

LINEAR ALGEBRA PROOFS

Q) Show that if AB and BA are both defined, then AB and BA are square matrix.

Solution: if AB is defined, a column of A is equal to rows of B ; if BA is defined it means a column of B equals rows of A . This means that AB and BA have equal rows & columns and thus are square matrix.

Q) Show that if A is $m \times n$ matrix and $A(BA)$ is defined, then B is an $n \times m$ matrix.

Mathematically

- let A is $m \times n$ matrix and B is $m_1 \times n$, matrix
- if $A(BA)$ is defined then first (BA) should be defined so $n_1 = m$ so (BA) becomes $m_1 \times n$ size
- Now if $A(BA)$ is defined then $n = m_1$ so the size of matrix becomes $m \times n$
- So this implies matrix B becomes $n \times m$.

Q) Show that if A has row of zeros and B is any matrix for which AB is defined, then AB also has row of zeros.

Assume that the entries of i -th row of A are all zeros.

We claim that the i -th row of AB is a row of zeros.

To see this pick an entry c_{ij} in the i -th row of AB . By definition of multiplication of AB , we have

$$c_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \dots + a_{in}b_{nj} = \sum_{k=1}^n a_{ik}b_{kj}$$

Since i -th row of A is zero, we have $a_{i1} = a_{i2} = \dots = a_{in} = 0$

$$c_{ij} = 0b_{1j} + 0b_{2j} + \dots + 0b_{nj} = \sum_{k=1}^n 0b_{kj} = 0$$

Hence i -th row of AB is a row of zeros.

* NO SOLUTION \rightarrow INCONSISTENT

* ATLEAST ONE SOLUTION \rightarrow CONSISTENT

* NON-SINGULAR/INVERTIBLE \rightarrow inverse of A exists and $\det(A) \neq 0$

* SINGULAR \rightarrow no inverse exists and $\det(A) = 0$

* HOMOGENOUS \rightarrow in $AX = B$, $B = 0 \rightarrow$ CONSISTENT

* NON-HOMOGENOUS \rightarrow $B \neq 0$

Q) If A and B are two square matrices of same size then find the condition such that

$$(A+B)^2 = A^2 + B^2 + 2AB.$$

$$(A+B)^2 = (A+B)(A+B)$$

$$= A^2 + \underline{AB + BA + B^2}$$

\rightarrow if A and B commute then

$$AB = BA$$

$$\therefore (A+B)^2 = A^2 + 2AB + B^2$$

Q) If B and C are both inverses of matrix A then
 $B = C$

$\therefore B$ is an inverse of A we have,

$$BA = I \quad \text{--- (1)}$$

$$C(BA) = I(C)$$

but $(BA)C = B(AC)$ by ASSOCIATIVE LAW

$$B(AC) = I(C)$$

$$BI = CI \quad \therefore AC = I$$

$B = C$ (proved)

Q) If A and B are invertible matrices of same size, then

$$(AB)^{-1} = B^{-1}A^{-1}$$

$$\text{Consider } (AB)(B^{-1}A^{-1}) = A(BB^{-1})A^{-1}$$

$$= A(I)A^{-1}$$

$$= AA^{-1} = I \quad \text{--- (1)}$$

$$(B^{-1}A^{-1})(AB) = B^{-1}(A^{-1}A)B$$

$$= B^{-1}B = I \quad \text{--- (2)}$$

from (1) and (2)

$$(AB)^{-1} = B^{-1}A^{-1} \quad (\text{proved})$$

* TO BE CONSISTENT A ROW HAS TO BE COMPLETELY ZERO.

* For an equation to be linear

① Variables should have no power ② Do not indulge any products or roots of variables ③ Variables do not appear as arguments for trigonometry, logarithmic or exponential function.

Q) If A and B are of same size then $(A+B)^T = A^T + B^T$

$$\text{Let } A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \quad B = \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix}$$

$$(A+B)^T = \begin{bmatrix} a_{11}+b_{11} & a_{12}+b_{12} \\ a_{21}+b_{21} & a_{22}+b_{22} \end{bmatrix}^T - ①$$

$$\text{also } A^T + B^T = \begin{bmatrix} a_{11} & a_{21} \\ a_{12} & a_{22} \end{bmatrix} + \begin{bmatrix} b_{11} & b_{21} \\ b_{12} & b_{22} \end{bmatrix} = \begin{bmatrix} a_{11}+b_{11} & a_{21}+b_{21} \\ a_{12}+b_{12} & a_{22}+b_{22} \end{bmatrix}$$

$$\therefore (A+B)^T = A^T + B^T$$

→ A square matrix A is called SYMMETRIC if $A^T = A$

→ A square matrix A is called SKEWSYMMETRIC if $A^T = -A$
↳ diagonal always ZERO.

