

NOBLEFIT

A Matlab/GNU Octave toolbox to fit (environmental) data

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1 What is NOBLEFIT?

NOBLEFIT is a flexible **Matlab**/GNU Octave toolbox for quantitative interpretation of (environmental) tracers in terms of environmental processes and models (e.g., dissolved noble gases, other atmospheric gases, or just about anything else that deserves quantitative model-based interpretation).

In contrast to similar tools[1] where the possible tracers and models are hard-wired into the code, NOBLEFIT is designed to allow the user to define his own tracers and models.

2 Installation and Setup

This text assumes you are familiar with **Matlab** or GNU Octave, and that you have a working installation of either **Matlab** or GNU Octave on your computer.

2.1 Download NOBLEFIT

There are two ways to get NOBLEFIT:

- The easy method is to download NOBLEFIT as a ZIP archive, and expand the files from the archive. You can download the ZIP archive from <http://sourceforge.net/p/noblefit/code/HEAD/tarball>.
- Alternatively, if you have subversion (SVN) software installed on your computer, you can get NOBLEFIT as a SVN repository, which makes upgrading NOBLEFIT very easy. You can checkout the SVN repository from <http://sourceforge.net/p/noblefit/code/HEAD/tree>.

2.2 Install NOBLEFIT

Once you have a copy of NOBLEFIT downloaded to your computer, you should move the NOBLEFIT folder to a convenient location on your computer. I like to keep all the **Matlab**/GNU Octave code and packages in one directory, which contains several subdirectories for the different packages and projects. This greatly helps **Matlab**/GNU Octave to find your files. For instance, I keep all my m-files in `~/m-files/`, so NOBLEFIT goes to `~/m-files/noblefit`. Then I tell **Matlab**/GNU Octave where to look for the NOBLEFIT functions by including the command `addpath('~/m-files/noblefit')` in the `startup.m` file (**Matlab**) or the `.octaverc` file (GNU Octave).

3 Working with NOBLEFIT

3.1 Overview

The general approach of the NOBLEFIT package is to fit a model to a given data set using the χ^2 regression method [2]. NOBLEFIT reports the best-fit values of the fitted model variables, their standard errors (calculated by propagation of the data errors), and the statistics about the goodness of the fit (χ^2 , p value, and degrees of freedom of the regression).

Before a model can be fitted to a data set, the fitting problem must be defined as follows (n : number of data values per data set, m : number of fitted model variables; $n > m$):

- The user must provide the measured (or observed) data to NOBLEFIT. Each data set consists of the observed values $\vec{y} = (y_1, \dots, y_n)$ and the associated standard errors $\vec{e} = (e_1, \dots, e_n)$ (note that data values without errors are useless). In simple cases, the data can be entered directly on the Matlab/GNU Octave terminal. If the data set is large, or if there are many different data sets (e.g., data from different samples), it may be more convenient and reliable to load the data from a file.
- The user must provide the model function $\vec{Y} = F(\vec{X})$ to NOBLEFIT. This is done by writing a Matlab/GNU Octave function that calculates the modelled data values $\vec{Y} = y_1, \dots, y_n$ as a function of the input variables $\vec{X} = X_1, \dots, X_m$ of the model.
- The user must provide the initial values of the fitted model variable. These initial values will be used as a starting point to find the best-fit values.
- If only a subset of the model variables is used in the fit, the user must provide the values of the model parameters that will be used to evaluate the model (i.e., the fixed values of the model variables that are not fitted).

Once the fitting problem is defined, the `noblefit.m` function is called to fit the model to the data using the χ^2 regression method [2]. To this end, `noblefit.m` finds the values of the fitted model variables that minimize the sum of the squares of the error-weighted residuals between the predicted and the measured data (χ^2):

$$\chi^2(\vec{X}) = \sum_1^n \left(\frac{Y_i - y_i}{e_i} \right)^2 = \sum_1^n \left(\frac{F_i(\vec{X}) - y_i}{e_i} \right)^2$$

Once `noblefit.m` found the χ^2 minimum, it reports the best-fit values of the fitted model variables \vec{X} , their errors ($\vec{E} = E_1, \dots, E_m$; calculated by propagation of the data errors), and the some information to assess the goodness of the fit (χ^2 and p values, degrees of freedom of the regression).

