeline ?



# TOY 5 Stage Pipeline ?



# TOY 5 Stage Pipeline !



# Performance Equations

## Definition of performance

$$\text{performance: } P_x \equiv \frac{1}{T_x} \quad \text{relative performance: } \frac{P_x}{P_y} = \frac{T_y}{T_x}$$

## CPU time equation

$$T_{CPU}(\text{execution}) = \frac{\# \text{ instructions}}{\text{execution}} \cdot \frac{\# \text{ cycles}}{\text{instruction}} \cdot \frac{\# \text{ seconds}}{\text{cycle}}$$

## Amdahl's law

$$T_{new} = \frac{\text{fraction effected} \cdot T_{old}}{\text{improvement}} + \text{fraction not effected} \cdot T_{old}$$



# Processor Performance Equations

$$T_X = \# \text{ instructions}_X \cdot \text{CPI}_X \cdot \text{cycleTime}_X$$

$$T_X = \frac{\# \text{ instructions}_X \cdot \text{CPI}_X}{\text{clockRate}_X}$$

$$\frac{P_X}{P_Y} = \frac{T_Y}{T_X} = \frac{\# \text{ instructions}_Y \cdot \text{CPI}_Y \cdot \text{cycleTime}_Y}{\# \text{ instructions}_X \cdot \text{CPI}_X \cdot \text{cycleTime}_X}$$

$$\frac{P_X}{P_Y} = \frac{T_Y}{T_X} = \frac{\# \text{ instructions}_Y \cdot \text{CPI}_Y \cdot \text{clockRate}_X}{\# \text{ instructions}_X \cdot \text{CPI}_X \cdot \text{clockRate}_Y}$$

# HW 13: Processor Performance

- 1) Processor A runs program P in 30 seconds executing  $12 \cdot 10^9$  instructions. Half of these are ALU instructions, a quarter are data transfer (load or store) instructions, and a quarter are branch instructions. Execution of the ALU and branch instructions require 4 cycles each. Execution of load and store instructions require 6 cycles each. What is the clock speed of processor A in GHz (billions of cycles per second)?
- 2) On processor B every instruction takes 3 cycles to execute. The clock for processor B is twice as fast as processor A's clock. How long does it take processor B to execute program P?
- 3) What is the relative performance of processor B to processor A?

# HW 13: Processor Performance

1) Processor A runs program P in 30 seconds executing  $12 \cdot 10^9$  instructions. Half of these are ALU instructions, a quarter are data transfer (load or store) instructions, and a quarter are branch instructions. Execution of the ALU and branch instructions require 4 cycles each. Execution of load and store instructions require 6 cycles each. What is the clock speed of processor A in GHz (billions of cycles per second)?

$$T_X = \frac{\# \text{ instructions}_X \cdot \text{CPI}_X}{\text{clockRate}_X}$$

$$30 = \frac{12 \cdot 10^9 \cdot (0.5 \cdot 4 + 0.25 \cdot 6 + 0.25 \cdot 4)}{X \text{ Hz}} = \frac{12 \cdot 4.5}{X \text{ Hz}} \cdot 10^9$$

$$X \text{ Hz} = \frac{54}{30} \cdot 10^9 \text{ Hz} = 1.8 \cdot 10^9 \text{ Hz} = 1.8 \text{ GHz}$$

# HW 13: Processor Performance

2) On processor B every instruction takes 3 cycles to execute. The clock for processor B is twice as fast as processor A's clock. How long does it take processor B to execute program P?

$$\begin{aligned}\frac{T_B}{T_A} &= \frac{\# \text{ instructions}_B \cdot \text{CPI}_B \cdot \text{clockRate}_A}{\# \text{ instructions}_A \cdot \text{CPI}_A \cdot \text{clockRate}_B} \\ \frac{T_B}{30} &= \frac{12 \cdot 10^9 \cdot 3 \cdot \text{clockRate}_A}{12 \cdot 10^9 \cdot (0.5 \cdot 4 + 0.25 \cdot 6 + 0.25 \cdot 4) \cdot 2 \cdot \text{clockRate}_A} \\ T_B &= 30 \cdot \frac{3}{4.5 \cdot 2} = \frac{90}{9} = 10\end{aligned}$$