→ If A is invertible then $Ax=0$ has trivial solution.

Q) If $AX=B$ represents a system of n equations in n variables then prove that solution is unique if A is invertible.

$$A^{-1}AX = A^{-1}B$$

$$X = A^{-1}B \quad \text{is unique } \because (AA^{-1} = I, IX = X)$$

→ ELEMENTARY ROW OPERATIONS

① Multiply a row by a non zero

② Interchange two rows

③ Add a multiple of one row to another

→ Equivalent Matrices is when one or more ERO is applied on matrix

→ Elementary Matrices is obtained by performing one single ERO on identity matrix.

Q) Since $Ax=0$ has only $x=0$ solution, Theorem 1.6.4 guarantees that A is invertible.

Q) Let $Bx=0$ be a homogeneous system of linear equation such that coefficient matrix is a square matrix and the system has only trivial solution. Show that if m is positive integer, then the system $B^m x=0$ also has only trivial solution.

Given $Bx=0$ then $B^m x=0$

$$\text{using theorem } (B^m)^{-1} = (B^{-1})^m$$

$$B^m x = 0$$

$$(B^m)^{-1} B^m x = (B^m)^{-1} 0$$

$$\underbrace{B^{-1} \dots B^{-1}}_{m \text{ times}} \cdot \underbrace{B \dots B}_{m \text{ time}} x = 0$$

$$I x = 0$$

$$x = 0$$

Q) Let $Ax=0$ be a homogeneous solution of n linear equation in n unknowns and let \varnothing be an invertible $n \times n$ matrix. Show that $Ax=0$ has just a trivial solution if & only if $(\varnothing A)x=0$ has just trivial sol.
Let $Ax=0$ holds.

$$\varnothing(Ax) = \varnothing 0$$

$$(\varnothing A)x = 0 \quad \therefore \text{Associative property}$$

Now we let $(\varnothing A)x=0$ and we apply \varnothing^{-1}

$$\underbrace{\varnothing^{-1} \varnothing}_{I} A x = \varnothing^{-1} 0$$

$$I A x = 0$$

$$A x = 0.$$



d) Suppose that x_1 is a fixed number which satisfies the equation $Ax_1 = b$. Further let x be any matrix whatsoever which satisfies $Ax = b$. We must then show that there is a matrix x_0 which satisfies both eq $x = x_1 + x_0$ and $Ax_0 = 0$. Clearly the ① eq implies that $x_0 = x - x_1$.

Given $x = x_1 + x_0$

$$x_0 = x - x_1$$

$$A(x_0) = A(x_1 - x)$$

$$A(x_0) = A(x_1) - A(x)$$

$$= b - b = 0$$

$$A(x_0) = 0$$

Now we show that $A(x_1 + x_0)$ has solution.

$$A(x_1 + x_0) = A(x_1) + A(x_0)$$

$$= b + 0$$

$$A(x_1 + x_0) = b$$

(parallel) (coincident)

→ When $\det(A) = 0$ then there will be NO SOLUTION/INFINITE

SOLUTION

→ When $\det(A) \neq 0$ then there is UNIQUE SOLUTION (Intersection of lines)

→ If A is NOT INVERTIBLE, then $\det(A) = 0$

→ If two columns/rows are IDENTICAL then $\det(A) = 0$

→ If a square matrix with two proportional rows/column, then $\det(A) = 0$

→ If a row/column of zeros, then $\det(A) = 0$

→ If a scalar k is multiplied $\det(B) = k\det(A)$

→ Adding row/column then determinant remains SAME.