The call to the `noblefit` function looks like this:

```
[X,E,chi2,DF,p] = noblefit (F,x,m,vf,v0,vs,vmin,vmax)
```

- Input arguments (see Sec. 3.2 for details):
 - `F`: model function
 - `x`: measured data
 - `m`: measured variables included in the fit
 - `vf`: index to the fitted model variables
 - `v0`: initial values of fit variables and values of fixed model variables
 - `vs`: scaling factors of model variables (optional)
 - `vmin`: minimum values of fitted model variables (optional)
 - `vmax`: maximum values of fitted model variables (optional)
- Output arguments (see Sec. 3.3 for details):
 - `X`: best fit values of fitted model variables
 - `E`: standard errors of `X`
 - `chi2`: χ^2 value
 - `DF`: degrees of freedom of the fit
 - `p`: p value of fit

3.2 Input arguments

3.2.1 Model function

(documentation is work in progress.)

3.2.2 Measured data

(documentation is work in progress.)

3.2.3 Measured variables included in the fit

(documentation is work in progress.)

3.2.4 Index to fitted model variables

(documentation is work in progress.)

3.2.5 Initial values of fit variables and values of fixed model variables

(documentation is work in progress.)

3.2.6 Scaling factors of model variables

(documentation is work in progress.)

3.2.7 Minimum values of fitted model variables

(documentation is work in progress.)

3.2.8 Maximum values of fitted model variables

(documentation is work in progress.)

3.3 Output arguments

3.3.1 Best fit values of fitted model variables

(documentation is work in progress.)

3.3.2 Standard errors of best fit values

(documentation is work in progress.)

3.3.3 χ^2 value

(documentation is work in progress.)

3.3.4 Degrees of freedom of the fit

(documentation is work in progress.)

3.3.5 p value of the fit

(documentation is work in progress.)

4 Worked examples

There are a few complete examples of how to use NOBLEFIT in the the examples folder. While I am working to improve and expand this manual, I'd recommend you take a look at those worked examples to get started.

5 NOBLEFIT tools reference

This section lists all NOBLEFIT functions and describes their functionality.

5.1 nf_atmos_gas

```
[C_atm,v_atm,D,M_mol,H] = nf_atmos_gas (gas,T,S,p_atm,year,
hemisphere)
```

Returns dissolved gas concentrations in air-saturated water,
volumetric gas content in dry air and molecular
diffusivity in water.

Concentrations are calculated as gas amount (ccSTP) per mass
of water (g) at temperature T and salinity S

INPUT:

T: temperature of water in deg. C

S: salinity in per mille (g/kg)

p_atm: total atmospheric air pressure, including water
vapour (hPa, which is the same as mbar)

gas: 'He', 'He-3', 'He-4' (after Weiss)

'RHe' (3He/4He ratio)

'Ne', 'Ne-20', 'Ne_20','Ne-22', 'Ne_22' (after
Weiss, isotope fractionation from Beyerle)

'Ar', 'Ar-36', 'Ar_36', 'Ar-40', 'Ar_40' (after
Weiss, isotope fractionation from Beyerle)

'Kr', 'Kr-78', 'Kr_78', 'Kr-80', 'Kr_80', 'Kr-82',
'Kr_82', 'Kr-84', 'Kr_84', 'Kr-86', 'Kr_86_(
after_Weiss)

xxxxxxxxxx'Xe', 'Xe-124', 'Xe_124', 'Xe-126', 'Xe_126', Xe
-128', 'Xe_128', 'Xe-129', 'Xe_129', 'Xe-130', 'Xe_130', '


```

Xe-131', 'Xe_131', 'Xe-132', 'Xe_132', 'Xe-134', 'Xe_134',
'Xe-136', 'Xe_136' (after Clever)
'SF6'
'CFC11', 'CFC12', 'CFC113'
'O2', 'O2-34', 'O2-35', 'O2-36'
'N2', 'N2-28', 'N2-29', 'N2-30'
year:      year of gas exchange with atmosphere (calendar
            year, with decimals; example: 1975.0 corresponds to 1.
            Jan of 1975.098 corresponds to 5. Feb. 1975, etc.). This
            is only relevant for those gases with time-variable
            partial pressures in the atmosphere (e.g. CFCs, SF6)
hemisphere: string indicating hemisphere (one of 'north', '
            south', or 'global'). If the hemisphere argument is not
            specified, hemisphere = 'global' is used.