3) What is the relative performance of processor B to processor A?

$$\frac{P_B}{P_A} = \frac{T_A}{T_B} = \frac{30}{10} = 3 \quad \text{B is 3 times as fast as A}$$

# Eras in Processor Architecture Evolution

Multi-cycle instructions

$$\text{CPI} > 1$$

Antiquated (ex. simple **TOY** processor)

Single-cycle instructions

$$\text{CPI} = 1$$

Long cycles

Pipelined instructions<sup>a</sup>

$$\text{CPI} = 1 + \sigma$$

Short cycles

$\sigma$  is **S**tall **C**ycles **P**er **I**nstruction (SCPI)

Multiple issue instructions

$$\text{CPI} < 1$$

Very Long Instruction **W**ord (VLIW)

Superscalar

<sup>a</sup> assumes CPI for the perfect pipeline = 1

# Performance Problems

## Conversions between “eras”

Multi-cycle to single-cycle instruction execution

Single-cycle to pipeline instruction execution

Cycle time:  $\text{sum}(\text{stage times})$  to  $\text{max}(\text{stage times}) + \Delta$

$\Delta$  is “pipeline overhead” (e.g. interstage register access)

Pipeline to pipeline

Multiple issue to pipeline

**CPU time = #instructions · CPI · cycle time**

Actual pipeline CPI =  $\text{CPI}_{\text{pp}}$  + **SCPI**

**Stall Cycles Per Instruction**

Sum over all types of hazard of

Frequency of occurrence · # cycles per occurrence

# HW 14 Pipeline Performance

This problem considers the performance of several implementations of the same instruction set architecture on a suite of programs with the following characteristics:

ALU instructions	45%	
Load instructions	20%	
Store instructions	10%	
Branch instructions	25%	
Unconditional	5%	
Conditional	20%	
Backward	16%	(taken 6%, not taken 10%)
Forward	4%	(taken 2%, not taken 2%)

# HW 14 part A

A multiple-cycle serial implementation has the following cycle counts for the various instructions:

ALU instructions	3 cycles
Load instructions	8 cycles
Store instructions	6 cycles
Unconditional branches	3 cycles
Taken conditional branches	5 cycles
Not-taken conditional branches	4 cycles

What is the CPI of the program suite on this implementation?

$$\begin{aligned}\text{CPI} &= 0.45 \cdot 3 + 0.20 \cdot 8 + 0.10 \cdot 6 + 0.05 \cdot 3 + (0.06 + 0.02) \cdot 5 + (0.10 + 0.02) \cdot 4 \\ &= 1.35 + 1.6 + 0.6 + 0.15 + 0.4 + 0.48 \\ &= 4.58\end{aligned}$$



# HW 14 part B

A second serial implementation executes every instruction in a single cycle. Instruction execution is performed in the following phases having the indicated execution times:

IF	instruction fetch	150 ps
RR	register read	100 ps
EX	ALU operation	400 ps
MW	memory write	300 ps
MR	memory read	150 ps
RW	register write	100 ps

How long is the cycle time for this implementation?

$$150 + 100 + 400 + 300 + 150 + 100 = 1200 \text{ ps}$$

# HW 14 part C

A third implementation executes instructions in a pipeline using the stages given in part B.

How long is the cycle time for this implementation?

$$\max(150, 100, 400, 300, 150, 100) = 400 \text{ ps}$$

What is the relative performance of this implementation to that of part B?

$$\frac{P_C}{P_B} = \frac{T_B}{T_C} = \frac{\text{cycleTime}_B}{\text{cycleTime}_C} = \frac{1200}{400} = 3.0$$

# HW 14 part D

A final implementation is also a pipeline of the stages given in part B except that the execute phase, EX, is partitioned into two phases, EX1 and EX2 each requiring 200 ps.

