RESULT: (P. 233 8TH ED.)
P. 244 7TH ED.)

IF S= { V1, V2, ...., Vn } 15 A BASIS FOR A VECTOR SPACE V THEN EVERY VECTOR U IN WICAN BE EXPRESSED IN THE FORM

10 = C1V1 + C2 V2 + .... + CnVn IN EXACTLY ONE WAY.

## PROOF:

2 = CIVI + CZVZ + .... + CNVn AND U = KIVI + K2V2 + .... + KNVn

SUBTRACTING THE SECOND FQU-ATION FROM THE FIRST GIVES

0 = (C1-K1)V1 + (C2-K2)V2+ .....

···+ (Cn-kn) Un

THE LINEAR INDEPENDENCE OF VECTORS IN { VI, V2, ...., Vn }

IMPLIES THAT

CI-KI=0, C2-K2=0, ...., Cn-Kn=0

=> C1= K1, C2= K2, ...., Cn= Kn WHICH COMPLETES THE PROOF. (1) {(1,0), (0,1)} IS STANDARD BASIS FOR R2.

(2) { (-3,7), (5,5) } IS A BASIS
BUT NOT A STANDARD BASIS
FOR P2

RECALL: (x,y) = x(1,0) + y(0,1)AND  $(x,y) = (y-x)(-3,7) + (7x+3y)^{1}$ 

 $\Rightarrow (x,y) = (y-x)(-3,7) + (7x+3y)(5,5)$ 

HOMOGENEOUS LINEAR SYSTEM

FOR AX = 0 , EXACTLY P.16 STHED,

ONE OF THE FOLLOWING

IS TRUE:

(I) THE SYSTEM HAS DNLY

THE TRIVIAL SOLUTION (ZERO

SOLUTION) IF A IS INVERTIBLE

(2) SYSTEM HAS INFINITELY MANY SOLUTIONS (NONTRIVIAL) IN ADDITION TO THE TRIVIAL SOLUTION.

i.e. A IS SINGULAR OR UNKNOW-NS ARE MORE THAN EQUATIONS. 3 IF S= {V1, V2, ...., V91} IS A NON-EMPTY SET OF VECTORS, THEN IN VECTOR EQUATION KIVI + K2 V2 + .... + K91 V2 = 0 IF ANY ONE OF THE SCALARS Ki +0,1 SIS LINEARLY DEPENDENT AND ALL THE VECTORS Vi,1 < ish, ARE LINEARLY DEPENDENT VECTORS. (P.112 6th ED.) (P. 232 7th ED.) EXAMPLE: CHECK WHETHER {(2,2),(1)]} IS INDEPENDENT OR DEPENDENT? SOLUTION: LET  $k_1(2,2) + k_2(1,1) = (0,0) - 1$  $\Rightarrow$   $2K_1 + K_2 = 0$ 2 K1+K2=0  $\Rightarrow \begin{bmatrix} 2 \\ 2 \end{bmatrix} \begin{bmatrix} k_2 \\ k_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ 

 $\begin{bmatrix} 2 \\ 2 \end{bmatrix} \begin{bmatrix} K_1 \\ K_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ ,  $det \begin{bmatrix} 2 \\ 2 \end{bmatrix} = 0$ 

4

: NONTRIVIAL (NONZERD)
SOLUTIONS EXIST, : GIVEN
VECTORS ARE LINEARLY DEPENDENT.

NOTE: IN  $2K_1 + K_2 = 0$ LET  $(K_1 = t)$ ,  $(K_2 = -2t)$ , IF (t = 1),  $K_1 = 1$ ,  $K_2 = -2$  WE GET (2,2) - 2(4) = (0,0)(2,2) = 2(1,1) FROM (1)

NOTE: RECALL THAT IF

AX=0 REPRESENTS A

HOMOGENEOUS SYSTEM OF

EQUATIONS THEN INFINITELY

MANY NONTRIVIAL (NONZERO)

SOLUTIONS EXIST IF A

IS SINGULAR i.e. det(A)=0

OR AT DOESN'T EXIST.

RE SULTS: 1 {CIVILICA, 2)} IS LINEARLY DEPENDENT AND 2) {(5,5), (-3,7)} IS LINEARLY INDEPENDENT (PROVED LAST TIME) CEOMETRIC INTERPRETATION IN (R2 TWO VECTORS ARE LINEARLY DEPE NDENT IF THEY LIE ON THE SAME LINE. 一日= (リリ) OP = (2,2) IN (R2) TWO VECTORS ARE LINEARLY INDE-PENDENT IF THEY DO NOT LIE ON THE SAME LINE.

NOTE: ALSO FOR ANY VECTOR SPACE V, THE SET [ VI, V23) IS DEPENDENT IF VI, V2 ARE SCALAR MULTIPLES OF EACHOTH FR AND {UI, UZ 3 IS INDEPL ENDENT IF AND ONLY IF NEITHER VECTOR IS A SCALAR MULTIPLE OF EACH OTHER. AS WE SAW THAT { (1,1), (2,2)} IS DEPEN-DENT AND (C2,2)=2(U) i.e. (1)1), (2,2) ARE SCALAR MULTIPLES OF EACHOTHER. ? (-3,7), (5,5) } IS INDER ENDENT AND NONE OF (-3,7), (5,5) IS A SCALAR MULTIPLE OF THE OTHER. 

