PD Control Home-Mass Mass-Mass Mass-Home $-RRT^*$ $-RRT^*$ $-RRT^*$ ---- Path Taken ---- Path Taken ---- Path Taken Desired State Desired State Desired State Initial State Initial State Initial State 1.6 1.5 1.5 13 0.5 0.8 -0.5 0.6 -1.5 🗸 -0.5 3.8 3.6 1.5 3.2 0.5