How long is the cycle time for this implementation?

$$\max(150, 100, 200, 200, 300, 150, 100) = 300 \text{ ps}$$

What is the relative performance of this implementation to that of part C?

$$\frac{P_D}{P_C} = \frac{T_C}{T_D} = \frac{\text{cycleTime}_C}{\text{cycleTime}_D} = \frac{400}{300} = 1.333... \approx 1.33$$

# Actual Pipeline CPI

Perfect pipeline (pp) ignores hazards

If each pipeline stage takes 1 cycle  $\text{CPI}_{\text{pp}} = 1$

Actual pipeline (ap) performance

Actual pipeline sometimes stalls due to hazards

A stall is a cycle without useful work

$$\text{CPI}_{\text{ap}} = \text{CPI}_{\text{pp}} + \text{SCPI}_{\text{ap}}$$

$\text{SCPI}_{\text{ap}}$  is **S**tall **C**ycles **P**er **I**nstruction

First calculate  $\text{CPI}_{\text{pp}}$  ignoring stalls

Then add in the average number of stalled cycles

# Memory Access Cost

Pipeline cycles per instruction:

$$CPI_{\text{actual}} = CPI_{\text{perfect pipeline}} + \sum_{h \in \{\text{Hazards}\}} SCPI_h$$

Stall cycles due to *memory access* hazards

$$SCPI_{\text{ma}} = \text{MAPI} \cdot SC_{\text{ma}}$$

**MAPI** – memory accesses per instruction

**SC<sub>ma</sub>** – stall cycles per memory access

**memory access cost (in cycles) – 1**

## Memory Access Cost

$$\text{MAC} = \text{cost}_{\text{hit}} + \text{miss}_{\text{rate}} \cdot \text{miss}_{\text{penalty}}$$

$$\text{hit}_{\text{rate}} = 1 - \text{miss}_{\text{rate}}$$

# Cost due to Memory Hazards

$$\text{SCPI}_{\text{ma}} = \text{MAPI} \cdot \text{SC}_{\text{ma}}$$

**MAPI** Memory Access Per Instruction

*(usually, ~ 1.3)*

Instruction fetch (*always*, 1 per instruction)

Data load (*usually*, ~ 0.2 per instruction)

Data store (*usually*, ~ 0.1 per instruction)

**SC<sub>ma</sub>** Stall Cycles per memory access

memory access cost – 1

$\text{cost}_{\text{hit}} + \text{miss}_{\text{rate}} \cdot \text{cost}_{\text{miss}}$  – 1

# Example Instruction Distribution

50%	ALU	700 ps	(IF, ID, EX, WB)
20%	Load	1000 ps	(IF, ID, EX, MEM, WB)
05%	Store	850 ps	(IF, ID, EX, MEM)
05%	uncond	550 ps	(IF, ID, EX)
20%	cond	700 ps	(IF, ID, EX, M1)

14%

01%

02%

03%

Conditional branches

backwards **(taken)**

backwards **(not taken)**

forwards **(taken)**

forwards **(not taken)**

# Stall Cycles Per Instruction

1 in 20 *loads* causes load-use data hazard

Frequency:

# stall cycles:

SCPI:

2 cycle stall per ***taken*** conditional branch

Frequency:

# stall cycles:

SCPI:

1 in 100 *memory accesses* takes 17 cycles

Frequency:

# stall cycles:

SCPI:

Total SCPI:



# Stall Cycles Per Instruction

1 in 20 *loads* causes load-use data hazard

Frequency:  $0.01 = 0.2 \cdot 0.05$

# stall cycles:  $1$

SCPI:  $0.01 = 0.01 \cdot 1$

2 cycle stall per ***taken*** conditional branch

Frequency:  $0.16 = 0.14 + 0.02$

# stall cycles:  $2$

SCPI:  $0.32 = 0.16 \cdot 2$

1 in 100 *memory accesses* takes 17 cycles

Frequency:  $0.0125 = (1 + 0.2 + 0.05) \cdot 0.01$

# stall cycles:  $16 = 17 - 1$  (last cycle is ***not*** a stall)

SCPI:  $0.20 = 0.0125 \cdot 16$

Total SCPI:  $0.53 = 0.01 + 0.32 + 0.20$

# Example SCPI Problem

This assignment concerns the cost of hazards to a pipeline processor with a perfect pipeline CPI of 1.0. Compute the Stall Cycles Per Instruction (SCPI) for each hazard on a program with the following instruction distribution:

50%	ALU	
20%	Load	
05%	Store	
05%	Unconditional branches	
20%	Conditional branches	(fraction)
	Backward-taken	0.75
	Backward-not-taken	0.10
	Forward-taken	0.05
	Forward-not-taken	0.10

# Example SCPI Hazards

A) **Def-use data hazard:** One out of every 40 ALU instructions is delayed by 3 cycles.

B) **Cache miss hazard:** One out of every 200 memory accesses takes 25 cycles.

C) **Conditional branch hazard:** Every taken conditional branch is delayed 1 cycle.

D) **Exception hazard:** 5 of every million instruction executions encounters an exception that requires 15 thousand cycles to handle.

Finally, what is the CPI of the actual pipeline that experiences each of the above hazards?

$$\text{CPI}_{\text{ap}} = \text{CPI}_{\text{pp}} + \sum_{h \in \{\text{Hazards}\}} f_h \cdot c_h$$

A) **Def-use data hazard:** One out of every 40 ALU instructions is delayed by 3 cycles.

$$\begin{aligned} \text{SCPI}_A &= f_A \cdot c_A \\ &= 0.5 \cdot \frac{1}{40} \cdot 3 \\ &= \frac{1}{80} \cdot 3 \\ &= \frac{3}{80} \\ &= 0.0375 \\ &\approx 0.038 \end{aligned}$$

$$\text{CPI}_{\text{ap}} = \text{CPI}_{\text{pp}} + \sum_{h \in \{\text{Hazards}\}} f_h \cdot c_h$$

B) **Cache miss hazard:** One out of every 200 memory accesses takes 25 cycles.

$$\begin{aligned} \text{SCPI}_B &= f_B \cdot c_B \\ &= \text{MAPI} \cdot \frac{1}{200} \cdot (25 - 1) \\ &= \frac{1 + 0.2 + 0.5}{200} \cdot 24 \\ &= \frac{1.25}{25} \cdot 3 \\ &= 0.05 \cdot 3 \\ &= 0.15 \end{aligned}$$

$$\text{CPI}_{\text{ap}} = \text{CPI}_{\text{pp}} + \sum_{h \in \{\text{Hazards}\}} f_h \cdot c_h$$

**C) Conditional branch hazard:** Every taken conditional branch is delayed 1 cycle.

$$\begin{aligned} \text{SCPI}_c &= f_c \cdot c_c \\ &= 0.2 \cdot (0.75 + 0.05) \cdot 1 \\ &= 0.2 \cdot 0.8 \cdot 1 \\ &= 0.16 \end{aligned}$$

$$\text{CPI}_{\text{ap}} = \text{CPI}_{\text{pp}} + \sum_{h \in \{\text{Hazards}\}} f_h \cdot c_h$$

D) **Exception hazard:** 5 of every million instruction executions encounters an exception that requires 15 thousand cycles to handle.

$$\begin{aligned} \text{SCPI}_D &= f_D \cdot c_D \\ &= \frac{5}{1000000} \cdot 15000 \\ &= \frac{5 \cdot 15}{1000} \\ &= 0.075 \end{aligned}$$

$$\text{CPI}_{\text{ap}} = \text{CPI}_{\text{pp}} + \sum_{h \in \{\text{Hazards}\}} f_h \cdot c_h$$

Finally, what is the CPI of the actual pipeline that experiences each of the above hazards?

$$\begin{aligned} \text{CPI}_{\text{ap}} &= \text{CPI}_{\text{pp}} + \sum_{h \in \{\text{Hazards}\}} \text{SCPI}_h \\ &= 1 + \text{SCPI}_A + \text{SCPI}_B + \text{SCPI}_C + \text{SCPI}_D \\ &= 1 + 0.0375 + 0.15 + 0.16 + 0.075 \\ &= 1.4225 \\ &\approx 1.42 \end{aligned}$$