

Evaluating Non-Expert Annotations for Natural Language Tasks

Abstract

Human linguistic annotation is crucial for many natural language processing tasks, but acquiring such labels can be extremely expensive and time-consuming. We explore Amazon’s Mechanical Turk system, a significantly cheaper and quicker method for collecting annotations from a broad base of non-expert volunteer contributors over the Web. We investigated five sufficiently simple tasks: recognizing textual entailment, affect recognition, word similarity, event temporal ordering, and word sense disambiguation. For all five, we show high agreement between Mechanical Turk volunteers and existing gold standard labels provided by expert labelers. For the task of affect recognition, we also show that using Turker labels for training machine learning algorithms can be as effective as using gold standard annotations from experts. We offer some methodological insights, and include bias correction, and time and completion studies. We conclude that many (although not all) large labeling tasks can be effectively designed and carried out in this method at a fraction of the usual monetary and temporal costs.

1 Introduction

Large scale annotation projects such as TreeBank (Marcus et al., 1993), ProbBank (Palmer et al., 2005), TimeBank (Pustejovsky et al., 2003), FrameNet (Baker et al., 1998), SemCor (Miller et al., 1993), and many others play an important role in statistical natural language processing, encouraging the development of novel ideas, tasks, and algorithms. The construction of these datasets, however,

is extremely expensive in annotator-hours as well as money. Since the performance of many natural language processing tasks is limited by the amount and quality of data available to them (Banko and Brill, 2001), a promising alternative, at least for some tasks, is collecting annotations from non-expert volunteers.

In this work we explore such a system, Amazon Mechanical Turk¹ (AMT) to study whether non-expert volunteers on the web can provide reliable natural language annotations. Our goals are to produce high quality labels for a number of NLP tasks, to investigate which tasks are appropriate for this kind of annotation, and to develop the methodological framework for achieving high-accuracy labels.

We chose five natural language understanding tasks that we felt would be sufficiently natural and learnable for non-experts, and for which we had gold standard labels from expert labelers, as well as (in some cases) human labeler agreement information. The tasks are: affect recognition, word similarity, recognizing textual entailment, event temporal ordering, and word sense disambiguation.

For each task, we used AMT to annotate data and measured the quality of the annotations by comparing them with the gold standard (expert) labels on the same data, and by using the AMT annotations to train machine learning classifiers. In the next sections of the paper we introduce the five tasks and the evaluation metrics, as well as our new methodological tools.

¹Amazon Mechanical Turk may be found online at <http://mturk.com>.

2 Related Work

The idea of collecting valuable annotations for use in machine learning from volunteer contributors has been employed for a variety of tasks; Luis von Ahn pioneered the collection of data via online annotation tasks in the form of games, including the ESPGame for labeling images (von Ahn and Dabbish, 2004) and Verbosity for filling in word relations (von Ahn et al., 2006). The Open Mind Initiative (Stork, 1999) has taken a similar approach, attempting to make such tasks as annotating word sense (Chklovski and Mihalcea, 2002) and common-sense word relations (Singh, 2002) sufficiently “easy and fun” to entice users into freely labeling data.

There have been an increasing number of experiments using Mechanical Turk for annotation. In (Su et al., 2007) workers provided output for four tasks in attribute extraction and entity resolution, including hotel name resolution, and extraction of age, product brand, and product model. Using previously acquired gold-standard labels the non-expert annotations were found to have high accuracy. In (Nakov, 2008) workers generated paraphrases of 250 noun-noun compounds in order to improve paraphrase-based noun compound interpretation; here the non-expert annotations were used as the gold standard dataset for evaluation of an automatic method of noun compound paraphrasing, and no external gold standard dataset was compared against. (Kaisser and Lowe, 2008) use AMT to help build a dataset for Question Answering. Following on to corpora constructed for the TREC QA Evaluation (Voorhees and Dang, 2006), where answers to factoid questions are annotated at the document level, (Kaisser and Lowe, 2008) used AMT to annotate the answers to 8107 questions at the more fine-grained level (the *sentence* containing the answer). (Kaisser et al., 2008) examines the task of customizing the summary length of query results in a QA system; here non-experts from AMT were requested to give their opinion of what ideal summary length suited their information needs for varying query types. (Zaenen, 2008) studied the agreement of annotators on the problem of recognizing textual entailment (a similar task and dataset is explained in more detail in Section 4).

