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Team Control Number

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2018
MCM/ICM
Summary Sheet

The L^AT_EX Template for MCM Version v6.2

Summary

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Keywords: keyword1; keyword2

The L^AT_EX Template for MCM Version v6.2



February 11, 2018

Summary

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Keywords: keyword1; keyword2

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1 Introduction

1.1 Background

1.1.1 Overview of The Problem

1.1.2 A new solution

Electric vehicles are gradually developing towards a niche market as a cleaner promising alternative of transportation. Acknowledge of alleviating the dependency of fuel and reducing green house emissions has brought control use of gas cars a serious position and production of electric vehicles has been raised since they are more effective and less polluted (Li et al., 2016). Unlike gas cars, electric vehicles require frequent charges due to limitation of their causing ability especially for a remote trip over provinces. Therefore, how to distribute chargers stations is a main concern for providing cars owners a more convenient and safe experience. Tesla Inc, an energy company, has already produced several models of technologically electric vehicles successfully and created routes of charges for customers to keep their vehicles charged all the time. However, there are still places to improve for the future development.

The first problem for Tesla is that the current design of charging routes in America might not still be reasonable when Tesla cars become numerous. Secondly, for other countries, population density and geographies are different, the charging routes design varies as well. Moreover, numbers of charging stations in a country are different when it owns different vehicles quantities so charging routes might evolve all the time. Therefore, it makes great sense to consider the main influential factors of a charging route design and to improve the Tesla charging network.

- minimizes the discomfort to the hands, or
- maximizes the outgoing velocity of the ball.

We focus exclusively on the second definition.

- the initial velocity and rotation of the ball,
- the initial velocity and rotation of the bat,
- the relative position and orientation of the bat and ball, and
- the force over time that the hitter hands applies on the handle.

Nulla malesuada porttitor diam. Donec felis erat, congue non, volutpat at, tincidunt tristique, libero. Vivamus viverra fermentum felis. Donec nonummy pellentesque ante. Phasellus adipiscing semper elit. Proin fermentum massa ac quam. Sed diam turpis, molestie vitae, placerat a, molestie nec, leo. Maecenas lacinia. Nam ipsum ligula, eleifend at, accumsan nec, suscipit a, ipsum. Morbi blandit ligula feugiat magna. Nunc eleifend consequat lorem. Sed lacinia nulla vitae enim. Pellentesque tincidunt purus vel magna.

Integer non enim. Praesent euismod nunc eu purus. Donec bibendum quam in tellus. Nullam cursus pulvinar lectus. Donec et mi. Nam vulputate metus eu enim. Vestibulum pellentesque felis eu massa.

- the angular velocity of the bat,
- the velocity of the ball, and
- the position of impact along the bat.

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center of percussion [Brody 1986], Fusce mauris. Vestibulum luctus nibh at lectus. Sed bibendum, nulla a faucibus semper, leo velit ultricies tellus, ac venenatis arcu wisi vel nisl. Vestibulum diam. Aliquam pellentesque, augue quis sagittis posuere, turpis lacus congue quam, in hendrerit risus eros eget felis. Maecenas eget erat in sapien mattis porttitor. Vestibulum porttitor. Nulla facilisi. Sed a turpis eu lacus commodo facilisis. Morbi fringilla, wisi in dignissim interdum, justo lectus sagittis dui, et vehicula libero dui cursus dui. Mauris tempor ligula sed lacus. Duis cursus enim ut augue. Cras ac magna. Cras nulla. Nulla egestas. Curabitur a leo. Quisque egestas wisi eget nunc. Nam feugiat lacus vel est. Curabitur consectetur.

Theorem 1.1. $\mathcal{L}T_{EX}$

Lemma 1.2. T_{EX} .