→ If row/column interchanging then $\det(B) = -\det(A)$

→ Determinant of identity matrix, $\det(I) = 1$

Q) Let A and B be $n \times n$ matrices. Show that if A is invertible then $\det(B) = \det(A^{-1}BA)$

$$\begin{aligned}\det(A^{-1}BA) &= \det(A^{-1}) \det(B) \det(A) \\ &= \frac{1}{\det(A)} \det(B) \det(A) \\ &= \det(B) \quad (\text{proved})\end{aligned}$$

Q) Let A and B be $n \times n$ matrices. You know from earlier work that AB is invertible if A and B are invertible. What can you say about the invertibility of AB if one or both of the factors are singular? If either A or B is singular, then either $\det(A) = 0$ or $\det(B) = 0$. Hence $\det(AB) = \det(A)\det(B) = 0$. Thus AB is also singular.

Q) Prove that if $\det(A)=1$ and all entries in A are integers, then all the entries in A^{-1} are integers. This follows from theorem 2.1.2 and the fact that the cofactors of A are integers if A has only integer entries since integers are under multiplication addition & subtraction $A^{-1} = \frac{1}{\det(A)} \text{adj}(A) = \frac{\text{adj}(A)}{\det(A)}$

Q) If B is $n \times n$ matrix and E is an elementary matrices of order $n \times n$ then $\det(EB) = \det(E)\det(B)$. If E is performed by multiplying row of I_n by scalar of k then this means that

$$EB = C \quad (\text{say})$$

$$\det(EB) = \det(C)$$

$$\det(EB) = k \det(B)$$

$$\text{Since } \det(E) = k \det(I) = k$$

$$\det(EB) = \det(E)\det(B).$$



Q) If A and B are square matrices of same size then
 $\det(AB) = \det(A)\det(B)$

CASE 1 IF A IS NOT INVERTIBLE

We have $\det(AB) = 0$ by Theorem 1.6.5 and $\det(A) = 0$
This implies

$$\det(AB) = 0 \cdot \det(B)$$

$$\det(AB) = \det(A)\det(B).$$

CASE 2 IF A IS INVERTIBLE

We take A as product of elementary matrices

$$A = E_r E_{r-1} \dots E_2 E_1$$

$$AB = E_r E_{r-1} \dots E_2 E_1 B$$

$$\det(AB) = \det(E_r E_{r-1} \dots E_2 E_1) \det(B)$$

$$\det(AB) = \det(E_r) \det(E_{r-1}) \dots \det(E_2) \det(E_1) \det(B)$$

$$\det(AB) = \det(A) \det(B)$$

Q) Show that a matrix with a row of zeros cannot have an inverse OR Show that a matrix with column of zeros cannot have an inverse.

Let A denote a matrix which has an entire row or an entire column of zeros. Then B is any matrix, either AB has an entire row of zeros or BA has entire column of zeros. Hence neither AB nor BA can be identity matrix, therefore A cannot have inverse.

Q) Show that the diagonal entries of 3×3 skew symmetric matrix are all zero.

Let $A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$ and $A^T = -A$ (skew-symmetric)

$$- \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = \begin{bmatrix} a_{11} & a_{21} & a_{31} \\ a_{12} & a_{22} & a_{32} \\ a_{13} & a_{23} & a_{33} \end{bmatrix}$$

$$\begin{bmatrix} a_{11} & a_{21} & a_{31} \\ a_{12} & a_{22} & a_{32} \\ a_{13} & a_{23} & a_{33} \end{bmatrix} + \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 2a_{11} & a_{21} + a_{12} & a_{31} + a_{13} \\ a_{12} + a_{21} & 2a_{22} & a_{32} + a_{23} \\ a_{13} + a_{31} & a_{23} + a_{32} & 2a_{33} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Equating the components of the matrices, so we have diagonal entries a_{11}, a_{22}, a_{33} equals to 0.

Q) Consider $AX=0$ has only trivial solution & want to prove that A can be transformed into I_n or row reduced echelon form.

$$\left[\begin{array}{ccc|c} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ a_{31} & a_{32} & \dots & a_{3n} \end{array} \right] \begin{array}{l} 0 \\ 0 \\ 0 \end{array}$$

This we can achieve with the idea of ERO which will transform the augmented matrix into

$$\left[\begin{array}{cccc|c} 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & 0 \end{array} \right]$$

If we disregard the last column, we can conclude that the matrix is in row reduced echelon form.