3 Task Design

In this section we describe Amazon Mechanical Turk and the experimental design we use for our set of experiments.

3.1 Amazon Mechanical Turk

We employ the Amazon Mechanical Turk system in order to elicit annotations from non-expert volunteers. The design of the system is as follows: one is required to have an Amazon account to either submit tasks for annotations or to annotate submitted tasks. These Amazon accounts are anonymous, but are referenced by a unique Amazon ID. A *Requester* can create a *group* of *Human Intelligence Tasks* (or *HITs*), and each *HIT* may be composed of an arbitrary number of questions. The user requesting annotations for the group of *HITs* can specify the number of unique annotations per *HIT* they are willing to pay for, as well as the price of each individual *HIT*. While this does not guarantee that unique people will annotate the task (since a single person could conceivably annotate tasks using multiple accounts, in violation of the user agreement), this does guarantee that annotations will be collected from unique accounts. Annotators (variously referred to as *Workers* or *Turkers*) then may annotate the tasks of their choosing. Finally, after each *HIT* has been annotated, the Requester has the option of approving the work and optionally giving a bonus to individual workers. There is a two-way communication channel between the task designer and the workers mediated by Amazon, and Amazon handles all financial transactions.

3.2 Task Design

In general we follow a few simple design principles: we attempt to keep our task descriptions as succinct as possible, and we attempt to give demonstrative examples for each class wherever possible. We do not include our task instructions here for lack of space, however we have published our full experimental design and the data we collect online². We have restricted our study to tasks where we require only a multiple-choice response or numeric in-

²All tasks and collected data have been published on an anonymous website for purposes of review at <http://nlpannotations.googlepages.com>.

put within a fixed range. Also, although AMT allows a requestor to only allow workers under certain sets of qualifying restrictions, such as sufficient accuracy on a small test set or a minimum percentage of previously accepted submissions, we require no such qualifications in our tasks.

4 Annotation Tasks

We analyze the quality of non-expert annotations on five tasks: affect recognition, word similarity, recognizing textual entailment, temporal event recognition, and word sense disambiguation. In this section we define each annotation task and the parameters of the the annotations we request using AMT. Additionally we give an initial analysis of the results we receive for each task.

4.1 Affective Text Analysis

This experiment is based on the affective text annotation task proposed in (Strapparava and Mihalcea, 2007), wherein each annotator is presented with a list of short headlines, such as “*Outcry at N Korea ‘nuclear test’*”, and are asked to respond with numeric judgments in the interval [0-100] of the emotional content of the headline for six emotions: anger, disgust, fear, joy, sadness, and surprise; and then, to give a numeric score in the interval [-100,100] to denote the overall *valence* of the emotional content of the headline.

We focus on this task for two reasons; first, the task can be effectively described to annotators with only a few lines of instruction, and second we have a full set of 1000 headlines each annotated by six experts, allowing us to give a rich comparison of the quality of non-expert-to-expert annotation.

For this evaluation we would like to compare the interannotator agreement of individual expert annotations to that of single non-expert and averaged non-expert annotations; in order to do this, we propose the following experiment: for each individual expert annotator we compute the Pearson correlation of the labels provided by that annotator with the average of the labels of the remaining 5 expert annotators; we then average these ITA scores across all expert annotators to compute the average expert ITA (reported in Table 1 as “E vs. E”). We then do the same for individual non-expert annotations, averag-

ing Pearson correlation across all sets of the five expert labelers (“NE vs. E”). We also compute similar interannotator scores for each expert and vs. the averaged labels from all other experts and non-experts (marked as “E vs. All”) and for each non-expert vs. the pool of other non-experts and all experts (“NE vs. All”). We compute these ITA scores for each emotion task separately, and compute the average of all seven tasks together as “Avg. All”, and the six emotion tasks (i.e., excluding valence) separately as “Avg. Emo”.

