| NSGS-AC (iter=10) | | NSGS-JM | |
|--|---------|---|--|
| NSGS-AC $(ho_{\mathbf{N}} = ho_T = 1)$ | | NSGS-JM-GP | |
| NSGS-AC $(ho_{\mathbf{N}} = ho_T = rac{1}{\lambda_{\max}(W)})$ | | NSGS-FP-VI-UPK iter=10 | |
| NSGS-AC $(\rho_{\mathbf{N}} = \frac{1}{\lambda_{max}(W_{\mathbf{N},\mathbf{N}})}, \rho_T = \frac{\lambda_{max}(W)}{\lambda_{max}(W_{\mathbf{N},\mathbf{N}})})$ | | NSGS-FP-VI-UPK iter=100 | |
| $ \text{NSGS-AC} \; (\rho_{\mathbf{N}} \; = \frac{1}{\lambda_{\max}(W_{NN})}, \rho_{T} \; = \frac{\lambda_{\max}(W)}{\lambda_{\max}(W_{TT})}) \\ \text{NSGS-AC-} \; (\text{iter=10}) $ | | NSGS-FP-DS-One | |
| NSGS-AC (iter=100) | | NSGS-EXACT | |
| NSGS-AC-GP (iter=100) | | NSGS-FP-VI-UPK $tol_{local} = 10^{-06}$ | |
| NSGS-AC-GP (Adaptive local tol) | . — — — | NSGS-FP-VI-UPK $tol_{local} = 10^{-14}$ | |
| NSGS-AC-GP (Adaptive local tol contact) | | | |
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