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Hash Functions and Hash Tables

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Hash Functions and Hash Tables

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Abstract

During this undergraduate thesis I will explain about two of the most fascinating and used ideas in Computer Science, hash functions and hash tables. I divided this thesis in three main parts:

- Hash functions
- Hash tables
- Applications

During the first part I explain why hash functions are an important idea in Computer Science, summarize some of the ideas Donald Knuth present on his book (The Art of Computer programming, Vol. 3) and use some metrics to evaluate what is a good hash function.

During the second part I talk about one of the most used data structures in computer programming, hash tables. I will explain what constitute a hash table, show some of the classic implementations of this data structure and explain some of the most used open addressing strategies. It is nice to observe here that although hash tables is a simple concept, there is still debates regarding this subject with no clear consensus on what is a state of the art hash table.

During the third, and last, part I will cite and explain some application of hash functions in computer science problems. I will explain Rabin-Karp, a string search algorithm that uses hashing and a solution to identify isomorphisms on trees using hashing functions.

I hope this is as fun to read for you as it was for me to write!

Keywords: hash functions, hash tables, collision-resolution, open-addressing.

Contents

Chapter 1

Introduction

One of the most used data structures in computer science are dictionaries. Those need to suport the operations of inserting, fiding and deleting an element. If you think about it, this is one of the most executed tasks in many softwares. For example, when you have the list of numbers you last called on your cell phone and you want to know for each phone number, what is the person associated with it. A dictionary perfoms the task of inserting for each phone number the name of the person, and then you can retrieve that information finding, for a phone number who is the person associated with it.

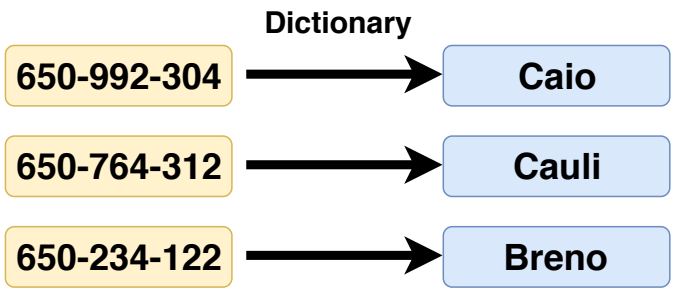

Figure 1.1: *Example of a dictionary that associates phone numbers to contact names.*

Other use of a dictonary that you can think is to count the number of times you called a certain number. One of the most used implementation of dictionaries is with a hash table.

The implementation of a hash table always requires a hash function. This function usually takes the element that you want to hash, or key as it is usually called (In our example, the phone numbers), and "digest" it into a number. That number is then used to indentify the value (In our eaxmple, the contact names), in this structure that we call hash table.

An example of a hash function, that "digest" the phone numbers is the following:

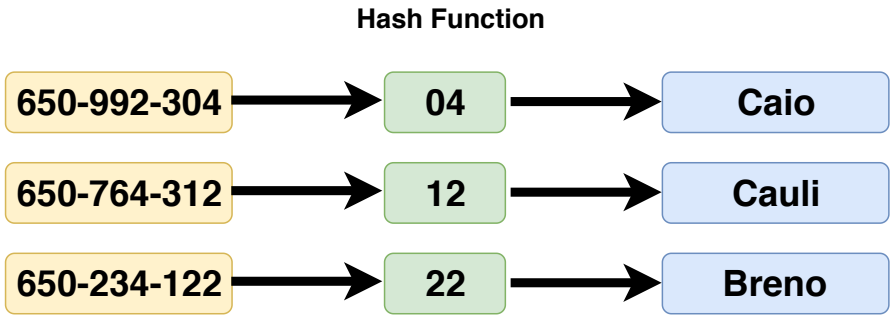

Figure 1.2: *Example of a hash function hash function that just take the last 2 digits of the phone number*

As you can see this is a pretty simple function, it simply take the last 2 digits of each phone number. In this specific case, this is enough to uniquely identify each phone. We can imagine a function that can't uniquely identify each phone number, like getting just the last digit (in this case, Cauli's and Breno's numbers would have the same hash value), this will cause a collision in the table. Solving collisions in a hash table is a complete topic by itself, and it will be addressed in Chapter 3, Hash Tables.

Solving collisions is actually a very important topic in hash tables, and that is because the vast majority of hash functions will have collisions. To picture that we can remember the "Birthday Paradox", that is the conclusion that we only need 23 people in a room to have a chance greater than 50% of 2 or more people having the same birthday. In Donald Knuth's famous book, The Art of Computer Programming (Vol. 3, Chapter 6.4) [**?**], he uses as an example a function from a 31-element set to a 41-element set, and from about 10^{50} functions only about 10^{43} give distinct values for each argument, that is about 1 in every 10 million functions. That shows that we will have collisions more often than not, so knowing how to deal with it is a major problem.

Hash functions and hash tables are among the most classic topics within computer science, yet is still one of the topics with most debate about what is state of the art. While the hash table was invented in 1953, widely discussed by Donald Knuth in his book, there are still many tweaks that can be made to boost its performance for specific use cases. One great example is F14, an open-source memory efficient hash table by Facebook [1].

An example of lack of consensus in this area are the different hash functions and hash table implementations in different languages. There is no clear consensus on how to decide the size of a hash table, what are the tradeoffs of the collision-resolution algorithms or even what defines a good hash function. Hopefully, we got years of research on the topic to study and present a view on the subject, and that is what I am presenting thoughout this undegraduate thesis.