Proof. The proof of theorem. □

1.2 Other Assumptions

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2 Analysis of the Problem

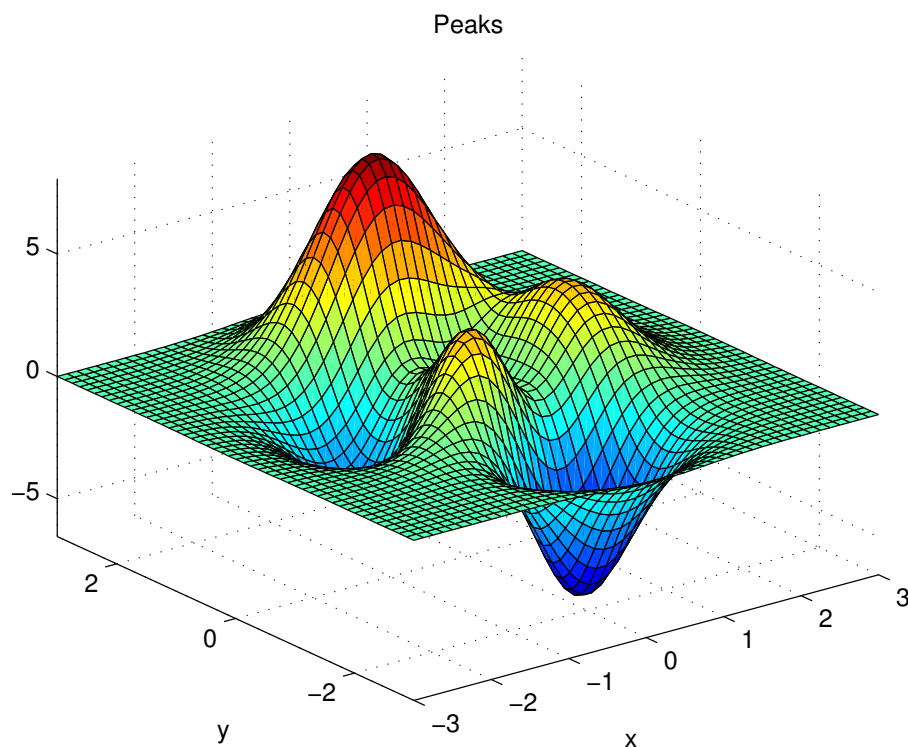


Figure 1: aa

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$$a^2$$

(1)

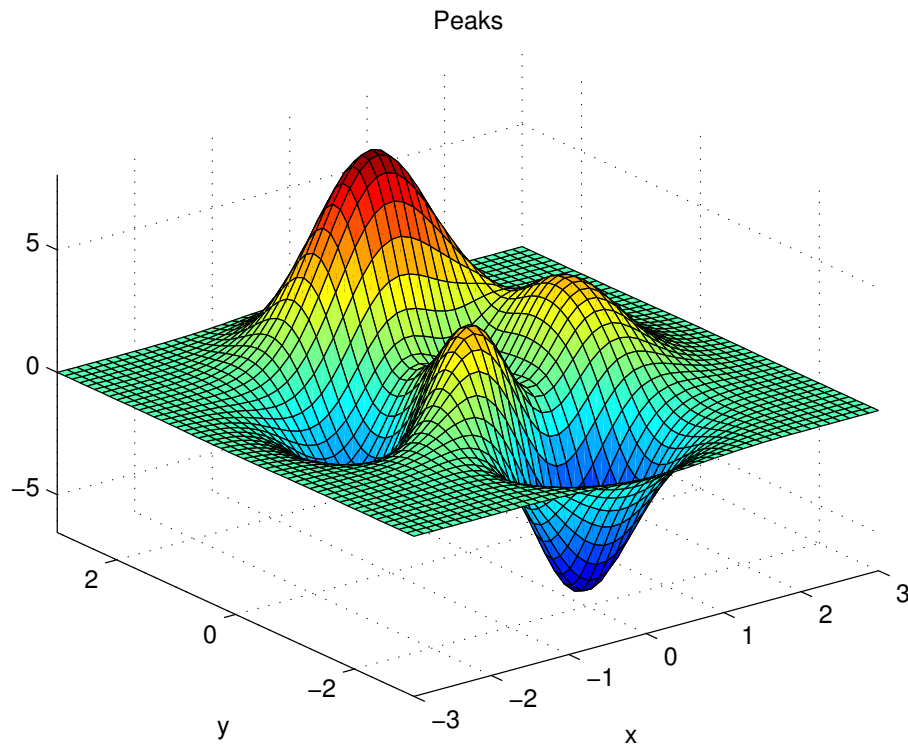


Figure 2: aa

$$\begin{pmatrix} *20ca_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} = \frac{Opposite}{Hypotenuse} \cos^{-1} \theta \arcsin \theta$$

There is the Why you need (1) ha

$$p_j = \begin{cases} 0, & \text{if } j \text{ is odd} \\ r! (-1)^{j/2}, & \text{if } j \text{ is even} \end{cases} \quad (2)$$

Suspendisse vitae elit. Aliquam arcu neque, ornare in, ullamcorper quis, commodo eu, libero. Fusce sagittis erat at erat tristique mollis. Maecenas sapien libero, molestie et, lobortis in, sodales eget, dui. Morbi ultrices rutrum lorem. Nam elementum ullamcorper leo. Morbi dui. Aliquam sagittis. Nunc placerat. Pellentesque tristique sodales est. Maecenas imperdiet lacinia velit. Cras non urna. Morbi eros pede, suscipit ac, varius vel, egestas non, eros. Praesent malesuada, diam id pretium elementum, eros sem dictum tortor, vel consectetur odio sem sed wisi.

$$\arcsin \theta = \bigoplus_{\varphi} \lim_{x \rightarrow \infty} \frac{n!}{r! (n-r)!} \quad (1)$$

3 Calculating and Simplifying the Model

Sed feugiat. Cum sociis natoque penatibus et magnis dis parturient montes, nascetur ridiculus mus. Ut pellentesque augue sed urna. Vestibulum diam eros, fringilla et, consectetur eu, nonummy id, sapien. Nullam at lectus. In sagittis ultrices mauris. Curabitur malesuada erat sit amet massa. Fusce blandit. Aliquam erat volutpat. Aliquam euismod. Aenean vel lectus. Nunc imperdiet justo nec dolor.