Q) If A and B are $n \times n$ matrices, then $\text{tr}(A+B) = \text{tr}(A) + \text{tr}(B)$

Note that the (i,i) -th entry of $A+B$ is $a_{ii}+b_{ii}$ the (i,i) -th entry of A^T is a_{ii} and the (i,i) -th entry of B^T is b_{ii} . Then consider the following

$$\begin{aligned}\text{tr}(A+B) &= (a_{11} + b_{11}) + \dots + (a_{nn} + b_{nn}) \\ &= (a_{11} + \dots + a_{nn}) + (b_{11} + \dots + b_{nn}) \\ &= \text{tr}(A) + \text{tr}(B)\end{aligned}$$

Q) Let A be any $m \times n$ matrix and let O be the $m \times n$ matrix each of whose entries is zero. Show that if $kA=O$ then $k=0$ or $A=O$

Given $kA=O$ and suppose $k \neq 0$ so

$$kA=O$$

$$\frac{1}{k}kA = \frac{1}{k}O$$

$$A=O$$

Now suppose $A \neq O$, if $kA=O$ and A is nonzero then the only possibility this outcome ($kA=O$) is $k=0$.

Q) Let $Ax=b$ be a system of n linear equations in n unknowns with integer coefficients & integer constants. Prove that if $\det(A)=1$ the solution x has integer entries.

Solution to $Ax=b$ is $x=A^{-1}b$, so A^{-1} is from the previous solution (the fact that cofactors of A are integers if A has only integer entries $A^{-1} = \frac{1}{\det(A)} \text{adj}(A) = \text{adj}(A)$ and multiplication, addition

& subtraction of integers are closed. Hence x has also integer entries) is an integer, so A^{-1} multiplied by b is also integer.



Q) Use relationship b/w elementary matrices & elementary row operation (ERO) to show that (EROS) that transform A to I will also transform I to A^{-1} . Let \mathcal{Q} be any ERO and E be the elementary matrix corresponding to \mathcal{Q} then,

$$\mathcal{Q}(A) = EA = B$$

Let $\mathcal{Q}_1, \mathcal{Q}_2, \dots, \mathcal{Q}_n$ be n number of EROS and E_1, E_2, \dots, E_n are elementary matrices such that when applied on an invertible matrix ' A ' give ' I '

$$\mathcal{Q}_n \dots \mathcal{Q}_1(A) = E_n \dots E_2 E_1 A = I$$

$$\text{where } P = E_n \dots E_2 E_1$$

$$PA = I \Rightarrow A \sim I$$

$$PAA^{-1} = IA^{-1}$$

$$PI = A^{-1} \Rightarrow I \sim A^{-1}$$

Q) Show that if A is invertible then prove that $(A^{-1})^T = (A^T)^{-1}$
we know that

$$(AA^{-1}) = I$$

Apply transpose on both sides

$$((A^{-1})(A))^T = I^T$$

$$A^T (A^{-1})^T = I$$

$$\underbrace{(A^T)^{-1}}_{I} A^T (A^{-1})^T = I (A^T)^{-1}$$

$$I (A^{-1})^T = (A^T)^{-1}$$

$$(A^{-1})^T = (A^T)^{-1} \quad (\text{proved})$$

Q) Let A be a non-singular $n \times n$ matrix. Show that $A^{-1} = \frac{\text{adj}(A)}{\det(A)}$

[You may assume that if $i \neq j$, then $a_{i1}c_{j1} + a_{i2}c_{j2} + \dots + a_{in}c_{jn} = 0$]

Let $A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \ddots & a_{2n} \\ \vdots & & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix}$

$\text{Adj } A = \begin{bmatrix} c_{11} & c_{21} & \dots & c_{n1} \\ c_{12} & \ddots & & \vdots \\ \vdots & & \ddots & \vdots \\ c_{n1} & & & c_{nn} \end{bmatrix}$

$$A \text{ Adj } A = \begin{bmatrix} a_{11}c_{11} + a_{12}c_{12} + \dots + a_{1n}c_{1n} & \dots \\ \vdots & \vdots \end{bmatrix}$$

using if $i \neq j$ then $a_{i1}c_{j1} + a_{i2}c_{j2} + \dots + a_{in}c_{jn} = 0$. All off diagonal gets zero. Only diagonal entries remaining

$$A \text{ Adj } A = \begin{bmatrix} \det(A) & 0 & \dots & 0 \\ 0 & \det(A) & & \\ \vdots & & \ddots & \\ 0 & & & \det(A) \end{bmatrix} = \det(A) I_n$$

Hence $A \text{ Adj } A = \det(A) I_n \Rightarrow A^{-1} = \frac{\text{adj}(A)}{\det(A)}$ $\therefore A$ is non-singular

Q) Let A be $n \times n$ matrix. Then prove that if reduced row-echelon form of A is I_n then A is expressible as product of elementary matrices.