[1] F14 is open sourced: https://engineering.fb.com/developer-tools/f14/

Chapter 2

Hash Functions

Outside computer science, the word *"hash"* in the english language means to "chop" or to "mix" something. This meaning is entirely related to what hash functions are supposed to do. hash functions are functions that are used to map data of an arbitrary size to data of a fized size [**?**].

They have wide applications in computer science, being used in information and data scurity, compilers, distributed systems and hardcore algorithms. During this chapter I first define and explain the basics of a hash function, then I give an intiution in some metrics of what is a good hash function, as discussed in the famous *"Red Dragon Book"* [**?**] along with some reproduction of known results in the area.

The value extracted from the hash function for an object is usually called *Hash Value*. The hash value is usually, but not necessarily, smaller than the object that generated it. For example, we can have a hash function that takes Gigabytes or Terabytes files and return an 8 bytes hash value.

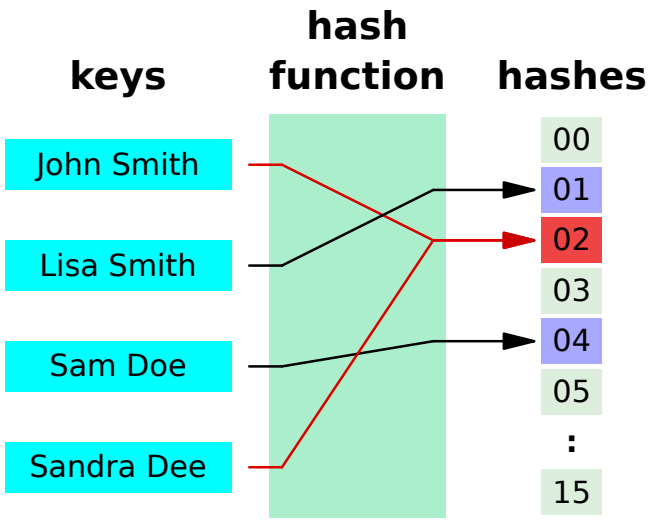

Figure 2.1: *Example of a hash function from string to 4 bit integer.*

To formalize a little, lets define a hash function as a function H that takes an element $x \in X$ and has $[0, M)$ as a codomain.

This is the same definition used by Donald Knuth [**?**] and some articles [**?**]. This definition makes sense for our case because we will be talking mostly about hash functions used in hash tables, and in that case we want integers that will be indexes in an array (as we will se later on). In other cases will may see hash functions value as strings, like for when we hash an string for password storage or when we use a hash function in files for check-sum (for when we are checking if two files are the same). For the goal of this thesis we will not be focusing on those functions, but it is important to notice that strings can also be abstracted to integers if we just look at the bytes.

For our specific case we are looking at a hash function that is good for the construction of hash tables, that is that is fast to calculate and minimizes the number of collisions. Depending on our goals we might want a different metric, for check-sums for example we may want a function that is very sensible to chages, and for passwords one that is very hard to find its inverse.

As said in Donald Knuth's book, we know that it is theoricatically impossible to create a hash functio that generates true random data from non random data in actual file, but we can do pretty close to that (or in some cases, even better). Donald Knuth describes 2 specific methods for simple hash function, named *division hashing* and *multiplicative hashing* techniques. As the name sugests, the first is based on division and the former on multiplication.

The divison hashing method simply to represent the data as a number take the remainder of that number modulo a value. Supposing that we can represent the data as a non negative integer X the division hashing would be to choose a value M and the hashing function would be $XmodM$. The C++14 code would look as following:

```
1 unsigned_int divisionHashing(unsigned_int X, unsigned_int M) {
2    return X % M;
3 }
```

In general large prime numbers tend to be a good value to M, because if not we may have repetitions. One great example of this is if M is even, then the parity of hash value of X will match the parity of X (which will cause a bad distribution). The same pattern will happen in different intervals for different powers of 2.

For the multiplicative hashing, we can furst imagine that the overflow is like a "natural" modulo operation (We also have methods to take the modulo without overflowing, to know more about that). Supposing that we can represent the data as an non negative integer X, the multiplication hashing would be to choose a value A that we mulitply by X and then take the value module 2^P (That is how is described in donald knuth book, by *"taking the leading bits of the least signifcant half of* $A * X$*"*). The C++14 code would look as follwing:

```
1 unsigned_int multiplicativeHashing(unsigned_int X,
2                                     unsigned_int A,
3                                     unsigned_int P) {
4   return (A * X) << P;
5 }
```

In knuth's book he restricts A to be relatively prime to w, being w the size of a "word" in the machine (which is MAX_INT in our case). That definition is often useful if you can retrieve a value Y for a given hash value F. It is good to note here that if $H(X) = F$ and $H(Y) = F$, X is not necessarily equal to Y, as two keys can have the same hash value.

Here it is also good to note, we have many ways of converting non numerical data to non negative integers. In the end, it is all just a sequence bytes, that when readed in a specific way form another type of data, such as images or strings. For example, one way of transforming a string to a non negative integer is summing the ASCII value of its characters. The C++14 code for that would look as following:

```
1 unsigned_int convertStringToInteger(string str) {
2   unsigned_int hashValue = 0;
3   for (char c : str) {
4     hashValue += (int) c;
5   }
6   return hashValue;
7 }
```

We always use usigned integers for our non negative integer calculations due to the natural modulo operation of it on overflow cases. It is equivalent to having a $mod\ 2^{32}$ every time it overflows (As we only look at the leading 32 bits). We can also use XOR function to mix numbers together.