4 The Model Results

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5 Validating the Model

Morbi luctus, wisi viverra faucibus pretium, nibh est placerat odio, nec commodo wisi enim eget quam. Quisque libero justo, consectetur a, feugiat vitae, porttitor eu, libero. Suspendisse sed mauris vitae elit sollicitudin malesuada. Maecenas ultricies eros sit amet ante. Ut venenatis velit. Maecenas sed mi eget dui varius euismod. Phasellus aliquet volutpat odio. Vestibulum ante ipsum primis in faucibus orci luctus et ultrices posuere cubilia Curae; Pellentesque sit amet pede ac sem eleifend consectetur. Nullam elementum, urna vel imperdiet sodales, elit ipsum pharetra ligula, ac pretium ante justo a nulla. Curabitur tristique arcu eu metus. Vestibulum lectus. Proin mauris. Proin eu nunc eu urna hendrerit faucibus. Aliquam auctor, pede consequat laoreet varius, eros tellus scelerisque quam, pellentesque hendrerit ipsum dolor sed augue. Nulla nec lacus.

6 Conclusions

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7 A Summary

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8 Evaluate of the Mode

9 Strengths and weaknesses

Etiam euismod. Fusce facilisis lacinia dui. Suspendisse potenti. In mi erat, cursus id, nonummy sed, ullamcorper eget, sapien. Praesent pretium, magna in eleifend egestas, pede pede pretium lorem, quis consectetuer tortor sapien facilisis magna. Mauris quis magna varius nulla scelerisque imperdiet. Aliquam non quam. Aliquam porttitor quam a lacus. Praesent vel arcu ut tortor cursus volutpat. In vitae pede quis diam bibendum placerat. Fusce elementum convallis neque. Sed dolor orci, scelerisque ac, dapibus nec, ultricies ut, mi. Duis nec dui quis leo sagittis commodo.

9.1 Strengths

- **Applies widely**

This system can be used for many types of airplanes, and it also solves the interference during the procedure of the boarding airplane, as described above we can get to the optimization boarding time. We also know that all the service is automate.

- **Improve the quality of the airport service**

Balancing the cost of the cost and the benefit, it will bring in more convenient for airport and passengers. It also saves many human resources for the airline.

-

References

- [1] D. E. KNUTH The T_EXbook the American Mathematical Society and Addison-Wesley Publishing Company , 1984-1986.
- [2] Lamport, Leslie, L^AT_EX: " A Document Preparation System ", Addison-Wesley Publishing Company, 1986.
- [3] <http://www.latexstudio.net/>
- [4] <http://www.chinatex.org/>

Appendices

θa^2	2	Here are simulation programmes we used in our model as follow
4	5	6
7	8	9

Appendix A First appendix

Aliquam lectus. Vivamus leo. Quisque ornare tellus ullamcorper nulla. Mauris porttitor pharetra tortor. Sed fringilla justo sed mauris. Mauris tellus. Sed non leo. Nullam elementum, magna in cursus sodales, augue est scelerisque sapien, venenatis congue nulla arcu et pede. Ut suscipit enim vel sapien. Donec congue. Maecenas urna mi, suscipit in, placerat ut, vestibulum ut, massa. Fusce ultrices nulla et nisl.

Here are simulation programmes we used in our model as follow.

Input matlab source:

```
function [t,seat,aisle]=OI6Sim(n,target,seated)
pab=rand(1,n);
for i=1:n
    if pab(i)<0.4
        aisleTime(i)=0;
    else
        aisleTime(i)=trirnd(3.2,7.1,38.7);
    end
end
end
```

Appendix B Second appendix

some more text **Input C++ source:**

```
//=====
// Name      : Sudoku.cpp
// Author    : wzlf11
// Version   : a.0
// Copyright  : Your copyright notice
// Description : Sudoku in C++.
//=====

#include <iostream>
#include <cstdlib>
#include <ctime>

using namespace std;

int table[9][9];

int main() {

    for(int i = 0; i < 9; i++){
```

```
        table[0][i] = i + 1;
    }

    srand((unsigned int)time(NULL));

    shuffle((int *)&table[0], 9);

    while(!put_line(1))
    {
        shuffle((int *)&table[0], 9);
    }

    for(int x = 0; x < 9; x++){
        for(int y = 0; y < 9; y++){
            cout << table[x][y] << " ";
        }

        cout << endl;
    }

    return 0;
}
```