If $A \xrightarrow{\text{EROs}} I_n$

then $A = E_1 \dots E_k$



To show,

let E_1, \dots, E_k is applied on A and it becomes I_n

$$E_n \dots E_1 A = I_n$$

$$E_n^{-1}(E_n E_{n-1} \dots E_1) A = E_n^{-1} I_n$$

$$(E_n^{-1} E_n)(E_{n-1} \dots E_1) A = E_n^{-1}$$

$$(I_n)(E_{n-1} \dots E_1) A = E_n^{-1}$$

Similarly for all E_i

$$A = E_1^{-1} E_2^{-1} \dots E_{n-1}^{-1} E_n^{-1} \quad (\text{proved})$$

$\rightarrow \det(kA) = k^n \det(A)$ where n is number of rows.

\rightarrow Minor is $ad - bc$

\rightarrow Cofactor is $(-1)^{i+j} M_{ij}$

\rightarrow Determinant of 3×3 Matrix

$$A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} \quad |A| = a(ei - fh) - b(di - gf) + c(dh - eg)$$

here minor is

$$\begin{vmatrix} e & f \\ g & i \end{vmatrix} \text{ of } a.$$

\rightarrow Adjoint (A)

$$\begin{bmatrix} C_{11} & C_{12} & C_{13} \\ C_{21} & C_{22} & C_{23} \\ C_{31} & C_{32} & C_{33} \end{bmatrix}^T$$

\rightarrow taking transpose of cofactors is adjoint of A .

\rightarrow To find $A^{-1} = \frac{1}{\det(A)} \text{adj}(A)$.

$$\rightarrow \vec{P_1 P_2} = \overrightarrow{OP_2} - \overrightarrow{OP_1}$$

$$\rightarrow \text{length of vector } u, \|u\| = \sqrt{u_1^2 + u_2^2}$$

$$\rightarrow \text{unit vector} = \frac{v}{\|v\|}$$

$$\left\{ \begin{array}{l} \rightarrow u \cdot v = \|u\| \|v\| \cos \theta \\ \rightarrow \text{orthogonal vector } \vec{u} \cdot \vec{v} = 0 \\ \rightarrow e_i \cdot e_j = 0 \text{ if } i \neq j \\ \rightarrow e_i \cdot e_j = 1 \text{ if } i = j \end{array} \right.$$

Q) Prove that any vector in 3-dimensional e.g. $u = (u_1, u_2, u_3)$ can be written as linear combination of e_1, e_2 and e_3 .

$$u = u_1 e_1 + u_2 e_2 + u_3 e_3$$

$$e_1 = (1, 0, 0) \quad e_2 = (0, 1, 0) \quad e_3 = (0, 0, 1)$$

$$= u_1 (1, 0, 0) + u_2 (0, 1, 0) + u_3 (0, 0, 1)$$

$$= u_1 (u_1, 0, 0) + (0, u_2, 0) + (0, 0, u_3) \Rightarrow (u_1, u_2, u_3) = \overrightarrow{OP} = u.$$

Q) If $u = (u_1, u_2, u_3) = u_1 e_1 + u_2 e_2 + u_3 e_3$ and $v = (v_1, v_2, v_3) = v_1 e_1 + v_2 e_2 + v_3 e_3$ then $u \cdot v = u_1 v_1 + u_2 v_2 + u_3 v_3$.

$$u \cdot v = (u_1 e_1 + u_2 e_2 + u_3 e_3) \cdot (v_1 e_1 + v_2 e_2 + v_3 e_3)$$

$$= u_1 v_1 e_1 \cdot e_1 + u_1 v_2 e_1 \cdot e_2 + u_1 v_3 e_1 \cdot e_3 + u_2 v_1 e_2 \cdot e_1 + u_2 v_2 e_2 \cdot e_2$$

$$+ u_3 v_3 e_3 \cdot e_3$$

$$= u_1 v_1 + u_2 v_2 + u_3 v_3.$$

→ Dot product of vector with itself is square of its norm.