There is also a very common type of hash functions that tend to work pretty well for strings [**?**]. It is a "Superset" of multiplicative hash functions, or a generalization. The C++14 code would look as following:

```
1 unsigned_int hashForString(string str,
2                             unsigned_int initialValue,
3                             unsigned_int multiplier,
4                             unsigned_int modulo) {
5   unsigned_int hash = initialValue;
6   for (char c : str) {
7     hash = (multiplier * hash + (int)c);
8   }
9   return hash % modulo;
10 }
```

The above function is very common for string hashing, and by just choosing a different initial value and multiplier we can have completely different hash funcitons. Although using summing or using XOR usually don't provide much difference, XOR is preferable due to the fact that we do not need to worry about overflow. Some values are of known hash funcitons, for example with $multiplier = 33$ and $initialValue = 5381$ generates *Bernstein hash djb2* [**?**] or $multiplier = 31$ and $initialValue = 0$ generates *Kernighan and Ritchie's hash* [**?**]. Those are famous functions and their values are not choosen randomly, as there are some factors that maximizes the chance of producing a good hash function (remembering, good means low collision rate and fast computation). Those factors are:

- The multiplier should be bigger than the size of your alphabet (in our case usually 26 for english words or 256 for ASCII). That is the case because if it is smaller we can have wrong matches easier. For example, suppose that $multiplier = 10$ and $initialValue = 0$, we have $H('ABA') = H('AAK') = 7225$ before taking the modulo operation.

- The multiplication by the multiplier should be easy to calculate with simple operations, such as bitwise operations and adding. That is quite intuitive as we want a hash function that is fast to calculate.

- The multiplier should be coprime with the modulo. That is because if not we will "cicle" hashes at a greater rate than the modulo (We can use some modular arithmetic to prove that). Usually prime numbers tend to be good multipliers.

Now that we know some good templates for producing hash functions lets try to find a concrete metric or formula that measures the quality of a hash function. Fortunately, the famous Red Dragon Book [**?**] has already proposed a formula to measures the quality of a hash function. The formula is the following:

$$\sum_{j=0}^{m-1} \frac{b_j(b_j+1)/2}{(n/2m)(n+2m-1)}$$

Where n is the number of keys, m is the number of total slots and b_j is the number of keys in the $j-th$ slot. The intuition for the numerator is the number of operations we will need to execute to find each element of the table. For example, we need 1 operation to find the first element, 2 to find the second, and so on. That means that we will end up with the follwing arithmetic progression. We know that a hash function that distributes the keys in a uniformly random distribution has expected bucket size of n/m, so we can calculate that the expected value of the numerator formula is $(n/2m)(n+2m-1)$. So that gives us a ratio of collisions (thinking just about operations to access a value) of "our" hash function with an "ideal" function. That means that a value close to 1.00 of the above formula is good, and values below to 1.00 means that we had less conflicts than an uniformly distributed random function.

From common data as used in Dragon Book and Strchr website [**?**] I will reproduce some tests with the previously cited hash functions.

