

Showing divergence free velocity fields from a Stokeslet

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We have that the velocity from a regularized Stokeslet (with fluid viscosity $\mu = 1$) is

$$\mathbf{u} = (\mathbf{f} \cdot \nabla) \nabla B_\epsilon(r) - \mathbf{f} \nabla^2 B_\epsilon(r),$$

where $r = |\mathbf{x}|$ and the radially symmetric function B_ϵ varies with the choice of blob function. The assumption of radial symmetry allows us to make some simplifications. In the following, ∂_i means take the derivative with respect to the i -th Cartesian coordinate, and n is the dimension of the domain.

$$\begin{aligned} \nabla B_\epsilon &= \frac{B'_\epsilon(r)}{r} \mathbf{x} \\ ((\mathbf{f} \cdot \nabla) \nabla B_\epsilon)_j &= \sum_{i=1}^n f_i \partial_i \left(\frac{B'_\epsilon(r)}{r} x_j \right) \\ &= \sum_{i=1}^n \frac{B'_\epsilon(r)}{r} f_i \delta_{ij} + \sum_{i=1}^n x_j f_i \partial_i \frac{B'_\epsilon(r)}{r} \\ &= \frac{B'_\epsilon(r)}{r} f_j + \sum_{i=1}^n x_j \frac{f_i x_i}{r} \left(\frac{B''_\epsilon(r)}{r} - \frac{B'_\epsilon(r)}{r^2} \right) \\ \Rightarrow (\mathbf{f} \cdot \nabla) \nabla B_\epsilon &= \frac{B'_\epsilon(r)}{r} \mathbf{f} + \left(\frac{B''_\epsilon(r)}{r^2} - \frac{B'_\epsilon(r)}{r^3} \right) (\mathbf{f} \cdot \mathbf{x}) \mathbf{x}. \end{aligned}$$

Then we may write

$$\begin{aligned} \mathbf{u} &= \left(\frac{B'_\epsilon(r)}{r} - \nabla^2 B_\epsilon(r) \right) \mathbf{f} + \left(\frac{B''_\epsilon(r)}{r^2} - \frac{B'_\epsilon(r)}{r^3} \right) (\mathbf{f} \cdot \mathbf{x}) \mathbf{x} \\ &= H_1(r) \mathbf{f} + H_2(r) (\mathbf{f} \cdot \mathbf{x}) \mathbf{x}. \end{aligned} \tag{1}$$

The Laplacian in H_1 introduces different dependencies on $B'_\epsilon(r)$ in two and three dimensions. In two dimensions,

$$\begin{aligned} H_1^{2D} &= \frac{B'_\epsilon(r)}{r} - \nabla^2 B_\epsilon \\ &= \frac{B'_\epsilon(r)}{r} - \frac{1}{r} (r B'_\epsilon(r))' \\ &= \frac{B'_\epsilon(r)}{r} - \frac{1}{r} (B'_\epsilon(r) + r B''_\epsilon(r)) \\ &= -B''_\epsilon(r). \end{aligned} \tag{2}$$

Additionally, in two dimensions we add a constant to H_1 , to remove a constant flow induced everywhere by the Stokeslet. This is equivalent to solving for a shifted velocity field. Since the divergence of a constant times the force, $c\mathbf{f}$, is zero, we ignore it in the following work.

In three dimensions, the Laplacian has a different form, and consequently, so does H_1 :

$$\begin{aligned}
H_1^{3D} &= \frac{B'_\epsilon(r)}{r} - \nabla^2 B_\epsilon \\
&= \frac{B'_\epsilon(r)}{r} - \frac{1}{r^2} (r^2 B'_\epsilon(r))' \\
&= \frac{B'_\epsilon(r)}{r} - \frac{1}{r^2} (2r B'_\epsilon(r) - r^2 B''_\epsilon(r)) \\
&= \frac{B'_\epsilon(r)}{r} - \frac{2B'_\epsilon(r)}{r} - B''_\epsilon(r) \\
&= -B''_\epsilon(r) - \frac{B'_\epsilon(r)}{r}.
\end{aligned} \tag{3}$$