Emotion	E vs. E	E vs. All	NE vs. E	NE vs. All
Anger	0.459	0.503	0.444	0.573
Disgust	0.583	0.594	0.537	0.647
Fear	0.711	0.683	0.418	0.498
Joy	0.596	0.585	0.340	0.421
Sadness	0.645	0.650	0.563	0.651
Surprise	0.464	0.463	0.201	0.225
Valence	0.759	0.767	0.530	0.554
Avg. Emo	0.576	0.603	0.417	0.503
Avg. All	0.580	0.607	0.433	0.510

Table 1: Average expert and non-expert inter-annotator correlation on test-set

The results in table 1 conform to the expectation that expert judgments correlate best with both other expert judgments and other non-expert judgments. Second, we observe that the average interannotator agreement generally increases as we add additional non-expert annotations to the gold standard; this is promising, as it suggests that the addition of the non-expert annotations in the average does increase the overall quality of the gold labels.

Next we consider averaging the labels of each possible subset of n non-expert annotations for each unit, for value of n in $\{1, 2, \dots, 10\}$. We then treat this average as though it is the output of a single ‘meta-labeler’, and compute the interannotator agreement with respect to each subset of five of the six expert annotators. We then average the results of these studies across each subset size; the result of this experiment are given in Table 2 and in figure 1. In addition to the single meta-labeler, we ask: what is the minimum number of non-expert annotations k from which we can create a meta-labeler that has equal to or better inter-annotator agreement than an expert annotator? In Table 2 we give the minimum k for each emotion, as well as the averaged inter-annotator achievement achieved by that meta-labeler

consisting of k non-experts (marked “ k -NE”). In Figure 1 we plot the expert inter-annotator correlation as the horizontal dashed line.

Emotion	E	10-NE	k	k -NE
Anger	0.459	0.675	2	0.536
Disgust	0.583	0.746	2	0.627
Fear	0.711	0.689	–	–
Joy	0.596	0.632	7	0.600
Sadness	0.645	0.776	2	0.656
Surprise	0.464	0.496	9	0.481
Valence	0.759	0.844	5	0.803
Avg. Emo.	0.576	0.669	4	0.589
Avg. All	0.603	0.694	4	0.613

Table 2: Average expert and averaged correlation over 10 non-experts on test-set

These results state that for all tasks except “Fear” we are able to achieve expert-level inter-annotator agreement with the held-out set of experts within 9 labelers, and frequently within only 2 labelers. On average it requires only 4 non-expert annotations per example to achieve the equivalent inter-annotator agreement as a single expert annotator; using this figure we may interpret our rate of 3500 non-expert labels per dollar on this task as at least 875 expert-equivalent labels per dollar.

Figure 1: Non-expert correlation for affect recognition

4.2 Word Similarity

This task replicates the word similarity task used in (Miller and Charles, 1991), following a previous task initially proposed by (Rubenstein and Goodenough, 1965). Specifically, we ask for numeric judgments of word similarity for 30 word pairs on a scale of [0,10], allowing fractional responses³. Numerous expert and non-expert studies have shown that this task tends to yield very high interannotator agreement as measured by Pearson correlation; (Miller and Charles, 1991) found a 0.97 correlation of the annotations of 38 subjects with the annotations given by 51 subjects in (Rubenstein and Goodenough, 1965), and a following study (Resnik, 1999) with 10 subjects found a 0.958 correlation with (Miller and Charles, 1991).

³(Miller and Charles, 1991) and others originally used a numerical score of [0,4].

In our experiment we ask for 10 annotations each of the full 30 word pairs, at an offered price of \$0.02 for each set of 30 annotations (or, equivalently, at the rate of 1500 annotations / dollar). The most surprising aspect of this study was the speed with which it was completed; this task of 300 annotations was completed by 10 annotators in less than 11 minutes from the time of submission, at the rate of 1724 annotations / hour.

As in the previous task we evaluate our non-expert annotations by averaging the numeric responses from each possible subset of n annotators and computing the interannotator agreement with respect to the gold scores reported in (Miller and Charles, 1991). Our results are displayed in Figure 2, with Resnik’s 0.958 correlation plotted as the horizontal line; we find that at 10 annotators we achieve a correlation of 0.952, well within the range of other studies of expert and non-expert annotations.