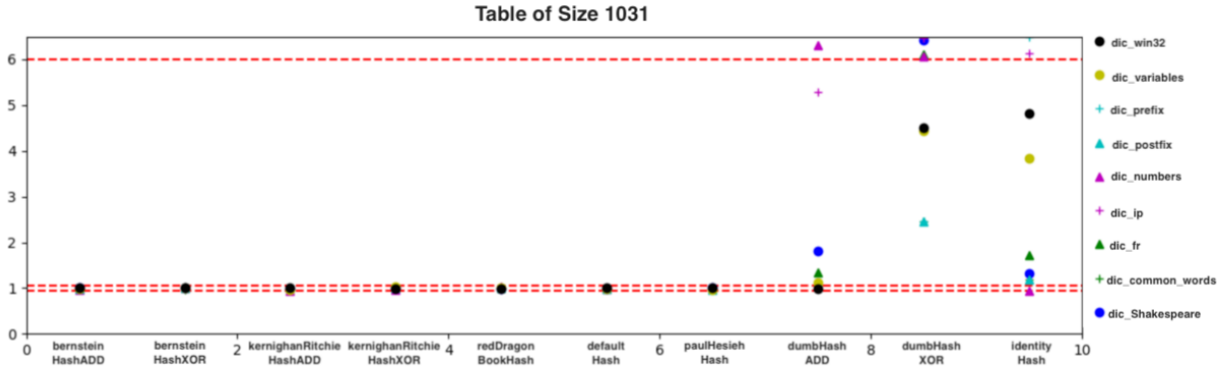

Figure 2.2: *Functions tested against a "small" table*

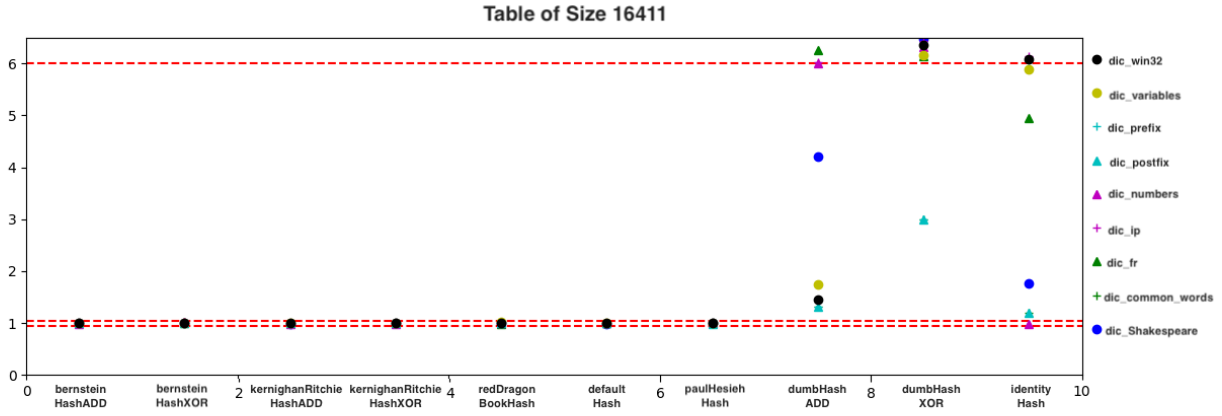

Figure 2.3: *Functions tested against a "medium" sized table*

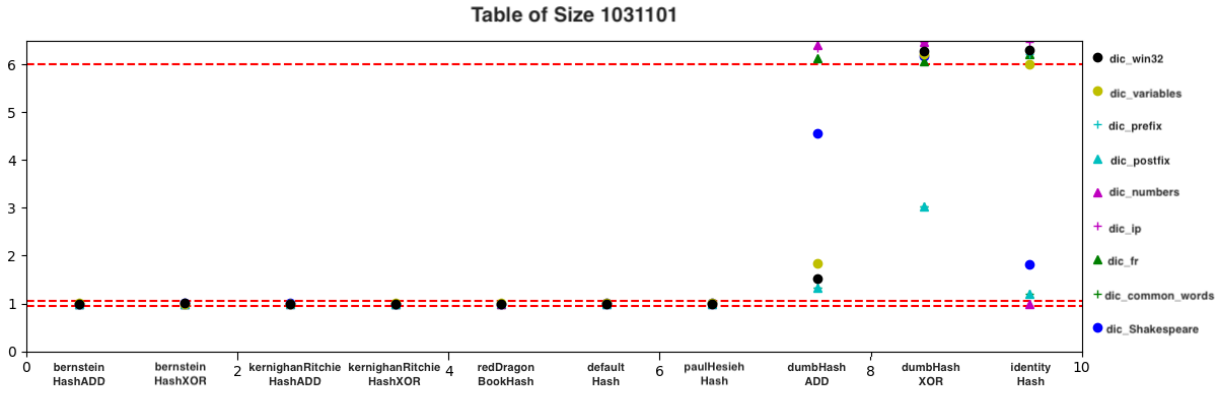

Figure 2.4: *Functions tested against a "large" table*

The results are shown in the same way displayed in the Red Dragon Book, with Hash functions in the X axis and the ratio displayed in the y axis, with different identification for each file. I choose 3 sizes of tables to count collisions, a "small", "medium" and a "large" table, the small table having a load factor (The percentage of the table occupied) of approximately ~ 0.5, the medium with ~ 0.05 and large with ~ 0.005. It's assumed that the modulo is not the responsaibility of the hash funciton, so all hash functions return values from 0 to $2^{32} - 1$, and the modulo is taken depending on the size of the table. From that we can already see that the load factor doesn't make a good hash function bad, but expose problems of "bad" hash functions in some cases.

Antoher thing that it is important to notice from the graph is the red dotted lines. The top one is the "Upper" threshold, which results greater than 6 are just considered "Big", as in some cases the ration exploded to values up to 200. The lower 2 red lines are in $y = 1.05$ and $y = 0.95$ which is the interval that we consider a hash function to have "Good" values.

The tests were made with 10 different hash functions, tested against 9 different files (Provided by strchr website). All of the code used to test this can be found in the github repo [**?**]. The 10 hash functions are the following:

- **bernsteinHashADD**: The bernstein hash function described earlier. We use the given hash template adding the elements. The multiplier is 33 and initial value is 5381. In the end we XOR the bits of the hash with itelf shifted 16 to the right (That is half of the bits with our implementation).
- **bernsteinHashXOR**: The same as above but substituting the first adding operator by the XOR operation.
- **kernighanRitchieHashADD** The Kernighan Ritchie Hash function described earlier. We use the given hash template adding the elements. The multiplier is 31 and initial value is 0.
- **kernighanRitchieHashXOR** The same as above but substituting the first adding operator by the XOR operation.
- **redDragonBookHash** The hash function tested in the red dragon book. It is described as x65599 in the book.
- **defaultHash** The default hash function of c++ standard template library.
- **paulHesiehHash** A fast hash function described by Paul Hesieh. It is fast to calculate and more complex than Knuth multiplicative or division Hashing.
- **dumbHashADD** A hash function that simply add all characters.
- **dumbHashXOR** A hash function that simply XOR all characters.

- **identityHash** A hash function that takes the first 4 bytes of the string.

We have a variety of hash functions, with all being considered "fast" hash functions. The files tested inlcude common words in english and french, strings of some IP values, numbers, common variable names and words with common prefix and posfix.

First thing we can notice from those graphs is that changing the ADD function to XOR doesn't make a good mulitiplicative hash function bad. Both are actually "Equivalent" given that we are also multiplying the values. For "dumbHashADD" and "dumbHashXOR" we can see clear differences, with "dumbHashXOR" being clearly worse. This can be explained by the cancelation property of XOR. We can see this example on the hash of this IP below:

$$dumbHashXOR(\text{"168.1.1.0"}) = dumbHashXOR(\text{"168.2.2.0"}) = dumbHashXOR(\text{"124.6.8.0"})$$

We can see that many different IPs hve the same hash value. More than that, XOR don't increase the number of bits, so all the hashes will be of just 1 byte.

Other thing that we can notice is that "identity" hash is good or perfect in some cases. One obvius case that "identity" work perfectly is for numbers (We will have 0 collisions). Some languages, like python 3, use the identity function to calculate hash for integers, as it is very fast and produces no collisions. But we can see that for other cases, such as common prefix, it works terrible as we just get the first 4 bytes.