We take the divergence (in Cartesian coordinates) of Eq. (1) in n dimensions:

$$\begin{aligned}
\nabla \cdot \mathbf{u} &= \sum_{i=1}^n \partial_i (H_1(r) f_i) + \partial_i (H_2(r) (\mathbf{f} \cdot \mathbf{x}) x_i) \\
&= \sum_{i=1}^n \frac{H'_1(r)}{r} f_i x_i + \sum_{i=1}^n \frac{H'_2(r)}{r} (\mathbf{f} \cdot \mathbf{x}) x_i^2 + \sum_{i=1}^n H_2(r) (\mathbf{f} \cdot \mathbf{x}) + \sum_{i=1}^n H_2(r) f_i x_i \\
&= \frac{H'_1(r)}{r} (\mathbf{f} \cdot \mathbf{x}) + \frac{H'_2(r)}{r} (\mathbf{f} \cdot \mathbf{x}) r^2 + n H_2(r) (\mathbf{f} \cdot \mathbf{x}) + H_2(r) (\mathbf{f} \cdot \mathbf{x}) \\
&= (\mathbf{f} \cdot \mathbf{x}) \left(\frac{H'_1(r)}{r} + r H'_2(r) + (n+1) H_2(r) \right).
\end{aligned}$$

In order for \mathbf{u} to be divergence free, we require that $\frac{H'_1(r)}{r} + r H'_2(r) + (n+1) H_2(r) = 0$. In both two and three dimensions, we have that

$$\begin{aligned}
H'_2(r) &= \frac{\partial}{\partial r} \left(\frac{B''_\epsilon(r)}{r^2} - \frac{B'_\epsilon(r)}{r^3} \right) \\
&= \frac{B'''_\epsilon(r)}{r^2} - \frac{2B''_\epsilon(r)}{r^3} - \frac{B''_\epsilon(r)}{r^3} + \frac{3B'_\epsilon(r)}{r^4} \\
\Rightarrow r H'_2(r) &= \frac{B'''_\epsilon(r)}{r} - \frac{3B''_\epsilon(r)}{r^2} + \frac{3B'_\epsilon(r)}{r^3}.
\end{aligned}$$

In two dimensions,

$$\frac{(H_1^{2D})'(r)}{r} = -\frac{B'''_\epsilon(r)}{r},$$

so that

$$\begin{aligned}
\frac{H'_1(r)}{r} + r H'_2(r) + (n+1) H_2(r) &= -\frac{B'''_\epsilon(r)}{r} + \frac{B'''_\epsilon(r)}{r} - \frac{3B''_\epsilon(r)}{r^2} + \frac{3B'_\epsilon(r)}{r^3} + \frac{3B''_\epsilon(r)}{r^2} - \frac{3B'_\epsilon(r)}{r^3} \\
&= 0,
\end{aligned}$$

yielding a divergence free velocity field as desired. In three dimensions,

$$\begin{aligned}\frac{(H_1^{3D})'(r)}{r} &= \frac{1}{r} \left(-B_\epsilon'''(r) - \frac{B_\epsilon''(r)}{r} + \frac{B_\epsilon'(r)}{r^2} \right) \\ &= -\frac{B_\epsilon'''(r)}{r} - \frac{B_\epsilon''(r)}{r^2} + \frac{B_\epsilon'(r)}{r^3},\end{aligned}$$

so that

$$\begin{aligned}\frac{H_1'(r)}{r} + rH_2'(r) + (n+1)H_2(r) &= -\frac{B_\epsilon'''(r)}{r} - \frac{B_\epsilon''(r)}{r^2} + \frac{B_\epsilon'(r)}{r^3} + \frac{B_\epsilon'''(r)}{r} - \frac{3B_\epsilon''(r)}{r^2} + \frac{3B_\epsilon'(r)}{r^3} \\ &\quad + \frac{4B_\epsilon''(r)}{r^2} - \frac{4B_\epsilon'(r)}{r^3} \\ &= 0,\end{aligned}$$

also yielding a divergence free velocity. This is the expected result, since the solution for \mathbf{u} is constructed using the incompressibility condition.

However, instead of starting with a blob function and deriving B_ϵ , one could replace $B'(r) = -1/8\pi$ (the derivative of the biharmonic function in the singular case) with a regularizing function $B'_\delta(r) = -(1/8\pi)F_\delta(r)$. By defining H_1 and H_2 using $B'_\delta(r)$ instead of $B'_\epsilon(r)$ in Eqs. (1), (2), and (3), we have just shown that a divergence free velocity would result. One could then back-solve to discover the associated blob function. This is what Karin did in the Brinkman paper.