Figure 2: Inter-annotator correlation for word similarity, and agreement for RTE, event annotation, and WSD tasks

4.3 Recognizing Textual Entailment

This task replicates the recognizing textual entailment task originally proposed in the PASCAL Recognizing Textual Entailment task (Dagan et al., 2006); here for each question the annotator is presented with two sentences and asked whether the second sentence can be inferred from the first. We gather 10 annotations each for all 800 sentence pairs in the PASCAL RTE-1 dataset. For this dataset expert interannotator agreement studies have been reported as achieving 91% and 96% agreement over various subsections of the corpus. For greater than 1 annotation we employ a simple voting mechanism; further, we break ties randomly and average our performance over all possible ways to break ties. We collect 10 annotations for each of 100 RTE sentence pairs; as displayed in Figure 2, we achieve a maximum accuracy of 89.7%, averaging over the annotations of 10 workers. We assign this task into HITs of 20 annotations apiece, each with a corresponding payment of US\$0.02, for a total cost of US\$8.00 (i.e., at a rate of 1000 annotations / dollar).

4.4 Event Annotation

This task is inspired by the TimeBank corpus (Pustejovsky et al., 2003); among other annotations, the TimeBank corpus contains temporal labels for event pairs, marking each pair with the temporal relation between them (out of fourteen possible relations, including before, after, during, etc).

We implement a simplified version of the TimeBank event temporal annotation task: rather than annotating all fourteen event types, we restrict our consideration to the two simplest labels: “strictly before” and “strictly after”; further, we only consider verb events. We extract the 462 verb event pairs labeled as “strictly before” or “strictly after” in the TimeBank corpus, and we present these pairs to annotators with a forced binary choice on whether two verb events occur *before* or *after* one another. The results of this task are presented in Figure 2. We achieve high agreement for this task, at a rate of 0.94 with simple voting over 10 annotators. While an expert inter-annotator agreement of 0.77 was reported for the more general task of deciding over all fourteen labels on both noun and verb events, no expert ITA numbers have been reported for this simplified task.

4.5 Word Sense Disambiguation

In this task we consider a very easy problem on which machine learning algorithms have been shown to produce extremely good results; here we annotate part of the Semeval Word Sense Disambiguation Lexical Sample task (Pradhan et al., 2007); specifically, we annotate 177 examples of the noun “president” for the three senses given in Semeval. As shown in Figure 2, performing simple voting over annotators results in a rapid accuracy plateau at a very high rate of 0.994 accuracy. In fact, further analysis reveals that there was only a single disagreement between the averaged nonexpert-annotator vote and the gold standard; on inspection it was observed that the annotators voted strongly against the original gold label (9-to-1 against), and that it was in fact revealed to be an error in the original gold standard annotation⁴. Hence correcting this

⁴The example sentence began “*The Egyptian president said he would visit Libya today...*” and was mistakenly marked as the “head of a company” sense in the gold annotation (example

error actually corresponds to a non-expert accuracy rate of 100% on the 177 examples in this task. This provides a specific example in which non-expert annotations can be used to correct expert annotations.

Since expert inter-annotator agreement was not reported per word on this dataset, we compare instead to the performance of the best automatic system performance for disambiguating “president” in Semeval 17(Cai et al., 2007), with a reported accuracy of 0.98.

4.6 Summary

Task	Labels	Cost (USD)	Time (hrs)	Labels per USD	Labels per hr
Affect	7000	\$2.00	5.93	3500	1180.4
WSim	300	\$0.20	0.174	1500	1724.1
RTE	8000	\$8.00	89.3	1000	89.59
Event	4620	\$13.86	39.9	333.3	115.85
WSD	1770	\$1.76	8.59	1005.7	206.1
Total	21690	25.82	143.9	840.0	150.7

Table 3: Summary of costs for non-expert labels

In Table 3 we give a summary of the costs associated with obtaining the non-expert annotations for each of our 5 tasks. Here *Time* is given as the total amount of time in hours elapsed from submitting the group of HITs to AMT until the last assignment is submitted by the last worker. We observe that in general we collect fewer answers for categorical tasks despite the increased cost per annotation compared to the numeric response tasks; we expect that this is due to the increased cognitive load of those tasks.