→ V is called vector space if following properties are satisfied.

① for all $u, v \in V$, $u+v \in V$ which means V is closed under VECTOR ADDITION

② $u+v=v+u$ (commutative property)

③ $u+(v+w)=(u+v)+w$ (associative property)

④ $0+u=u+0=u$

⑤ Negative of u / Additive inverse of u $u+(-u)=(-u)+u=0$

⑥ $k u$, if k is any scalar & u is an object then V is closed under SCALAR MULTIPLICATION

⑦ $k(u+v) = ku+kv$

⑧ $(k+l)u = ku + lu$

⑨ $k(lu) = (kl)u$

⑩ $1u = u$.



Q) $V = R^n$

$$v_1 = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix}, v_2 = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$v_1 + v_2 = \begin{bmatrix} a_1 + b_1 \\ a_2 + b_2 \\ \vdots \\ a_n + b_n \end{bmatrix} \in R^n$$

Q) Prove $\|u + v\| \leq \|u\| + \|v\|$

$$\|u + v\|^2 = (u + v)(u + v)$$

$$= (u \cdot u) + 2(u \cdot v) + (v \cdot v)$$

$$= \|u\|^2 + 2\|u\|\|v\| + \|v\|^2$$

$$= (\|u\| + \|v\|)^2$$

$$\|u + v\| = \|u\| + \|v\|$$

Q) $(u + v) \cdot w = u \cdot w + v \cdot w$

$$\begin{aligned} (u + v) \cdot w &= (u_1 + v_1, u_2 + v_2, \dots, u_n + v_n) \cdot (w_1, \\ &\quad w_2, \dots, w_n) \\ &= (u_1 + v_1)w_1 + (u_2 + v_2)w_2 + \dots + \\ &\quad (u_n + v_n)w_n \\ &= (u_1 w_1 + u_2 w_2 + \dots + u_n w_n) + \\ &\quad (v_1 w_1 + v_2 w_2 + \dots + v_n w_n) \\ &= u \cdot w + v \cdot w \end{aligned}$$

Q) $d(\vec{u}, \vec{v}) \leq d(\vec{u}, \vec{w}) + d(\vec{w}, \vec{v})$

$$d(\vec{u}, \vec{v}) = d(\vec{u}, \vec{v})$$

$$= \|\vec{u} - \vec{v}\|$$

$$= \|(\vec{u} - \vec{w}) + (\vec{w} - \vec{v})\|$$

$$= \|\vec{u} - \vec{w}\| + \|\vec{w} - \vec{v}\|$$

$$= d(\vec{u}, \vec{w}) + d(\vec{w}, \vec{v})$$

Q) Prove $\vec{u} \cdot \vec{v} = \frac{1}{4} \|u + v\|^2 - \frac{1}{4} \|u - v\|^2$

Q) $u \cdot u \geq 0$. Further if $u \cdot u = 0$ if

and only if $u = 0$.

We have $u \cdot u = u_1^2 + u_2^2 + \dots + u_n^2 \geq 0$

$$\frac{1}{4} \|u + v\|^2 - \frac{1}{4} \|u - v\|^2 = \frac{1}{4} (\vec{u} + \vec{v}).$$

further equality holds if and if

$u_1 = u_2 = \dots = u_n = 0$ - that is if

and only if $u = 0$:

$$(\vec{u} + \vec{v}) - \frac{1}{4} (\vec{u} - \vec{v})(\vec{u} - \vec{v})$$

$$= \frac{1}{4} (\vec{u} \cdot \vec{u} + \vec{v} \cdot \vec{u} + \vec{u} \cdot \vec{v} + \vec{v} \cdot \vec{v})$$

