## 6\_Quiz \_L2

- Due Dec 2 at 2:15pm
- Points 10
- Questions 10
- Available until Dec 2 at 2:15pm
- Time Limit 15 Minutes

## Instructions

This is a timed, closed book, closed notes quiz.

There are 10 questions.

Total time is 15 mins.

You can navigate front and back.

For code related questions, write the whole code in the area provided.

There should not be any other tab or window open on your laptop while you are attempting the quiz. Offenders will get a 0.

You cannot use chatgpt or any other AI tool to obtain answers. Offenders will get a 0.

Good luck!!!

This quiz was locked Dec 2 at 2:15pm.

## **Attempt History**

	Attempt	Time	Score
LATEST	Attempt 1	9 minutes	10 out of 10
(!) Correct answers a	are hidden.		
Score for this quiz: 10	out of 10		
Submitted Dec 2 at 2:0	02pm		
This attempt took 9 mi	nutes.		
0 0 0 0 0 0			
Question 1			
1 / 1 pts			
Concurrency requires	implementation of		and
Race Condition			
Synchronization			
Mutual Exclusion			
Critical Section			
* * * * * * * * * * * * * * * * * * *			
Question 2			
1 / 1 pts			
Race conditions happe	en when		(Choose all that apply)
<b>V</b>			
Due to interrupts as one t	hread is unable to finish its	s update of the shared	variable before a second thread accesses
the same shared variable			
Two or more threads t	ry to access a shared varia	able.	
▼ Two or more threads expression is a second of the second of t	enter critical section at the	same time	
CPU is idle			
::			

1 / 1 pts
Which of the following functions in the POSIX threads (pthreads) API is used to create a new thread?
<pre>pthread_mutex_lock() pthread_exit() pthread_join() pthread_create()  Question 4 1 / 1 pts</pre>
What is the primary purpose of a mutex in a multi-threaded program?
<ul> <li>To automatically distribute workloads between threads</li> <li>To terminate threads after execution</li> <li>To provide mutual exclusion for shared resource access</li> <li>To enable threads to communicate with each other</li> <li>Question 5</li> <li>1 / 1 pts</li> </ul>
In POSIX threads, which function is used to lock a mutex?
<pre>pthread_mutex_lock()  pthread_lock()  pthread_mutex_init()  pthread_mutex_acquire()  ii  Question 6 1 / 1 pts</pre>
What will happen if a thread attempts to lock a mutex that it has already locked in POSIX threads?
<ul> <li>The thread will raise a segmentation fault.</li> <li>The thread will be blocked indefinitely.</li> <li>The thread will sleep</li> <li>The thread will lock the mutex and continue execution.</li> <li>Question 7</li> <li>1 / 1 pts</li> </ul>
In lock-based concurrent data structures, which strategy is often used to ensure that updates to shared data are atomic?
<ul> <li>Read-write locks</li> <li>Mutex Locks</li> <li>Condition variables</li> <li>Spinlocks</li> <li></li> <li>Question 8</li> <li>1 / 1 pts</li> </ul>
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What is a significant disadvantage of using mutex locks in concurrent programming?

Question 3

They cannot be used in multi-core processors.
They prevent race conditions but can lead to excessive CPU usage.
They introduce the risk of deadlock and contention between threads.
They guarantee that all threads will execute concurrently without interference.
Question 9
1 / 1 pts
What is the purpose of using the mutex queue->lock in the enqueue and dequeue functions in the following code:

```
1
     #include <stdlib.h>
     #include <pthread.h>
     typedef struct Queue {
         int* data;
         int front;
         int rear;
         int capacity;
9
         pthread_mutex_t lock;
10
     } Queue;
11
     void initQueue(Queue* queue, int capacity) {
12
         queue->data = (int*)malloc(sizeof(int) * capacity);
13
         queue->front = queue->rear = 0;
14
15
         queue->capacity = capacity;
16
         pthread_mutex_init(&queue->lock, NULL);
17
18
19
     void enqueue(Queue* queue, int value) {
20
         pthread_mutex_lock(&queue->lock);
21
         if ((queue->rear + 1) % queue->capacity == queue->front)
22
              printf("Queue is full\n");
23
         } else {
24
             queue->data[queue->rear] = value;
25
             queue->rear = (queue->rear + 1) % queue->capacity;
26
27
         pthread_mutex_unlock(&queue->lock);
28
     }
29
30
     int dequeue(Queue* queue) {
31
         pthread_mutex_lock(&queue->lock);
32
         if (queue->front == queue->rear) {
33
              printf("Queue is empty\n");
34
             pthread_mutex_unlock(&queue->lock);
35
             return -1; // Empty queue
36
         } else {
37
              int value = queue->data[queue->front];
38
              queue->front = (queue->front + 1) % queue->capacity;
39
              pthread_mutex_unlock(&queue->lock);
40
              return value;
41
42
43
44
     int main() {
45
         Queue queue;
46
         initQueue(&queue, 5);
47
         enqueue(&queue, 1);
48
         enqueue(&queue, 2);
49
         enqueue(&queue, 3);
```

```
printf("Dequeued value: %d\n", dequeue(&queue));
printf("Dequeued value: %d\n", dequeue(&queue));

return 0;

The mutex is used to prevent memory allocation errors when the queue becomes full.

Question 10
```

1 / 1 pts

Which of the following best describes "critical section" in the context of concurrency?

- A section of code that only one thread should access at a time to ensure data consistency.
- A section of memory shared between all threads for faster access.
- A section of code where multiple threads are allowed to run concurrently without synchronization.
- A section of code where threads are prevented from executing at all.

Quiz Score: 10 out of '