The most common multiplicative hash functions tend to work similarly well, being reasonably close to the ideal hash function in all cases.

As we can see, we don't need a lot of complexity to make a good hash function for a hash table. We have some functions working better for some specific case, like identity function working well for numbers, but general functions already work well enough.

One thing that is important to say here is that hash function is a very vast topic, and here we just covered hash functions related to hash tables. Hash functions have applications in distributed systems (With consistent hashing), database indexing, caching, compilers (As it is explored in the red dragon book) and criptography. Each application has different requirements and make some hash functions better than others.

Chapter 3

Hash Tables

Hash tables or hash maps is one of the most used applications of hash functions. It is actually so used in computer science that is almost impossible to talk about one without mentioning the other. This data structure consists in associating a *key* to a *value* in a table. That is, given a *key*, it can retrieve the correct *value* for it.

It is considered one of the possible (and one of the best) implementations of a dictionary. It has to implement the **INSERT**, **FIND** and **REMOVE** opreations, that can be accessed from outside the dictionary. It usually implements a lot of other private methods.

This data structure is usually considered very useful among software engineers and computer scientists, although it usually has a linear worst case cost for retrieving, inserting and deleting a key-value pair. That is because it has a constant average cost for those operations.

Moreover, when talking about hash tables we have the problem of key collision, that is when two keys maps to the same hash value. As we saw in the previous chapter, this is collisions are more common than not. To solve that problem, we have several techniques that envolves different tradeoffs. Those techniques are usually divided into two main categories, open addressing and separate chaining. Other problem to consider regarding this data structure is when to resize the hash table, to minimize the chance of collision and the use o memory. For this last one we usually consider a load factor, α, that is the ratio of keys with the available slots.

Also, hash tables can be easily abstracted to hash sets, that are commonly used to store a set of elements and check if an element is there. We can abstract that data structure to a hash table always with an empty value. Hash sets are one of the common ways to implement sets in programming languages, like unordered_set from C++14.

It is also important to notice that hash tables have applications in different areas of computer science also, like compilers, caches and database indexing.

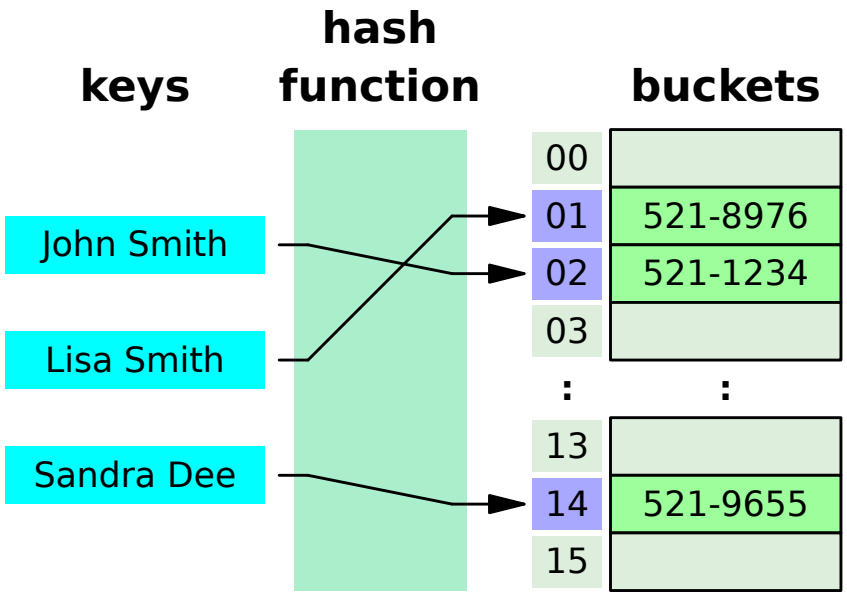

Figure 3.1: *Example of a hash table from string to string, more specifically name to number*

3.1 Open Addressing

3.1.1 Implementing a no collision hash table

To start I will give an example of a hash table that has a perfect hash function, that has no collisions. For that example we will use open addressing, that basically means that all data will be contained in an array. The operations **INSERT**, **FIND** and **REMOVE** would be very easy to imeplement. For the sake of simplicity, I will assume all the keys are strings. To start lets look at this simple class with dummy methods:

```
1 class HashTable {
2     vector< pair<string, int> > table;
3     int m, n;
4
5     HashTable() {
6         m = 16;
7         table.resize(m);
8         n = 0;
9     }
10
11    unsigned_int hashFunction(string s) {}
12
13    void insert(string key, int value) {}
14
15    int find(string key) {}
16
17    void remove(string key) {}
```

```
18
19 private:
20     double alpha = 1;
21     void resizeIfNecessary() {}
22 }
```

As we can see it is pretty simple. The constructor builds a table of size 16, and for now we can assume a dinamic resizing every time we have 16 elements. Later on we will see that this means that we resize every time the load factor, α, is equal to 1.00. We also can note that at the table part we are storing a pair of key and value, not just value. This is because we may want to retrieve all pairs of the table (like in a regular dictionary). The pairs are usually unordered (If they are not ordered by chance ...), and the iterator has $O(1)$ step. We will jump the implementation of hashFunction, as already saw plenty of it in the last chapter, so we will go right in for the implementation of **insert**:

```
1 void insert(string key, int value) {
2   unsigned int idx = hashFunction(key);
3   table[idx] = pair<string, int>(key, value);
4   n++;
5   resizeIfNecessary();
6 }
```

That is pretty simple, that is mostly because we will assume that we will never have a collision, so we just put the key on the position returned by the hash function. The method **find** is implemented as following:

```
1 int find(string key) {
2   unsigned int idx = hashFunction(key);
3   if (table[idx].first == key)
4     return table[idx].second;
5   return 0;
6 }
```

Also very simple, we always know the value will be in position returned by idx. The **remove** will be of the same simplicity, as following:

```
1 void remove(string key) {
2   unsigned int idx = hashFunction(key);
3   table[idx].first = pair<string, int>("", 0);
4   n--;
5 }
```

Here we make the assumption that an empty position has an empty string. We could also carry a boolean (usually called a tombstone) to check if the position is occupied or not.