Q) If $u = (u_1, u_2, \dots, u_n)$ then

$ku = (ku_1, ku_2, \dots, ku_n)$, prove

that $\|ku\| = \|k\| \|u\|$

$$\|ku\| = \sqrt{(ku_1)^2 + (ku_2)^2 + \dots + (ku_n)^2}$$

$$= |k| \sqrt{(u_1)^2 + (u_2)^2 + \dots + (u_n)^2}$$

$$= |k| \|u\|$$

$$- \frac{1}{4} (\vec{u} \cdot \vec{u} - \vec{v} \cdot \vec{u} - \vec{u} \cdot \vec{v} + \vec{v} \cdot \vec{v})$$

$$= \frac{1}{4} (4 \vec{u} \cdot \vec{v}) = \vec{u} \cdot \vec{v}$$

$$Q) (\vec{A}\vec{u}) \cdot \vec{v} = \vec{u} \cdot (\vec{A}^T \vec{v})$$

$$(\vec{A}\vec{u}) \cdot \vec{v} = (\vec{A}\vec{u})^T \cdot \vec{v}$$

$$= \vec{u}^T \vec{A}^T \vec{v} \quad \because \vec{u}^T = \vec{u}$$

$$(\vec{A}\vec{u}) \cdot \vec{v} = \vec{u} \cdot (\vec{A}^T \vec{v})$$

Q) Prove $0\vec{u} = \vec{0}$.

$$Ax 8 \Rightarrow (k+l)\vec{u} = k\vec{u} + l\vec{u}$$

$$0\vec{u} + 0\vec{u} = (0+0)\vec{u}$$

$$Ax 4 \Rightarrow u \in V \Leftrightarrow -u \in V$$

$$0\vec{u} + 0\vec{u} + (-0\vec{u}) = 0\vec{u} + (-0\vec{u})$$

$$Ax 3 \Rightarrow 0\vec{u} + (0\vec{u} + (-0\vec{u})) = 0\vec{u} + (-0\vec{u})$$

$$Ax 5 \Rightarrow 0\vec{u} + 0 = 0$$

$$Ax 4 \Rightarrow 0\vec{u} = 0$$

$$Q) \|u+v\|^2 + \|u-v\|^2 = 2(\|u\|^2 + \|v\|^2)$$

$$\|u+v\|^2 = (u+v)(u+v)$$

$$= \|u\|^2 + 2\|u\|\|v\| + \|v\|^2$$

$$\|u-v\|^2 = (u-v)(u-v)$$

$$= (u-u) - 2(u \cdot v) + (v \cdot v)$$

$$= \|u\|^2 - 2\|u\|\|v\| + \|v\|^2$$

Adding both eqs.

$$\|u\|^2 + 2\|u\|\|v\| + \|v\|^2 + \|u\|^2 -$$

$$2\|u\|\|v\| + \|v\|^2$$

$$= 2(\|u\|^2 + \|v\|^2)$$

Q) Prove $(-1)\vec{u} = -\vec{u}$

$$\vec{u} + (-1)\vec{u} = \vec{0}$$

$$1\vec{u} + (-1)\vec{u} = \vec{0}$$

$$(1 + (-1))\vec{u} = \vec{0}$$

$$0\vec{u} = \vec{0}$$

Q) Prove: If u and v are vectors in \mathbb{R}^n and k is any scalar, then

$$u \cdot (kv) = k(u \cdot v)$$

$$\vec{u} \cdot (kv) = (u_1, u_2, \dots, u_n) \cdot (k(v_1, v_2, \dots, v_n))$$

$$= (u_1, u_2, \dots, u_n) \cdot (kv_1, kv_2, \dots, kv_n)$$

$$= u_1(kv_1) + u_2(kv_2) + \dots + u_n(kv_n)$$

$$= k u_1 v_1 + k u_2 v_2 + \dots + k u_n v_n$$

$$= k(u_1 v_1 + u_2 v_2 + \dots + u_n v_n)$$

$$= k(\vec{u} \cdot \vec{v})$$

Q) Show that u and v are orthogonal vectors in \mathbb{R}^n if

$$\|u+v\| = \|u-v\|.$$

$$u \cdot v = \frac{1}{4} \|u+v\|^2 - \frac{1}{4} \|u-v\|^2. \text{ Now}$$

(b) The result states a theorem about parallelogram in \mathbb{R}^2 , what is the theorem?