5 Bias correction for non-expert annotators

The reliability of individual workers varies. Some are very accurate, while others are more careless and make mistakes; and a small few give very noisy responses. Furthermore, for most AMT data collection experiments, a relatively small number of workers do a large portion of the task, since workers may do as much or as little as they please. Figure 3 shows accuracy rates for individual workers for one task. Both the overall variability, as well as the prospect of identifying high-volume but low-quality

id 24:0@24@wsj/23/wsj_2381@wsj@en@on).

We restrict our attention to categorical examples, though in principle a similar method could be used with numeric data.

5.1 Bias correction in categorical data

We model labels and workers with a multinomial model similar to Naive Bayes. Every example i has a true label x_i . For simplicity, assume two labels $\{Y, N\}$. Several different workers give labels $y_{i1}, y_{i2}, \dots, y_{iW}$. A worker's conditional probability of response is modeled as multinomial. Each worker's judgment is conditionally independent of other workers given the true label x_i , i.e.:

$$P(y_{i1}, \dots, y_{iW}, x_i) = \left(\prod_w P(y_{iw} | x_i) \right) p(x_i)$$

Figure 3: Worker accuracies on RTE-1. Each point is one worker. Vertical jitter has been added to points on the left to illustrate the large number of workers who did the minimum amount of work (20 examples).

workers, suggest that controlling individual worker quality could yield higher quality overall judgments.

In general, there are at least three ways to enhance quality in the face of worker error. More workers can be used, as described in previous sections. Another method is to use Amazon's compensation mechanisms to give monetary bonuses to highly-performing workers and deny payments to unreliable ones; this is useful, but beyond the scope of this paper. In this section we explore a third alternative, to model the reliability of individual workers and correct for their biases.

A wide number of methods have been explored to correct for the bias of annotators. (Dawid and Skene, 1979) introduced an EM algorithm to estimate clinician diagnosis biases for unknown labels. It is similar to the one developed below in using a multinomial Naive Bayes setup. (Wiebe et al., 1999) analyze annotator agreement statistics to find bias, and also use a similar model to correct labels.

Here we consider the problem of using a small amount of expert-labeled training data in order to correct for the individual biases of different non-expert annotators. The idea is to recalibrate worker's responses to more closely match expert behavior.

To infer the posterior probability of the true label for a new example, worker judgments are integrated via Bayes rule, yielding the posterior log-odds:

$$\begin{aligned} & \log \frac{P(x_i = Y | y_{i1} \dots y_{iW})}{P(x_i = N | y_{i1} \dots y_{iW})} \\ &= \sum_w \log \frac{P(y_{iw} | x_i = Y)}{P(y_{iw} | x_i = N)} + \log \frac{P(x_i = Y)}{P(x_i = N)} \end{aligned}$$

The worker response likelihoods $P(y_w | x = Y)$ and $P(y_w | x = N)$ can be directly estimated from frequencies of worker performance on gold standard examples. (Under maximum likelihood estimation with no Laplace smoothing, each $y_w | x$ is just the worker's empirical confusion matrix.) For MAP label estimation, the above equation describes a weighted voting rule: each worker's vote is weighted by their log likelihood ratio for their given response. Intuitively, workers who are more than 50% accurate have positive votes; workers whose judgments are pure noise have zero votes; and anticorrelated workers have negative votes. (A simpler form of the model only considers accuracy rates, thus weighting worker votes by $\log \frac{\text{acc}_w}{(1 - \text{acc}_w)}$. But we use the full unconstrained multinomial model here.)

5.1.1 Example tasks: RTE-1 and event annotation

We used this model to improve accuracy on the RTE-1 and event annotation tasks. (The other categorical task, word sense disambiguation, could not be improved because it already had maximum accuracy.) First we took a sample of annotations giving k responses per example. Within this sample, we trained and tested the above model via 20-fold cross-validation across examples. Workers models were fit using Laplace smoothing of 1 pseudocount; label priors were uniform, which was reasonably similar to the empirical distribution for both tasks.

Figure 4: Gold-calibrated labels versus raw labels

Figure 4 shows improved accuracy at different numbers of annotators. The lowest line is for the naive 50% majority voting rule. (This is equivalent to the model under uniform priors and equal accuracies across workers and labels.) Each point is the data set’s accuracy against the gold labels, averaged across resamplings each of which obtains k annotations per example. RTE has an average +.040 accuracy rate increase, averaged across 2 through 10 annotators; and similarly +.034 for event annotation.