3.1.2 Formal definition

We can define open addressing in a general way as a hash table algorithm where the data always stay within the same vector. So, in the case of a collision, we need to define a sistematic way to traverse the table. The sequence of elements I need to traverse when I have a collision is called *"Proble sequence"*. With that our hash function would change to the following:

$$H(x, i)$$

Where x is our key and i is the sequence number. So every time we have a collision in $H(x, i)$ we can simply go to $H(x, i + i)$. Given that, lets look into some different probe sequences.

3.1.3 Linear Probing

Linear probing is one of the most simple an practical probe sequences known. The probe sequence is basically:

$$H(x, i) = (H(x) + i) \mod M$$

where M is the table size. That is a very simple probe sequence with not much secret on it. To implement the **insert** we can do the follwing:

```
1 void insert(string key, int value) {
2   unsigned int idx = hashFunction(key);
3   while (table[idx] != pair<string, int>("", 0))
4     idx = (idx + 1) % m;
5   table[idx] = pair<string, int>(key, value);
6   n++;
7   resizeIfNecessary();
8 }
```

That assumes that pair<string, int>("", 0) is the empty position, and performs a linear search until it finds one empty position to put the new (key, value) pair. The implementation of find **find** is very similar:

```
1 int find(string key) {
2   unsigned int idx = hashFunction(key);
3   while (table[idx] != pair<string, int>("", 0)) {
4     if (table[idx].first == key)
5       return table[idx].second;
6     idx = (idx + 1) % m;
7   }
```

```
8   return 0;
9 }
```

It performs a linear search until it finds the element. If it does not find the element, it then returns a default value that in our case is 0.

For removal, we have the problem that we cannot leave "Holes" in our table. That will be discussed more in depth later on the section "How to delete an entry". For now we will remove the elment, and shift the rest of the sequence one position. For that we can do the following:

```
1 void remove(string key) {
2   unsigned int idx = hashFunction(key);
3   while (table[idx] != pair<string, int>("", 0)) {
4     if (table[idx].first == key)
5       break;
6       idx = (idx + 1) % m;
7   }
8
9   if (table[idx].first == key) {
10    table[idx] = pair<string, int>("", 0);
11    while (table[(idx + 1) % m] != pair<string, int>("", 0)) {
12      swap(table[idx], table[idx + 1]);
13      idx = (idx + 1) % m;
14    }
15    n--;
16  }
17 }
```

With that, the three operations have linear complexity. As we saw, we know hash functions that are considered good, with a rate of collision very close to an uniformly random function. Those functions will leave us with an expected constant time for those operations, and we will see later on that in practice it is much faster than linear access.

3.1.4 Quadratic Probing

3.1.5 When to resize an array

3.1.6 How to delete an entry

3.2 Chaining Hashing

Chaining hashing is the implementation of a hash table using a container, usally called bucket, to store the (key, value) pairs with a given hash. On this implementation, each bucket of the table is a pointer to a node of a linked list, that will carry the key value pair in our

case. We deal with collisions with this implementation by adding a new node to the end of the list.

This implementation is considered simpler than open addressing, usually because the way of dealing with collisions is clearer. Also it is less system dependant if we consider performance (as we saw ine of the key advantages of open addressing is that it is cache friendly). That is one of the key reasons that C++ uses chaining hashing for its default implementation of unordered_hash [**?**].

Below we will discuss an implementation of chaining hashing in C++14:

3.2.1 Simple Chaining Hashing Algorithm

For this Chaining hashing implementation we will use C++14 STL data structure list as our container. list is a doubly linked list. For our **insert** we can implement it in the following way:

```
1 void insert(string key, int value) {
2   unsigned int idx = hashFunction(key);
3   table[idx].emplace_front(key, value);
4   n++;
5   resizeIfNecessary();
6 }
```

As we can see it is a very simple implementation, we just push a new element in the front of the list pointed in the idx. As before we add the counter of elements in the list and call resizeIfNcessary().

For **find** we can implement in the following way:

```
1 int find(string key) {
2   unsigned int idx = hashFunction(key);
3   auto it = find_if(table[idx].begin(), table[idx].end(),
4                     [&key](auto kv) { return kv.first == key; });
5   if (it != table[idx].end())
6     return it->second;
7   return 0;
8 }
```

That implementation is very succint but uses some of the features of C++14 (such as generic lambdas). For **erase** we can implement in a very similar fashion:

```
1 void remove(string key) {
2   unsigned int idx = hashFunction(key);
3   auto it = find_if(table[idx].begin(), table[idx].end(),
4                     [&key](auto kv) { return kv.first == key; });
```

```
5    if (it != table[idx].end()) {
6      table[idx].erase(it);
7      n--;
8    }
9  }
```

As we can see, with linked list it is clearly easier to erase an element.