```

OUTPUT:

```

C_atm: concentration in air-saturated water (ccSTP/g)
v_atm: volume fraction in dry air
D:      molecular diffusivities (m^2/s)
M_mol:  molar mass of the gas (g/mol), values taken from
        http://www.webqc.org/mmcaltc.php
H:      Henrys Law coefficient in (hPa/(ccSTP/g)), as in p
        * = H * C_atm, where p* is the partial pressure of the
        gas species in the gas phase

```

EXAMPLES:

1. To get the Kr ASW concentration (ccSTP/g) in fresh water (temperature = 7.5 deg.C) at atmospheric pressure of 991 hPa:

```
[C_atm,v_atm,D,M_mol,H] = nf_atmos_gas ('Kr',7.5,0,991);
C_atm
```
2. To get the SF6 ASW concentration (ccSTP/g) in mid-1983 northern hemisphere in fresh water (temperatures of 0-10 deg.C, salinity 6 g/kg) at atmospheric pressure of 983 hPa:

```
[C_atm,v_atm,D,M_mol,H] = nf_atmos_gas ('SF6'
,[0:10],6,983,1983.5,'north'); C_atm
```

5.2 nf_objfun

```
G = nf_objfun (PF,P0,PFmin,PFmax,mdl,X_val,X_err)
```

Objective function for minimization in parameter regression. Determines the modelled values using the model for the given parameter values, and calculates the χ^2 value from the difference to the data values. If called with

fit parameter values that exceed the limits in PFmin and PFmax, the χ^2 value will be calculated such that the χ^2 minimizer will look elsewhere for a 'better' optimum (see commented code for details). Note that many techniques for fitting with constrained parameter ranges rely on mapping the "infinite χ^2 surface" to the allowed parameter range. This distorts the χ^2 surface, and while the minimum χ^2 value will correspond to the correct best-fit parameter values, the "distorted" χ^2 value cannot be statistically interpreted in the same way as the "undistorted" χ^2 . `nf_objfun.m` therefore avoids distorting the χ^2 surface in the allowed parameter range, and the resulting χ^2 value can be interpreted using the conventional χ^2 statistics.

INPUT:

PF: vector of fitted model parameter values
P0: vector of constant model parameter values
PFmin: vector of minimum values allowed for the fitted parameters
PFmax: vector of maximum values allowed for the fitted parameters
mdl: string containing call to the model function using PF and P0
X_val: values of observed/measured data (rows correspond to samples, columns correspond to one tracers)
X_err: standard errors of X_val

OUTPUT:

G: χ^2 value

5.3 nf_read_datafile

```
[data,tracers] = nf_read_datafile (file,options);
```

Reads data from a formatted text file. The data needs to be organized in columns as follows:

- Columns are assumed to be separated by tabs. Other delimiters may be specified using 'options'.
- The first line must be a header line with names of the data in the columns.
- The first column must contain sample names (treated as string).
- The remaining columns must contain the data values (either numbers, NA, NaN, or empty).
- If column titles include units (or anything else) in parentheses, the parentheses part is removed from the

- name (it may be useful to have the units in the data file, but the unit will be in the way for data formatting)
- Data columns containing the data uncertainties (errors) are identified by adding 'err' somewhere in the title. Example: if the Ne concentrations are given in column with title 'Ne', the column title of the corresponding errors could be 'Ne_err', 'err._Ne', 'Ne_err', etc.

INPUT:

- file: file name, may include path to file (string)
- options (optional): struct to provide options. May be useful to provide details about the format of the data file, may be useful to specify special file formats (e.g. output from 4D database or input files for Franks noble fitter. Known options:
- options.replace_zeros: if set, replace data values equal to zero by opt_replace_zeros (scalar)
 - options.filter_InvIsotopeRatios: if set to non-zero value (scalar), try to make sure that isotope ratios are such that the low-mass isotope is divided by the high-mass isotope (e.g., replace $40\text{Ar}/36\text{Ar}$ by $36\text{Ar}/40\text{Ar}$).

