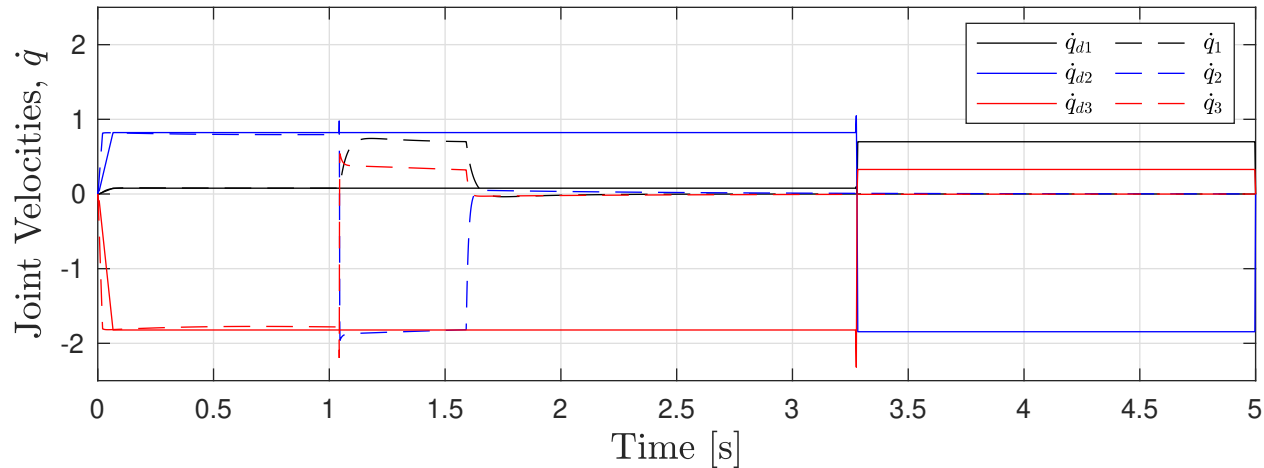


# End Effector Velocity with Adaptive control



# End Effector Velocity with PD control