3.2.2 Move to front

3.2.3 When to resize an array

3.2.4 How to delete an entry

3.3 Open Addressing vs Chaining Hashing

When comparing Open Addressing vs Chaning hashing we can cite many pros and cons. I will start with the open addressing pros. Among the pros of open addressing we can see that open addressing techniques such as linear probing tend to be more cache friendly. That is because as the key value pairs are stored in the memory in a sequential way with the vector, when loading a key value pair we will load a chuck of memory that is around him (that will have other key value pairs). Another thing that can be said to ilustrate that is the 80 / 20 percent rule, that when applied to hash tables means that "in practice" 80% of the keys will be accessed 20% of the time (and 20% of the keys will be accessed 80% of the time). This is only for illustration purposes, obviously this is not valid for every application, as we can artificially create one that don't apply. Another advantage of open addressing is that all the memory will be in a single and sequential "Block" of memory.

Chapter 4

Applications

Hash functions and hash tables have a great number of applications in computer science. During this last section I focus on applications of hash functions in algorithms, but citing superficially applications in other areas (like criptography, data deduplication and caching).

Among the applications that I explain in this section there is a focus in two applications: Rabin-Karp string matching algorithm and hashing of a rooted tree for isomorphism checking. Rabin-karp string matching algorithm is one of the main application of a technique called rolling hashing. Hahsing of rooted tree for isomorphism checking is an interesting application sometimes used in competitive programming.

To motivate the start of this thesis I will start using hash tables to solve a very simple, yet famous, problem called 3-sum.

4.1 3-sum problem

The problem is stated as following:

"*Make a function that given an array of integer numbers and an integer S, it returns if there are any 3 different elements in this array that its sum equals S. Assume that there are no three different elements in the array that overflow a 32-bit integer when summed together.*"

This a very interesting problem that has many different solutions. To start I will show and explain to you the brute force solution:

```
1 bool threeSumWithoutHashTable(vector<int> v, int S) {
2     for (int i = 0; i < v.size(); i++) {
3         for (int j = i + 1; j < v.size(); j++) {
4             for (int k = j + 1; k < v.size(); k++) {
5                 if (v[i] + v[j] + v[k] == S) return true;
6             }
7         }
8     }
```

```
9     return false;
10 }
```

The above solution solves the problem in $O(n^3)$ time complexity and $O(1)$ memory complexity, being n the size of the array. It don't allocate any memory but checks every triple to find if one satisfy the condition. The question is, can we do better in time complexity using hash tables? The answer is yes:

```
1 bool threeSumWithHashTable(vector<int> v, int S) {
2     unordered_map<int, int> hashTable;
3     for (int i = 0; i < v.size(); i++) {
4         hashTable[v[i]]++;
5     }
6     for (int i = 0; i < v.size(); i++) {
7         for (int j = i + 1; j < v.size(); j++) {
8             hashTable[v[i]]--;
9             hashTable[v[j]]--;
10            if (hashTable.find(S - v[i] - v[j]) != hashTable.end() &&
11                hashTable[S - v[i] - v[j]] > 0) return true;
12            hashTable[v[i]]++;
13            hashTable[v[j]]++;
14        }
15    }
16    return false;
17 }
```

The above solution solves the problem in $O(n^2)$, time complexity (average) and $O(n)$ memory complexity. Although the worst case scenario is $O(n^3)$ and it uses more memory, this solution is way faster in practice for large input cases. To showcase this I made simmulations with the codes shown (that can be found in bibliography), the results are:

ArraySize	Time Without Hash Table	Time with Hash Table	Increase in Performance
128	4.231ms	6.494ms	-53.4%
256	34.223ms	26.665ms	22.0%
512	267.499ms	99.130ms	62.9%
1024	1742.688ms	302.453ms	82.6%
2048	7345.126ms	683.197ms	90.6%
4096	25029.888ms	761.363ms	96.9%

As we can see for the table above, the three sum solution using hash table quickly surpasses the brute force implementation.

4.2 Rabin-Karp

Rabin karp is a famous pattern matching on string algorithm. Differently than other classic solutions to pattern matching, such as Knuth-Morris-Pratt algorithm or Boyer Moore, Rabin karp is based on hashing. It relies on the property that if the hash of two strings is different, they are certainly different strings, and if they are equal, they can be the same string. The definition of the pattern matching problem is the following:

"*Make a function that given two strings, one string t and one string p, it returns the index of the first occurrence of p in t, or -1 if p is not present in t. It is guaranteed that the lenght of t is greater than the lenght of p.*"

So given two strings, we need to find the first ocurrence of p in t. To first solve this problem, I will use the naive, brute force solution:

```
1 int findPatternBruteForce(string t, string p) {
2     for (int i = 0; i <= t.size() - p.size(); i++) {
3         bool match = true;
4         for (int j = 0; j < p.size(); j++) {
5             if (t[i + j] != p[j]) {
6                 match = false;
7                 break;
8             }
9         }
10        if (match) return i;
11    }
12
13    return -1;
14 }
```

We can see that the brute force solution has worst case scenario of $O(nm)$ being $n = |t|$, the size of the string t, and $m = |p|$, the size of the string p. One posible optimization for this solution is if we could check a text interval against the pattern quicket than $O(m)$. If we had the hash of the pattern and the hash of the text interval, we could easily do that. The hash of the pattern is constant, but we have $O(n)$ intervals to check, and given that each interval has $O(m)$ size, if we calculated each of them alone this would take $O(nm)$ again. However, for some hash functions, given the hash of an interval we could calculate the next hash faster. One example of a hash function with this property is the $dumbHashXOR$ hash function presented in chapter 1. Lets test it with intervals in "abracadabra" with intervals of size 4:

$$dumbHashXOR(\text{"}brac\text{"}) = dumbHashXOR(\text{"}abra\text{"}) \oplus \text{"}a\text{"} \oplus \text{"}c\text{"}$$

So given the hash of 'abra' we could easily move to 'brac'. Functions with this "shifting" property are called rolling hash functions. As we saw in the hash function chapter, "dumb-