OUTPUT:

- data: array of structs with data values and corresponding errors. Every struct corresponds to one line in the data file. Fieldnames correspond to the column titles in the header line. Sample names are stored in field 'name'.

5.4 noblefit

```
[par_val, par_err, chi2, DF, pVal, cov, res] = noblefit (model,
    tracer_data, tracers, par_usage, par0, par_norm, par_range,
    par_min, par_max);
```

Frontend to fit a given model to observed data using χ^2 regression.

INPUT:

- model: model name (string). More specifically, this is the name of the function that returns can either be the name of one of the standard models provided with gasfit, or a custom model function provided by the user (function name must be on the search path).
- tracer_data: either the name of an ASCII file containing the data (with column headers that correspond to the tracer names) or a struct variable containing the observed data (either a single struct corresponding to one sample, or a

vector of structs for more than one sample). The tracer names must correspond to those in the model function.

tracers: a cell string containing the names of the tracers that are to be used in the fit (names must correspond to those used by the model function).

par_usage: vector indicating usage of the model parameter values. par_usage is of the same format as the vector used as the input argument of the model function. Values are as follows:

- par_usage(i) = 0: The i-th model parameter is used as a constant in the minimization problem, i.e., it is not optimized during fitting of the model to the data.
- par_usage(i) = 1: the i-th parameter is optimized to obtain the best model fit for each individual sample.
- other values may be implemented in a later version (e.g ., for ensemble fits of a model parameter to an ensemble of data from multiple samples)

par0: parameter values used for the regression (vector of the same format as used for the input argument of the model function). Depending on the parameter usage (see par_usage), the values are used as fixed values or initial values used in the minimization problem.

par_norm (optional): typical scale of variation of the parameter values, used to normalise fitting parameters during model fitting (vector or matrix of same size as par0, values used for fit parameters must not be zero). Note that the scaling factors reflect the RANGE OF VARIATION, not the absolute value. For instance, if infiltration date is somewhere between 1950 and 2013, a suitable scaling factor would be 10, not 1000.

par_min (optional): min allowed parameter values for fit (vector or matrix of same size as par0, only values for fitted parameters will be used). Values may be -Inf to indicate no limits. Note: fit results may slightly exceed the limits, if the best fit value is close to the limit. This is due to the way the limits are treated in the fitting routine. The effect should be small, but please make sure the values are ok for you.

par_max (optional): max allowed parameter values for fit (vector or matrix of same size as par0, only values for fitted parameters will be used). Values may be Inf to indicate no limits. Note: fit results may slightly exceed the limits, if the best fit value is close to the limit. This is due to the way the limits are treated in the fitting routine. The effect should be small, but please make sure the values are ok for you.

OUTPUT:

`par_val`: best-fit estimates of the parameter values (vector of the same format as used for the input argument of the model function).
`par_err`: standard errors of `par_val` (vector).
`chi2`: chi2 of fit
`DF`: degrees of freedom of fit (= number of data points - number of fitted model parameters)
`pVal`: p-value of chi2, as given from cumulative chi2-density function with `DF` degrees of freedom: `pVal = 1 - chi2cdf(chi2,DF)`
`cov`: covariance matrices of the fits (cell array of matrices)
`res`: error-weighted residuals of observed values (X) of sample `k` relative to modeled values (M), normalised by the standard error (E) of the observed values, i.e.: `res(k,i) = (X_i - M_i) / E_i`, where `i` is an index to the corresponding tracer (`res` is a matrix, each row corresponds to one sample, columns correspond to 'tracers')

EXAMPLES:

see files in Examples folder.

References

- [1] W. Aeschbach-Hertig, F. Peeters, U. Beyerle, and R. Kipfer. Interpretation of dissolved atmospheric noble gases in natural waters. *Water Resour. Res.*, 35(9):2779–2792, 1999.
- [2] W. H. Press, P. F. Flannery, S. A. Teukolsky, and W. T. Vetterling. *Numerical Recipes*. Cambridge University Press, Cambridge, London, New York, 1986.