It states that sum of squares of length of four sides of a parallelogram equals sum of squares of length of two diagonals.

substitute $\|u+v\| = \|u-v\|$, we have $u \cdot v = \frac{1}{4} \|u-v\|^2 - \frac{1}{4} \|u-v\|^2$, so

$$u \cdot v = 0. \text{ Hence it is orthogonal}$$

Q) Prove $d(u, v) \geq 0$.

$$d(u, v) = \|u-v\| = \sqrt{(u_1-v_1)^2 + \dots + (u_n-v_n)^2}$$

hence by property of squaring each component it must be greater and equal to zero.



Q) Prove the following generalization of Theorem 4.1.7. If v_1, v_2, \dots, v_n are pairwise orthogonal vectors in \mathbb{R}^n , then

$$\|v_1 + v_2 + \dots + v_r\|^2 = \|v_1\|^2 + \|v_2\|^2 + \dots + \|v_r\|^2$$

$$\|v_1 + v_2 + \dots + v_r\|^2 = \|v_1 + (v_2 + \dots + v_r)\|^2$$

$$= \|v_1\|^2 + \|v_2 + v_3 + \dots + v_r\|^2$$

$$\text{We know } \|v_1 + v_2\|^2 = \|v_1\|^2 + \|v_2\|^2 \quad \because v_i, v_j \text{ are orthogonal}$$

Apply this procedure $r-1$ times

$$= \|v_1\|^2 + \|v_2\|^2 + \dots + \|v_r\|^2$$

Q) Prove: If u and v are $n \times 1$ matrices and A is $n \times n$ an matrix then $(v^T A^T A u)^2 \leq (u^T A^T A u)(v^T A^T A v)$

Let $u = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix}$ be vectors and $v = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$ in \mathbb{R}^n and let

A be an $n \times n$ matrix. So, letting $u = Au$ and $v = Av$ and this multiplication possible. Hence the inner product is $(a, b) = a \cdot b = b^T a$

$$(u, v) = Au \cdot Av = (Av)^T Au$$

$$\text{So we have } (u, v) = v^T A^T A u$$

In special case we have $(u, u) = u^T A^T A u$ and $(u, v) = v^T A^T A v$

The Cauchy-Schwarz inequality is

$$(u, v)^2 \leq (u, u)(v, v)$$

By substituting the previous we get

$$(u^T A^T A u)^2 \leq (u^T A^T A u)(v^T A^T A v).$$



$$\rightarrow \text{Proj}_a u = \frac{(u \cdot a)}{\|a\|^2} a$$

\rightarrow Vector component of u orthogonal to a $u - \text{proj}_a u$

Q) If u and v are vectors in 2-space or 3-space and $4 \neq 0$

then $\text{proj}_a u = \frac{(u \cdot a)}{\|a\|^2} a$ and $u - \text{proj}_a u = u - \frac{(u \cdot a)}{\|a\|^2} a$

$$u = w_1 + w_2$$

$$\therefore w_1 = ka$$

$$u = ka + w_2$$

$$w_2 = u - ka$$

taking dot product with a

$$w_2 \cdot a = (u - ka) \cdot a = 0$$

$$u \cdot a - ka \cdot a = 0$$

$$k = \frac{u \cdot a}{a \cdot a} = \frac{(u \cdot a)}{\|a\|^2} = k$$

$$\therefore w_1 = \frac{(u \cdot a)}{\|a\|^2} a \quad \text{and} \quad w_2 = u - \frac{(u \cdot a)}{\|a\|^2} a.$$

Q) Let V be vector space and the zero vector of V is 0 . If k is some scalar, then prove that $k0 = 0$.

$$k0 + k0 = k(0+0) \therefore \text{Axiom 7}$$

$$k0 + k0 = k(u) \therefore \text{Axiom 4}$$

$$(k0 + k0) + (-k0) = k(u) + (-k0)$$

$$k0 + (k0 + (-k0)) = (k0 + (-k0))$$

$$k0 + 0 = 0$$

$$k0 = 0 \quad (\text{proved})$$

Q) Show that it is not possible for vector u in vector space V to have two different additive inverses both of which satisfy axioms for vector space.

Let there exists two inverses of u .

$$u + u_1 = 0 \quad \text{and} \quad u + u_2 = 0$$

$$u + u_1 = 0$$

$$u_2 + (u + u_1) = u_2 + 0$$

$$(u_2 + u) + u_1 = u_2$$

$$0 + u_1 = u_2$$

$$u_1 = u_2$$