HashXOR" is a bad hash function. Hopefully, we have better rolling hash functions for that, one example is polynomial hashing. The polynomial hashing of a string s with prime P would be:

$$\sum_{i=0}^{m-1} s[i] * P^i$$

So we know that given hash of $s[0...m-1]$ we can calculate the hash of $s[1...m]$ in $O(1)$ in the following way:

$$PolynomialHash(s[1...m]) = \sum_{i=1}^{m} s[i] * P^{i-1} = \sum_{i=0}^{m-1} s[i] * P^i - s[0] + s[m] * P^{m-1}$$

We would just need to store P^{m-1} for recalculating the hash. So we can check if the pattern is matched on the text quicker with hashing. As just hashing may return a match where we don't have a match, we need to double check to have 100% accuracy. So the algorithm will be:

```
1 const int PRIME = 33;
2 const int MOD = 1000033;
3 int findPatternRabinKarp(string t, string p) {
4    int textHash = 0, patternHash = 0;
5    int pot = 1;
6
7    // pot will be PRIME^{p.size() - 1}
8    for (int i = 0; i < p.size() - 1; i++)
9       pot = (pot * PRIME) % MOD;
10
11   for (int i = 0; i < p.size(); i++) {
12      textHash = (textHash * PRIME + t[i]) % MOD;
13      patternHash = (patternHash * PRIME + p[i]) % MOD;
14   }
15
16   for (int i = 0; i <= t.size() - p.size(); i++) {
17      if (textHash == patternHash) {
18         bool match = true;
19         for (int j = 0; j < p.size(); j++) {
20            if (t[i + j] != p[j]) {
21               match = false;
22               break;
23            }
24         }
25         if (match) return i;
26      }
27
```

```
28          textHash = (PRIME * (textHash - pot * t[i]) + t[i + p.size()] + MOD)
                % MOD;
29      }
30
31      return -1;
32  }
```

the complexity of this algorithm is $O(n)$ expected, because the number of string collusions on line 17 on the code above is expected to be low. One interesting fact is that when testing both algorithms shown against each other, for random strings, generated with random characters, the first algorithm is actually faster. That is because in most cases we would exit the brute force early on (we have actually $(1/26)^j$ chance of getting to the next step for each check for an alphabetical random string), making it "expected linear" for this case. And as Rabin Karp has an overhead for calculating the hash, that makes it slower for that case. But that doesn't mean that the algorithm is actually worse, for real text and for random strings where each character is repeated 100 times the algorithm show its strength.

All the code and tests made for this algorithm can be find in my github [**?**].

4.3 Hashing trees to check for Isomorphism

For this last alogrithmic application of hash functions and hash tables I will describe how to decide if two rooted trees are isomorphic. We can say that two trees, T_1 and tree T_2 are isomorphic if there is a bijection between vertices V_1 and V_2 such that:

$$\forall u, v \in V_1 \;\; u \; adj_{T_1} \; v \iff \phi(u) \; adj_{T_2} \; \phi(v)$$

That is, if u is adjacent to v in the first tree, $phi(u)$ must be adjacent to $phi(v)$ in the second tree (and vice versa).

Given that definition, we can state the problem of deciding if two trees are isomorphic:

"*Make a function that given two rooted trees, decide if they are isomorphic.*"

We could solve this problem using hash functions if we knew how to hash trees to integers. As we saw in the first chapter, everything is bits in the end and we just need a smart way of representing our data. We can represent a rooted tree as a node that points to its child nodes and so on. So we could define a great hash function that always collide when we have isomorphic trees. The following hash function was described by competitive programmer *rng_58* in his blog [**?**].

$$Hash(N) = \begin{cases} 1 \text{ if N is a leaf (has no childs)} \\ \Pi_{i=1}^{k}(x_d + Hash(C_i)) \; modM \text{ where } C_i \text{ is a child node, and d is the depth of N} \end{cases}$$

For that function we need an array x at the least the size of the maximum depth between both trees. That function is actually a polynomial value of our tree. We can visualize that on the following image:

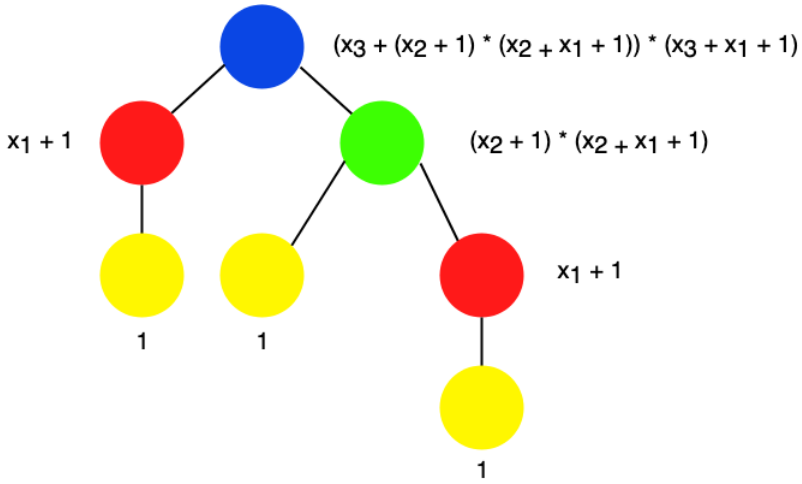

Figure 4.1: *Example of a tree with the hash of each node.*

Chapter 5

Conclusions

Texto texto[1].

[1]Exemplo de referência para página Web: www.vision.ime.usp.br/~jmena/stuff/tese-exemplo

Appendix A

Apendix

Texto texto.