EXAMPLE: P.222 (6th ED.) LT P. 232 (7th ED.) 7 LET VI = (2,-1,0,3), V2=(1,2,5,-1) AND V3 = (7,-1,5,8) THEN (a) CHECK WHETHER {U1,U2,V3} IS LINEARLY DEPENDENT OR INDEPENDENT. SOLUTION: LET KIVI+K2V2+K3V3 =0 / 中 K1(2,-1,0,3) 十 K2(1,2,5,-1)+K3(7,-1,5,8) = (0,0,0,0) -- (1) COMPARING BOTH SIDES 2K1 + K2 + 7K3 = 0 -> 2  $-K_1 + 2K_2 - K_3 = 0 \rightarrow 3$  $K_2 + K_3 = 0 \rightarrow 4$ 3k1-K2+8K3=0+5 WHICH IS A HOMOGENEOUS SYSTEM OF GEQUATIONS WITH THREE UNKNOWNS. SO THERE ARE TWO POSSIBILITIES TO SOLVE THIS SYSTEM, LE SOLUE 2,3,9 AND CHECK IF THE SOLUTION SATISFIES 5 OR ONLY SOLVE @, 3,9 " (5) CAN BE OBTAINED BY SUBTRACTING 3 FROM 2  $\begin{array}{c} ? & 2K_1 + K_2 + 7K_3 = 0 \rightarrow @ ] SUB - \\ = & K_1 + 2K_2 - K_3 = 0 \rightarrow @ ) \\ \hline = & K_1 + 2K_2 - K_3 = 0 \rightarrow @ ) \\ = & K_1 + 2K_2 - K_3 = 0 \rightarrow @ ) \\ \hline = & K$ 3K1-K2+8K3=0+5 NOW IN MATRIX NOTATION, WE HAVE  $\begin{bmatrix} 2 & 1 & 7 \\ -1 & 2 & -1 \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 6 \\ 0 \\ 0 \end{bmatrix}$ BUT DET [217] = 0 (CHECK) .. NONTRIVIAL SOLUTIONS EXIST THE GIVEN VECTORS ARE LINEARLY DEPENDENT : 3, 3,4 ARE SATISFIED BY NONZERO VALUES OF KIJKZ AND K3

SINCE THE SYSTEM IS

HOMOGENEOUS AND THE

COEFFICIENT MATRIX IS

NOT INVERTIBLE i-e. A-1

DOESN'T EXIST THEREFORE

INFINITE NONTRIVIAL (NONZERO)

SOLUTIONS EXIST FOR

AX = 0 WHERE

 $A = \begin{bmatrix} 2 & 1 & 7 \\ -1 & 2 & -1 \\ 0 & 1 & 1 \end{bmatrix}, X = \begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix}$ 

(b) PROVE THAT V3 CAN BE WRITTEN AS THE LINEAR COMBINATION OF V2 AND V1.

SOLUTION: HINT: FOR

THIS WE HAVE TO SOLVE

THE ABOVE SYSTEM i-e.

AX=0 FOR KI, K2 AND K3, i.e.

10 | SOLUTIONOF  $2k_1 + k_2 + 7k_3 = 0 - 0$  |

TO FIND THE  $-k_1 + 2k_2 - k_3 = 0 - 0$  |  $-k_1 + 2k_2 - k_3 = 0 - 0$  |  $-k_2 + k_3 = 0 - 0$  | LET  $K_1=t$   $3 \Rightarrow K_3=-K_2=-t$ 1 => K1= 2K2-K3= 2t-(-t)=3t  $\begin{bmatrix} k_1 \\ k_2 \\ k_3 \end{bmatrix} = \begin{bmatrix} 3t \\ t \\ -t \end{bmatrix} = t \begin{bmatrix} 3 \\ 1 \end{bmatrix}_{ALSO}$ SATISFIES FOR (t=1, K1=3, K2=1, K3=-1) KIVI + K2 V2 + K3 V3 = 3(2,-1,0,3)+(1,2,5,-1) -(7,-1,5,8)=(6,-3,0,9)+ (-6,3,0,-9) = (0,0,0,0)⇒ 3V1 + V2 - V3 = 0 OR 13 = 12 +34 RESULT: (P.224 6th ED.) (P.234 7th ED.) A SET S WITH TWO OR MORE VECTORS IS

(A) LINEARLY DEPENDENT IF AND ONLY IF AT LEAST ONE OF THE VECTORS IN S IS EXPRESSIBLE AS A LINEAR COMBINATION OF THE OTHER VECTORS IN S.

M

E.G. IN THE LAST EXAMPLE

{VI, V2, V3} IS DEPENDENT

AND V3 = V2 + 3V1 i.e. V3 IS

A LINEAR COMBINATION OF

VI AND V2.

(b) LINEARLY INDEPENDENT

IF AND ONLY IF NO VECTOR IN

S IS EXPRESSIBLE AS A

LINEAR COMBINATION OF THE

OTHER VECTORS IN S

E.C. { e1, e2, e3} IS LINEARLY

INDEPENDENT : NONE OF e1,

e2, e3 IS A LINEAR COMBINA

ATION OF THE OTHER TWO.

LET e3 = k1e1 + k2e2

 $\Rightarrow e_3 = k_1 e_1 + k_2 e_2$   $\Rightarrow (0,0,1) = k_1(1,0,0) +$ 

K2 (0,1,0) => (0,0,1) = (k1, k2,0) WHICH IS NOT POSSIBLE AS A LINEAR COMBINATION e, AND e2.