6 Training a system with non-expert annotations

In this section we compare a simple supervised affect recognition system trained with expert vs. non-expert annotations.

6.1 Experimental Design

For the purpose of this experiment we create a simple bag-of-words unigram model for predicting affect and valence, similar to the SWAT system (Katz et al., 2007), one of the top-performing systems on the SemEval Affective Text task. For each token t

that appears in our training set, we assign t a weight for each emotion e equal to the average emotion score observed in each headline H that t participates in. i.e., if \mathbf{H}_t is the set of headlines containing the token t , then:

$$Score(e, t) = \frac{\sum_{H \in \mathbf{H}_t} Score(e, H)}{|\mathbf{H}_t|}$$

Having computed the weights of the individual tokens we may then compute the score for an emotion e of a new headline H as the average score over the set of tokens $t \in H$ that we’ve observed in the training set (ignoring those tokens not in the training set), i.e.:

$$Score(e, H) = \sum_{t \in H} \frac{Score(e, t)}{|H|}$$

Where $|H|$ is simply the number of tokens in headline H , ignoring tokens not observed in the training set. Unlike the SWAT system we perform no lemmatization, synonym expansion, or any other preprocessing of the tokens; we simply use whitespace-separated tokens within each headline.

In order to compare between expert and non-expert trained classifiers we restrict our training set to the 100 headlines (examples 500-599 from the test set of Semeval Task 14) annotated by non-expert annotators, and we test on the remaining 900 headlines in the test set.

6.2 Experiments

Here we compare the performance of this model as trained on non-expert annotations vs. the individual expert annotations. Since we are fortunate to have the six separate expert annotations in this task, we can perform an extended systematic comparison of the performance of the classifier trained with expert vs. non-expert data.

For this evaluation we would like to compare the performance of a system trained on non-expert annotations to that of one trained with expert annotations; in order to do this, we propose the following experiment: for each expert annotator we train a system using only the judgments provided by that annotator, and then create a gold standard test set using the average of the responses of the remaining five

Emotion	Exp	10-NE	k	k -NE
Anger	0.084	0.233	1	0.172
Disgust	0.130	0.231	1	0.185
Fear	0.159	0.247	1	0.176
Joy	0.130	0.125	–	–
Sadness	0.127	0.174	1	0.141
Surprise	0.060	0.101	1	0.061
Valence	0.159	0.229	2	0.146
Avg. Emo	0.116	0.185	1	0.135
Avg. All	0.122	0.191	1	0.137

Table 4: Performance comparison of expert-trained and non-expert-trained classifier on test-set

labelers on that set. In this way we create six independent expert-trained systems and compute the average across their performance, calculated as Pearson correlation to the gold standard; this is reported in the “Exp” column of Table 4.

Next we train systems using non-expert labels; for each possible subset of n annotators, for n in the interval $[1, 10]$ we train a new system, and evaluate calculating Pearson correlation with the same set of gold standard datasets used for the expert-trained system evaluation. We then average the results of these studies across each subset size; the result of this experiment are given in Table 4.

As in Table 2 we calculate the minimum number of non-expert annotations per example k required on average to achieve similar performance to the expert annotations; surprisingly we find that for five of the seven tasks, the average system trained with a single set of non-expert annotations outperforms the average system trained with the labels from a single expert. One possible hypothesis for the cause of this non-intuitive result is that individual labelers (including experts) tend to have a strong bias, and since multiple non-expert labelers may contribute to a single set of non-expert annotations, the annotator diversity within the single set of labels may have the effect of reducing annotator bias and thus increasing system performance.

7 Conclusion

We demonstrate the effectiveness of using Amazon Mechanical Turk for a variety of natural language annotation tasks. We perform an in-depth evaluation of labeler data vs. expert annotations for six tasks; we discover that for many tasks only a small number

of annotations per unit are necessary in order to emulate the same performance as an expert annotator. In a detailed study of expert and non-expert agreement for an affect recognition task we find that we require an average of 4 non-expert labels per item in order to emulate expert-level label quality.

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