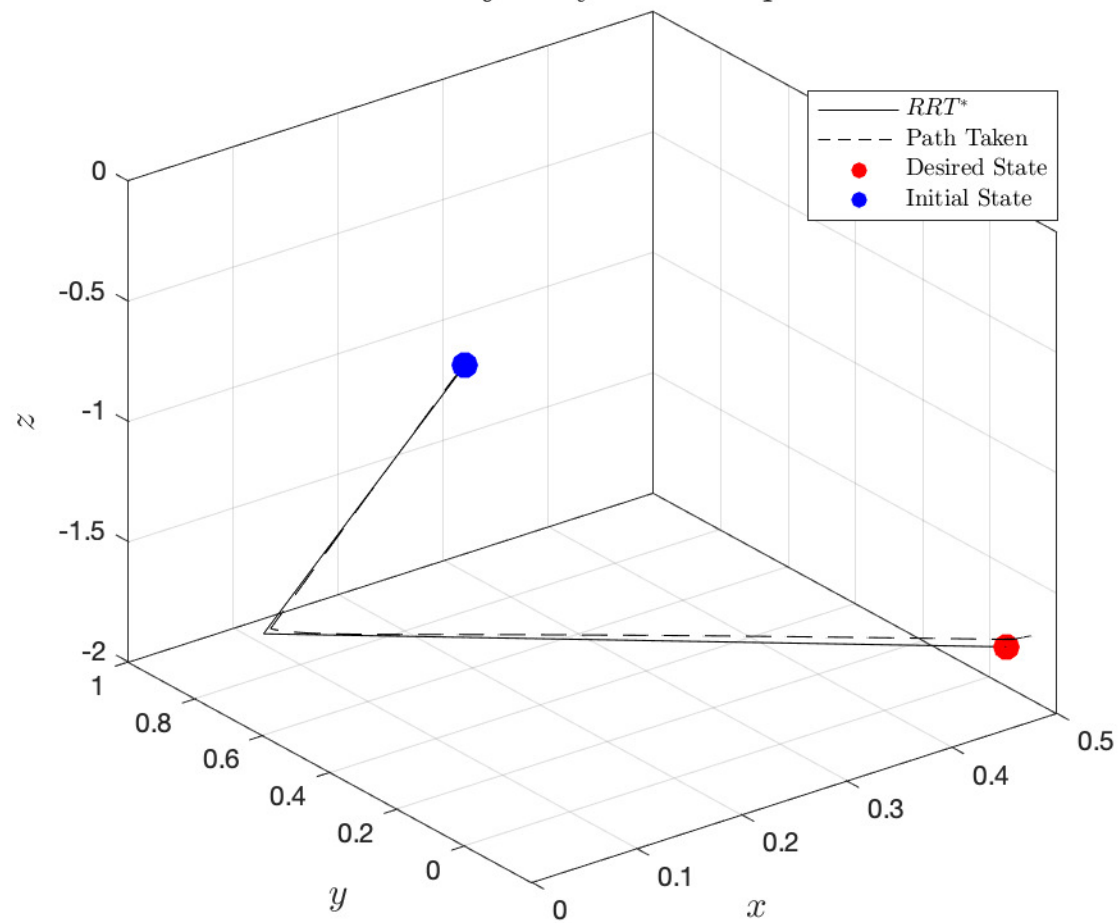


End Effector Trajectory with Adaptive Control



End Effector Trajectory with PD Control

